

PHILIPS

Power diodes

S2a 1987

PHILIPS

Data handbook



Electronic
components
and materials

Semiconductors

Book S2a

1987

Rectifier diodes

Regulator diodes

Breakover diodes

High - voltage rectifier stacks

Accessories

POWER DIODES

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DATA HANDBOOK SYSTEM

Our Data Handbook System comprises more than 60 books with specifications on electronic components, subassemblies and materials. It is made up of four series of handbooks:

ELECTRON TUBES	BLUE
SEMICONDUCTORS	RED
INTEGRATED CIRCUITS	PURPLE
COMPONENTS AND MATERIALS	GREEN

The contents of each series are listed on pages iv to vii.

The data handbooks contain all pertinent data available at the time of publication, and each is revised and reissued periodically.

When ratings or specifications differ from those published in the preceding edition they are indicated with arrows in the page margin. Where application information is given it is advisory and does not form part of the product specification.

Condensed data on the preferred products of Philips Electronic Components and Materials Division is given in our Preferred Type Range catalogue (issued annually).

Information on current Data Handbooks and on how to obtain a subscription for future issues is available from any of the Organizations listed on the back cover.

Product specialists are at your service and enquiries will be answered promptly.

ELECTRON TUBES (BLUE SERIES)

The blue series of data handbooks comprises:

- T1** **Tubes for r.f. heating**
- T2a** **Transmitting tubes for communications, glass types**
- T2b** **Transmitting tubes for communications, ceramic types**
- T3** **Klystrons**
- T4** **Magnetrons for microwave heating**
- T5** **Cathode-ray tubes**
Instrument tubes, monitor and display tubes, C.R. tubes for special applications
- T6** **Geiger-Müller tubes**
- T8** **Colour display systems**
Colour TV picture tubes, colour data graphic display tube assemblies, deflection units
- T9** **Photo and electron multipliers**
- T10** **Plumbicon camera tubes and accessories**
- T11** **Microwave semiconductors and components**
- T12** **Vidicon and Newvicon camera tubes**
- T13** **Image intensifiers and infrared detectors**
- T15** **Dry reed switches**
- T16** **Monochrome tubes and deflection units**
Black and white TV picture tubes, monochrome data graphic display tubes, deflection units

SEMICONDUCTORS (RED SERIES)

The red series of data handbooks comprises:

- S1 Diodes**
Small-signal silicon diodes, voltage regulator diodes (< 1,5 W), voltage reference diodes, tuner diodes, rectifier diodes
- S2a Power diodes**
- S2b Thyristors and triacs**
- S3 Small-signal transistors**
- S4a Low-frequency power transistors and hybrid modules**
- S4b High-voltage and switching power transistors**
- S5 Field-effect transistors**
- S6 R.F. power transistors and modules**
- S7 Surface mounted semiconductors**
- S8a Light-emitting diodes**
- S8b Devices for optoelectronics**
Optocouplers, photosensitive diodes and transistors, infrared light-emitting diodes and infrared sensitive devices, laser and fibre-optic components
- S9 Power MOS transistors**
- S10 Wideband transistors and wideband hybrid IC modules**
- S11 Microwave transistors**
- S12 Surface acoustic wave devices**
- S13 Semiconductor sensors**
- *S14 Liquid Crystal Displays**

*To be issued shortly.

INTEGRATED CIRCUITS (PURPLE SERIES)

The NEW SERIES of handbooks is now completed. With effect from the publication date of this handbook the "N" in the handbook code number will be deleted. Handbooks to be replaced during 1986 are shown below.

The purple series of handbooks comprises:

IC01	Radio, audio and associated systems Bipolar, MOS	new issue 1986 IC01N 1985
IC02a/b	Video and associated systems Bipolar, MOS	new issue 1986 IC02Na/b 1985
IC03	Integrated circuits for telephony Bipolar, MOS	new issue 1987 IC03N 1985
IC04	HE4000B logic family CMOS	new issue 1986 IC4 1983
IC05N	HE4000B logic family – uncased ICs CMOS	published 1984
IC06N	High-speed CMOS; PC74HC/HCT/HCU Logic family	published 1986
IC08	ECL 10K and 100K logic families	New issue 1986 IC08N 1984
IC09N	TTL logic series	published 1986
IC10	Memories MOS, TTL, ECL	new issue 1986 IC7 1982
IC11N	Linear LSI	published 1985
Supplement to IC11N	Linear LSI	published 1986
IC12	I²C-bus compatible ICs	not yet issued
IC13	Semi-custom Programmable Logic Devices (PLD)	new issue 1986 IC13N 1985
IC14	Microcontrollers and peripherals Bipolar, MOS	published 1986
IC15	FAST TTL logic series	new issue 1986 IC15N 1985
IC16	CMOS integrated circuits for clocks and watches	first issue 1986
IC17	Integrated Services Digital Networks (ISDN)	not yet issued
IC18	Microprocessors and peripherals	new issue 1986

COMPONENTS AND MATERIALS (GREEN SERIES)

The green series of data handbooks comprises:

- C2** Television tuners, coaxial aerial input assemblies, surface acoustic wave filters
- C3** Loudspeakers
- C4** Ferroxcube potcores, square cores and cross cores
- C5** Ferroxcube for power, audio/video and accelerators
- C6** Synchronous motors and gearboxes
- C7** Variable capacitors
- C8** Variable mains transformers
- C9** Piezoelectric quartz devices
- C11** Varistors, thermistors and sensors
- C12** Potentiometers, encoders and switches
- C13** Fixed resistors
- C14** Electrolytic and solid capacitors
- C15** Ceramic capacitors
- C16** Permanent magnet materials
- C17** Stepping motors and associated electronics
- C18** Direct current motors
- C19** Piezoelectric ceramics
- C20** Wire-wound components for TVs and monitors
- C22** Film capacitors

SELECTION GUIDE

SELECTION GUIDE

RECTIFIER DIODES

General purpose

$I_F(AV)_{max}$ (A)		Outline	V_{RRMmax} (V)				Page
			300	600	1200	1600	
6	BYX38	DO-4	•	•	•		55
6.5	BY249	TO-220AC	•	•			39
10	BYX98	DO-4	•	•	•		93
12	BYX42	DO-4	•	•	•		67
15	BYX99	DO-4	•	•	•		99
30	BYX96	DO-4	•	•	•	•	81
47	BYX97	DO-5	•	•	•	•	87
48	BYX52	DO-5	•	•	•		71

Avalanche

$I_F(AV)_{max}$ (A)		Outline	V_{RWMmax} (V)					Page
			600	800	1000	1200	1400	
9.5	BYX39	DO-4	•	•	•	•	•	61
20	BYX25	DO-4	•	•	•	•	•	45
48	BYX56	DO-5	•	•	•	•	•	75

FAST RECTIFIER DIODES

Ultra fast (epitaxial) types

IF(AV)max (A)	Outline	VRRMmax (V)										Page			
		50	100	150	200	300	400	500	600	700	800		1000		
1	BYV26	SOD-57				•			•			•		•	255
2	BYV27	SOD-57	•	•	•	•									261
3.5	BYV28	SOD-64	•	•	•	•									269
7	BYX50	DO-4				•	•								487
8	BYP21	TO-220AC	•	•	•	•									173
8	BYR29	TO-220AC									•	•	•		207
8	BYR29F	SOT-186									•	•	•		217
8	BYW29	TO-220AC	•	•	•	•									413
8	BYW29F	SOT-186	•	•	•	•									423
9	BYV29	TO-220AC					•	•	•						275
9	BYV29F	SOT-186					•	•	•						285
10	BYQ28*	TO-220AB	•	•	•	•									197
10	BYT28	TO-220AB					•	•	•						227
12	BYV32F*	SOT-186	•	•	•	•									321
14	BYT79	TO-220AC					•	•	•						237
14	BYV30	DO-4					•	•	•						295
14	BYV79	TO-220AC	•	•	•	•									389
14	BYW30	DO-4	•	•	•	•									433
20	BYP22*	TO-220AB	•	•	•	•									183
20	BYV32*	TO-220AB	•	•	•	•									311
20	BYV34*	TO-220AB					•	•	•						331
28	BYV31	DO-4					•	•	•						303
28	BYW31	DO-4	•	•	•	•									441
30	BYV42*	TO-220AB	•	•	•	•									341
30	BYV44*	TO-220AB					•	•	•						351
30	BYV72*	SOT-93	•	•	•	•									369
30	BYV74*	SOT-93					•	•	•						379
35	BYV92	DO-5					•	•	•						399
40	BYW92	DO-5	•	•	•	•									449
60	BYP59	DO-5					•	•							193
60	BYW93	DO-5	•	•	•	•									457

*Monolithic dual rectifier diodes.

SELECTION GUIDE

FAST RECTIFIER DIODES (Cont.)

$I_F(AV)_{max}$ (A)	Outline	V_{RRMmax} (V)						Page	
		50	100	200	300	400	500		600
Very-fast types									
6	1N3879	DO-4	•						495
6	1N3880	DO-4		•					495
6	1N3881	DO-4			•				495
6	1N3882	DO-4				•			495
6	1N3883	DO-4					•		495
12	1N3889	DO-4	•						501
12	1N3890	DO-4		•					501
12	1N3891	DO-4			•				501
12	1N3892	DO-4				•			501
12	1N3893	DO-4					•		501
14	BYX30**	DO-4			•	•	•	•	465
22	BYX46**	DO-4			•	•	•	•	475
30	1N3909	DO-5	•						507
30	1N3910	DO-5		•					507
30	1N3911	DO-5			•				507
30	1N3912	DO-5				•			507
30	1N3913	DO-5					•		507

	Outline	V_{RRMmax} (V)						Page		
		200	400	600	800	1000	1200		1300	1500
6.5	BY359	TO-220AC					•	•	•	165
7	BY229	TO-220AC	•	•	•	•				129
7	BY229F	SOT-186	•	•	•	•				141
8	BY329	TO-220AC				•	•	•		153
12	BYV24	DO-4				•	•			247
15	BYV60	TO-238				•	•	•		361
40	BYW25	DO-5				(850 V)	•	•		407

**With avalanche characteristics

SCHOTTKY RECTIFIER DIODES

$I_{F(AV)max}$ (A)	Outline	V_{RRMmax} (V)					Page	
		30	35	40	40A [▲]	45		
10	BYV18*	TO-220AB	•	•	•	•	•	517
10	BYV19	TO-220AC	•	•	•	•	•	527
15	BYV20	DO-4	•	•	•	•	•	535
16	BYV39	TO-220AC	•	•	•	•	•	587
20	BYV33*	TO-220AB	•	•	•	•	•	567
20	BYV33F*	SOT-186	•	•	•	•	•	577
26	BYV43F*	SOT-186	•	•	•	•	•	603
30	BYV21	DO-4	•	•	•	•	•	543
30	BYV43*	TO-220AB	•	•	•	•	•	595
30	BYV73*	SOT-93	•	•	•	•	•	611
60	BYV22	DO-5	•	•	•	•	•	551
60	PHSD51	DO-5	•	•	•	•	•	619
80	BYV23	DO-5	•	•	•	•	•	559

*Monolithic dual rectifier diodes

▲With guaranteed reverse surge capability

BREAKOVER DIODES

I_{TRMmax} (A)	Outline	$V_{(BO)nom}$ (V)								Page				
		65	100	120	140	160	180	200	220		240	260	280	
40	BR210	TO-220AC	•	•	•	•	•	•	•	•	•	•	•	627
40	BR216*†	TO-220AB	•	•	•	•	•	•	•	•	•	•	•	639
40	BR220*	TO-220AB	•	•	•	•	•	•	•	•	•	•	•	643

*Monolithic dual breakover diodes.

*†Asymmetrical breakover diode.

SELECTION GUIDE

REGULATOR DIODES

Regulated voltage	Suppression stand-off voltage	REGULATOR SERVICE P_{tot} max		
		20 W	100 W	—
		SUPPRESSOR SERVICE P_{RSM} max		
		700 W	9.5 kW	25 kW
4.7 V	3.6 V			
5.1 V	3.9 V			
5.6 V	4.3 V			
6.2 V	4.7 V			
6.8 V	5.1 V			
7.5 V	5.6 V			
8.2 V	6.2 V			
9.1 V	6.8 V			
10 V	7.5 V			
11 V	8.2 V			
12 V	9.1 V			
13 V	10 V			
15 V	11 V			
16 V	12 V			
18 V	13 V			
20 V	15 V			
22 V	16 V			
24 V	18 V			
27 V	20 V			
30 V	22 V			
33 V	24 V			
36 V	27 V			
39 V	30 V			
43 V	33 V			
47 V	36 V			
51 V	39 V			
56 V	43 V			
62 V	47 V			
68 V	51 V			
75 V	56 V			
82 V	62 V			
Outline		DO-4	DO-5	DO-30
Polarity		both	both	both

Type No. BZY93 (page 713)

Type No. BZY91 (page 693)

Type No. BZW86 (page 659)

Normal polarity (cathode to stud)

no end-letter

Reverse polarity (anode to stud)

R

Both polarities available

(R)

HIGH-VOLTAGE RECTIFIER STACKS

Type No.	I _{F(AV)} max.	V _{RWM} max.	Page	Configuration
OSS9115-3 to -36	3.5 A (6 A in oil)	4.5 kV to 54 kV	733	
OSS9215-3 to -36	5 A (20 A in oil)		743	
OSS9415-3 to -36	10 A (30 A in oil)		753	
OSB9115-4 to -36	7 A (12 A in oil)	3 kV to 27 kV	733	
OSB9215-4 to -36	10 A (40 A in oil)		743	
OSB9415-4 to -36	20 A (60 A in oil)		753	
OSM9115-4 to -36	3.5 A (6 A in oil)	3 kV to 27 kV	733	
OSM9215-4 to -36	5 A (20 A in oil)		743	
OSM9415-4 to -36	10 A (30 A in oil)		753	
OSM9510-12	1.5 A	6 kV	761	

GENERAL SECTION

**Type Designation
Rating Systems
Letter Symbols
Quality Conformance
and Reliability
General Explanatory Notes
Heatsinks**

PRO ELECTRON TYPE DESIGNATION CODE FOR SEMICONDUCTOR DEVICES

This type designation code applies to discrete semiconductor devices — as opposed to integrated circuits —, multiples of such devices and semiconductor chips.

“Although not all type numbers accord with the Pro Electron system, the following explanation is given for the ones that do.”

A basic type number consists of:

TWO LETTERS FOLLOWED BY A SERIAL NUMBER

FIRST LETTER

The first letter gives information about the material used for the active part of the devices.

- A. GERMANIUM or other material with band gap of 0,6 to 1,0 eV.
- B. SILICON or other material with band gap of 1,0 to 1,3 eV.
- C. GALLIUM-ARSENIDE or other material with band gap of 1,3 eV or more.
- R. COMPOUND MATERIALS (e.g. Cadmium-Sulphide).

SECOND LETTER

The second letter indicates the function for which the device is primarily designed.

- A. DIODE; signal, low power
- B. DIODE; variable capacitance
- C. TRANSISTOR; low power, audio frequency ($R_{th j-mb} > 15 K/W$)
- D. TRANSISTOR; power, audio frequency ($R_{th j-mb} \leq 15 K/W$)
- E. DIODE; tunnel
- F. TRANSISTOR; low power, high frequency ($R_{th j-mb} > 15 K/W$)
- G. MULTIPLE OF DISSIMILAR DEVICES – MISCELLANEOUS; e.g. oscillator
- H. DIODE; magnetic sensitive
- L. TRANSISTOR; power, high frequency ($R_{th j-mb} \leq 15 K/W$)
- N. PHOTO-COUPLER
- P. RADIATION DETECTOR; e.g. high sensitivity phototransistor
- Q. RADIATION GENERATOR; e.g. light-emitting diode (LED)
- R. CONTROL AND SWITCHING DEVICE; e.g. thyristor, low power ($R_{th j-mb} > 15 K/W$)
- S. TRANSISTOR; low power, switching ($R_{th j-mb} > 15 K/W$)
- T. CONTROL AND SWITCHING DEVICE; e.g. thyristor, power ($R_{th j-mb} \leq 15 K/W$)
- U. TRANSISTOR; power, switching ($R_{th j-mb} \leq 15 K/W$)
- X. DIODE; multiplier, e.g. varactor, step recovery
- Y. DIODE; rectifying, booster
- Z. DIODE; voltage reference or regulator (transient suppressor diode, with third letter W)

TYPE DESIGNATION

The remainder of the type number is a **serial number** indicating a particular design or development and is in one of the following two groups:

- (a) A **serial number** consisting of three figures from 100 to 999.
- (b) A **serial number** consisting of one letter (Z, Y, X, W, etc.) followed by two figures.

RANGE NUMBERS

Where there is a range of variants of a basic type of rectifier diode, thyristor or voltage regulator diode the type number as defined above is often used to identify the range; further letters and figures are added after a hyphen to identify associated types within the range. These additions are as follows:

RECTIFIER DIODES, THYRISTORS AND TRIACS

A **group of figures** indicating the rated repetitive peak reverse voltage, V_{RRM} , or the rated repetitive peak off-state voltage, V_{DRM} , whichever value is lower, in volts for each type.

The **final letter R** is used to denote a reverse polarity version (stud-anode) where applicable. The normal polarity version (stud cathode) has no special final letter.

REGULATOR DIODES

A **first letter** indicating the nominal percentage tolerance in the operating voltage V_Z .

- A. 1% (according to IEC 63: series E96)
- B. 2% (according to IEC 63: series E48)
- C. 5% (according to IEC 63: series E24)
- D. 10% (according to IEC 63: series E12)
- E. 20% (according to IEC 63: series E6)

A **group of figures** indicating the typical operating voltage V_Z for each type at the nominal operating current I_Z rating of the range.

The **letter V** is used to denote a decimal sign.

The **final letter R** is used to denote a reverse polarity version (stud anode) where applicable. The normal polarity version (stud cathode) has no special final letter.

Examples:

- BYX38-600 Silicon rectifier in the BYX38 range with 600 V maximum repetitive peak voltage, normal polarity, stud connected to cathode.
- BZY91-C7V5 Silicon voltage regulator diode in the BZY91 range with 7.5 V operating $\pm 5\%$ tolerance, normal polarity, stud connected to cathode.

RATING SYSTEMS

The rating systems described are those recommended by the International Electrotechnical Commission (IEC) in its Publication 134.

DEFINITIONS OF TERMS USED

Electronic device. An electronic tube or valve, transistor or other semiconductor device.

Note

This definition excludes inductors, capacitors, resistors and similar components.

Characteristic. A characteristic is an inherent and measurable property of a device. Such a property may be electrical, mechanical, thermal, hydraulic, electro-magnetic, or nuclear, and can be expressed as a value for stated or recognized conditions. A characteristic may also be a set of related values, usually shown in graphical form.

Bogey electronic device. An electronic device whose characteristics have the published nominal values for the type. A bogey electronic device for any particular application can be obtained by considering only those characteristics which are directly related to the application.

Rating. A value which establishes either a limiting capability or a limiting condition for an electronic device. It is determined for specified values of environment and operation, and may be stated in any suitable terms.

Note

Limiting conditions may be either maxima or minima.

Rating system. The set of principles upon which ratings are established and which determine their interpretation.

Note

The rating system indicates the division of responsibility between the device manufacturer and the circuit designer, with the object of ensuring that the working conditions do not exceed the ratings.

ABSOLUTE MAXIMUM RATING SYSTEM (As used throughout this book)

Absolute maximum ratings are limiting values of operating and environmental conditions applicable to any electronic device of a specified type as defined by its published data, which should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking no responsibility for equipment variations, environmental variations, and the effects of changes in operating conditions due to variations in the characteristics of the device under consideration and of all other electronic devices in the equipment.

The equipment manufacturer should design so that, initially and throughout life, no absolute maximum value for the intended service is exceeded with any device under the worst probable operating conditions with respect to supply voltage variation, equipment component variation, equipment control adjustment, load variations, signal variation, environmental conditions, and variations in characteristics of the device under consideration and of all other electronic devices in the equipment.

DESIGN MAXIMUM RATING SYSTEM

Design maximum ratings are limiting values of operating and environmental conditions applicable to a bogey electronic device of a specified type as defined by its published data, and should not be exceeded under the worst probable conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device, taking responsibility for the effects of changes in operating conditions due to variations in the characteristics of the electronic device under consideration.

The equipment manufacturer should design so that, initially and throughout life, no design maximum value for the intended service is exceeded with a bogey device under the worst probable operating conditions with respect to supply voltage variation, equipment component variation, variation in characteristics of all other devices in the equipment, equipment control adjustment, load variation, signal variation and environmental conditions.

DESIGN CENTRE RATING SYSTEM

Design centre ratings are limiting values of operating and environmental conditions applicable to a bogey electronic device of a specified type as defined by its published data, and should not be exceeded under normal conditions.

These values are chosen by the device manufacturer to provide acceptable serviceability of the device in average applications, taking responsibility for normal changes in operating conditions due to rated supply voltage variation, equipment component variation, equipment control adjustment, load variation, signal variation, environmental conditions, and variations in the characteristics of all electronic devices.

The equipment manufacturer should design so that, initially, no design centre value for the intended service is exceeded with a bogey electronic device in equipment operating at the stated normal supply voltage.

LETTER SYMBOLS FOR RECTIFIER DIODES, THYRISTORS, TRIACS AND BREAKOVER DIODES

LETTER SYMBOLS FOR CURRENTS, VOLTAGES AND POWERS

Basic letters: – The basic letters to be used are:

I, i = current

V, v = voltage

P, p = power

Lower-case basic letters shall be used for the representation of instantaneous values which vary with time. In all other instances upper-case letters shall be used.

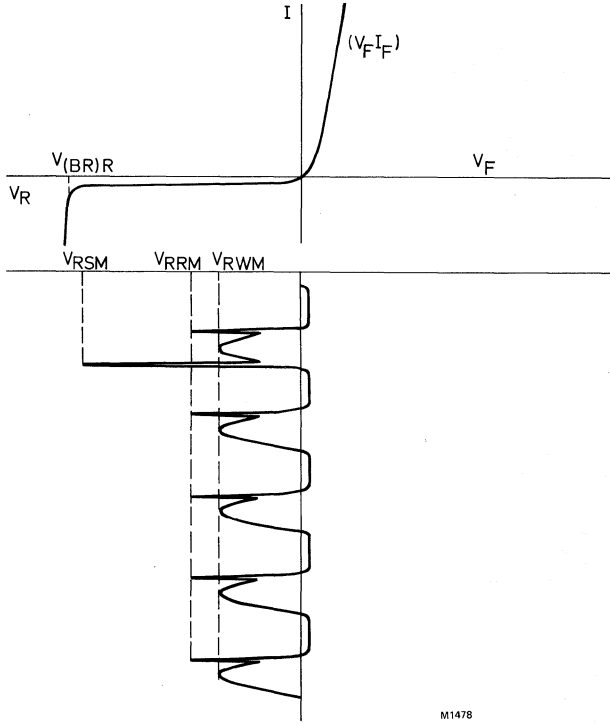
Subscripts

amb	Ambient
(AV), (av)	Average value
(BO)	Breakover
(BR)	Breakdown
case	Case
C	Controllable
D,d	Forward off-state ¹⁾ , non-triggered (gate voltage or current)
F,f	Forward ¹⁾ , fall
G,g	Gate terminal
H	Holding
I,i	Input
J,j	Junction
L	Latching
M,m	Peak or crest value
min	Minimum
O,o	Output, open circuit
(OV)	Overload
P,p	Pulse
Q,q	Turn-off
R,r	As first subscript: reverse, rise As second subscript: repetitive, recovery
(RMS), (rms)	R.M.S. value
S,s	As first subscript: storage, stray, series, source, switching As second subscript: non-repetitive
stg	Storage
T,t	Forward on-state ¹⁾ , triggered (gate voltage or current)
th	Thermal
(TO)	Threshold
tot	Total
W	Working
Z	Reference or regulator (i.e. zener)

For power rectifier diodes, thyristors and triacs, the terminals are **not** indicated in the subscript, except for the gate-terminal of thyristors and triacs.

¹⁾ For the anode-cathode voltage of thyristors and triacs, F is replaced either by D or T, to distinguish between 'off-state' (non-triggered) and 'on-state' (triggered).

Example of the use of letter symbols



M1478

Simplified rectifier characteristic together with an anode-cathode voltage as a function of time.

QUALITY CONFORMANCE AND RELIABILITY

In addition to 100% testing of all major device parameters in the production department, independently controlled statistical sampling for conformance and reliability takes place using BS6001 'Sampling Procedures and Tables'. BS6001 is consistent with MIL-STD-105D, DEF131A, ISO2859, CA-C-115.

The market demand for a continuously improving product quality is being met by the annual updating of formal quality improvement plans.

The 'Defect free' and 'Right first time' concepts are applied regularly as part of an overall quality programme covering all aspects of device quality from initial design to final production. These concepts, together with the quality assurance requirements, embrace all the principles outlined in DEF STAN 05-21, AQAP-1, and BS5750 Pt1.

CONFORMANCE

The Company actively promote a policy of customer cooperation to determine their quality problems and future requirements. This cooperation is often in the form of a 'ppm' activity. The 'ppm' is a measure of conformance of the outgoing product, and is expressed as the number of reject devices found per million of products delivered (e.g. a process average of 0.01% = 100 ppm). Mutually agreed ppm targets are set, and a programme of quality improvement work initiated.

In addition to the above, special inspection and/or test procedures are available, following consultation with the customer and the agreement of a special specification.

RELIABILITY

'Screening', or 'Burn-in' procedures are also available, based on the requirements of CECC 50 000.

CECC 50 000 offers a choice of four screening sequences: 'A', 'B', 'C', 'D'. The Company's standard 'Hi-rel' procedure offers a combination of 'C' and 'D' sequences.

Sequence 'C'

1. High temperature storage — 24 hours minimum.
2. Rapid change of temperature — as detailed in agreed specification.
3. Sealing — fine leak test.
— gross leak test.
4. Functional electrical characteristics — within group 'A' limits.

Sequence 'D'

1. 'Burn-in' — high-voltage reverse bias, 48 hours duration. Conditions as specified in CECC 50 000.
2. Post 'Burn-in' measurements — functional electrical characteristics, within group 'A' limits.

Other 'Hi-rel', 'Burn-in', or 'Screening' procedures may be available on request.

RECTIFIER DIODES

REVERSE RECOVERY

When a semiconductor rectifier diode has been conducting in the forward direction sufficiently long to establish the steady state, there will be a charge due to minority carriers present. Before the device can block in the reverse direction this charge must be extracted. This extraction takes the form of a transient reverse current and this, together with the reverse bias voltage results in additional power dissipation which reduces the rectification efficiency. At sine-wave frequencies up to about 400 Hz these effects can often be ignored, but at higher frequencies and for square waves the switching losses must be considered.

Stored charge

The area under the I_R -time curve is known as the stored charge (Q_s) and is normally quoted in micro- or nanocoulombs. Low stored charge devices are preferred for fast switching applications.

Reverse recovery time

Another parameter which can be used to determine the speed of the rectifier is the reverse recovery time (t_{rr}). This is measured from the instant the current passes through zero (from forward to reverse) to the instant the current recovers to 10% of its peak reverse value. Low reverse recovery times are associated with low stored charge devices.

The conditions which need to be specified are:

- Steady-state forward current (I_F); high currents increase recovery time.
- Reverse bias voltage (V_R); low reverse voltage increases recovery time.
- Rate of fall of anode current (dI_F/dt); high rates of fall reduce recovery time, but increase stored charge.
- Junction temperature (T_j); high temperatures increase both recovery time and stored charge.

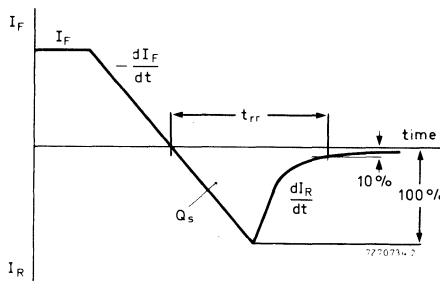


Fig. 1 Waveform showing the reverse recovery aspects.

REVERSE RECOVERY (continued)

Softness of recovery

In many switching circuits it is not just the magnitude but the shape of the reverse recovery characteristic that is important. If the positive-going edge of the characteristic has a fast rise time (as in a so-called 'snap-off' device) this edge may cause conducted or radiated r.f.i., or it may generate high voltages across inductors which may be in series with the rectifier. The maximum slope of the reverse recovery current (dI_R/dt) is quoted as a measure of the 'softness' of the characteristic. Low values are less liable to give r.f.i. problems. The measurement conditions which need to be specified are as above. When stored charges are very low, e.g. for epitaxial and Schottky-barrier rectifier diodes, this softness characteristic can be ignored.

DOUBLE-DIFFUSED RECTIFIER DIODES

A single-diffused diode with a two layer p-n structure cannot combine a high forward current density with a high reverse blocking voltage.

A way out of this dilemma is provided by the three layer double-diffused structure. A lightly doped silicon layer, called the base, is sandwiched between highly doped diffused p^+ and n^+ outer layers giving a $p^+ - pn^+$ or $p^+ - nn^+$ layer. Generally, the base gives the diode its high reverse voltage, and the two diffused regions give the high forward current rating.

Although double-diffused diodes are highly efficient, a slight compromise is still necessary. Generally, for a given silicon chip area, the thicker the base layer the higher the V_R and the lower the I_F . Reverse switching characteristics also determine the base design. Fast recovery diodes usually have n-type base regions to give 'soft' recovery. Other diodes have the base type, n or p, chosen to meet their specific requirements.

ULTRA FAST RECTIFIER DIODES

Ultra fast rectifier diodes, made by epitaxial technology, are intended for use in applications where low conduction and switching losses are of paramount importance and relatively low reverse blocking voltage ($V_{RWM} = 150 \text{ V}$) is required: e.g., switched-mode power supplies operating at frequencies of about 50 kHz.

The use of epitaxial technology means that there is very close control over the almost ideal diffusion profile and base width giving very high carrier injection efficiencies leading to lower conduction losses than conventional technology permits. The well defined diffusion profile also allows a tight control of stored minority carriers in the base region, so that very fast turn-off times (35 ns) can be achieved. The range of devices also has a soft reverse recovery and a low forward recovery voltage.

SCHOTTKY-BARRIER RECTIFIER DIODES

Schottky-barrier rectifiers find application in low-voltage switched-mode power supplies (e.g. 5 V output) where they give an increase in efficiency due to the very low forward drop, and low switching losses. Power Schottky diodes are made by a metal-semiconductor barrier process to minimise forward voltage losses, and being majority carrier devices have no stored charge. They are therefore capable of operating at extremely high speeds. Electrical performance in forward and reverse conduction is uniquely defined by the device's metal-semiconductor 'barrier height'. We have a process to minimise forward voltage, whilst maintaining reverse leakage current at full rated working voltage and $T_{j \text{ max}}$ at an acceptable level.

To obtain the maximum benefit from the use of Schottky devices it is recommended that particular attention be paid to the adequate suppression of voltage transients in practical circuit designs.

SWITCHING LOSSES (see also Fig.3)

The product of transient reverse current and reverse bias voltage is a power dissipation, most of which occurs during the fall time. In repetitive operation an average power can be calculated. This is then added to the forward dissipation to give the total power. The peak value of transient reverse current is known as I_{RRM} .

The conditions which need to be specified are:

- Forward current (I_F); high currents increase switching losses.
- Rate of fall of anode current (dI_F/dt); high rates of fall increase switching losses. This is particularly important in square-wave operation. Power losses in sine-wave operation for a given frequency are considerably less due to the much lower dI_F/dt .
- Frequency (f); high frequency means high losses.
- Reverse bias voltage (V_R); high reverse bias means high losses.
- Junction temperature (T_j); high temperature means high losses.

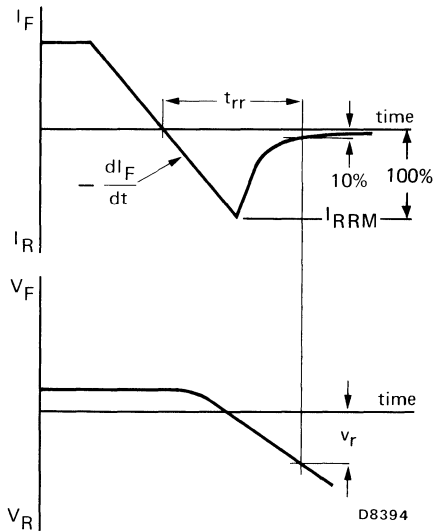


Fig.2 Waveforms showing the reverse switching losses aspects.

SWITCHING LOSSES (continued)

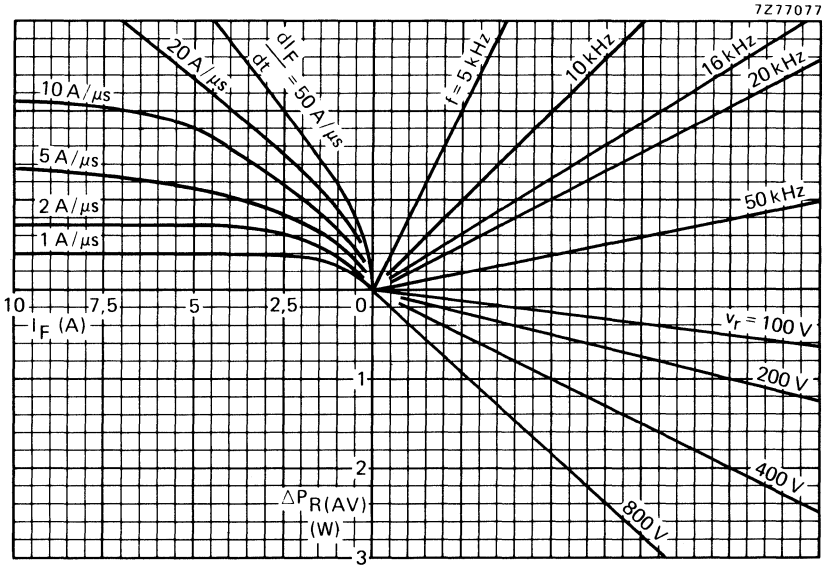


Fig. 3 Nomogram (example of reverse switching losses). Power loss ΔP_R (AV) due to switching only (to be added to steady-state power losses). I_F = forward current just before switching off; $T_j = 150 \text{ }^\circ\text{C}$.

FORWARD RECOVERY

At the instant a semiconductor rectifier diode is switched into forward conduction there are no carriers present at the junction, hence the forward voltage drop may be instantaneously of a high value. As the stored charge builds-up, conductivity modulation takes place and the forward voltage drop rapidly falls to the steady-state value. The peak value of forward voltage drop is known as the forward recovery voltage (V_{fr}). The time from the instant the current reaches 10% of its steady-state value to the time the forward voltage drop falls to within 10% of its final steady-state value is known as the forward recovery time (t_{fr}).

The conditions which need to be specified are:

- Forward current (I_F); high currents give high recovery voltages.
- Current pulse rise time (t_r); short rise times give high recovery voltages.
- Junction temperature (T_j); the influence of temperature is slight.

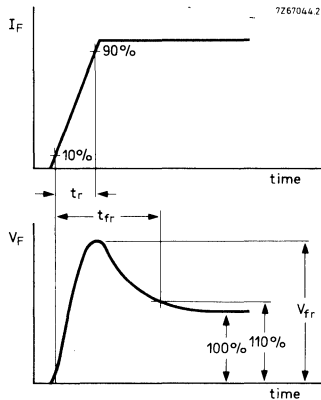


Fig. 4 Waveforms showing the forward recovery aspects.

OPERATING NOTES

When there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage ¹⁾, a damping circuit should be connected across the transformer.

Either a series RC circuit or a voltage dependent resistor may be used. Suitable component values for an RC circuit across the transformer primary or secondary may be calculated as follows:

$\frac{V_{RSM}}{V_{RWM}}$	RC across primary of transformer		RC across secondary of transformer	
	C (μF)	R (Ω)	C (μF)	R (Ω)
2.0	$200 \frac{I_{mag}}{V_1}$	$\frac{150}{C}$	$225 \frac{I_{mag} T^2}{V_1}$	$\frac{200}{C}$
1.5	$400 \frac{I_{mag}}{V_1}$	$\frac{225}{C}$	$450 \frac{I_{mag} T^2}{V_1}$	$\frac{275}{C}$
1.25	$550 \frac{I_{mag}}{V_1}$	$\frac{260}{C}$	$620 \frac{I_{mag} T^2}{V_1}$	$\frac{310}{C}$
1.0	$800 \frac{I_{mag}}{V_1}$	$\frac{300}{C}$	$900 \frac{I_{mag} T^2}{V_1}$	$\frac{350}{C}$

where I_{mag} = magnetising primary r.m.s. current (A)

V_1 = transformer primary r.m.s. voltage (V)

V_2 = transformer secondary r.m.s. voltage (V)

T = V_1/V_2

V_{RSM} = the transient voltage peak produced by the transformer

V_{RWM} = the actually applied crest working reverse voltage

The capacitance values calculated from the above table are minimum values; to allow for circuit variations and component tolerances, larger values should be used.

¹⁾ For controlled avalanche types read: non-repetitive peak reverse power.

BREAKOVER DIODES

GENERAL

Breakover diodes (BODs) are two-terminal devices that operate in either an off (non-conducting) state or an on (conducting) state. A BOD will remain in the off-state until the maximum breakover voltage is applied across its terminals. A BOD will then conduct with a low on-state voltage until the current is reduced below the minimum holding current.

BODs are available as single or dual symmetric (operation in 1st and 3rd quadrants) types in a TO-220 outline. BODs are graded according to breakover voltage.

BREAKOVER DIODE CHARACTERISTICS

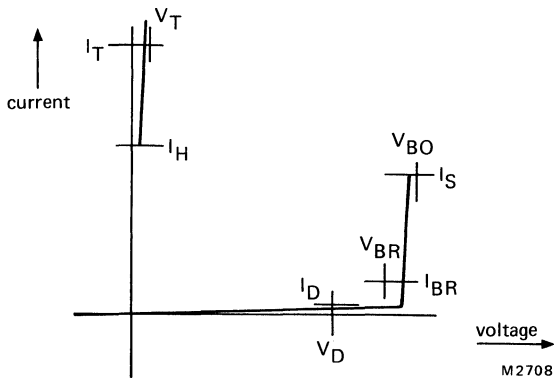


Fig.1 Breakover diode characteristics (1st quadrant).

The main characteristics are illustrated in Fig.1. These characteristics are:-

- V_{BO} breakover voltage, the maximum voltage appearing across the BOD before switching to the on-state.
- V_D stand-off voltage, maximum normal operating voltage.
- I_D off-state current, normally quoted at V_D .
- V_{BR} breakdown voltage, at which the BOD will commence avalanche breakdown.
- I_{BR} breakdown current, with V_{BR} applied.
- I_S switching current, the avalanche current required to switch the BOD to the on-state.
- I_T on-state current.
- V_T on-state voltage, specified at a given I_T .
- I_H holding current, the minimum current at which the BOD will remain in the on-state.

USE OF BREAKOVER DIODES

BODs are primarily designed to protect electronic equipment connected to transmission lines against transient overvoltages. However, there are many uses for BODs as breakover switches.

In designing BOD circuits the following must be considered:-

Off-state conditions

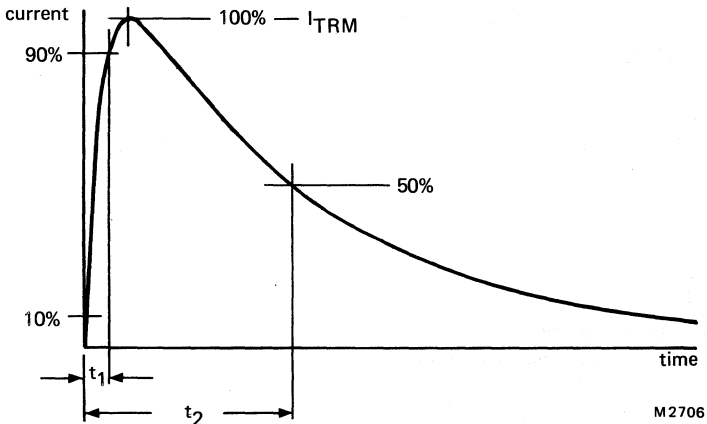
- V_D Must not be exceeded in normal off-state operation. In the off-state the BOD will not pass more current than I_D .
- dV_D/dt The rate of rise of voltage must not exceed that quoted for the device. If this is exceeded, the BOD may switch to on-state.
- V_{BR} Low voltage transients may be required not to switch the BOD to the on-state. To ensure the BOD remains in the off-state the voltage must remain below the minimum V_{BR} . If this is exceeded then clipping of the voltage or switching of the BOD may occur.
- I_S If V_{BR} is exceeded but the current limited to below I_S minimum, the BOD is prevented from switching to the on-state.
- C_j The off-state capacitance across the BOD. In transmission line protection applications this will be across the termination of the line.

Switching conditions

- V_{BO} A transient voltage greater than V_{BO} maximum is required to switch the BOD. V_{BO} may be greater than the voltage across the BOD passing current I_S maximum.
- I_S To enable the BOD to switch to the on-state a current greater than I_S maximum is required.

On-state conditions

- V_T The on-state voltage is quoted for a given I_T .
- I_H To enable the BOD to switch to the off-state the current must fall below I_H minimum.
- I_{TRM} I_{TRM} specifies the rate of increase and duration of a transient peak on-state current. The convention used to specify I_{TRM} is illustrated in Fig.2. This waveform is specified as a t_1/t_2 μs impulse.



M2706

Fig.2 Definition of I_{TRM} waveform.

Thermal conditions

R_{th} For extended on-state operation ($> 0.1\text{ms}$) the steady-state thermal resistance should be considered. The total thermal resistance to ambient should be sufficiently low to dissipate the heat generated by the device. For this type of application it is recommended that the BOD is mounted on a heatsink.

Z_{th} If the BOD is used only during transient overvoltages then the transient thermal impedance to ambient should be considered. It may be sufficient to mount the BOD in free-air.

Mains contact

Fig.3 illustrates the operation of a BOD during one cycle of a mains contact fault. The BOD will generate heat in avalanche breakdown until the instantaneous current is greater than I_S maximum. When this current is reached the BOD will switch and generate heat in the on-state.

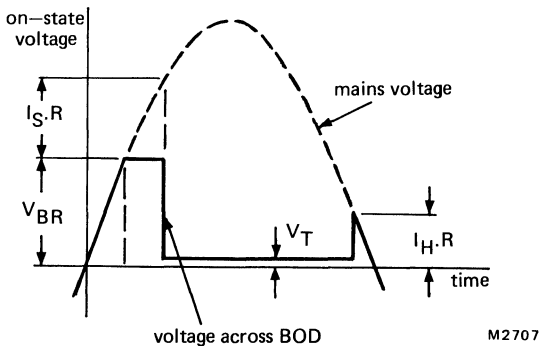


Fig.3 Voltage across BOD during mains contact fault,
 R = total fault impedance.

During avalanche a large amount of heat is generated. If the mains fault impedance is sufficiently high the BOD will remain in avalanche breakdown until the mains voltage falls below V_{BR} minimum. Under this condition the junction temperature may be raised considerably.

Power dissipation curves are not published for BODs during avalanche breakdown. This is because individual cases will vary greatly. However, in general if the fault impedance is about 500Ω - $5k\Omega$ then there will be excessive dissipation due to the avalanche breakdown.

If mains contact faults are likely with impedances in the range quoted, the dissipation of the BOD should be considered carefully.

BREAKOVER DIODE SYMBOLS AND CHARACTERISTICS

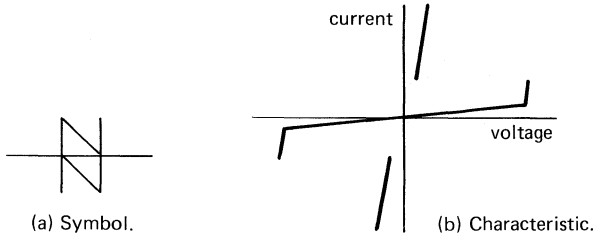


Fig.4 Symmetric BOD.

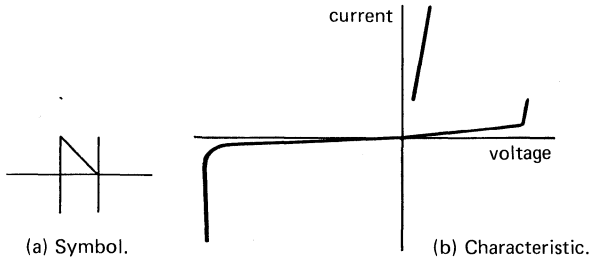


Fig.5 Reverse-blocking BOD.

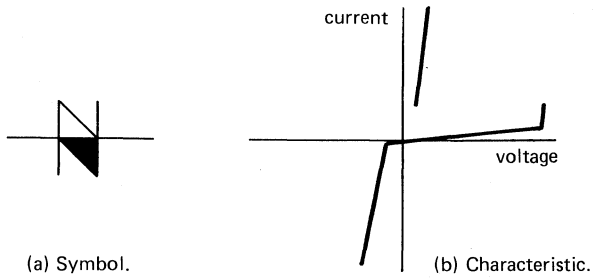


Fig.6 Reverse-conducting BOD.

Heatsinks are used where a semiconductor device is unable of itself to dissipate the heat generated by its internal power losses without the junction temperature exceeding its maximum. The simplest form of heatsink is a flat metal plate, but for economy in weight, size, and cost, more complex shapes are usually used.

Apart from information on heat transfer and the construction of assemblies, this Section shows how to take advantage of reverse polarity types, describes three types of heatsink, and gives calculation examples.

HEAT TRANSFER PATH

In, for example, a silicon rectifier the heat is generated inside the wafer and flows mainly by way of the base, through a heatsink to the ambient air.

The heat flow can be likened to the flow of electric current, with thermal resistance (R_{th} in $^{\circ}\text{C}/\text{W}$) analogous to the electric resistance (R in Ω).

Fig. 1 shows the heat path from junction to ambient as three thermal resistances in series:

- $R_{th\ j-mb}$ The thermal resistance from junction to mounting base. Its value is given in the data sheets of a device.
- $R_{th\ mb-h}$ The thermal resistance from mounting base to heatsink (contact thermal resistance). It is caused by the imperfect nature and limited size of the contact between the two. Its value is also given in the data sheets.
- $R_{th\ h-a}$ The thermal resistance between the contact surface mentioned above and the ambient air.

For thermal balance air warmed by the heatsink must be replaced by cool, i. e., there must be an air flow.

From Fig. 1: $T_j - T_{amb} = P \times (R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a})$

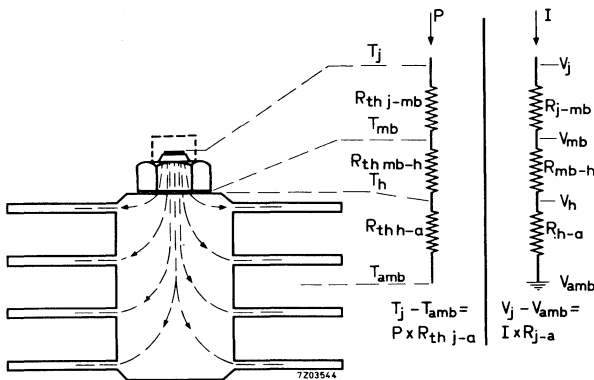


Fig. 1

IMPROVING HEAT TRANSFER

Heat transfer can be improved by reducing the thermal resistance of the contact and the thermal resistance of the heatsink.

Contact thermal resistance

- Make the contact area large
- Make the contact surfaces plane parallel by attention to drilling and punching, and make them burr-free.
- Apply sufficient pressure. Use a torque spanner adjusted to at least the rated minimum torque.
- Use metal oxide-loaded compound to fill air pockets.

Heatsink thermal resistance

- Paint or anodise the surface to improve radiation
- Increase the flow of cooling air
- Use a larger heatsink

The simplest form of air flow is natural convection. Mount the fins vertically, make in-take and outlet apertures large, avoid obstructions, create a draught (chimney effect). A blower or fan must be used where free convection is not enough or where a smaller heatsink is wanted.

INSULATED MOUNTING

Where a semiconductor must be insulated from its heatsink (e.g., in bridge rectifiers) by a mica or teflon washer, the contact thermal resistance will be about ten times higher than without insulation. This must be compensated by a reduction in R_{thh-a} to keep the total thermal resistance below the maximum given for P and T_{amb} . A larger heatsink may be necessary.

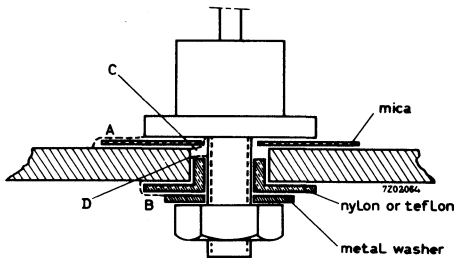


Fig. 2 Creepage distances with an insulated diode

Note: care must be taken that the creepage distances, see Fig. 2, are sufficient for the voltage involved. While A and B can be made large enough, C and D are likely to be the critical ones.

CONSTRUCTIONS

Good thermal coupling is essential to semiconductors connected in parallel to ensure good current sharing in view of the forward characteristics, and semiconductors in series in view of the reverse characteristics.

Mounting the semiconductors on the same heatsink not only saves mounting costs but also provides the needed thermal coupling.

Fig. 3 shows the construction for a plain heatsink, and Fig. 4 the construction for an extruded heatsink. The electrical connection is made with a copper strip at least 1 mm thick. For two diodes a plain heatsink should be twice the area, and an extruded heatsink twice the length needed for a single diode.

Reverse polarity devices are convenient for series connection of two diodes on a common heatsink. Figs. 5, 6 and 7 show how the use of normal polarity and reverse polarity diodes simplifies the construction of single-phase and three-phase bridge rectifiers.

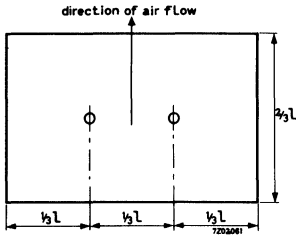


Fig. 3 Plain cooling fin with two diodes

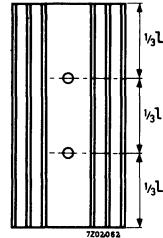


Fig. 4 Extruded aluminium heatsink with two diodes

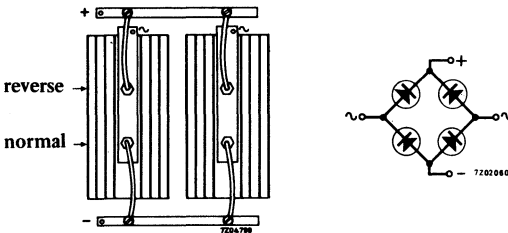


Fig. 5 Single phase full wave rectifier with diodes of different polarity on extruded aluminium heatsinks

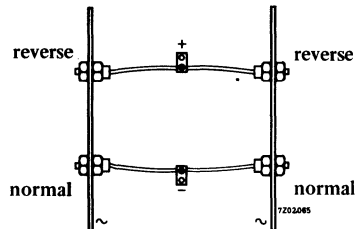


Fig. 6 Single phase full wave rectifier with diodes of different polarity on plain cooling fins (top view)

CONSTRUCTIONS (continued)

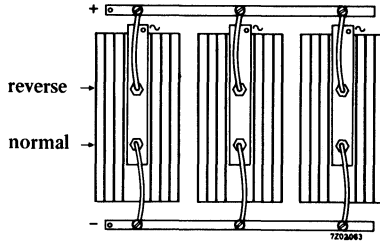


Fig. 7 Three phase full wave rectifier with diodes of different polarity on extruded aluminium heatsinks

EXAMPLES OF HEATSINK CALCULATION

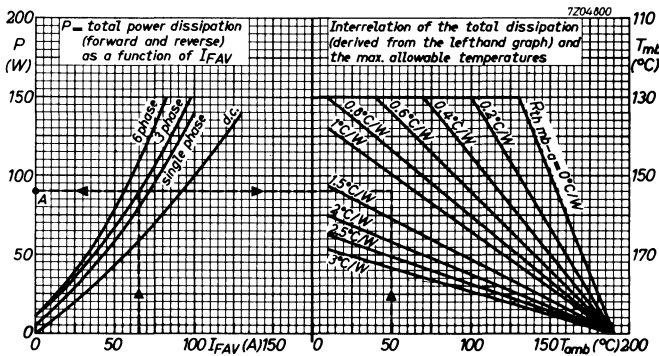
1. Devices without controlled avalanche properties.

Assume that the diode of which the outlines are shown, is used in a three phase 50 Hz rectifier circuit at $T_{amb} = 50\text{ }^{\circ}\text{C}$. Further assume: average forward current per diode $I_{F(AV)} = 65\text{ A}$; contact thermal resistance $R_{th\ mb-h} = 0,1\text{ }^{\circ}\text{C/W}$.



Stud: M12
Mounting base, across the flats: max. 27 mm

From the data of the diode the graph to be used is shown below.



From the lefthand graph it follows that $P_{tot} = 90\text{ W}$ per diode (point A).
From the righthand graph it follows that $R_{th\ mb-a} \approx 1,2\text{ }^{\circ}\text{C/W}$.
Thus $R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h} = (1,2 - 0,1)\text{ }^{\circ}\text{C/W} = 1,1\text{ }^{\circ}\text{C/W}$.
This may be achieved by different types of heatsinks as shown below.

Type	Free convection	Forced cooling
flat, blackened	-	125 cm ² ; 2 m/s or 300 cm ² ; 1 m/s
flat, bright	-	175 cm ² ; 2 m/s
diecast 56280	applicable	
extrusion		
56230 bright	$\ell = 12\text{ cm}$	$\ell = 5\text{ cm}^1$; 1 m/s
blackened	$\ell = 8\text{ cm}$	$\ell = 5\text{ cm}^1$; 1 m/s
56231 bright	$\ell = 7\text{ cm}$	
blackened	$\ell = 5\text{ cm}^1$)	

¹⁾ Practical minimum length

EXAMPLES OF HEATSINK CALCULATION (continued)

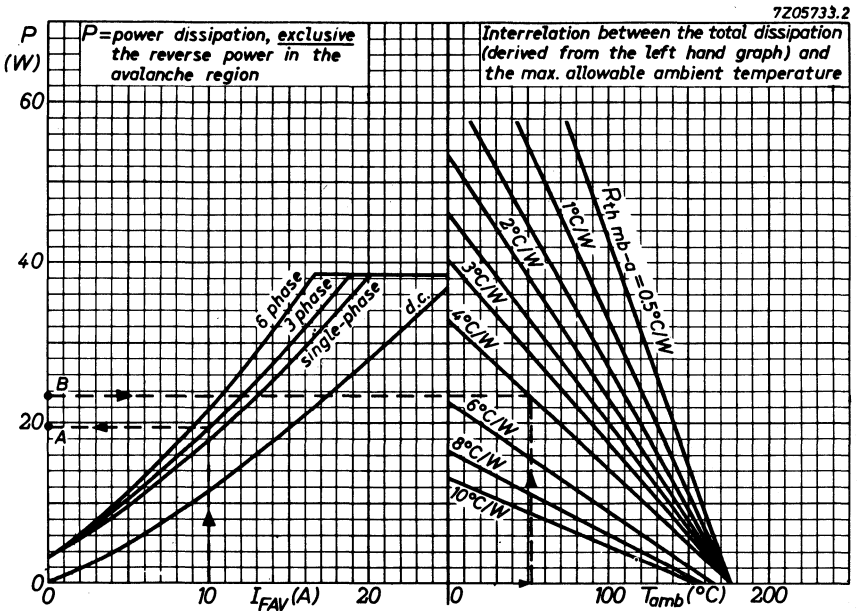
2. Devices with controlled avalanche properties

Assume that the diode of which the outlines are shown, is used in a three phase 50 Hz rectifier circuit at $T_{amb} = 40\text{ }^{\circ}\text{C}$. Further assume: average forward current per diode $I_{F(AV)} = 10\text{ A}$; contact thermal resistance: $R_{th\ mb-h} = 0,5\text{ }^{\circ}\text{C/W}$; repetitive peak reverse power in the avalanche region ($t = 40\mu\text{s}$) $P_{RRM} = 2\text{ kW}$ (per diode).



Stud: M12
Mounting base, across the flats: max. 27 mm

From the data of this diode the graph to be used is shown below.



From the lefthand graph it follows that $P_{tot} = 19,5\text{ W}$ per diode (point A). The average reverse power in the avalanche region, averaged over any cycle, follows from

$$P_{R(AV)} = \delta \times P_{RRM}, \text{ where the duty cycle } \delta = \frac{40\ \mu\text{s}}{20\ \text{ms}} = 0,002.$$

Thus $P_{R(AV)} = 0,002 \times 2\text{ kW} = 4\text{ W}$.

Therefore the total device power dissipation $P_{tot} = 19,5 + 4 = 23,5\text{ W}$ (point B). From the righthand graph it follows that $R_{th\ mb-a} = 4\text{ }^{\circ}\text{C/W}$. Hence the heatsink thermal resistance should be:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h} = (4 - 0,5)\text{ }^{\circ}\text{C/W} = 3,5\text{ }^{\circ}\text{C/W}.$$

A table of applicable heatsinks, similar to that on the foregoing page, can be derived for this case.

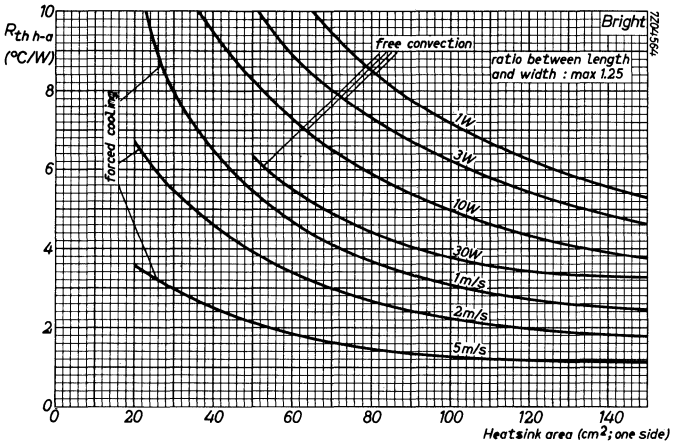
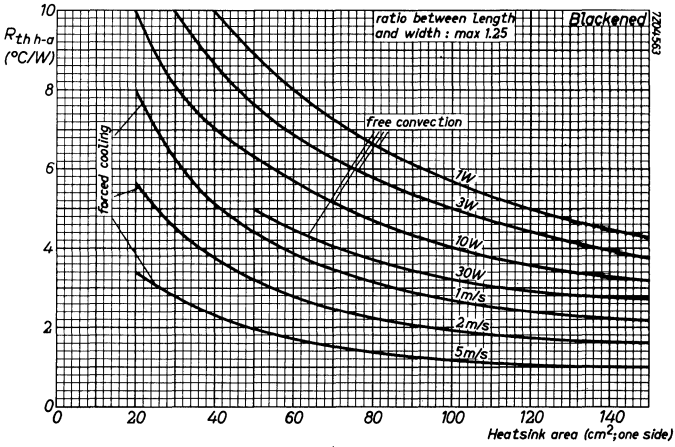
Flat heatsink

Thermal resistance of flat heatsinks of 2 mm copper or 3 mm aluminium.
The graphs are valid for the combination of device and heatsink.



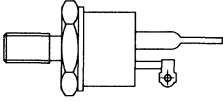
Studs: 10-32UNF

Mounting bases, across the flats: max. 11,0 mm

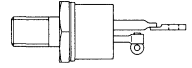


Flat heatsink

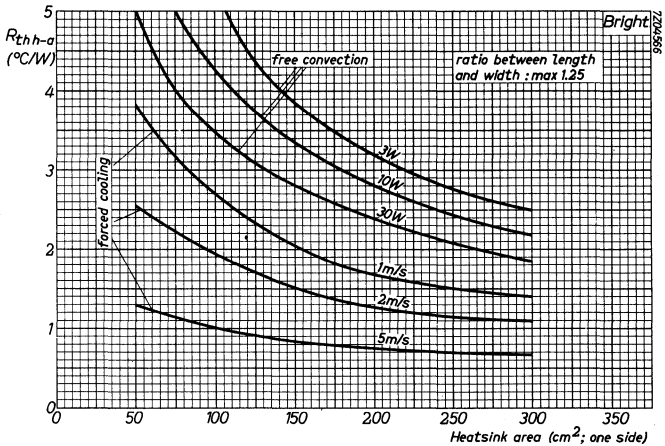
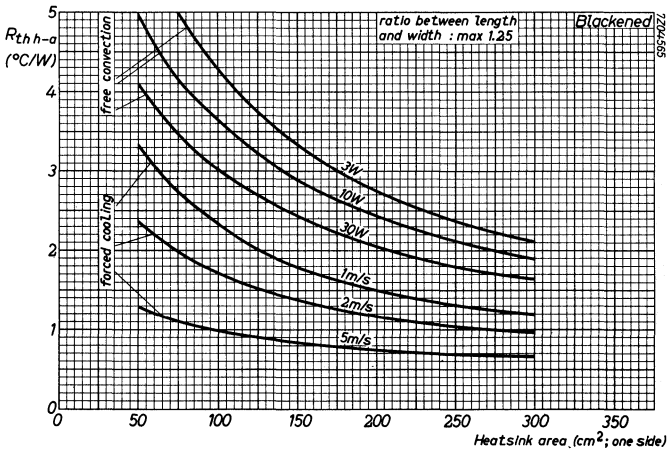
Thermal resistance of flat heatsinks of 2 mm copper or 3 mm aluminium.
The graphs are valid for the combination of device and heatsink.



Stud: $\frac{1}{4}$ " x 28 UNF
Mounting base, across the flats: max. 17 mm



Stud: M6
Stud: $\frac{1}{4}$ " x 28 UNF
Mounting base, across the flats: max. 14,0 mm



RECTIFIER DIODES

SILICON RECTIFIER DIODES

Glass-passivated double-diffused rectifier diodes in TO-220 plastic envelopes, intended for power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to base plate): BY249-300 and BY249-600.

Reverse polarity (anode to base plate): BY249-300R and BY249-600R.

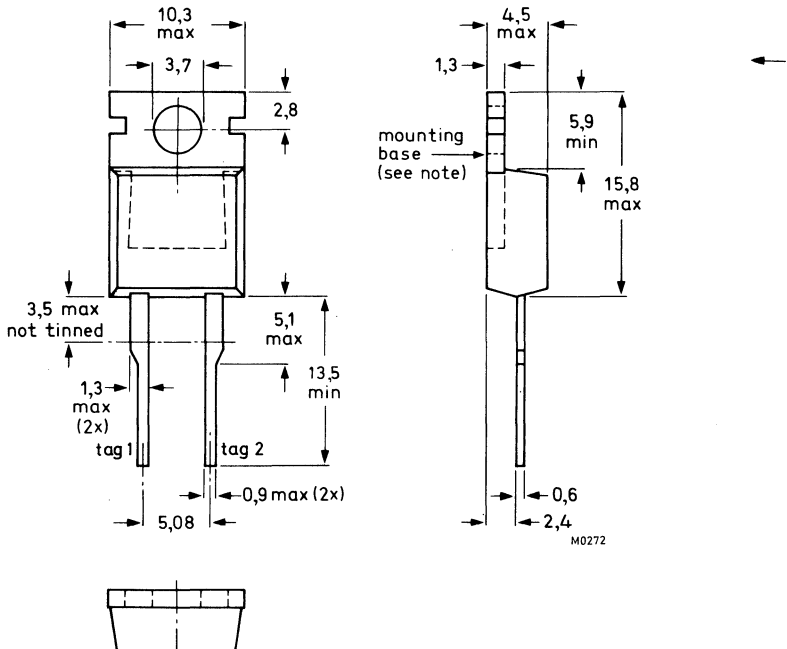
QUICK REFERENCE DATA

		BY249-300(R)		600(R)	
Repetitive peak reverse voltage	V_{RRM} max.	300	600		V
Average forward current	$I_{F(AV)}$ max.			6.5	A
Non-repetitive peak forward current	I_{FSM} max.			60	A

MECHANICAL DATA (see next page for polarity of connections)

Dimensions in mm

Fig. 1 TO-220AC



Note: The exposed metal mounting base is directly connected to tag 1.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

MECHANICAL DATA (continued)

Polarity of connections:

	BY249-300 BY249-600	BY249-300R BY249-600R
base plate	cathode	anode
tag 1	cathode	anode
tag 2	anode	cathode

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages*			BY249-300(R)		600(R)	
Non-repetitive peak reverse voltage	V_{RSM}	max.	300	600	V	
Repetitive peak reverse voltage	V_{RRM}	max.	300	600	V	
Crest working reverse voltage	V_{RWM}	max.	200	400	V	
Continuous reverse voltage	V_R	max.	200	400	V	

Currents

Average forward current;

sinusoidal; up to $T_{mb} = 110^\circ C$ $I_{F(AV)}$ max. 6.5 A

sinusoidal; at $T_{mb} = 125^\circ C$ $I_{F(AV)}$ max. 4.0 A

R.M.S. forward current $I_{F(RMS)}$ max. 9.5 A

Repetitive peak forward current;

$t = 10$ ms; half sine-wave I_{FRM} max. 60 A

Non-repetitive peak forward current;

$t = 10$ ms; half sine-wave;

$T_j = 150^\circ C$ prior to surge;

with re-applied V_{RWMmax} I_{FSM} max. 60 A

$I^2 t$ for fusing; $t = 10$ ms $I^2 t$ max. 18 $A^2 s$

Temperatures

Storage temperature T_{stg} -40 to +150 $^\circ C$

Junction temperature T_j max. 150 $^\circ C$

CHARACTERISTICS

Forward voltage

$I_F = 20$ A; $T_j = 25^\circ C$ $V_F < 1.6$ V**

$I_F = 5$ A; $T_j = 100^\circ C$ $V_F < 1.05$ V**

Reverse current

$V_R = V_{RWMmax}$; $T_j = 125^\circ C$ $I_R < 0.4$ mA

*To ensure thermal stability, $R_{th j-a} < 15^\circ C/W$ for continuous reverse voltage.

**Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 4.2\ \text{°C/W}$$

Transient thermal impedance; $t = 1\ \text{ms}$

$$Z_{th\ j-mb} = 0.46\ \text{°C/W}$$

Influence of mounting method

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3\ \text{°C/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4\ \text{°C/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2\ \text{°C/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8\ \text{°C/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4\ \text{°C/W}$$

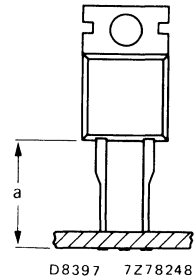
2. Free-air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air: mounted on a printed-circuit board at a = any lead length.

$$R_{th\ j-a} = 60\ \text{°C/W}$$

Fig. 2

**MOUNTING INSTRUCTIONS**

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.

2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.

3. It is recommended that the circuit connection be made to tag 1, rather than direct to the heatsink.

4. Mounting by means of a spring clip is the best mounting method because it offers:

a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than screw mounting.

b. safe isolation for mains operation.

However, if a screw is used, it should be M3 cross-recess pan-head. Care should be taken to avoid damage to the plastic body.

5. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.

6. Rivet mounting (only possible for non-insulated mounting)

Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

SINUSOIDAL OPERATION

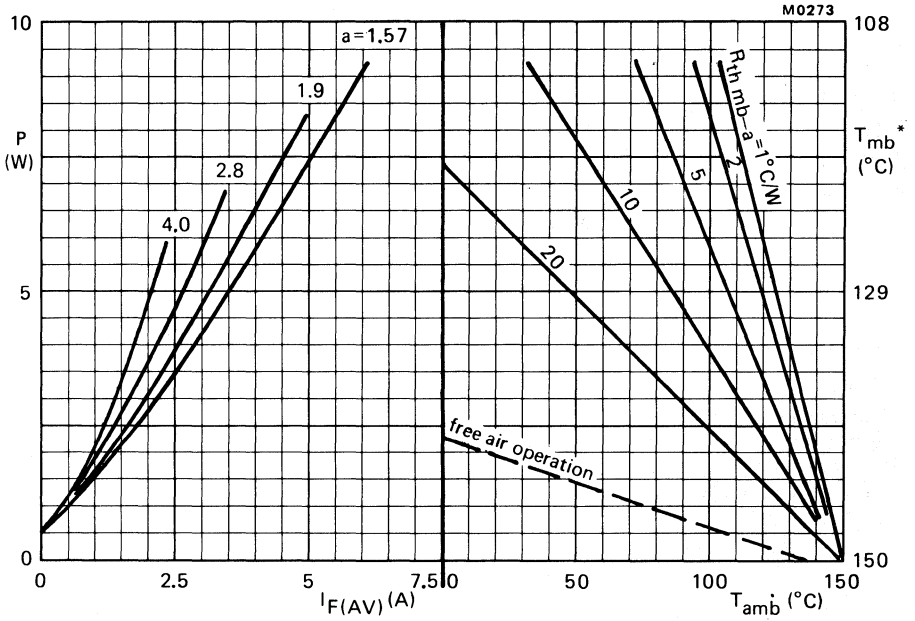


Fig. 3 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

a = form factor = $I_{F(RMS)}/I_{F(AV)}$.

* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 19.3$ $^{\circ}C/W$.

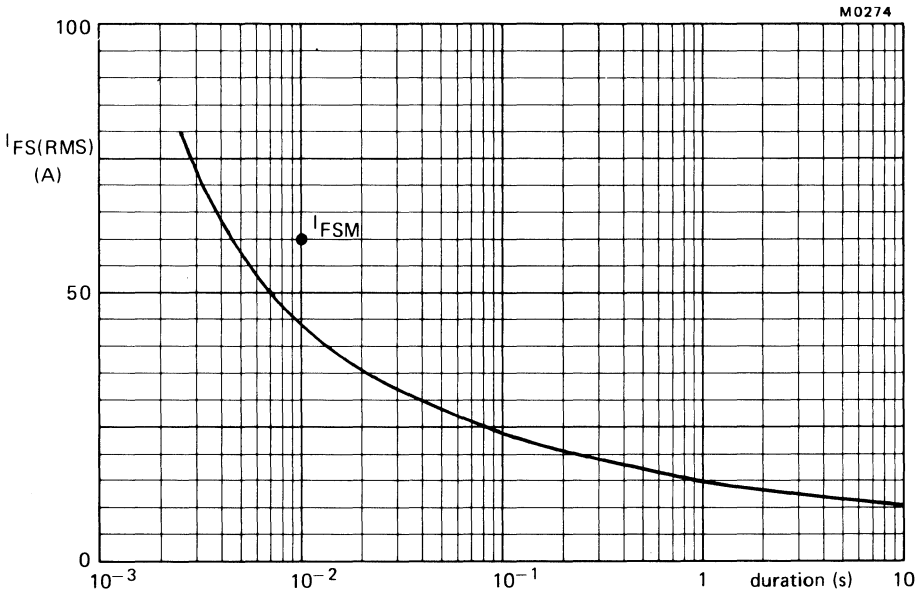


Fig. 4 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 150$ °C prior to surge.

