Instruction Manual

PTM DUAL SERIES NARROW RANGE POWER SUPPLIES

INCLUDES THE FOLLOWING PTM MODELS:

MODULE I 12-1D 15-.8D

POWERSUPPLES

MODULE II 12-1.6D 15-1.5D MODULE III 12-3D 15-2.8D

Sorensen Company

676 Island Pond Road Manchester, N.H. 03103 Tel: 603-668-4500 Twx: 710-220-1339



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SORENSEN COMPANY

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1. INTRODUCTION

1.1 **PURPOSE**

This manual contains operating and maintenance instructions on the dual PTM modular power-supply line, manufactured by the Sorensen Company, 676 Island Pond Road, Manchester, N.H. The line consists of 9 models, all similar in electrical design and physical appearance. The models are grouped into 3 sizes; Modules I, II, & III, which differ in the power output rating and in overall size. (See Table 1-1, General Specifications.)

1.2 DESCRIPTION

1.2.1 General

Designed for operation on any of three separate single-phase inputs, the units provide a variety of highly regulated dc outputs. (Refer to table 1-1 for general specifications.) They also offer extremely fast recovery times as well as characteristically low output impedances.

The supplies are designed to be mounted in any one of three positions; end, bottom or side. Four tapped mounting holes are provided on each side.

For Module II and Module III, an extruded-aluminum finned heat sink (radiator) is supplied on the rear side to eliminate the need for an external heat-dissipation device. For Module I the heat sink is mount-ed internally.

1.2.2 Functional

Operational features of the PTM series power supplies include remote sensing, remote programming, overload and short-circuit protection by current limiting (foldback), and over-voltage protection by an integral electronic crowbar circuit. (Refer to table 1-1.)

1.2.2.1 Remote Sensing

In applications where variations in the load-lead drops adversely affect load regulation, remote sensing may be used to extend the unit's regulating point from the output terminals to the load. In the PTM series, remote sensing will compensate for 250 mV of drop per load lead, maximum.

1.2.2.2 Remote Programming

With the remote-programming feature, unit output voltage may be altered from a remote location by introducing a calculated resistance into the programming network. The ohms/volt ratio is approximately $500 \pm 8\%$.

1.2.2.3 Series Operation

The PTM dual series is not suitable for series connection. Series operation generally makes start-up difficult because of the fold-back current-limiting feature.

1.2.2.4 Parallel Operation

The PTM dual series is not suitable for parallel operation.

1.2.2.5 Overcurrent Protection

In the event of an overcurrent condition, such as a short circuit, a current-foldback circuit (pre-set at the factory to 125% of rated current at 40° C), operates to reduce both the unit output voltage and current.

1.2.2.6 Overvoltage Protection

In the event of an overvoltage condition on the output, such as a failure in the power supply or an externally induced condition, an overvoltage electronic crowbar is actuated by an integral OVP sensing circuit. The crowbar acts quickly to reduce the output voltage to approximately zero, and the cause power supply to go into current foldback condition.

1.3 Input Options

Standard PTM Dual models are factory wired for 115 Vac operation. Units may be field or factory modified, however, to accept inputs of 220 Vac (M1 option) or 230 Vac (M2 option). Refer to Figure 2-1 on page 2-3 for required input transformer modifications.

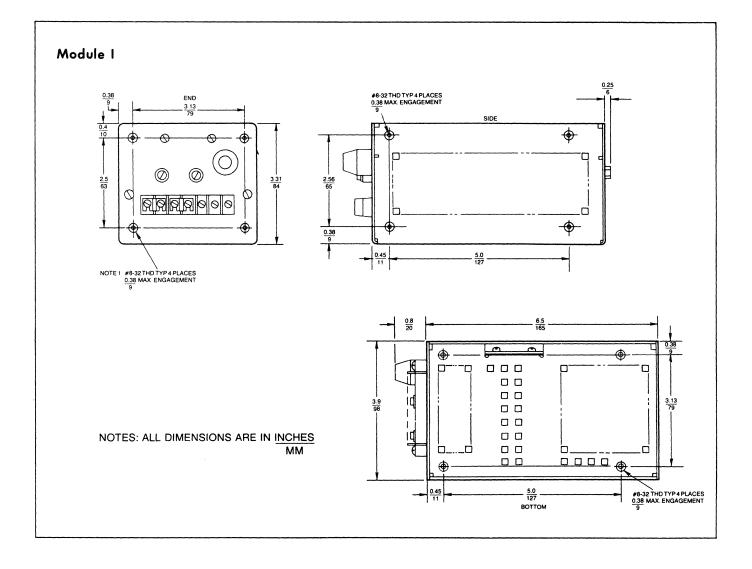


Figure 1-1 PTM Outline Drawing (Module I)

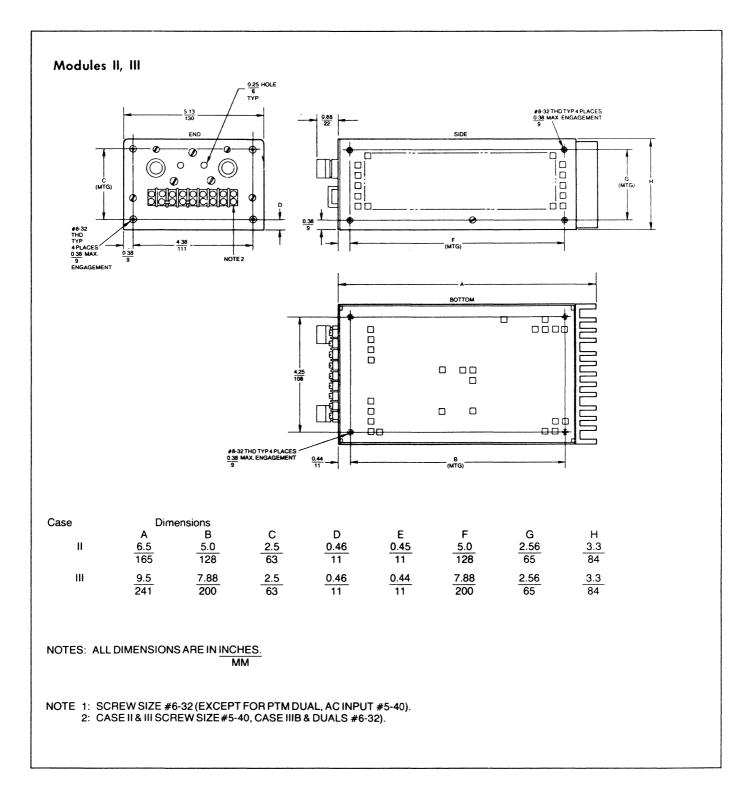


Figure 1-2 PTM Outline Drawing (Modules II, III)

MODULE I	<u>INPL</u> V	II A	(+)V	<u>OUTPU</u> A	I (-)V	A	NOMINAL AC INPUT FUSE (A)
12-1D	105-125	.60	11-13	1.0	11-13	1.0	1.0
158D	105-125	.60	14-16	.8	14-16	.8	1.0
12-1DM1	200-240	.35	11-13	1.0	11-13	1.0	.5
158DM1	200-240	.35	14-16		14-16	.8	.5
12-1DM2	210-250	.30	11-13	1.0	11-13	1.0	.5
158DM2	210-250	.30	14-16	.8	14-16	.8	.5
MODULE II							
12-1.6D	105-125	.90	11-13	1.6	11-13	1.6	1.5
15-1.5D	105-125	.90	14-16	1.5	14-16	1.5	1.5
12-1.6DM1	200-240	.80	11-13	1.6	11-13	1.6	.75
15-1.5DM1	200-240	,80	14-16	1.5	14-16	1.5	
12-1.6DM2	210-250	.45	11-13	1.6	11-13	1.6	.75
15-1.5DM2	210-250	.45	14-16	1.5	14-16	1.5	.75
MODULE III							
12-3D	105-125	1.8	11-13	3.0	11-13	3.0	2.0
15-2.8D	105-125	1.8	14-16	2.8	14-16	2.8	2.0
12-3DM1	200-240	.96	11-13	3.0	11-13	3.0	1.0
15-2.8DM1	200-240	.95	14-16	2.8	14-16	2.8	1.0
12-3DM2	210-250	.90	11-13	3.0	11-13	3.0	1.0
15-2.8DM2	210-250	.90	14-16	2.8	14-16	2.8	1.0