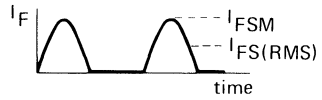
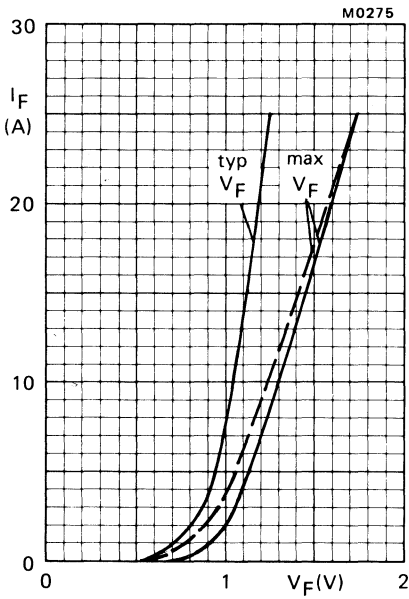


Fig. 5 ——— $T_j = 25$ °C; - - - $T_j = 100$ °C

M0276

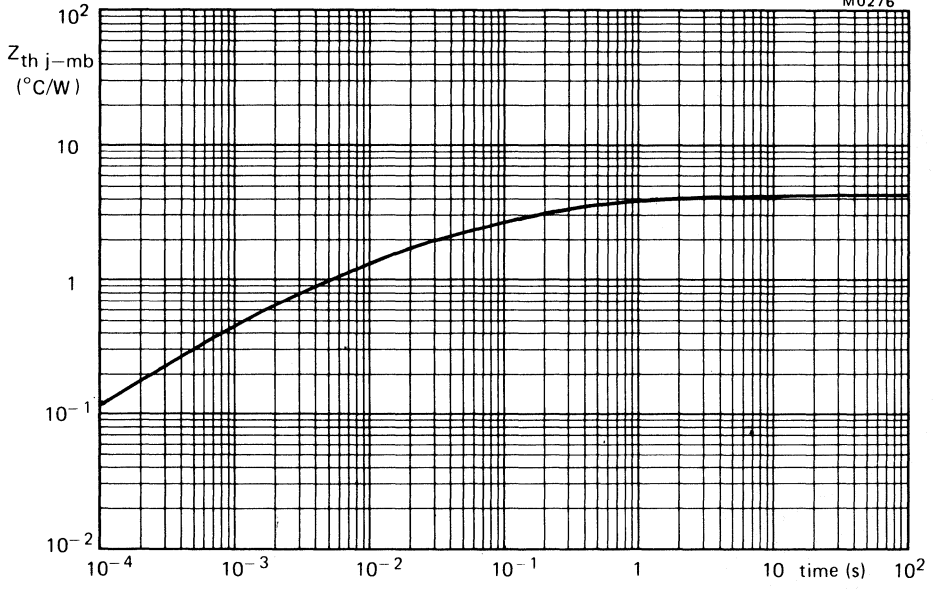


Fig. 6

CONTROLLED AVALANCHE RECTIFIER DIODES



Diffused silicon diodes in DO-4 metal envelopes, capable of absorbing transients and intended for power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): BYX25-600 to BYX25-1400.

Reverse polarity (anode to stud): BYX25-600R to BYX25-1400R.

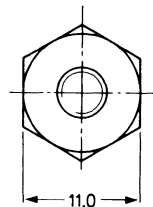
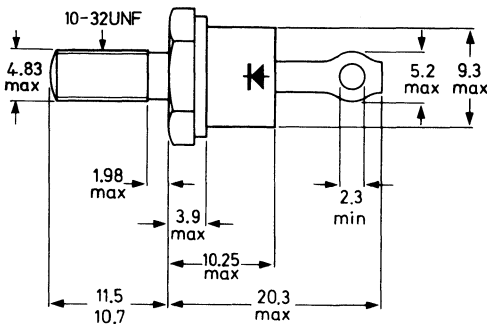
QUICK REFERENCE DATA

		BYX25-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	V_{RWM}	max. 600	800	1000	1200	1400	V
Reverse avalanche breakdown voltage	$V_{(BR)R}$	> 750	1000	1250	1450	1650	V
Average forward current	$I_{F(AV)}$	max. 20					A
Non-repetitive peak forward current	I_{FSM}	max. 360					A
Non-repetitive peak reverse power	P_{RSM}	max. 18					kW

MECHANICAL DATA

Fig. 1 DO-4.

Dimensions in mm



M0184A

Net mass: 7 g.

Diameter of clearance hole: max. 5.2 mm.

Accessories supplied on request:
see ACCESSORIES section

Supplied with device: 1 nut, 1 lock washer.

Nut dimensions across the flats: 9.5 mm

Products approved to CECC 50 009-022 available on request.

Torque on nut:
min. 0.9 Nm (9 kg cm),
max. 1.7 Nm (17 kg cm).

The mark shown applies to the normal polarity types.

BYX25 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

Voltages*

		BYX25-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	V_{RWM}	max. 600	800	1000	1200	1400	V
Continuous reverse voltage	V_R	max. 600	800	1000	1200	1400	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 125^\circ\text{C}$	$I_F(AV)$	max.	20	A
Repetitive peak forward current	I_{FRM}	max.	440	A
Non-repetitive peak forward current $t = 10\text{ ms}$ (half sine-wave); $T_j = 175^\circ\text{C}$ prior to surge; with reapplied V_{RWMmax}	I_{FSM}	max.	360	A
$I^2 t$ for fusing	$I^2 t$	max.	650	A^2s

Reverse power dissipation

Average reverse power dissipation (averaged over any 20 ms period); $T_j = 175^\circ\text{C}$	$P_R(AV)$	max.	38	W
Repetitive peak reverse power dissipation $t = 10\ \mu\text{s}$ (square-wave; $f = 50\text{ Hz}$); $T_j = 175^\circ\text{C}$	P_{RRM}	max.	3	kW
Non-repetitive peak reverse power dissipation $t = 10\ \mu\text{s}$ (square-wave) $T_j = 25^\circ\text{C}$ prior to surge	P_{RSM}	max.	18	kW
$T_j = 175^\circ\text{C}$ prior to surge	P_{RSM}	max.	3	kW

Temperatures

Storage temperature	T_{stg}		-55 to +175	$^\circ\text{C}$
Junction temperature	T_j	max.	175	$^\circ\text{C}$

*To ensure thermal stability: $R_{th\ j-a} < 5\text{ K/W}$ (a.c.)

THERMAL RESISTANCE

From junction to ambient in free air	$R_{th\ j-a}$	=	50	°C/W
From junction to mounting base	$R_{th\ j-mb}$	=	1.3	°C/W
From mounting base to heatsink	$R_{th\ mb-h}$	=	0.5	°C/W

CHARACTERISTICS

		BYX25-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Forward voltage $I_F = 50\text{ A}; T_j = 25\text{ °C}$	V_F	< 1.8	1.8	1.8	1.8	1.8	V*
Reverse avalanche breakdown voltage $I_R = 5\text{ mA}; T_j = 25\text{ °C}$	$V_{(BR)R}$	> 750	1000	1250	1450	1650	V
		< 2400	2400	2400	2400	2400	V
Peak reverse current $V_R = V_{RWMmax};$ $T_j = 125\text{ °C}$	I_R	< 1.0	0.8	0.6	0.5	0.5	mA

*Measured under pulse conditions to avoid excessive dissipation.

OPERATING NOTES

1. Voltage sharing of series connected controlled avalanche diodes.

If diodes with avalanche characteristics are connected in series, the usual R and C elements for voltage sharing can be omitted.

2. The top connector should not be bent; it should be soldered into the circuit so that there is no strain on it.
 During soldering the heat conduction to the junction should be kept to a minimum by using a thermal shunt.

Determination of the heatsink thermal resistance

Example:

Assume a diode, used in a three phase rectifier circuit.

frequency	f = 50 Hz
average forward current	I _{FAV} = 10 A (per diode)
ambient temperature	T _{amb} = 40 °C
repetitive peak reverse power dissipation in the avalanche region	P _{RRM} = 2 kW (per diode)
duration of P _{RRM}	t = 40 μs

From the left hand part of the upper graph on page 5 it follows that at I_{FAV} = 10 A in a three phase rectifier circuit the average forward power + average leakage power = 19.5 W per diode (point A). The average reverse power in the avalanche region, averaged over any cycle, follows from:

$$P_{RAV} = \delta \times P_{RRM}, \text{ where the duty cycle } \delta = \frac{40 \mu s}{20 \text{ ms}} = 0.002$$

Thus: P_{RAV} = 0.002 x 2 kW = 4 W

Therefore the total device power dissipation P_{tot} = (19.5 + 4) W = 23.5 W (point B).

In order to avoid excessive peak junction temperatures resulting from the pulse character of the repetitive peak reverse power in the avalanche region, the value of the maximum junction temperature should be reduced. If the repetitive peak reverse power in the avalanche region is 2 kW; t = 40 μs; f = 50 Hz, the maximum allowable junction temperature should be 163 °C instead of 175 °C, thus 12 °C lower (see the lower graph on page 49).

Allowance can be made for this by assuming an ambient temperature 12 °C higher than before, in this case 52 °C instead of 40 °C.

Using this in the curve leads to a thermal resistance

$$R_{th \text{ mb-a}} \approx 4 \text{ °C/W}$$

The contact thermal resistance R_{th mb-h} = 0.5 °C/W

Hence the heatsink thermal resistance should be:

$$R_{th \text{ h-a}} = R_{th \text{ mb-a}} - R_{th \text{ mb-h}} = (4 - 0.5) \text{ °C/W} = 3.5 \text{ °C/W}$$

7205733.2

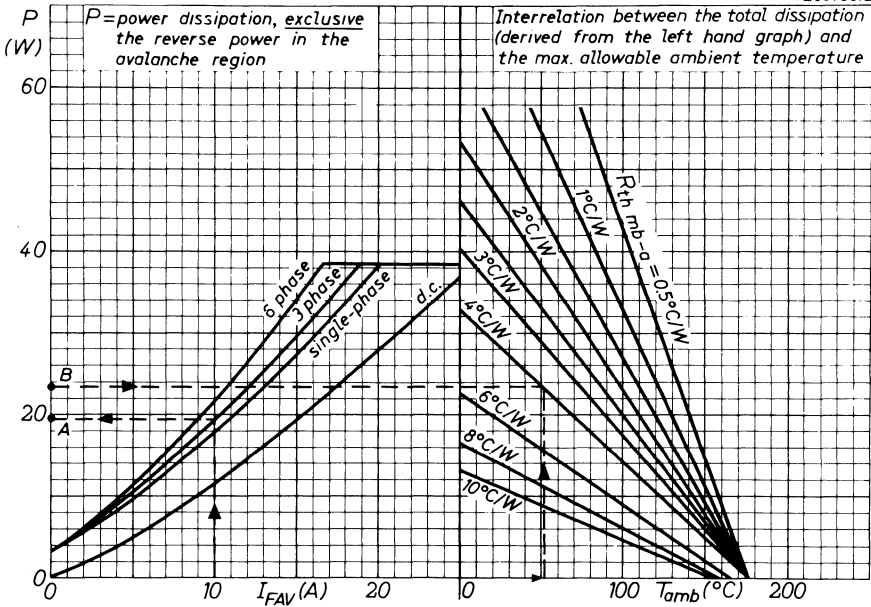


Fig.2

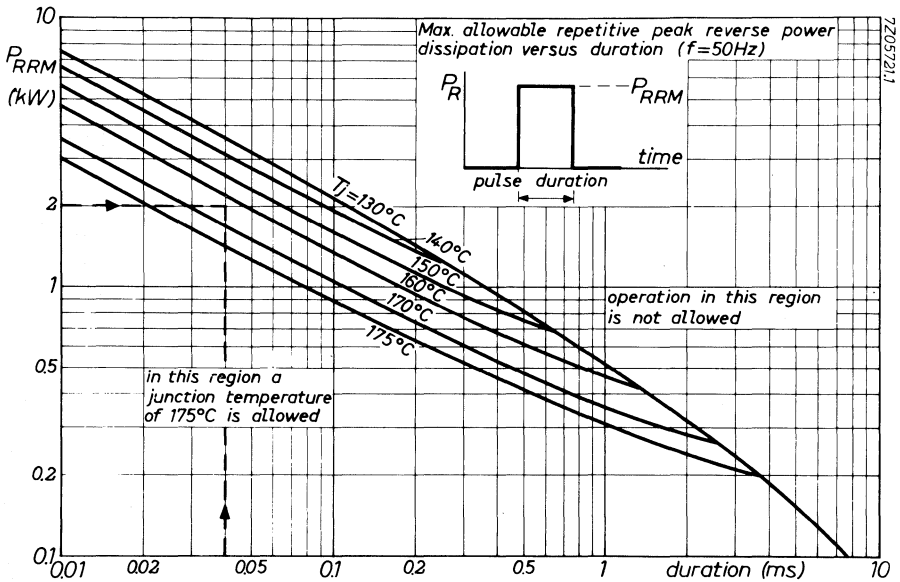


Fig.3

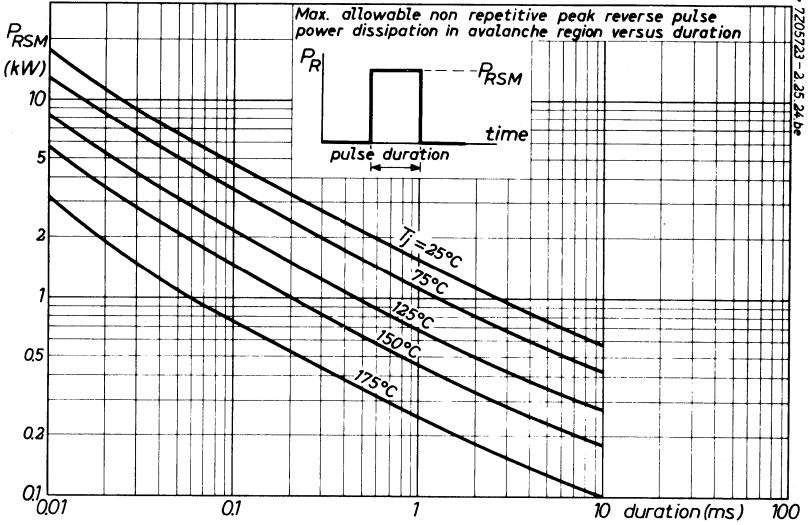


Fig.4

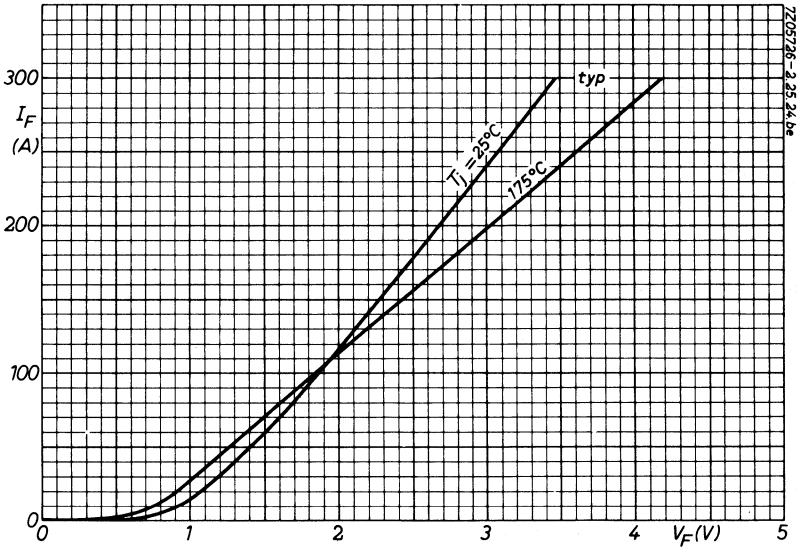


Fig.5

7272545.1

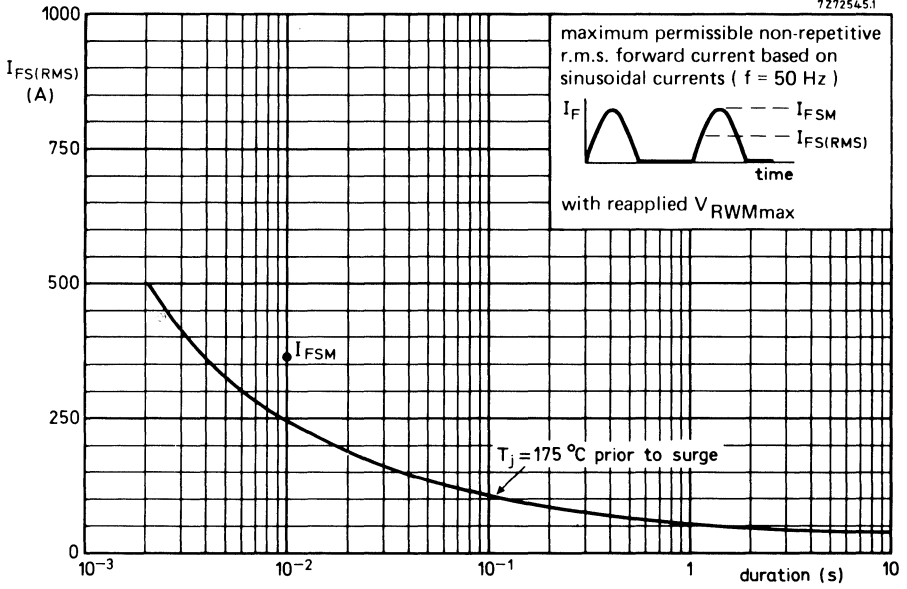


Fig.6

SILICON RECTIFIER DIODES

Diffused silicon diodes in metal envelopes with ceramic insulation, intended for power rectifier application. The series consists of the following types:

Normal polarity (cathode to stud): BYX32-600 to BYX32-1600

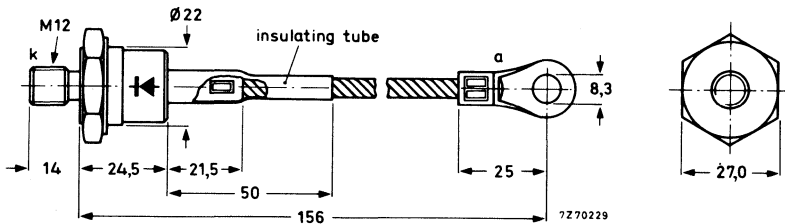
Reverse polarity (anode to stud): BYX32-600R to BYX32-1600R

QUICK REFERENCE DATA

		BYX32-600	600R	800	800R	1000	1000R	1200	1200R	1600	1600R	
Crest working reverse voltage	V_{RWM} max.	600	800	1000	1200	1200	1600					V
Repetitive peak reverse voltage	V_{RRM} max.	600	800	1000	1200	1600						V
Average forward current	$I_F(AV)$ max.					150						A
Non-repetitive peak forward current	I_{FSM} max.					1600						A

MECHANICAL DATA

Dimensions in mm



Normal polarity (⚡): blue cable. Reverse polarity (⚡): red cable.

Net mass: 115 g

Diameter of clearance hole: max. 13.0 mm

Torque on nut: min. 10 Nm
 (100 kg cm)
 max. 25 Nm
 (250 kg cm)

BYX32 SERIES

All information applies to frequencies up to 400 Hz.

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages ¹⁾			BYX32-				
			600 600R	800 800R	1000 1000R	1200 1200R	1600 1600R
Continuous reverse voltage	V_R	max.	600	800	1000	1200	1200 V
Crest working reverse voltage	V_{RWM}	max.	600	800	1000	1200	1200 V
Repetitive peak reverse voltage	V_{RRM}	max.	600	800	1000	1200	1600 V
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM}	max.	650	900	1100	1300	1600 V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 100^\circ\text{C}$ at $T_{mb} = 125^\circ\text{C}$	$I_{F(AV)}$	max.	150 A
	$I_{F(AV)}$	max.	115 A
Forward current (d. c.)	I_F	max.	240 A
R. M. S. forward current	$I_{F(RMS)}$	max.	240 A
Repetitive peak forward current	I_{FRM}	max.	750 A
Non-repetitive peak forward current ($t = 10$ ms; half sine wave) $T_j = 190^\circ\text{C}$ prior to surge	I_{FSM}	max.	1600 A
I squared t for fusing ($t = 10$ ms)	I^2t	max.	12800 A ² s

Temperatures

Storage temperature	T_{stg}	-55 to +200 $^\circ\text{C}$
Operating junction temperature	T_j	max. 190 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	0.4 $^\circ\text{C/W}$
From mounting base to heatsink without heatsink compound	$R_{th\ mb-h}$	=	0.1 $^\circ\text{C/W}$
From mounting base to heatsink with heatsink compound (Dow Corning 340)	$R_{th\ mb-h}$	=	0.04 $^\circ\text{C/W}$
Transient thermal impedance; $t = 1$ ms	$Z_{th\ j-mb}$	=	0.025 $^\circ\text{C/W}$

¹⁾ To ensure thermal stability: $R_{th\ j-a} < 0.75^\circ\text{C/W}$ (continuous reverse voltage) or $< 1.5^\circ\text{C/W}$ (a. c.)

For smaller heatsinks T_j should be derated.

For continuous reverse voltage: $R_{th\ j-a} = 1^\circ\text{C/W}$, then $T_{jmax} = 184^\circ\text{C}$
 $R_{th\ j-a} = 1.2^\circ\text{C/W}$, then $T_{jmax} = 180^\circ\text{C}$
 $R_{th\ j-a} = 1.5^\circ\text{C/W}$, then $T_{jmax} = 175^\circ\text{C}$

SILICON RECTIFIER DIODES



Silicon rectifier diodes in DO-4 metal envelopes, intended for use in power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): BYX38-300 to 1200.

Reverse polarity (anode to stud): BYX38-300R to 1200R.

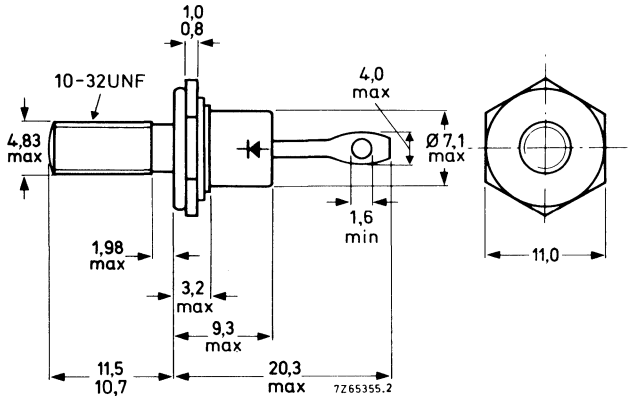
QUICK REFERENCE DATA

		BYX38-300(R)	600(R)	1200(R)
Repetitive peak reverse voltage	V_{RRM}	max. 300	600	1200 V
Average forward current	$I_{F(AV)}$	max.	6	A
Non-repetitive peak forward current	I_{FSM}	max.	50	A

MECHANICAL DATA

Dimensions in mm

DO-4



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request:
see ACCESSORIES section

Torque on nut: min. 0,9 Nm
(9 kg cm)
max. 1,7 Nm
(17 kg cm)

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 9,5 mm

The mark shown applies to normal polarity types.

BYX38
SERIES

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		BYX38-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM}	max. 300	600	1200	V
Repetitive peak reverse voltage ($\delta \leq 0,01$)	V_{RRM}	max. 300	600	1200	V
Crest working reverse voltage	V_{RWM}	max. 200	400	800	V
Continuous reverse voltage	V_R	max. 200	400	800	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 110$ °C at $T_{mb} = 125$ °C	$I_F(AV)$	max.	6	A
	$I_F(AV)$	max.	4	A
R. M. S. forward current	$I_F(RMS)$	max.	10	A
Repetitive peak forward current	I_{FRM}	max.	50	A
Non-repetitive peak forward current ($t = 10$ ms; half sine-wave) $T_j = 150$ °C prior to surge; with reapplied V_{RWMmax}	I_{FSM}	max.	50	A
I^2t for fusing ($t = 10$ ms)	I^2t	max.	13	A ² s

Temperatures

Storage temperature	T_{stg}	-55 to +150	°C
Junction temperature	T_j	max. 150	°C

THERMAL RESISTANCE

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	4	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,5	°C/W
without heatsink compound	$R_{th mb-h}$	=	0,6	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0,3	°C/W

CHARACTERISTICSForward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_F < 1,7 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWM\max}; T_j = 125 \text{ }^\circ\text{C} \qquad I_R < 200 \text{ } \mu\text{A}$$

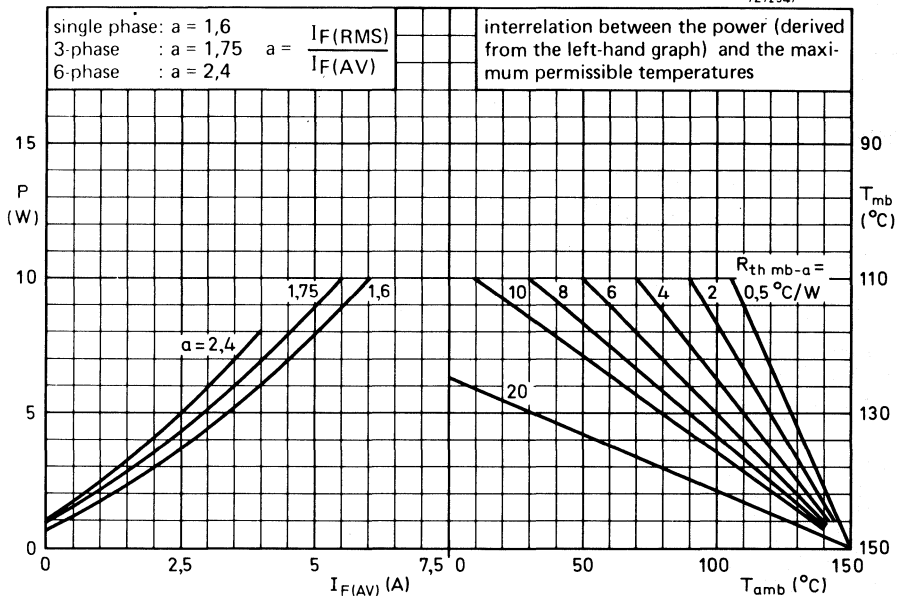
OPERATING NOTES

1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits.

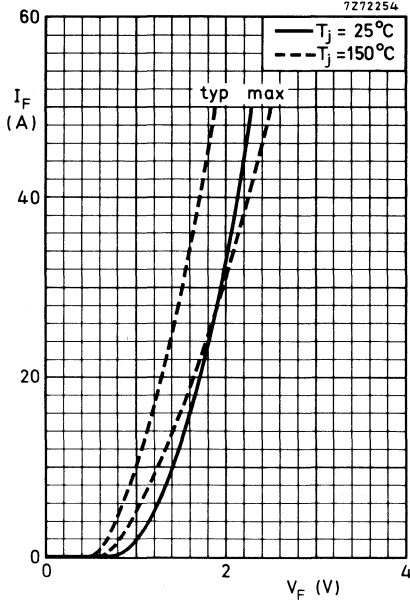
¹⁾ Measured under pulse conduction to avoid excessive dissipation.

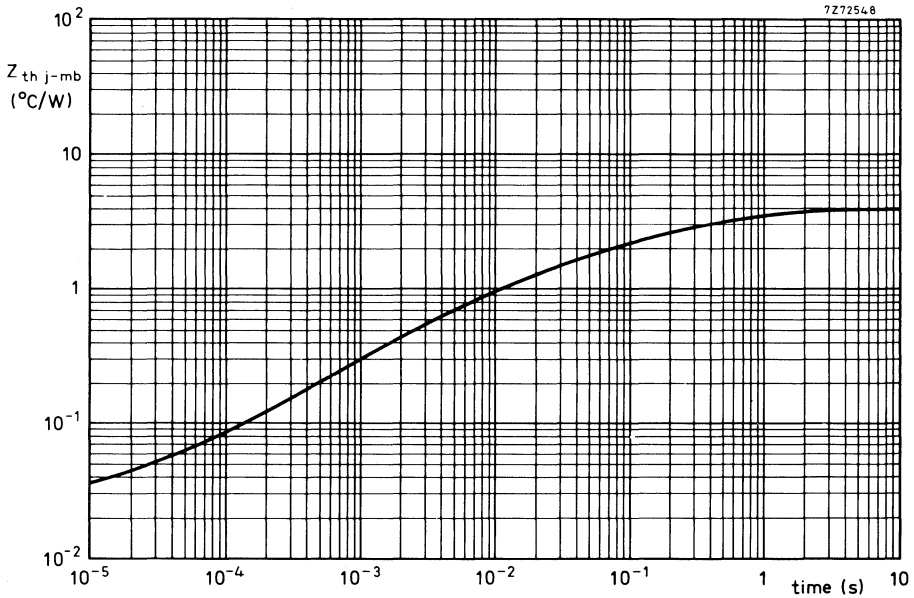
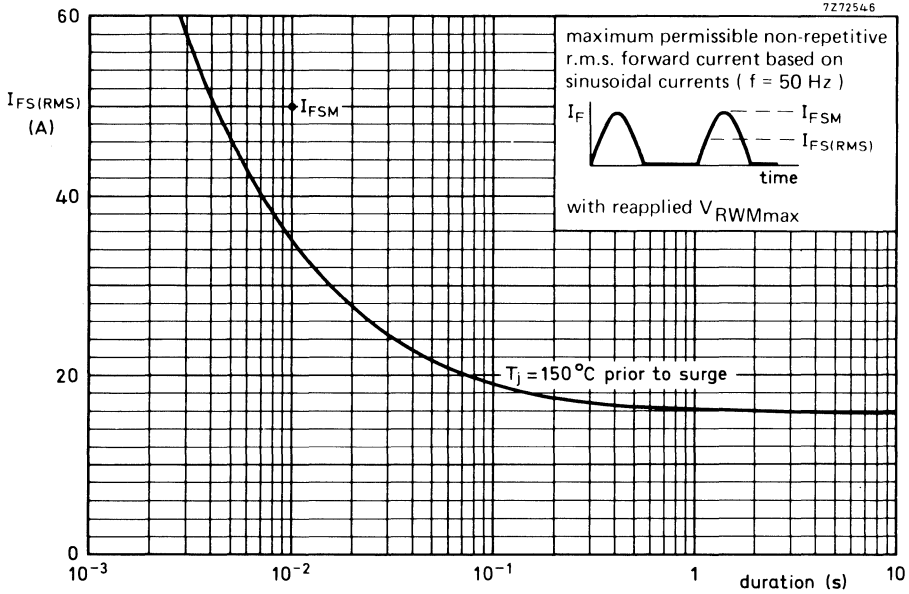
BYX38 SERIES

7272547



7272254





CONTROLLED AVALANCHE RECTIFIER DIODES

Also available to BS9333-F005

Silicon diodes in a DO-4 metal envelope, capable of absorbing transients and intended for use in power rectifier application.

The series consists of the following types:

Normal polarity (cathode to stud): BYX39-600 to BYX39-1400.

Reverse polarity (anode to stud): BYX39-600R to BYX39-1400R.

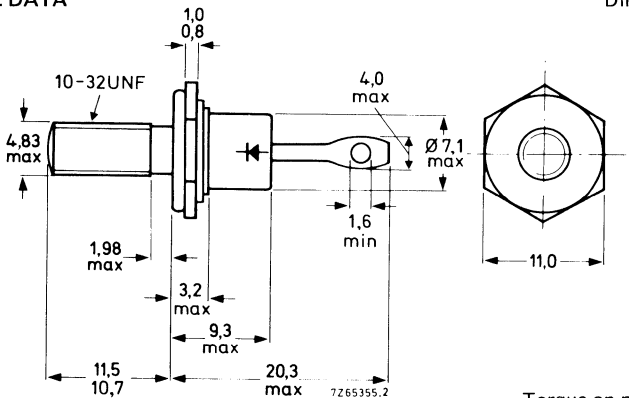
QUICK REFERENCE DATA

		BYX39-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	V_{RWM} max.	600	800	1000	1200	1400	V
Reverse avalanche breakdown voltage	$V_{(BR)R} >$	750	1000	1250	1450	1650	V
Average forward current	$I_F(AV)$ max.			9.5			A
Non-repetitive peak forward current	I_{FSM} max.			125			A
Non-repetitive peak reverse power dissipation	P_{RSM} max.			4			kW

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4



Net mass: 6 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:

see ACCESSORIES section

Supplied with device: 1 nut, 1 lock-washer.

Nut dimensions across the flats: 9.5 mm.

The mark shown applies to normal polarity types.

Torque on nut:
min. 0.9 Nm (9 kg cm),
max. 1.7 Nm (17 kg cm).

BYX39 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

Voltages*		BYX39-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Continuous reverse voltage	V_R	max. 600	800	1000	1200	1400	V
Crest working reverse voltage	V_{RWM}	max. 600	800	1000	1200	1400	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 85^\circ\text{C}$
at $T_{mb} = 125^\circ\text{C}$

$I_{F(AV)}$ max. 9.5 A
 $I_{F(AV)}$ max. 6.0 A

R.M.S. forward current

$I_{F(RMS)}$ max. 15 A

Repetitive peak forward current

I_{FRM} max. 100 A

Non-repetitive peak forward current
 $t = 10$ ms (half sine-wave); $T_j = 175^\circ\text{C}$ prior to surge;
with reapplied V_{RWMmax}

I_{FSM} max. 125 A

$I^2 t$ for fusing ($t = 10$ ms)

$I^2 t$ max. 78 A^2s

Reverse power dissipation

Average reverse power dissipation
(averaged over any 20 ms period); $T_j = 125^\circ\text{C}$

$P_{R(AV)}$ max. 10 W

Repetitive peak reverse power dissipation
 $t = 10$ μs (square-wave; $f = 50$ Hz); $T_j = 125^\circ\text{C}$

P_{RRM} max. 2 kW

Non-repetitive peak reverse power dissipation
 $t = 10$ μs (square-wave)
 $T_j = 25^\circ\text{C}$ prior to surge
 $T_j = 175^\circ\text{C}$ prior to surge

P_{RSM} max. 4 kW
 P_{RSM} max. 0.8 kW

Temperatures

Storage temperature

T_{stg} -55 to +175 $^\circ\text{C}$

Junction temperature

T_j max. 175 $^\circ\text{C}$

*To ensure thermal stability: $R_{th\ j-a} \leq 5^\circ\text{C/W}$ (continuous reverse voltage) or $\leq 20^\circ\text{C/W}$ (a.c.)

THERMAL RESISTANCE

From junction to ambient in free air	$R_{th\ j-a}$	=	50	°C/W
From junction to mounting base	$R_{th\ j-mb}$	=	4.5	°C/W
From mounting base to heatsink				
without heatsink compound	$R_{th\ mb-h}$	=	1.0	°C/W
with heatsink compound	$R_{th\ mb-h}$	=	0.5	°C/W
with mica washer	$R_{th\ mb-h}$	=	2.0	°C/W
Transient thermal impedance; $t = 1\ ms$	$Z_{th\ j-mb}$	=	0.35	°C/W

CHARACTERISTICS

		BYX39-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Forward voltage							
$I_F = 20\ A; T_j = 25\ ^\circ C$	V_F	< 1.7	1.7	1.7	1.7	1.7	V*
Reverse avalanche breakdown voltage							
$I_R = 5\ mA; T_j = 25\ ^\circ C$	$V_{(BR)R}$	> 750	1000	1250	1450	1650	V
		< 2400	2400	2400	2400	2400	V
Reverse current							
$V_R = V_{RWMmax}; T_j = 125\ ^\circ C$	I_R	< 200	200	200	200	200	μA

OPERATING NOTES

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

*Measured under pulse conditions to avoid excessive dissipation.

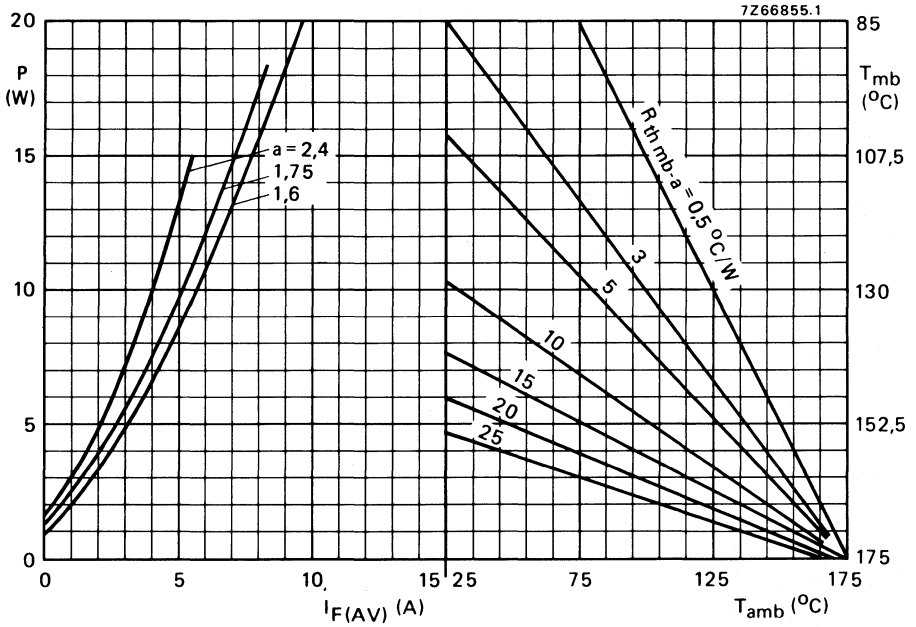


Fig.2

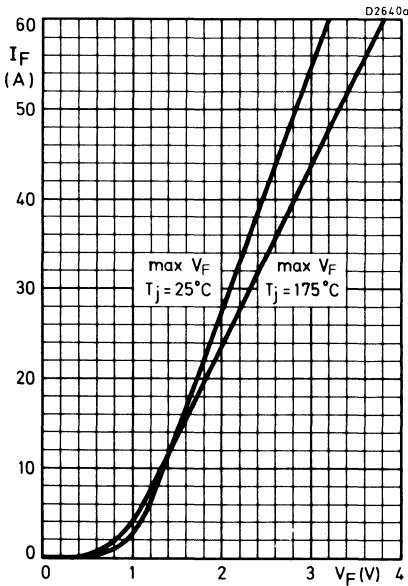


Fig.3

The right-hand part shows the inter-relationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = dissipation excluding power in the avalanche region.

single phase: $a = 1.6$

3-phase : $a = 1.75$

6-phase : $a = 2.4$

$$a = I_F(RMS)/I_F(AV)$$

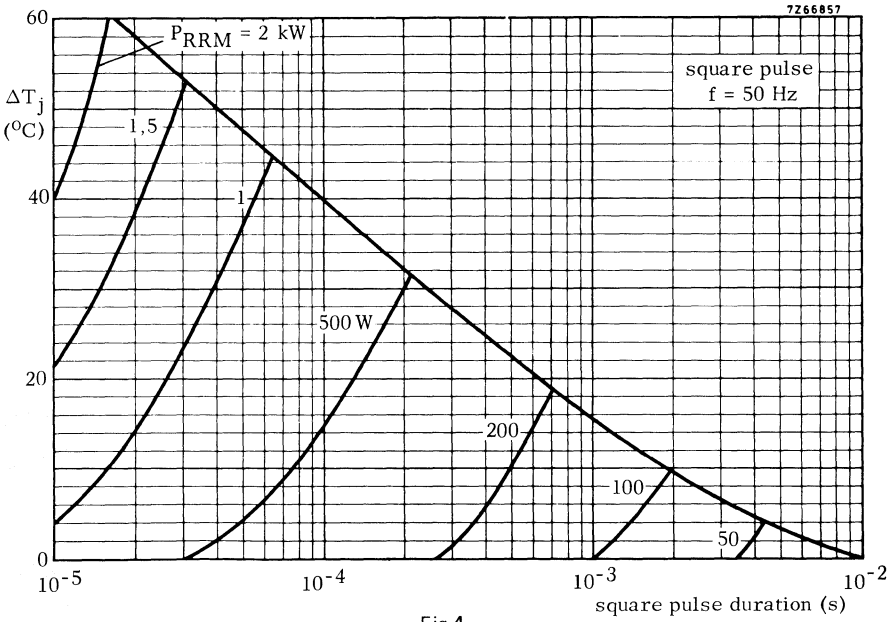


Fig.4

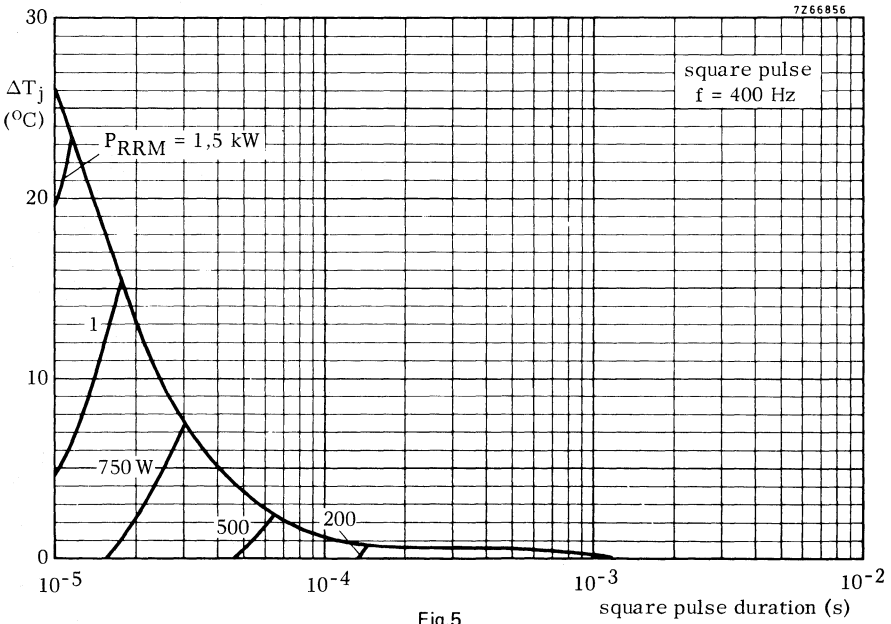


Fig.5

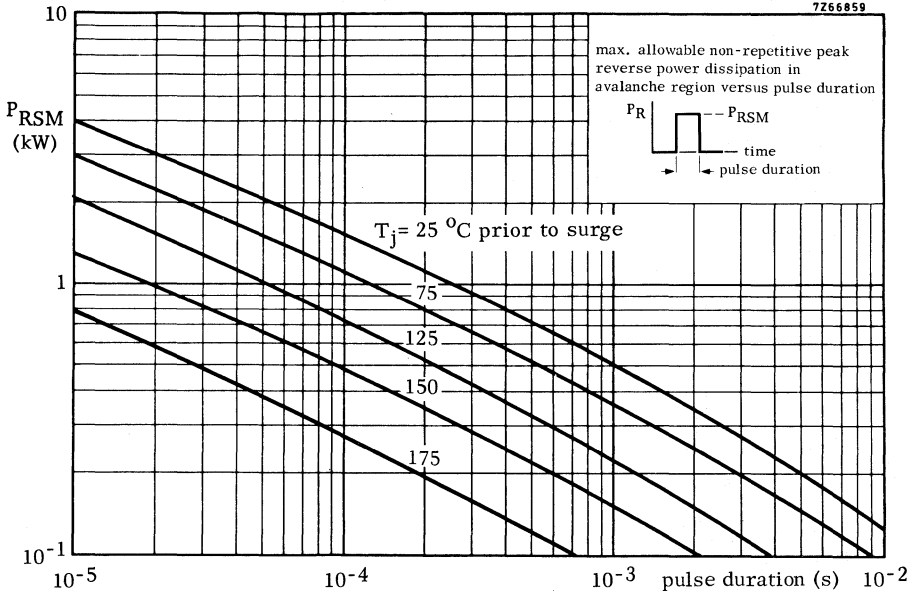


Fig.6

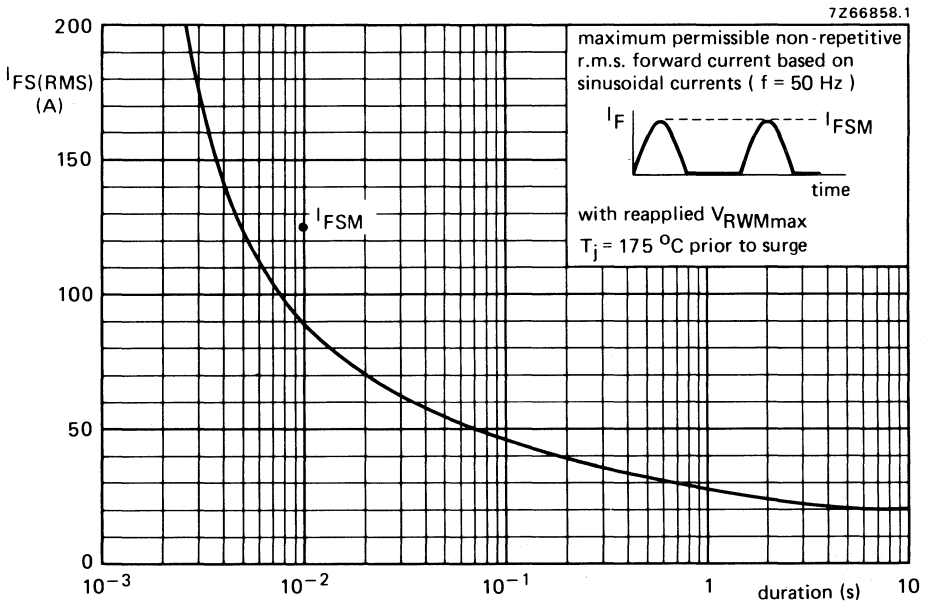


Fig.7

SILICON RECTIFIER DIODES



Diffused silicon rectifier diodes in DO-4 metal envelopes, intended for power rectifier applications.
 The series consists of the following types:
 Normal polarity (cathode to stud): BYX42-300 to 1200.
 Reserve polarity (anode to stud): BYX42-300R to 1200R.

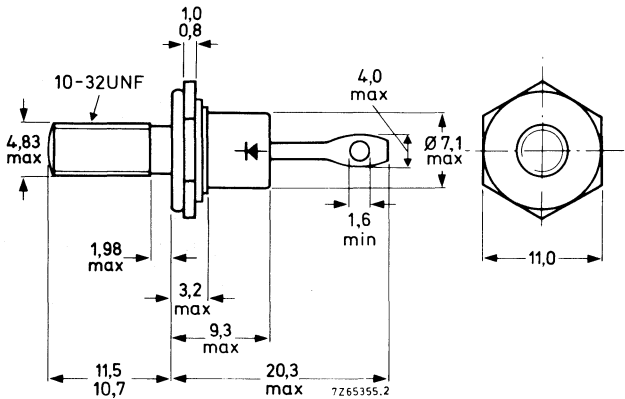
QUICK REFERENCE DATA

		BYX42-300(R)	600(R)	1200(R)
Repetitive peak reverse voltage	V_{RRM}	max. 300	600	1200 V
Average forward current	$I_{F(AV)}$	max. 12		A
Non-repetitive peak forward current	I_{FSM}	max. 125		A

MECHANICAL DATA

Dimensions in mm

DO-4



Net mass: 6 g

Diameter of clearance hole: 5,2 mm

Accessories supplied on request:
 see ACCESSORIES section

Torque on nut: min. 0,9 Nm
 (9 kg cm)
 max. 1,7 Nm
 (17 kg cm)

Supplied with device: 1 nut, 1 lock washer
 Nut dimensions across the flats: 9,5 mm
 The mark shown applies to normal polarity types.

Products approved to CECC 50 009-020 available on request.

BYX42 SERIES

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		BYX42-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM}	max. 300	600	1200	V
Repetitive peak reverse voltage ($\delta \leq 0,01$)	V_{RRM}	max. 300	600	1200	V
Crest working reverse voltage	V_{RWM}	max. 200	400	800	V
Continuous reverse voltage	V_R	max. 200	400	800	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 115$ °C	$I_{F(AV)}$	max.	12	A
	$I_{F(AV)}$	max.	10	A
R. M. S. forward current	$I_F(RMS)$	max.	20	A
Repetitive peak forward current	I_{FRM}	max.	60	A
Non-repetitive peak forward current ($t = 10$ ms; half sine-wave) $T_j = 175$ °C prior to surge; with reapplied V_{RWMmax}	I_{FSM}	max.	125	A

Temperatures

Storage temperature	T_{stg}	-55 to +175	°C
Junction temperature	T_j	max. 175	°C

THERMAL RESISTANCE

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	3	°C/W
From mounting base to heatsink	$R_{th mb-h}$	=	0,5	°C/W

CHARACTERISTICS

<u>Forward voltage</u> at $I_F = 15$ A; $T_j = 25$ °C	V_F	<	1,4	V ¹⁾
<u>Reverse current</u> at $V_R = V_{RWMmax}$; $T_j = 125$ °C	I_R	<	200	µA

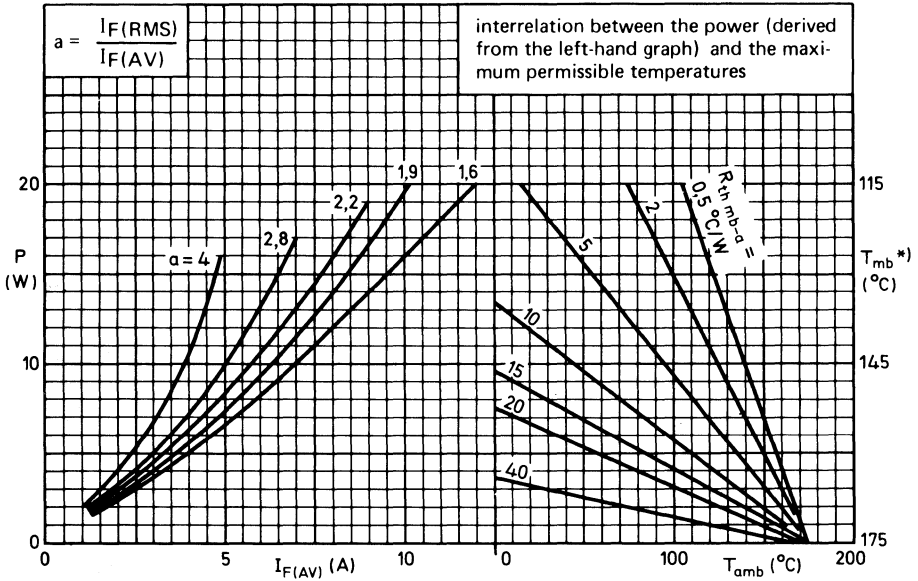
MOUNTING INSTRUCTIONS

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

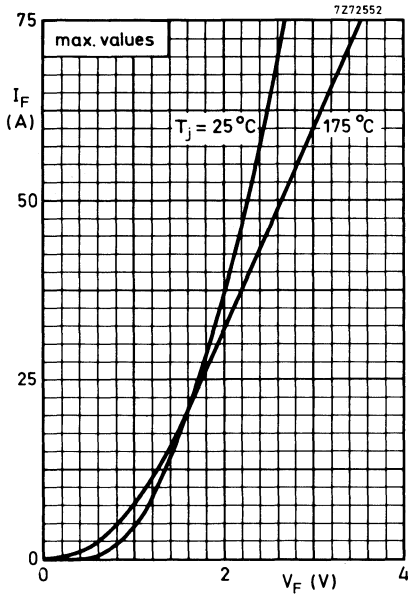
During soldering the heat conduction to the junction should be kept to a minimum.

¹⁾ Measured under pulse conditions to avoid excessive dissipation.

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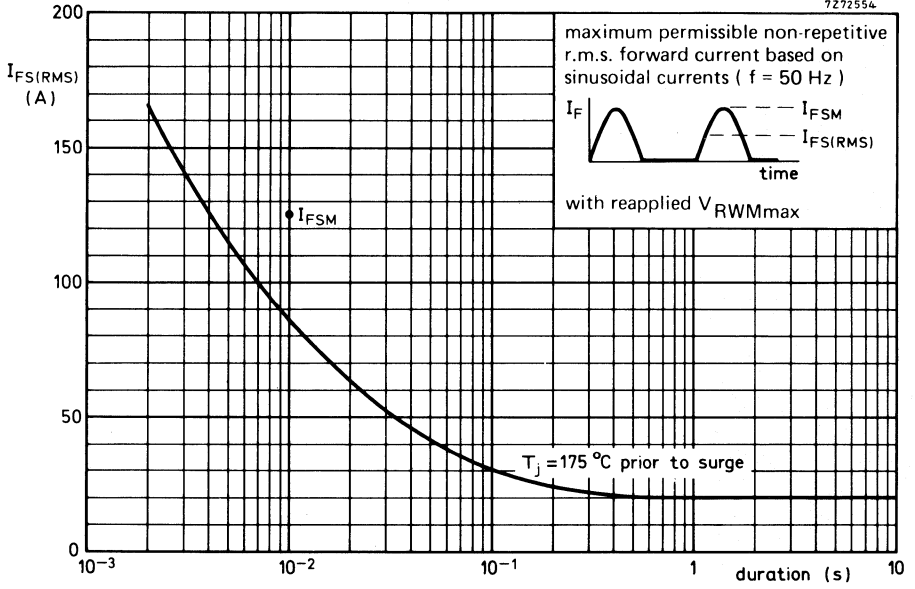


*) T_{mb} -scale is for comparison purposes only and is correct only for $R_{th mb-a} \leq 22 \text{ } ^\circ\text{C/W}$



BYX42
SERIES

7272554



RECTIFIER DIODES



Silicon rectifier diodes in DO-5 metal envelopes, intended for use in power rectifier applications.
 The series consists of the following types:
 Normal polarity (cathode to stud): BYX52-300, BYX52-600, BYX52-1200.
 Reverse polarity (anode to stud): BYX52-300R, BYX52-600R, BYX52-1200R.

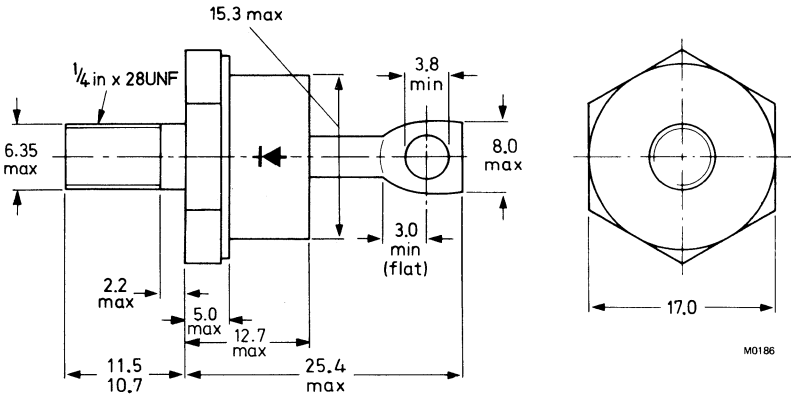
QUICK REFERENCE DATA

	V_{RRM}	BYX52-300(R) 600(R) 1200(R)			V
		max.	300	600	
Repetitive peak reverse voltage					
Average forward current		$I_F(AV)$	max.	48	A
Non-repetitive peak forward current		I_{FSM}	max.	800	A

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5 Supplied with device: 1 nut, 1 lock-washer
 Nut dimensions across the flats: 11.1 mm



Net mass: 22 g
 Diameter of clearance hole: max. 6.5 mm
 Accessories supplied on request:
 see ACCESSORIES section

Torque on nut: min. 1.7 Nm
 (17 kg cm)
 max. 3.5 Nm
 (35 kg cm)

The mark shown applies to the normal polarity types

Products approved to CECC 50 009-024 available on request.

BYX52 SERIES

RATINGS

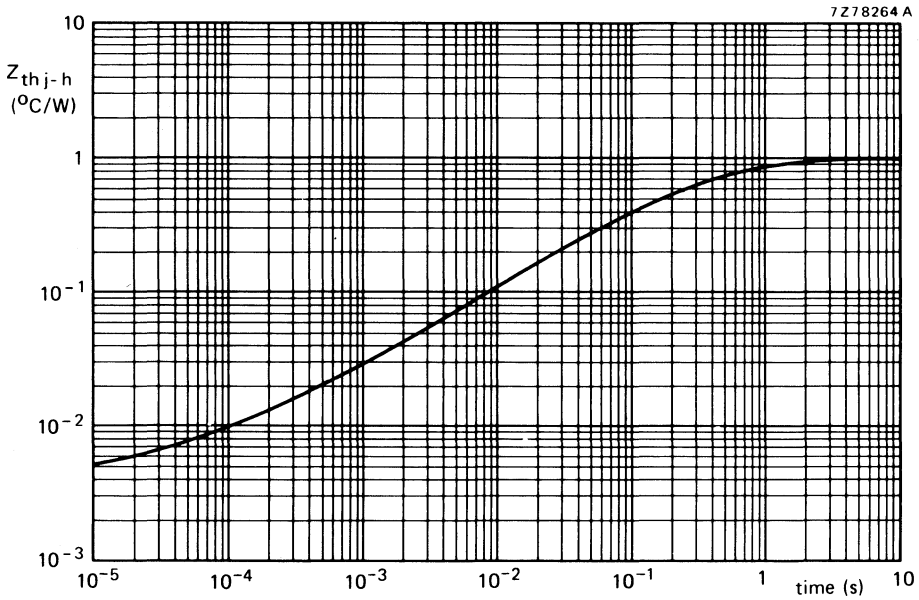
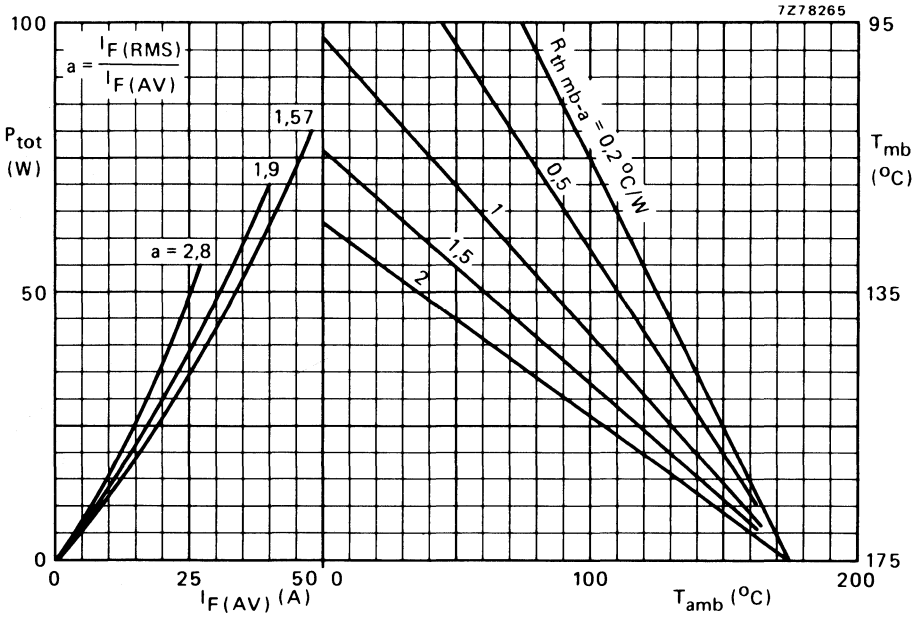
Limiting values in accordance with the Absolute Maximum System (IEC134).

Voltages		BYX52-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM}	max. 300	600	1200	V
Repetitive peak reverse voltage ($\delta = 0.01$)	V_{RRM}	max. 300	600	1200	V
Crest working reverse voltage	V_{RWM}	max. 200	400	800	V
Currents					
Average forward current (averaged over any 20 ms period) up to $T_{mb} = 112$ °C		$I_F(AV)$	max. 48		A
		$I_F(AV)$	max. 40		A
R.M.S. forward current		$I_F(RMS)$	max. 75		A
Repetitive peak forward current		I_{FRM}	max. 450		A
Non-repetitive peak forward current ($t = 10$ ms; half-sinewave) $T_j = 175$ °C prior to surge		I_{FSM}	max. 800		A
$I^2 t$ for fusing ($t = 10$ ms)		$I^2 t$	max. 3200		A ² s
Temperatures					
Storage temperature		T_{stg}	-55 to +175		°C
Junction temperature		T_j	max. 175		°C
THERMAL RESISTANCE					
From junction to mounting base		$R_{th j-mb}$	= 0.8		°C/W
From mounting base to heatsink		$R_{th mb-h}$	= 0.2		°C/W
CHARACTERISTICS					
Forward voltage		V_F	< 1.8		V*
Reverse current		I_R	< 1.6		mA
$V_R = V_{RWM} \text{ max}; T_j = 125$ °C					

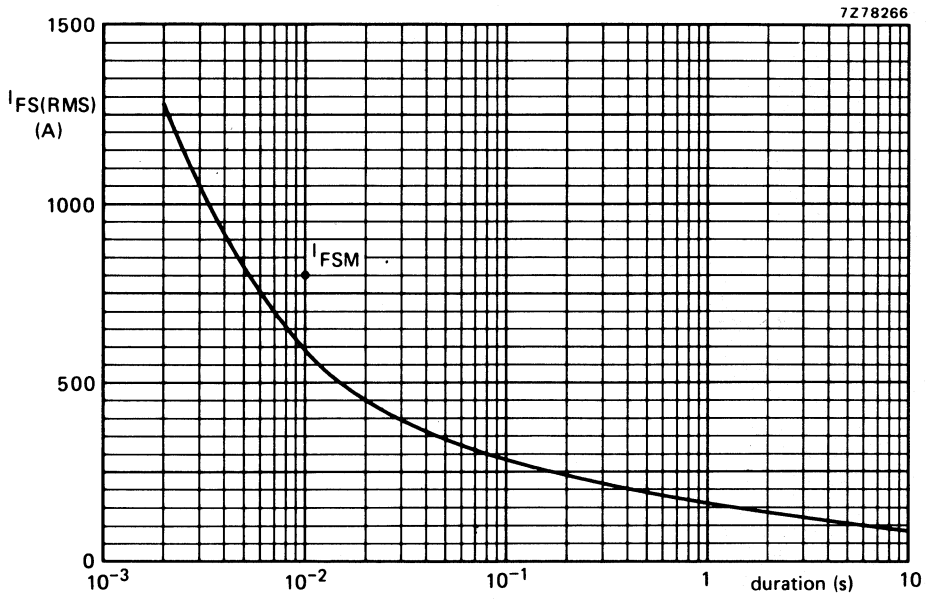
OPERATING NOTE

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

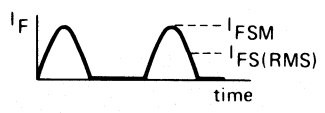
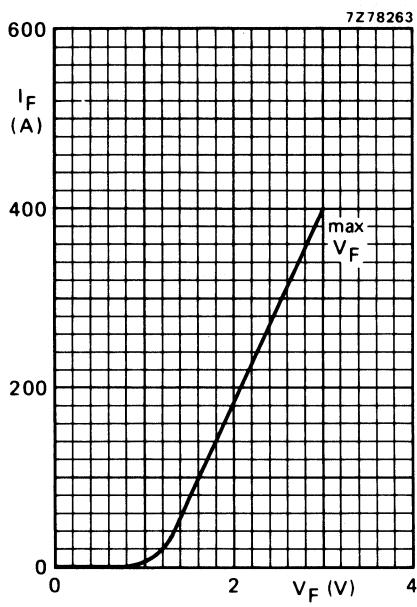
*Measured under pulse conditions to avoid excessive dissipation.



BYX52 SERIES



Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 175$ °C prior to surge; with reapplied V_{RWMmax} .



CONTROLLED AVALANCHE RECTIFIER DIODES



Silicon diodes in a DO-5 metal envelope, capable of absorbing transients and intended for power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX56-600 to BYX56-1400.

Reverse polarity (anode to stud): BYX56-600R to BYX56-1400R.

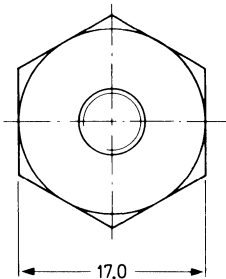
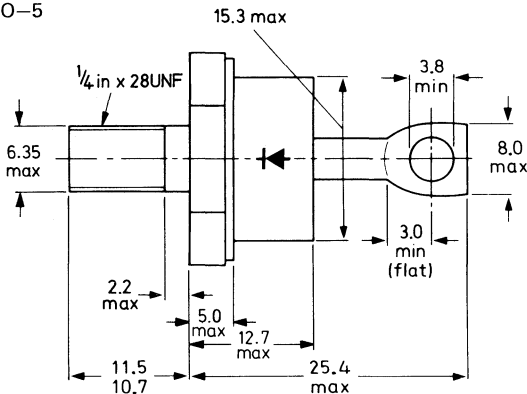
QUICK REFERENCE DATA

		BYX56-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	V_{RWM}	max. 600	800	1000	1200	1400	V
Reverse avalanche breakdown voltage	$V_{(BR)R}$	> 750	1000	1250	1450	1650	V
Average forward current	$I_F(AV)$	max. 48					A
Non-repetitive peak forward current	I_{FSM}	max. 800					A
Non-repetitive peak reverse power dissipation	P_{RSM}	max. 40					kW

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-5



M0186

Net mass: 22 g

Diameter of clearance hole: max. 6.5 mm

Accessories supplied on request:

see ACCESSORIES section

Supplied with device: 1 nut, 1 lock washer.

Nut dimensions across the flats: 11.1 mm.

Torque on nut:

min. 1.7 Nm (17 kg cm),

max. 2.5 Nm (25 kg cm).

The mark shown applies to normal polarity types.

Products approved to CECC 50 009-023 available on request.

BYX56 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

Voltages*		BYX56-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Crest working reverse voltage	V_{RWM}	max. 600	800	1000	1200	1400	V
Continuous reverse voltage	V_R	max. 600	800	1000	1200	1400	V

Currents

Average forward current

(averaged over any 20 ms period)

up to $T_{mb} = 112^\circ\text{C}$

at $T_{mb} = 125^\circ\text{C}$

$I_F(AV)$ max. 48 A

$I_F(AV)$ max. 40 A

R.M.S. forward current

$I_F(RMS)$ max. 75 A

Repetitive peak forward current

I_{FRM} max. 450 A

Non-repetitive peak forward current

$t = 10$ ms (half sine-wave);

$T_j = 175^\circ\text{C}$ prior to surge;

with reapplied V_{RWMmax}

I_{FSM} max. 800 A

$I^2 t$ for fusing ($t \leq 10$ ms)

$I^2 t$ max. 3200 A^2s

Reverse power dissipation

Repetitive peak reverse power dissipation

$t = 10$ μs (square-wave; $f = 50$ Hz);

$T_j = 175^\circ\text{C}$

P_{RRM} max. 6.5 kW

Non-repetitive peak reverse power dissipation

$t = 10$ μs (square-wave)

$T_j = 25^\circ\text{C}$ prior to surge

$T_j = 175^\circ\text{C}$ prior to surge

P_{RSM} max. 40 kW

P_{RSM} max. 6.5 kW

Temperatures

Storage temperature

T_{stg} -55 to +175 $^\circ\text{C}$

Junction temperature

T_j max. 175 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base

$R_{th j-mb} = 0.8$ $^\circ\text{C/W}$

From mounting base to heatsink

$R_{th mb-h} = 0.2$ $^\circ\text{C/W}$

Transient thermal impedance; $t = 1$ ms

$Z_{th j-h} = 0.03$ $^\circ\text{C/W}$

*To ensure thermal stability: $R_{th j-a} < 2.2$ $^\circ\text{C/W}$ (a.c.)

CHARACTERISTICS

	BYX56-600(R)	800(R)	1000(R)	1200(R)	1400(R)	
Forward voltage $I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$ V_F	< 1.8	1.8	1.8	1.8	1.8	V*
Reverse avalanche breakdown voltage $I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$ $V_{(BR)R}$	> 750	1000	1250	1450	1650	V
	< 2400	2400	2400	2400	2400	V
Reverse current $V_R = V_{RWMmax};$ $T_j = 125 \text{ }^\circ\text{C}$ I_R	< 1.6	1.6	1.6	1.6	1.6	mA

OPERATING NOTES

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum by using a thermal shunt.

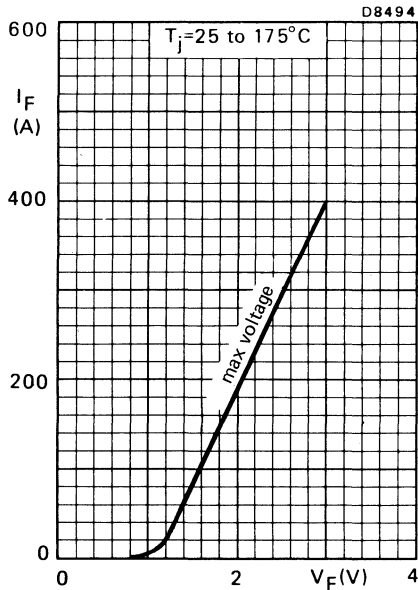


Fig.2

*Measured under pulsed conditions to avoid excessive dissipation.