TABLE 1-1 GENERAL SPECIFICATIONS (ALL MODELS)

Turn-ON/OFF Overshoot:	None (output voltage)
Transient Response:	50 microseconds for load changes of 10 to 100% or 100 to 10\%, based on recovery to within a ± 20 mV band
Remote Programming:	500 ohms per volt (approximately)
Current Limit:	Automatic, adjustable, foldback-type. Minimum range 50 to 130% of 40°C rated current. Factory set to approximately 125% of rated (40°C) current (see indi- vidual unit specifications).
Overvoltage Limit:	Automatic, adjustable (OVP) crowbar action, self-contained. Factory set (see indivi- dual unit specifications for setting).
	Outputs are sensed separately and both outputs are shorted by an internal SCR within 50 microseconds.
	OVP stability .05%/°C of voltage trip setting (typical).
EMI (RFI):	Requirements CEO3 (conducted emissions over 20 kHz to 50 MHz) and REO2 (radiated emissions over 15 kHz to 10 GHz) of MIL- STD-461 apply.
Stability:	After one hour warm-up, 0.1% for 24 hours with all external effects held constant.
Parallel Operation:	Not recommended.
Series Operation:	Not recommended.

TABLE 1-1 GENERAL SPECIFICATIONS (cont'd)

TABLE	1-1	GENERAL	SPECIFICATIONS	(cont'd)
			51 2011 10/11 10/15	

Remote Sensing:	250 mV drop per leg maximum. Remote sense (+) & (-) terminals provided
Ambient Rating:	O to 71ºC (see current ratings in indivi- dual unit specifications)
Cooling:	Natural convection (maintain free airflow from under unit)
Dimensions inches (mm): Width: Height: Depth:	Module I Module II Module III 3-7/8 (98) 5-1/8 (120) 5-1/8 (130) 3-5/16 (84) 3-5/16 (84) 3-5/16 (84) 6-1/2 (165) 6-1/2 (165) 9-1/2 (241)
Weight lbs.(kg):	5-1/4 (2.4) 7-1/2 (3.4) 11 (5)
Input-Output Connec- tions:	All connections on Modules II & III are made to a 10-terminal barrier strip using #5-40 screws. On Module I all input con- nections are made on a 3-terminal barrier strip. A 7-terminal barrier strap is used for the output connections.

Model No	12-1D		158D	
Output Ratings Nominal Voltage (Vdc) Voltage Range (Vdc) Regulation (mV) Current (Adc)* @ 40°C @ 50°C @ 60°C @ 71°C	+12 11-12 6.5 1.0 .9 .7 .4	-12 11-12 6.5 1.0 .9 .7 .4	+15 14-16 8.0 .8 .72 .56 .32	-15 14-16 8.0 .8 .72 .56 .32
Current Limit (Adc) Factory set to	1.2	1.2	.95	.95
Overvoltage Limit (Vdc) Factory set to	14.6	14.6	17.5	17.5
Input Ratings Efficiency (%) Power Factor (%)	55 80	55 80	54 80	54 80
Output Adjust Resolution (mV)	25	25	25	25

TABLE 1-1 UNIT SPECIFICATIONS-MODULE I

*NOTE

Specifications listed for balanced load conditions. If unit is to be operated with unbalanced loads, consult factory for applications assistance.

Model No.	12	-1.6D	15-	·1.5D
Output Ratings Nominal Voltage (Vdc) Voltage Range (Vdc) Regulation (mV) Current (Adc)* @ 40°C @ 50°C @ 60°C @ 71°C	+12 11-13 6.5 1.6 1.4 1.1 .65	-12 11-13 6.5 1.6 1.4 1.1 .65	+15 14-16 8.0 1.5 1.35 1.05 .6	-15 14-16 8.0 1.5 1.35 1.05 *6
Current Limit (Adc) Factory set to	1.8	1.8	1.7	1.7
Overvoltage Limit (Vdc) Factory set to	14.6	14.6	17.5	17.5
Input Ratings Efficiency (%) Power Factor (%)	53 81	53 81	52 81	52 81
Output Adjust Resolution (mV)	25	25	25	25

TABLE 1-1 UNIT SPECIFICATIONS-MODULE II

*NOTE

Specifications listed for balanced load conditions. If unit is to be operated with unbalanced loads, consult factory for applications assistance.

Model No.	12	-3D	15-	-2.8D
Output Ratings Nominal Voltage (Vdc) Voltage Range (Vdc) Regulation (mV) Current (Adc)* @ 40°C @ 50°C @ 60°C @ 71°C	+12 11-12 6.5 3.0 2.7 2.1 1.2	-12 11-12 6.5 3.0 2.7 2.1 1.2	+15 1 4 -16 8.0 2.8 2.4 1.9 1.1	-15 14-16 8.0 2.8 2.4 1.9 1.1
Current Limit (Adc) Factory set to	3.4	3.4	3.2	3.2
Overvoltage Limit (Vdc) Factory set to	14.6	14.6	17.5	17.5
Input Ratings Efficiency (%) Power Factor (%)	57 82	57 82	56 82	56 82
Output Adjust Resolution (mV)	25	25	25	25

TABLE 1-1 UNIT SPECIFICATIONS-MODULE III

*NOTE

Specifications listed for balanced load conditions. If unit is to be operated with unbalanced loads, consult factory for applications assitance.

2. INSTALLATION

2.1 GENERAL

Following unpacking, general inspection and preliminary check-out procedures should be performed to assure that the unit is in proper working order. These consist of visually inspecting for physical damage and performing a few electrical checks. If it is determined that the unit is damaged, the carrier should be notified immediately. The carrier's claim agent will prepare a report of damage. The user is required to send this report to the Service Department, Sorensen Company, 676 Island Pond Road, Manchester, N.H. 03103. Sorensen will advise the user as to what action is required to repair or replace the supply.

2.2 INSPECTION

Check for damage incurred during shipment as follows:

- 1. Inspect enclosures for dents, chips and other obvious signs of damage.
- 2. Check condition of external terminal board. Make certain that all terminal screws are in place and that links are fitted over the barrier strips between terminals 1 and 2, 3 and 4, and between 5, 6 and 7.
- 3. Inspect fuse holders for evidence of damage.
- 4. If internal damage is suspected;
 - a. Remove the (4) flat-head screws on front panel.
 - b. (Group III Only) remove the (2) flat-head screws, one on each side.

- c. Remove the (6) round-head screws on rear heat sink, top edge and end side.
- d. Loosen the (2) round-head screws on the lower edge of the heat sink.
- e. Inspect PCB, transformer, capacitor and potentiometers.
- 5. The PCB and potentiometer bracket assembly can be removed by removing the three round-head screws retaining the bracket to the front panel.
- 6. The heat-sink assembly at the rear can be removed by removing the two lower rear round-head screws. Check that the power transistors are firmly plugged into their sockets. These may be readily removed for servicing.

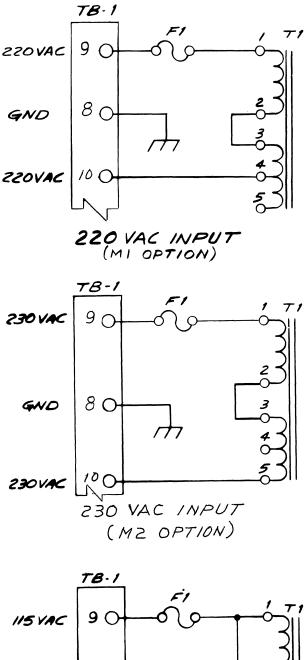
2.3 INPUT CONNECTIONS

If either of the two alternatives to a nominal 115-Vac input is to be used, transformer T1 primary tap wiring should be changed as indicated in figure 2-1. The factory-wired 115-Vac configuration is included to facilitate reconversion to this input if such action becomes desirable. Remount enclosures following inspection or tap changing.