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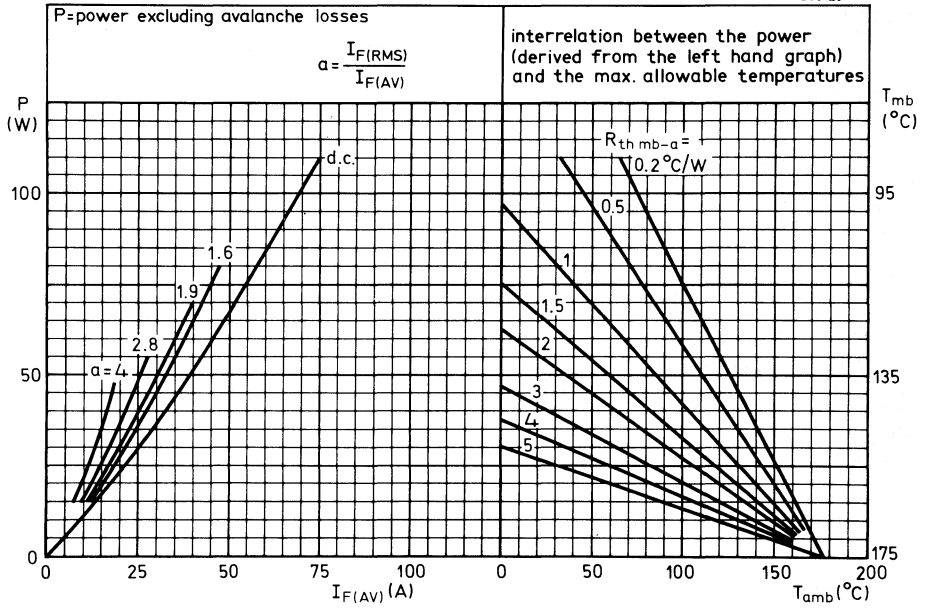


Fig.3

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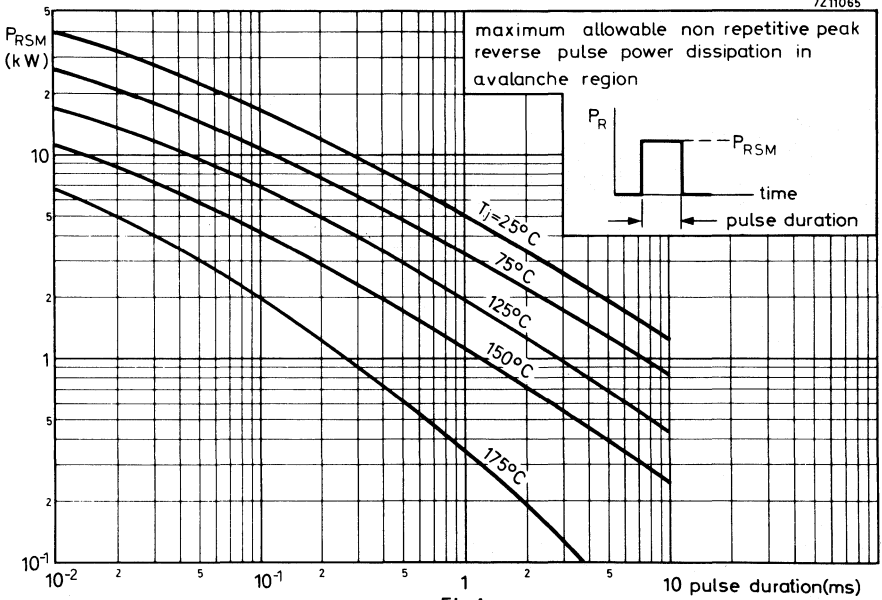


Fig.4

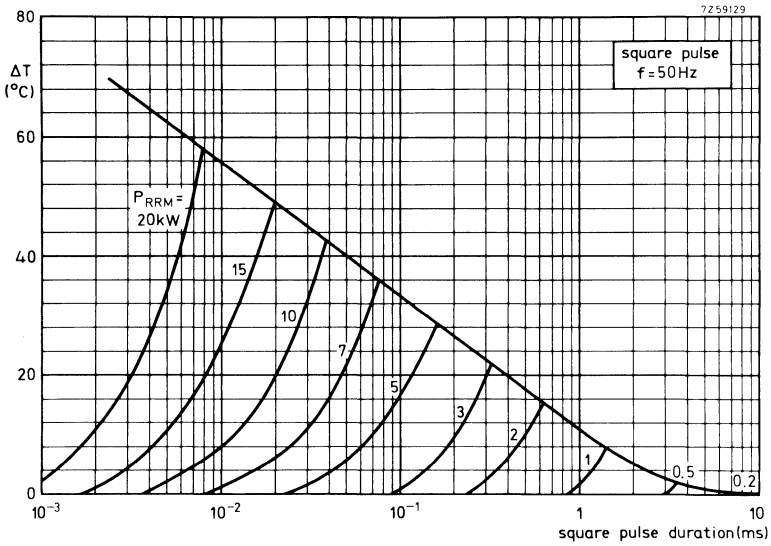


Fig.5

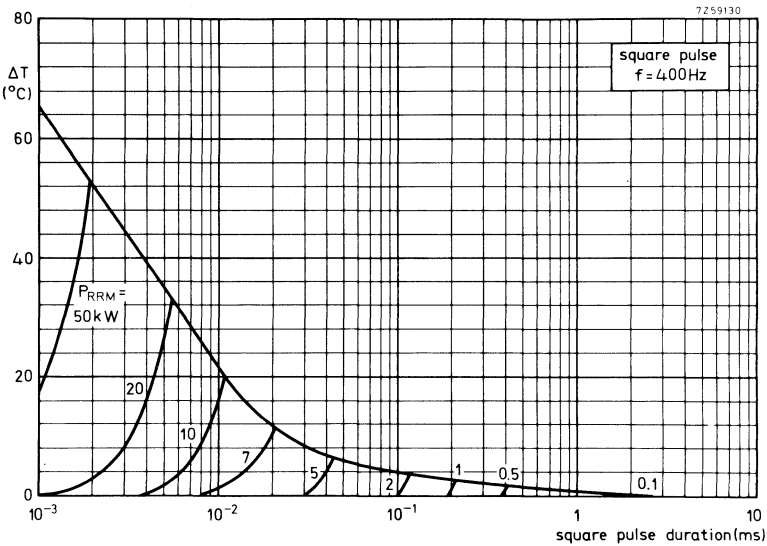


Fig.6

ΔT = necessary derating of T_{jmax} to accommodate repetitive transients in the reverse direction. Allowance can be made for this by assuming the ambient temperature ΔT higher.

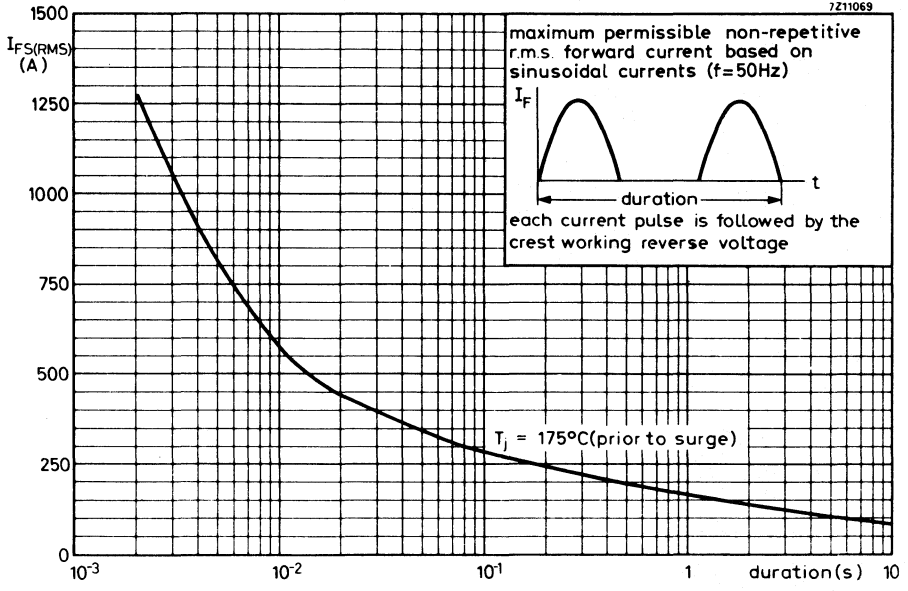


Fig.7

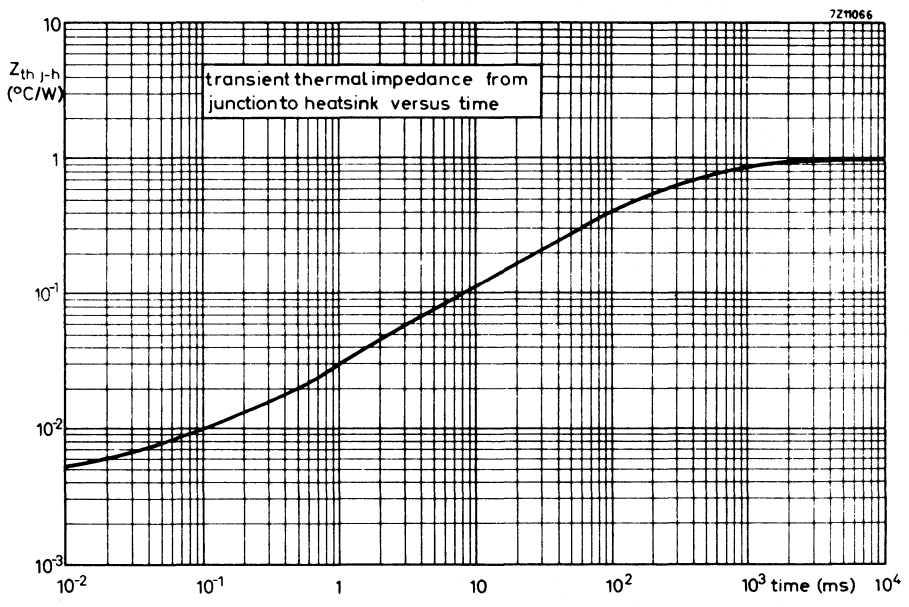


Fig.8

RECTIFIER DIODES

Also available to BS9331-F129

Silicon rectifier diodes in metal envelopes similar to DO-4, intended for use in power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX96-300 to 1600.

Reverse polarity (anode to stud): BYX96-300R to 1600R.

QUICK REFERENCE DATA

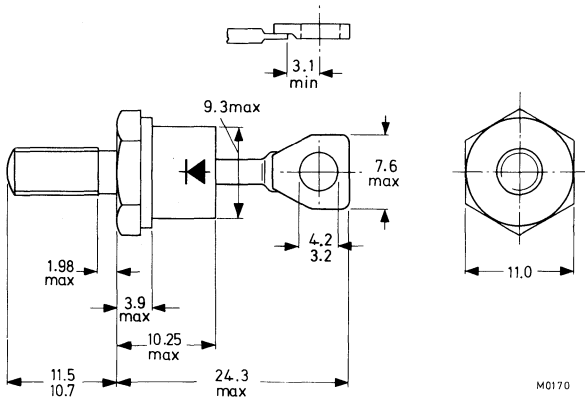
		BYX96-300(R)	600(R)	1200(R)	1600(R)	
Repetitive peak reverse voltage	V_{RRM}	max. 300	600	1200	1600	V
Average forward current	$I_F(AV)$		max.		30	A
Non-repetitive peak forward current	I_{FSM}		max.		400	A

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4: with metric M5 stud (ϕ 5 mm); e.g. BYX96-300(R).

Types with 10-32 UNF stud (ϕ 4,83 mm) are available on request. These are indicated by the suffix U; e.g. BYX96-300U(RU).



Supplied with device: 1 nut, 1 lock-washer

Nut dimensions across the flats, M5 thread: 8 mm, 10-32 UNF thread: 9.5 mm

Net mass: 7 g

Diameter of clearance hole: max. 5.2 mm

Supplied on request: see ACCESSORIES section
a version with insulated flying leads

The mark shown applies to normal polarity types.

Torque on nut: min. 0.9 Nm
(9 kg cm)
max. 1.7 Nm
(17 kg cm)

BYX96 SERIES

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u> ¹⁾		BYX96-300(R)	600(R)	1200(R)	1600(R)	
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM}	max. 300	600	1200	1600	V
Repetitive peak reverse voltage ($\delta \leq 0,01$)	V_{RRM}	max. 300	600	1200	1600	V
Crest working reverse voltage	V_{RWM}	max. 200	400	800	800	V
Continuous reverse voltage	V_R	max. 200	400	800	800	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 125$ °C	$I_{F(AV)}$	max.	30	A
R.M.S. forward current	$I_{F(RMS)}$	max.	48	A
Repetitive peak forward current	I_{FRM}	max.	400	A
Non-repetitive peak forward current ($t = 10$ ms; half sine-wave) $T_j = 175$ °C prior to surge; with reapplied V_{RWMmax}	I_{FSM}	max.	400	A
I^2t for fusing ($t = 10$ ms)	I^2t	max.	800	A ² s

Temperatures

Storage temperature	T_{stg}	-55 to +175	°C
Junction temperature	T_j	max. 175	°C

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	1,0	°C/W
From mounting base to heatsink without heatsink compound	$R_{th\ mb-h}$	=	0,5	°C/W
with heatsink compound	$R_{th\ mb-h}$	=	0,3	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th\ j-mb}$	=	0,2	°C/W

¹⁾ To ensure thermal stability: $R_{th\ j-a} \leq 2$ °C/W (continuous reverse voltage) or ≤ 8 °C/W (a.c.)

For smaller heatsinks $T_{j\ max}$ should be derated. For a.c. see page 4.

For continuous reverse voltage: if $R_{th\ j-a} = 4$ °C/W, then $T_{j\ max} = 138$ °C,
if $R_{th\ j-a} = 6$ °C/W, then $T_{j\ max} = 125$ °C.

CHARACTERISTICSForward voltage

$$I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 1,7 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

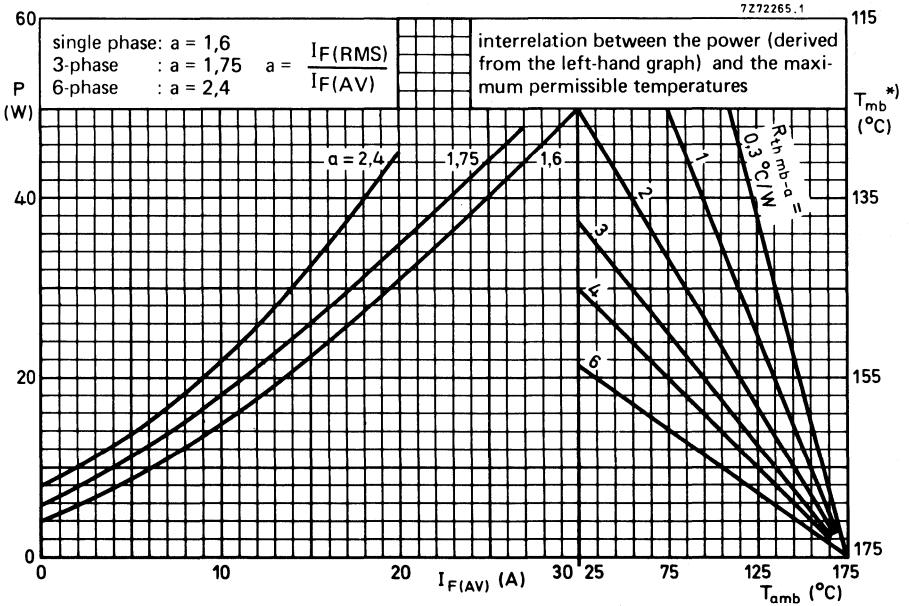
$$I_R < 1 \text{ mA}$$

OPERATING NOTES

1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits.

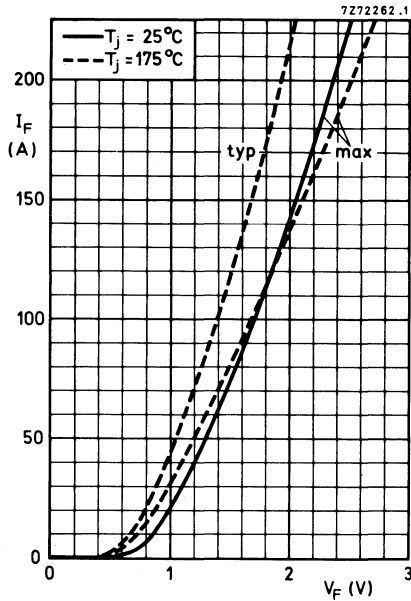
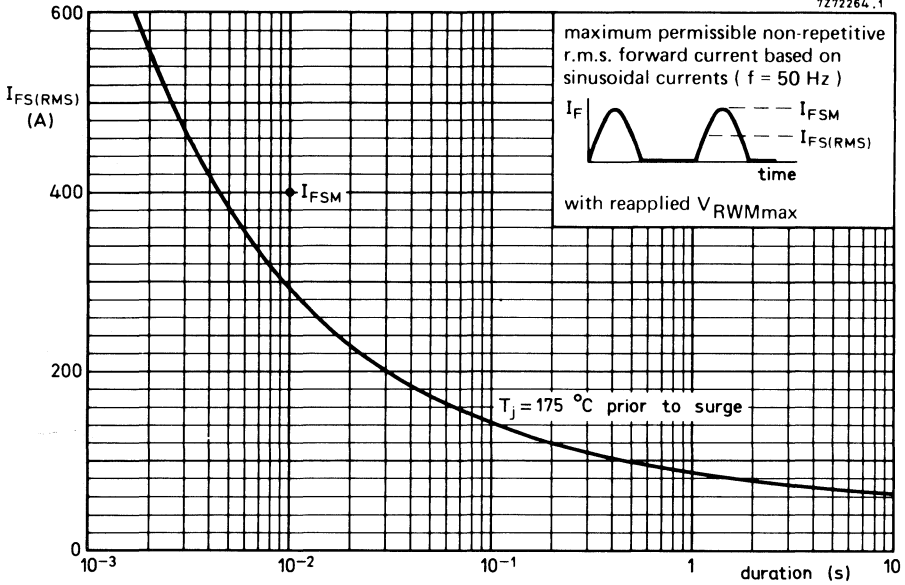
¹⁾ Measured under pulse conditions to avoid excessive dissipation.

BYX96
SERIES

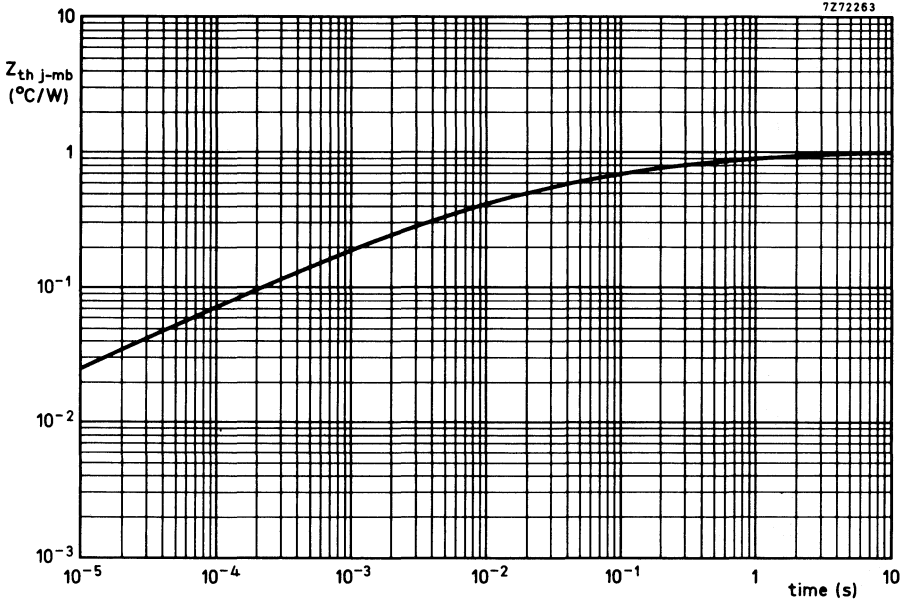


*) T_{mb} -scale is for comparison purposes only and is correct only for $R_{th\ mb-a} \leq 6,5\ C/W$

7272264.1



BYX96
SERIES



RECTIFIER DIODES

Also available to BS9331-F130

Silicon rectifier diodes in metal envelopes similar to DO-5, intended for use in power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX97-300 to 1600.

Reverse polarity (anode to stud): BYX97-300R to 1600R.

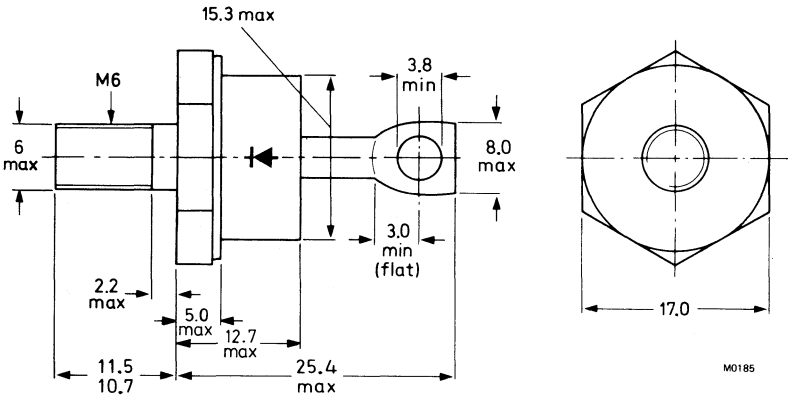
QUICK REFERENCE DATA

		BYX97-300(R)	600(R)	1200(R)	1600(R)	
Repetitive peak reverse voltage	V_{RRM}	max. 300	600	1200	1600	V
Average forward current	$I_F(AV)$		max.		47	A
Non-repetitive peak forward current	I_{FSM}		max.		800	A

MECHANICAL DATA

Dimensions in mm

DO-5 (except for M6 stud); Supplied with device: 1 nut, 1 lock-washer
Nut dimensions across the flats: 10 mm



Net mass: 22 g .

Diameter of clearance hole: max. 6.5 mm

Supplied on request: see ACCESSORIES section
a version with insulated flying leads

The mark shown applies to normal polarity types.

Torque on nut: min. 1.7 Nm
(17 kg cm)
max. 3.5 Nm
(35 kg cm)

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages ¹⁾		BYX97-300(R)	600(R)	1200(R)	1600(R)	
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM}	max. 300	600	1200	1600	V
Repetitive peak reverse voltage ($\delta \leq 0,01$)	V_{RRM}	max. 300	600	1200	1600	V
Crest working reverse voltage	V_{RWM}	max. 200	400	800	800	V
Continuous reverse voltage	V_R	max. 200	400	800	800	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 120$ °C at $T_{mb} = 125$ °C	$I_F(AV)$	max.	47	A
	$I_F(AV)$	max.	40	A
R. M. S. forward current	$I_F(RMS)$	max.	75	A
Repetitive peak forward current	I_{FRM}	max.	550	A
Non-repetitive peak forward current ($t = 10$ ms; half sine-wave) $T_j = 150$ °C prior to surge; with reapplied V_{RWMmax}	I_{FSM}	max.	800	A
I^2t for fusing ($t = 10$ ms)	I^2t	max.	3200	A ² s

Temperatures

Storage temperature	T_{stg}	-55 to +150	°C
Junction temperature	T_j	max. 150	°C

THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	0,6	°C/W
From mounting base to heatsink without heatsink compound	$R_{th mb-h}$	=	0,3	°C/W
with heatsink compound	$R_{th mb-h}$	=	0,2	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0,1	°C/W

1) To ensure thermal stability: $R_{th j-a} \leq 1$ °C/W (continuous reverse voltage) or ≤ 4 °C/W (a.c.)

For smaller heatsinks $T_{j max}$ should be derated. For a.c. see page 90.

For continuous reverse voltage: if $R_{th j-a} = 2$ °C/W, then $T_{j max} = 138$ °C,
if $R_{th j-a} = 3$ °C/W, then $T_{j max} = 125$ °C.

CHARACTERISTICSForward voltage

$$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 1,45 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

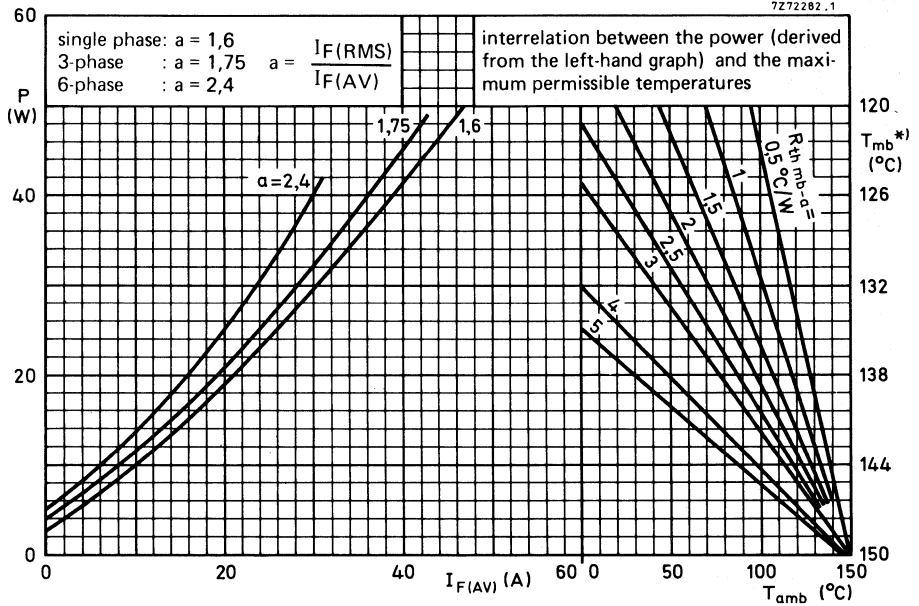
$$I_R < 4 \text{ mA}$$

OPERATING NOTES

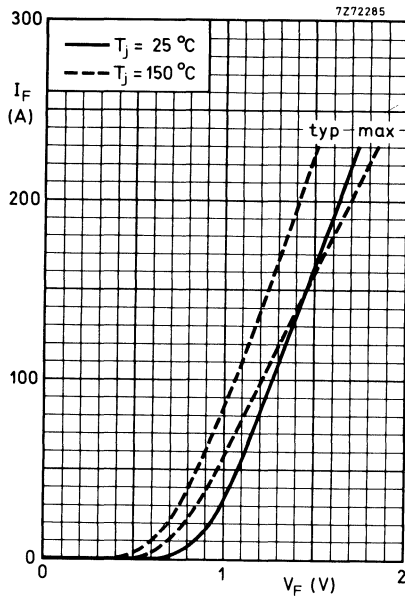
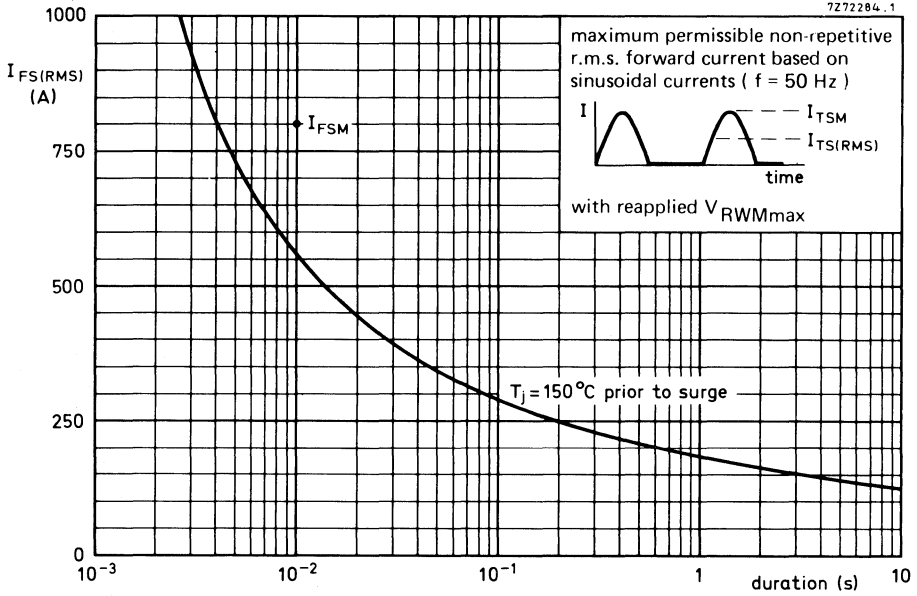
1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits.

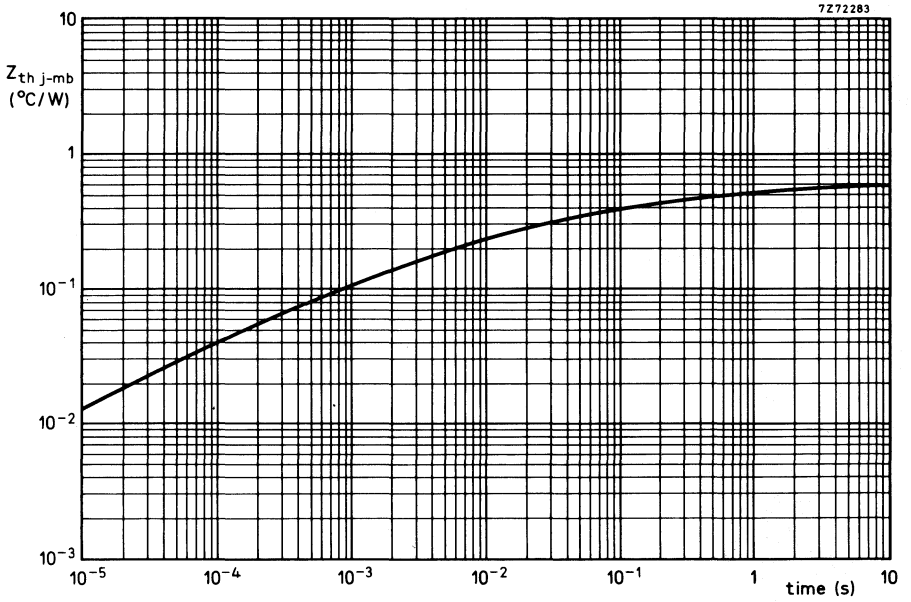
¹⁾ Measured under pulse conditions to avoid excessive dissipation.

**BYX97
SERIES**



*) T_{mb} -scale is for comparison purposes only and is correct only for $R_{th\ mb-a} \leq 3,4$ $^{\circ}C/W$





RECTIFIER DIODES



Silicon rectifier diodes in DO-4 metal envelopes, intended for use in power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX98-300 to 1200.

Reverse polarity (anode to stud): BYX98-300R to 1200R.

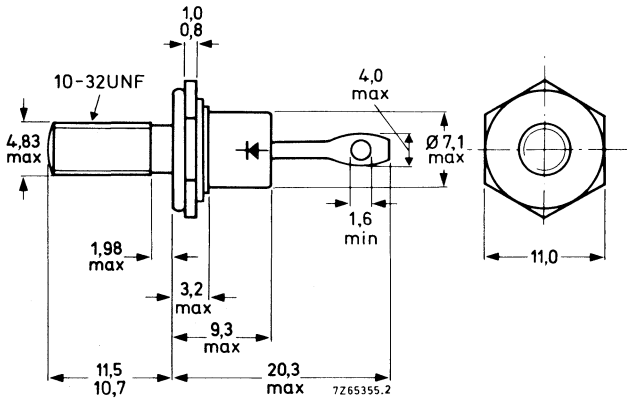
QUICK REFERENCE DATA

		BYX98-300(R)	600(R)	1200(R)	
Repetitive peak reverse voltage	V_{RRM}	max. 300	600	1200	V
Average forward current	$I_F(AV)$		max. 10		A
Non-repetitive peak forward current	I_{FSM}		max. 75		A

MECHANICAL DATA

Dimensions in mm

DO-4: Supplied with device: 1 nut, 1 lock-washer
 Nut dimensions across the flats: 9.5 mm



Net mass: 6 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:
 see ACCESSORIES section

The mark shown applies to normal polarity types.

Torque on nut: min. 0.9 Nm
 (9 kg cm)
 max. 1.7 Nm
 (17 kg cm)

BYX98 SERIES

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		BYX98-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM}	max. 300	600	1200	V
Repetitive peak reverse voltage ($\delta \leq 0.01$)	V_{RRM}	max. 300	600	1200	V
Crest working reverse voltage	V_{RWM}	max. 200	400	800	V
Continuous reverse voltage	V_R	max. 200	400	800	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 97$ °C at $T_{mb} = 125$ °C	$I_F(AV)$	max.	10	A
	$I_F(AV)$	max.	6	A
R. M. S. forward current	$I_F(RMS)$	max.	16	A
Repetitive peak forward current	I_{FRM}	max.	75	A
Non-repetitive peak forward current ($t = 10$ ms; half sine-wave) $T_j = 150$ °C prior to surge; with reapplied V_{RWMmax}	I_{FSM}	max.	75	A
I^2t for fusing ($t = 10$ ms)	I^2t	max.	28	A ² s

Temperatures

Storage temperature	T_{stg}	-55 to +150	°C
Junction temperature	T_j	max. 150	°C

THERMAL RESISTANCE

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	3	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0,5	°C/W
without heatsink compound	$R_{th mb-h}$	=	0,6	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0,3	°C/W

CHARACTERISTICS

Forward voltage

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1,7 \text{ V } 1)$

Reverse current

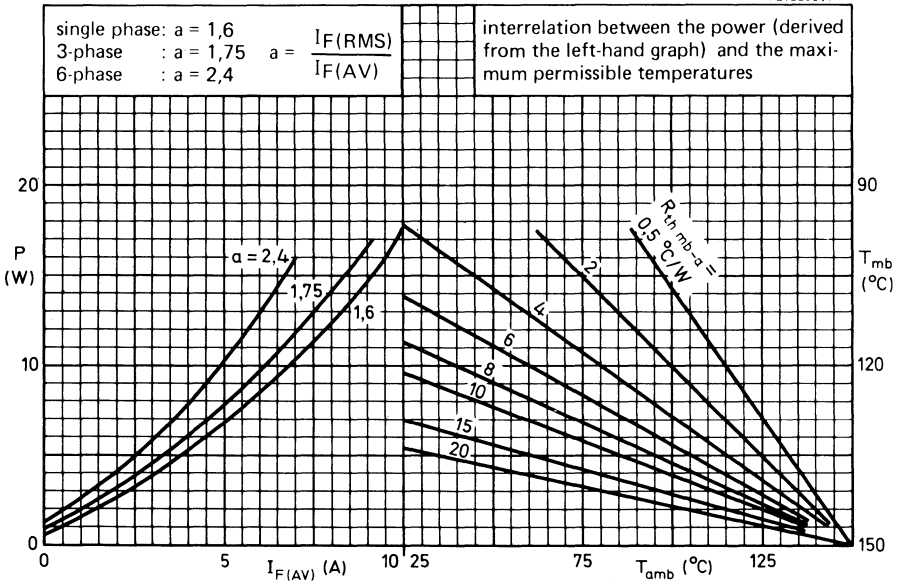
$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 200 \text{ } \mu\text{A}$

OPERATING NOTES

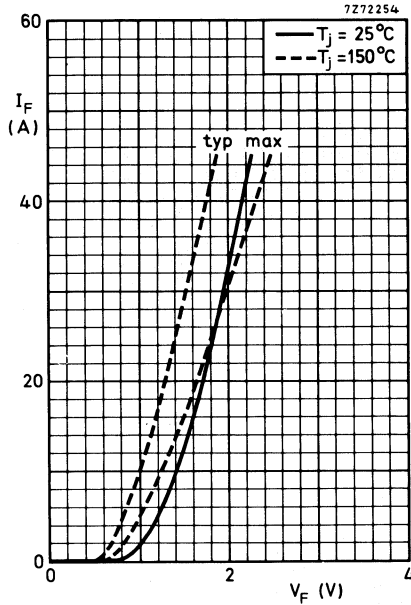
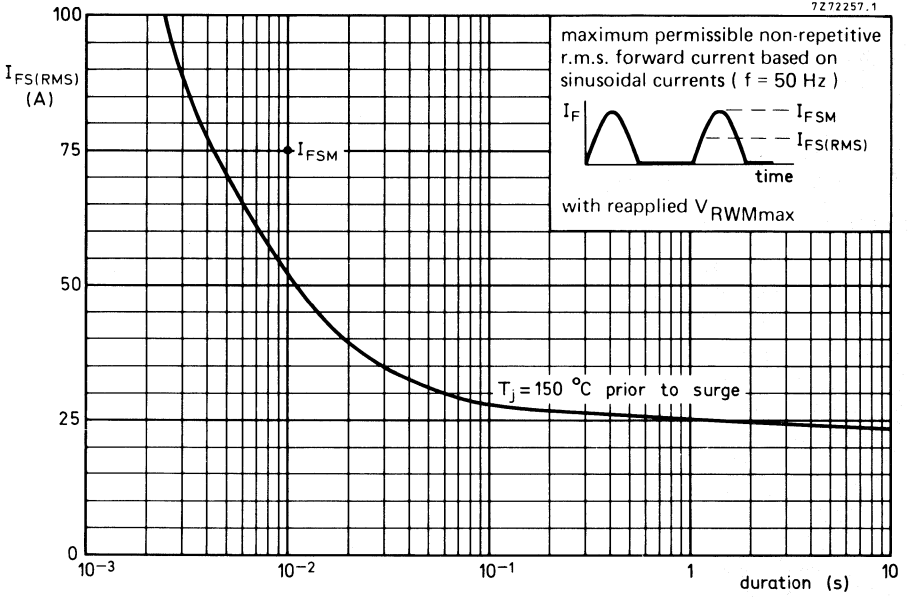
1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits.

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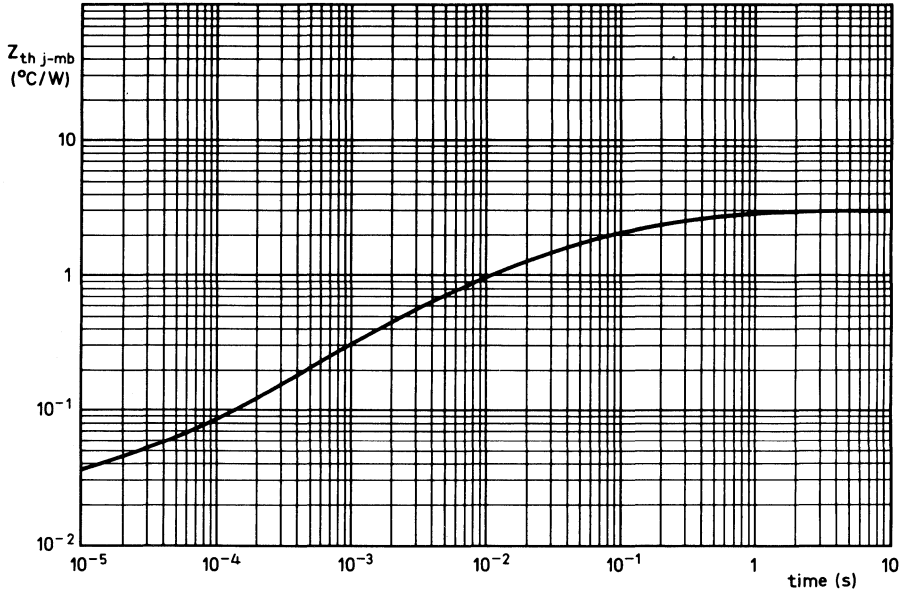


1) Measured under pulse conditions to avoid excessive dissipation.

**BYX98
SERIES**



7272255



RECTIFIER DIODES



Silicon rectifier diodes in DO-4 metal envelopes, intended for use in power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX99-300 to 1200.

Reverse polarity (anode to stud): BYX99-300R to 1200R.

QUICK REFERENCE DATA

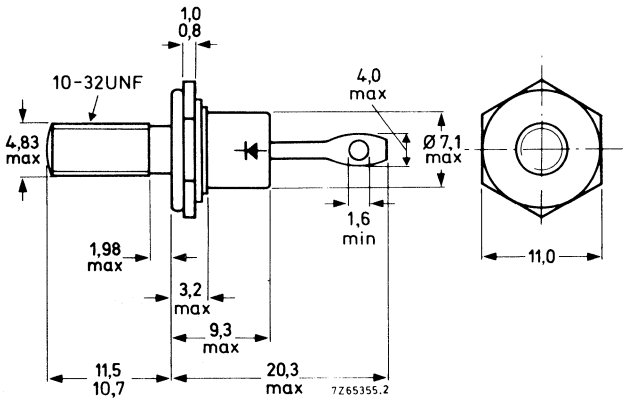
		BYX99-300(R)	600(R)	1200(R)	
Repetitive peak reverse voltage	V_{RRM}	max. 300	600	1200	V
Average forward current	$I_{F(AV)}$		max. 15		A
Non-repetitive peak forward current	I_{FSM}		max. 180		A

MECHANICAL DATA

Dimensions in mm

DO-4: Supplied with device: 1 nut, 1 lock-washer

Nut dimensions across the flats: 9.5 mm



Net mass: 6 g

Diameter of clearance hole: 5.2 mm

Accessories supplied on request:

see ACCESSORIES section

The mark shown applies to normal polarity types.

Torque on nut: min. 0.9 Nm

(9 kg cm)

max. 1.7 Nm

(17 kg cm)

BYX99 SERIES

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC 134)

<u>Voltages</u>		BYX99-300(R)	600(R)	1200(R)	
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM}	max. 300	600	1200	V
Repetitive peak reverse voltage ($\delta \leq 0,01$)	V_{RRM}	max. 300	600	1200	V
Crest working reverse voltage	V_{RWM}	max. 200	400	800	V
Continuous reverse voltage	V_R	max. 200	400	800	V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 129$ °C	$I_{F(AV)}$	max.	15	A
R.M.S. forward current	$I_{F(RMS)}$	max.	24	A
Repetitive peak forward current	I_{FRM}	max.	180	A
Non-repetitive peak forward current ($t = 10$ ms; half sine-wave) $T_j = 175$ °C prior to surge; with reapplied V_{RWMmax}	I_{FSM}	max.	180	A
I^2t for fusing ($t = 10$ ms)	I^2t	max.	162	A ² s

Temperatures

Storage temperature	T_{stg}	-55 to +175	°C
Junction temperature	T_j	max. 175	°C

THERMAL RESISTANCE

From junction to ambient in free air	$R_{th j-a}$	=	50	°C/W
From junction to mounting base	$R_{th j-mb}$	=	2, 3	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0, 5	°C/W
without heatsink compound	$R_{th mb-h}$	=	0, 6	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0, 13	°C/W

CHARACTERISTICSForward voltage

$$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_F < 1,55 \text{ V } ^1)$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C} \qquad I_R < 200 \text{ } \mu\text{A}$$

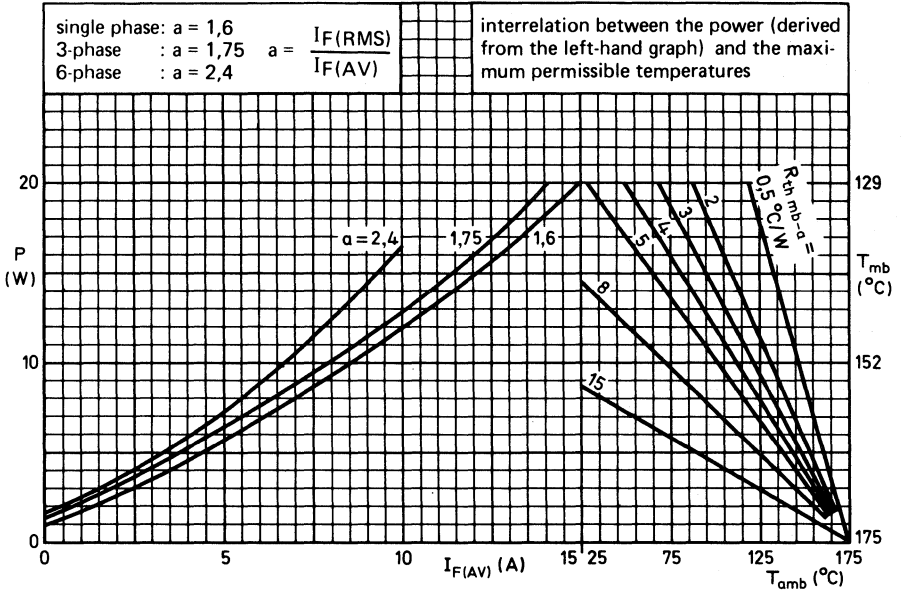
OPERATING NOTES

1. The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.
During soldering the heat conduction to the junction should be kept to a minimum.
2. Where there is a possibility that transients, due to the energy stored in the transformer, will exceed the maximum permissible non-repetitive peak reverse voltage, see General Section for information on damping circuits.

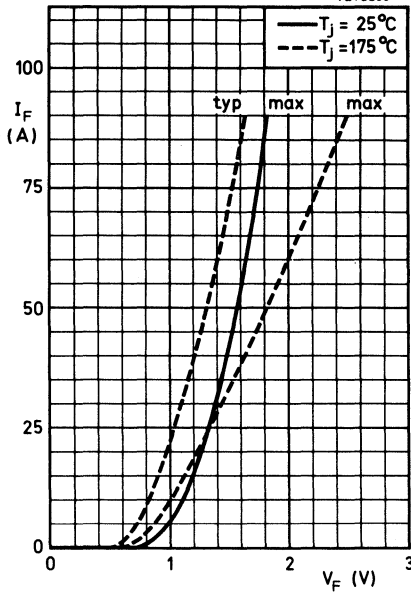
¹⁾ Measured under pulse conduction to avoid excessive dissipation.

BYX99
SERIES

7272261.1

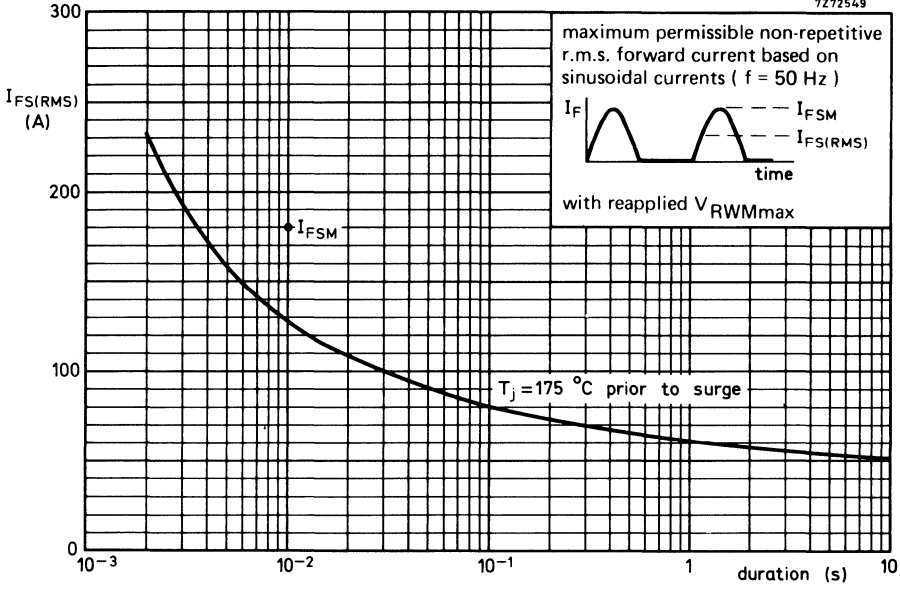


7272258

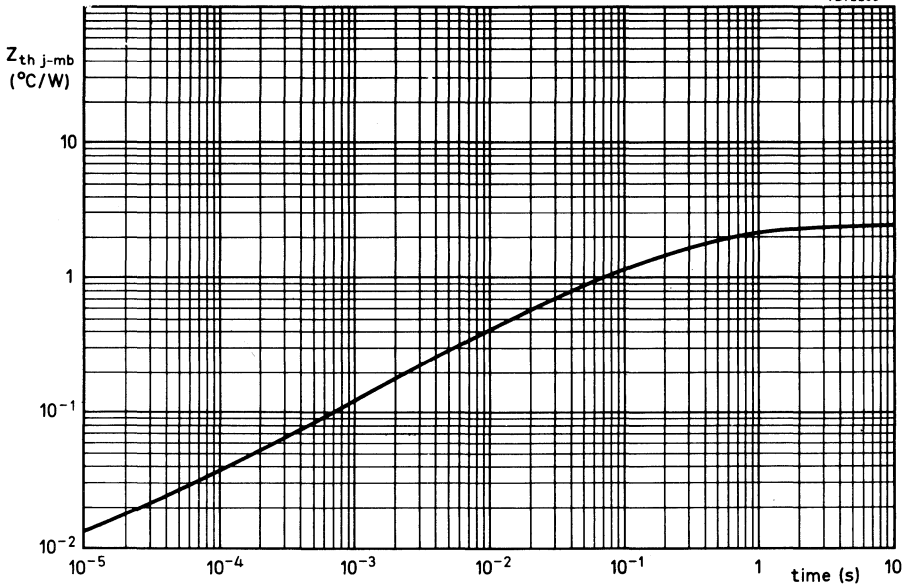


BYX99 SERIES

7272549



7272259



RECTIFIER BRIDGES

SILICON BRIDGE RECTIFIERS

Ready-for-use mains full-wave bridges, each consisting of four double-diffused silicon diodes, in a plastic encapsulation. The bridges are intended for use in equipment supplied from mains with r.m.s. voltages up to 280 V and are capable of delivering up to 1000 W into capacitive loads. They may be used in free air or clipped to a heatsink.

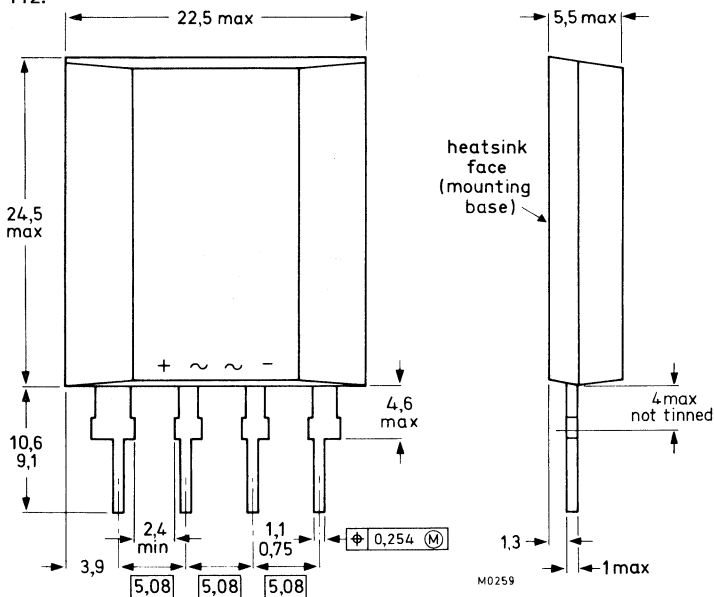
QUICK REFERENCE DATA

Input		BY224-400	600 V
R.M.S. voltage	$V_I(\text{RMS})$	max. 220	280 V
Repetitive peak voltage	V_{IRM}	max. 400	600 V
Non-repetitive peak current	I_{ISM}	max.	100 A
Peak inrush current	I_{IIM}	max.	200 A
Output			
Average current	$I_O(\text{AV})$	max.	4,8 A

MECHANICAL DATA (see also Fig.1a)

Dimensions in mm

Fig. 1 SOT-112.



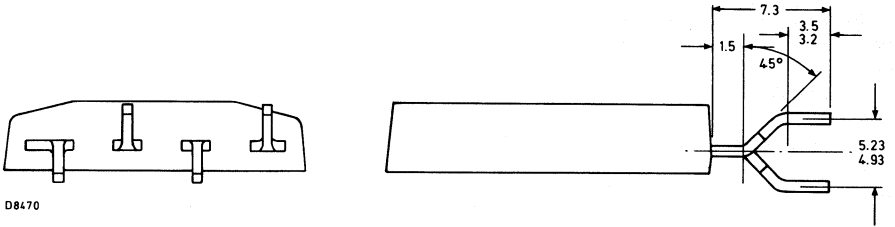
Net mass: 6,8 g

Accessories supplied on request: 56379 (clip); see Accessories and Mounting Instructions.

The sealing of the plastic withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

MECHANICAL DATA (continued)

Fig. 1a



A 600V version with cranked pins (as shown in figure 1a) is available as type OF432.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Input

	BY224-400		600
Non-repetitive peak voltage ($t \leq 10$ ms)	V_{ISM}	max. 400	600 V
Repetitive peak voltage	V_{IRM}	max. 400	600 V
Crest working voltage	V_{IWM}	max. 350	400 V
R.M.S. voltage (sine-wave)	$V_{I(RMS)}$	max. 220	280 V
Non-repetitive peak current			
half sine-wave; $t = 20$ ms; with reapplied V_{IWMmax}			
$T_j = 25$ °C prior to surge	I_{ISM}	max.	100 A
$T_j = 150$ °C prior to surge	I_{ISM}	max.	85 A
Peak inrush current (see Fig. 6)	I_{IIM}	max.	200 A

Output

Average current (averaged over any 20 ms period; see Figs 2 and 3)			
heatsink operation up to $T_{mb} = 90$ °C	$I_{O(AV)}$	max.	4,8 A
free-air operation at $T_{amb} = 45$ °C; (mounting method 1a)	$I_{O(AV)}$	max.	2,5 A
Repetitive peak current	I_{ORM}	max.	50 A

Temperatures

Storage temperature	T_{stg}		-40 to +150 °C
Junction temperature	T_j	max.	150 °C

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 4,0\ ^\circ C/W$$

Influence of mounting method

1. Free-air operation

The quoted values of $R_{th\ j-a}$ should be used only when no loads of other dissipating components run to the same tie-point (see Fig. 3).

Thermal resistance from junction to ambient in free air

a. Mounted on a printed-circuit board with 4 cm² of copper laminate to + and – leads

$$R_{th\ j-a} = 19,5\ ^\circ C/W$$

b. Mounted on a printed-circuit board with minimal copper laminate

$$R_{th\ j-a} = 25\ ^\circ C/W$$

2. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. With zinc-oxide heatsink compound

$$R_{th\ mb-h} = 1,0\ ^\circ C/W$$

b. Without heatsink compound

$$R_{th\ mb-h} = 2,0\ ^\circ C/W$$

MOUNTING INSTRUCTIONS

- Soldered joints must be at least 4 mm from the seal.
- The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
- Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than 150 °C.
- Leads should not be bent less than 4 mm from the seal. Exert no axial pull when bending.
- Recommended force of clip on device is 120 N (12 kgf).
- The heatsink should be in contact with the entire mounting base of the device and heatsink compound should be used.

CHARACTERISTICS

Forward voltage (2 diodes in series)

$$I_F = 10\ A; T_j = 25\ ^\circ C$$

$$V_F < 2,3\ V^*$$

Reverse current (2 diodes in parallel)

$$V_R = V_{IWMmax}; T_j = 25\ ^\circ C$$

$$I_R < 200\ \mu A$$

* Measured under pulse conditions to avoid excessive dissipation.

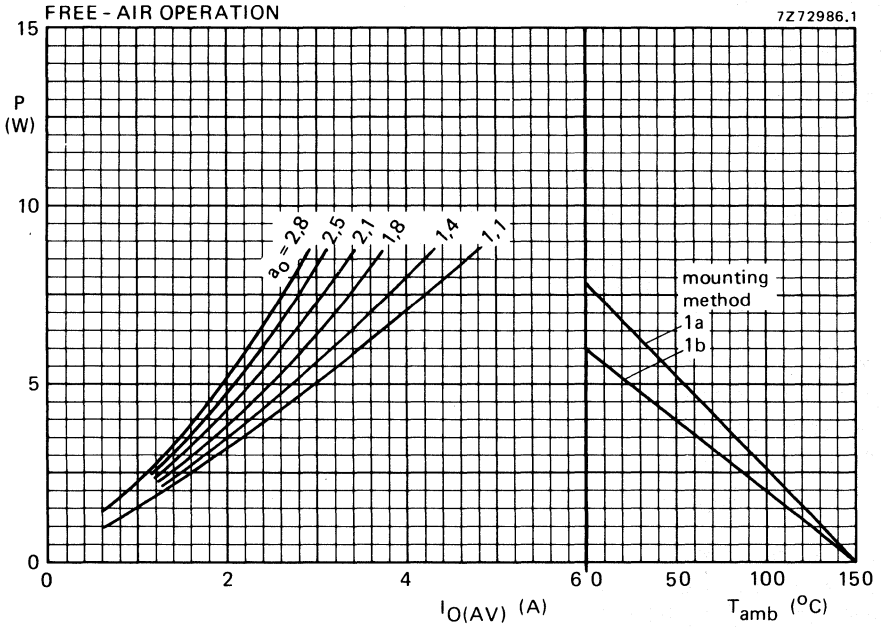


Fig. 2 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible ambient temperature.

Output form factor $a_0 = I_{O(RMS)}/I_{O(AV)} = 0,707 \times I_{F(RMS)}/I_{F(AV)}$ per diode.

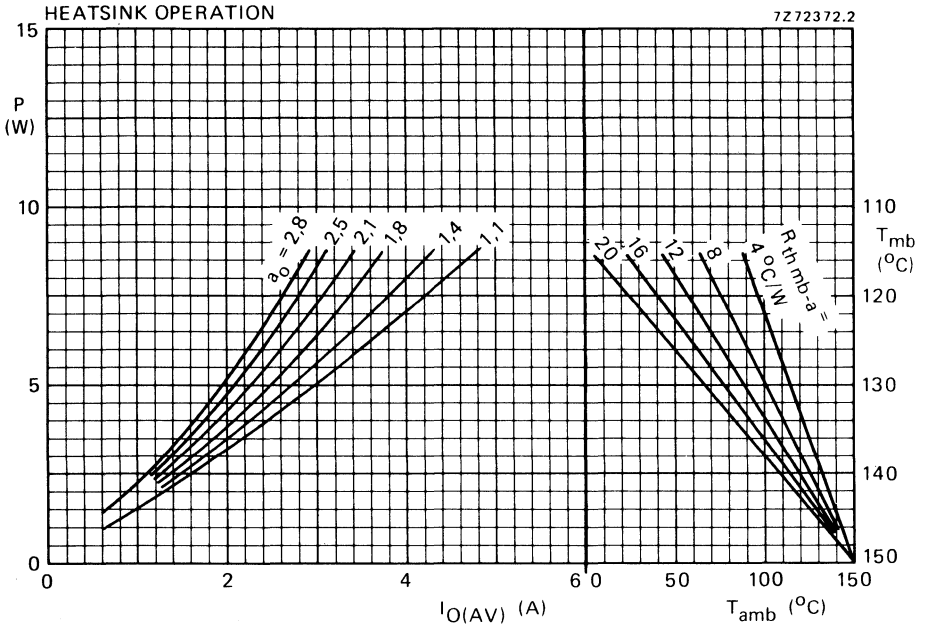


Fig. 3 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible temperatures.

Output form factor $a_0 = I_{O(RMS)}/I_{O(AV)} = 0,707 \times I_{F(RMS)}/I_{F(AV)}$ per diode.

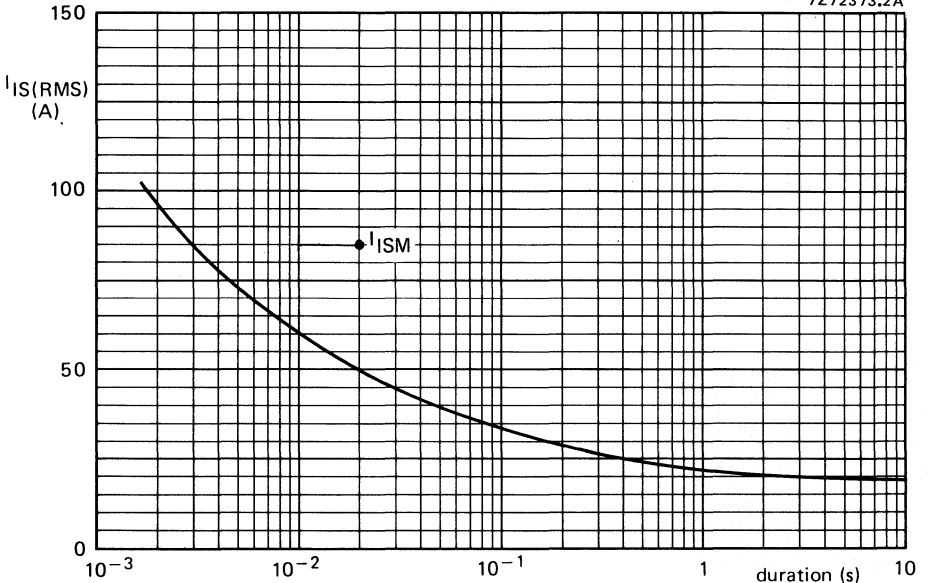


Fig.4 Maximum permissible non-repetitive r.m.s. input current based on sinusoidal currents ($f = 50$ Hz); $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{IWMmax} .

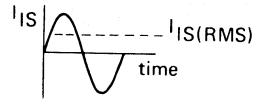
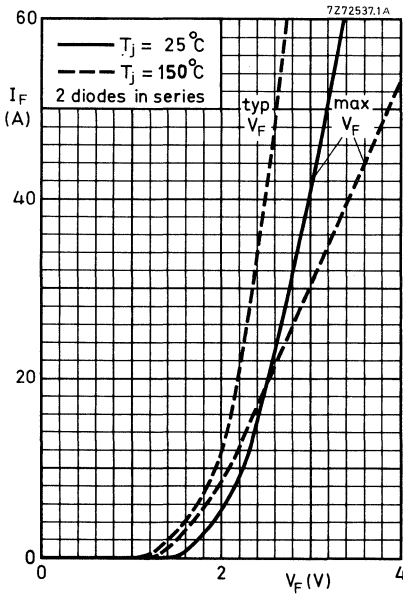
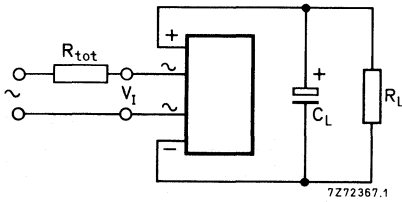
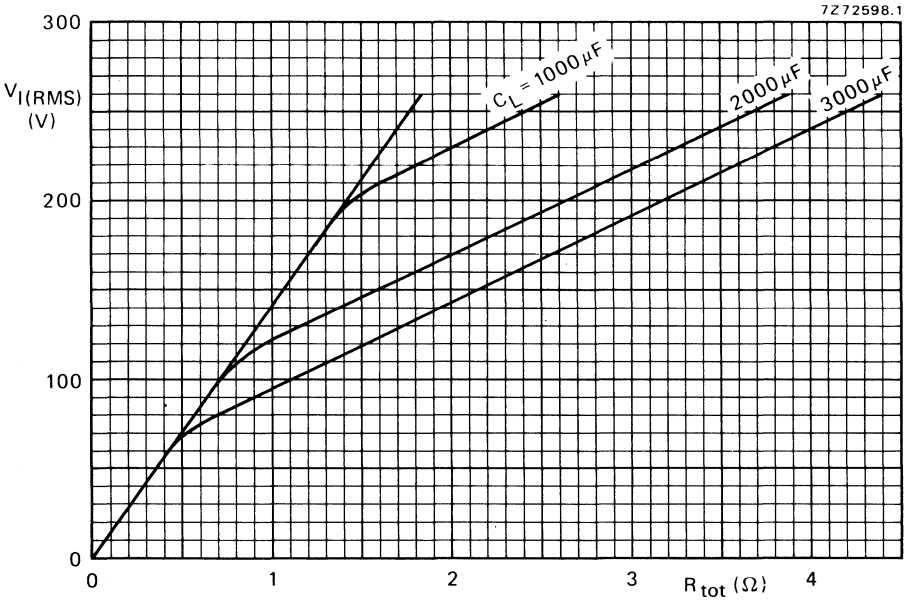


Fig.5

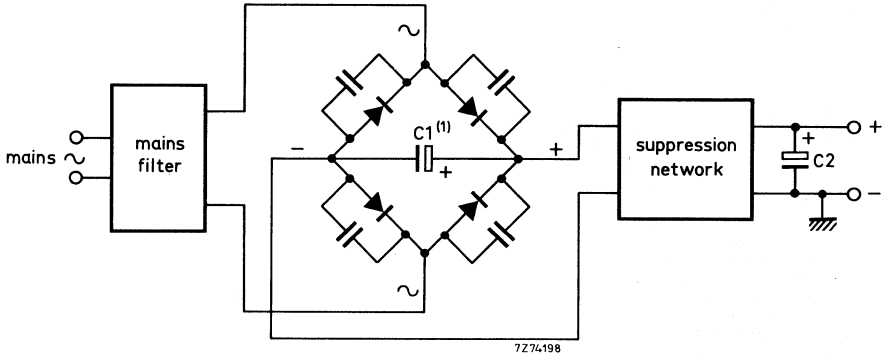


The graph takes the possibility of the following spreads into account:

- mains voltage +10%
- capacitance +50%
- resistance -10%

Fig. 6 Minimum value of the total series resistance R_{tot} (including the transformer resistance) required to limit the peak inrush current.

APPLICATION INFORMATION



(1) External capacitor.

Fig. 7 Because smoothing capacitor C2 is not always connected directly across the bridge (a suppression network may be sited between capacitor and bridge as shown), it is necessary to connect a capacitor of about 1 μ F, C1, between the + and - terminals of the bridge. This capacitor should be as close to the bridge as possible, to give optimum suppression of mains transients.

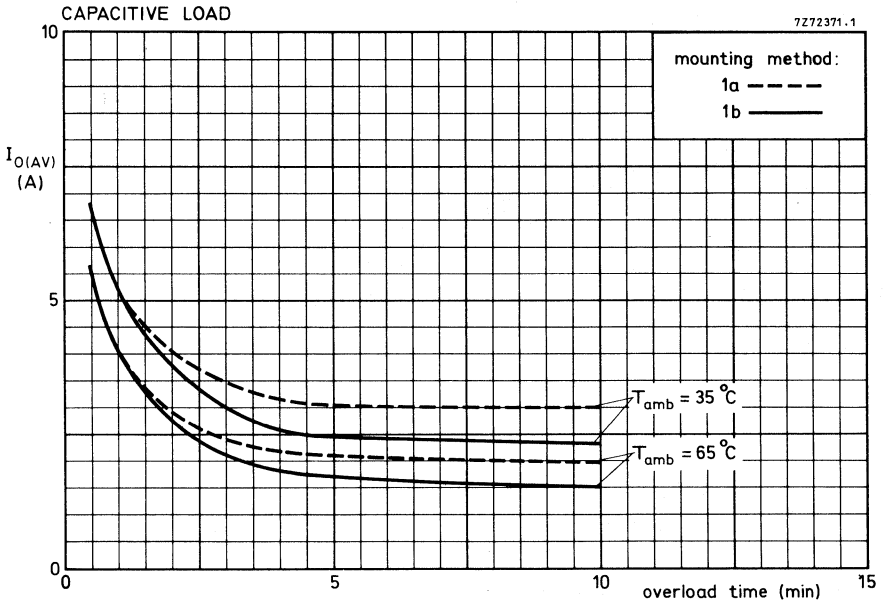


Fig.8

SILICON BRIDGE RECTIFIERS

Ready-for-use full-wave bridge rectifiers in a plastic encapsulation. The bridges are intended for use in equipment supplied from a.c. with r.m.s. voltages up to 80 V and are capable of delivering output currents up to 4,8 A. They are also suitable for use in hi-fi audio equipments and low-voltage industrial power supplies. They may be used in free air or clipped to a heatsink.

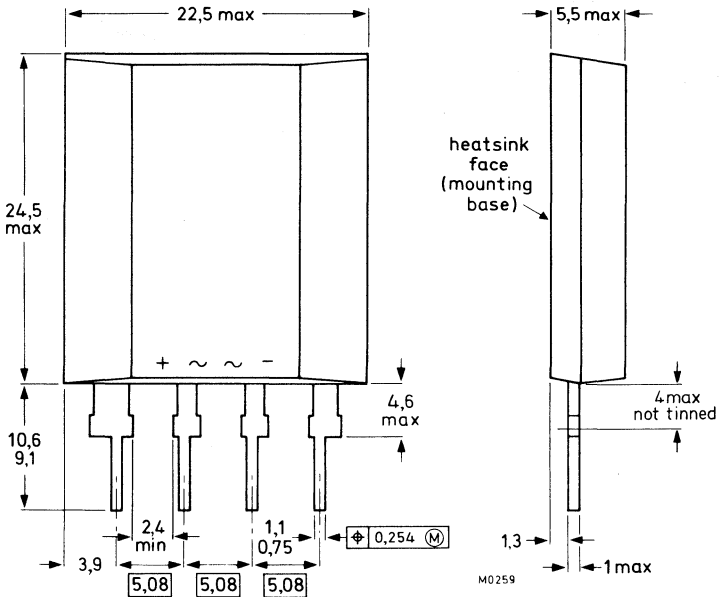
QUICK REFERENCE DATA

Input		BY225-100		200
R.M.S. voltage	$V_I(\text{RMS})$	max.	50	80 V
Repetitive peak voltage	V_{IRM}	max.	100	200 V
Non-repetitive peak current	I_{ISM}	max.		100 A
Peak inrush current	I_{IIM}	max.		200 A
Output				
Average current	$I_O(\text{AV})$	max.		4,8 A

MECHANICAL DATA

Dimensions in mm

Fig. 1 SOT-112.



Net mass: 6,8 g

Accessories supplied on request: 56379 (clip); see Accessories and Mounting Instructions.

The sealing of the plastic withstands the accelerated damp heat test of IEC recommendation 68-2 (test D, severity IV, 6 cycles).

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Input

		BY225-100	200
Non-repetitive peak voltage ($t \leq 10$ ms)	V_{ISM}	max. 100	200 V
Repetitive peak voltage	V_{IRM}	max. 100	200 V
Crest working voltage	V_{IWM}	max. 70	112 V
R.M.S. voltage (sine-wave)	$V_{I(RMS)}$	max. 50	80 V

Non-repetitive peak current;
half sine-wave; $t = 20$ ms; with reapplied V_{IWMmax}

$T_j = 25$ °C prior to surge

$T_j = 150$ °C prior to surge

Peak inrush current (see Fig. 6)

I_{ISM}	max.	100 A
I_{ISM}	max.	85 A
I_{IIM}	max.	200 A

Output

Average current (averaged over any 20 ms period;

see Figs 2 and 3)

heatsink operation up to $T_{mb} = 115$ °C

heatsink operation at $T_{mb} = 125$ °C

free-air operation at $T_{amb} = 45$ °C;

(mounting method 1a)

Repetitive peak current

$I_{O(AV)}$	max.	4,8 A
$I_{O(AV)}$	max.	3,6 A
$I_{O(AV)}$	max.	3,2 A
I_{ORM}	max.	50 A

Temperatures

Storage temperature

Junction temperature

T_{stg}		-40 to +150 °C
T_j	max.	150 °C

THERMAL RESISTANCE

From junction to mounting base $R_{th\ j-mb} = 4,0\ ^\circ C/W$

Influence of mounting method

1. Free-air operation

The quoted values of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie-point (see Fig. 2).

Thermal resistance from junction to ambient in free air

a. Mounted on a printed-circuit board with 4 cm² of copper laminate to + and - leads $R_{th\ j-a} = 19,5\ ^\circ C/W$

b. Mounted on a printed-circuit board with minimal copper laminate $R_{th\ j-a} = 25\ ^\circ C/W$

2. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. With zinc-oxide heatsink compound $R_{th\ mb-h} = 1,0\ ^\circ C/W$

b. Without heatsink compound $R_{th\ mb-h} = 2,0\ ^\circ C/W$

MOUNTING INSTRUCTIONS

1. Soldered joints must be at least 4 mm from the seal.
2. The maximum permissible temperature of the soldering iron or bath is 270 °C; contact with the joint must not exceed 3 seconds.
3. Avoid hot spots due to handling or mounting; the body of the device must not come into contact with or be exposed to a temperature higher than 150 °C.
4. Leads should not be bent less than 4 mm from the seal. Exert no axial pull when bending.
5. Recommended force of clip on device is 120 N (12 kgf).
6. The heatsink should be in contact with the entire mounting base of the device and heatsink compound should be used.