2.4 ELECTRICAL CHECK

To perform an initial electrical check, proceed as follows:

 Make certain that the unit is located in an area where free passage of air is unrestricted. For Modules II & III connect input leads to terminals 9 and 10 (IN) on unit terminal board. Use terminal 8 (GND) for input system ground. For Module



HSVAC = 90

115 VAC INPUT

MODULE I (SAME AS 115 Vac EXCEPT) 1) REMOVE JUMPER FROM T1-1 TO T1-3 2) REMOVE JUMPER FROM T1-2 to T1-5 &LOCATE FROM T1-2 to T1-3 3) REMOVE JUMPER FROM TB1-2 to T1-5 & LOCATE FROM TB1-2 TO T1-4 4) CHANGE FUSES: .5 AMP. 250V to .25 AMP. 250V-PN 226-7176P32 (5/12DI) OR 1 AMP. 250V to .5 AMP. 250V-PN 226-7176P36 (all others) MODULES II AND III (SAME AS 115 Vac EXCEPT) 1) REMOVE JUMPER FROM T1-1 TO T1-3 2).REMOVE JUMPER FROM T1-2 TO T1-5 3) REMOVE JUMPER FROM TB1-10 TO T1-5 & LOCATE FROM TB1-10 TO T1-4 4) CHANGE FUSES: 1.5 AMP. 250V TO .75 AMP. 25CV-PN 226-7176P38 (MOD.II) OR 2 AMP, 250V TO 1 AMP, 250V, PN 226-7176P39 (MOD. III) MODULE I (SAME AS 115 Vac EXCEPT) 1) REMOVE JUMPER FROM T1-1 to T1-3 2) REMOVE JUMPER FROM T1-2 TO T1-5 & LOCATE FROM T1-2 TO T1-3 3) CHANGE FUSES: .5 AMP. 250V to .25 AMP. 250V-PN 226-7176P32 (5/12DI) OR 1 AMP. 250V TO .5AMP. 250V-PN 226-7176P 36 (all others) MODULES II & III (SAME AS 115 Vac EXCEPT) 1) REMOVE JUMPER FROM T1-1 TO T1-3 2) REMOVE JUMPER FROM T1-2 TO T1-5 3) CHANGE FUSES: 1.5 AMP. 250V TO .75 AMP. 250V-PN 226-7176P38 (MOD. II) 2 AMP 250V TO 1 AMP. 250V-PN 226-7176P39 (MOD. III)

MODULE I T1 PIN 1 TO TB-1 PIN 1 T1 PIN 2 TO TB-1 PIN 2 TB-1 PIN 3 IS GND. MODULES II & III T1 PIN 1 TO TB-1 PIN 9 T1 PIN 2 TO TB-1 PIN 10 TB-1 PIN 8 IS GND.

FIGURE 2-1 INPUT CONNECTIONS

I use 3-position terminal board. Connect input leads to terminals 1 and 2, and use terminal 3 (GND) for input system ground.

- Connect a dc voltmeter across terminals 2 and 4, (+V) and 4 and 6 (-V). Select a voltage range compatible with rated output.
- 3. Apply nominal rated input power.
- Rotate output adjust sufficiently to swing the dc voltmeter from minimum to maximum rated voltage (per table 1-1). Do not exceed the maximum ratings.
- 5. Set output voltage to the unit's nominal value and remove input power.

2.5 MOUNTING

These units may be mounted in a variety of positions and locations, including rack mounting.

 For cantilever - type mounting from a vertical panel or wall (where free access to vertical airflow is available):

End Mounting - Use knockout per figure 2-2 for Module I units, figure 2-3 for Module II units, or figure 2-4 for Module III units. This knockout clears the terminal block and fuses.

Side or Bottom Mounting - No knockout is needed. Use the four mounting holes shown in figures 2-2, 2-3 or 2-4.

2. For flat mounting from a horizontal surface (where free access to vertical airflow is not available):

End Mounting - Not recommended.

<u>Side Mounting</u> - Use knockout per figures 2-2, 2-3 or 2-4. Note that dotted area is suggested for additional heat-sink cooling, but is optional for Modules II & III only.

Bottom Mounting - Use knockout per figures 2-2, 2-3 or 2-4.

- 3. Vertical panel mounting per 1. preceding is preferred since maximum airflow is assured. Horizontal surface mounting per 2. preceding, using bottom mounting with proper knockout is the second preference.
- 4. Mounting screws should be No. 8-32 and just long enough to penetrate 1/4 inch into the PTM unit and through the mounting surface and lock/flat washers used.

NOTE

Vertical panel mounting per paragraph 1 preceding is preferred since maximum airflow is assured. Horizontal surface mounting, using bottom mounting with proper knockout is the second preference.

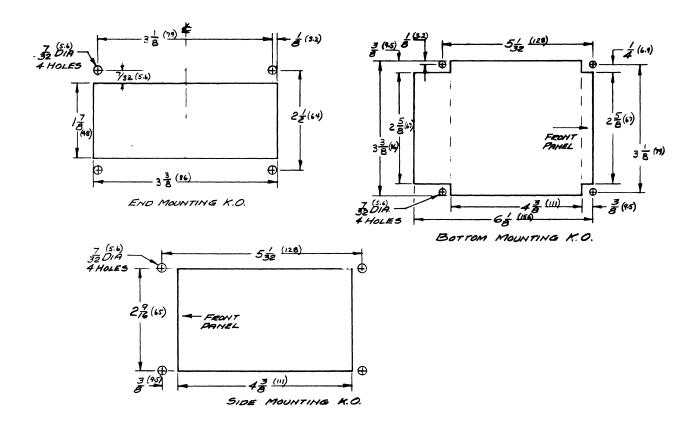


Figure 2-2 Knockout Dimensions Module I

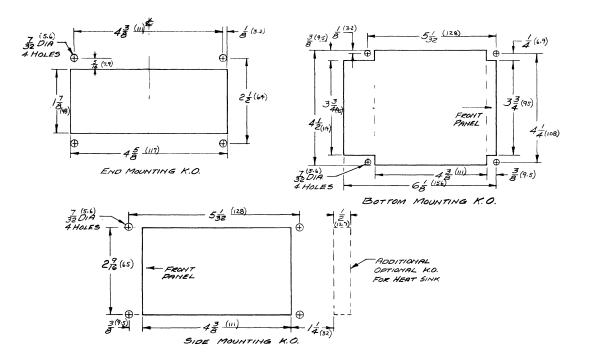


Figure 2-3 Knockout Dimensions Module II

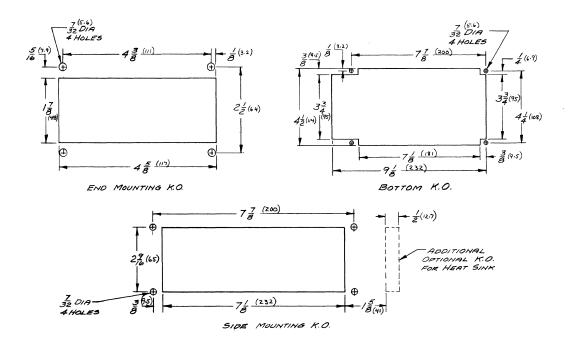


Figure 2-4 Knockout Dimensions Module III

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3. OPERATION

3.1 GENERAL

This section contains instructions on how to adapt the unit to, and operate it in, a number of varied applications. These include local sensing, remote sensing, and remote programming.



The sensing and power circuits form a closed loop. Opening this loop, either by removing a terminal board link or disconnecting a sensing or programming lead will result in a high unit output and will cause the OVP crowbar to operate, (Para. 4.3.4).

3.2 CONTROLS

PTM dual units are equipped with two panel output controls. The output adjust control is used to vary the output voltage. Both are factory-set to nominal values (see table 1-1).

3.3 **PRE-OPERATION CONSIDERATIONS**

3.3.1 Current-Foldback Setting

The current foldback point is factory-set to approximately 125% of rated 40°C current. If the unit is to be operated in other ambients, the rated output current is derated per table 1-1. It is recommended for ambient temperatures above 40°C, the foldback should be reset to approximately 125% of the derated output current.

3.3.2 Current-Foldback Reset

To reset the current foldback, proceed as follows:

- 1. Adjust R4 and R18 fully counterclockwise (CCW).
- 2. Short negative output.
- Adjust R4 potentiometer on printed circuit card until current is approximately that shown on table 4-1 (Short Circuit Limits).
- 4. Remove short from negative output.
- 5. Increase load to maximum foldback current as per table 4-1.
- Adjust R18 clockwise until power supply goes out of regulation.
- 7. Maximum current limit is then set per table 1-1.

3.3.3 OVP Setting for 12-Volt and 15-Volt Models

- 1. Set output voltage to nominal value, (12 or 15 volts).
- 2. Adjust R25 on printed circuit card to its approximate center position.
- 3. To test for OVP trip point, remove jumper from terminals 1 and 2 or 5 and 6. In either case OVP should trip.

3.4 LOCAL SENSING

The unit is shipped ready for use in the local-sensing mode. In this mode, regulation is at the output terminals, not at the load. If variations in load-line voltage drops are expected to be prohibitive, refer to paragraph 3.5, remote sensing.

To operate the unit, proceed as follows:

- Connect a voltmeter across output terminals 2 and 4 (+V) or 4 and 6 (-V).
- Attach the input leads on Modules II or III to terminals 9 and 10. Use terminal 8 (GRD) to ground input system. On Module I, use terminals 1 and 2 on 3-position board. Use terminal 3 to ground input system.
- 3. Apply nominal input power.
- 4. Rotate output adjust until desired output voltage is indicated on voltmeter.
- 5. Remove input power, disconnect voltmeter and connect load leads to terminals 2 and 4 or 4 and 6. Do not remove or loosen any of the interconnecting links. Apply nominal input. Unit supplies highly regulated power to load.



Do not touch enclosure while unit is operating under load. Surface temperature is comparatively high. If unit must be handled immediately after operation, wear heat-resistant gloves.

3.5 REMOTE SENSING

If it is desirable to sense (regulate) unit output at the load rather than at output terminals, remove the links between terminals 1 and 2, 3 and 4, and 5 and 6. Run sense leads from terminals 2, 4 and 6 as shown in figure 3.1. Sensing leads should be fabricated using a shielded and twisted pair of wires. Put unit into operation per paragraph 3.4. With remote sensing unit transient response degenerates slightly. The load carrying leads at terminals 1, 3 and 5 should be selected to limit the voltage drop to 250 millivolts per lead.

3.6 REMOTE PROGRAMMING

The unit may be programmed to supply pre-determined output voltages by inserting a calculated resistance into the voltage-sensing circuit. Programming sensitivity is approximately 500-ohms-per volt; that is 500 ohms are required for each volt difference between the desired output and the minimum value of the unit's specified range. The program resistor should be a 1/8-watt (or larger) precision film resistor with a 25 PPM/^OC coefficient (equal to MIL style RN55E). The programming current is approximately 2 milliamperes.

To adapt the unit for remote programming, proceed as follows:

 With normal local sensing (see paragraph 3.4), apply power and set output control for specified rated minimum output voltage (see table 1-1 for specific model). For example, for a 12-volt module, set the output to 11.0 volts.

- 2. At this point, any value within rated output range (table 1-1) can be obtained by inserting 500 ohms-per volt difference between the desired voltage and the minimum voltage. For example, to obtain 12.0-volt output in the above example the difference is 12.0 (-) 11.0 or 1.0 volt. The programming resistor should be 1.0 X 500 or 500 ohms.
- 3. Remove input power. Connect programming resistor (Rp) per figure 3-2. Note that either local or remote sense can be used.
- 4. Apply input power and verify load voltage across terminals 2 and 4, 4 and 6 as the desired value (using local sense).

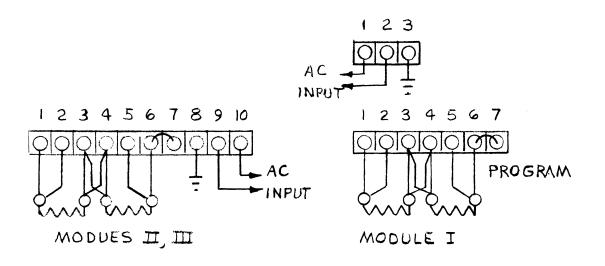


Figure 3-1 Remote Sensing Configuration

3.6.1 Fixed Output Voltage Setting

For the optimum long-term stability of the output voltage, the remote program feature can be used to reduce the long-term drift of the output by disabling the output control. Proceed as follows:

- 1. Remove top cover per paragraph 2.2.4. Remove three screws holding printed circuit card to front panel per paragraph 2.2.5.
- 2. Short out the potentiometer R35 or R34 by soldering a wire between the two end pins of the potentiometer.
- 3. Reassemble printed circuit card and cover.
- 4. Connect a precision variable potentiometer or decade box for the programming resistor per figure 3-2.
- 5. Set variable resistor to zero and apply input power.
- 6. Vary resistor value until desired output voltage is obtained.
- 7. Remove power, measure variable resistor, and replace it by a fixed precision resistor (see 3.6 preceding for type).
- 8. Set power to ON and verify that the output voltage is proper value.

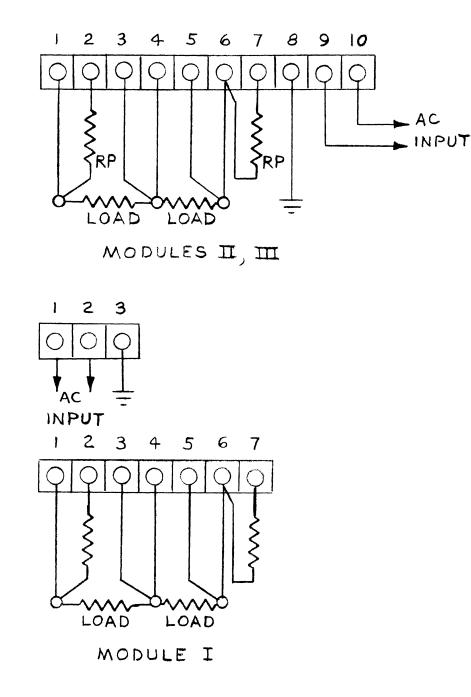


Figure 3-2 Resistance Programming Set-up

4. THEORY OF OPERATION

4.1 GENERAL

This section provides basic PTM unit operating principles which, when used with the troubleshooting data from section 5, should contribute to the rapid isolation of unit faults. Where differences in circuitry among units are significant, separate discussions are provided.

4.2 PASSING-STAGE PRINCIPLE

The PTM modules utilize the series passing-stage principle in regulating unit output. With this approach, a variable impedance absorbs the difference between the desired regulated output and the filtered "brute-force" dc. The variable impedance is provided by a transistor stage which is fed by an output-related control signal.

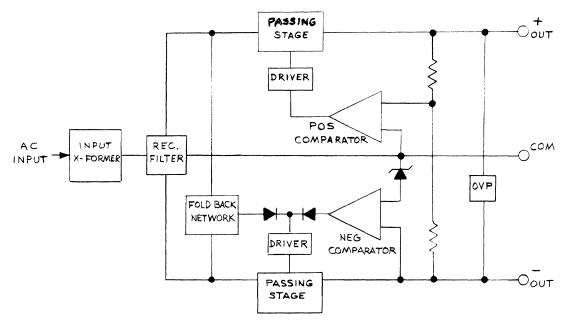


Figure 4-1 PTM Dual Simplified Diagram

4.3 FUNCTIONAL THEORY

Referring to figure 4-1: The transformer center tap steps down the ac input and applies it to a rectifier circuit and filter. The dc output is fed through a passing stage to the load. The passing stage absorbs the difference between the rectifier output and the desired output voltage. The feedback loop to the passing stage includes an output voltage sensing network and a reference voltage. These two signals are compared in a differential amplifier. The amplified error signal is used to vary the drive current to the pass stage. This discussion applies to both positive and negative outputs.

Overcurrent protection is provided by the foldback section. In the event of a short circuit or overload, this circuit reduces the drive on the pass stage. Overvoltage protection is provided by a sensing network which triggers on electronic crowbar circuit in the event of excessive output voltage. (Refer to figure 5-2.)

4.3.1 Sensing and Error Amplification

The positive and negative integrated circuits, U2 and U3 act to maintain a zero error signal across the IC input terminals. The amplified error signal is used to drive the passing stages; via comparators and drivers. The IC output is phased such that an increase in output voltage acts to decrease the drive. This action restores the output voltage to its regulated value (as set by the reference voltage and sense resistors).