CHARACTERISTICS

Forward voltage (2 diodes in series)

$I_F = 10\ A; T_j = 25\ ^\circ C$ $V_F < 2,3\ V^*$

Reverse current (2 diodes in parallel)

$V_R = V_{IWMmax}; T_j = 25\ ^\circ C$ $I_R < 200\ \mu A$

* Measured under pulse conditions to avoid excessive dissipation.

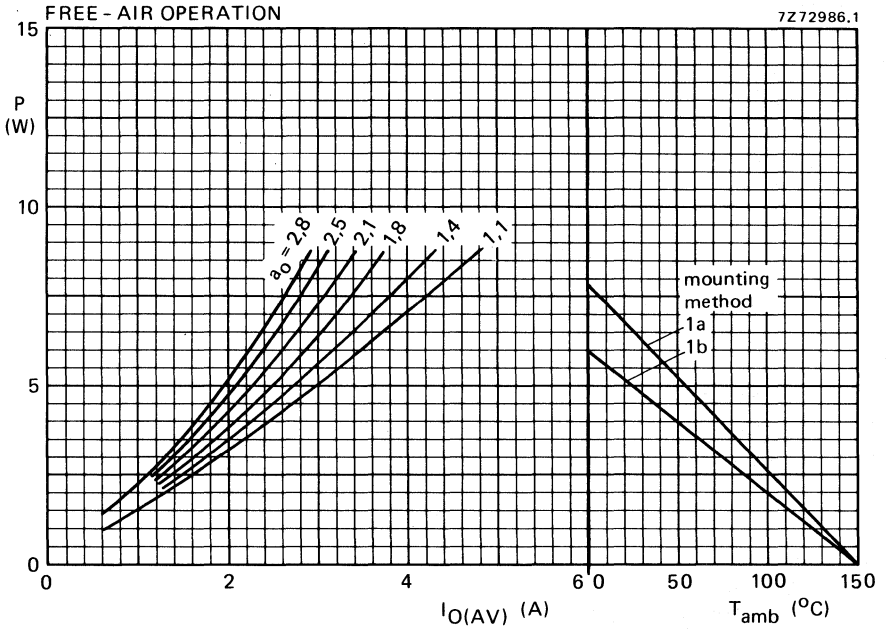


Fig. 2 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible ambient temperature.

Output form factor $a_o = I_{O(RMS)}/I_{O(AV)} = 0,707 \times I_{F(RMS)}/I_{F(AV)}$ per diode.

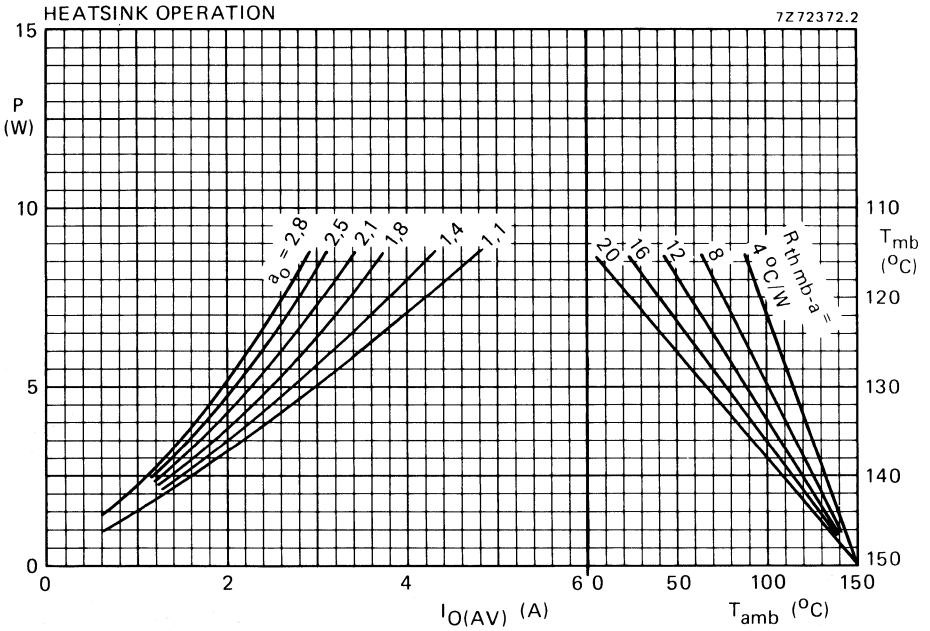


Fig. 3 The right-hand part shows the interrelationship between the power (derived from the left-hand graph) and the maximum permissible temperatures.

Output form factor $a_0 = I_{O(RMS)}/I_{O(AV)} = 0,707 \times I_{F(RMS)}/I_{F(AV)}$ per diode.

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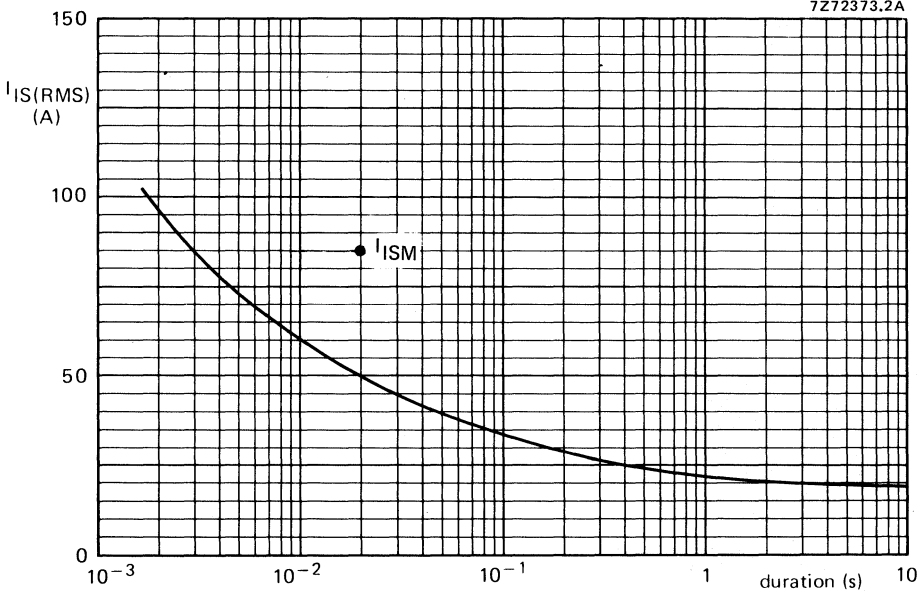


Fig. 4 Maximum permissible non-repetitive r.m.s. input current based on sinusoidal currents ($f = 50$ Hz); $T_j = 150$ °C prior to surge; with reapplied V_{IWMmax} .

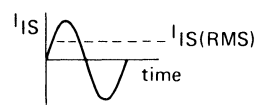
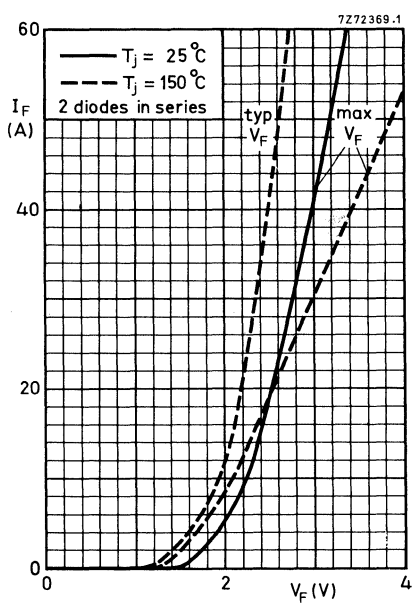
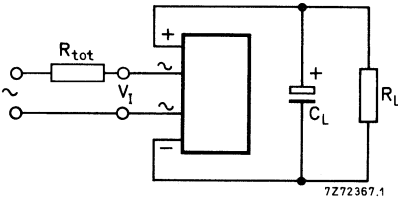
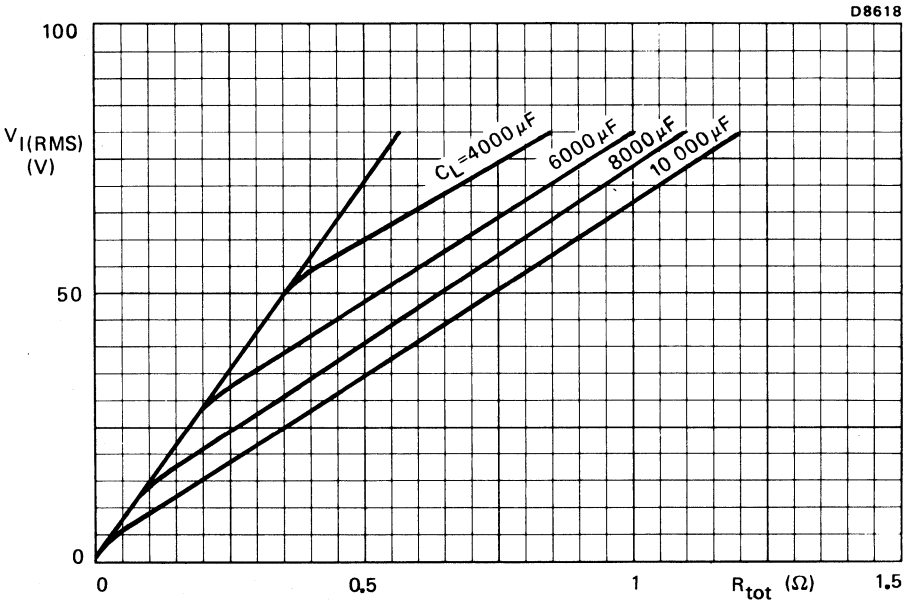


Fig. 5.



The graph takes the possibility of the following spreads into account:

- input voltage +10%
- capacitance +50%
- resistance -10%

Fig. 6 Minimum value of the total series resistance R_{tot} (including the transformer resistance) required to limit the peak inrush current.

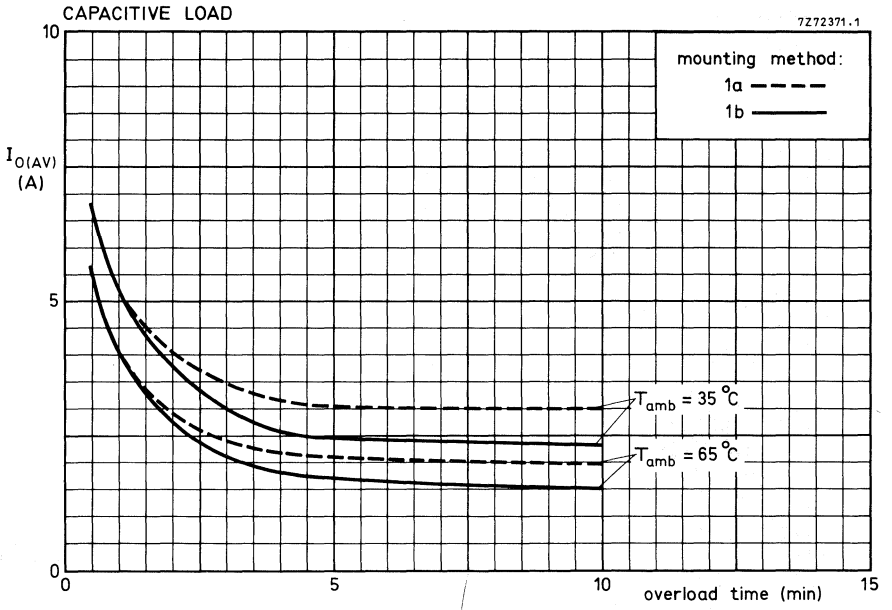


Fig. 7.

SILICON BRIDGE RECTIFIERS

Ready for use full-wave bridge rectifiers in a plastic encapsulation. The bridges are intended for use in equipment supplied from a.c. with r.m.s. voltages up to 420 V and are capable of delivering output currents up to 12A. They are also suitable for use in hi-fi audio equipments and low-voltage industrial power supplies. They may be used in free air or on a heatsink.

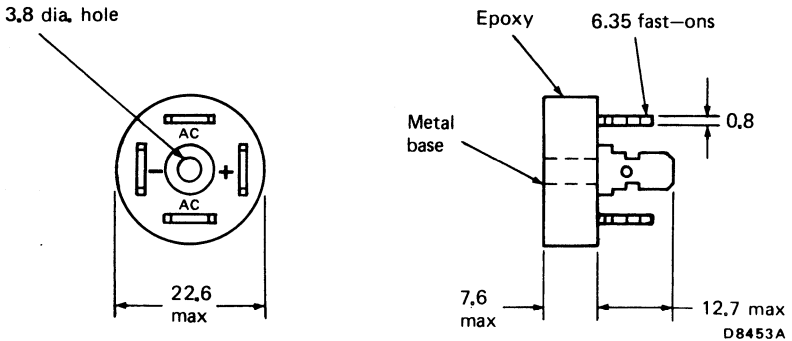
QUICK REFERENCE DATA

Input		BY260-200			400	600
		140	280	420		
R.M.S. voltage	$V_I(\text{RMS})$	max.	140	280	420	V
Repetitive peak voltage	V_{IRM}	max.	200	400	600	V
Non-repetitive peak current	I_{ISM}	max.	125		A	
Peak inrush current	I_{IIM}	max.	250		A	
Output					12	A
Average current	$I_{O(AV)}$	max.	12		A	

MECHANICAL DATA

Dimensions in mm

Fig. 1.



BY260 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

Input		BY260-200	400	600	
Non-repetitive peak voltage ($t \leq 10$ ms)	V_{ISM}	max. 200	400	600	V
Repetitive peak voltage	V_{IRM}	max. 200	400	600	V
Crest working voltage	V_{IWM}	max. 200	400	600	V
R.M.S. voltage (sine-wave)	$V_{I(RMS)}$	max. 140	280	420	V
Non-repetitive peak current					
half-sinewave; $t = 20$ ms; with reapplied V_{IWMmax}					
$T_j = 25$ °C prior to surge	I_{ISM}	max.	125		A
$T_j = 150$ °C prior to surge	I_{ISM}	max.	100		A
Peak inrush current (see Fig. 5)	I_{IIM}	max.	250		A
Output					
Average current (averaged over any 20 ms period)					
heatsink operation up to $T_{mb} = 60$ °C (R-load)	$I_{O(AV)}$	max.	12		A
heatsink operation up to $T_{mb} = 60$ °C (C-load)	$I_{O(AV)}$	max.	7.5		A
Repetitive peak current	I_{ORM}	max.	20		A
Temperatures					
Storage temperature	T_{stg}		-55 to +150		°C
Junction temperature	T_j	max.	150		°C
THERMAL RESISTANCE					
From junction to mounting base	$R_{th j-mb}$	=	4.5		°C/W
CHARACTERISTICS					
Forward voltage (2 diodes in series)					
$I_F = 7$ A; $T_j = 25$ °C	V_F	<	2.0		V*
Reverse current (2 diodes in parallel)					
$V_R = V_{IWMmax}$; $T_j = 100$ °C	I_R	<	150		μA

*Measured under pulse conditions to avoid excessive dissipation.

SILICON BRIDGE RECTIFIERS

Ready for use full-wave bridge rectifiers in a plastic encapsulation.

The bridges are intended for use in equipment supplied from a.c. with r.m.s. voltages up to 420 V and are capable of delivering output currents up to 25A. They may be used in free air or on a heatsink.

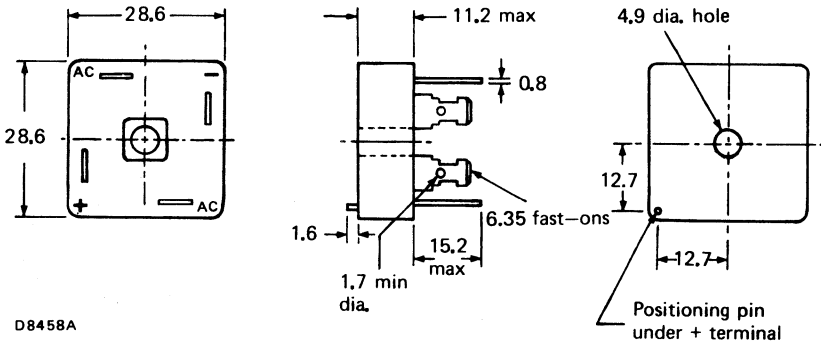
QUICK REFERENCE DATA

Input		BY261-200			400	600	
		max.	140	280			
R.M.S. voltage	$V_I(\text{RMS})$	max.	140	280	420	V	
Repetitive peak voltage	V_{IRM}	max.	200	400	600	V	
Non-repetitive peak current	I_{ISM}	max.	320		A		
Peak inrush current	I_{IIM}	max.	640		A		
Output							
Average current	$I_{O(AV)}$	max.	25		A		

MECHANICAL DATA

Dimensions in mm

Fig. 1



D8458A

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

Input		BY261-200	400	600	
Non-repetitive peak voltage ($t \leq 10$ ms)	V_{ISM}	max. 200	400	600	V
Repetitive peak voltage	V_{IRM}	max. 200	400	600	V
Crest working voltage	V_{IWM}	max. 200	400	600	V
R.M.S. voltage (sine-wave)	$V_I(RMS)$	max. 140	280	420	V

Non-repetitive peak current
half sinewave; $t = 20$ ms; with reapplied V_{IWMmax}

$T_j = 25$ °C prior to surge	I_{ISM}	max.	320	A
$T_j = 150$ °C prior to surge	I_{ISM}	max.	250	A

Peak inrush current (see Fig. 5)	I_{IIM}	max.	640	A
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Output

Average current (averaged over any 20 ms period)
heatsink operation; up to $T_{mb} = 55$ °C (R-load)
heatsink operation; up to $T_{mb} = 55$ °C (C-load)

$I_{O(AV)}$	max.	25	A
$I_{O(AV)}$	max.	18	A

Repetitive peak current	I_{ORM}	max.	75	A
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Temperatures

Storage temperature	T_{stg}	-55 to +175	°C
Junction temperature	T_j	max. 175	°C

THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	2.5	°C/W
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CHARACTERISTICS

Forward voltage (2 diodes in series)

$I_F = 12$ A; $T_j = 25$ °C	V_F	<	2.3	V*
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Reverse current (2 diodes in parallel)

$V_R = V_{IWMmax}$; $T_j = 100$ °C	I_R	<	200	μ A
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*Measured under pulse conditions to avoid excessive dissipation.

FAST RECTIFIER DIODES

FAST SOFT-RECOVERY RECTIFIER DIODES



Glass-passivated double-diffused rectifier diodes in plastic envelopes, featuring fast reverse recovery times and non-snap-off characteristics. They are intended for use in chopper applications as well as in switched-mode power supplies, as efficiency diodes and scan rectifiers in television receivers.

The series consists of the following types:

Normal polarity: BY229-200 to 800.

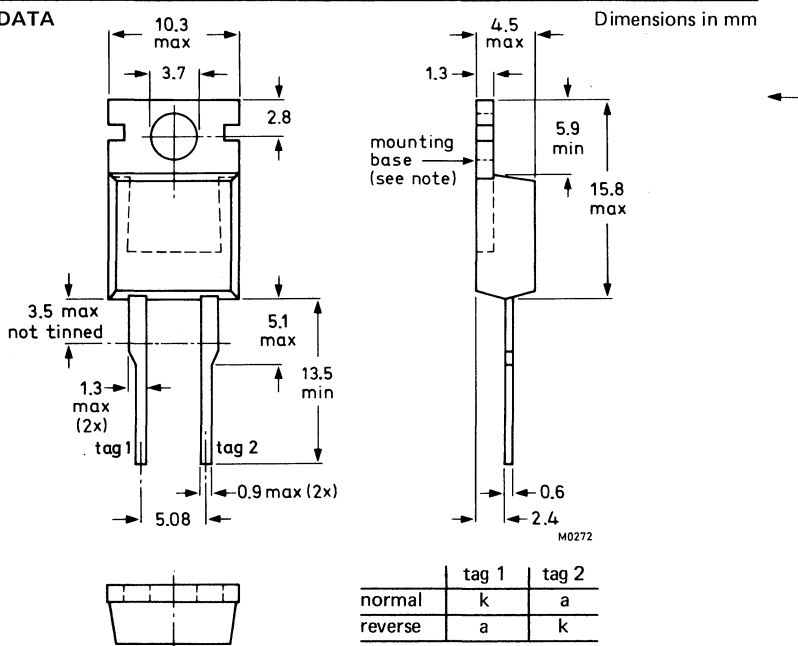
Reverse polarity: BY229-200R to 800R.

QUICK REFERENCE DATA

		BY229-200(R) 400(R) 600(R) 800(R)				
Repetitive peak reverse voltage	V_{RRM}	max. 200	400	600	800	V
Average forward current	$I_F(AV)$	max. 7				A
Non-repetitive peak forward current	I_{FSM}	max. 60				A
Reverse recovery time	t_{rr}	< 150				ns ←

MECHANICAL DATA

Fig.1 TO-220AC



Note: The exposed metal mounting base is directly connected to tag 1. Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

Products approved to CECC 50 009-021 available on request.

BY229 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages*

		BY229-200(R)	400(R)	600(R)	800(R)	
Non-repetitive peak reverse voltage	V_{RSM}	max. 200	400	600	800	V
Repetitive peak reverse voltage	V_{RRM}	max. 200	400	600	800	V
Crest working reverse voltage	V_{RWM}	max. 150	300	500	600	V
Continuous reverse voltage	V_R	max. 150	300	500	600	V

Currents

Average forward current assuming zero switching losses

square-wave; $\delta = 0.5$; up to $T_{mb} = 100\text{ }^\circ\text{C}$	$I_F(AV)$	max.	7		A
square-wave; $\delta = 0.5$; at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_F(AV)$	max.	4.1		A
sinusoidal; up to $T_{mb} = 100\text{ }^\circ\text{C}$	$I_F(AV)$	max.	6.5		A
sinusoidal; at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_F(AV)$	max.	4		A

R.M.S. forward current $I_F(RMS)$ max. 10 A

→ Repetitive peak forward current $t_p = 20\text{ }\mu\text{s}$; $\delta \leq 0.02$ I_{FRM} max. 135 A

Non-repetitive peak forward current $t = 10\text{ ms}$; half sine-wave;

$T_j = 150\text{ }^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max I_{FSM} max. 60 A

→ $I^2 t$ for fusing ($t = 10\text{ ms}$) $I^2 t$ max. 18 A^2s

Temperatures

Storage temperature	T_{stg}		-40 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.	150		$^\circ\text{C}$

*To ensure thermal stability: $R_{th\ j-a} \leq 15\text{ K/W}$ for continuous reverse voltage.

THERMAL RESISTANCE

From junction to mounting base $R_{th\ j-mb} = 4.5\ K/W$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

- | | |
|---|---------------------------|
| a. with heatsink compound | $R_{th\ mb-h} = 0.3\ K/W$ |
| b. with heatsink compound and 0.06 mm maximum mica insulator | $R_{th\ mb-h} = 1.4\ K/W$ |
| c. with heatsink compound and 0.1 mm maximum mica insulator (56369) | $R_{th\ mb-h} = 2.2\ K/W$ |
| d. with heatsink compound and 0.25 mm maximum alumina insulator (56367) | $R_{th\ mb-h} = 0.8\ K/W$ |
| e. without heatsink compound | $R_{th\ mb-h} = 1.4\ K/W$ |

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$R_{th\ j-a} = 60\ K/W$

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm. ←
3. It is recommended that the circuit connection be made to tag 1, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than screw mounting;
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting (only possible for non-insulated mounting)

Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise specified

Forward voltage

$I_F = 20\text{ A}$	V_F	<	1.85	V*
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Reverse current

$V_R = V_{RWMmax}; T_j = 125\text{ }^\circ\text{C}$	normal polarity	I_R	<	0.4	mA
	reverse polarity	I_R	<	0.6	mA

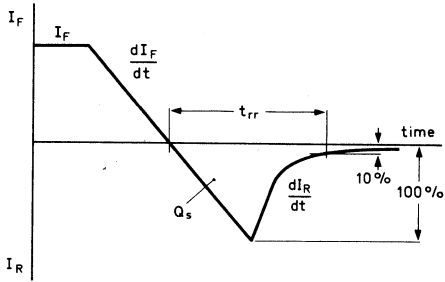
Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$	recovery time	t_{rr}	<	150	ns
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$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$	recovered charge	Q_s	<	0.7	μC
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Maximum slope of the reverse recovery current

$I_F = 2\text{ A}, -dI_F/dt = 20\text{ A}/\mu\text{s}$	normal polarity	$ dI_R/dt $	<	60	$\text{A}/\mu\text{s}$
	reverse polarity	$ dI_R/dt $	<	75	$\text{A}/\mu\text{s}$



D8403

Fig.3 Definition of t_{rr} and Q_s .

*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

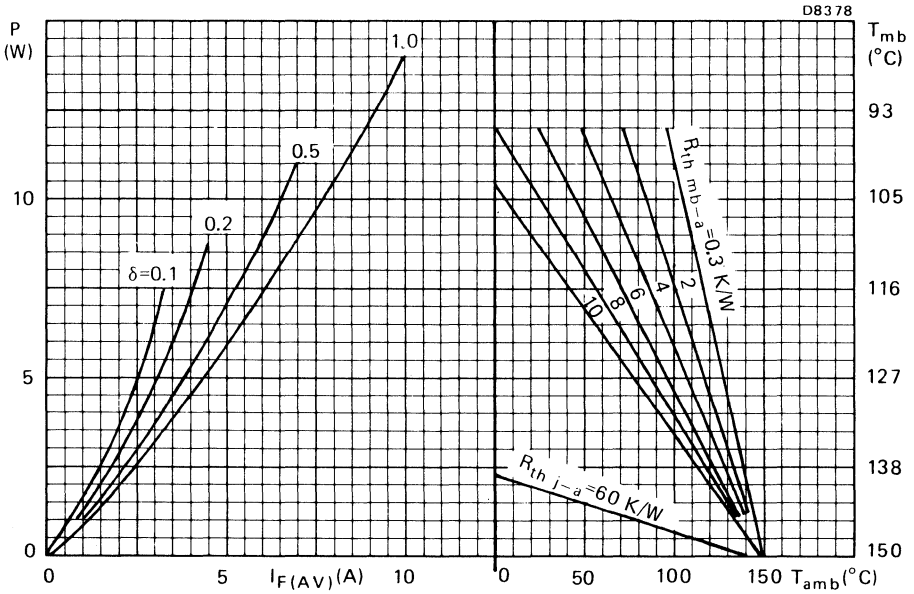
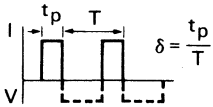


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

SINUSOIDAL OPERATION

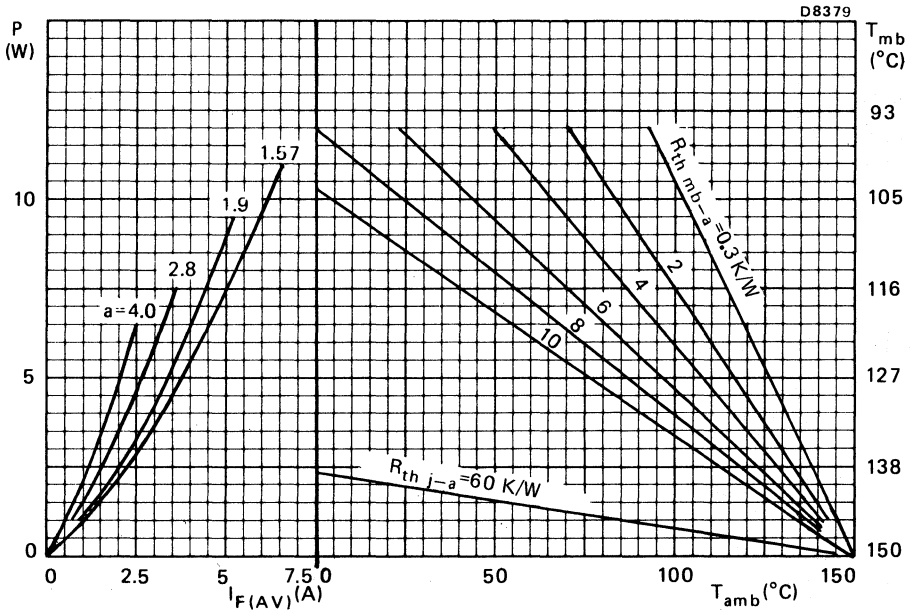


Fig. 5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.

a = form factor = $I_F(RMS)/I_F(AV)$.

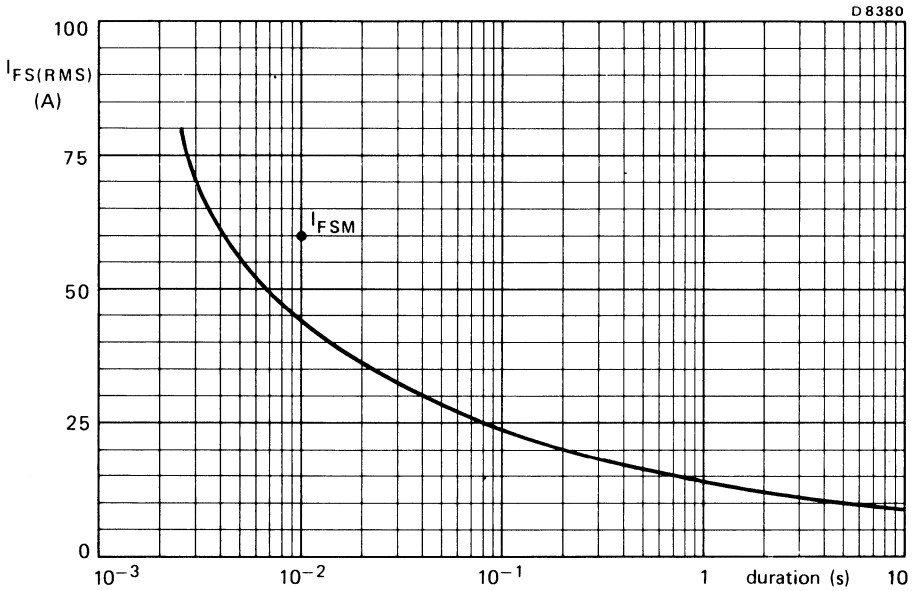


Fig. 6 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 150$ °C prior to surge; with reapplied V_{RWMmax} .

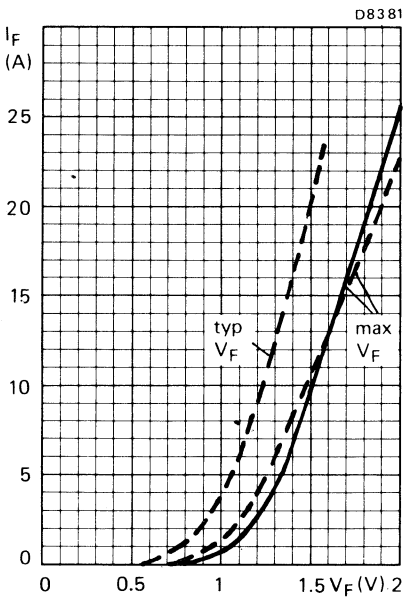
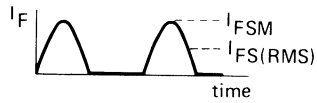


Fig. 7 — $T_j = 25$ °C; - - - $T_j = 125$ °C



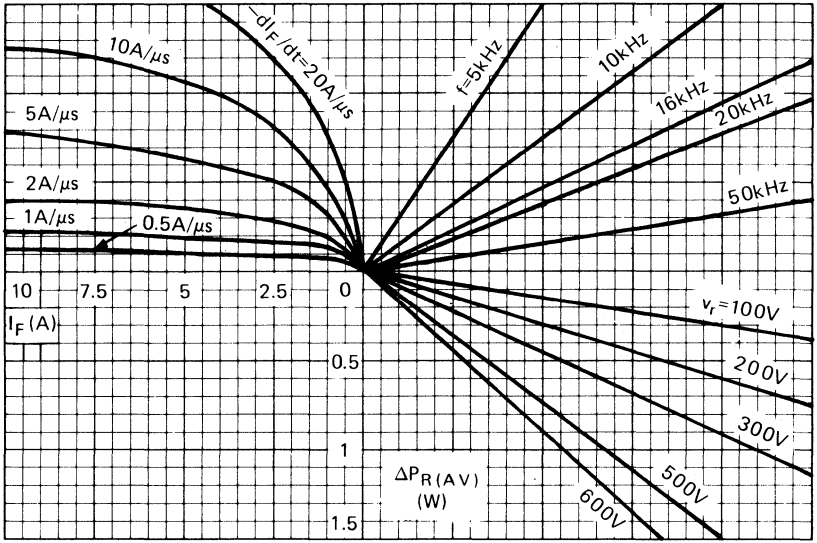
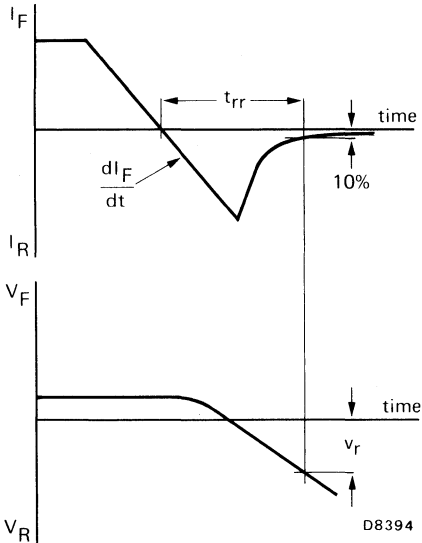


Fig. 8 NOMOGRAM

Power loss $\Delta P_{R(AV)}$ due to switching only (to be added to steady state power losses).
 I_F = forward current just before switching off; $T_j = 150^\circ\text{C}$



D8394

D8392

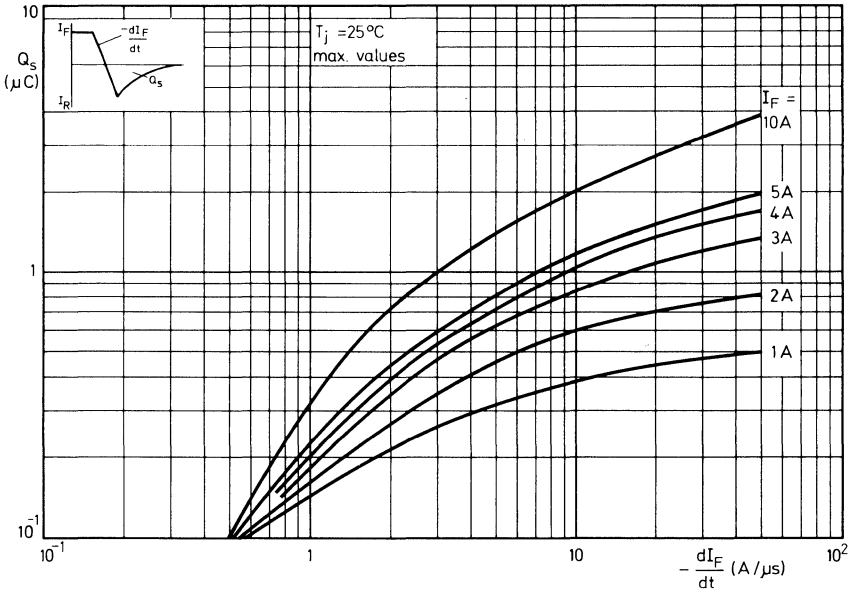


Fig.9

D8393

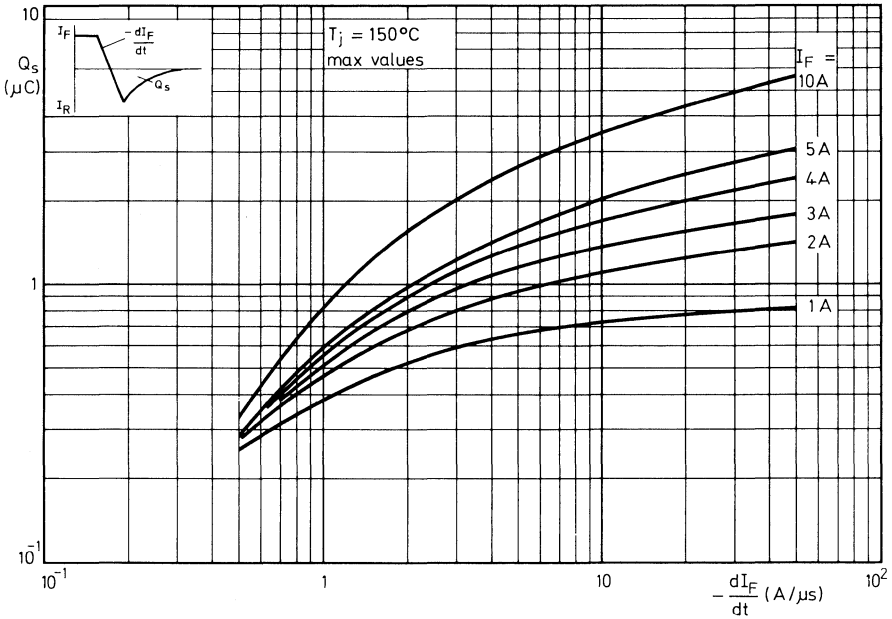


Fig.10

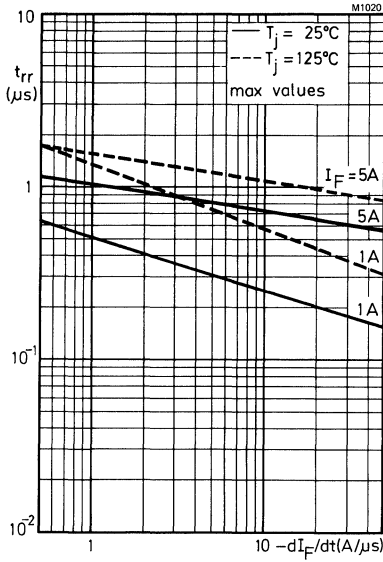


Fig. 11

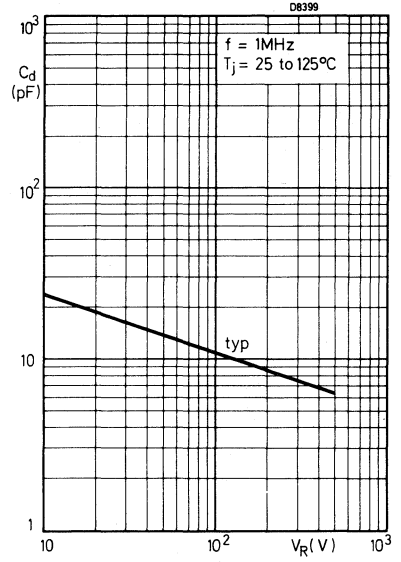


Fig. 12

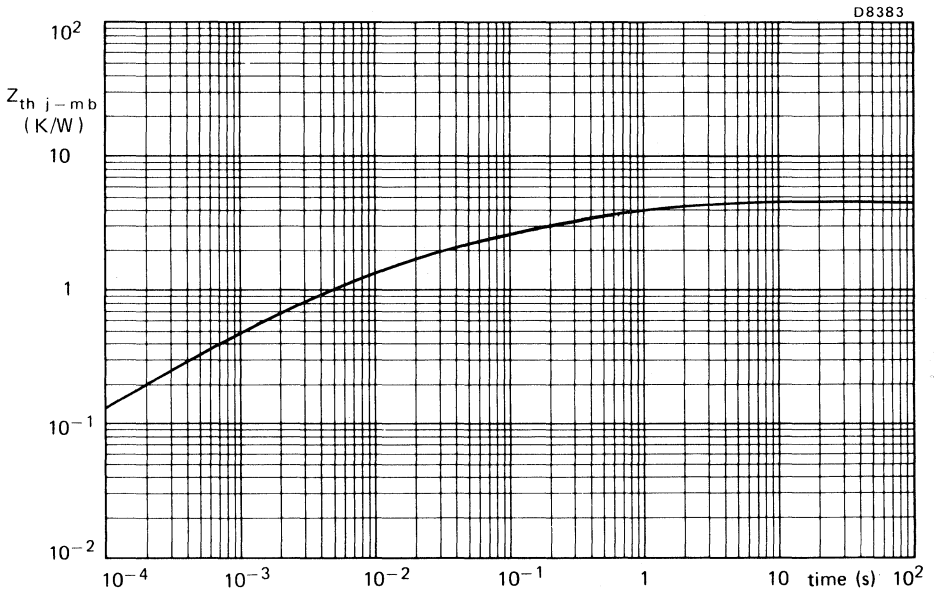
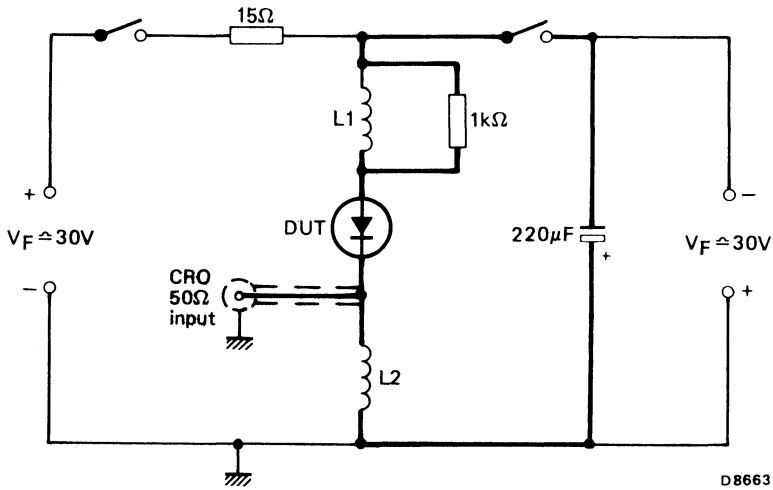


Fig. 13



D8663

Fig.14 Simplified circuit diagram of practical apparatus to test softness of recovery.

NOTES

1. Duty factor of forward current should be low, $< 2\%$.
2. dI_F/dt is set by $L1$, $1.5 \mu H$ gives $20 A/\mu s$
3. dI_R/dt is measured across $L2$, $200 nH$ gives $5A/\mu s/V$.
4. Wiring shown in heavy should be kept as short as possible.



FAST SOFT-RECOVERY ELECTRICALLY ISOLATED RECTIFIER DIODES

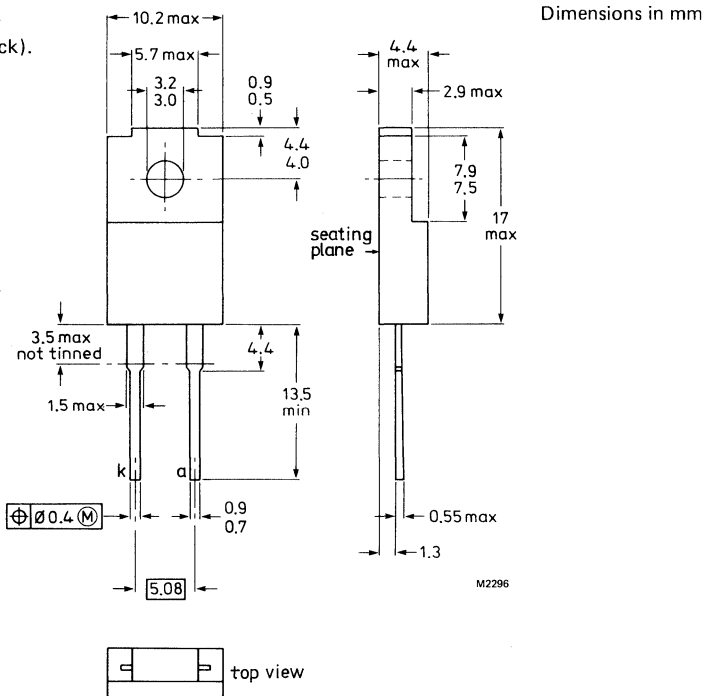
Glass-passivated, double-diffused rectifier diodes in full-pack plastic envelopes, featuring fast reverse recovery times and non-snap-off characteristics. Their electrical isolation makes them ideal for mounting on a common heatsink alongside other components without the need for additional insulators. They are intended for use in chopper applications as well as in switched-mode power supplies and as efficiency diodes and scan rectifiers in television receivers.

QUICK REFERENCE DATA

		BY229F-200				400	600	800	
Repetitive peak reverse voltage	V_{RRM}	max.	200	400	600	800		V	
Average forward current	$I_F(AV)$	max.	7					A	
Non-repetitive peak forward current	I_{FSM}	<	60					A	
Reverse recovery time	t_{rr}	<	150					ns ←	

MECHANICAL DATA

Fig.1 SOT-186 (full-pack).



M2296

Net mass: 2 g.

The seating plane is electrically isolated from all terminals.

Accessories supplied on request (see data sheets Mounting instructions for F-pack devices and Accessories for SOT-186 envelopes).

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

Voltages (Note 1)

		BY229F-200	400	600	800	
Non-repetitive peak reverse voltage	V_{RSM} max.	200	400	600	800	V
Repetitive peak reverse voltage	V_{RRM} max.	200	400	600	800	V
Crest working reverse voltage	V_{RWM} max.	150	300	500	600	V
Continuous reverse voltage	V_R max.	150	300	500	600	V

Currents

Average forward current assuming zero switching losses (Note 2)

square wave; $\delta = 0.5$; up to $T_{HS} = 90^\circ\text{C}$
 sinusoidal; up to $T_{HS} = 93^\circ\text{C}$

$I_F(AV)$	max.	7	A
$I_F(AV)$	max.	6.25	A

R.M.S. forward current

$I_F(RMS)$	max.	10	A
------------	------	----	---

Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$

I_{FRM}	max.	135	A
-----------	------	-----	---

Non-repetitive peak forward current
 half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max

$t = 10 \text{ ms}$

$t = 8.3 \text{ ms}$

I_{FSM}	max.	60	A
i_{FSM}	max.	65	A

$I^2 t$ for fusing ($t = 10 \text{ ms}$)

$I^2 t$	max.	18	$\text{A}^2 \text{s}$
---------	------	----	-----------------------

Temperatures

Storage temperature

T_{stg}		-40 to +150	$^\circ\text{C}$
-----------	--	-------------	------------------

Junction temperature

T_j	max.	150	$^\circ\text{C}$
-------	------	-----	------------------

ISOLATION

Peak isolation voltage from all terminals to external heatsink

V_{isol}	max.	1000	V
------------	------	------	---

Isolation capacitance from cathode to external heatsink (Note 3)

C_p	typ.	12	pF
-------	------	----	----

Notes

1. To ensure thermal stability: $R_{th j-a} < 15 \text{ K/W}$ for continuous reverse voltage.
2. The quoted temperatures assume heatsink compound is used.
3. Mounted without heatsink compound and 20 Newtons pressure on the centre of the envelope.

THERMAL RESISTANCE

From junction to external heatsink with minimum of 2 kgf (20 Newtons) pressure on the centre of the envelope,

without heatsink compound	$R_{th\ j-h}$	=	7.2	K/W
with heatsink compound	$R_{th\ j-h}$	=	5.5	K/W

Free-air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same point.

Thermal resistance from junction to ambient in free air, mounted on a printed circuit board

$R_{th\ j-a}$	=	55	K/W
---------------	---	----	-----

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise specified

Forward voltage

$I_F = 20\text{ A}$	V_F	<	1.85	V*
---------------------	-------	---	------	----

Reverse current

$V_R = V_{RWM\ max}; T_j = 125\text{ }^\circ\text{C}$	I_R	<	0.4	mA
---	-------	---	-----	----

Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$, recovery time	t_{rr}	<	150	ns ←
---	----------	---	-----	------

$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$ recovered charge	Q_s	<	0.7	μC
--	-------	---	-----	---------------

Maximum slope of the reverse recovery current

$I_F = 2\text{ A}, -dI_F/dt = 20\text{ A}/\mu\text{s}$	$ dI_R/dt $	<	60	$\text{A}/\mu\text{s}$
--	-------------	---	----	------------------------

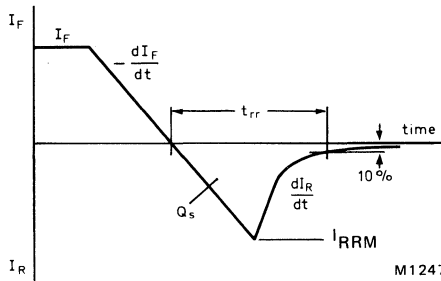


Fig.2 Definition of t_{rr} and Q_s .

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- 2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers a good thermal contact under the crystal area and slightly lower $R_{th\ j-h}$ values than screw mounting. The force exerted on the top of the device by the clip should be at least 2 kgf (20 Newtons) to ensure good thermal contact and must not exceed 3.5 kgf (35 Newtons) to avoid damage to the device.
4. If screw mounting is used, it should be M3 cross-recess pan head.

Minimum torque to ensure good thermal contact:	5.5 kgf (0.55 Nm)
Maximum torque to avoid damage to the device:	8.0 kgf (0.80 Nm)
5. For good thermal contact, heatsink compound should be used between baseplate and heatsink. Values of $R_{th\ j-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting.

It is not recommended to use rivets, since extensive damage could result to the plastic, which could destroy the insulating properties of the device.
- 7. The heatsink must have a flatness in the mounting area of 0.02 mm maximum per 10 mm. Mounting holes must be deburred.

OPERATING NOTES

The various components of junction temperature rise above ambient are illustrated in Fig.3.

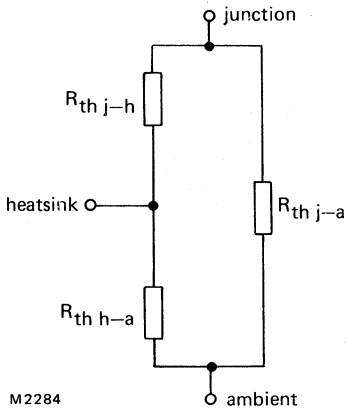
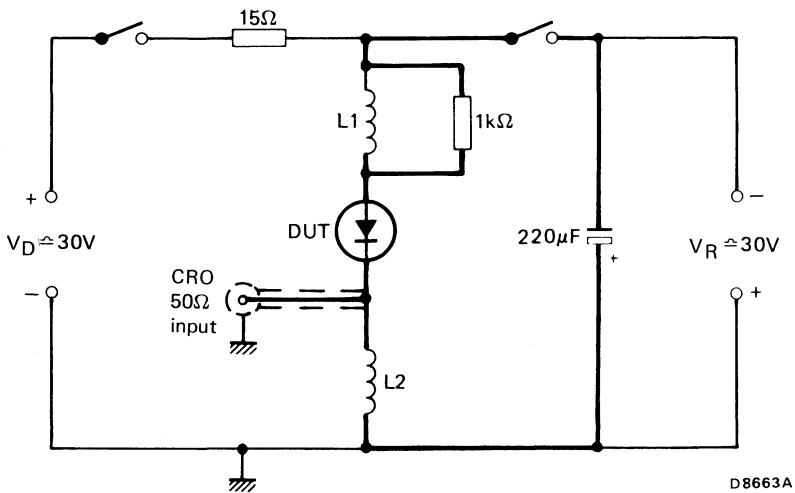


Fig.3.

Any measurement of heatsink temperature should be immediately adjacent to the device.



D8663A

Fig.4 Simplified circuit diagram of practical apparatus to test softness of recovery.

NOTES

1. Duty factor of forward current should be low, $< 2\%$.
2. dI_F/dt is set by $L1$, $1.5 \mu H$ gives $20 A/\mu s$.
3. dI_R/dt is measured across $L2$, $200 nH$ gives $5 A/\mu s/V$.
4. Wiring shown in heavy should be kept as short as possible.

SQUARE-WAVE OPERATION

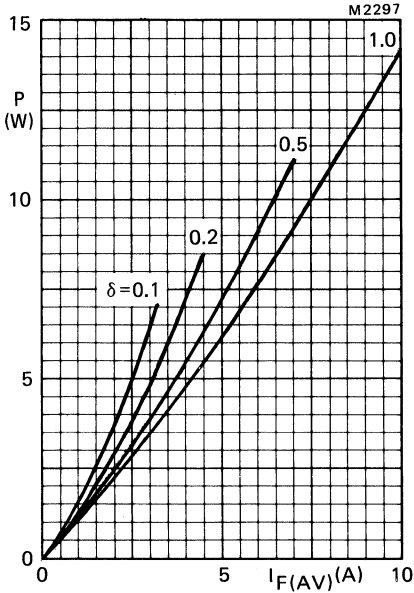
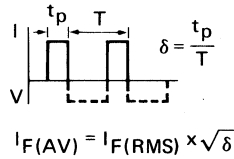


Fig.5 Power rating.

The power loss in the diode should first be determined from the required forward current on the $I_{F(AV)}$ axis and the appropriate duty cycle.

Having determined the power (P), use Fig.7 (if heatsink compound is not being used) or Fig.8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.



SINUSOIDAL OPERATION

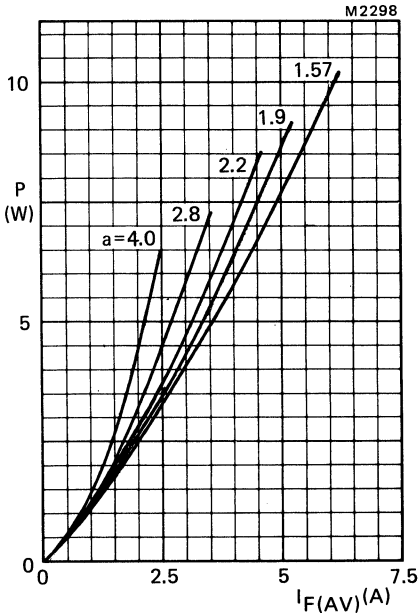


Fig.6 Power rating.

The power loss in the diode should first be determined from the required forward current on the $I_{F(AV)}$ axis and the appropriate form factor.

Having determined the power (P), use Fig.7 (if heatsink compound is not being used) or Fig.8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$

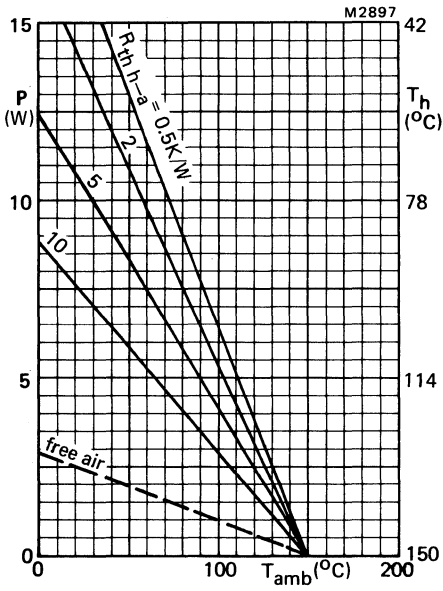


Fig.7 Heatsink rating; without heatsink compound.

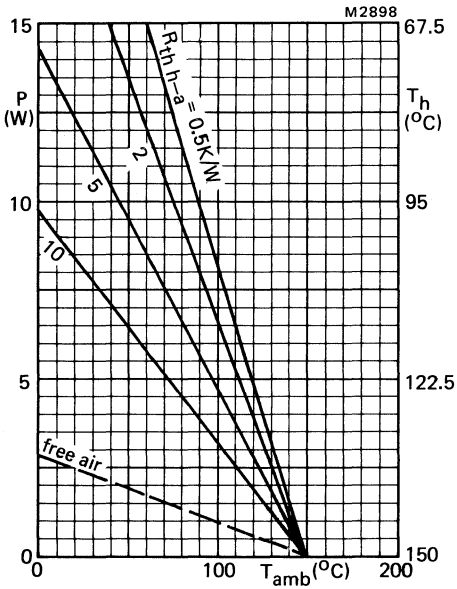


Fig.8 Heatsink rating; with heatsink compound.

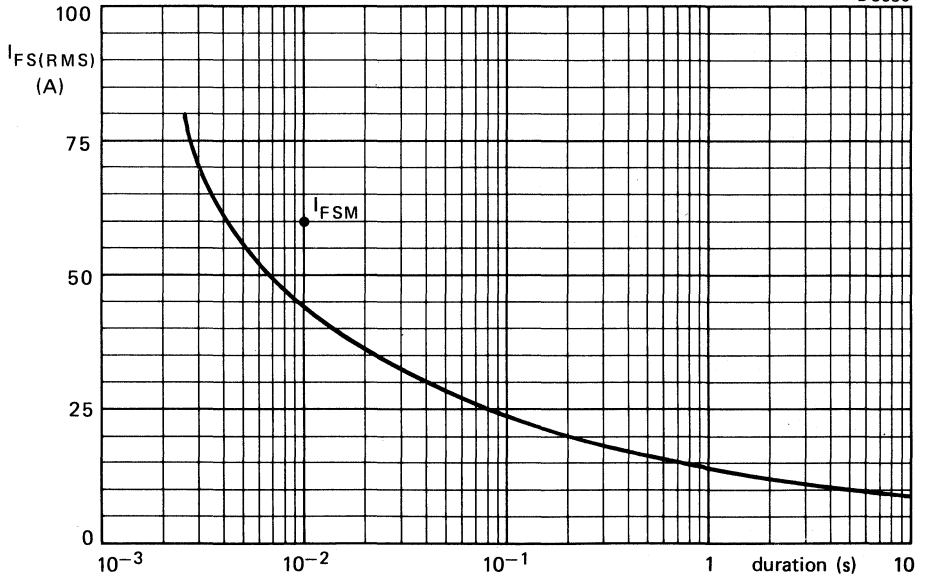


Fig.9 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 150$ °C prior to surge; with reapplied V_{RWMmax} .

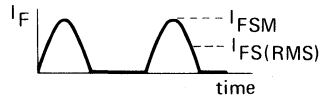
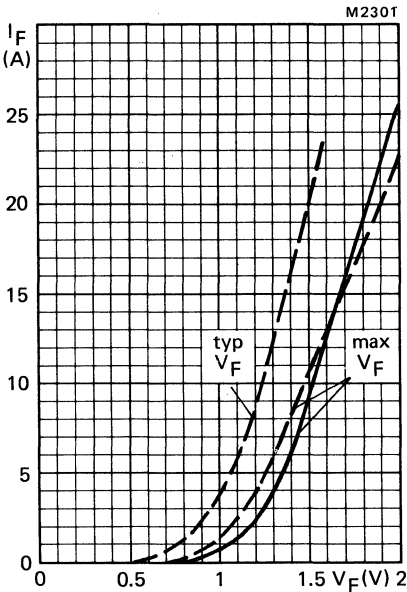


Fig.10 ——— $T_j = 25$ °C; - - - - $T_j = 125$ °C.

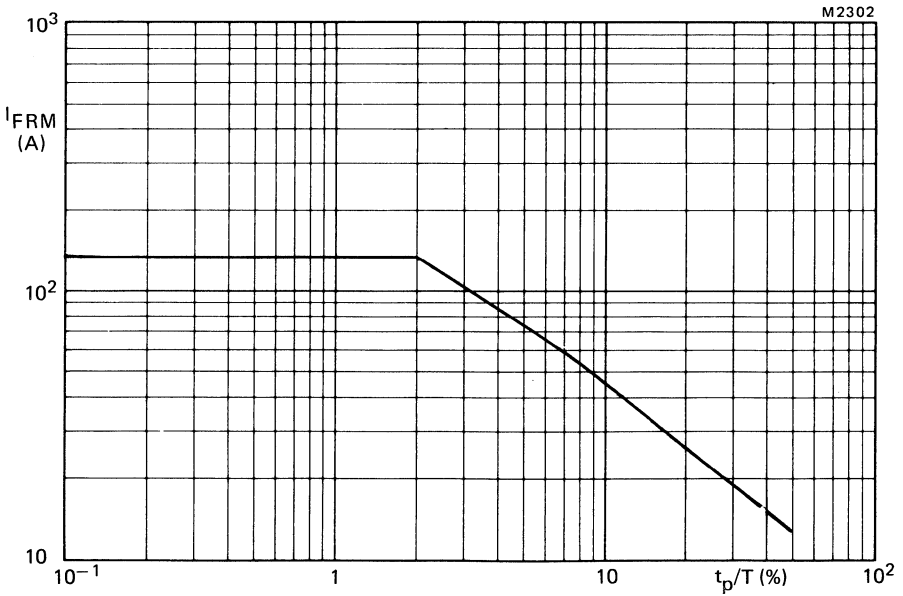
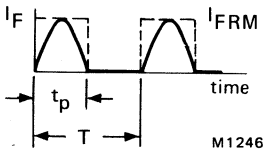


Fig.11 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM}
and t_p/T .

D8382

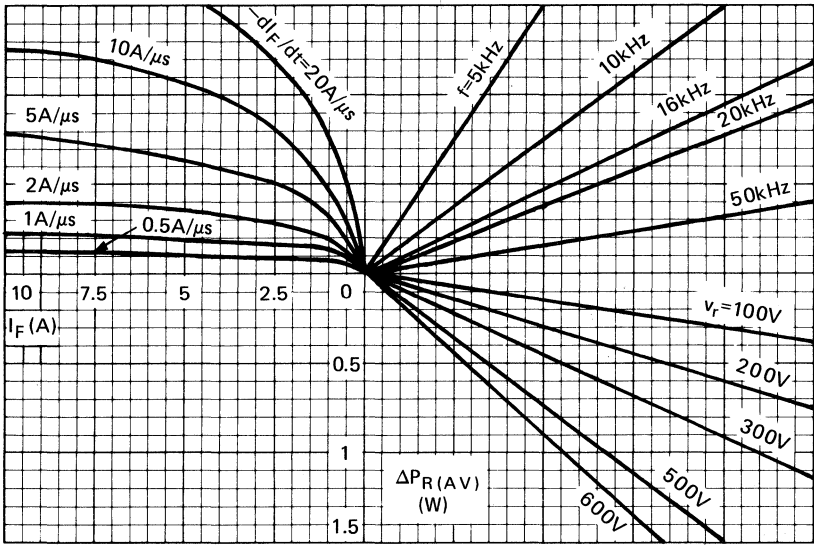
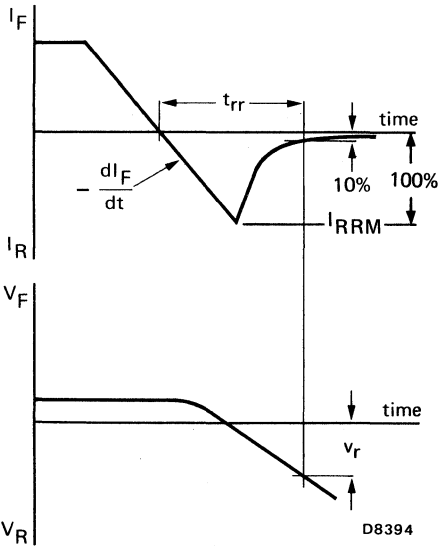


Fig.12 NOMOGRAM

Power loss $\Delta P_R(AV)$ due to switching only (to be added to steady state power losses).
 I_F = forward current just before switching off; $T_j = 150^\circ C$.



D8394

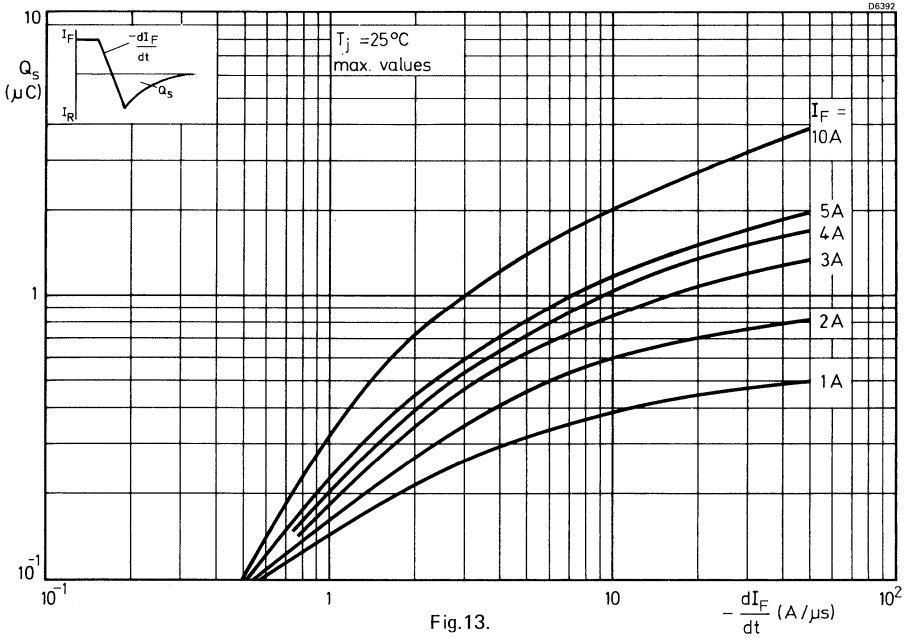


Fig. 13.

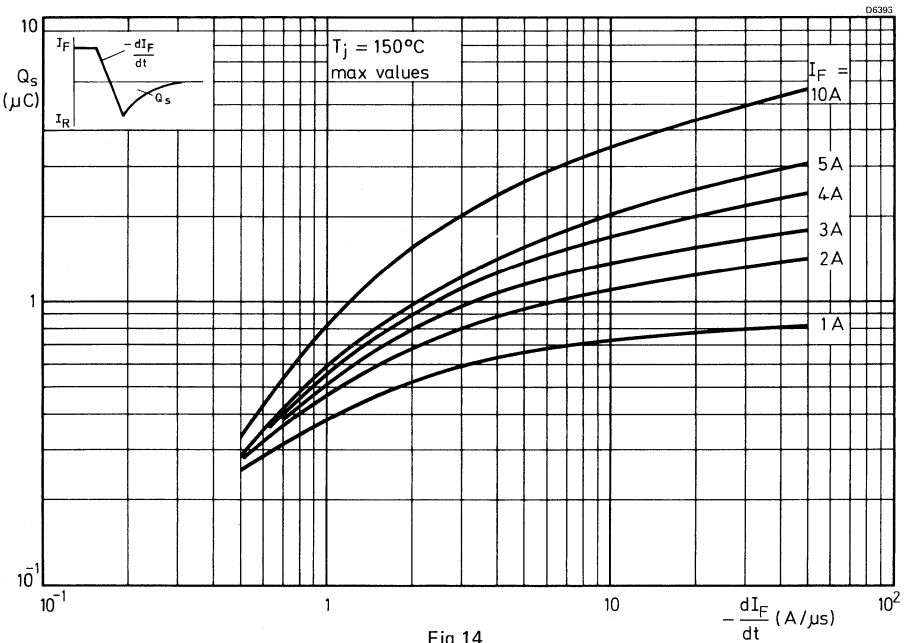


Fig. 14.

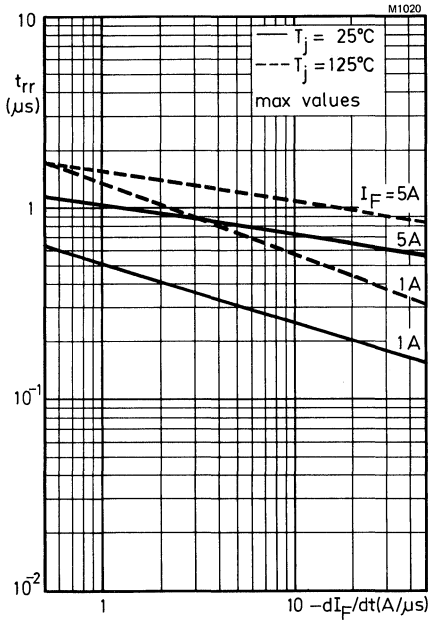


Fig.15.

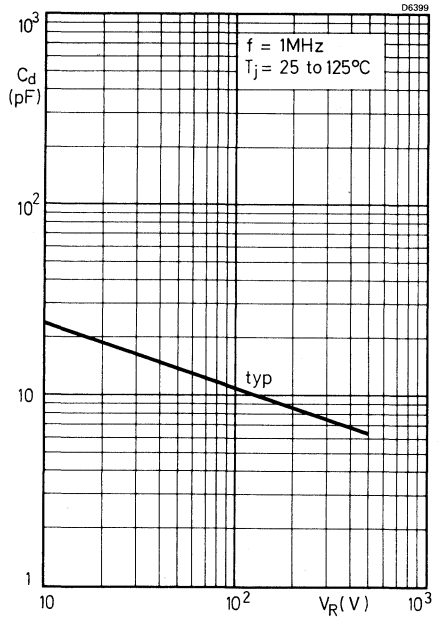


Fig.16.

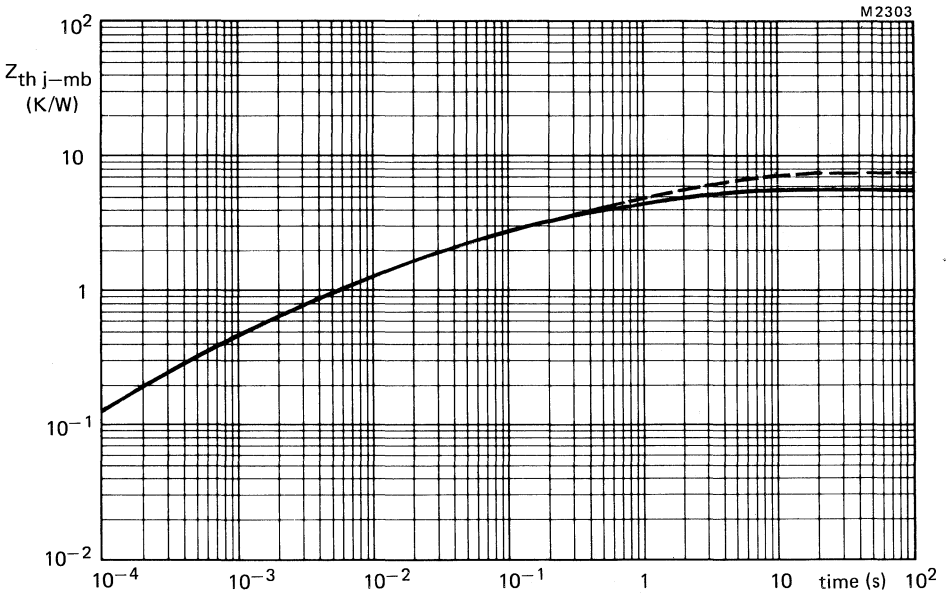


Fig.17 — with heatsink compound; - - - without heatsink compound.

FAST SOFT-RECOVERY RECTIFIER DIODES

Glass-passivated double-diffused rectifier diodes in plastic envelopes, featuring fast reverse recovery times and non-snap-off characteristics. They are intended for use in chopper applications as well as in switched-mode power supplies, as efficiency diodes and scan rectifiers in television receivers. The series consists of normal polarity types (cathode to mounting base).

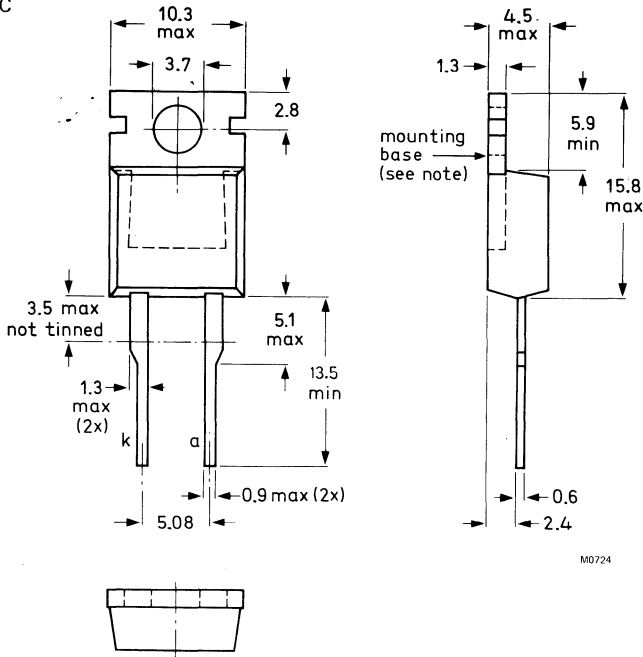
QUICK REFERENCE DATA

		BY329-800	1000	1200	
Repetitive peak reverse voltage	V_{RRM}	max. 800	1000	1200	V
Average forward current	$I_F(AV)$	max. 8	8		A
Non-repetitive peak forward current	I_{FSM}	max. 80	80		A
Reverse recovery time	t_{rr}	<	150		ns

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AC



M0724

Note: The exposed metal mounting base is directly connected to the cathode. Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages

		BY329-800	1000	1200	
Non-repetitive peak reverse voltage	V_{RSM}	max. 800	1000	1200	V
Repetitive peak reverse voltage	V_{RRM}	max. 800	1000	1200	V
Crest working reverse voltage	V_{RWM}	max. 600	800	1000	V

Currents

Average forward current assuming zero switching losses

square-wave; $\delta = 0.5$; up to $T_{mb} = 108^\circ\text{C}$

$I_F(AV)$ max. 8 A

square-wave; $\delta = 0.5$; at $T_{mb} = 125^\circ\text{C}$

$I_F(AV)$ max. 5.3 A

sinusoidal; up to $T_{mb} = 113^\circ\text{C}$

$I_F(AV)$ max. 7 A

sinusoidal; at $T_{mb} = 125^\circ\text{C}$

$I_F(AV)$ max. 5.2 A

R.M.S. forward current

$I_F(RMS)$ max. 11 A

Repetitive peak forward current

I_{FRM} max. 80 A

Non-repetitive peak forward current: $t = 10$ ms

half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge;

with reapplied V_{RWM} max

I_{FSM} max. 80 A

→ $I^2 t$ for fusing ($t = 10$ ms)

$I^2 t$ max. 32 A^2s

Temperatures

Storage temperature

T_{stg} -40 to +150 $^\circ\text{C}$

Junction temperature

T_j max. 150 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base

$R_{th\ j-mb}$ = 3.0 K/W

Influence of mounting method

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$R_{th\ mb-h}$ = 0.3 K/W

b. with heatsink compound and 0.06 mm maximum mica insulator

$R_{th\ mb-h}$ = 1.4 K/W

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$R_{th\ mb-h}$ = 2.2 K/W

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$R_{th\ mb-h}$ = 0.8 K/W

e. without heatsink compound

$R_{th\ mb-h}$ = 1.4 K/W

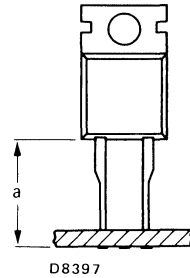
THERMAL RESISTANCE (continued)

2. Free-air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie-point. Thermal resistance from junction to ambient in free air: mounted on a printed-circuit board at a = any lead length.

$$R_{th\ j-a} = 60 \text{ } ^\circ\text{C/W}$$

Fig.2



CHARACTERISTICS

Forward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ } ^\circ\text{C}$$

$$V_F < 1.85 \text{ V}^*$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ } ^\circ\text{C}$$

$$I_R < 1.0 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ } ^\circ\text{C}$$

Recovered charge

$$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ } ^\circ\text{C}$$

$$Q_s < 0.7 \text{ } \mu\text{C}$$

Recovery time

$$t_{rr} < 150 \text{ ns}$$

Maximum slope of the reverse recovery current

$$I_F = 2 \text{ A}; -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ } ^\circ\text{C}$$

$$|dI_R/dt| < 60 \text{ A}/\mu\text{s}$$

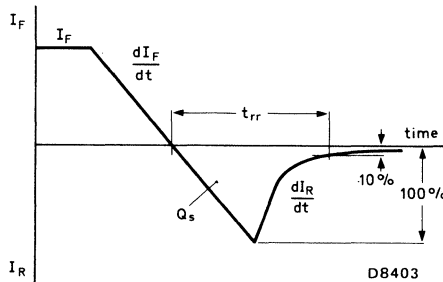


Fig.3 Definition of t_{rr} and Q_s

*Measured under pulse conditions to avoid excessive dissipation

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. It is recommended that the circuit connection be made to the cathode tag, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than screw mounting;
 - b. safe isolation for mains operation.However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting (only possible for non-insulated mounting).

Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

SQUARE-WAVE OPERATION

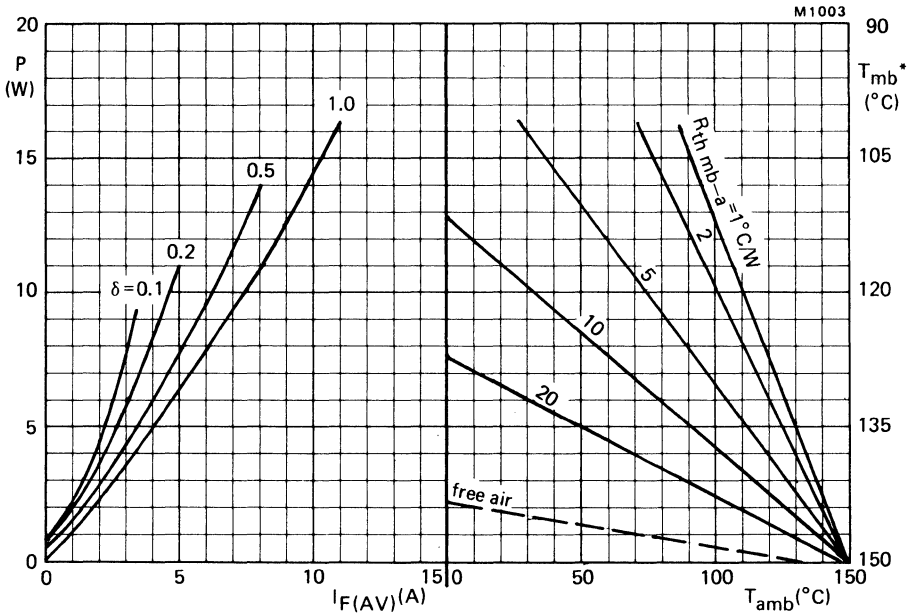
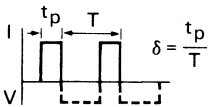


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.
 P = power including reverse current losses but excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 10^{\circ}C/W$.

SINUSOIDAL OPERATION

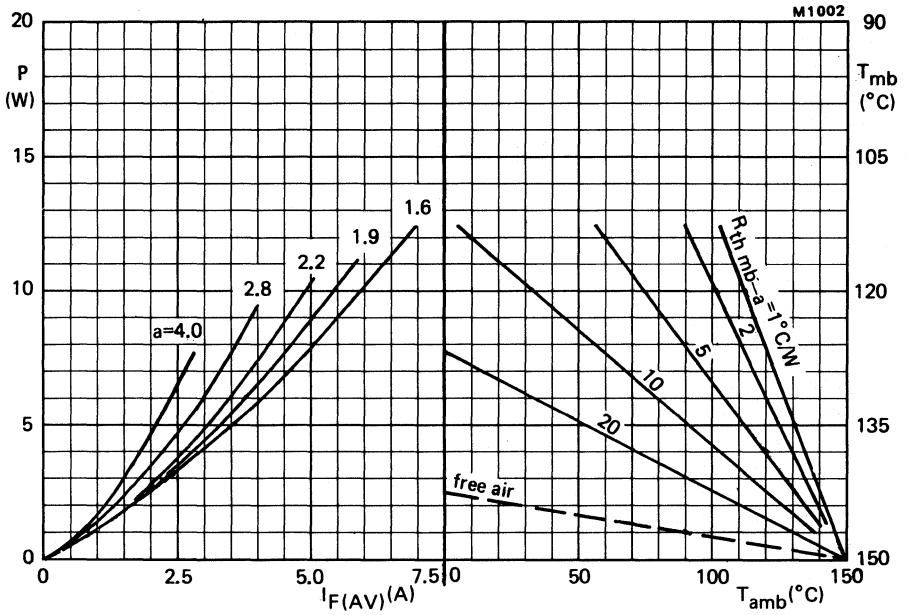


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.

a = form factor = $I_F(RMS)/I_F(AV)$.

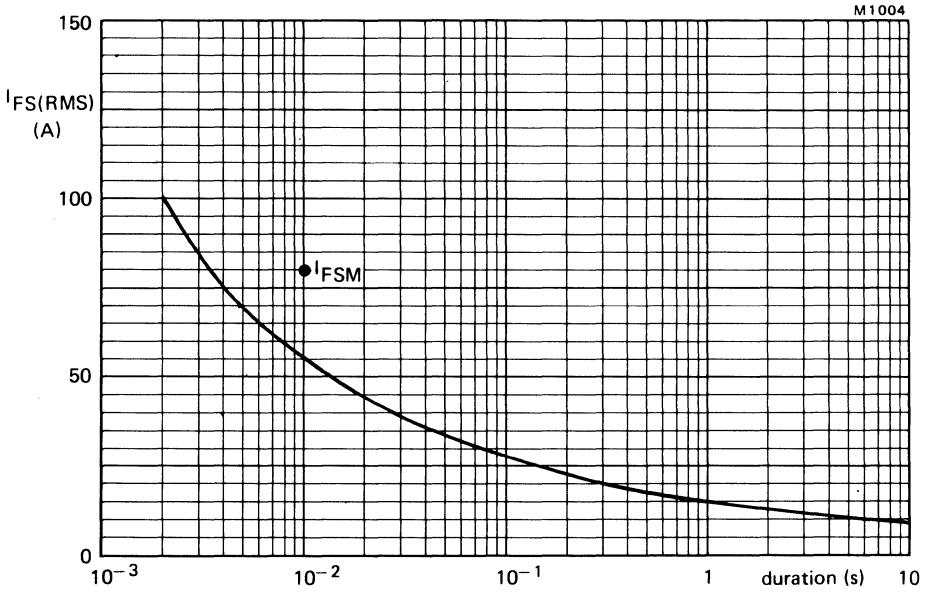


Fig.6 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 150$ °C prior to surge; with reapplied V_{RWMmax} .

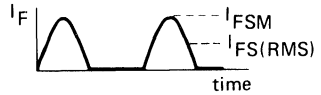
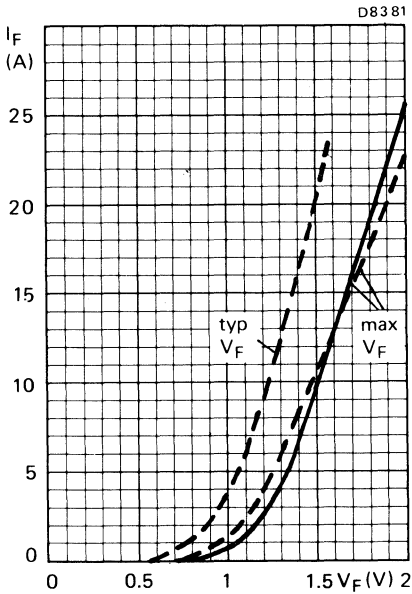


Fig.7 ———— $T_j = 25$ °C; - - - - $T_j = 125$ °C

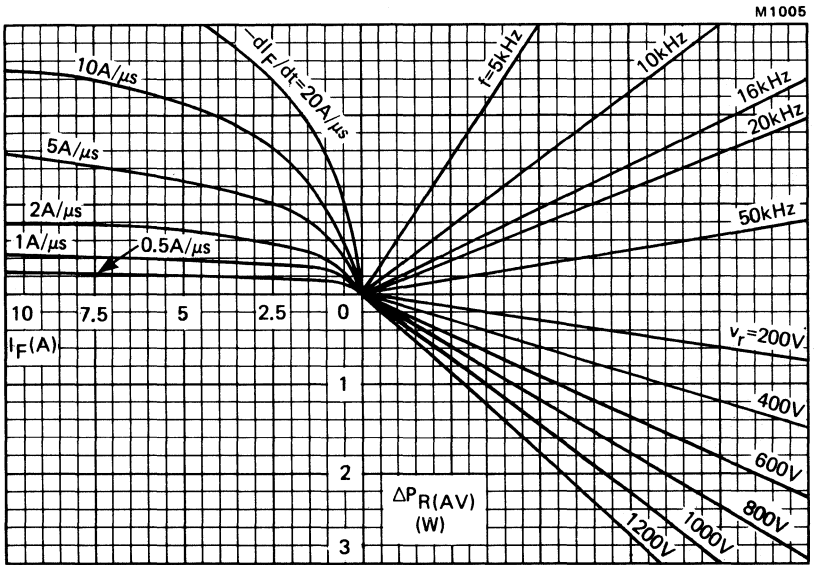
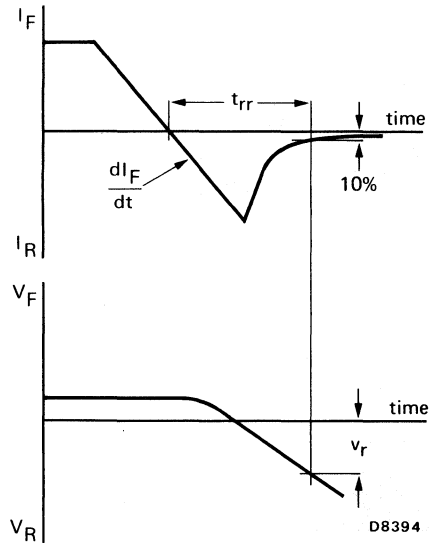
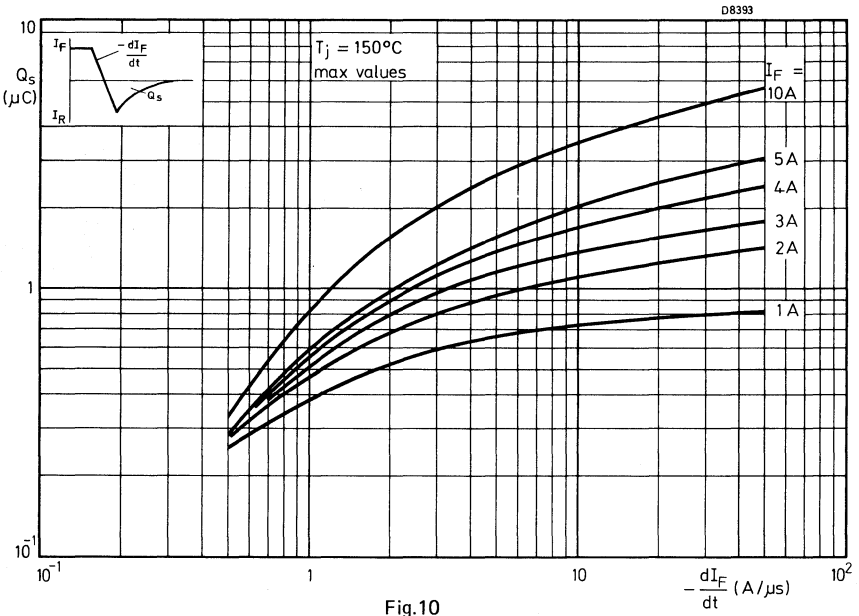
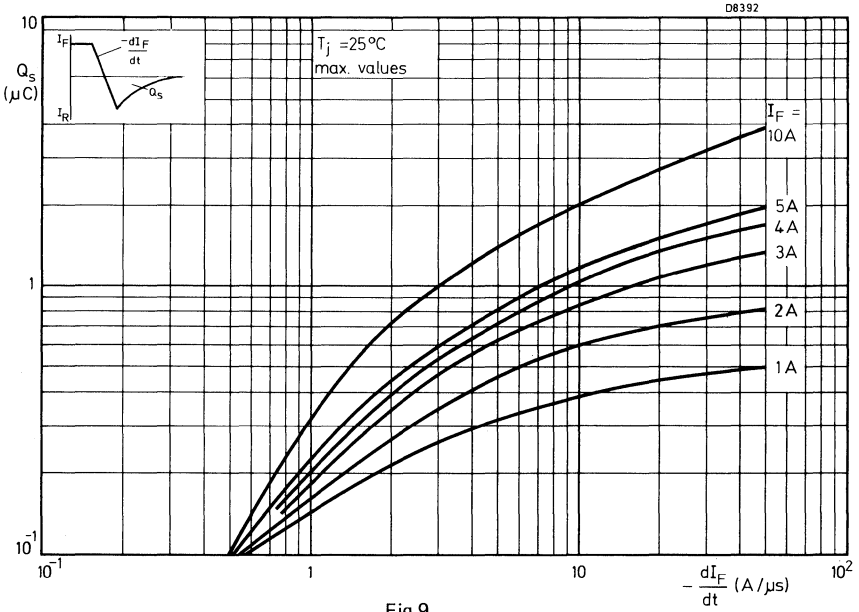


Fig.8 NOMOGRAM

Power loss $\Delta P_{R(AV)}$ due to switching only (to be added to steady state power losses).
 I_F = forward current just before switching off; $T_j = 150^\circ\text{C}$





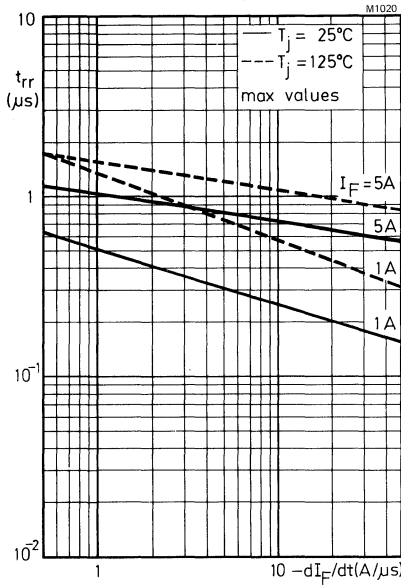


Fig.11

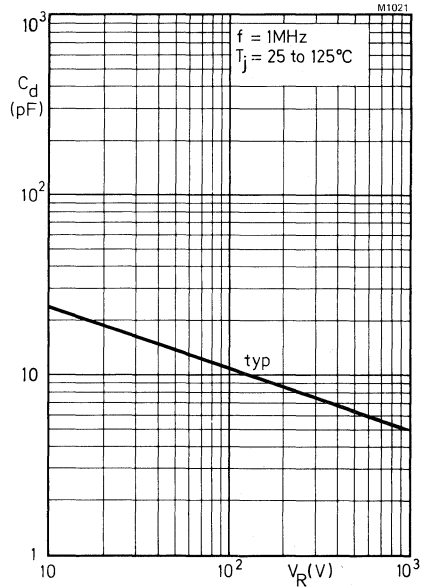


Fig.12

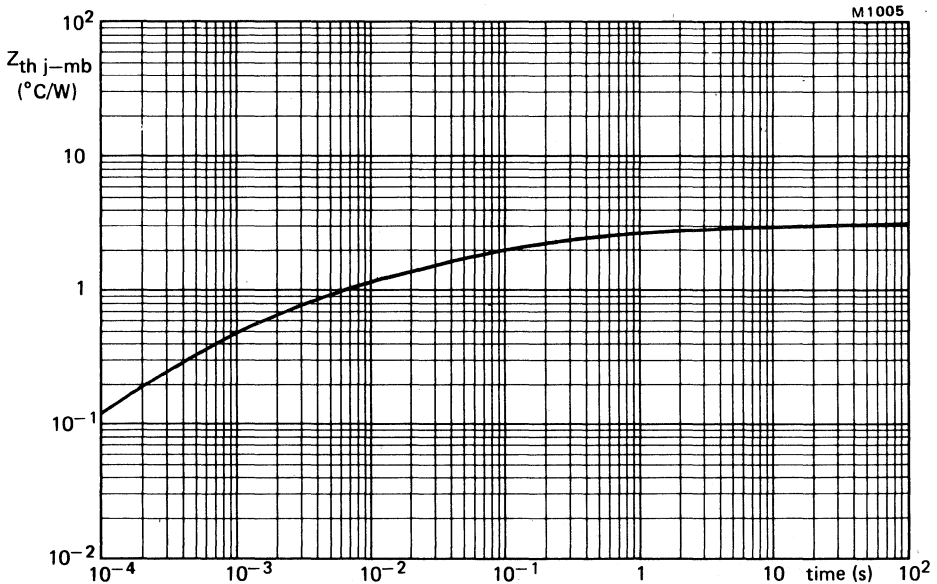


Fig.13

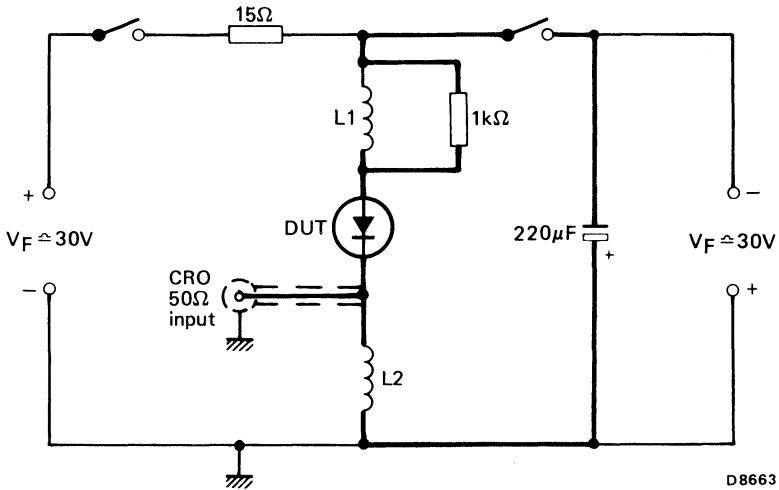


Fig.14 Simplified circuit diagram of practical apparatus to test softness of recovery.

NOTES

1. Duty factor of forward current should be low, $< 2\%$.
2. dI_F/dt is set by L1, $1.5 \mu H$ gives $20 A/\mu s$.
3. dI_R/dt is measured across L2, $200 nH$ gives $5 A/\mu s/V$.
4. Wiring shown in heavy should be kept as short as possible.

FAST HIGH-VOLTAGE RECTIFIER DIODES

Glass-passivated double-diffused rectifier diodes in TO-220 plastic envelopes, featuring fast recovery times. They are intended for use as an anti-parallel diode to GTOs and similar high-voltage switches, in chopper applications such as Series Resonant Power Supplies (SRPS) and other high-voltage circuits. The series consists of normal polarity types (cathode to mounting base).

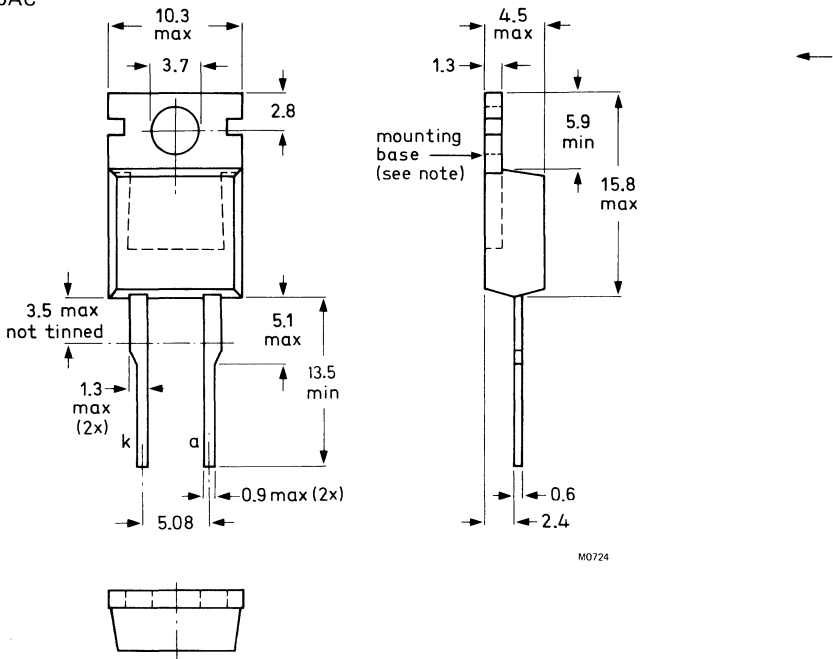
QUICK REFERENCE DATA

		BY359-1000			1300	1500	
Repetitive peak reverse voltage	V_{RRM}	max.	1000	1300	1500		V
Average forward current	$I_{F(AV)}$	max.		6.5			A
Non-repetitive peak forward current	I_{FSM}	max.		60			A
Reverse recovery time	t_{rr}	<		0.6			μs

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AC



Note: The exposed metal mounting base is directly connected to the cathode. Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages*

		BY359-1000	1300	1500	
Non-repetitive peak reverse voltage	V_{RSM}	max. 1100	1500	1650	
Repetitive peak reverse voltage	V_{RRM}	max. 1000	1300	1500	V
Crest working reverse voltage	V_{RWM}	max. 800	1200	1300	V
Continuous reverse voltage	V_R	max. 600	750	800	V

Currents

Average forward current assuming zero switching losses sinusoidal; up to $T_{mb} = 94\text{ }^\circ\text{C}$

$I_{F(AV)}$ max. 6.5 A

R.M.S. forward current

$I_{F(RMS)}$ max. 10 A

Repetitive peak forward current

I_{FRM} max. 60 A

Non-repetitive peak forward current: $t = 10\text{ ms}$ half sine-wave; $T_j = 125\text{ }^\circ\text{C}$ prior to surge; with reapplied $V_{RWM\text{ max}}$

I_{FSM} max. 60 A

Temperatures

Storage temperature

T_{stg} -40 to +150 $^\circ\text{C}$

Junction temperature

T_j max. 125 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base

$R_{th\ j-mb}$ = 3.0 $^\circ\text{C/W}$

Influence of mounting method

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$R_{th\ mb-h}$ = 0.3 $^\circ\text{C/W}$

b. with heatsink compound and 0.06 mm maximum mica insulator

$R_{th\ mb-h}$ = 1.4 $^\circ\text{C/W}$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$R_{th\ mb-h}$ = 2.2 $^\circ\text{C/W}$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$R_{th\ mb-h}$ = 0.8 $^\circ\text{C/W}$

e. without heatsink compound

$R_{th\ mb-h}$ = 1.4 $^\circ\text{C/W}$

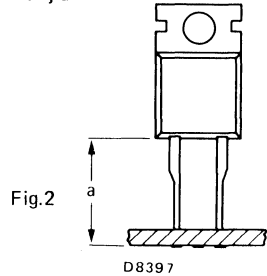
*To ensure thermal stability: $R_{th\ j-a} \leq 10.4\text{ }^\circ\text{C/W}$ for continuous reverse voltage.

THERMAL RESISTANCE (continued)

2. Free-air operation

The quoted value of $R_{th j-a}$ should be used only when no leads of other dissipating components run to the same tie-point. Thermal resistance from junction to ambient in free air: mounted on a printed-circuit board at a = any lead length

$$R_{th j-a} = 60 \text{ } ^\circ\text{C/W}$$



CHARACTERISTICS

Forward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ } ^\circ\text{C}$$

$$V_F < 2.3 \text{ V}^*$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 100 \text{ } ^\circ\text{C}$$

$$I_R < 0.6 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ } ^\circ\text{C}$$

recovered charge

$$Q_S < 2.0 \text{ } \mu\text{C}$$

recovery time

$$t_{rr} < 0.6 \text{ } \mu\text{s}$$

Forward recovery when switched to

$$I_F = 5 \text{ A with } t_r = 0.1 \text{ } \mu\text{s}; T_j = 25 \text{ } ^\circ\text{C}$$

recovery time

$$t_{fr} < 1.0 \text{ } \mu\text{s}$$

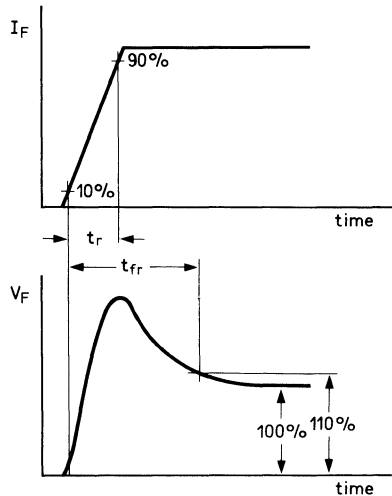
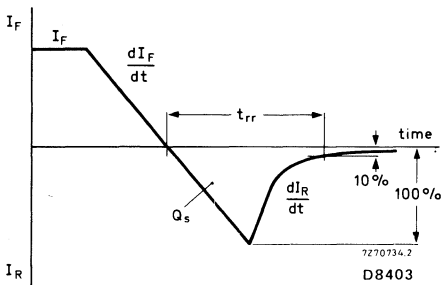


Fig.3 Definition of t_{rr} and Q_S .

Fig.4 Definition of t_{fr} .

*Measured under pulse conditions to avoid excessive dissipation

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- 2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. It is recommended that the circuit connection be made to the cathode tag, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than screw mounting;
 - b. safe isolation for mains operation.However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

SINUSOIDAL OPERATION

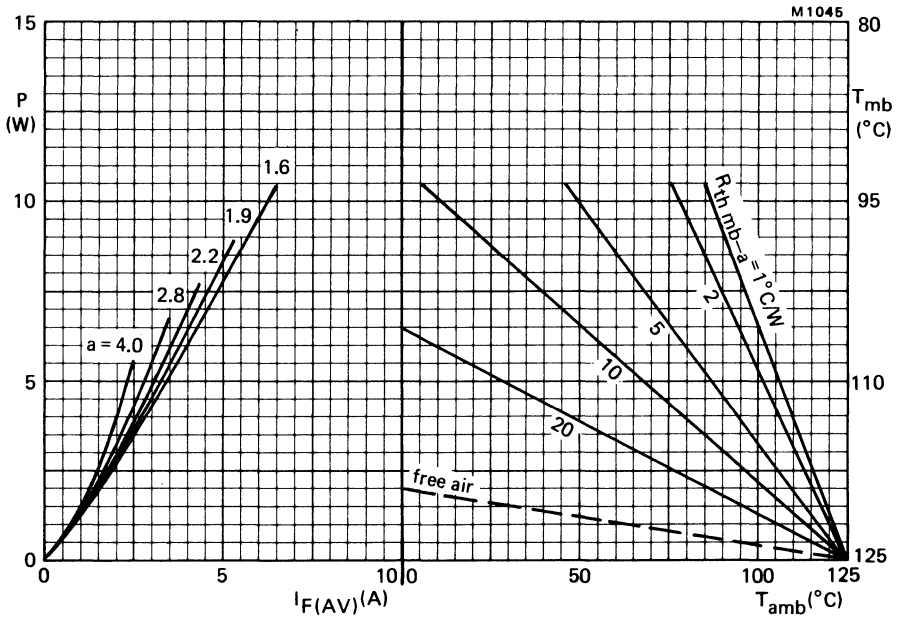


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.

a = form factor = $I_{F(RMS)}/I_{F(AV)}$.

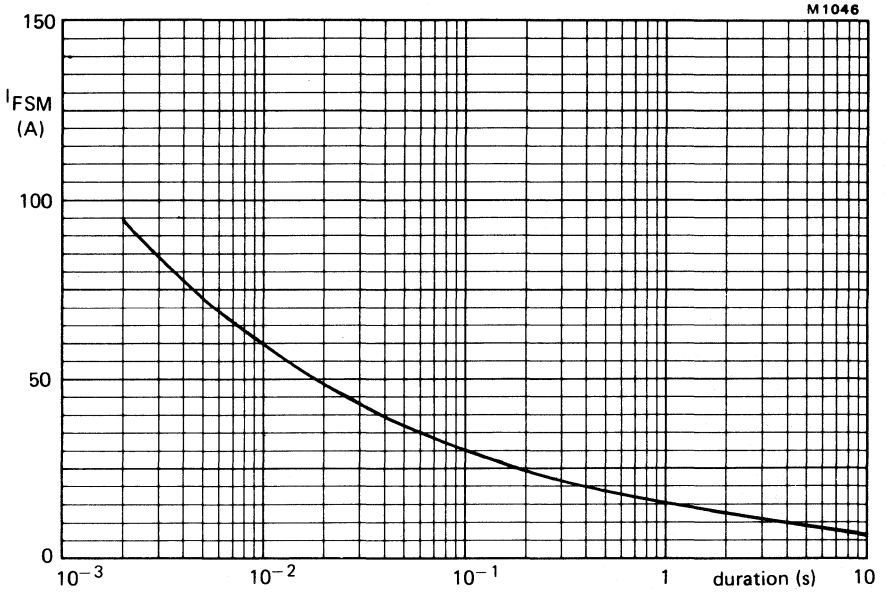


Fig.6 Maximum permissible non-repetitive peak forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 125$ °C prior to surge; with reapplied V_{RWMmax} .

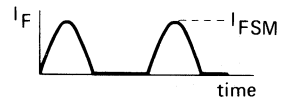
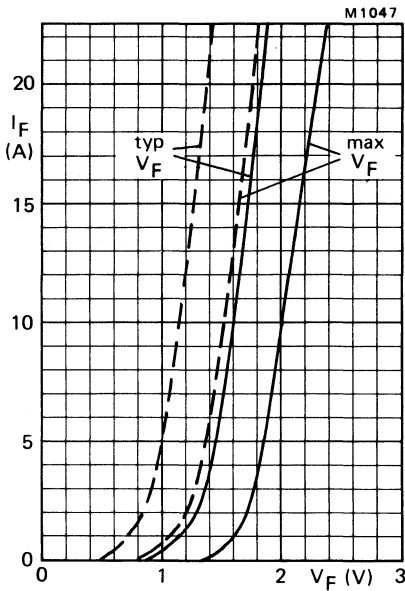


Fig.7 ——— $T_j = 25$ °C; - - - - $T_j = 100$ °C.

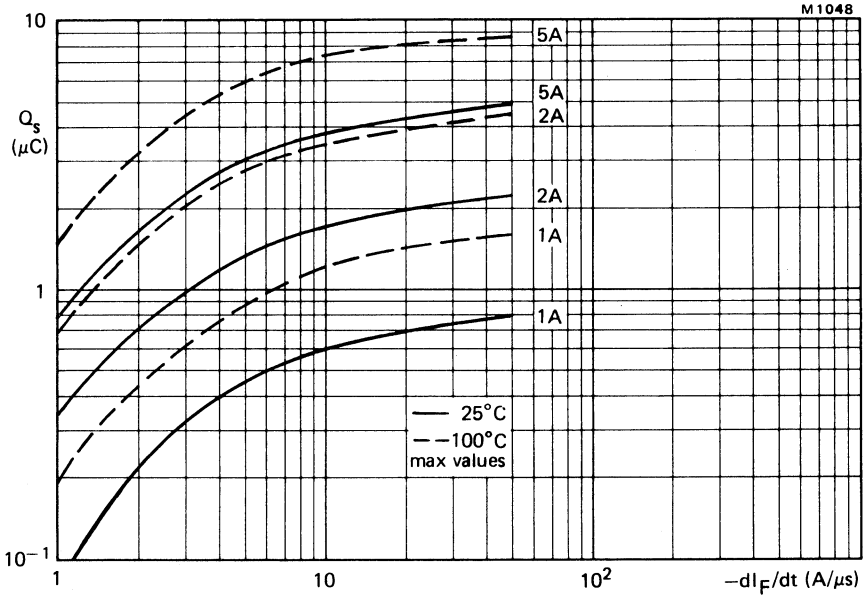


Fig.8

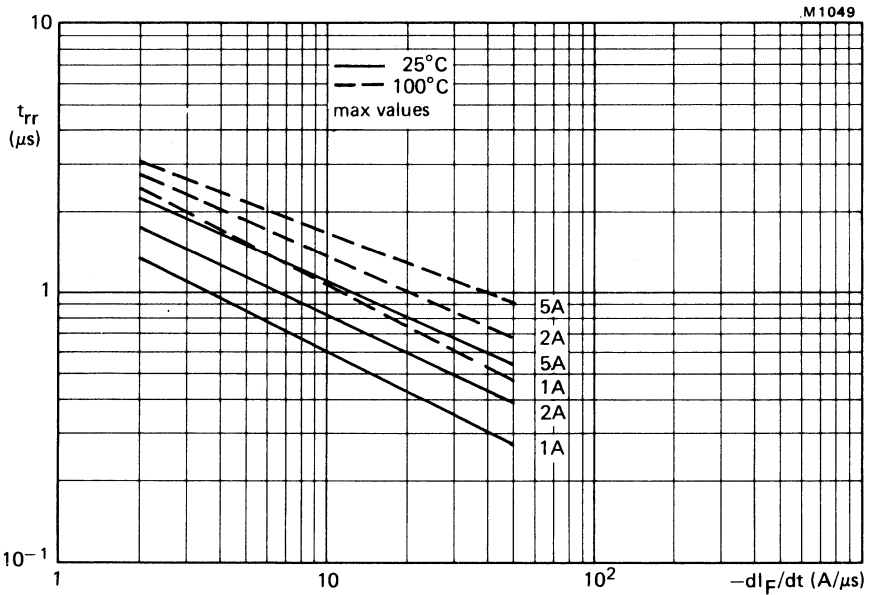


Fig.9

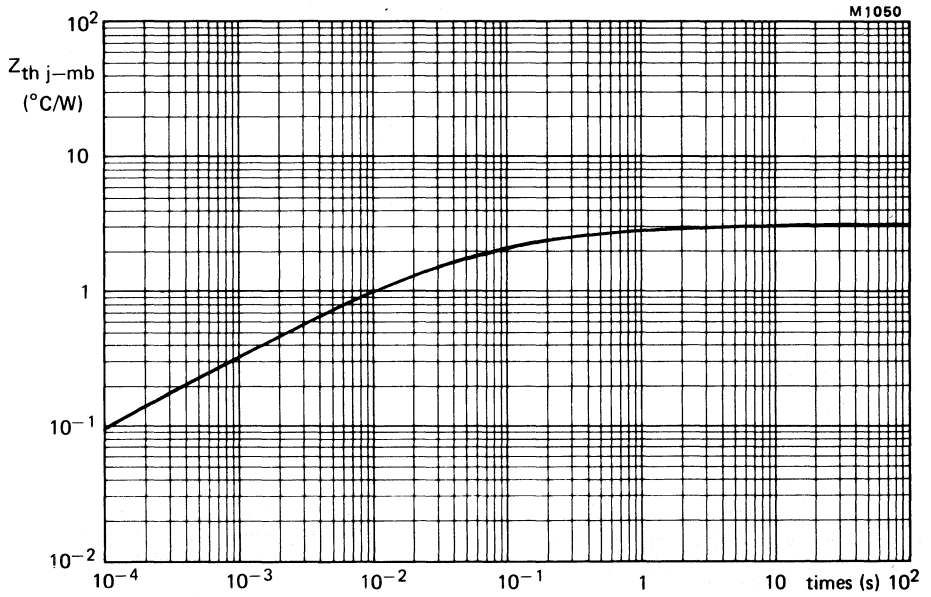


Fig.10

ULTRA FAST-RECOVERY RECTIFIER DIODES FEATURING LOW REVERSE LEAKAGE

Glass-passivated, high-efficiency epitaxial rectifier diodes in plastic envelopes, featuring low reverse leakage current, low forward voltage drop, ultra fast reverse recovery times, very low stored charge and soft recovery characteristics. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction and low switching losses are essential. The series consists of normal polarity (cathode to mounting base) types.

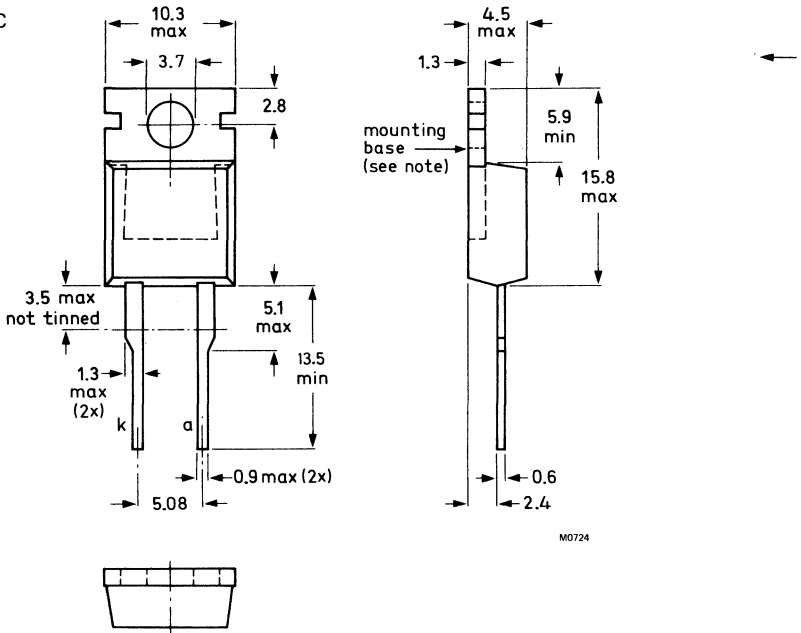
QUICK REFERENCE DATA

			BYP21-50				100	150	200	
			50	100	150	200				
Repetitive peak reverse voltage	V_{RRM}	max.							V	
Average forward current	$I_{F(AV)}$	max.	8						A	
Forward voltage	V_F	<	0.895						V	
Reverse recovery time	t_{rr}	<	25						ns	
Reverse leakage current	I_R	<	5						μA	

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AC



M0724

Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

BYP21 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

			BYP21-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max.	50	100	150	200	V
Continuous reverse voltage	V_R	max.	50	100	150	200	V

Currents

Average forward current; switching losses negligible up to 500 kHz square wave; $\delta = 0.5$; up to $T_{mb} = 150^\circ\text{C}$

$I_{F(AV)}$ max. 8 A

sinusoidal; up to $T_{mb} = 150^\circ\text{C}$

$I_{F(AV)}$ max. 9.4 A

R.M.S. forward current

$I_{F(RMS)}$ max. 11.5 A

Repetitive peak forward current
 $t_p = 20 \mu\text{s}$; $\delta = 0.02$

I_{FRM} max. 175 A

Non-repetitive peak forward current
half sine-wave; $T_j = 175^\circ\text{C}$ prior to surge; with reapplied V_{RWMmax}

$t = 10 \text{ ms}$

I_{FSM} max. 80 A

$t = 8.3 \text{ ms}$

I_{FSM} max. 100 A

$I^2 t$ for fusing ($t = 10 \text{ ms}$)

$I^2 t$ max. 32 A^2s

Temperatures

Storage temperature

T_{stg} -65 to +175 $^\circ\text{C}$

Junction temperature

T_j max. 175 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 2.7\ K/W$$

Influence of mounting method

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3\ K/W$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4\ K/W$$

c. with heatsink compound and 0.1 mm maximum mica washer (56369)

$$R_{th\ mb-h} = 2.2\ K/W$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8\ K/W$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4\ K/W$$

2. Free air operation

The quoted values of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.Thermal resistance from junction to ambient in free air:
mounted on a printed circuit board at

a = any lead length

$$R_{th\ j-a} = 60\ K/W$$

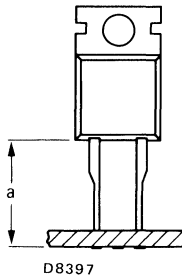


Fig.2

BYP21 SERIES

CHARACTERISTICS

Forward voltage

$$I_F = 8 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$$

$$I_F = 8 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

V_F	<	0.895	V*
V_F	<	1.045	V*
V_F	<	1.15	V*

Reverse current

$$V_R = V_{RWMmax}; T_j = 175 \text{ }^\circ\text{C}$$

$$T_j = 125 \text{ }^\circ\text{C}$$

$$T_j = 100 \text{ }^\circ\text{C}$$

$$T_j = 25 \text{ }^\circ\text{C}$$

I_R	<	500	μA
I_R	<	250	μA
I_R	<	50	μA
I_R	<	5	μA

Reverse recovery when switched from

$$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s};$$

$$T_j = 25 \text{ }^\circ\text{C}; \text{ recovery time}$$

t_{rr}	<	25	ns
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Step reverse recovery when switched from

$$I_F = 0.5 \text{ A to } I_R = 1 \text{ A, measured at}$$

$$I_{RR} = 0.25 \text{ A; recovery time}$$

t_{rr}	<	25	ns
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$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s};$$

$$T_j = 25 \text{ }^\circ\text{C}; \text{ recovered charge}$$

Q_s	<	15	nC
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$$I_F = 10 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s};$$

$$T_j = 100 \text{ }^\circ\text{C}; \text{ peak recovery current}$$

I_{RRM}	<	2	A
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Forward recovery when switched to $I_F = 1 \text{ A}$

$$\text{with } dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

V_{fr}	typ.	0.9	V
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M80-1319/3

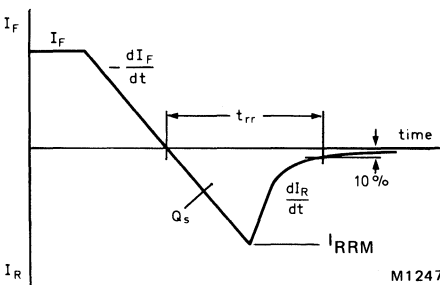


Fig.3 Definition of t_{rr} , Q_s and I_{RRM} .

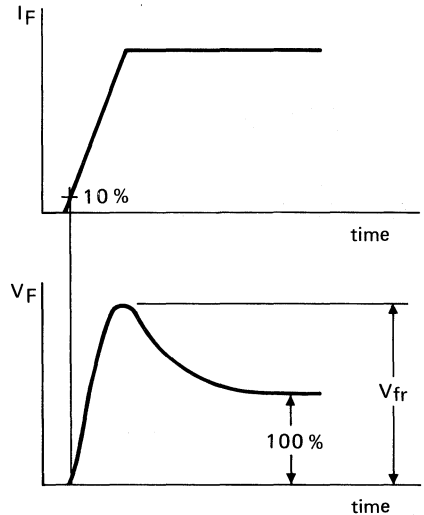


Fig.4 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275°C ; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
- Mounting by means of a spring clip is the best mounting method because it offers:
 - a good thermal contact under the crystal area and slightly lower $R_{\text{th mb-h}}$ values than does screw mounting.
 - safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{\text{th mb-h}}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
- Rivet mounting (only possible for non-insulated mounting). Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink considerations:

- The various components of junction temperature rise above ambient are illustrated below:

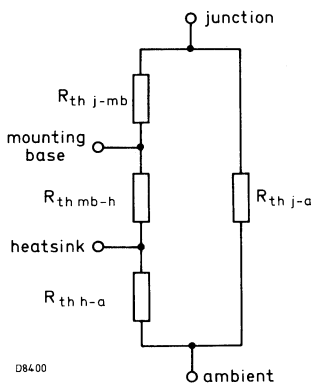


Fig.5

- The method of using Figs.6 and 7 is as follows:

Starting with the required current on the $I_F(AV)$ axis, trace upwards to meet the appropriate duty factor or form factor curve. Trace right horizontally and upwards from the appropriate value on the T_{amb} scale. The intersection determines the $R_{\text{th mb-a}}$. The heatsink thermal resistance value ($R_{\text{th h-a}}$) can now be calculated from:

$$R_{\text{th h-a}} = R_{\text{th mb-a}} - R_{\text{th mb-h}}$$

- Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION

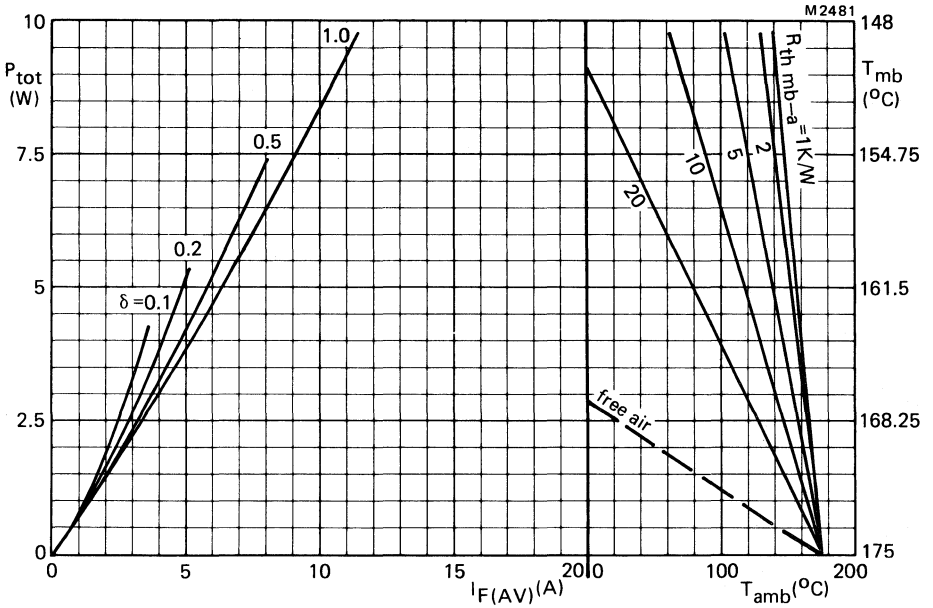
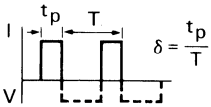


Fig.6 The right-hand part shows the relationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 500$ kHz.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

SINUSOIDAL OPERATION

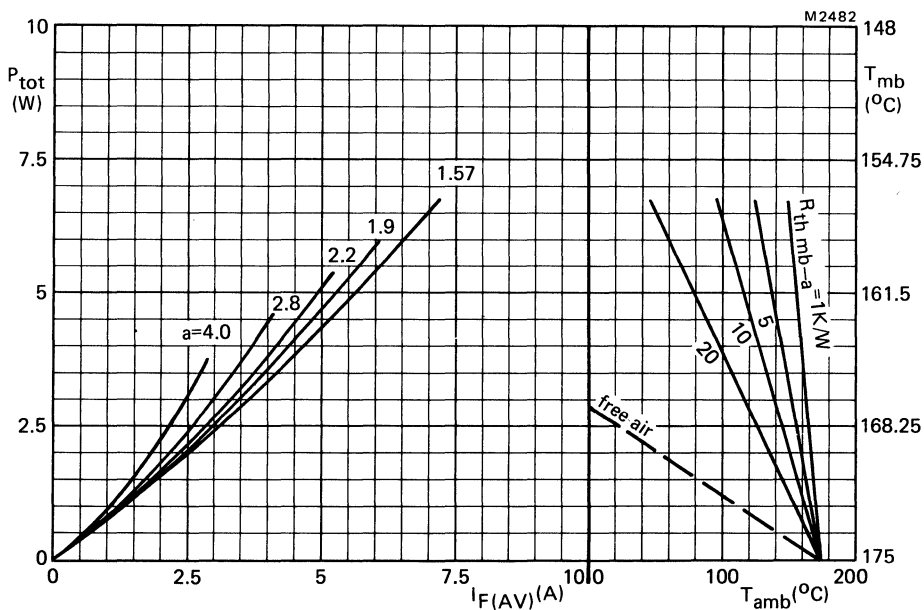


Fig.7 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$a = \text{form factor} = I_F(RMS)/I_F(AV)$.

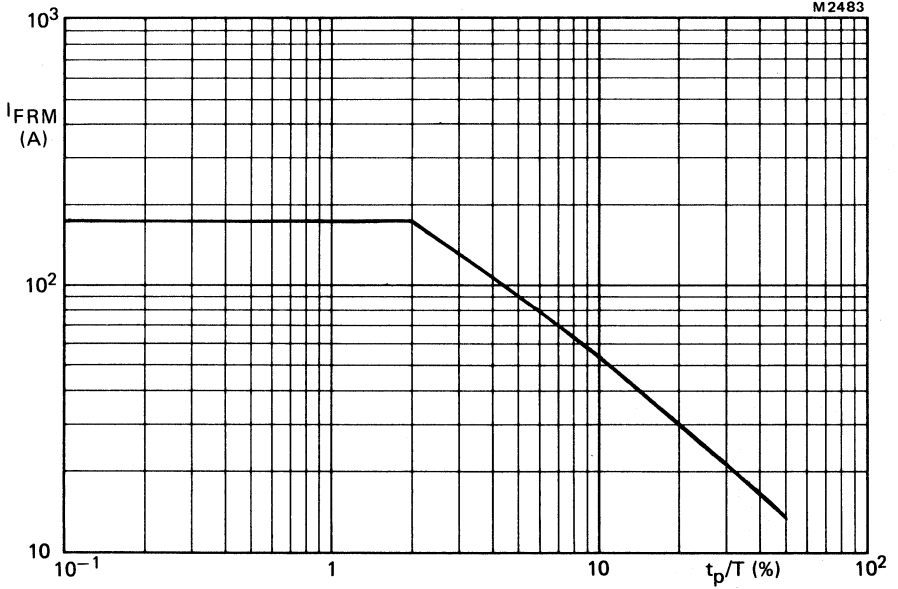


Fig.8 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1$ ms.

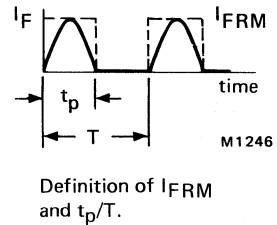
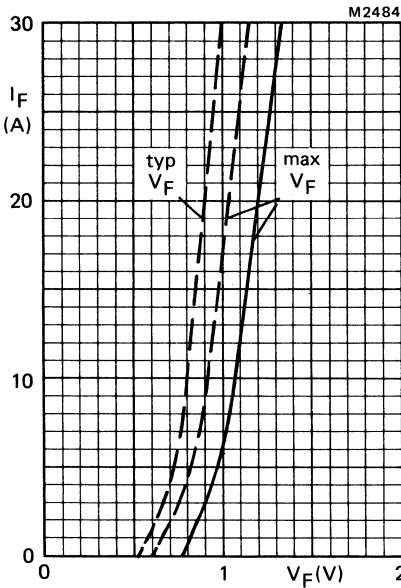


Fig.9 ——— $T_j = 25^\circ C$; - - - $T_j = 100^\circ C$.

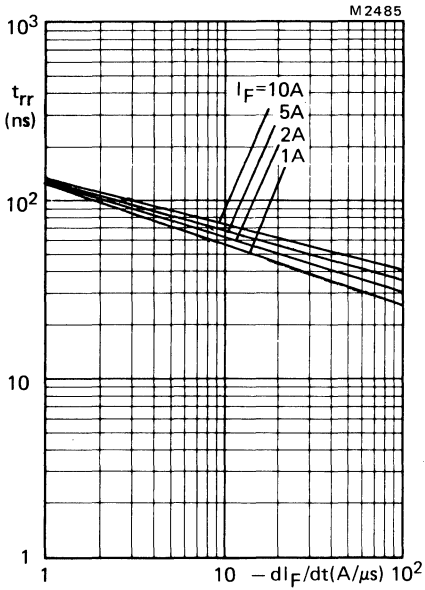


Fig.10 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

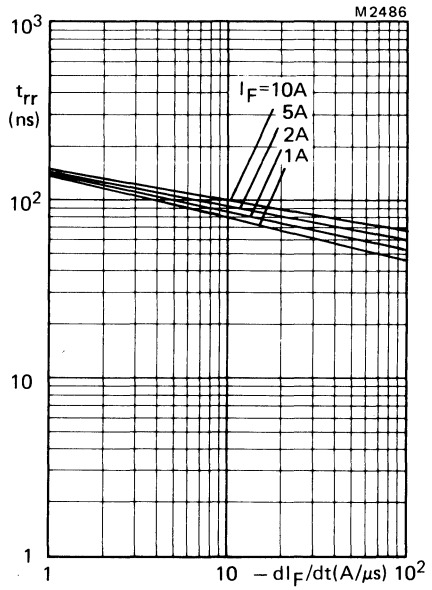


Fig.11 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

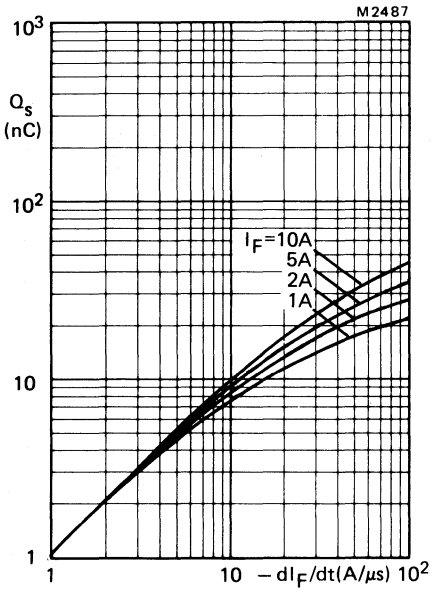


Fig.12 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

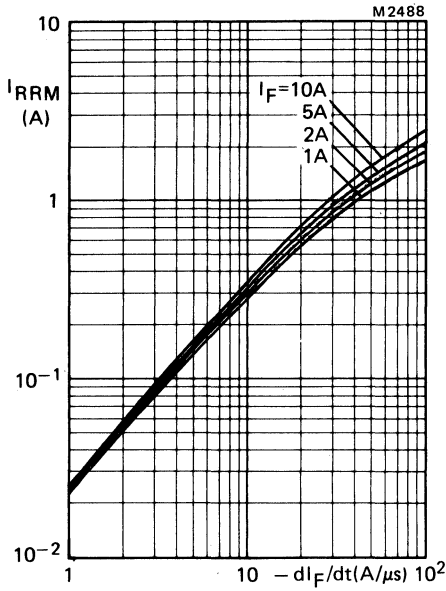


Fig.13 Maximum I_{RRM} at $T_j = 25$ °C.

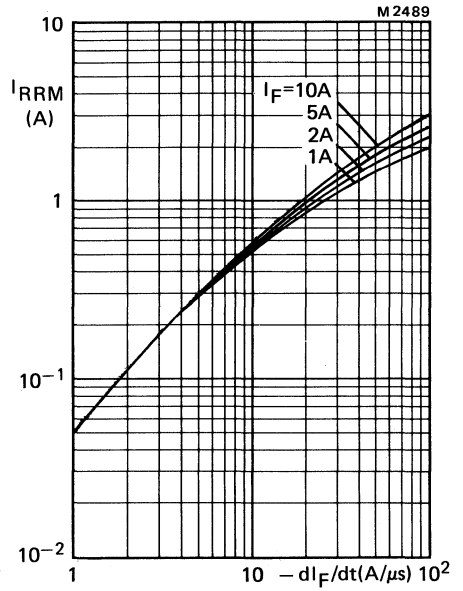


Fig.14 Maximum I_{RRM} at $T_j = 100$ °C.

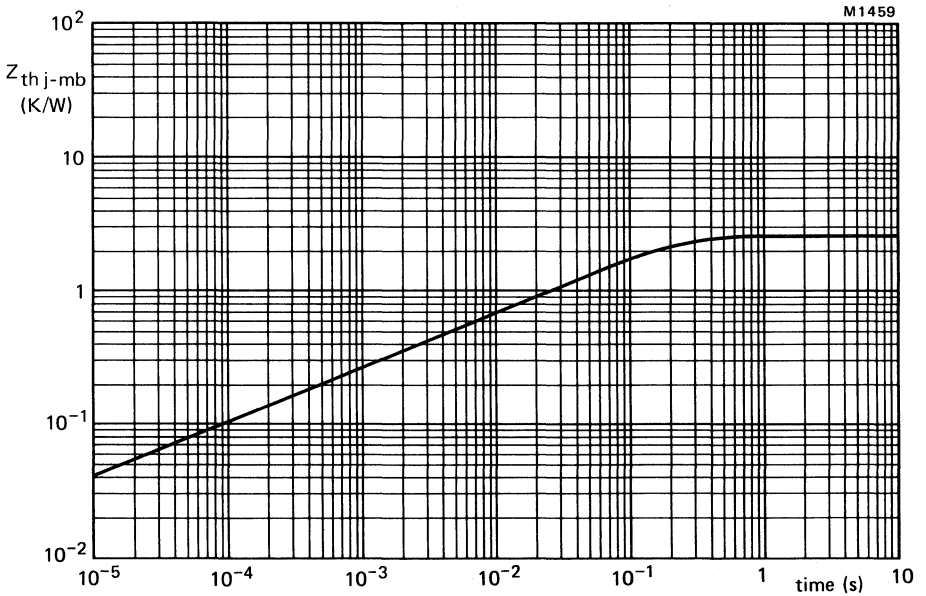


Fig.15 Transient thermal impedance.

ULTRA FAST-RECOVERY DOUBLE RECTIFIER DIODES FEATURING LOW REVERSE LEAKAGE

Glass-passivated, high-efficiency epitaxial rectifier diodes in plastic envelopes, featuring low reverse leakage current, low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft recovery characteristics. They are intended for use in switched-mode power supplies and high frequency circuits in general, where both low conduction and low switching losses are essential. Their single chip construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common-cathode types.

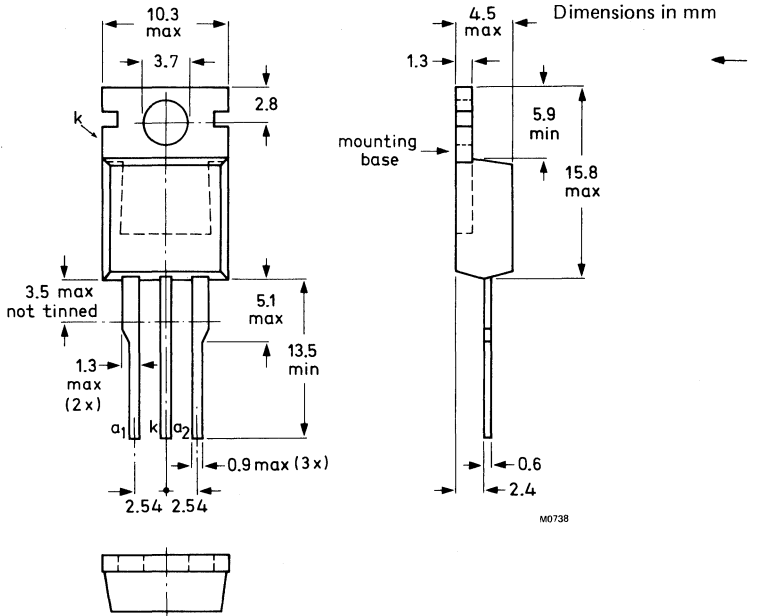
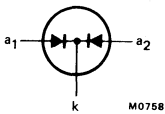
QUICK REFERENCE DATA

Per diode, unless otherwise stated

			BYP22-50				V
			50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200	V
Output current (both diodes conducting)	I_O	max.			20		A
Forward voltage	V_F	<			0.895		V
Reverse recovery time	t_{rr}	<			25		ns
Reverse leakage current	I_R	<			5		μA

MECHANICAL DATA

Fig.1 TO-220AB



Net mass: 2 g

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

			BYP22-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max.	50	100	150	200	V
Continuous reverse voltage	V_R	max.	50	100	150	200	V

Currents (both diodes conducting; note 1)

Output current; switching

losses negligible up to 500 kHz;

square wave; $\delta = 0.5$;

up to $T_{mb} = 150^\circ\text{C}$

I_O	max.	16	A
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square wave; $\delta = 0.5$;

up to $T_{mb} = 143^\circ\text{C}$

I_O	max.	20	A
-------	------	----	---

sinusoidal; up to $T_{mb} = 150^\circ\text{C}$

I_O	max.	16	A
-------	------	----	---

R.M.S. forward current	$I_F(\text{RMS})$	max.	20	A
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Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$ (note 2)

I_{FRM}	max.	230	A
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Non-repetitive peak forward current

half sine-wave; $T_j = 175^\circ\text{C}$ prior to

surge; with reapplied V_{RWM} max. (note 2)

$t = 10 \text{ ms}$

I_{FSM}	max.	140	A
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$t = 8.3 \text{ ms}$

I_{FSM}	max.	150	A
-----------	------	-----	---

$I^2 t$ for fusing ($t = 10 \text{ ms}$; note 2)	$I^2 t$	max.	98	A^2s
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Temperatures

Storage temperature	T_{stg}		-65 to +175	$^\circ\text{C}$
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Junction temperature	T_j	max.	175	$^\circ\text{C}$
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Notes

1. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
2. Figures apply to each diode.

THERMAL RESISTANCE

From junction to mounting base; total package	$R_{th\ j-mb}$	=	1.6	K/W
per diode	$R_{th\ j-mb}$	=	2.4	K/W

Influence of mounting method

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound	$R_{th\ mb-h}$	=	0.3	K/W
b. with heatsink compound and 0.06 mm maximum mica insulator	$R_{th\ mb-h}$	=	1.4	K/W
c. with heatsink compound and 0.1 mm maximum mica washer (56369)	$R_{th\ mb-h}$	=	2.2	K/W
d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)	$R_{th\ mb-h}$	=	0.8	K/W
e. without heatsink compound	$R_{th\ mb-h}$	=	1.4	K/W

2. Free air operation

The quoted values of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air:
mounted on a printed circuit board at any lead length

$R_{th\ j-a}$	=	60	K/W
---------------	---	----	-----

CHARACTERISTICS

Forward voltage

$$I_F = 8 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$$

$$I_F = 8 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 0.895 \text{ V}^*$$

$$V_F < 0.975 \text{ V}^*$$

$$V_F < 1.15 \text{ V}^*$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 175 \text{ }^\circ\text{C}$$

$$T_j = 125 \text{ }^\circ\text{C}$$

$$T_j = 100 \text{ }^\circ\text{C}$$

$$T_j = 25 \text{ }^\circ\text{C}$$

$$I_R < 500 \text{ } \mu\text{A}$$

$$I_R < 250 \text{ } \mu\text{A}$$

$$I_R < 50 \text{ } \mu\text{A}$$

$$I_R < 5 \text{ } \mu\text{A}$$

Reverse recovery when switched from

$$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s};$$

$$T_j = 25 \text{ }^\circ\text{C}; \text{ recovery time}$$

$$t_{rr} < 25 \text{ ns}$$

Step reverse recovery when switched from

$$I_F = 0.5 \text{ A to } I_R = 1 \text{ A, measured at}$$

$$I_{RR} = 0.25 \text{ A; recovery time}$$

$$t_{rr} < 25 \text{ ns}$$

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s};$$

$$T_j = 25 \text{ }^\circ\text{C}; \text{ recovered charge}$$

$$Q_s < 15 \text{ nC}$$

$$I_F = 10 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s};$$

$$T_j = 100 \text{ }^\circ\text{C}; \text{ peak recovery current}$$

$$I_{RRM} < 2 \text{ A}$$

Forward recovery when switched to $I_F = 1 \text{ A}$

$$\text{with } dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_{fr} \text{ typ. } 0.9 \text{ V}$$

M80-1319/3

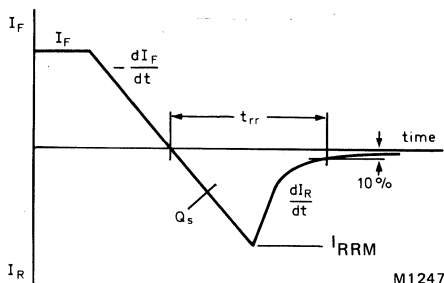


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

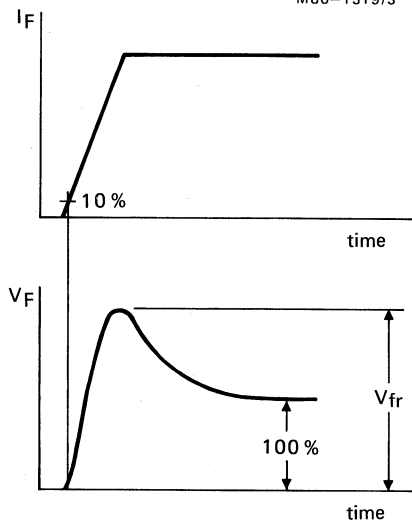


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
- Mounting by means of a spring clip is the best mounting method because it offers:
 - a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
- Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink considerations:

The various components of junction temperature rise above ambient are illustrated below:

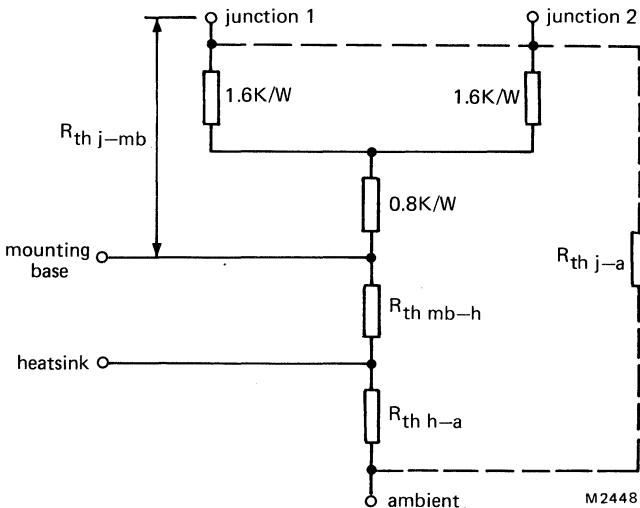


Fig.4

Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION (PER DIODE)

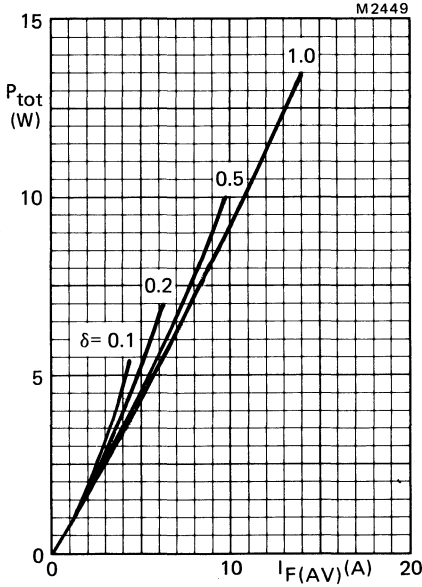
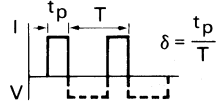


Fig.5 Power rating per diode.