4.3.2 Drivers and Passing Stage

Ql and Q2 serve as drivers for the positive and negative output passstages respectively. Resistors R37, R38, R40 and R41 in Module III units insure equal current sharing by all transistors.

4.3.3 Current Foldback Section

Signals from two current monitoring resistors are fed to operational amplifier (U1) input through dividers R1 through R5. These two current signals are added by the divider resistors. The U1 input voltage is then proportional to the sum of the two current-monitoring resistor voltage drops. The output of the current limit operational amplifier is connected to an OR gate consisting of CR1, CR3 and R14. Once the current limit is exceeded, U1 takes control of Q2 thus taking control of the negative supply. The positive supply is slaved to the negative half and is controlled indirectly by U1.

4.3.4 Overvoltage Protection

The dc outputs are protected from an overvoltage condition by an internally adjustable protection circuit. The outputs are sensed separately, and in the event of an overvoltage condition in either output, an internal SCR shorts the positive output to the negative output within 50 microseconds. This feature together with built-in reverse-polarity diodes on each output effectively keeps the outputs within 2.5 volts of the common after an OVP trip. The circuit is designed to tolerate the OVP tripped condition indefinitely. Table 4-1 represents the span of possible trip voltages for all units.

4.3.5 Loop Stability

Inherent in any high-gain feedback amplifier is the tendency for the loop to become unstable under certain operating conditions. To preclude this in the PTM amplifier loop, RC networks consisting of these are C2, C3, C1, R10, R13, C4, C5 and R20 have been incorporated.

M	ODEL	SHORT CIRCUIT LIMITS (A)	MAX. FOLDBACK <u>CURRENT LIMITS (A)</u>
MOD I	12-1D	0.4	1.25
	158D	0.4	1.0
MOD II	12-1.6D	0.5	2.0
	15-1.5D	0.5	1.9
MOD III	12-3D	1.0	3.75
	15-2.8D	1.0	3.5

*

TABLE 4-1 POSSIBLE TRIP VOLTAGES

5 SERVICE AND REPAIR

5.1 GENERAL

This section provides troubleshooting data, periodic servicing, and calibration and performance-testing procedures. The troubleshooting data should be used in conjunction with both the schematic diagram, (figure 5-1) and section 4, which outlines the principles of operation. Also, figures 5-2 and 5-3 physically locate the parts contained in a typical supply. Any questions pertaining to repair should be directed to the nearest Sorensen Service Representative or to the Service Dept., Sorensen Company, 676 Island Pond Road, Manchester, N.H. 03103. Should it be necessary to return a unit to the factory for repair, authorization from the Sorensen Service Dept. must first be obtained.

5.2 PERIODIC SERVICING

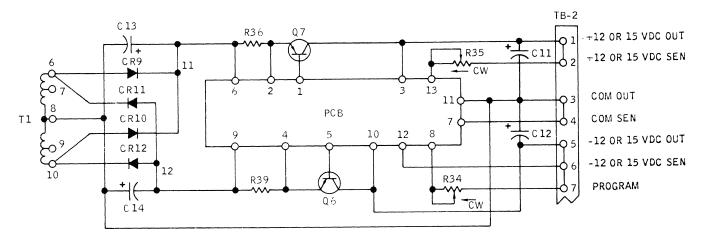
PTM Dual models should periodically be removed from service and cleaned of any accumulations of dust or other debris which could impede natural air-flow through the unit.

5.3 CALIBRATION

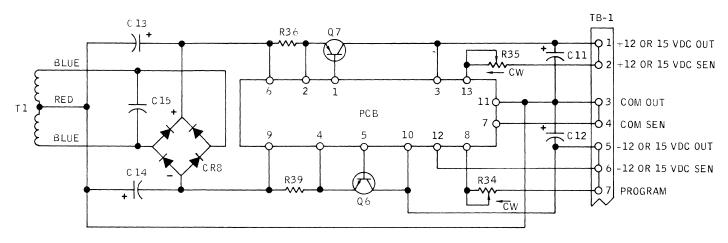
Calibration entails the checking and, if necessary, the adjustment of the foldback and OVP circuits. For foldback adjustments, use the procedure described in section 3, paragraph 3.3.2.* The overvoltage set adjustment procedure is outlined in section 3, paragraph 3.3.3/4. The factory-set limits for these adjustments are listed in table 1-1.

5.4 TROUBLESHOOTING

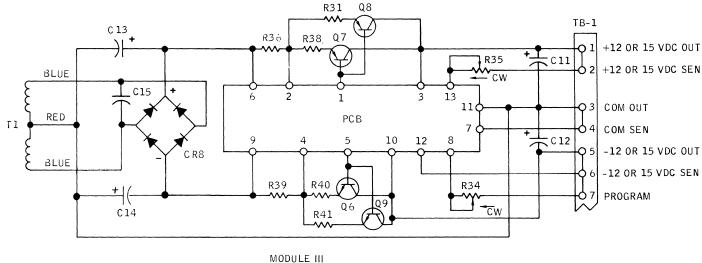
Table 5-1 lists a number of malfunction symptoms and probable causes. The table covers symptoms which are attributable to a single component failure only. This should not be interpreted to mean that there could not be other causes for the tabulated symptoms. Footnotes in the table indicate which components may be damaged due to a "chain-reaction" effect. If any amplifier components are replaced, unit may require recalibration. (Refer to paragraph 5.3.)







MODULE II 12-1.6D 15-1.5D



12-3D 15-2.8D

Figure 5-1. Partial Schematic Diagrams

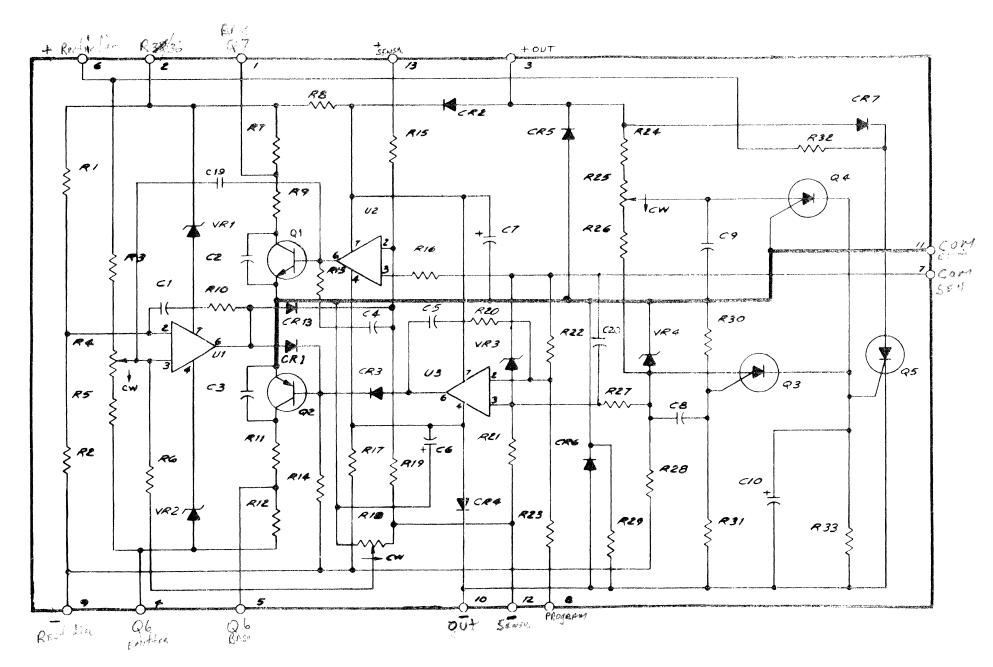


Figure 5-2. Typical P. C. Board Ass'y

5-3 -3

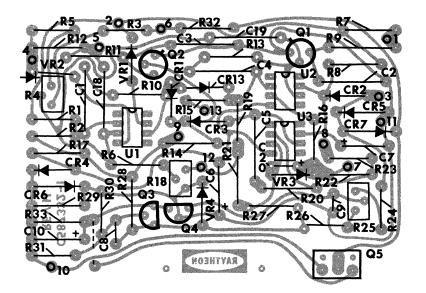


Figure 5-2B Typical PC Card Assembly (Module II Shown)