The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

Power includes reverse current losses and switching losses up to $f = 500$ kHz

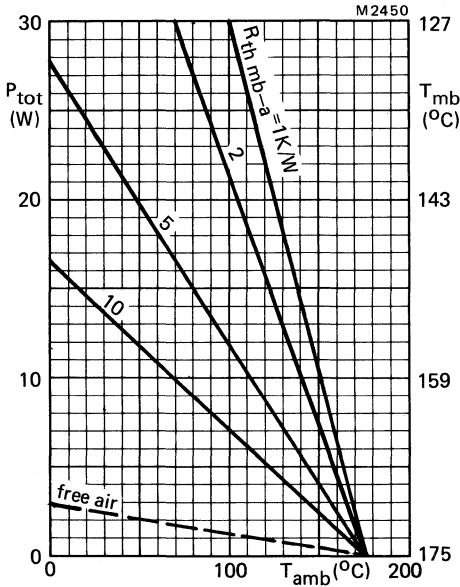


Fig.6

SINUSOIDAL OPERATION (PER DIODE)

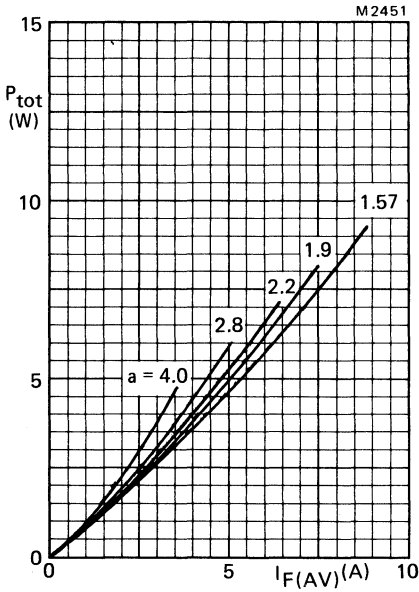


Fig.7 Power rating per diode. The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$

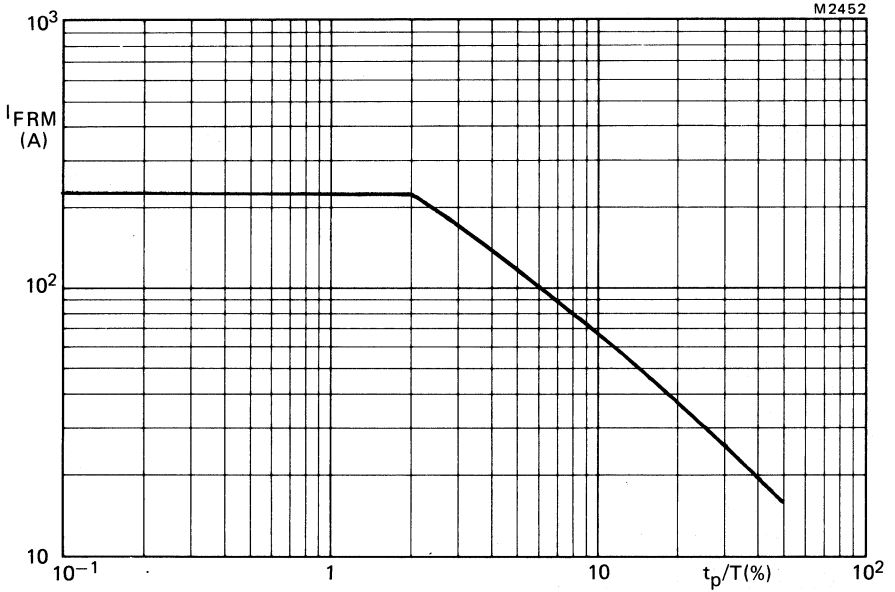
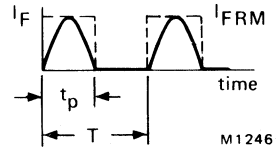
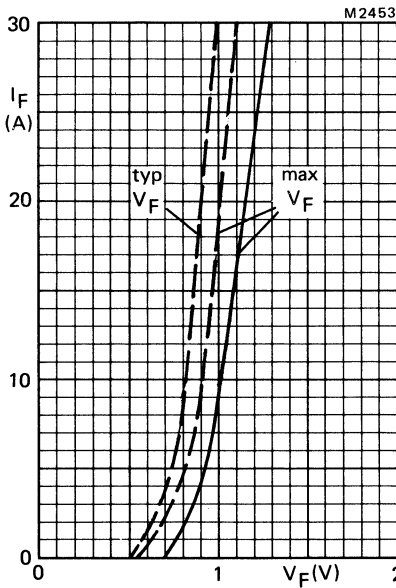


Fig.8 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.9 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 100 \text{ }^\circ\text{C}$.
per diode.

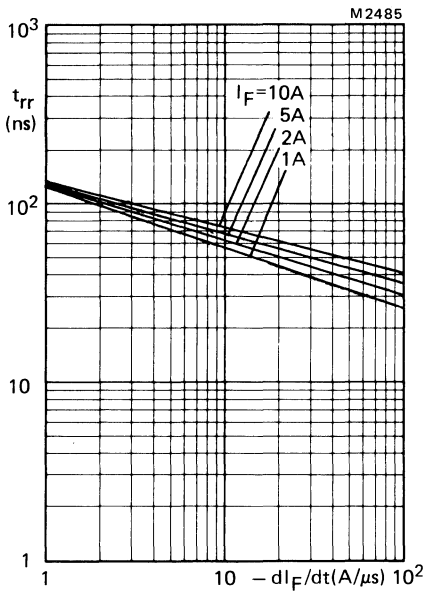


Fig.10 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

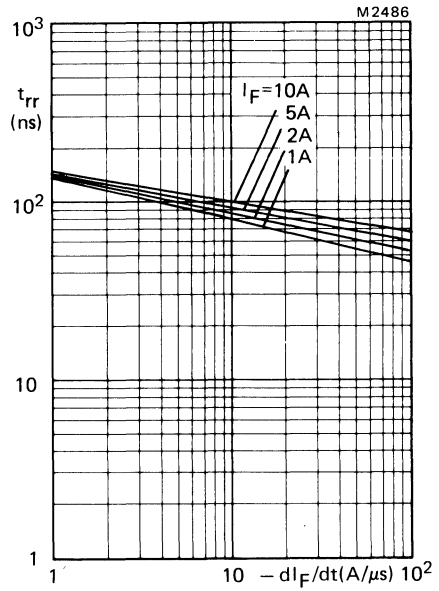


Fig.11 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

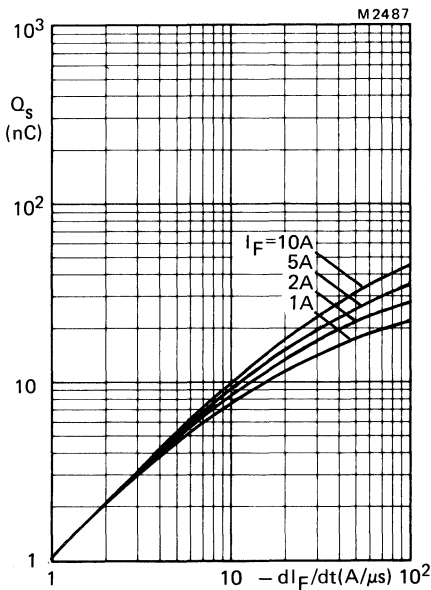


Fig.12 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

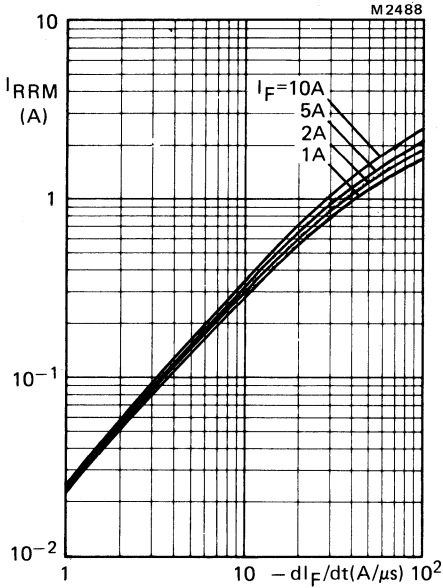


Fig.13 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

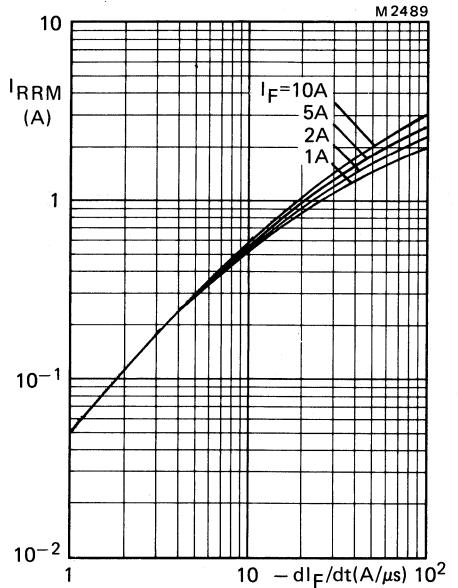


Fig.14 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

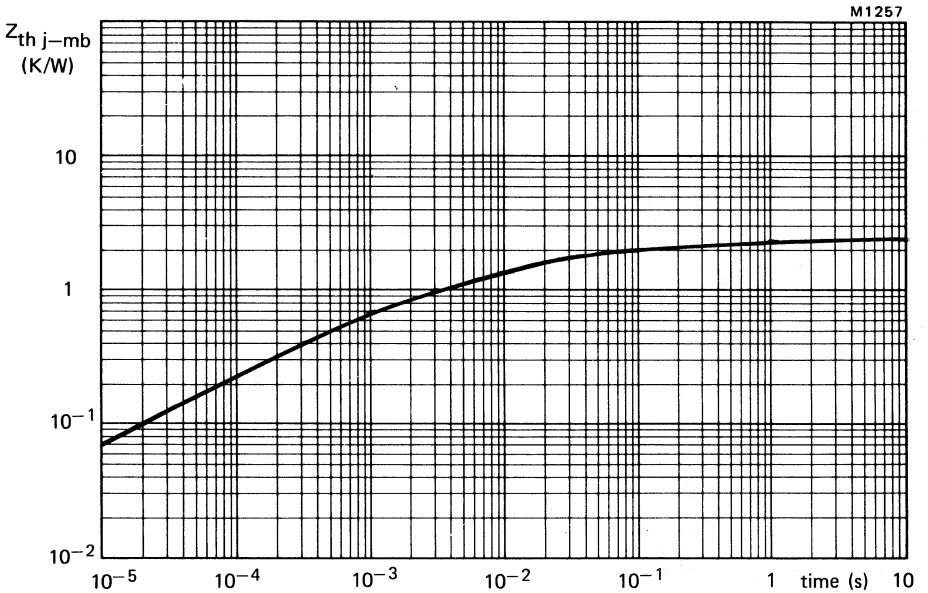


Fig.15 Transient thermal impedance; one diode conducting.

DEVELOPMENT DATA

This data sheet contains advance information and specifications are subject to change without notice.

BYP59 SERIES

ULTRA FAST RECOVERY RECTIFIER DIODES FEATURING LOW REVERSE LEAKAGE

Glass-passivated, high-efficiency epitaxial rectifier diodes in DO-5 metal envelopes, featuring low reverse leakage current, low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential.

The series consists of normal polarity (cathode to stud) types.

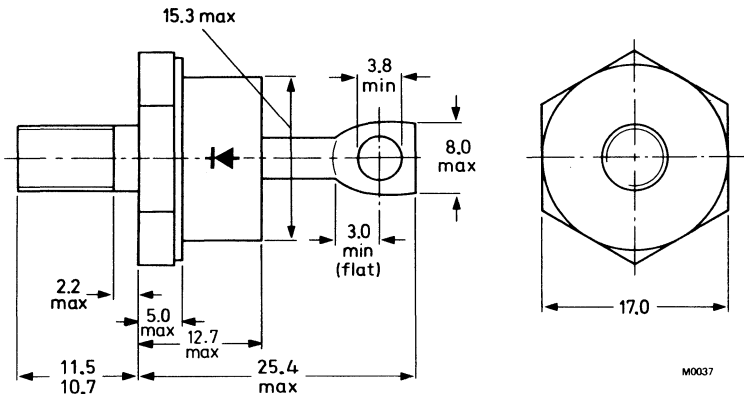
QUICK REFERENCE DATA

		BYP59-300		400	
		max.	300	400	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	V
Average forward current	$I_F(AV)$	max.	60		A
Forward voltage	V_F	<	1.05		V
Reverse recovery time	t_{rr}	<	60		V
Reverse leakage current	I_R	<	25		μA

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5: with 1/4 in x 28 UNF stud ($\phi 6.35$ mm); e.g. BYP59-300U,
with metric M6 stud ($\phi 6$ mm); e.g. BYP59-300M.



Net mass: 22 g

Diameter of clearance hole: max. 6.5 mm

Accessories supplied on request:

56264a (mica washer)

56264b (insulating bush).

Supplied with device: 1 nut, 1 lock washer

Torque on nut: min. 1.7 Nm (17 kg cm),
max. 3.5 Nm (35 kg cm).

Nut dimensions across the flats:

1/4 in x 28 UNF: 11.1 mm, M6: 10.0 mm.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages		BYP59-300		400	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	V
Crest working reverse voltage	V_{RWM}	max.	200	300	V
Continuous reverse voltage	V_R	max.	200	300	V
Currents					
Average forward current; switching losses negligible up to 200 kHz; square wave; $\delta = 0.5$; up to $T_{mb} = 100^\circ\text{C}$	$I_F(AV)$	max.	60		A
R.M.S. forward current	$I_F(RMS)$	max.	85		A
Repetitive peak forward current $t_p = 20 \mu\text{s}$, $\delta = 0.02$	I_{FRM}	max.	1200		A
Non-repetitive peak forward current half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max	I_{FSM}	max.	650		A
$t = 10 \text{ ms}$	I_{FSM}	max.	700		A
$t = 8.3 \text{ ms}$	$I^2 t$	max.	2100		A^2s
$I^2 t$ for fusing ($t = 10 \text{ ms}$)					
Temperatures					
Storage temperature	T_{stg}		-55 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.	150		$^\circ\text{C}$
THERMAL RESISTANCE					
From junction to mounting base	$R_{th j-mb}$	=	0.7		K/W
From mounting base to heatsink:					
a. with heatsink compound	$R_{th mb-h}$	=	0.2		K/W
b. without heatsink compound	$R_{th mb-h}$	=	0.3		K/W

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

CHARACTERISTICS

Forward voltage

$I_F = 60 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$
 $I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.05 \text{ V}^*$
 $V_F < 1.4 \text{ V}^*$

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$
 $V_R = V_{RWM \text{ max}}; T_j = 25 \text{ }^\circ\text{C}$

$I_R < 0.5 \text{ mA}$
 $I_F < 25 \text{ } \mu\text{A}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s};$
 $T_j = 25 \text{ }^\circ\text{C};$ recovery time

$t_{rr} < 60 \text{ ns}$

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s};$
 $T_j = 25 \text{ }^\circ\text{C};$ recovered charge

$Q_s < 100 \text{ nC}$

$I_F = 10 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s};$
 $T_j = 100 \text{ }^\circ\text{C};$ peak recovery current

$I_{RRM} < 5 \text{ A}$

Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$V_{fr} \text{ typ. } 2.5 \text{ V}$

DEVELOPMENT DATA

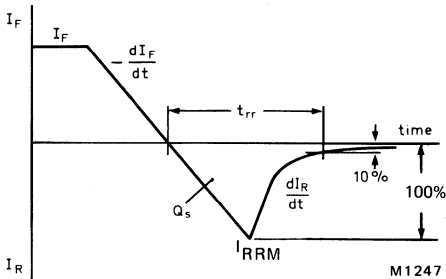


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

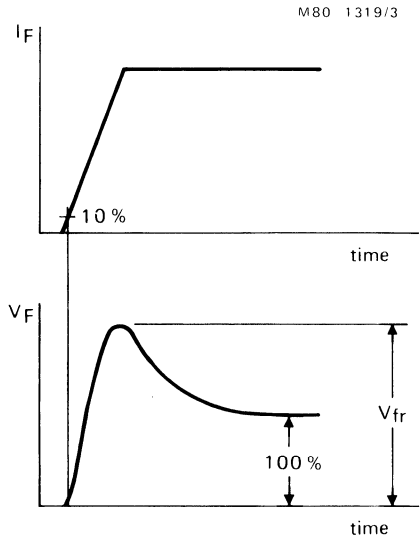


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation

ULTRA FAST RECOVERY DOUBLE RECTIFIER DIODES

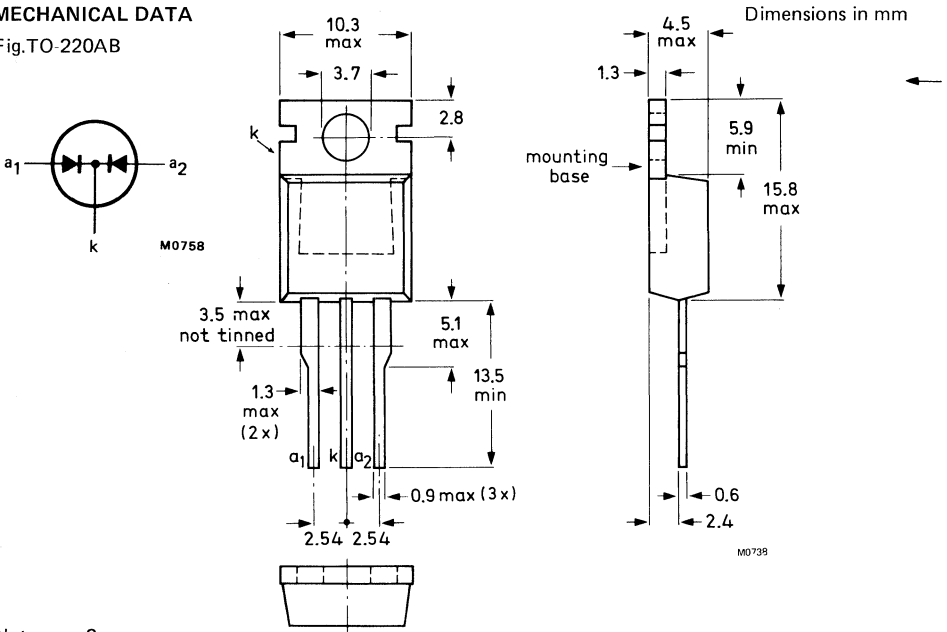
Glass-passivated, high-efficiency double rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times and soft recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. Their single chip (monolithic) construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common cathode types.

QUICK REFERENCE DATA

Per diode, unless otherwise stated		BYQ28-50				100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200		V	
Output current (both diodes conducting)	I_O	max.			10			A	
Forward voltage	V_F	<			0.85			V	
Reverse recovery time	t_{rr}	<			20			ns	

MECHANICAL DATA

Fig.TO-220AB



Net mass: 2 g

Note: the exposed metal mounting base is directly connected to the common cathode.

Accessories supplied on request: see data sheets Mounting Instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)		BYQ28-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage	V_R	max. 50	100	150	200	V
Currents (both diodes conducting; note 1)						
Output current; switching losses negligible up to 500 kHz;						
square wave; $\delta = 0.5$; up to $T_{mb} = 128\text{ }^\circ\text{C}$	I_O	max.		10		A
sinusoidal; up to $T_{mb} = 130\text{ }^\circ\text{C}$	I_O	max.		10		A
R.M.S. forward current	$I_{F(RMS)}$	max.		14		A
Repetitive peak forward current $t_p = 20\text{ }\mu\text{s}$, $\delta = 0.02$ (per diode)	I_{FRM}	max.		80		A
Non-repetitive peak forward current (per diode) half sine-wave; $T_j = 150\text{ }^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max						
$t = 10\text{ ms}$	I_{FSM}	max.		50		A
$\tau = 8.3\text{ ms}$	I_{FSM}	max.		60		A
$I^2 t$ for fusing ($t = 10\text{ ms}$, per diode)	$I^2 t$	max.		12.5		A^2s
Temperatures						
Storage temperature	T_{stg}			-40 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.		150		$^\circ\text{C}$

Notes:

1. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.

CHARACTERISTICS (per diode)

Forward voltage

$I_F = 5 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$

$V_F < 0.85 \text{ V}^*$

$I_F = 15 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.3 \text{ V}^*$

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$

$I_R < 0.2 \text{ mA}$

$V_R = V_{RWM \text{ max}}; T_j = 25 \text{ }^\circ\text{C}$

$I_R < 10 \text{ } \mu\text{A}$

Reverse recovery when switched from

$I_F = 1 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
recovery time

$t_{rr} < 20 \text{ ns}$

$I_F = 2 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
recovered charge

$Q_s < 5.5 \text{ nC}$

$I_F = 5 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 100 \text{ }^\circ\text{C}$
peak recovery current

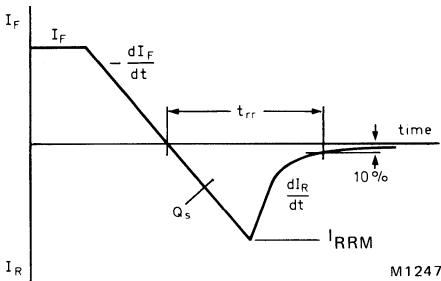
$I_{RRM} < 1.2 \text{ A}$

Forward recovery when switched to $I_F = 1 \text{ A}$

with $dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

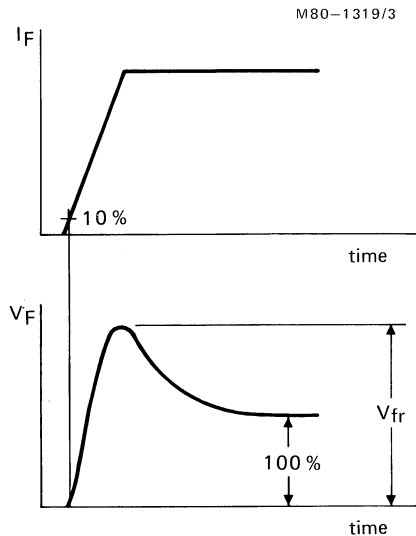
recovery voltage

$V_{fr} \text{ typ. } 1.0 \text{ V}$



M1247

Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .



M80-1319/3

Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)	$R_{th\ j-mb}$	=	2.2	K/W
From junction to mounting base (per diode)	$R_{th\ j-mb}$	=	3.0	K/W

→ **Influence of mounting method**

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound	$R_{th\ mb-h}$	=	0.3	K/W
b. with heatsink compound and 0.06 mm maximum mica insulator	$R_{th\ mb-h}$	=	1.4	K/W
c. with heatsink compound and 0.1 mm maximum mica insulator (56369)	$R_{th\ mb-h}$	=	2.2	K/W
d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)	$R_{th\ mb-h}$	=	0.8	K/W
e. without heatsink compound	$R_{th\ mb-h}$	=	1.4	K/W

2. Free air operation

The quoted values of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air:

mounted on a printed circuit board at any device lead length and with copper laminate on the board	$R_{th\ j-a}$	=	60	K/W
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MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

The various components of junction temperature rise above ambient are illustrated in Fig.4.

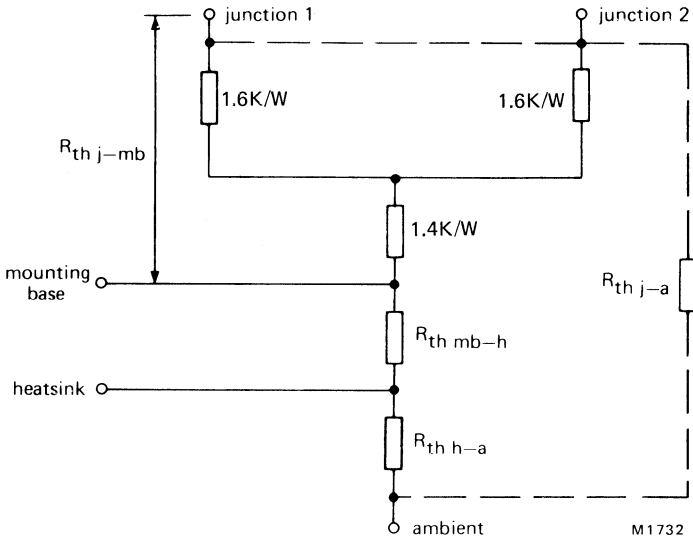


Fig.4.

Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION (PER DIODE)

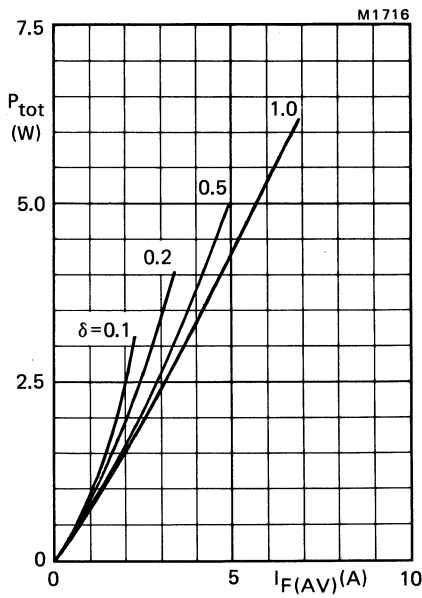


Fig.5 Power rating per diode. The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

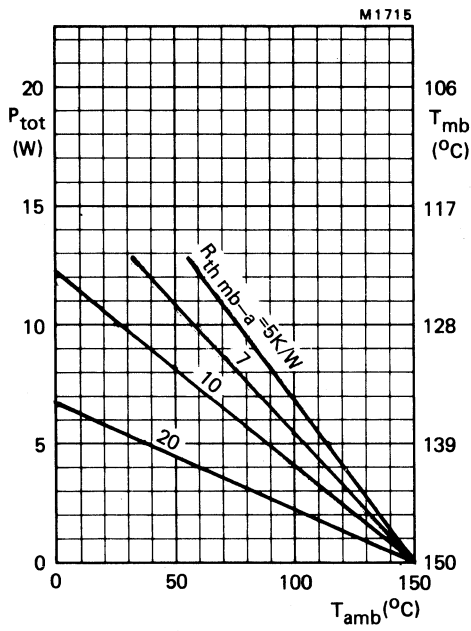
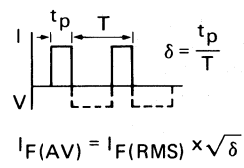


Fig.6

SINUSOIDAL OPERATION (PER DIODE)

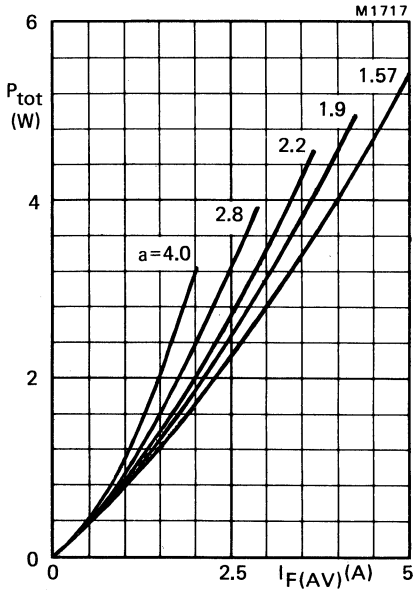


Fig.7 Power rating per diode.

The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$

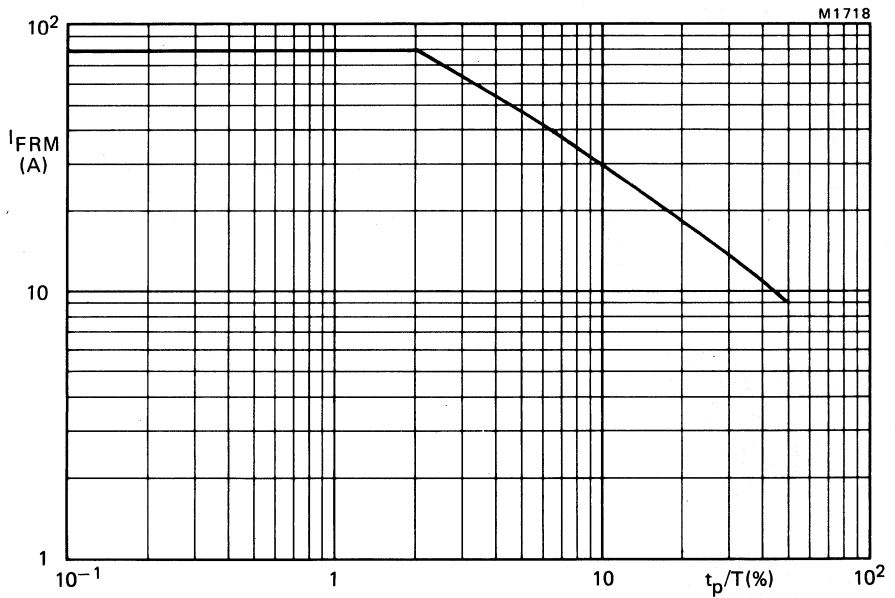


Fig.8 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 \text{ ms}$.

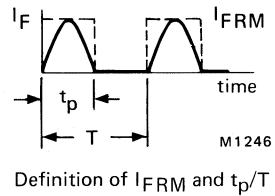
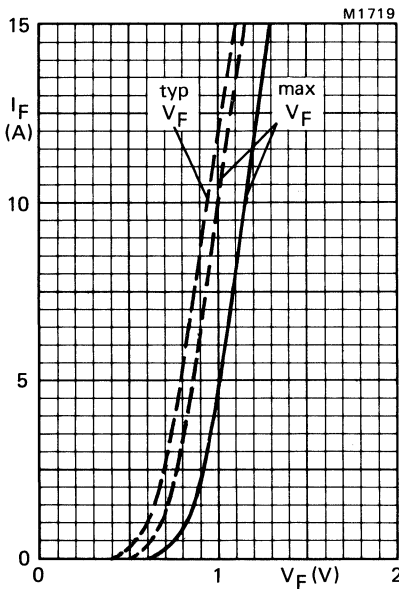


Fig.9 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$ per diode.

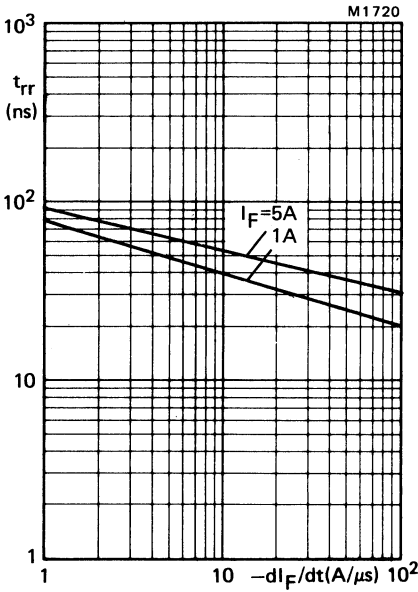


Fig.10 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

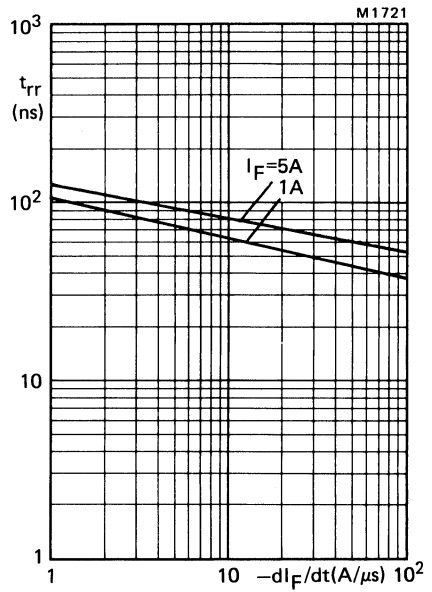


Fig.11 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

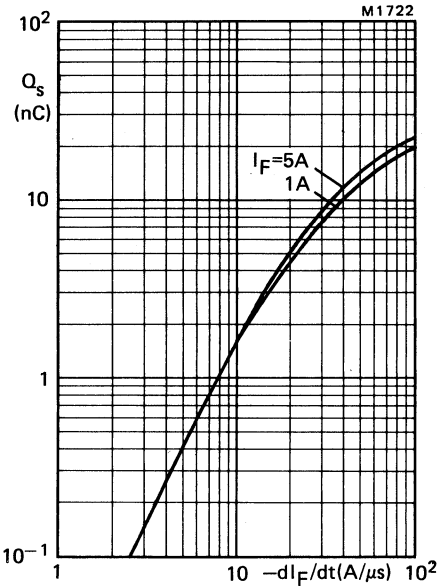


Fig.12 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

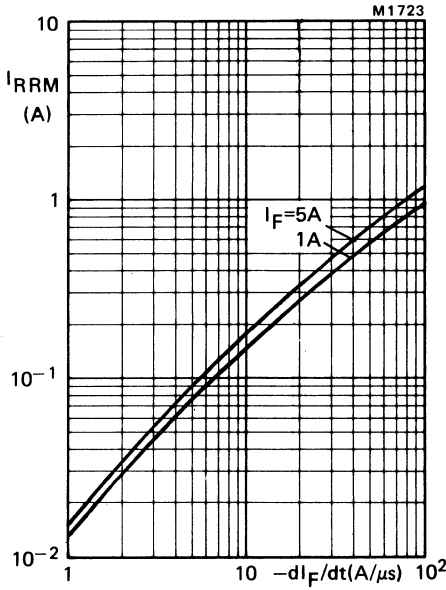


Fig.13 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$

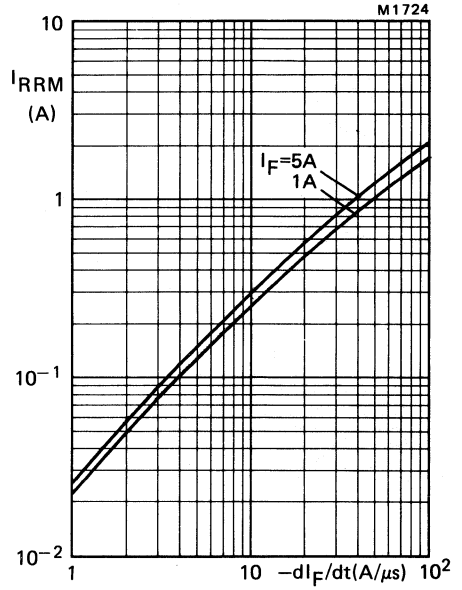


Fig.14 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$;

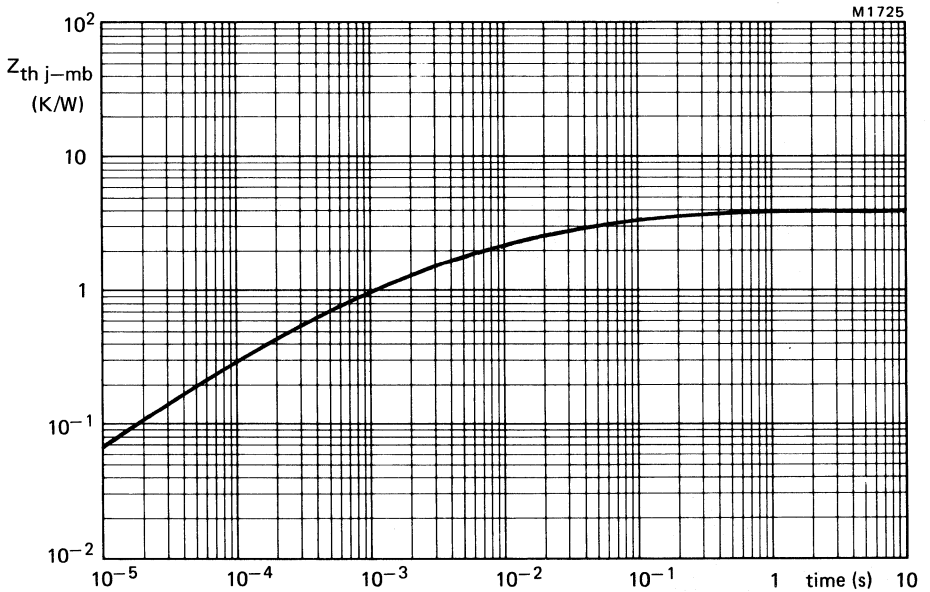


Fig.15 One diode conducting.

ULTRA FAST RECOVERY RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. The series consists of normal polarity (cathode to mounting base) types.

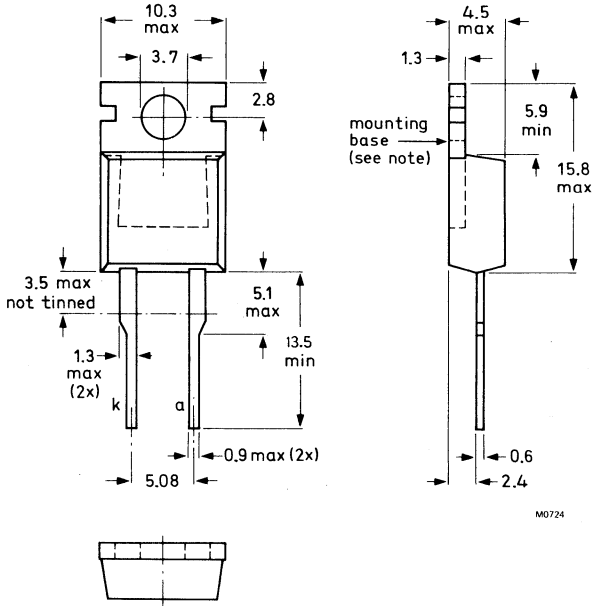
QUICK REFERENCE DATA

			BYR29-600	700	800	
Repetitive peak reverse voltage	V_{RRM}	max.	600	700	800	V
Average forward current	$I_F(AV)$	max.	8			A
Forward voltage	V_F	<	1.3			V
Reverse recovery time	t_{rr}	<	75			ns

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AC



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

			BYR29-600	700	800	
→ Voltages						
Repetitive peak reverse voltage	V_{RRM}	max.	600	700	800	V
Crest working reverse voltage	V_{RWM}	max.	500	500	600	V
Continuous reverse voltage*	V_R	max.	500	500	600	V
Currents						
Average forward current; switching losses negligible up to 100 kHz						
square wave; $\delta = 0.5$; up to $T_{mb} = 117^\circ\text{C}$	$I_{F(AV)}$	max.		8		A
up to $T_{mb} = 125^\circ\text{C}$	$I_{F(AV)}$	max.		6.5		A
sinusoidal; up to $T_{mb} = 120^\circ\text{C}$	$I_{F(AV)}$	max.		7.8		A
up to $T_{mb} = 125^\circ\text{C}$	$I_{F(AV)}$	max.		7.2		A
R.M.S. forward current	$I_{F(RMS)}$	max.		11.5		A
Repetitive peak forward current						
$t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.		130		A
Non-repetitive peak forward current						
half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge;						
with reapplied V_{RWMmax} :						
$t = 10 \text{ ms}$	I_{FSM}	max.		60		A
$t = 8.3 \text{ ms}$	I_{FSM}	max.		72		A
$I^2 t$ for fusing ($t = 10 \text{ ms}$)	$I^2 t$	max.		18		A^2s
Temperatures						
Storage temperature	T_{stg}			-40 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.		150		$^\circ\text{C}$

*To ensure thermal stability: $R_{th j-a} \leq 5.7 \text{ K/W}$.

CHARACTERISTICS

Forward voltage

$I_F = 10 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$
 $I_F = 25 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

V_F	<	1.30	V*
V_F	<	1.75	V*

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$
 $T_j = 25 \text{ }^\circ\text{C}$

I_R	<	0.2	mA
I_R	<	10	μA

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovery time

t_{rr}	<	75	ns
----------	---	----	----

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 20 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovered charge

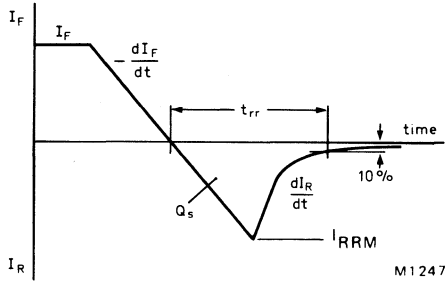
Q_s	<	200	nC
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$I_F = 10 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 50 \text{ A}/\mu\text{s}$;
 $T_j = 100 \text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	6	A
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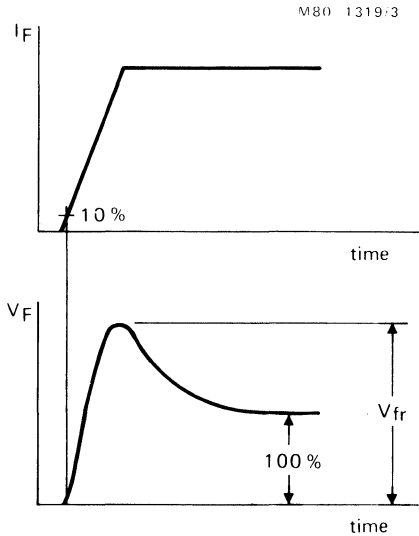
Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

V_{fr}	typ.	5	V
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M1247

Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .



M80 1319:3

Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 2.5 \text{ K/W}$$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275°C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
- Mounting by means of a spring clip is the best mounting method because it offers:
 - a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
- Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

- The various components of junction temperature rise above ambient are illustrated in Fig.4.

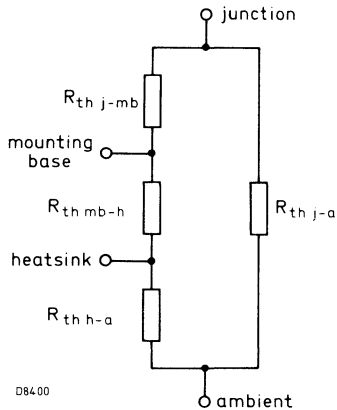


Fig. 4.

- Any measurement of heatsink temperature should be made immediately adjacent to the device.
- The method of using Figs. 5 and 6 is as follows:
Starting with the required current on the $I_F(AV)$ axis, trace upwards to meet the appropriate duty cycle or form factor curve. Trace right horizontally and upwards from the required value on the T_{amb} scale. The intersection determines the $R_{th\ mb-a}$. The heatsink thermal resistance value ($R_{th\ h-a}$) can be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

SQUARE-WAVE OPERATION

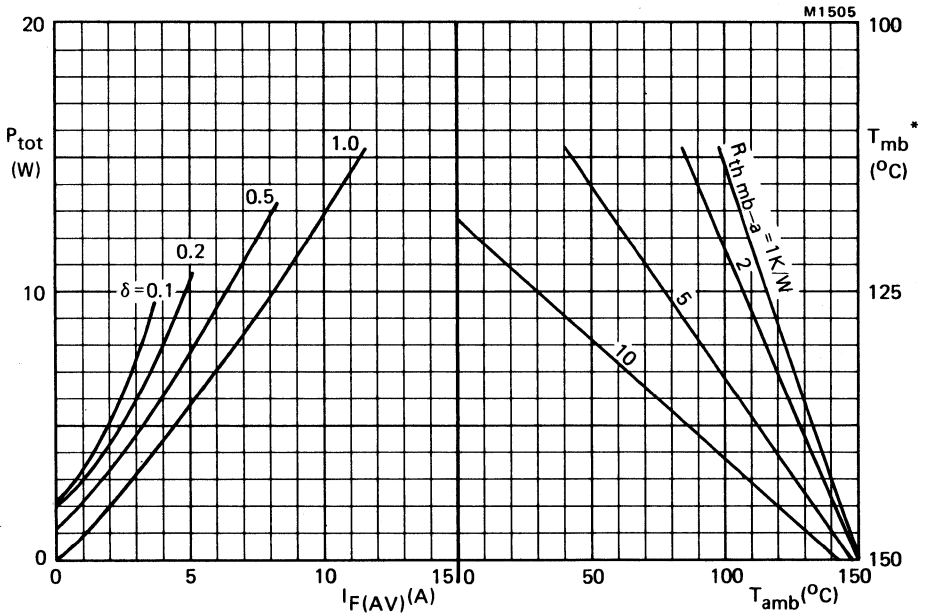
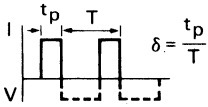


Fig.5 The right-hand part shows the relationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 100$ kHz.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 3.2$ K/W.

SINUSOIDAL OPERATION

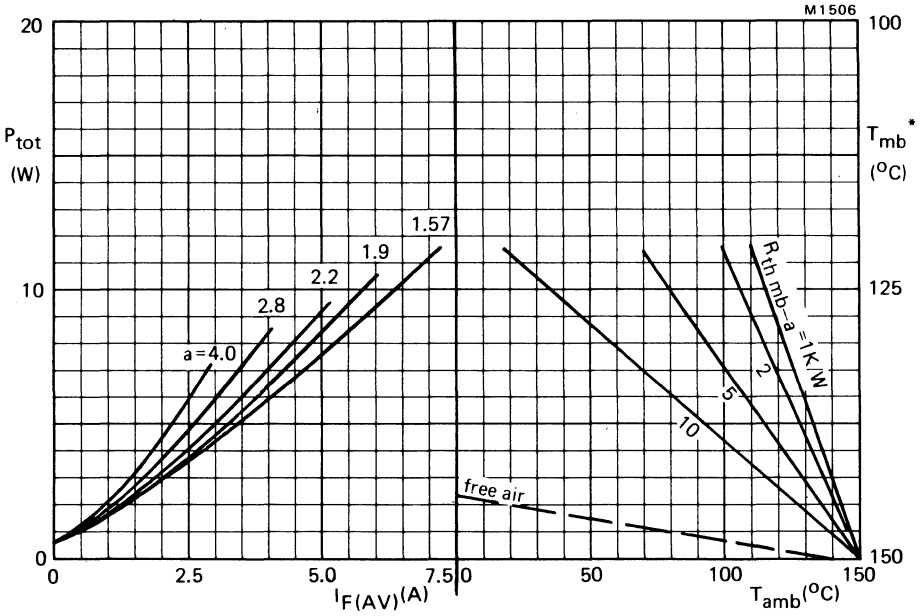


Fig.6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$.

* T_{mb} scale is for comparison purposes and is correct only for $R_{th mb-a} < 16 K/W$.

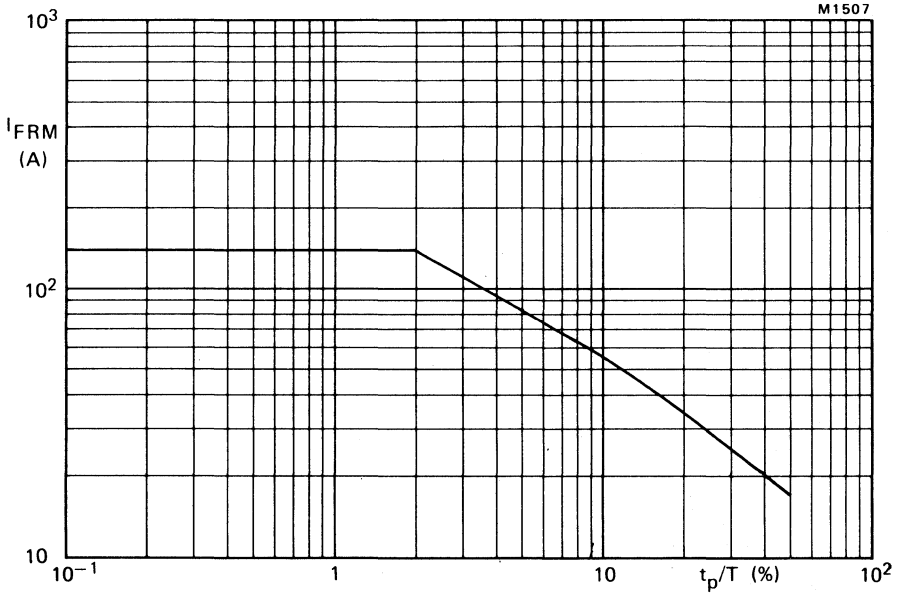
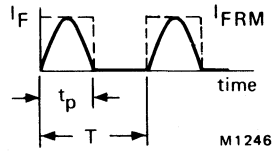
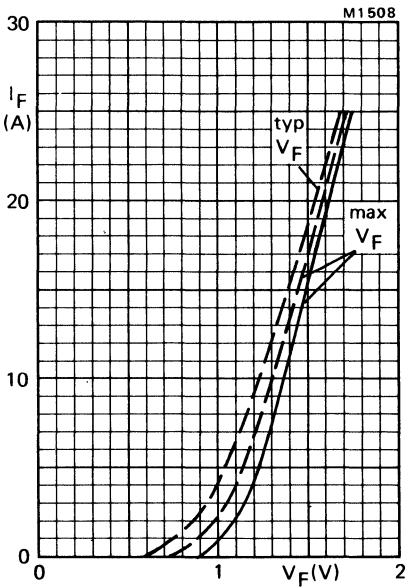


Fig.7 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1$ ms.



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$.

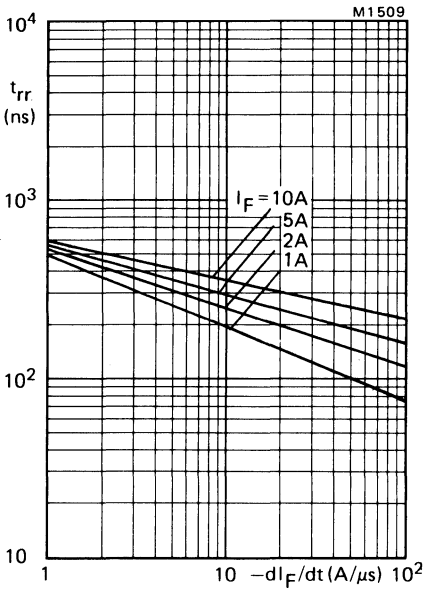


Fig.9 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

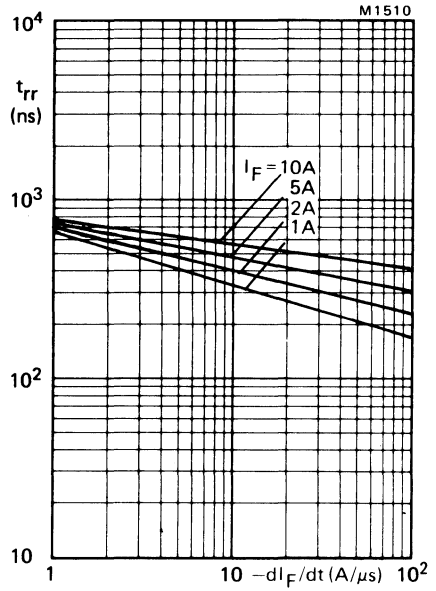


Fig.10 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

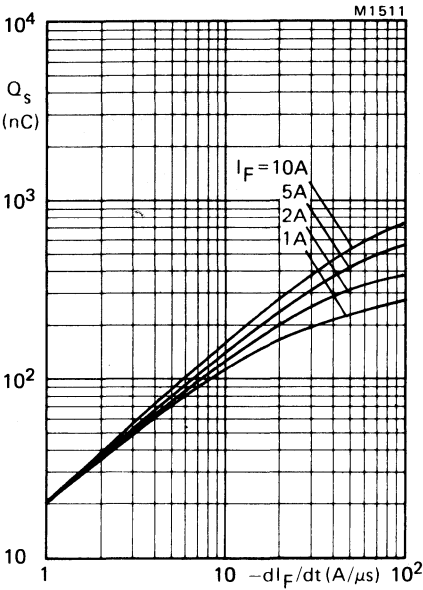


Fig.11 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$

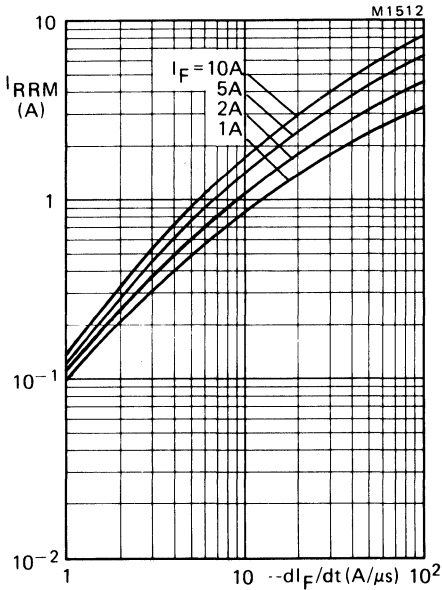


Fig.12 Maximum I_{RRM} at $T_j = 25$ °C.

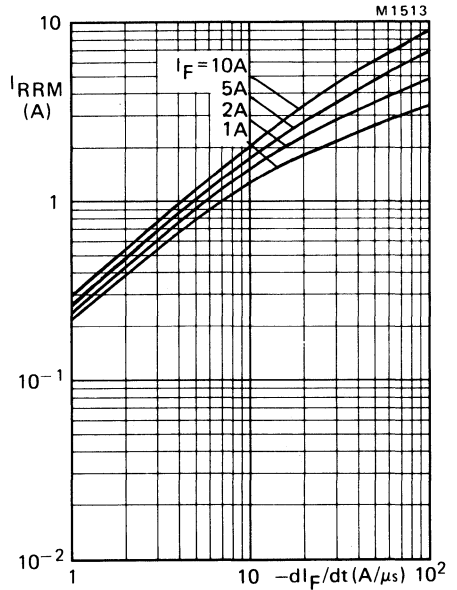


Fig.13 Maximum I_{RRM} at $T_j = 100$ °C.

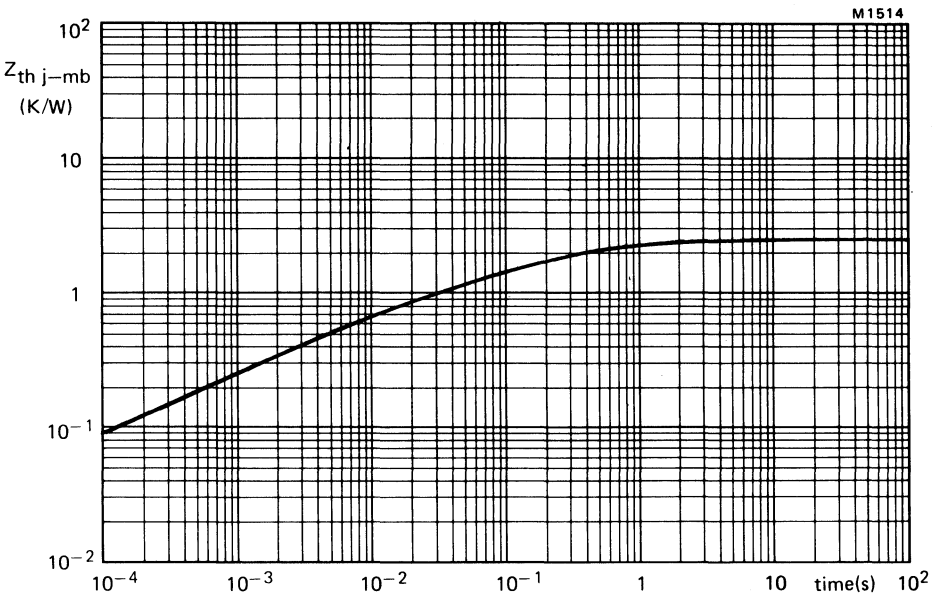


Fig.14 Transient thermal impedance.

ULTRA FAST RECOVERY ELECTRICALLY-ISOLATED RECTIFIER DIODES

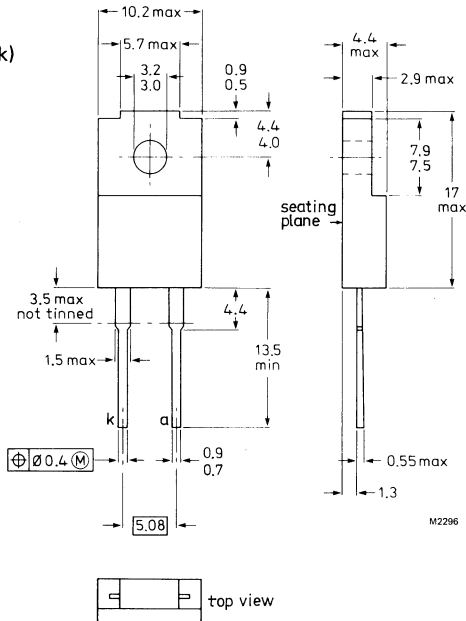
Glass-passivated, high-efficiency epitaxial rectifier diodes in SOT-186 (full-pack) envelopes, featuring low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. Their electrical isolation makes them ideal for mounting on a common heatsink alongside other components without the need for additional insulators. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential.

QUICK REFERENCE DATA

		BYR29F-600			700	800		
		600	700	800				
Repetitive peak reverse voltage	V_{RRM}	max.			600	700	800	V
Average forward current	$I_F(AV)$	max.			8		A	
Forward voltage	V_F	<			1.3		V	
Reverse recovery time	t_{rr}	<			75		ns	

MECHANICAL DATA

Fig. 1 SOT-186 (full-pack)



Dimensions in mm

Net mass: 2 g.

The seating plane is electrically isolated from all terminals.

Accessories supplied on request (see data sheets Mounting instructions for F-pack devices and Accessories for SOT-186 envelopes).

BYR29F SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages			BYR29F- 600	700	800	
Repetitive peak reverse voltage	V_{RRM}	max.	600	700	800	V
Crest working reverse voltage	V_{RWM}	max.	500	500	600	V
Continuous reverse voltage (note 1)	V_R	max.	500	500	600	V
Currents						
Average forward current; switching losses negligible up to 100 kHz (note 2); square wave; $\delta = 0.5$; up to $T_{mb} = 79^\circ\text{C}$ sinusoidal; up to $T_{mb} = 87^\circ\text{C}$						
	$I_{F(AV)}$	max.		8		A
	$I_{F(AV)}$	max.		7.2		A
R.M.S. forward current	$I_{F(RMS)}$	max.		11.5		A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.		130		A
Non-repetitive peak forward current half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max						
$t = 10 \text{ ms}$	I_{FSM}	max.		60		A
$t = 8.3 \text{ ms}$	I_{FSM}	max.		72		A
$I^2 t$ for fusing ($t = 10 \text{ ms}$)	$I^2 t$	max.		18		A ² s
Temperatures						
Storage temperature	T_{stg}			-40 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.		150		$^\circ\text{C}$
ISOLATION						
Peak isolation voltage from all terminals to external heatsink	V_{isol}	max.		1000		V
Isolation capacitance from cathode to external heatsink (note 3)	C_p	typ.		12		pF

Notes:

1. To ensure thermal stability: $R_{th j-a} < 5.7 \text{ K/W}$.
2. The quoted temperatures assume heatsink compound is used.
3. Mounted without heatsink compound and 20 Newtons pressure on the centre of the envelope.

THERMAL RESISTANCE

From junction to external heatsink with minimum of 2 kgf (20 Newtons) pressure on the centre of the envelope, with heatsink compound without heatsink compound

$R_{th\ j-a}$ =	5.5	K/W
$R_{th\ j-a}$ =	7.2	K/W

Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same point.

Thermal resistance from junction to ambient in free air, mounted on a printed circuit board

$R_{th\ j-a}$ =	55	K/W
-----------------	----	-----

CHARACTERISTICS

$T_j = 25^\circ\text{C}$ unless otherwise stated

Forward voltage

$I_F = 10\text{ A}; T = 150^\circ\text{C}$
 $I_F = 25\text{ A}$

V_F <	1.3	V*
V_F <	1.75	V*

Reverse current

$V_R = V_{RWM\ max}; T_j = 100^\circ\text{C}$
 $V_R = V_{RWM\ max}$

I_R <	0.2	mA
I_R <	10	μA

Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$; recovery time

t_{rr} <	75	ns
------------	----	----

$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$; recovered charge

Q_s <	200	nC
---------	-----	----

$I_F = 10\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$; $T_j = 100^\circ\text{C}$; peak recovery current

I_{RRM} <	6	A
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Forward recovery when switched to $I_F = 10\text{ A}$ with $dI_F/dt = 10\text{ A}/\mu\text{s}$

V_{fr} typ.	5	V
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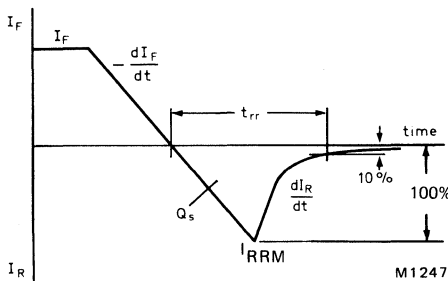


Fig. 2 Definition of t_{rr} , Q_s and I_{RRM} .

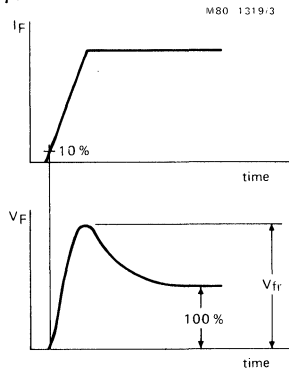


Fig. 3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers a good thermal contact under the crystal area and slightly lower $R_{th\ j-h}$ values than screw mounting. The force exerted on the top of the device by the clip should be at least 2 kgf (20 Newtons) to ensure good thermal contact and must not exceed 3.5 kgf (35 Newtons) to avoid damage to the device.
4. If screw mounting is used, it should be M3 cross-recess pan head.
 Minimum torque to ensure good thermal contact: 5.5 kgf (0.55 Nm)
 Maximum torque to avoid damage to the device: 8.0 kgf (0.80 Nm)
5. For good thermal contact, heatsink compound should be used between baseplate and heatsink. Values of $R_{th\ j-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting.
 It is not recommended to use rivets, since extensive damage could result to the plastic, which could destroy the insulating properties of the device.
7. The heatsink must have a flatness in the mounting area of 0.02 mm maximum per 10 mm. Mounting holes must be deburred.

OPERATING NOTES

The various components of junction temperature rise above ambient are illustrated in Fig.4.

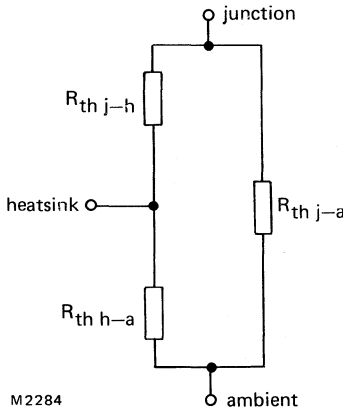


Fig.4.

Any measurement of heatsink temperature should be immediately adjacent to the device.

SQUARE-WAVE OPERATION

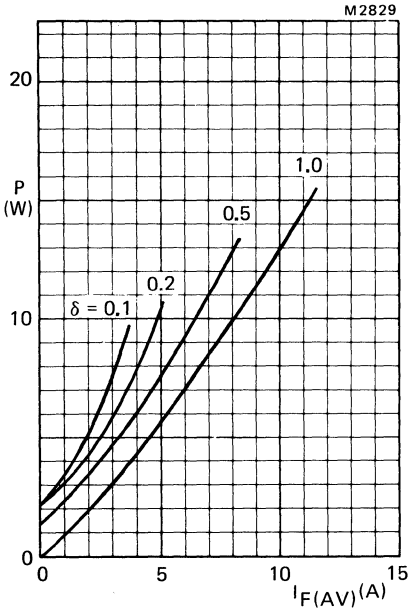
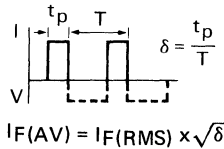


Fig. 5 Power rating.

The power loss in the diode should first be determined from the required forward current on the $I_F(AV)$ axis and the appropriate duty cycle.

Having determined the power (P), use Fig. 7 (if heatsink compound is not being used) or Fig. 8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.



SINUSOIDAL OPERATION

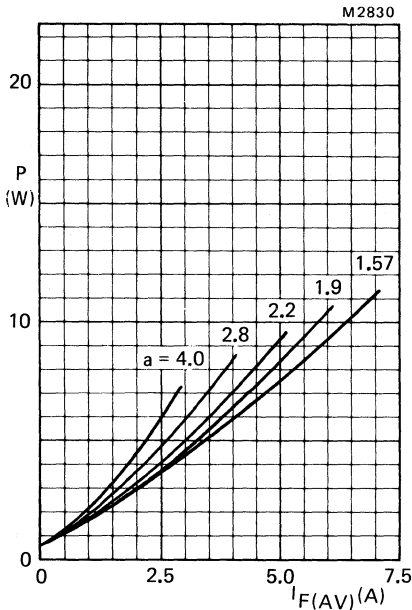


Fig. 6 Power rating.

The power loss in the diode should first be determined from the required forward current on the $I_F(AV)$ axis and the appropriate form factor.

Having determined the power (P), use Fig. 7 (if heatsink compound is not being used) or Fig. 8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.

a = form factor = $I_F(RMS)/I_F(AV)$

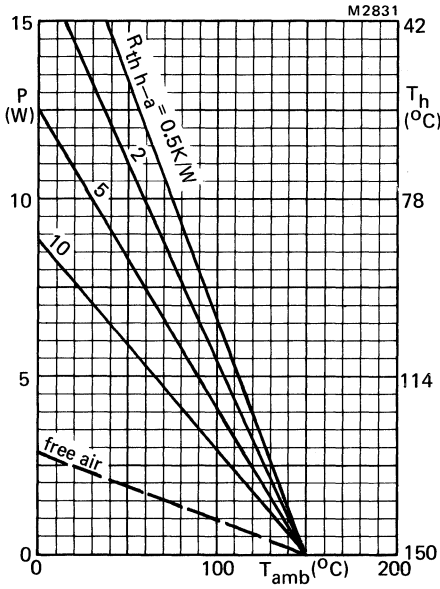


Fig. 7 Heatsink rating; without heatsink compound.

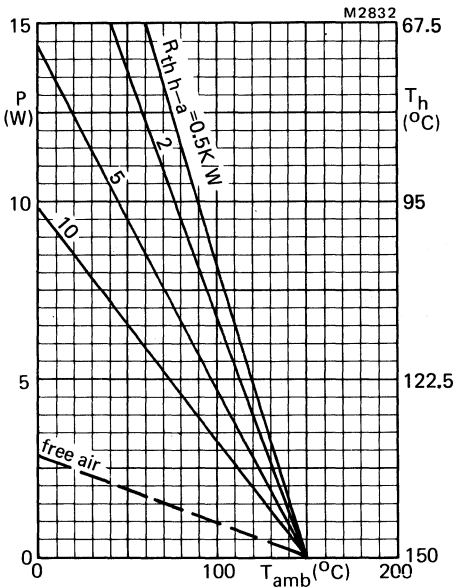


Fig. 8 Heatsink rating; with heatsink compound.

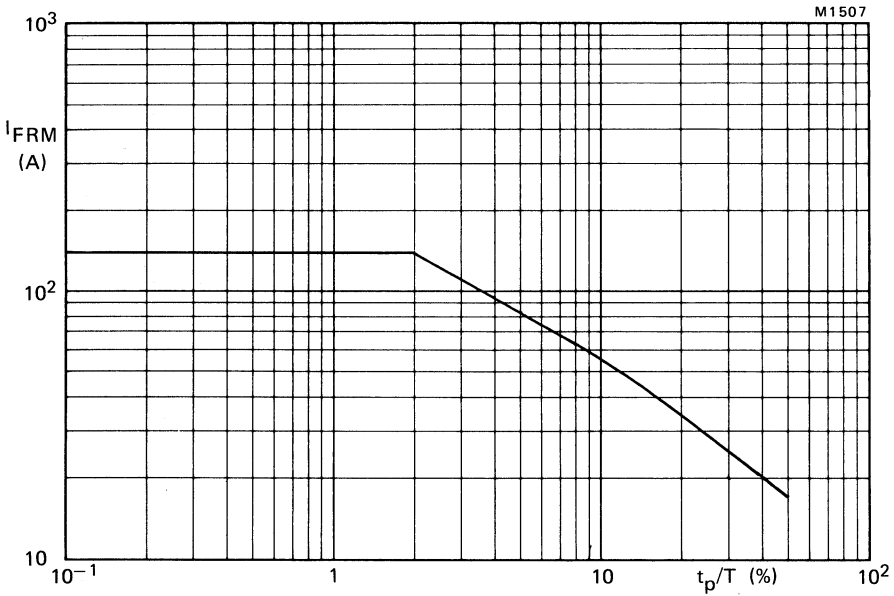


Fig. 9 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.

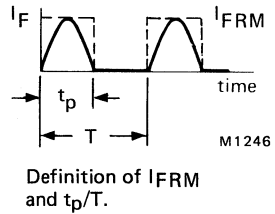
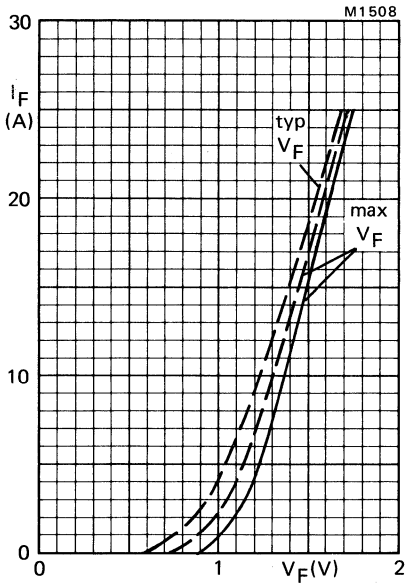


Fig. 10 — $T_j = 25^\circ\text{C}$; - - - $T_j = 150^\circ\text{C}$

BYR29F SERIES

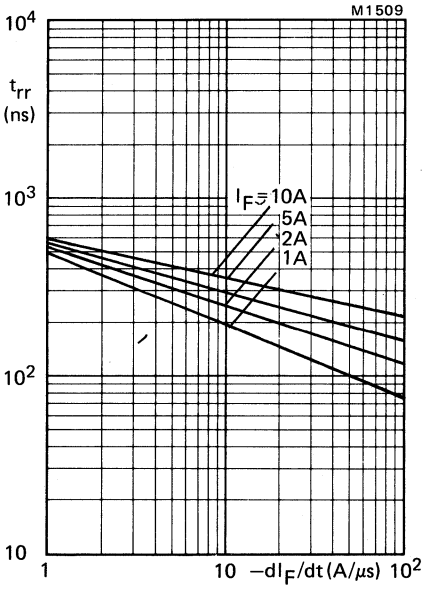


Fig. 11 Maximum t_{rr} at $T_j = 25^\circ\text{C}$

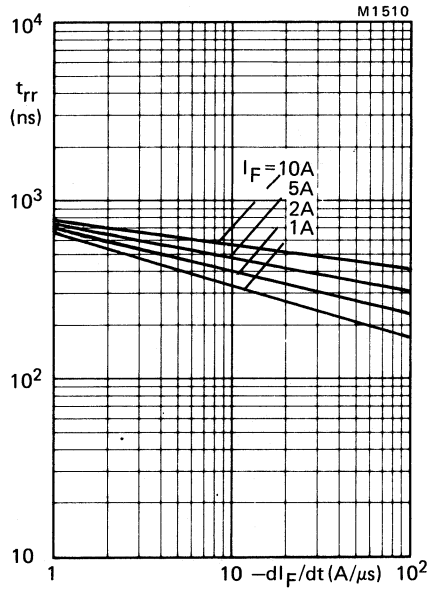


Fig. 12 Maximum t_{rr} at $T_j = 100^\circ\text{C}$.