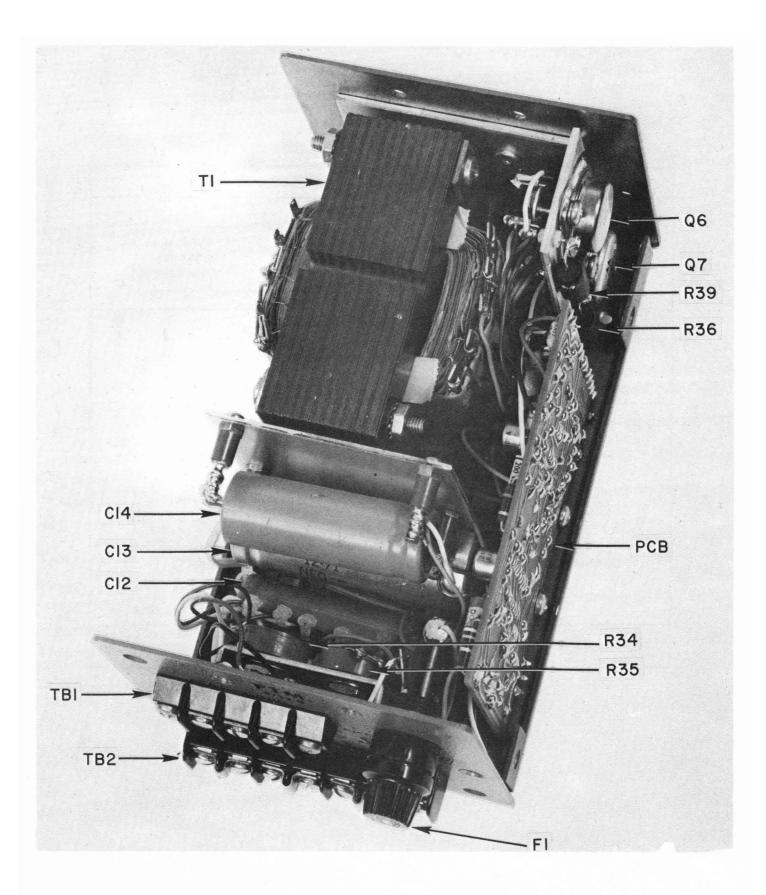


Figure 5-3 Typical Chassis Component Layout

SYMPTOM		PROBABLE CAUSE
No Output (Positive Side):	a.	Fuse Fl open.
	b.	Transistor Q1, Q2, Q6, Q7, Q8* or Q9* open.
	с.	U3, U2 or U1 defective.
No Output (Negative Side):	a.	Fuse Fl open.
	b.	Transistor Q2, Q6 or Q9* open.
	с.	U3 or U1 defective.
High Output (Positive Side):	a.	Transistors Q1, Q7, Q8* or Q9* shorted.
	b.	U2 defective.
	с.	Potentiometer R35 defective.
	d.	Sense links (1-2 or 3-4) open.
High Output (Negative Side):	a.	Transistors Q2, Q6 or Q9* shorted.
	b.	U3 defective.
*Q8/Q9 used only in Module II	ΙΙ.	

TABLE 5-1 TROUBLESHOOTING DATA

SYMPTOM	PROBABLE CAUSE
High Output (Negative Side): (cont'd)	c. Potentiometer R34 open.
	d. Sense links (3-4 or 5-6-7) open.
Low Output (Positive Side):	a. Overload (external) causing foldback limiting.
	b. OV tripped.
	c. Defective U3, U2 or U1.
	d. Potentiometers R4 or R18 need to be readjusted.
Foldback Circuit Inoperative:	a. CR1 open.
-	b. Defective Ul.
	c. Shorted Q1, Q2, Q6, Q7, Q8* or Q9* shorted.
Overvoltage Circuit	a. Shorted Q3, Q4 or Q5.
Inoperative:	b. Shorted VR4.
* Q8/Q9 used only in Module II	II.

TABLE 5-1 TROUBLESHOOTING DATA (cont'd)

SYMPTOM		PROBABLE CAUSE
Fl (AC) Fuse Blows:	a.	Foldback inoperative.
	b.	Diode(s) shorted*.
	c.	Cl3 or Cl4 shorted.
Ripple Specifications Degen-	a.	Open diode(s)*.
erate Positive or Negative:	b.	IC regulator U2 or U3 defective.
	c.	Foldback set too low.
Regulation Specifications Degenerate:	a.	IC regulator U2 or U3 defective.
	b.	Foldback set too low.
* <u>Diode</u> <u>Used on Modules</u> :		
CR8 - II, III CR9 - I CR10 - I CR11 - I CR12 - I		

TABLE 5-1 TROUBLESHOOTING DATA (cont'd)

5.5 PERFORMANCE TESTING

5.5.1 Output-Ripple

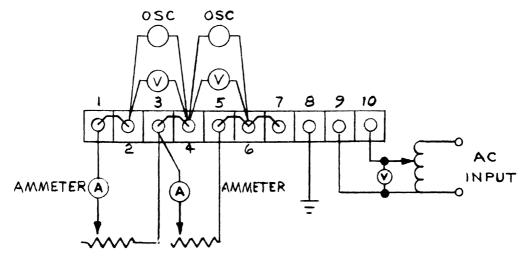
To measure output ripple, proceed as follows:

- Connect a test set-up per figure 5-4. Set oscilloscope for 1 mV/cm vertical sensitivity and 10 ms/cm horizontal. The oscilloscope should have at least a 10-MHz bandwidth. Select a 0-150 Vac meter. Choose a 1-mv range for the rms voltmeter. Select a range for the dc ammeter compatible with the unit output rated current. Use a resistive load capable of fully loading the unit to rated maximum current.
- 2. At no load, apply an input of 115 Vac @ 60 Hz. Adjust output for nominal voltage (per table 1-1).
- 3. Apply load and observe oscilloscope and rms meter. Voltmeter should not exceed 1 mV and oscilloscope display should not exceed 5 mV peak-to-peak.

5.5.2 Regulation

To measure the output voltage dc regulation, proceed as follows:

- 1. Connect unit to test set-up per figure 5-4.
- 2. Check the ripple per preceding paragraph 5.5.1.
- 3. Use a sensitive differential dc voltmeter or dvm capable of indicating the output voltage to within 1 mV. (For example, read 12.004 volts on a 12 V unit.)
- 4, Apply 125 Vac, 60-Hz input at no load. Observe dc-voltmeter indication.
- 5. Increase load to full rated load with 105 Vac input. The dc-voltmeter indication should not change more than the value listed in table 1-1 under "Unit Specifications".



MODULES II AND III

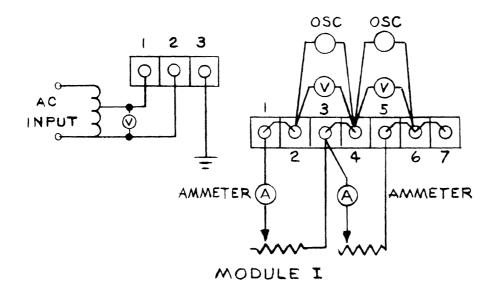


Figure 5-4 Test Equipment Setup

6. REPLACEABLE PARTS LIST

6.1 INTRODUCTION

This section provides a coded replaceable parts list, keyed to both the schematic diagram and parts location diagram appearing in section 5. All models are covered in the parts list.

6.2 **APPLICATION**

The parts list includes the replaceable parts for the following models:

Model	Final Assemblies
MODULE I	
12-1D 158D	587596-1 587596-2
MODULE II	
12-1.6D 15-1.5D	586874-1 586874-2
MODULE III	
12-3D 15-2.8D	586991-1 586991-2

6.3 TABLE HEADINGS DEFINED

6.3.1 Circuit Symbol

This number will identify the part as called out on the schematic diagram.

6.3.2 Sorensen Part No.

This number should be used when ordering parts directly from

Sorensen Company Replacement Parts Dept. 676 Island Pond Road Manchester, N. H. 03103

6.3.3 Mfr., Type

This is the basic group or series under which the part is listed by a manufacturer. The coded identification of representative manufacturers are summarized below, listed alphabetically.