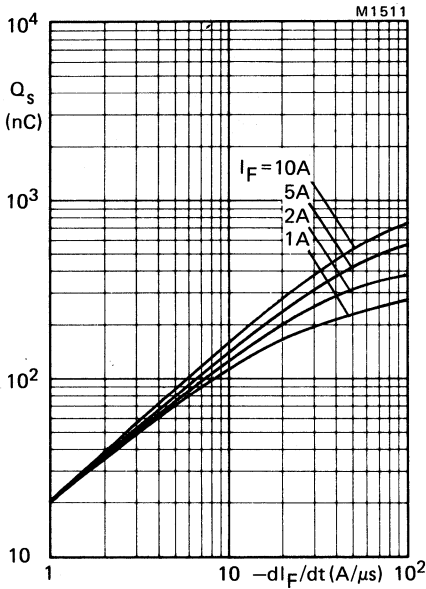


Fig. 13 Maximum Q_s at $T_j = 25^\circ\text{C}$.

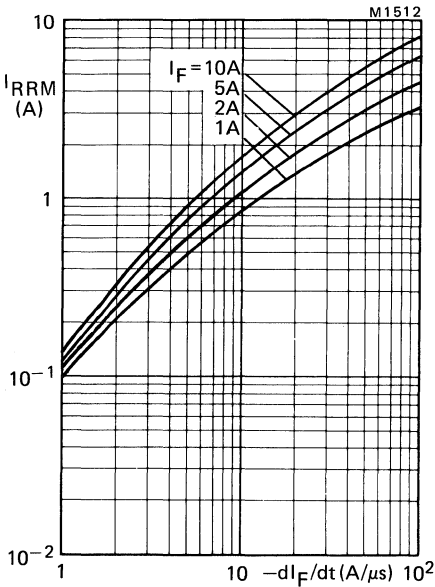


Fig. 14 Maximum I_{RRM} at $T_j = 25^\circ C$.

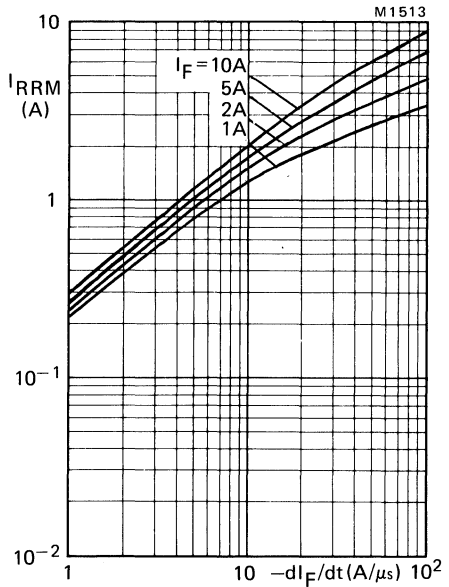


Fig. 15 Maximum I_{RRM} at $T_j = 100^\circ C$.

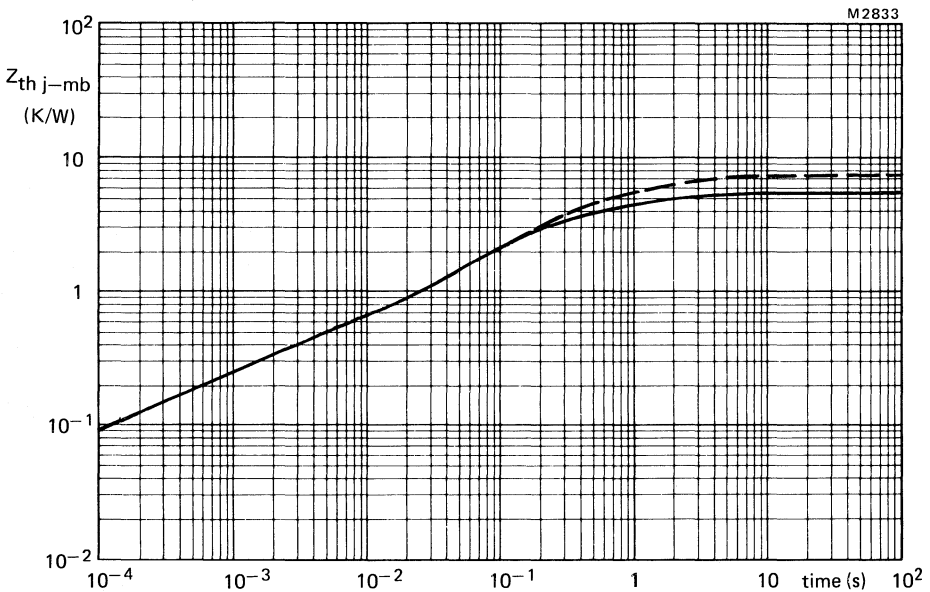


Fig. 16 Transient thermal impedance; — with heatsink compound; - - - without heatsink compound.

ULTRA FAST RECOVERY DOUBLE RECTIFIER DIODES

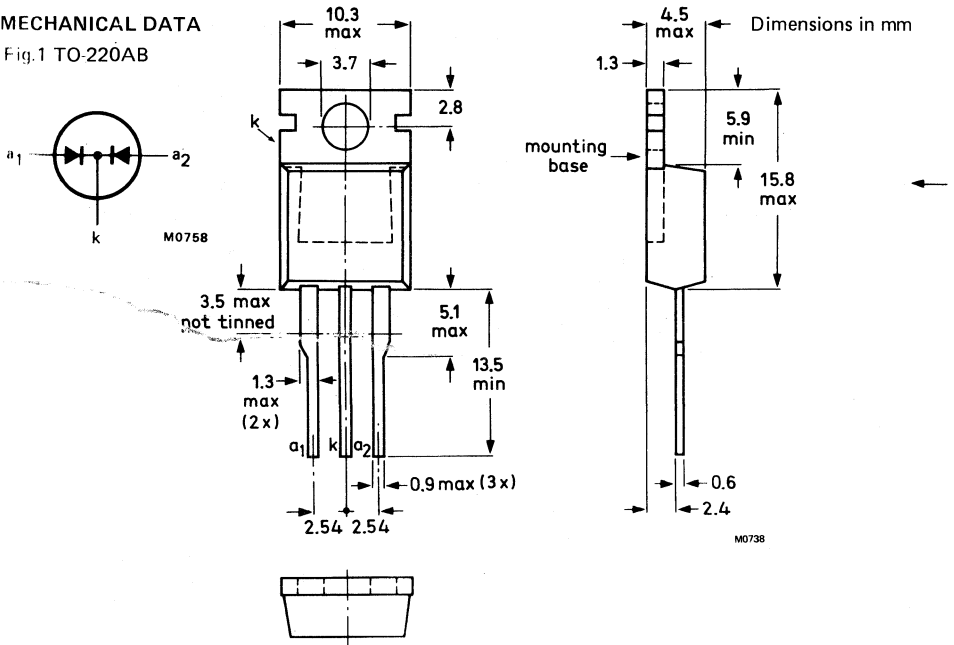
Glass-passivated, high-efficiency double rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. Their single chip (monolithic) construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common-cathode types.

QUICK REFERENCE DATA

Per diode, unless otherwise stated				BYT28-300			400	500	
Repetitive peak reverse voltage	V_{RRM}	max.		300	400	500		V	
Output current (both diodes conducting)	I_O	max.					10	A	
Forward voltage	V_F	<					1.05	V	
Reverse recovery time	t_{rr}	<					50	ns	

MECHANICAL DATA

Fig.1 TO-220AB



Net mass: 2 g

Note: the exposed metal mounting base is directly connected to the common cathode.

Accessories supplied on request: see data sheet Mounting Instructions and accessories for TO-220 envelopes.

BYT28 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

Voltages (per diode)			BYT28-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V
Crest working reverse voltage	V_{RWM}	max.	200	300	400	V
Continuous reverse voltage	V_R	max.	200	300	400	V

→ Currents (both diodes conducting: note 1)

Output current; switching

losses negligible up to 200 kHz;

square wave; $\delta = 0.5$; up to $T_{mb} = 117^\circ\text{C}$

I_O max. 10 A

sinusoidal; up to $T_{mb} = 120^\circ\text{C}$

I_O max. 10 A

R.M.S. forward current

$I_F(\text{RMS})$ max. 14 A

Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$ (per diode)

I_{FRM} max. 80 A

Non-repetitive peak forward current (per diode)

half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge

with re-applied V_{RWM} max

$t = 10$ ms

I_{FSM} max. 50 A

$t = 8.3$ ms

I_{FSM} max. 60 A

I^2t for fusing ($t = 10$ ms; per diode)

I^2t max. 12.5 A^2s

Temperatures

Storage temperature

T_{stg} -40 to +150 $^\circ\text{C}$

Junction temperature

T_j max. 150 $^\circ\text{C}$

Notes

1. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.

CHARACTERISTICS (per diode)

Forward voltage

$I_F = 5 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$

$V_F < 1.05 \text{ V}^*$

$I_F = 15 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.4 \text{ V}^*$

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$

$I_R < 0.2 \text{ mA}$

$V_R = V_{RWM \text{ max}}; T_j = 25 \text{ }^\circ\text{C}$

$I_R < 10 \text{ } \mu\text{A}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
recovery time

$t_{rr} < 50 \text{ ns}$

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
recovered charge

$Q_s < 50 \text{ nC}$

$I_F = 5 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 100 \text{ }^\circ\text{C}$
peak recovery current

$I_{RRM} < 3.0 \text{ A}$

Forward recovery when switched to $I_F = 1 \text{ A}$
with $dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
recovery voltage

$V_{fr} \text{ typ. } 2.5 \text{ V}$

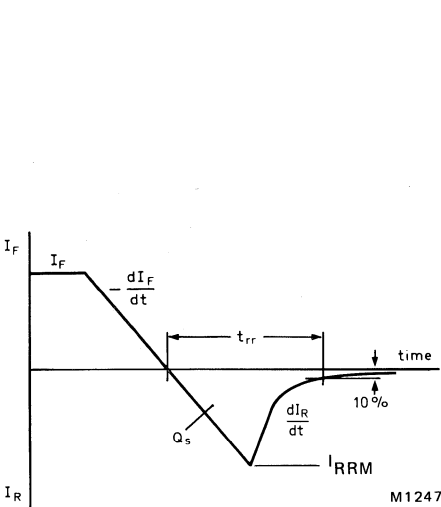


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

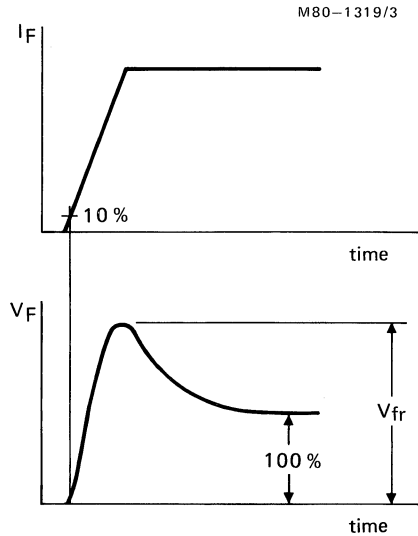


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)

$$R_{th\ j-mb} = 2.5 \text{ K/W}$$

From junction to mounting base (per diode)

$$R_{th\ j-mb} = 3.5 \text{ K/W}$$

→ **Influence of mounting method**

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

The various components of junction temperature rise above ambient are illustrated in Fig.4

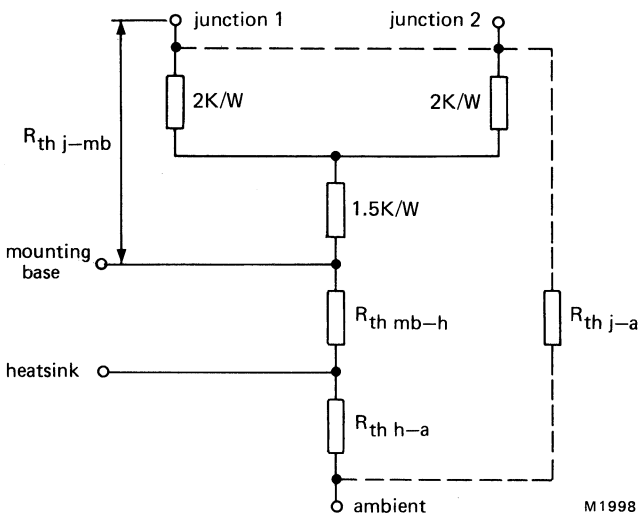


Fig.4

Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION (PER DIODE)

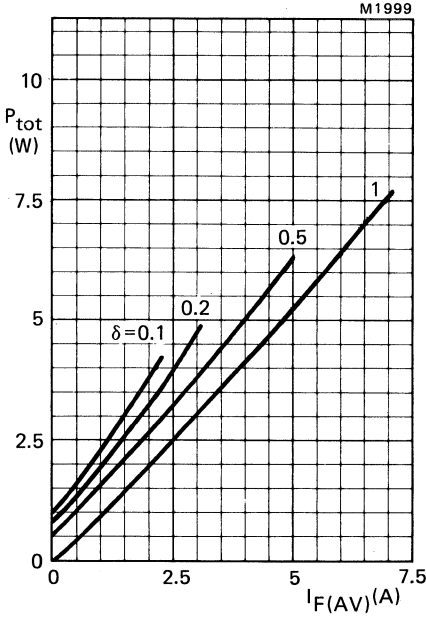
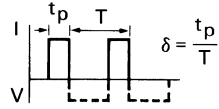


Fig.5 Power rating per diode.

The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

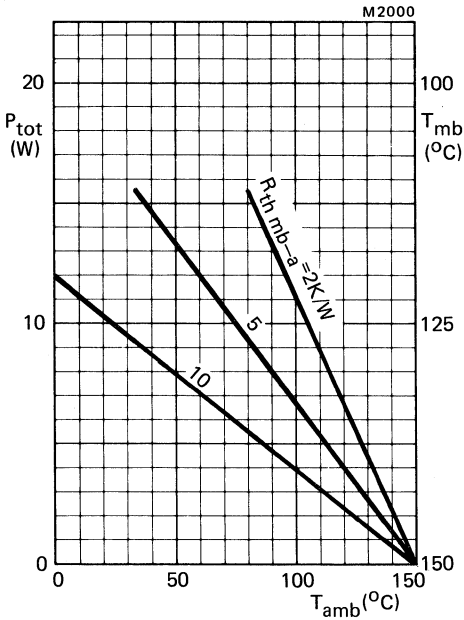


Fig.6

SINUSOIDAL OPERATION (PER DIODE)

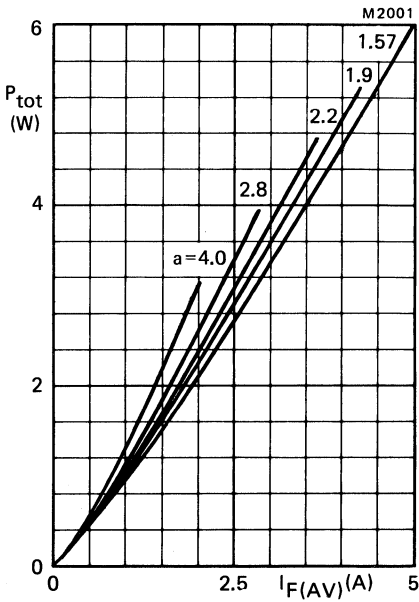
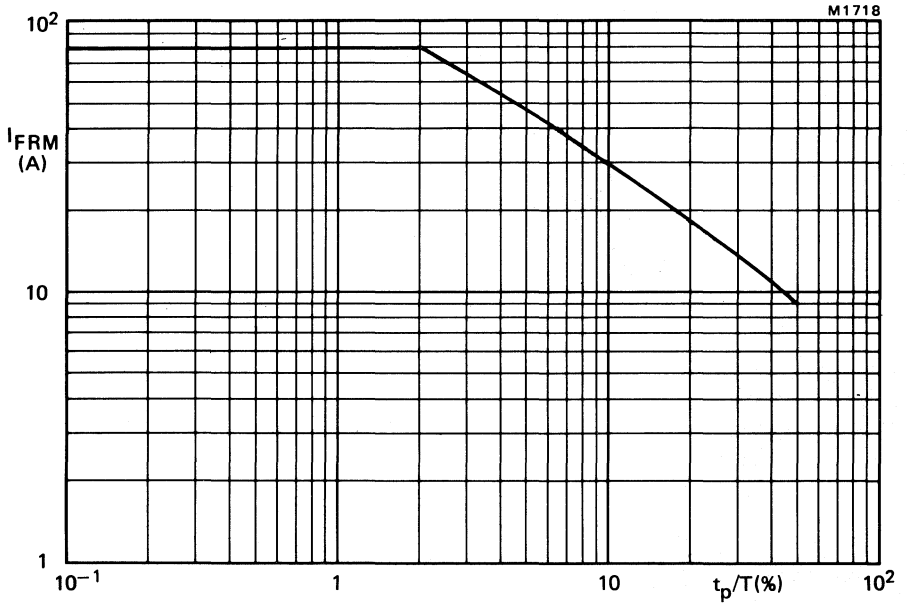


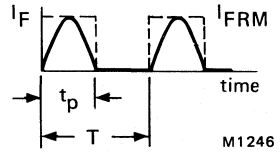
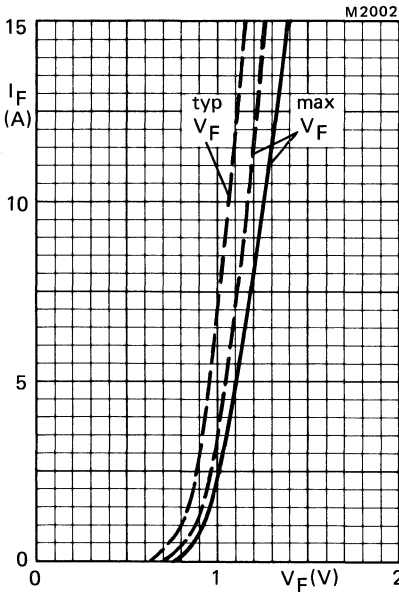
Fig.7 Power rating per diode.

The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$



→ Fig.8 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 ms$ per diode.



Definition of I_{FRM} and t_p/T

Fig.9 ——— $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$ per diode.

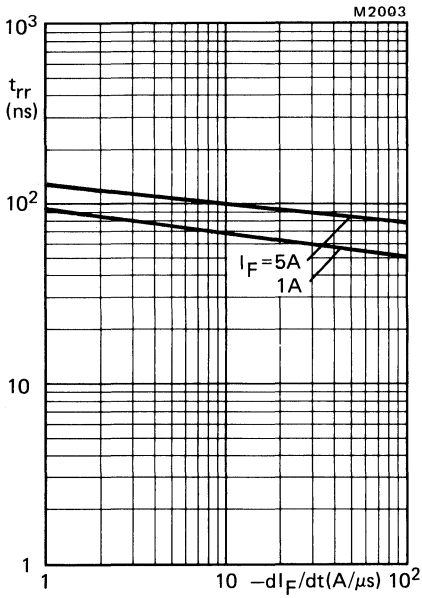


Fig.10 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$; per diode.

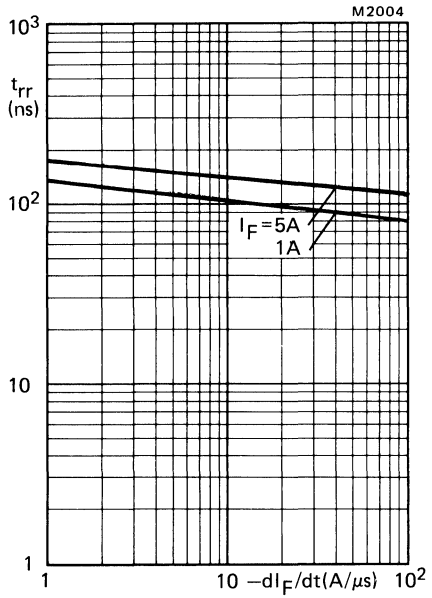


Fig.11 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$; per diode.

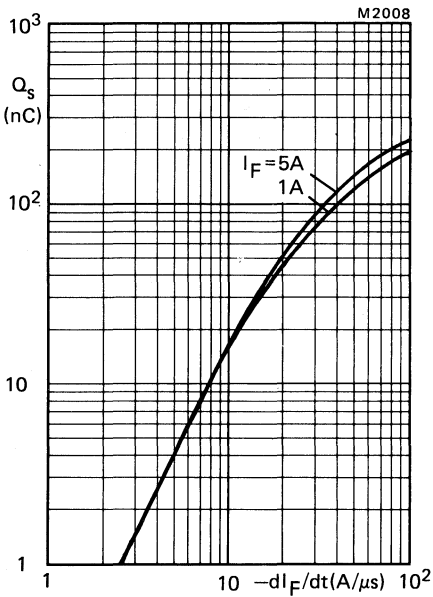


Fig.12 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$; per diode.

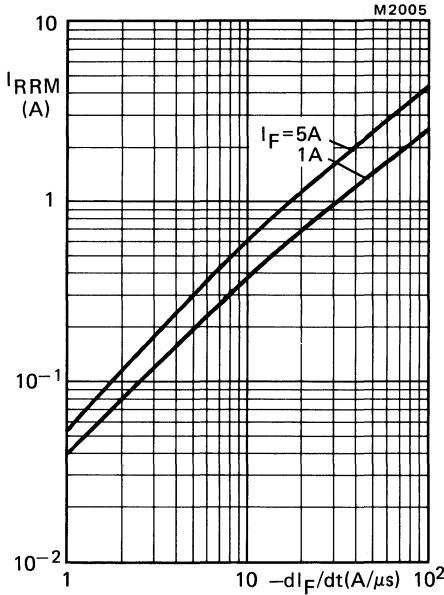


Fig.13 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$; per diode.

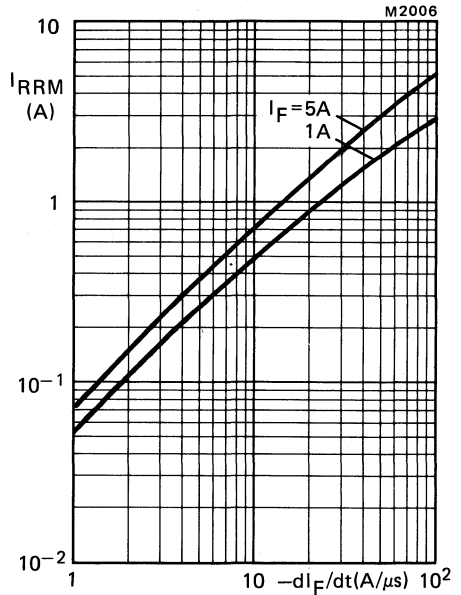


Fig.14 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$; per diode.

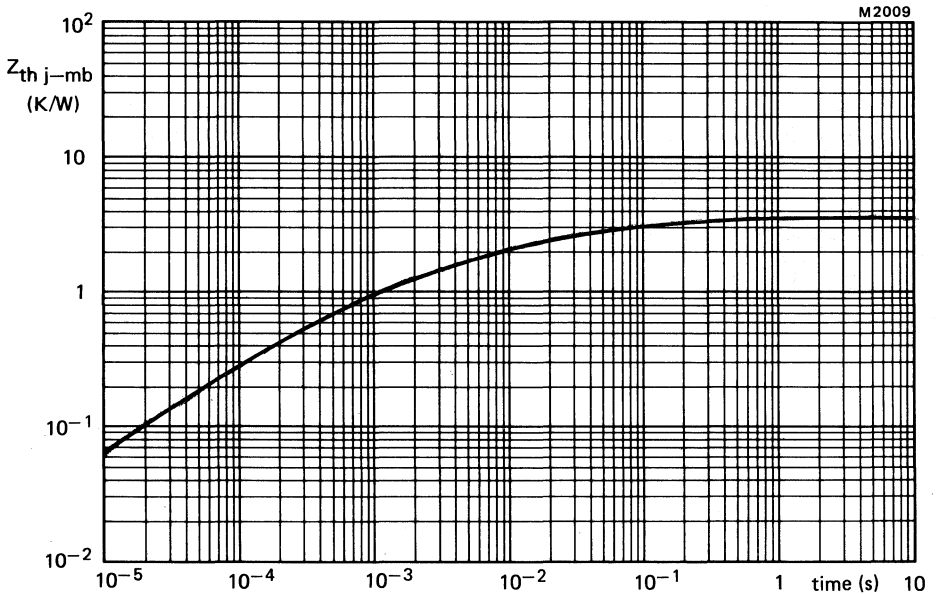


Fig.15 Transient thermal impedance (one diode conducting).

ULTRA FAST RECOVERY RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential.

The series consists of normal polarity (cathode to mounting base) types.

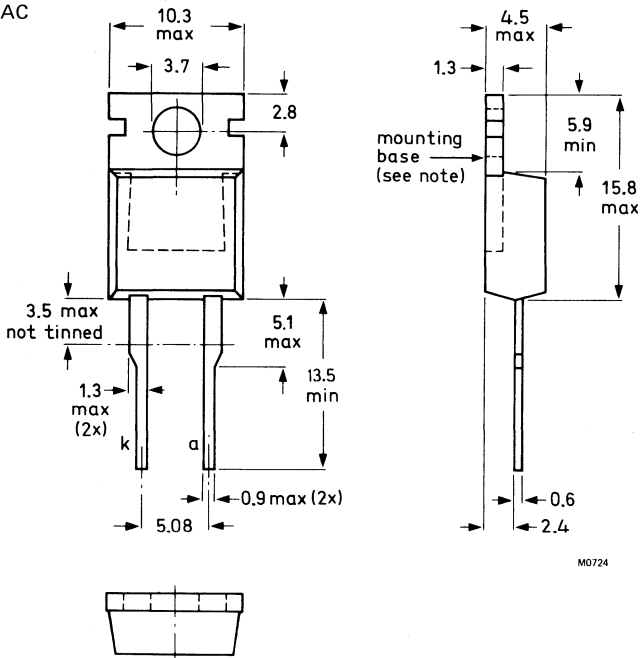
QUICK REFERENCE DATA

			BYT79-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V
Average forward current	$I_F(AV)$	max.	14			A
Forward voltage	V_F	<	1.05			V
Reverse recovery time	t_{rr}	<	50			ns

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AC



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

BYT79 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

			BYT79-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V
Crest working reverse voltage	V_{RWM}	max.	200	300	400	V
Continuous reverse voltage*	V_R	max.	200	300	400	V

Currents

Average forward current; switching						
→ losses negligible up to 200 kHz;						
square wave; $\delta = 0.5$; up to $T_{mb} = 113\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	14			A
up to $T_{mb} = 125\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	10			A
sinusoidal; up to $T_{mb} = 118\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	12.5			A
up to $T_{mb} = 125\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	10			A
R.M.S. forward current	$I_{F(RMS)}$	max.	20			A
Repetitive peak forward current						
$t_p = 20\text{ }\mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.	320			A
Non-repetitive peak forward current						
half sine-wave; $T_j = 150\text{ }^\circ\text{C}$ prior to surge;						
with reapplied V_{RWMmax} :						
$t = 10\text{ ms}$	I_{FSM}	max.	150			A
$t = 8.3\text{ ms}$	I_{FSM}	max.	180			A
$I^2 t$ for fusing ($t = 10\text{ ms}$)	$I^2 t$	max.	112			A^2s

Temperatures

Storage temperature	T_{stg}		-40 to +150			$^\circ\text{C}$
Junction temperature	T_j	max.	150			$^\circ\text{C}$

*To ensure thermal stability: $R_{th\ j-a} \leq 4.6\text{ K/W}$.

CHARACTERISTICS

Forward voltage

$I_F = 15 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$

$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

V_F	<	1.05	V*
V_F	<	1.40	V*

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$
 $T_j = 25 \text{ }^\circ\text{C}$

I_R	<	0.8	mA
I_R	<	50	μA

Reverse recovery when switched from

$I_F = 1 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovery time

$I_F = 2 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 20 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovered charge

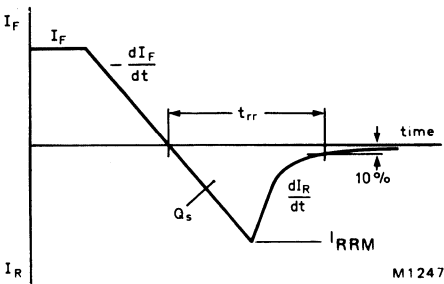
$I_F = 10 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 50 \text{ A}/\mu\text{s}$;
 $T_j = 100 \text{ }^\circ\text{C}$; peak recovery current

t_{rr}	<	50	ns
Q_s	<	50	nC

I_{RRM}	<	5.2	A
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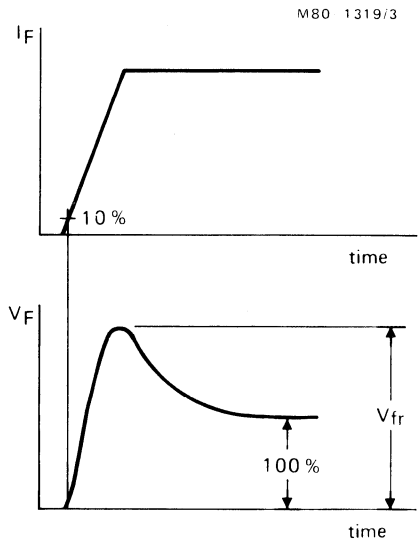
Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}$; $T_j = 25 \text{ }^\circ\text{C}$

V_{fr}	typ.	2.5	V
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M1247

Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .



M80 1319/3

Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 2 \text{ K/W}$$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275°C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

- a. The various components of junction temperature rise above ambient are illustrated in Fig.4.

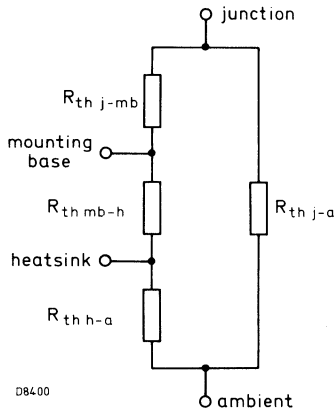


Fig. 4.

- b. Any measurement of heatsink temperature should be made immediately adjacent to the device.
- c. The method of using Figs. 5 and 6 is as follows:
Starting with the required current on the $I_F(AV)$ axis, trace upwards to meet the appropriate duty cycle or form factor curve. Trace right horizontally and upwards from the required value on the T_{amb} scale. The intersection determines the $R_{th\ mb-a}$. The heatsink thermal resistance value ($R_{th\ h-a}$) can be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

SQUARE-WAVE OPERATION

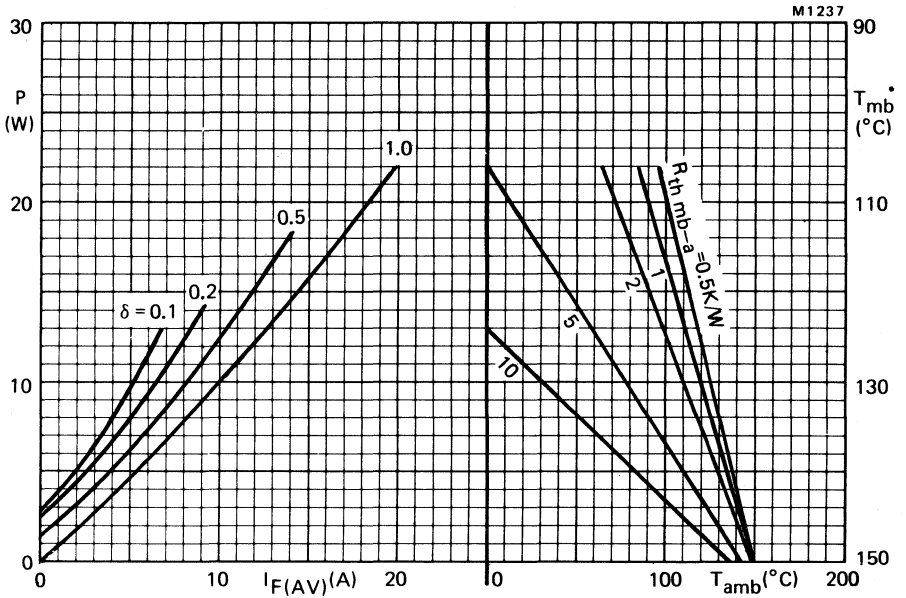
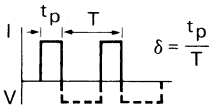


Fig.5 The right-hand part shows the relationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 200$ kHz.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 4.1$ K/W.

SINUSOIDAL OPERATION

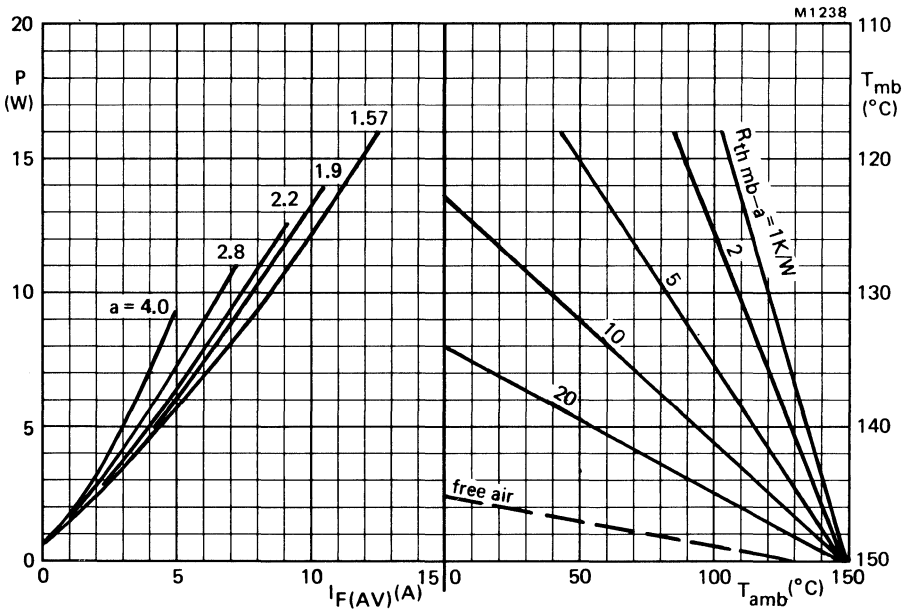


Fig.6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.
 $a = \text{form factor} = I_F(RMS)/I_F(AV)$.

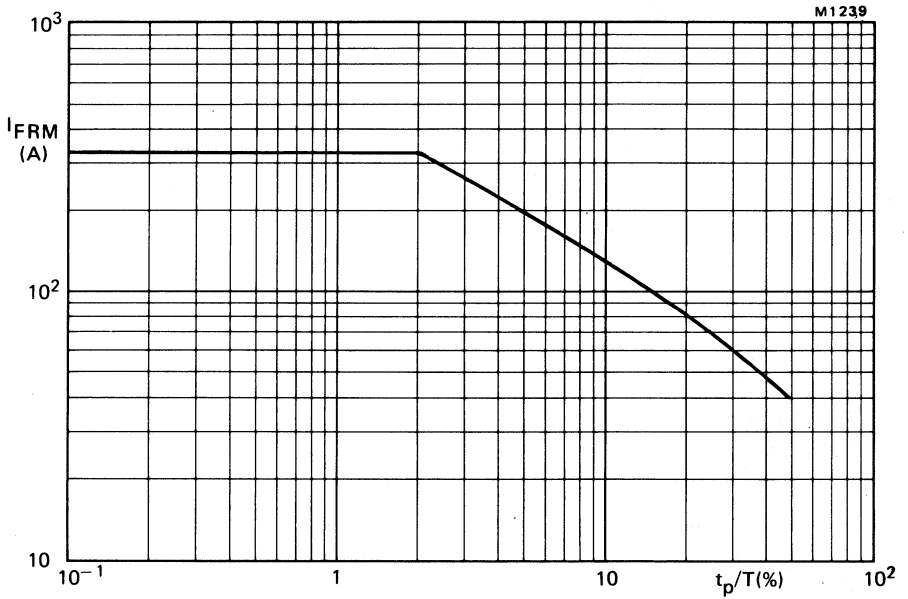
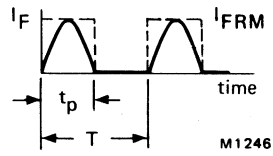
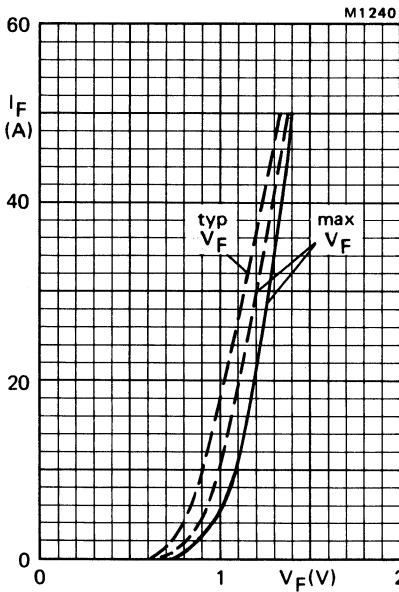


Fig.7 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 ms$.



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25^\circ C$; - - - $T_j = 150^\circ C$.

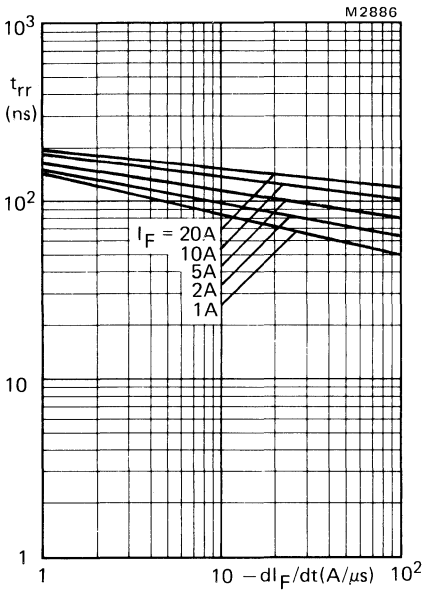


Fig.9 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

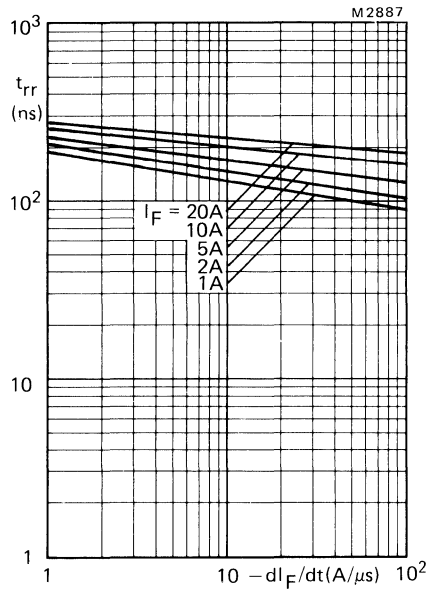


Fig.10 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

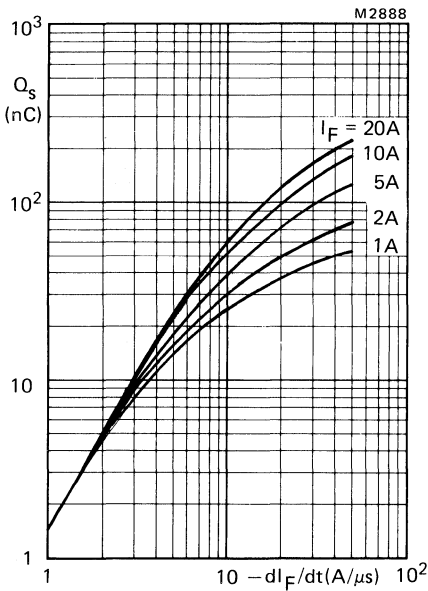


Fig.11 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

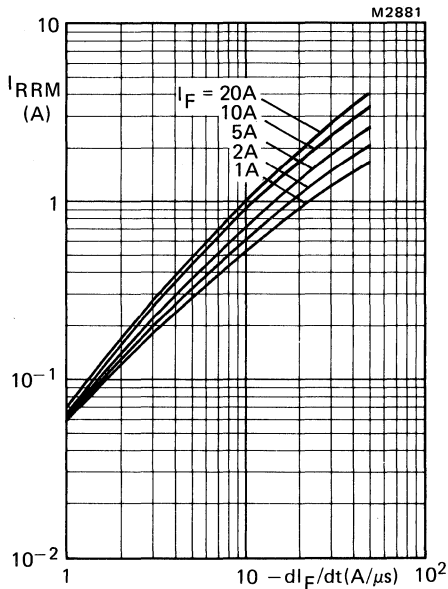


Fig.12 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

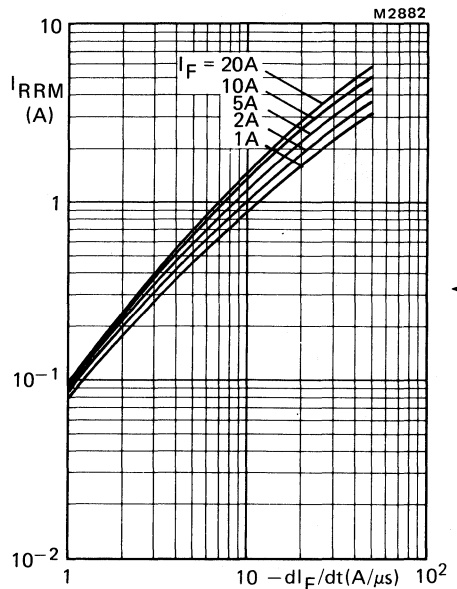


Fig.13 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

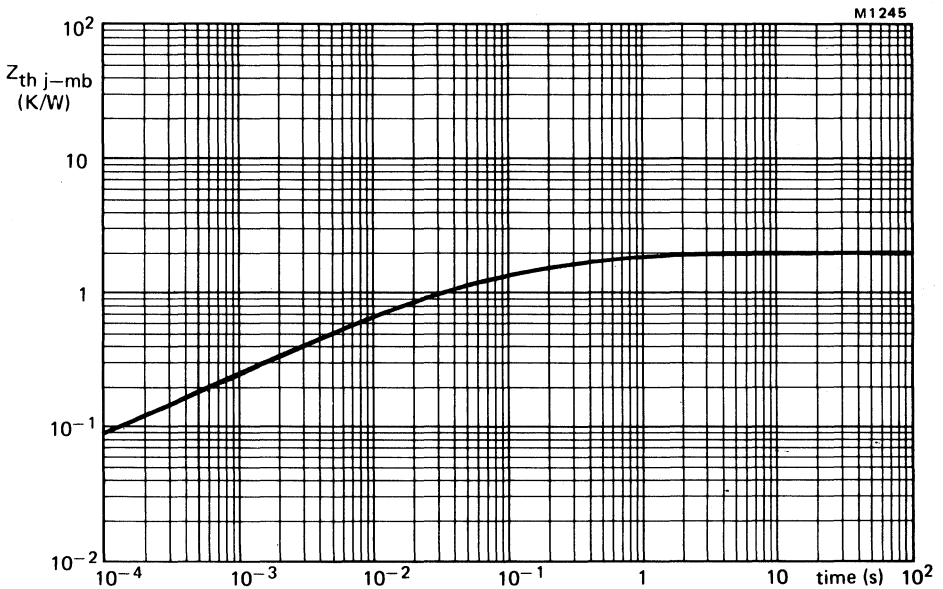


Fig.14 Transient thermal impedance.

FAST SOFT-RECOVERY RECTIFIER DIODES

Fast soft-recovery diodes in DO-4 metal envelopes especially suitable for operation as main and commutating diodes in 3-phase a.c. motor speed control inverters and in high frequency power supplies in general.

The series consists of the following types:

Normal polarity (cathode to stud): BYV24-800 and BYV24-1000.

Reverse polarity (anode to stud): BYV24-800R and BYV24-1000R.

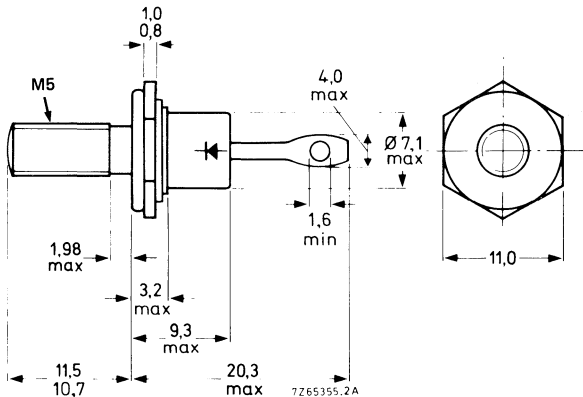
QUICK REFERENCE DATA

		BYV24-800(R)		1000(R)	
Repetitive peak reverse voltage	V_{RRM}	max. 800	1000		V
Average forward current	$I_{F(AV)}$	max. 12			A
Non-repetitive peak forward current	I_{FSM}	max. 150			A
Reverse recovery time	t_{rr}	<	450		ns

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4: with metric M5 stud ($\phi 5$ mm)



Net mass: 6 g

Diameter of clearance hole: max 5.2 mm

Accessories supplied on request:
see ACCESSORIES section

Supplied with device: 1 nut, 1 lock washer.

Torque on nut: min. 0.9 Nm (9 kg cm)

max. 1.7 Nm (17 kg cm)

Nut dimensions across the flats: 8.0 mm.

The mark shown applies to the normal polarity types.

BYV24 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages*

			BYV24-800(R)	1000(R)	
Non-repetitive peak reverse voltage	V_{RSM}	max.	1000	1200	V
Repetitive peak reverse voltage	V_{RRM}	max.	800	1000	V
Crest working reverse voltage	V_{RWM}	max.	650	850	V
Continuous reverse voltage	V_R	max.	650	850	V

Currents

Average forward current					
sinusoidal; up to $T_{mb} = 103\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	12		A
sinusoidal; at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	7		A
square-wave; $\delta = 0.5$; up to $T_{mb} = 103\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	14		A
square-wave; $\delta = 0.5$; at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	8		A
R.M.S. forward current	$I_{F(RMS)}$	max.	20		A
Repetitive peak forward current	I_{FRM}	max.	120		A
Non-repetitive peak forward current					
$t = 10\text{ ms}$; half sine-wave;					
$T_j = 150\text{ }^\circ\text{C}$ prior to surge;	I_{FSM}	max.	150		A
without re-applied voltage	I_{FSM}	max.	120		A
with re-applied V_{RWMmax}					
$I^2 t$ for fusing ($t = 10\text{ ms}$)	$I^2 t$	max.	72		A^2s

Temperatures

Storage temperature	T_{stg}		-55 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.	150		$^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	2.0		$^\circ\text{C/W}$
From mounting base to heatsink					
with heatsink compound	$R_{th\ mb-h}$	=	0.3		$^\circ\text{C/W}$
without heatsink compound	$R_{th\ mb-h}$	=	0.5		$^\circ\text{C/W}$
Transient thermal impedance; $t = 1\text{ ms}$	$Z_{th\ j-mb}$	=	0.85		$^\circ\text{C/W}$

MOUNTING INSTRUCTIONS

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

*To ensure thermal stability: $R_{th\ j-a} \leq 8\text{ }^\circ\text{C/W}$ (continuous reverse voltage).

CHARACTERISTICS

Forward voltage

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C} \qquad V_F < 1.7 \text{ V}^*$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C} \qquad I_R < 1.5 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 10 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovery time $t_{rr} < 450 \text{ ns}$

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovered charge $Q_s < 800 \text{ nC}$

Maximum slope of the reverse recovery current

$$\text{when switched from } I_F = 2 \text{ A to } V_R \geq 30 \text{ V};$$

$$\text{with } -dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C} \qquad |dI_R/dt| < 7 \text{ A}/\mu\text{s}$$

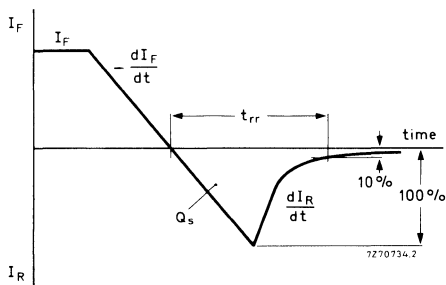


Fig.2 Definition of t_{rr} and Q_s .

*Measured under pulse conditions to avoid excessive dissipation.

SINUSOIDAL OPERATION

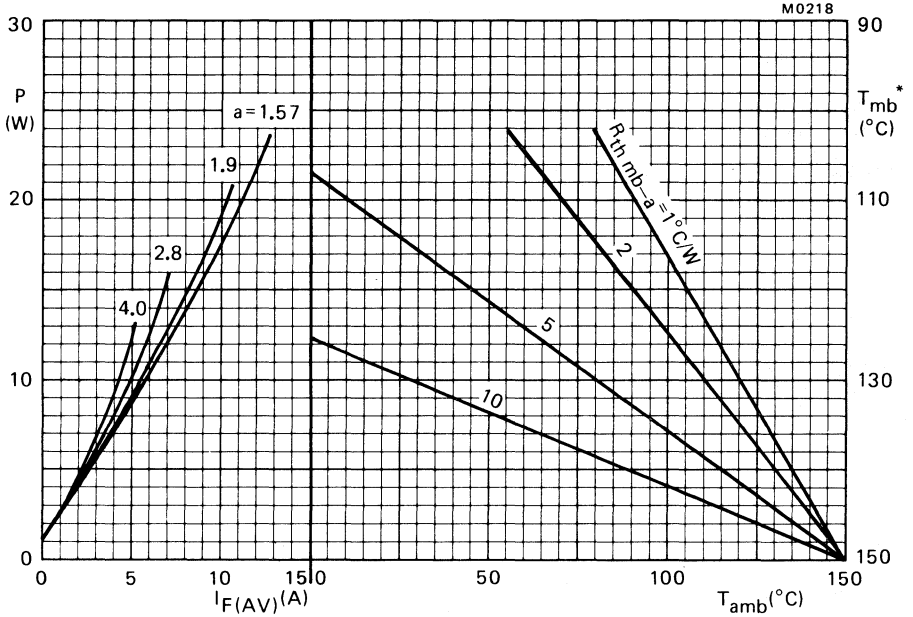


Fig.3 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.

a = form factor = $I_F(RMS)/I_F(AV)$.

*T_{mb} scale is for comparison purposes and is correct only for R_{th mb-a} < 8 °C/W.

SQUARE-WAVE OPERATION

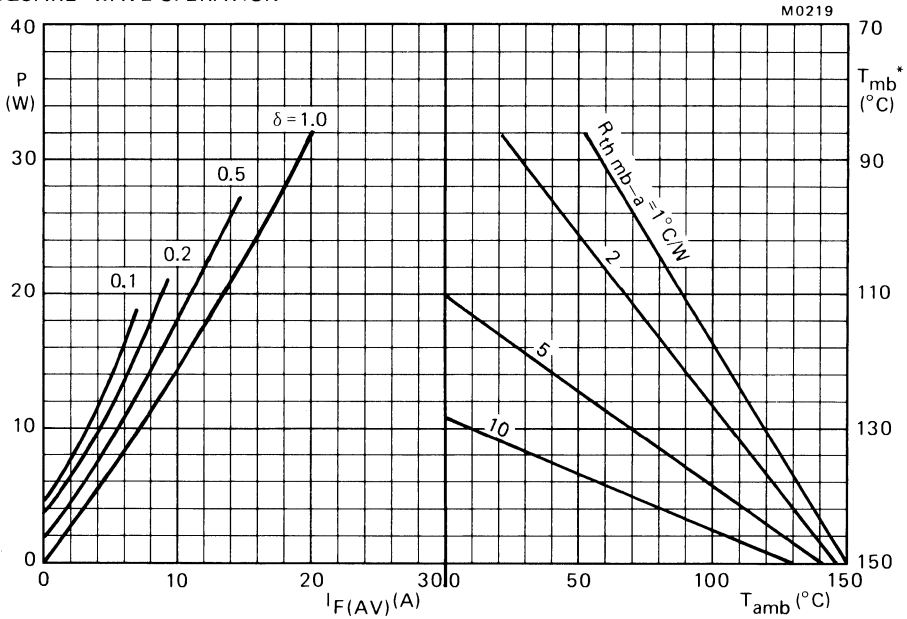
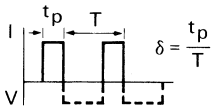


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

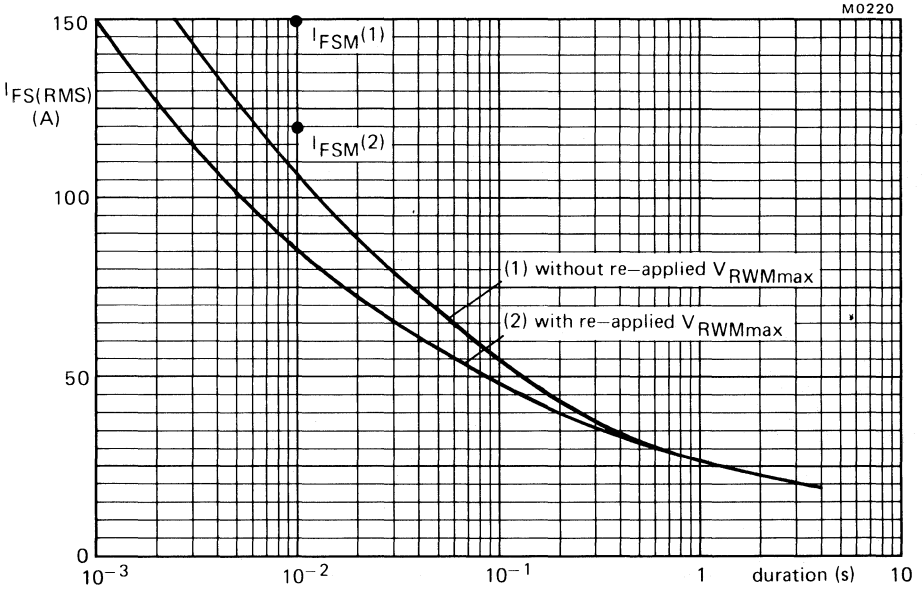


Fig.5 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 150$ °C prior to surge.

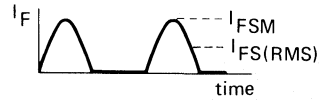
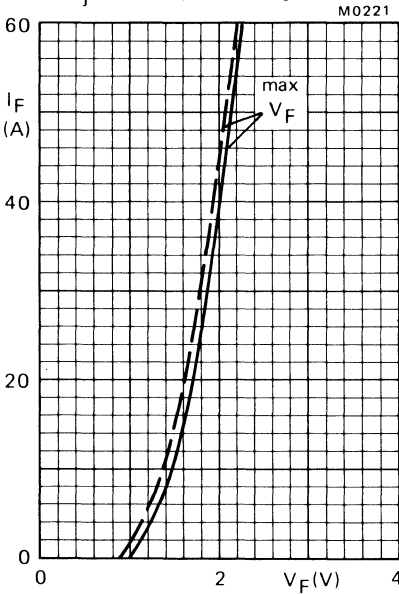


Fig.6. — $T_j = 25$ °C; - - - $T_j = 100$ °C.

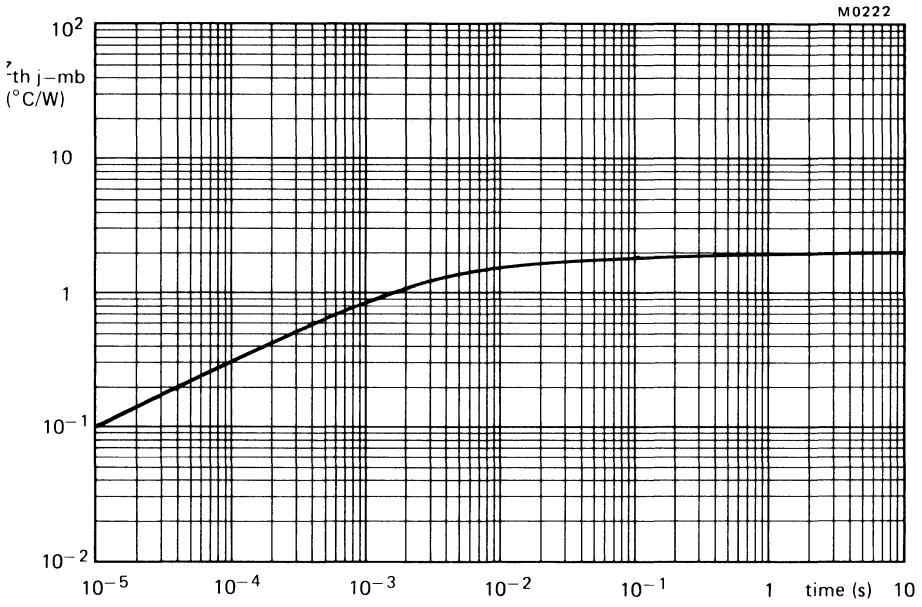


Fig.7

VERY FAST SOFT-RECOVERY AVALANCHE RECTIFIER DIODES

Glass passivated rectifier diodes in hermetically sealed axial-led glass envelopes. They are intended for use in switched-mode power supplies and high-frequency inverter circuits. In general, they are used where high output voltages and low switching losses are essential. The devices feature non-snap-off (soft-recovery) switching characteristics and are capable of absorbing reverse transient energy.

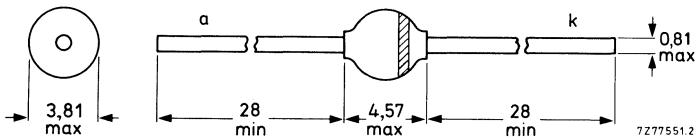
QUICK REFERENCE DATA

		BYV26A	26B	26C	26D	26E
Repetitive peak reverse voltage	V_{RRM}	max. 200	400	600	800	1000 V
Continuous reverse voltage	V_R	max. 200	400	600	800	1000 V
Average forward current	$I_F(AV)$	max. 1	1	1	1	1 A
Non-repetitive peak forward current	I_{FSM}	max. 30	30	30	30	30 A
Non-repetitive peak reverse energy	E_{RSM}	max. 10	10	10	10	10 mJ
Reverse recovery time	t_{rr}	< 30	30	30	75	75 ns

MECHANICAL DATA

Dimensions in mm

Fig. 1 SOD-57.



The marking band indicates the cathode.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

		BYV26A	26B	26C	26D	26E
Repetitive peak reverse voltage	V_{RRM}	max. 200	400	600	800	1000 V
Continuous reverse voltage	V_R	max. 200	400	600	800	1000 V
Average forward current averaged over any 20 ms period						
$T_{tp} = 85\text{ }^\circ\text{C}$; lead length 10 mm	$I_{F(AV)}$	max.		1		A
$T_{amb} = 60\text{ }^\circ\text{C}$; see Fig. 2	$I_{F(AV)}$	max.		0,65		A
Repetitive peak forward current; see Figs 11 and 12	I_{FRM}	max.		10		A
Non-repetitive peak forward current $t = 10\text{ ms}$; half-sinewave; $T_j = T_{j\text{ max}}$ prior to surge; $V_R = V_{RRM\text{ max}}$	I_{FSM}	max.		30		A
Non-repetitive peak reverse avalanche energy $I_R = 400\text{ mA}$; $T_j = T_{j\text{ max}}$ prior to surge; with inductive load switched off	E_{RSM}	max.		10		mJ
Storage temperature	T_{stg}			-65 to +175		$^\circ\text{C}$
Junction temperature	T_j	max.		175		$^\circ\text{C}$

THERMAL RESISTANCE

Influence of mounting method

1. Thermal resistance from junction to tie-point at a lead length of 10 mm
 $R_{th\ j\text{-}tp} =$ 46 K/W
2. Thermal resistance from junction to ambient; device mounted on an 1,5 mm thick epoxy-glass printed-circuit board; Cu-thickness $> 40\text{ }\mu\text{m}$; Fig. 2
 $R_{th\ j\text{-}a} =$ 100 K/W

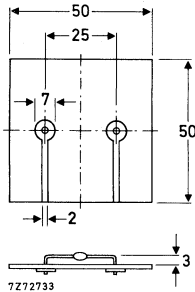


Fig. 2 Mounted on a printed-circuit board.

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise specified

		BYV26A	26B	26C	26D	26E
Forward voltage*	$I_F = 1\text{ A}; T_j = 175\text{ }^\circ\text{C}$	$V_F < 1,3$	1,3	1,3	1,3	1,3 V*
	$I_F = 1\text{ A}$	$V_F < 2,5$	2,5	2,5	2,5	2,5 V
Reverse avalanche breakdown voltage	$I_R = 0,1\text{ mA}$	$V_{(BR)R} > 300$	500	700	900	1100 V
Reverse current	$V_R = V_{RRMmax}$	$I_R < 5$	5	5	5	5 μA
	$V_R = V_{RRMmax}; T_j = 165\text{ }^\circ\text{C}$	$I_R < 150$	150	150	150	150 μA
Reverse recovery time when switched from $I_F = 0,5\text{ A}$ to $I_R = 1\text{ A}$; measured at $I_R = 0,25\text{ A}$ for definition see Figs 3 and 4	t_{rr}	< 30	30	30	75	75 ns

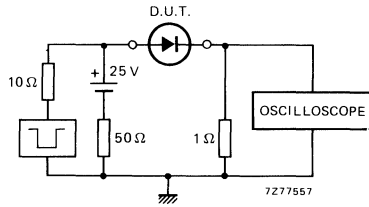


Fig. 3 Test circuit. Input impedance oscilloscope: 1 M Ω ; 22 pF; rise time < 7 ns. Source impedance: 50 Ω ; rise time < 15 ns.

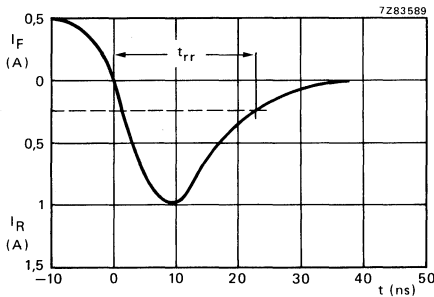


Fig. 4 Reverse recovery time characteristic.

* Measured under pulse conditions to avoid excessive dissipation.

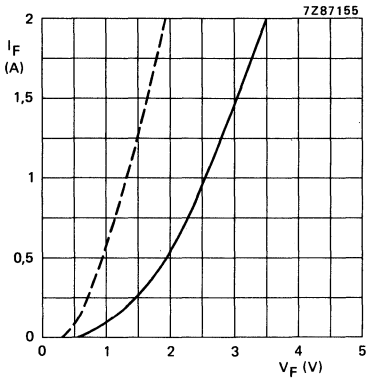


Fig. 5 Maximum forward voltage at
 — $T_j = 25^\circ\text{C}$
 - - - $T_j = 175^\circ\text{C}$.

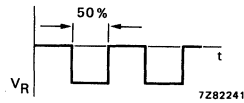
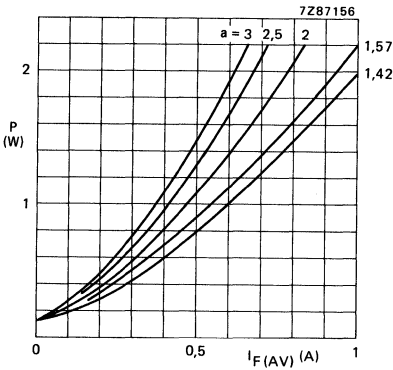


Fig. 6 Maximum steady state power dissipation (forward plus leakage current) excluding switching losses as a function of the average forward current.
 The graph is for switched-mode application.

$a = I_F(\text{RMS})/I_F(\text{AV})$;

$V_R = V_{RRM\text{max}}$, $\delta = 0,5$.

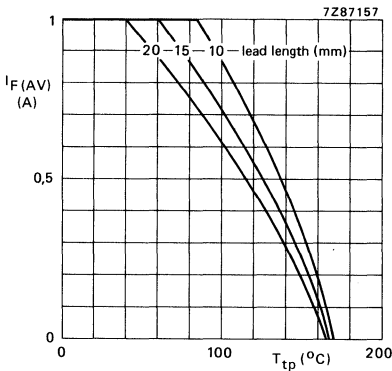


Fig. 7 Maximum average forward current as a function of the tie-point temperature; the curves include losses due to reverse leakage.

The graph is for switched-mode application. $V_R = V_{RRM\text{max}}$, $\delta = 0,5$;
 $a = 1,42$.

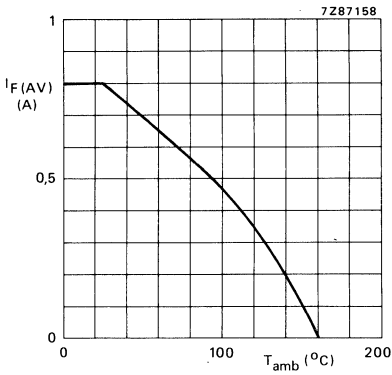


Fig. 8 Maximum average forward current as a function of the ambient temperature; the curve includes losses due to reverse leakage. Mounting method see Fig. 2. The graph is for switched-mode application. $V_R = V_{RRMmax}$, $\delta = 0,5$; $a = 1,42$.

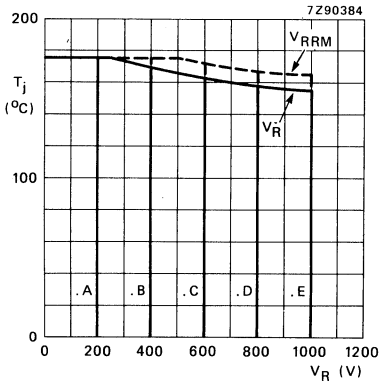


Fig. 9 Maximum permissible junction temperature as a function of the applied reverse voltage.

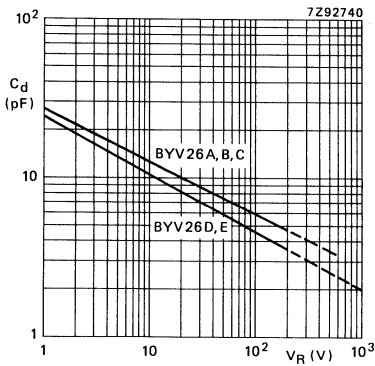


Fig. 10 Capacitance versus voltage; typical values.

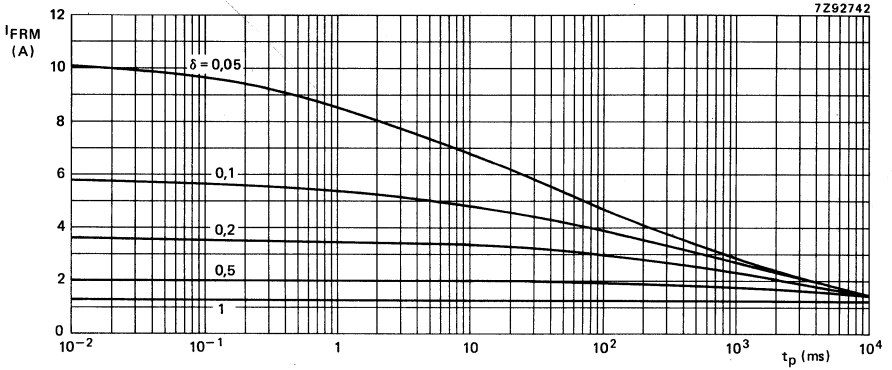


Fig. 11 Maximum repetitive peak forward current versus pulse time (square pulse) and duty factor δ at $T_{tp} = 85^\circ\text{C}$; $R_{th j-tp} = 46 \text{ K/W}$; V_{RRM} during $1 - \delta$; the curves include derating for $T_j \text{ max}$ at $V_{RRM} = 1000 \text{ V}$.

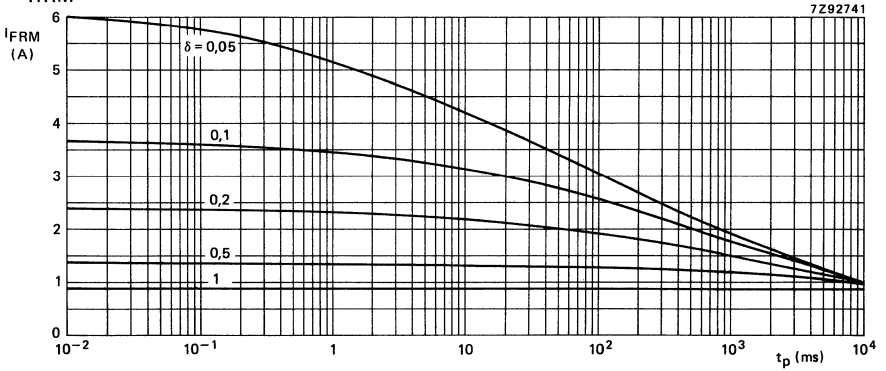


Fig. 12 Maximum repetitive peak forward current versus pulse time (square pulse) and duty factor δ at $T_{amb} = 60^\circ\text{C}$; $R_{th j-a} = 100 \text{ K/W}$; V_{RRM} during $1 - \delta$; the curves include derating for $T_j \text{ max}$ at $V_{RRM} = 1000 \text{ V}$.

EPITAXIAL AVALANCHE DIODES

Glass passivated epitaxial rectifier diodes in hermetically sealed axial-led glass envelopes. They feature low forward voltage drop, very fast recovery, very low stored charge, non-snap-off switching characteristics and are capable of absorbing reverse transient energy (e.g. during flashover in a picture tube). These properties make the diodes very suitable for use in switched-mode power supplies and in general high-frequency circuits, where low conduction and switching losses are essential.