Mfr. Code	Manufacturer	Mfr. Code	Manufacturer
АВ	Allen Bradley Co.	МА	Motorola
AM	Ammons Instrument Co.	MAL	P.'R. Mallory Co.
AX	Acushnet Capacitor Co.	NS	National Semiconductor
BNS	Bourns, Incorporated	RAM	RAM Electronics
BUS	Bussman Mfg./Div. McGraw-Edison	RCA	RCA Corporation
CD	Cornell-Dublier Corp.	RCL	RCL Electronics
CG	Corning Glass Works	RDM	Radio Material Co./Div. P.R. Mallory
CL	Clarostat Corp.	SAN	Sangamo Electric
CTS	CTS Corporation	SE	Seacor, Incorporated
ELA	Electra/Midland	SEM	Semtech Corporation
EMC	Electromotive Manufacturing Co.	SP	Sprague Electric
GE	General Electric Co.	SR	Sorensen Company
GI	General Illuminating Co.	ST	Solitron Devices
IND	Industrial Devices	STM	STM Corporation
IRC	International Resistance Co.	TEL	Tel-Labs
KEM	Kemet Division Union Carbide Corp.	TI	Texas Instruments
КС	Keystone Carbon	UC	Union Carbide
LF	Littelfuse Corporation	WH	Westinghouse Semiconductor Division
		WL	Ward Leonard

REPLACEABLE PARTS LIST

		PTM	1 DU	IAL	MOD	EL				 			
CIRCUIT SYMBOL							\$ /			 7	DESCRIPTION Capacitors (uF unless noted)	SORENSEN PART NUMBER	MANUFACTURER, TYPE
C1 C2	X X	X		X	Х		X	Х			.0068, 200V .001, 200V	24-2409-6 24-2409-1	AX, V146XR AX, V146XR
C3 C4 C5 C6 C7 C8 C9	X X X X X X X X	X X X X X X X X		X X X X X X X X X X	X X X X X X X X X		X X X X X X X X X X	X X X X X X X X X X X X			.0068, 200V .001, 200V .0068, 200V .0068, 200V .0068, 200V 2.2, 20V 2.2, 20V 820pF, 300V 820pF, 300V	24-2409-6 24-2409-1 24-2409-6 24-2409-6 24-2409-6 586385-2 586385-2 235-7053P334 235-7053P334	AX, V146XR AX, V146XR AX, V146XR AX, V146XR AX, V146XR UC, T110 UC, T110 EMC, DM15 EMC, DM15
C10 C11 C12 C13	X X X X	X X X X		X X X	X X X		X X X	X X X			.47, 35V 1000, 25V 1000, 25V 1700, 25V 1200, 30V	586058-3 235-7353P84 235-7353P84 235-7353P84 235-7353P88 24-2449-2	KEM, T110A SP, 39D SP, 39D SP, 39D SP, 39D SP, 34D
				X	x		x	x			8500, 25V 4600, 40V 19500, 25V 10600, 40V	586043-1 586044-1 586043-2 586044-2	STM, 91S STM, 91S STM, 91S STM, 91S
C14	х	x									1700, 25V 1200, 30V	235-7353P88 24-2449-2	SP, 39D SP, 34D
C15 C16-18 C19 C20	X X X	X X X		X X X X X X	X X X X X X		X X X X X X	X X X X X X	,		8500, 25V 4600, 40V 19500, 25V 10600, 24V .33, 200V Not Used .0068, 200V 68, 15V	586043-1 586044-1 586043-2 586044-2 24-2409-16 24-2409-6 235-7395P43	STM. 91S STM, 91S STM, 91S STM, 91S AX, V146XR AX, V146XR UC

		РТМ	I DU	AL	MOD				 		1	1
CIRCUIT SYMBOL		J.		\$/ _^	<u>}</u>	Ż	43)			DESCRIPTION	SORENSEN PART NUMBER	MANUFACTURER, TYPE
										Diodes		
CR1 CR2 CR3 CR4 CR5 CR6 CR7 CR8 CR9	X X X X X X X X X	X X X X X X X X X X		X	X X X X X X X X X X		X X X X X X X X X X X	X X X X X X X X X X X		200 PIV 200 PIV 200 PIV 200 PIV 1N5401 1N5401 1N5401 Bridge 100 PIV	587565-2 587565-2 587565-2 587565-2 587566-1 587566-1 587566-1 586050-1 586050-1 587565-1	SEM, S12 SEM, S12 SEM, S12 SEM, S12 SEM, 3S11 SEM, 3S11 SEM, 3S11 SEM, SCBE1 SEM, S11
CR10	х	Х								100 PIV	587565-1	SEM, S11
CR11 CR12 CR13	X X X	X X X		х	х		х	х		100 PIV 100 PIV 200 PIV	587565-1 587565-1 587565-2	SEM, S11 SEM, S11 SEM, S12
										Fuses		
F1*	Х	Х								1 Amp, 250V	226-7176P39	BUS, AGC-1
				х	х		Х	Х		2 Amp, 250V 1.5A, 250V Transistors	226-7176P43 226-7176P41	BUS, AGC-1 BUS, AGC-1
Q1	Х	х		v			.,			2N2222A	386-7249P57	GE
Q2	х	х		X	X			X		2N2219A 2N2907A	386-7249P32 386-7249P58	GE GE
	X X X	X X X		X X X	X X X		X X	X X X		2N2905 2N6027 2N6027 2N4441, Mod	386-7249P28 386-7304P1 386-7304P1 587760-1	GE GE GE SR
Q6 Q7 Q8 Q9	X X	X X		X X X	X X X		X X	X X X X X		2N4441 2N3055 2N6246 2N6246 2N3055	586820-1 18-151 586862-3 586862-3 18-151	MA RCA RCA RCA RCA

*Ref. page 2-3 for 220V (M1 option) or 230V
(M2 option) inputs.

		ртм	DU/	AL I	10D	EL			i				
CIRCUIT SYMBOL		Ja V K						N.		$\left[\right]$	DESCRIPTION	SORENSEN PART NUMBER	MANUFACTURER, TYPE
											Resistors (ohms, ±10%, 1/8W unless noted)		
R1	Х	Х		Х	Х		Х	х			15.4K, 1%	586250-131	ELA, MF4
R2 R3	X X	X X		X X	X X		X X	X X			15.4K, 1% 15.4K, 1%	586250-131 586250-131	ELA, MF4 ELA, MF4
R4 R5 R6	X X X	X X X		X X X	X X X		X X X	X X X			500 , 1/2W, Pot 15.4K, 1% 330K, 1/2W	167877-3 586250-131 280-1145P164	B NS, 3389H ELA, MF4 AB, EB
R7 R8	X X	X X		X X	X X		X X	X X			390, 1/2W, 5% 470, 1/2W, 5% 2200, 1/2W	280-1145P58 280-1145P61 280-1145P86	AB, EB AB, EB AB, EB
R9	x	х									240, 3W, 5%	27-397-82	WL, 3X
				Х	х			х			150, 3W, 5%	27-397-77	WL, 3X
R10 R11	x	X X		x	х		X X	х			110, 3W, 5% 270, 1/2W 150, 1/2W 820, 3W, 5%	27-397-74 280-1145P53 280-1145P44 27-397-95	WL, 3X AB, EB AB, EB WL, 3X
	Х			x	х		x	Х			240, 3W, 5% 390, 3W, 5%	27-397-82 27-397-87	WL, 3X WL, 3X
R12	Х	Х		Х	Х		x	x			180, 3W, 5% 390, 1/2W, 5%	27-397-79 280-1145P58 280-1145P61	WL, 3X AB, EB
R13	Х	Х		Х	х		X	X			470, 1/2W, 5% 1200, 1/2W, 5%	280-1145P76	AB, EB AB, EB
R14 R15	X X	X X		X X	Х		X X	Х			6200, 1/2W, 5% 5110, 1% 6490, 1%	280-1145P102 586055-108 586055-113	AB, EB ELA, MF4* ELA, MF4*
R16	х	х		х	X X		х	X X			6490, 1% 3650, 1%	586055-113 586250-101	ELA, MF4* ELA, MF4
								<u> </u>		1	coofficient	<u> </u>	I

*Order with ± 25 PPM (T9 or E) temperature coefficient

CIRCUIT		PTM		AL I	-		~ ~	7	\&/ /	DESCRIPTION	SORENSEN PART NUMBER	MANUFACTURER, TYPE
SYMBOL			5/	ß	Ż	2	Ĺ	ŶĮŚ/	<u> ///</u>	DESCRIPTION	PART NUMBER	
										Resistors (ohms, ±10%, 1/8W unless noted-cont'd)		
R17	Х	х		х	Х		Х	х		2200, 1/2W	280-1145P86	AB, EB
R18 R19 R20	X X X	X X X		X X X	X X X		X X X	X X X		10K, 1/2W, Pot 6190, 1% 7500, 1% 1200, 1/2W, 5%	586370-7 586055-112 586055-116 280-1145P76	BNS, 3389H ELA, MF4* ELA, MF4* AB, EB
R21 R22	X X	x x		X X	X X		X X X	X X		825, 1% 1150, 1% 3010, 1%	586250-70 586250-77 586055-97	ELA, MF4 ELA, MF4 ELA, MF4* ELA, MF4*
R23 R24 R25 R26	X X X X	X X X X X		X X X X	X X X X		X X X	X X X X		2050, 1% 3480, 1% 2150, 1% 1000, 1/2W, Pot 825, 1%	586055-89 586250-100 586250-90 586370-4 586250-70	ELA, MF4 ELA, MF4 ELA, MF4 BNS, 3389H ELA, MF4*
R27 R28 R29 R30	X X X X	X X X X		X X X X	X X X X		X X X X	X X X X		39K, 1/2W 1000, 1/2W 1000, 1/2W 20.5K, 1% 13K, 1%	280-1145P131 280-1145P74 280-1145P74 586250-137 586055-189	AB, EB AB, EB AB, EB ELA, MF4 ELA, MF4*
R31 R32	X X	X X		X X	Х		X X	X X		21.5K, 1% 1000, 1/2W	586250-138 280-1145P74 280-1145P65	ELA, MF4 AB, EB AB, EB
R33 R34 R35	X X X	X X X		X X X	X X X		X X X	X X X		390, 1/2W, 5% 2500, 2W, Pot 2500, 2W, Pot	585348-12 585348-12	BNS, 3859A BNS, 3859A
R36	х	Х		х	Х					.15, 5W	586054-3	RCL, T5
R37							x x	X X		.05, 5W .33, 5W, 5%	586054-68 586054-7	RCL, T5 RCL, T5
R38							х	Х		.33, 5W, 5%	586054-7	RCL, T5

*Order with ± 25 PPM (T9 or E) temperature coefficient

· · ·

			 	MO	DEL		,				CODENCEN	MANUEACTURED
CIRCUIT SYMBOL		X X X			\$] }]				1	DESCRIPTION	SORENSEN PART NUMBER	MANUFACTURER, TYPE
								·	I	Resistors (ohms)		
R39	Х	Х	х	Х						.15, 5W, 5%	586054-3	RCL, T5
						х	x			.05, 5W, 5%	586054-68	RCL, T5
R40						х	х			.33, 5W, 5%	586054-7	RCL, T5
R41						Х	Х			.33, 5W, 5%	586054-7	RCL, T5
										Transformers		
T1	х	х								Ass'y	587585-1 587585-2	SR SR
			х	х							586808-1 586808-2	SR SR
						Х	x				586999-1 586999-2	SR SR
TB1 TB2	x x	X X	x	Х		x	х		1	3-Terminal Board 10-Terminal Board 7-Terminal Board	247-7201P3 587423-10 587423-7	Kulka Kulka, 1599 Kulka, 1599
	~	'n								Integrated Circuits		
U1 U2 U3	X X X	X X X	X X X	X X X		X X X	X X X			ICLM741CN ICLM741CN ICLM741CN	586372-3 586372-3 586372-3	NS NS NS
												,

		PT	MD	UAL	MO	DEL			 		1	1
CIRCUIT SYMBOL							~?~/	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		DESCRIPTION	SORENSEN PART NUMBER	MANUFACTURER, TYPE
		Γ	\int	Γ	[Voltage Regulator		
VR1 VR2 VR3 VR4	X X X X	X X X X		X X X X	X X X X		X X X X	X X X X		1N5235 1N5242 1N5235 1N5242 1N825 1N5235	588101-10 588101-15 588101-10 588101-15 588105-3 588101-10	MA MA MA Transitron MA
										Miscellaneous		
	х	x								Printed-circuit Boards	587586-1 587586-2	SR SR
				х	х						587373 - 1 587373-2	SR SR
							х	x			587333-1 587333-2	SR SR
	х	x								Schematic Diagrams	D587593 D587594	SR SR
				х	х						D586823 D586824	SR SR
							х	x			D587593 D587594	SR SR
						2						

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1

SERVICE NOTES

FIELD SERVICE REPRESENTATIVES

UNITED STATES

ALABAMA

B & C Instruments, Inc. 7920 Unit 5, Charlotte Drive Huntsville, Alabama 35802 Tel: (205)883-6530

ARIZONA

Arizona Electronic Standards Lab. 1848 West Campbell Phoenix, Arizona 85015 Tel: (602)264-9351

Arizona Electronic Standards Lab. 1842 W. Grant Road - Suite 101 Tucson, Arizona 85703 Tel: (602)623-5779

CALIFORNIA

J.D. & Associates 1012 Morse Avenue Suite #6 Sunnyvale, California 94086 Tel: (408)734-5529

Power Specialist Company 10601 Bloomfield Street Los Alamitos, California 90720 Tel: (213)594-9418

COLORADO

R & R Instruments, Inc. 1554 Elmira St. Aurora, Colorado 80010 Tel: (303)364-8325

MARYLAND

Applied Metrology Inc. 10067 N. 2nd Street Laurel, Maryland 20810 Tel: (301)953-1010

MICHIGAN

Comtel Standards Laboratory 21223 Hilltop Street P. O. Box 5034 Southfield, Michigan 48037 Tel: (313)358-2500

MINNESOTA

Chris-Tec, Inc. 5366 Kimberly Road P. O. Box 1010 Minnetonka, Minnesota 55343 Tel: (612)934-1334

NEW HAMPSHIRE

Sorensen Company 676 Island Pond Road Manchester, N. H. 03103 Tel: (603)668-4500

NEW JERSEY

Ampower Electronic Instrument Co., Inc. 26 Just Road Fairfield, New Jersey 07006 Tel: (201)227-7720

UNITED STATES

NEW MEXICO Instrument Service Laboratories 630 Haines Avenue N.W. Albuquerque, New Mexico 87102 Tel: (505)842-1107

<u>OHIO</u>

Comtel Instrument Company 5387 Avion Park Drive Cleveland, Ohio 44143 Tel: (216)442-8080

TEXAS

Certified Test Equipment Sales, Inc. 601 Easy Street Garland, Texas 75042 Tel: (214)494-3446

WASHINGTON

XTEK Corporation 14824 Northeast 31st Circle Redmond, Washington 98052 Tel: (206)885-6969

WORLDWIDE

CANADA

Brunelle Instrument Company 826 Belvedere Street Sherbrooke, P.Q., Canada J1H4B8 Tel: (819)569-1408

ENGLAND

Cossor Electronics Ltd. The Pinnacles, Harlow Essex CM19 5BB, England Tel: (0279)26862

ISRAEL

Agentex Ltd. ATIDIM Scientific Industries Park End of Dvora Hanevia Road P. O. Box 10150 Tel Aviv 61101 Israel Tel: 03-493111

ITALY

3G Electronics S.r.1. Via Perugino 9 20135 Milano, Italy Tel: 39-2-54-42-91

JAPAN

Kansai Electronics Co, Tokyo Office 24-17 Sendagaya 4-Chome, Shibu Yaku, Tokyo Tel: 03-404-2585 Telex 2423371

WEST GERMANY/AUSTRIA

Neumuller GmbH Eschenstrasse 2 8028 Taufkirchen/Muenchen W. Germany Tel: 089/61181

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