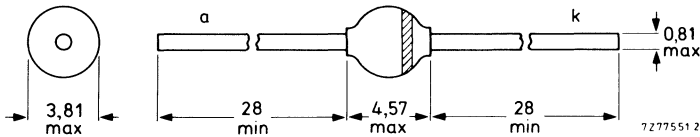
QUICK REFERENCE DATA

		BYV27-50	100	150	200
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200 V
Continuous reverse voltage	V_R	max. 50	100	150	200 V
Average forward current	$I_F(AV)$	max.	2		A
Non-repetitive peak reverse energy	E_{RSM}	max.	40		mJ
Reverse recovery time	t_{rr}	<	25		ns

MECHANICAL DATA

Dimensions in mm

Fig. 1 SOD-57.



The marking band indicates the cathode.

The diodes are type-branded.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

		BYV27-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Continuous reverse voltage	V_R	max. 50	100	150	200	V
Average forward current (switching losses negligible up to 200 kHz) square wave; $\delta = 0,5$						
$T_{tp} = 85\text{ }^\circ\text{C}$; lead length = 10 mm	$I_{F(AV)}$	max.		2		A
$T_{amb} = 60\text{ }^\circ\text{C}$; Fig. 2	$I_{F(AV)}$	max.		1,3		A
Repetitive peak forward current	I_{FRM}	max.		15		A
Non-repetitive peak forward current ($t = 10\text{ ms}$; half sine-wave) $T_j = T_{j\text{ max}}$ prior to surge; with reapplied V_{RRM}	I_{FSM}	max.		50		A
Non-repetitive peak reverse avalanche energy; $I_R = 600\text{ mA}$; prior to surge; with inductive load switched off: $T_j = 25\text{ }^\circ\text{C}$, prior to surge $T_j = T_{j\text{ max}}$, prior to surge	E_{RSM}	max.		40		mJ
	E_{RSM}	max.		20		mJ
Storage temperature	T_{stg}		-65 to +175			$^\circ\text{C}$
Junction temperature	T_j	max.		175		$^\circ\text{C}$

THERMAL RESISTANCE

Influence of mounting method

1. Thermal resistance from junction to tie-point at a lead length of 10 mm
 $R_{th\ j\text{-}tp} = 46\text{ K/W}$
2. Thermal resistance from junction to ambient when mounted on a 1,5 mm thick epoxy-glass printed-circuit board; Cu-thickness $\geq 40\text{ }\mu\text{m}$; Fig. 2
 $R_{th\ j\text{-}a} = 100\text{ K/W}$

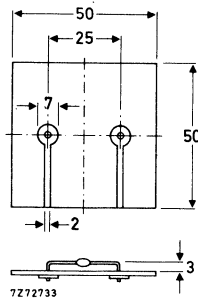


Fig. 2 Mounted on a printed-circuit board.

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise specified

	BYV27-50	100	150	200	
Reverse avalanche breakdown voltage $I_R = 0,1\text{ mA}$	$V_{(BR)R} >$	55	110	165	220 V
Forward voltage* $I_F = 3\text{ A}; T_j = T_{j\text{ max}}$	$V_F <$		0,88		V
$I_F = 3\text{ A}$	$V_F <$		1,07		V
Reverse current $V_R = V_{RRM\text{ max}}$	$I_R <$		1		μA
$V_R = V_{RRM\text{ max}}; T_j = 165\text{ }^\circ\text{C}$	$I_R <$		150		μA
Reverse recovery time when switched from $I_F = 0,5\text{ A}$ to $I_R = 1\text{ A}$; measured at $I_R = 0,25\text{ A}$ for definition see Figs 3 and 4	$t_{rr} <$		25		ns

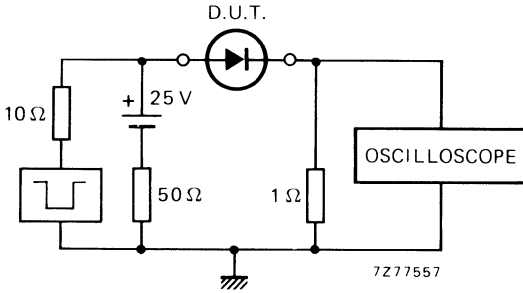


Fig. 3 Test circuit.
Input impedance oscilloscope 1 M Ω ; 22 pF. Rise time $\leq 7\text{ ns}$.
Source impedance 50 Ω . Rise time $\leq 15\text{ ns}$.

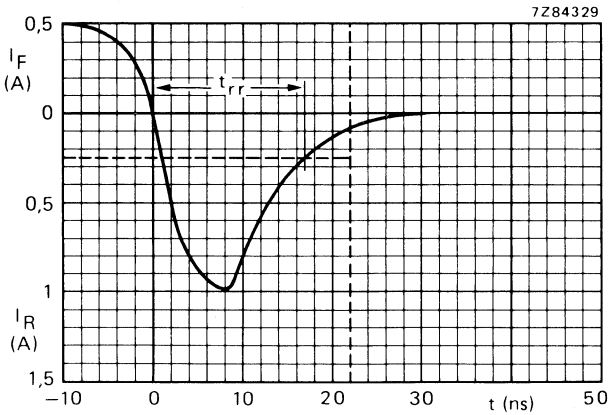


Fig. 4 Reverse recovery time characteristic.

* Measured under pulse conditions to avoid excessive dissipation.

Reverse recovery when switched from
 $I_F = 1 \text{ A}$ to $V_R \geq 30 \text{ V}$ with
 $-dI_F/dt = 20 \text{ A}/\mu\text{s}$ (see Fig. 5)
 recovered charge
 recovery time

$Q_s < 15 \text{ nC}$
 $t_{rr} < 50 \text{ ns}$

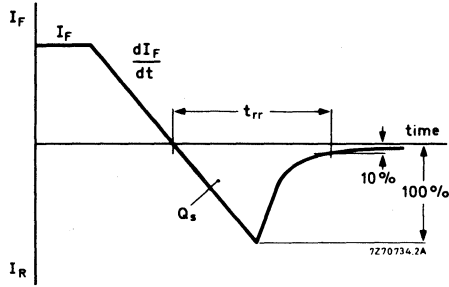


Fig. 5 Definitions of t_{rr} and Q_s .

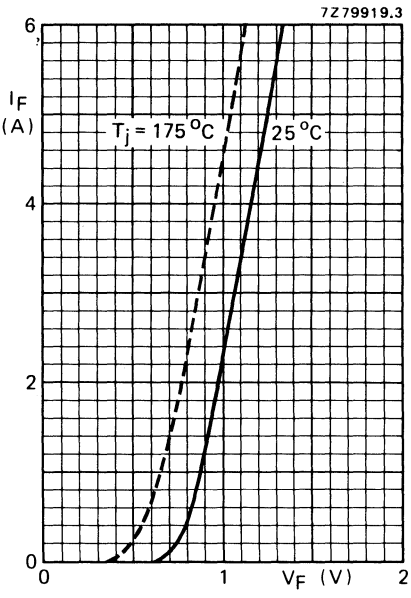


Fig.6 Maximum forward voltage.

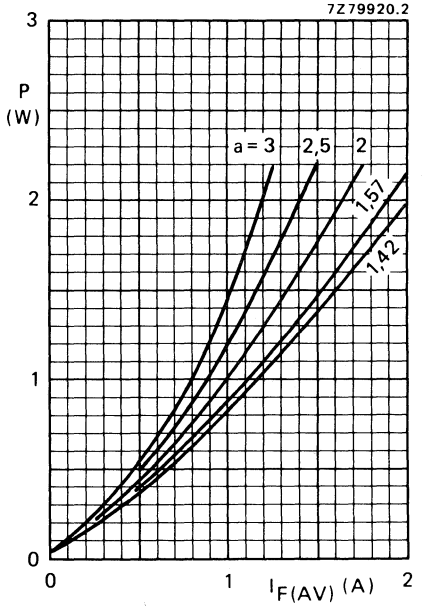


Fig. 7 $a = I_F(\text{RMS})/I_F(\text{AV})$; $V_R = V_{RRMmax}$. Pulsed reverse voltage; $\delta = 0,5$. (Including reverse current losses and switching losses up to $f = 200 \text{ kHz}$).

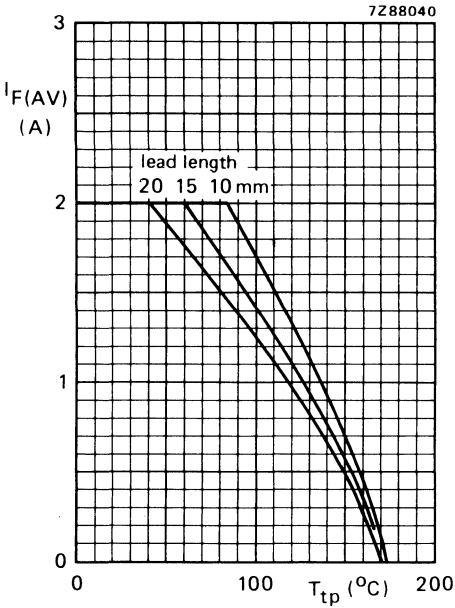


Fig. 8 Maximum average forward current. The curves include losses due to reverse current and switching up to $f = 200$ kHz. Pulsed reverse voltage, $\delta = 0,5$. $V_R = V_{RRMmax}$. Square wave current, $a = 1,42$.

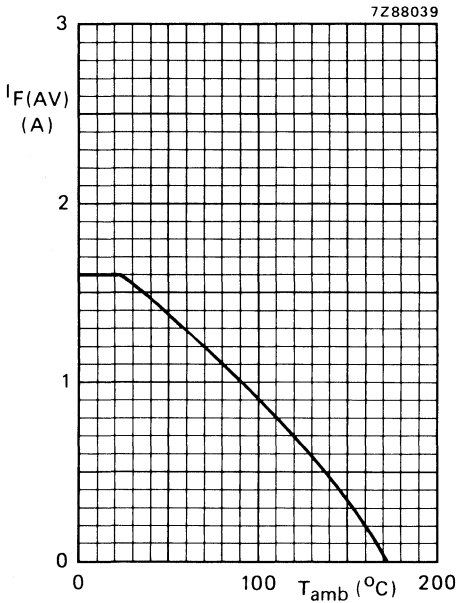


Fig. 9 Maximum average forward current. The curve includes losses due to reverse current and switching up to $f = 200$ kHz. Mounting method see Fig. 2. Pulsed reverse voltage, $\delta = 0,5$. $V_R = V_{RRMmax}$. Square wave current, $a = 1,42$.

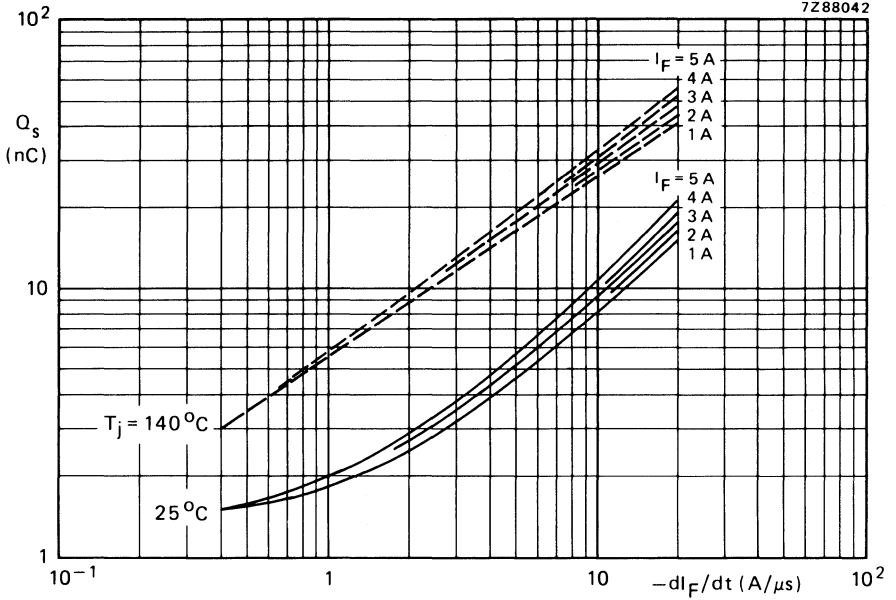


Fig. 10 Maximum values reverse recovery charge. For definition see Fig. 5.

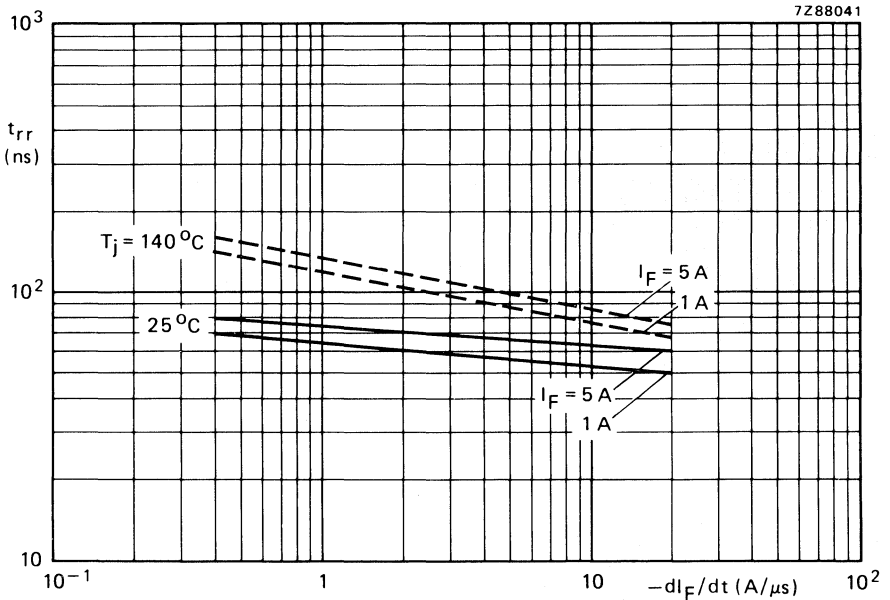


Fig. 11 Maximum values reverse recovery time. For definition see Fig. 5.

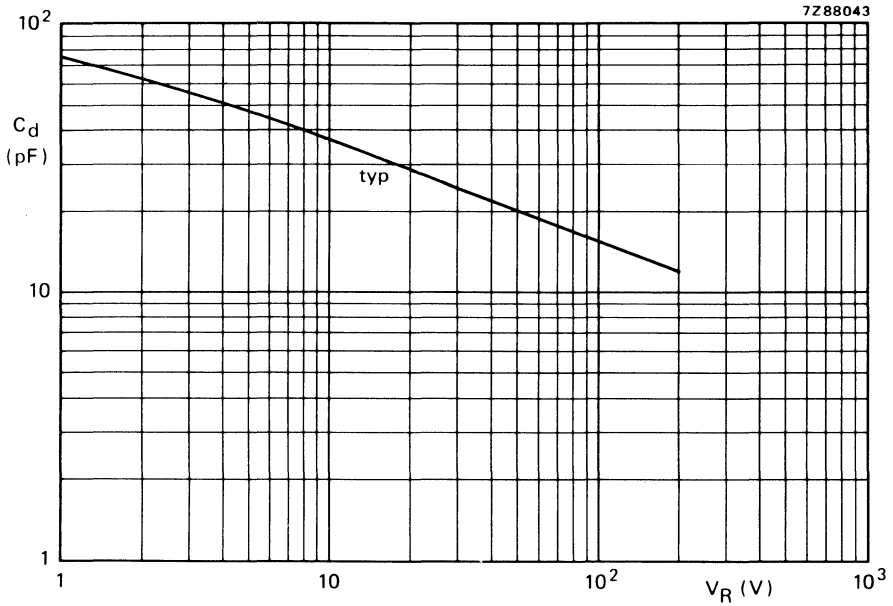


Fig. 12 Typical values diode capacitance at $f = 1$ MHz; $T_j = 25$ °C.

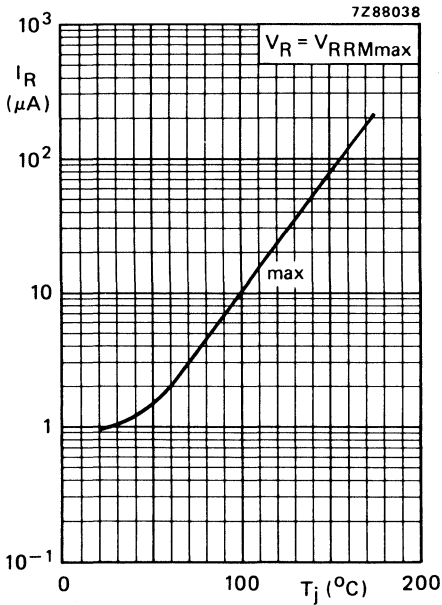


Fig. 13 Maximum values reverse current.

EPITAXIAL AVALANCHE DIODES

Glass passivated epitaxial rectifier diodes in hermetically sealed axial-leaded glass envelopes. They feature low forward voltage drop, very fast recovery, very low stored charge, non-snap-off switching characteristics and are capable of absorbing reverse transient energy (e.g. during flashover in a picture tube). These properties make the diodes very suitable for use in switched-mode power supplies and in general in high-frequency circuits, where low conduction and switching losses are essential.

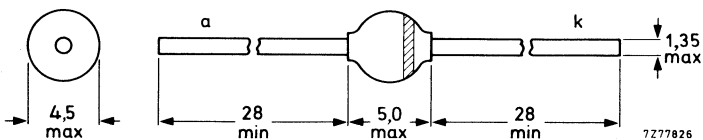
QUICK REFERENCE DATA

		BYV28-50			
		100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200 V
Continuous reverse voltage	V_R	max. 50	100	150	200 V
Average forward current	$I_F(AV)$	max.	3,5	A	
Non-repetitive peak reverse energy	E_{RSM}	max.	40	mJ	
Reverse recovery time	t_{rr}	<	30	ns	

MECHANICAL DATA

Dimensions in mm

Fig. 1 SOD-64.



The marking band indicates the cathode.

The diodes are type-branded.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

		BYV28-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Continuous reverse voltage	V_R	max. 50	100	150	200	V
Average forward current (averaged over any 20 ms period)						
$T_{tp} = 85\text{ }^\circ\text{C}$; lead length = 10 mm	$I_{F(AV)}$	max.		3,5		A
$T_{amb} = 60\text{ }^\circ\text{C}$; p.c.b. mounting (see Fig. 2)	$I_{F(AV)}$	max.		1,9		A
Repetitive peak forward current	I_{FRM}	max.		25		A
Non-repetitive peak forward current (t = 10 ms; half sine-wave) $T_j = T_j \text{ max}$ prior to surge; with reapplied V_{RRM}	I_{FSM}	max.		90		A
Non-repetitive peak reverse avalanche energy; $I_R = 600\text{ mA}$; with inductive load switched off						
$T_j = 25\text{ }^\circ\text{C}$, prior to surge	E_{RSM}	max.		40		mJ
$T_j = T_j \text{ max}$, prior to surge	E_{RSM}	max.		20		mJ
Storage temperature	T_{stg}			-65 to +175		$^\circ\text{C}$
Junction temperature	T_j	max.		175		$^\circ\text{C}$

THERMAL RESISTANCE

Influence of mounting method

1. Thermal resistance from junction to tie-point at a lead length of 10 mm
 $R_{th\ j-tp} = 25\text{ K/W}$
2. Thermal resistance from junction to ambient when mounted on a 1,5 mm thick epoxy-glass printed-circuit board; Cu-thickness $\geq 40\text{ }\mu\text{m}$; Fig. 2
 $R_{th\ j-a} = 75\text{ K/W}$

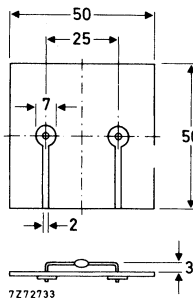


Fig. 2 Mounted on a printed-circuit board.

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$, unless otherwise specified

Reverse avalanche breakdown voltage

$I_R = 0,1\text{ mA}$

		BYV28-50	100	150	200
$V_{(BR)R}$	>	55	110	165	220 V

Forward voltage*

$I_F = 5\text{ A}$;

$I_F = 5\text{ A}; T_j = T_{j\text{ max}}$

V_F	<		1,10		V
V_F	<		0,89		V

Reverse current

$V_R = V_{RRM\text{ max}}$

$V_R = V_{RRM\text{ max}}; T_j = 165\text{ }^\circ\text{C}$

I_R	<		1		μA
I_R	<		150		μA

Reverse recovery time when switched from

$I_F = 0,5\text{ A}$ to $I_R = 1\text{ A}$; measured at

$I_R = 0,25\text{ A}$ for definition see

Figs 3 and 4

t_{rr}	<		30		ns
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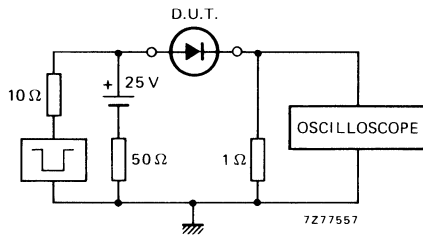


Fig. 3 Test circuit.

Input impedance oscilloscope 1 M Ω ; 22 pF; Rise time $\leq 7\text{ ns}$.
Source impedance 50 Ω . Rise time $\leq 15\text{ ns}$.

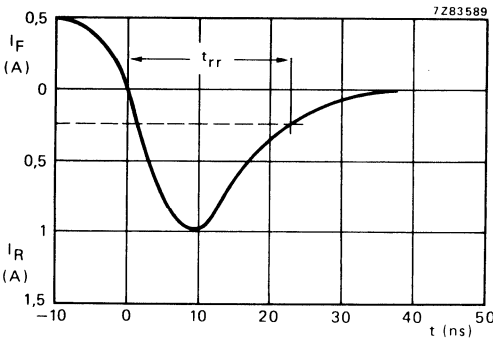


Fig. 4 Reverse recovery time characteristic.

* Measured under pulse conditions to avoid excessive dissipation.

Reverse recovery when switched from
 $I_F = 1 \text{ A}$ to $V_R \geq 30 \text{ V}$ with
 $-dI_F/dt = 20 \text{ A}/\mu\text{s}$ (see Fig. 5)
 recovered charge
 recovery time

$Q_s < 20 \text{ nC}$
 $t_{rr} < 50 \text{ ns}$

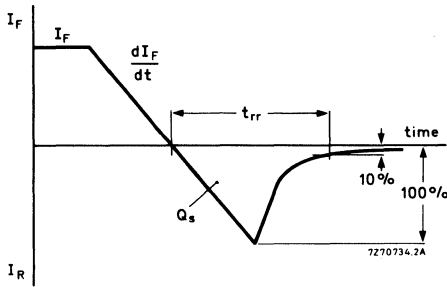


Fig. 5 Definitions of t_{rr} and Q_s .

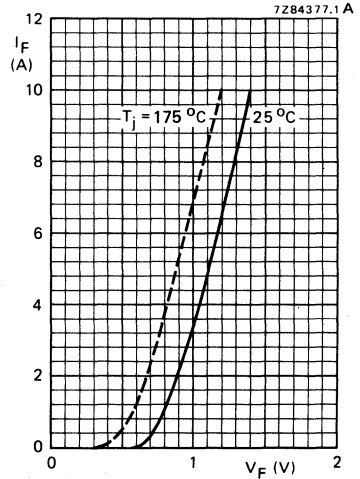


Fig. 6 Maximum forward voltage.

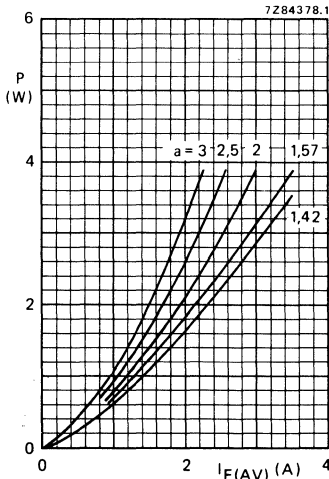


Fig. 7 Power dissipation (forward plus leakage current) as a function of the average forward current. Pulsed reverse voltage; $\delta = 50\%$.
 $a = I_{F(RMS)}/I_{F(AV)}$; $V_R = V_{RRMmax}$.

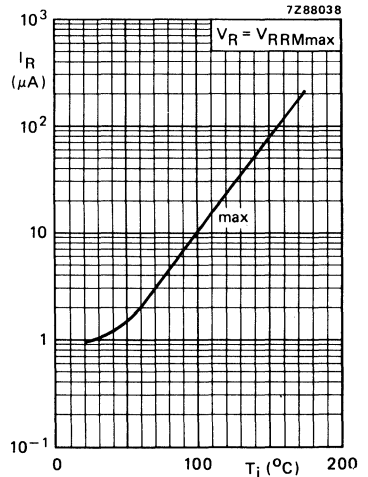


Fig. 8 Reverse current as a function of the junction temperature

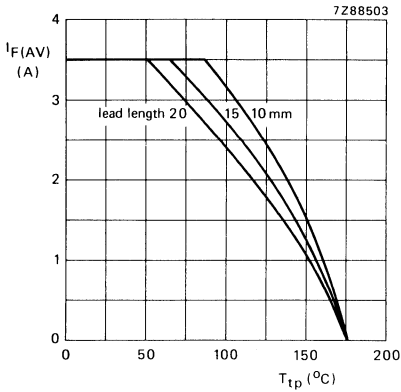


Fig. 9 Maximum average forward current. The curves include losses due to reverse current and switching up to $f = 200$ kHz. Pulsed reverse voltage; $\delta = 0,5$ $V_R = V_{RRM}$ max. Square-wave current; $a = 1,42$.

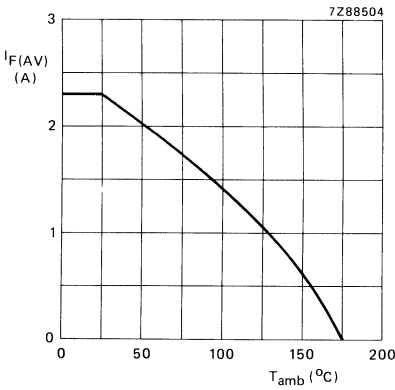


Fig. 10 Maximum average forward current. The curve includes losses due to reverse current and switching up to $f = 200$ kHz; mounting method see Fig. 2. Pulsed reverse voltage; $\delta = 0,5$ $V_R = V_{RRM}$ max. Square-wave current; $a = 1,42$.

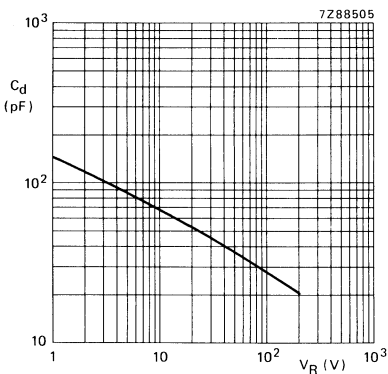


Fig. 11 Typical values diode capacitance at $f = 1$ MHz. $T_j = 25$ °C.

ULTRA FAST RECOVERY RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and switching losses are essential.

The series consists of normal polarity (cathode to mounting base) types.

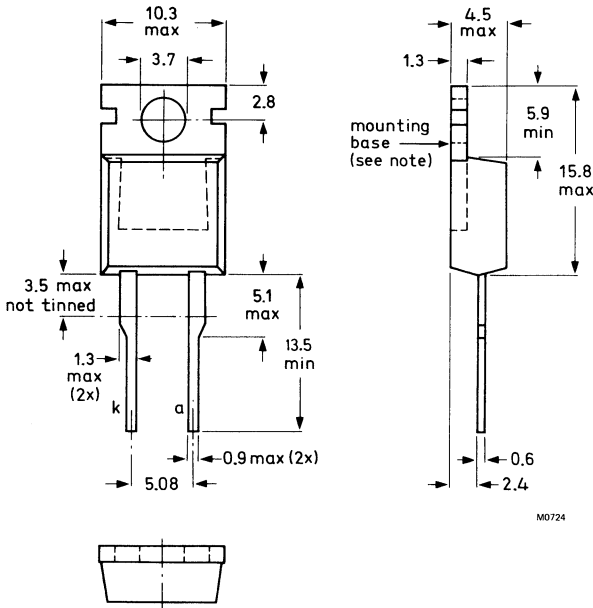
QUICK REFERENCE DATA

			BYV29-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V
Average forward current	$I_F(AV)$	max.		9		A
Forward voltage	V_F	<		1.05		V
Reverse recovery time	t_{rr}	<		50		ns

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AC



M0724

Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

BYV29 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

		BYV29-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max. 300	400	500	V
Crest working reverse voltage	V_{RWM}	max. 200	300	400	V
Continuous reverse voltage (note 1)	V_R	max. 200	300	400	V

→ Currents

Average forward current; switching losses negligible up to 200 kHz; square wave; $\delta = 0.5$; up to $T_{mb} = 116^\circ\text{C}$	$I_{F(AV)}$	max.	9	A
sinusoidal; up to $T_{mb} = 125^\circ\text{C}$	$I_{F(AV)}$	max.	7.4	A
R.M.S. forward current	$I_{F(RMS)}$	max.	13	A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.	200	A
Non-repetitive peak forward current half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max	I_{FSM}	max.	100	A
$t = 10 \text{ ms}$	I_{FSM}	max.	110	A
$t = 8.3 \text{ ms}$	$I^2 t$	max.	50	A^2s
$I^2 t$ for fusing ($t = 10 \text{ ms}$)				

Temperatures

Storage temperature	T_{stg}		-40 to +150	$^\circ\text{C}$
Junction temperature	T_j	max.	150	$^\circ\text{C}$

Notes:

1. To ensure thermal stability: $R_{th j-a} < 6.8 \text{ K/W}$.

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated

Forward voltage

$I_F = 5\text{ A}; T_j = 100\text{ }^\circ\text{C}$

$I_F = 20\text{ A}$

V_F	<	1.05	V*
V_F	<	1.4	V*

Reverse current

$V_R = V_{RWM\text{ max}}; T_j = 100\text{ }^\circ\text{C}$

$V_R = V_{RWM\text{ max}}$

I_R	<	0.35	mA
I_R	<	10	μA ←

Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$;
recovery time

t_{rr}	<	50	ns
----------	---	----	----

$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$;
recovered charge

Q_s	<	55	nC
-------	---	----	----

$I_F = 10\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$;
 $T_j = 100\text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	5.5	A ←
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Forward recovery when switched to $I_F = 10\text{ A}$
with $dI_F/dt = 10\text{ A}/\mu\text{s}$

V_{fr}	typ.	2.5	V
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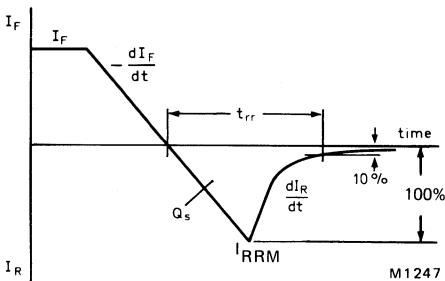


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

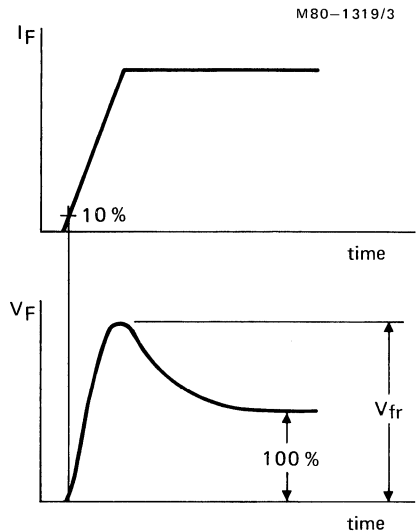


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 2.5 \text{ K/W}$$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275°C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm. ←
- Mounting by means of a spring clip is the best mounting method because it offers:
 - a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
- Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

- The various components of junction temperature rise above ambient are illustrated in Fig. 4.

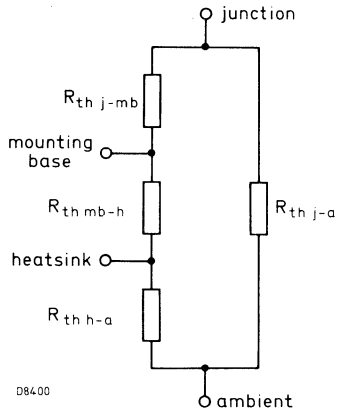


Fig. 4.

- Any measurement of heatsink temperature should be made immediately adjacent to the device.
- The method of using Figs. 5 and 6 is as follows:
Starting with the required current on the $I_F(AV)$ axis, trace upwards to meet the appropriate duty cycle or form factor curve. Trace right horizontally and upwards from the required value on the T_{amb} scale. The intersection determines the $R_{th\ mb-a}$. The heatsink thermal resistance value ($R_{th\ h-a}$) can be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

SQUARE-WAVE OPERATION

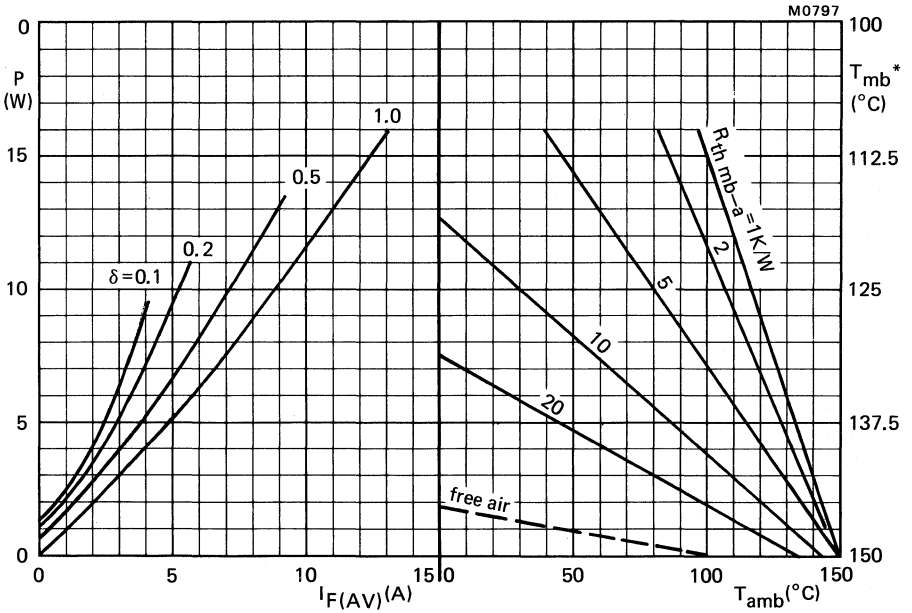
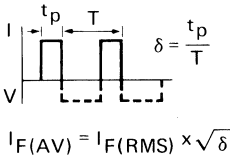


Fig.5 The right-hand part shows the relationship between the power (derived from the left-hand part) and the maximum permissible temperatures.



* T_{mb} scale is for comparison purposes and is correct only for $R_{th,mb-a} < 4.1 \text{ }^\circ\text{K/W}$.

SINUSOIDAL OPERATION

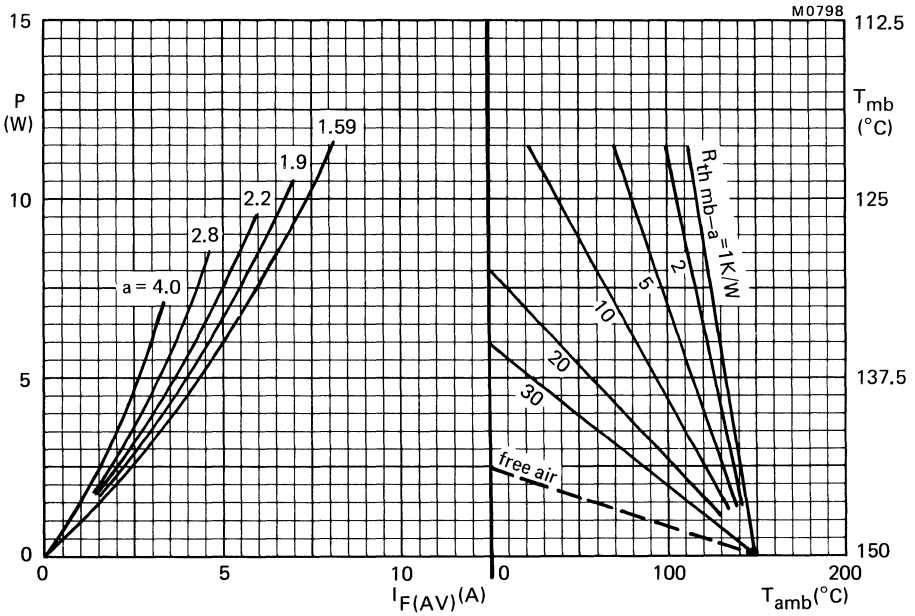


Fig.6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$a = \text{form factor} = I_F(RMS) / I_F(AV)$.

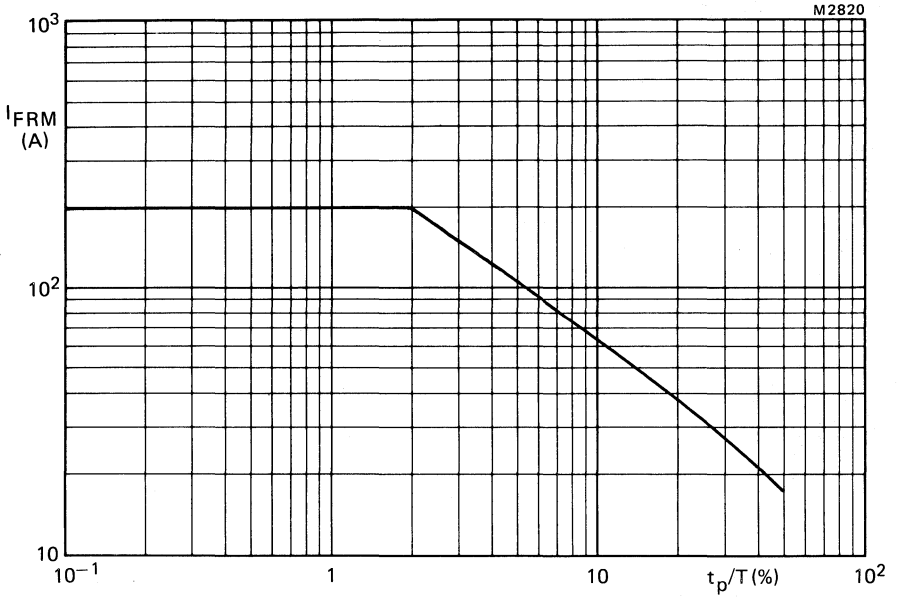
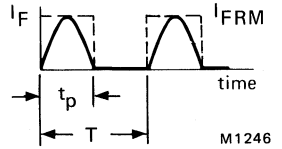
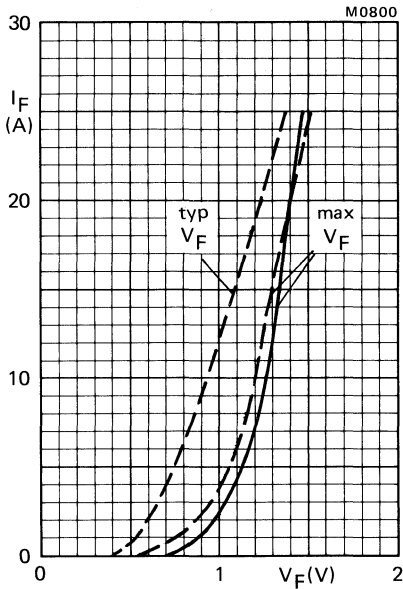


Fig.7 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 100 \text{ }^\circ\text{C}$.

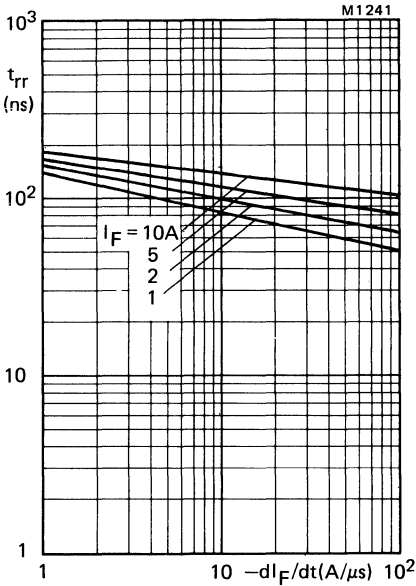


Fig.9 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

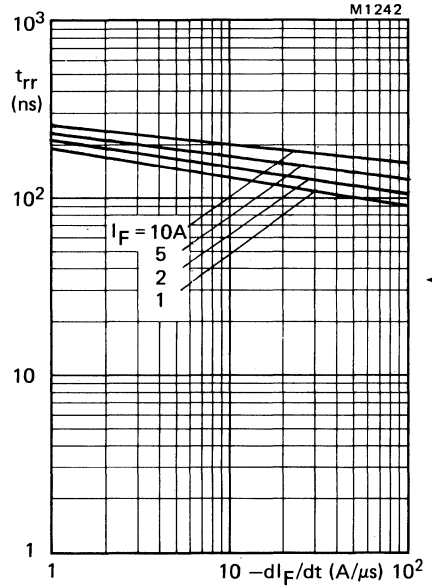


Fig.10 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

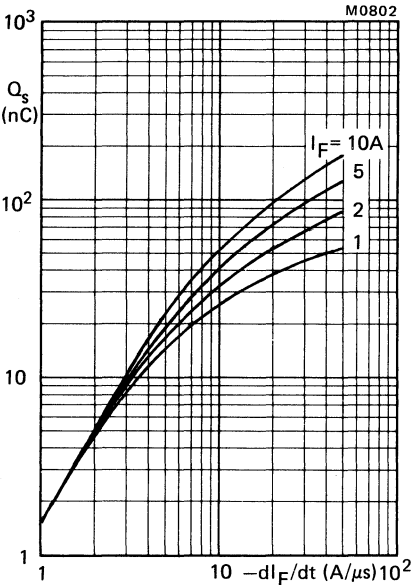


Fig.11 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

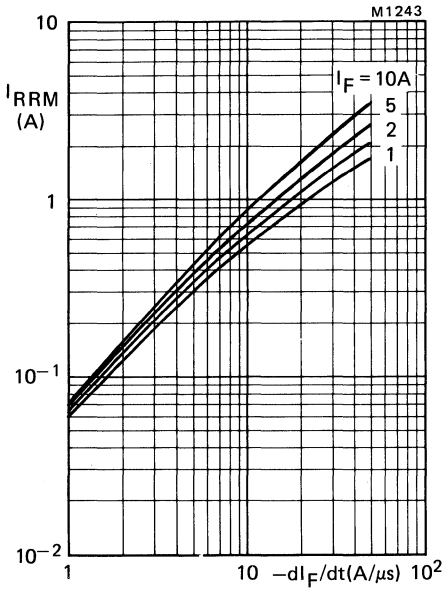


Fig.12 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

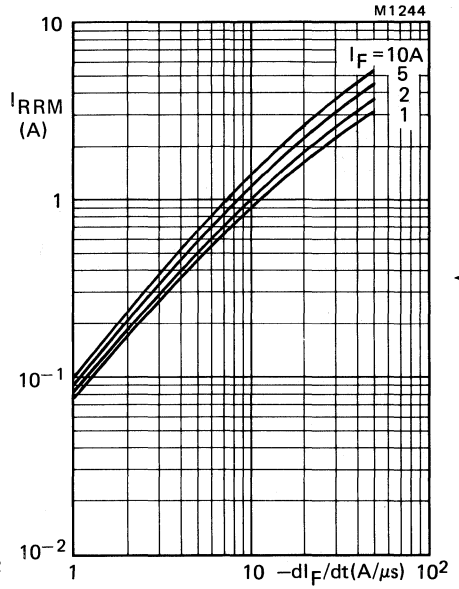


Fig.13 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

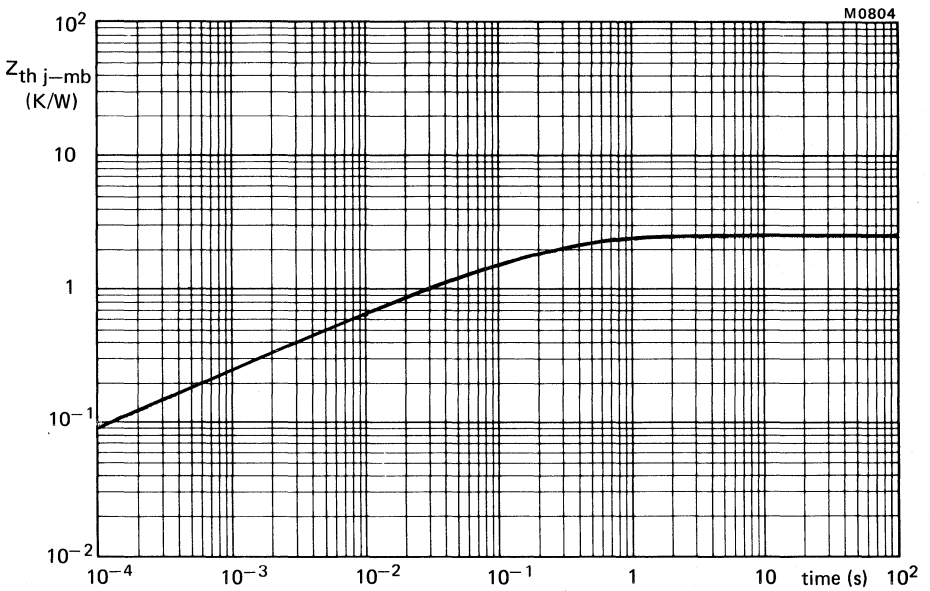


Fig.14 Transient thermal impedance.

ULTRA FAST RECOVERY ELECTRICALLY ISOLATED RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in full-pack envelopes, featuring low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. Their electrical isolation makes them ideal for mounting on a common heatsink alongside other components without the need for additional insulators. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential.

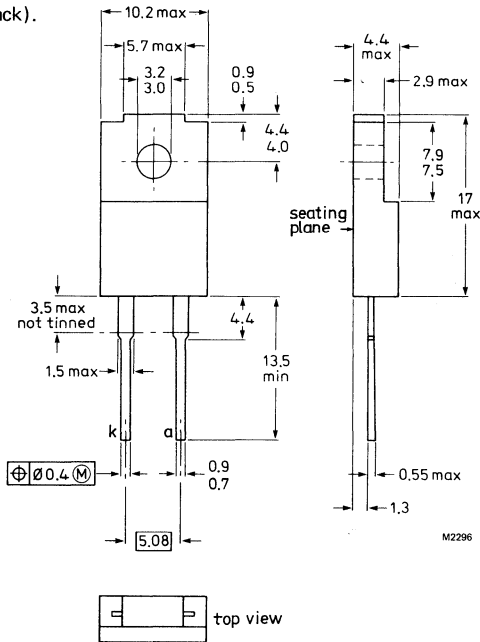
QUICK REFERENCE DATA

		BYV29F-300			400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V	
Average forward current	$I_F(AV)$	max.	9			A	
Forward voltage	V_F	<	1.05			V	
Reverse recovery time	t_{rr}	<	50			ns	

MECHANICAL DATA

Dimensions in mm

Fig.1 SOT-186 (full-pack).



Net mass: 2 g.

The seating plane is electrically isolated from all terminals.

Accessories supplied on request (see data sheets Mounting instructions for F-pack devices and Accessories for SOT-186 envelopes).

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

		BYV29F—	300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V
Crest working reverse voltage	V_{RWM}	max.	200	300	400	V
Continuous reverse voltage (note 1)	V_R	max.	200	300	400	V

Currents

Average forward current; switching losses negligible up to 200 kHz (note 2); square wave; $\delta = 0.5$; up to $T_{mb} = 76^\circ\text{C}$ sinusoidal; up to $T_{mb} = 87^\circ\text{C}$	$I_{F(AV)}$	max.		9	A
	$I_{F(AV)}$	max.		8	A
	$I_{F(RMS)}$	max.		13	A
R.M.S. forward current	$I_{F(RMS)}$	max.		13	A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.		200	A
Non-repetitive peak forward current half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max $t = 10 \text{ ms}$ $t = 8.3 \text{ ms}$	I_{FSM}	max.		100	A
	I_{FSM}	max.		110	A
	$I^2 t$	max.		50	A^2s

Temperatures

Storage temperature	T_{stg}			-40 to +150	$^\circ\text{C}$
Junction temperature	T_j	max.		150	$^\circ\text{C}$

ISOLATION

Peak isolation voltage from all terminals to external heatsink	V_{isol}	max.		1000	V
Isolation capacitance from cathode to external heatsink (note 3)	C_p	typ.		12	μF

Notes:

1. To ensure thermal stability: $R_{th j-a} < 6.8 \text{ K/W}$.
2. The quoted temperatures assume heatsink compound is used.
3. Mounted without heatsink compound and 20 Newtons pressure on the centre of the envelope.

THERMAL RESISTANCE

From junction to external heatsink with minimum of 2 kgf (20 Newtons) pressure on the centre of the envelope,
 with heatsink compound
 without heatsink compound

$R_{th\ j-h}$	=	5.5	K/W
$R_{th\ j-h}$	=	7.2	K/W

Free-air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same point.

Thermal resistance from junction to ambient in free air, mounted on a printed circuit board

$R_{th\ j-a}$	=	55	K/W
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CHARACTERISTICS

Forward voltage

$I_F = 5\text{ A}; T_j = 100\text{ }^\circ\text{C}$
 $I_F = 20\text{ A}; T_j = 25\text{ }^\circ\text{C}$

V_F	<	1.05	V*
V_F	<	1.4	V*

Reverse current

$V_R = V_{RWM\ max}; T_j = 100\text{ }^\circ\text{C}$
 $V_R = V_{RWM\ max}; T_j = 25\text{ }^\circ\text{C}$

I_R	<	0.35	mA
I_R	<	10	μA

Reverse recovery when switched from

$I_F = 1\text{ A to } V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$;
 $T_j = 25\text{ }^\circ\text{C}$; recovery time

t_{rr}	<	50	ns
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$I_F = 2\text{ A to } V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$;
 $T_j = 25\text{ }^\circ\text{C}$; recovered charge

Q_s	<	55	nC
-------	---	----	----

$I_F = 10\text{ A to } V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$;
 $T_j = 100\text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	5.5	A
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Forward recovery when switched to $I_F = 10\text{ A}$
 with $dI_F/dt = 10\text{ A}/\mu\text{s}$; $T_j = 25\text{ }^\circ\text{C}$

V_{fr}	typ.	2.5	V
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M80-1319/3

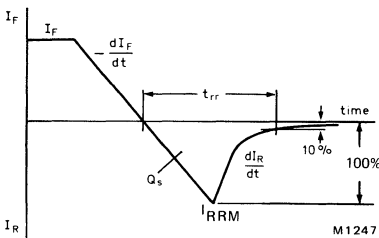


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

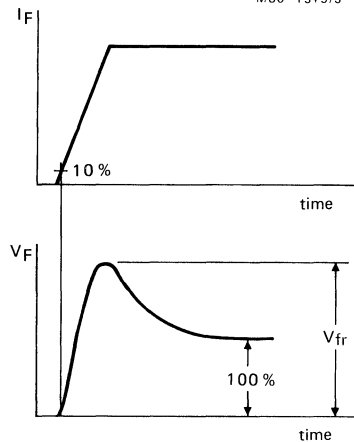


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers a good thermal contact under the crystal area and slightly lower $R_{th\ j-h}$ values than screw mounting. The force exerted on the top of the device by the clip should be at least 2 kgf (20 Newtons) to ensure good thermal contact and must not exceed 3.5 kgf (35 Newtons) to avoid damage to the device.
4. If screw mounting is used, it should be M3 cross-recess pan head.
 Minimum torque to ensure good thermal contact: 5.5 kgf (0.55 Nm)
 Maximum torque to avoid damage to the device: 8.0 kgf (0.80 Nm)
5. For good thermal contact, heatsink compound should be used between baseplate and heatsink. Values of $R_{th\ j-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting.
 It is not recommended to use rivets, since extensive damage could result to the plastic, which could destroy the insulating properties of the device.
7. The heatsink must have a flatness in the mounting area of 0.02 mm maximum per 10 mm. Mounting holes must be deburred.

OPERATING NOTES

The various components of junction temperature rise above ambient are illustrated in Fig.4.

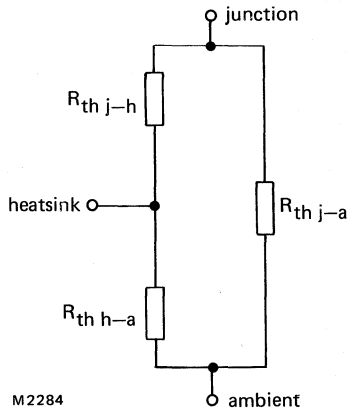


Fig.4.

Any measurement of heatsink temperature should be immediately adjacent to the device.

SQUARE-WAVE OPERATION

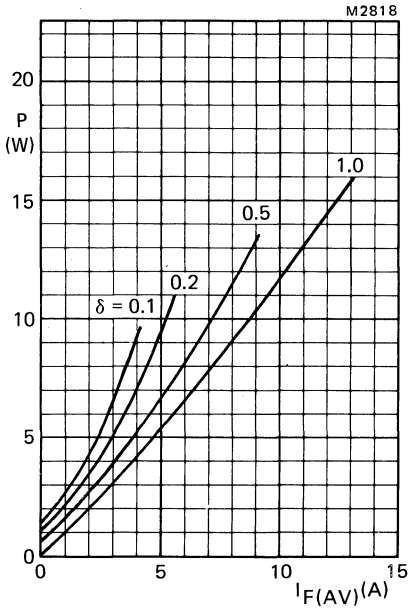
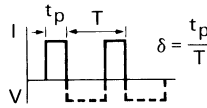


Fig.5 Power rating.

The power loss in the diode should first be determined from the required forward current on the $I_{F(AV)}$ axis and the appropriate duty cycle.

Having determined the power (P), use Fig.7 (if heatsink compound is not being used) or Fig.8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

SINUSOIDAL OPERATION

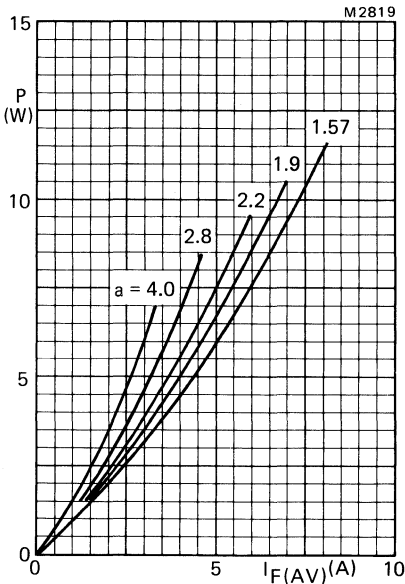


Fig.6 Power rating.

The power loss in the diode should first be determined from the required forward current on the $I_{F(AV)}$ axis and the appropriate form factor.

Having determined the power (P), use Fig.7 (if heatsink compound is not being used) or Fig.8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$

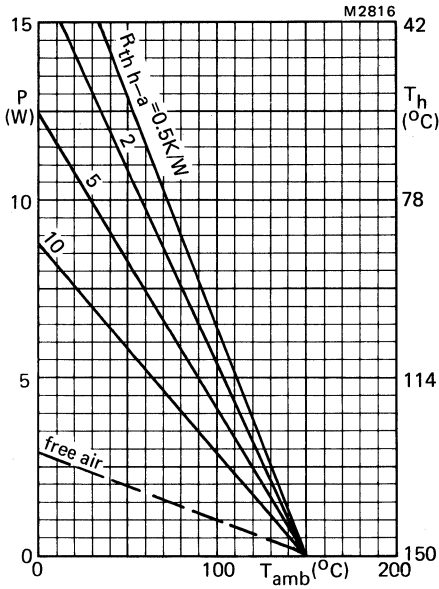


Fig.7 Heatsink rating; without heatsink compound.

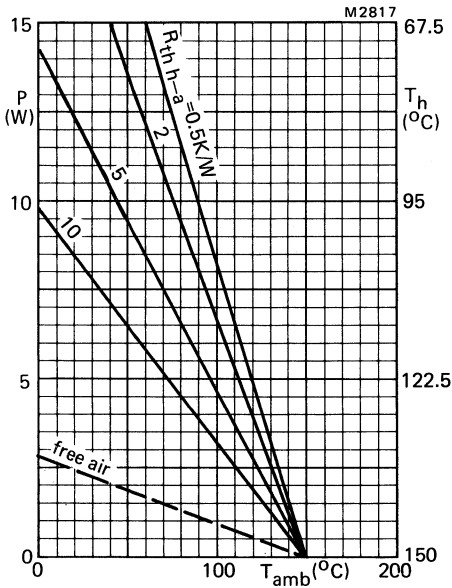


Fig.8 Heatsink rating; with heatsink compound.

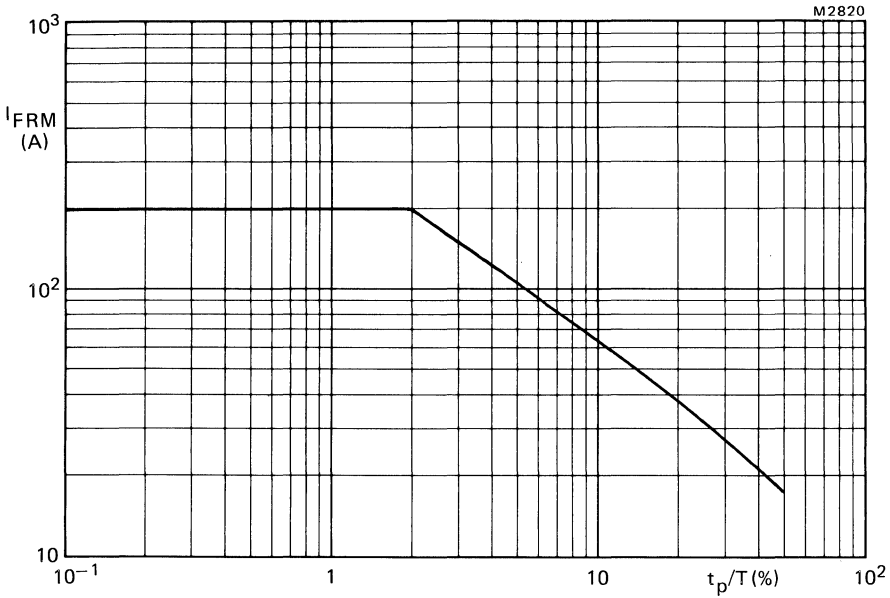


Fig.9 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu\text{s} < t_p < 1 \text{ ms}$.

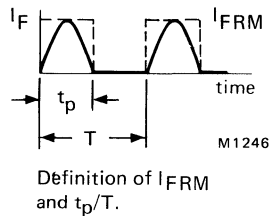
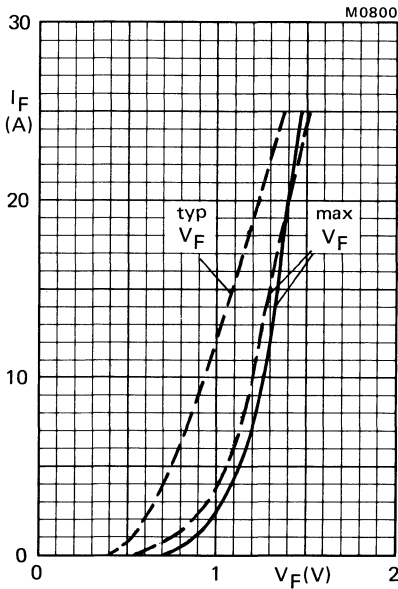


Fig.10 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 100 \text{ }^\circ\text{C}$.

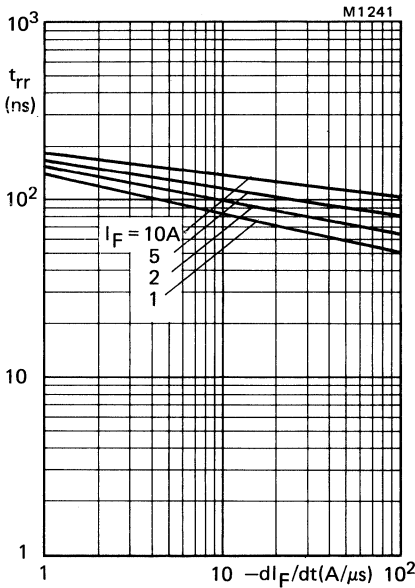


Fig.11 Maximum t_{rr} at $T_j = 25$ °C.

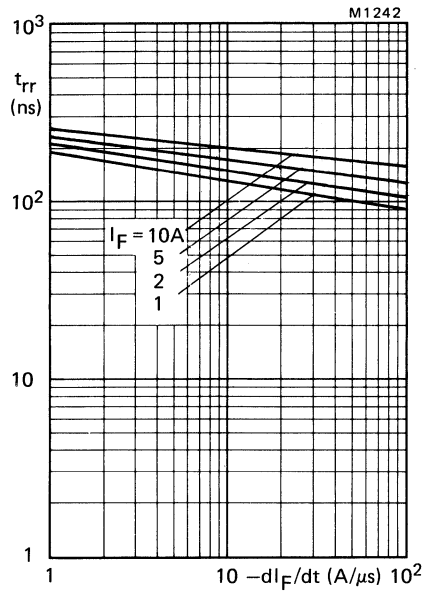


Fig.12 Maximum t_{rr} at $T_j = 100$ °C.

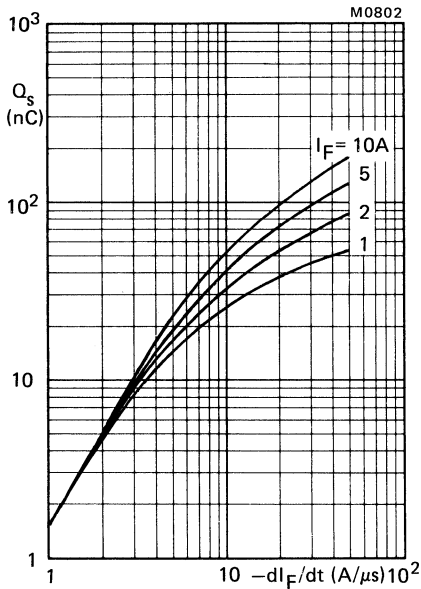


Fig.13 Maximum Q_s at $T_j = 25$ °C.

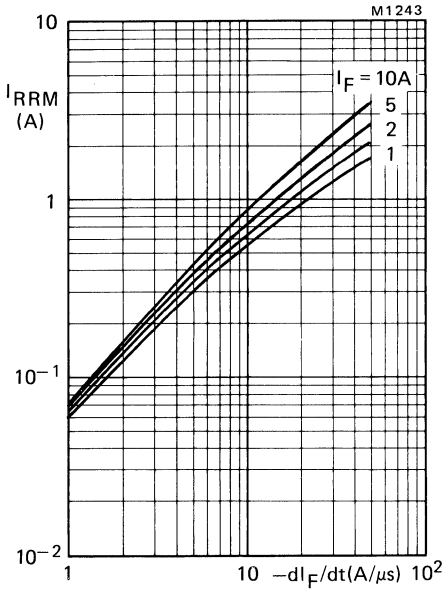


Fig.14 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

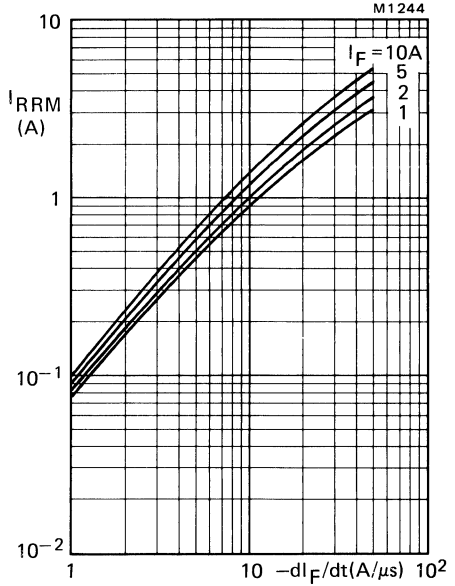


Fig.15 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

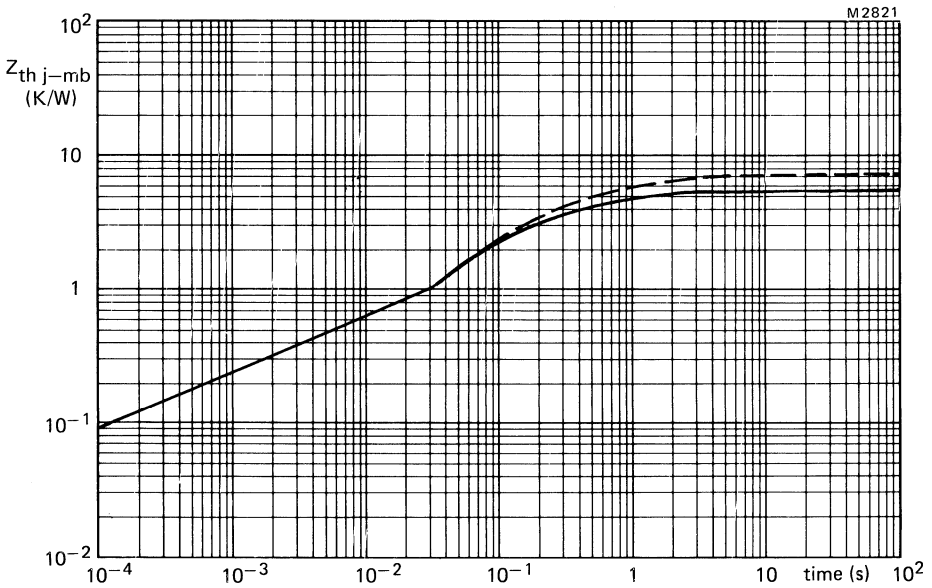


Fig.16 Transient thermal impedance; — with heatsink compound; - - - without heatsink compound.

ULTRA FAST RECOVERY RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, ultra fast reverse recovery times, very low stored charge and soft recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode to stud) types.

QUICK REFERENCE DATA

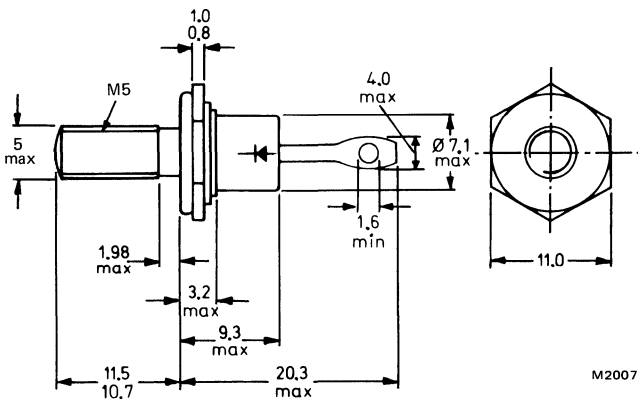
			BYV30-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V
Average forward current	$I_F(AV)$	max.	14			A
Forward voltage	V_F	<	1.05			V
Reverse recovery time	t_{rr}	<	50			ns

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4 with metric (M5) stud as standard.

10-32 UNF is available upon request with suffix U (e.g. BYV30-400U).



Net mass: 6 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request: see data sheets

Mounting instructions and Accessories for DO-4 envelopes.

Supplied with device: 1 nut, 1 lock washer.

Nut dimensions across the flats: 9.5 mm

Torque on nut:

min. 0.9 Nm (9 kg cm)

max. 1.7 Nm (17 kg cm)

BYV30 SERIES

→ RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

			BYV30-300	400	500	V
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V
Crest working reverse voltage	V_{RWM}	max.	200	300	400	V
Continuous reverse voltage*	V_R	max.	200	300	400	V

Currents

Average forward current; switching losses negligible up to 100 kHz

square wave; $\delta = 0.5$; up to $T_{mb} = 113^\circ\text{C}$	$I_F(\text{AV})$	max.		14	A
up to $T_{mb} = 125^\circ\text{C}$	$I_F(\text{AV})$	max.		10	A

sinusoidal; up to $T_{mb} = 118^\circ\text{C}$	$I_F(\text{AV})$	max.		12.5	A
up to $T_{mb} = 125^\circ\text{C}$	$I_F(\text{AV})$	max.		10	A

R.M.S. forward current	$I_F(\text{RMS})$	max.		20	A
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Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.		320	A
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Non-repetitive peak forward current

half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge;

with reapplied V_{RWMmax} ;

$t = 10 \text{ ms}$	I_{FSM}	max.		150	A
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$t = 8.3 \text{ ms}$	I_{FSM}	max.		180	A
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$I^2 t$ for fusing ($t = 10 \text{ ms}$)	$I^2 t$	max.		112	A^2s
--	---------	------	--	-----	----------------------

Temperatures

Storage temperature	T_{stg}		-65 to +175	$^\circ\text{C}$
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Junction temperature	T_j	max.	150	$^\circ\text{C}$
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→ THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	2.0	K/W
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From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0.3	K/W
---	---------------	---	-----	-----

From junction to ambient in free air	$R_{th j-a}$	=	50	K/W
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*To ensure thermal stability: $R_{th j-a} \leq 4.6 \text{ K/W}$.

CHARACTERISTICS

Forward voltage

$I_F = 15 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$
 $I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

V_F	<	1.05	V*
V_F	<	1.40	V*

Reverse current

$V_R = V_{RWM} \text{ max}; T_j = 100 \text{ }^\circ\text{C}$
 $T_j = 25 \text{ }^\circ\text{C}$

I_R	<	0.8	mA
I_R	<	50	μA

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovery time

t_{rr}	<	50	ns
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$I_F = 2 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 20 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovered charge

Q_s	<	50	nC
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$I_F = 10 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 50 \text{ A}/\mu\text{s}$;
 $T_j = 100 \text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	5.2	A
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Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}$; $T_j = 25 \text{ }^\circ\text{C}$

V_{fr}	typ.	2.5	V
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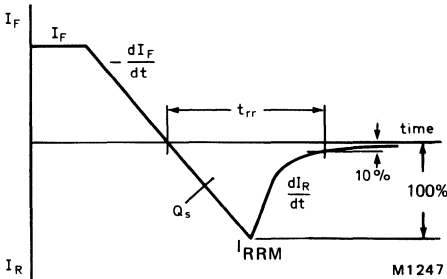


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

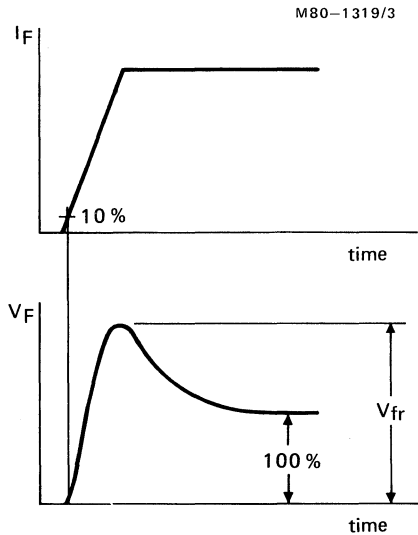


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

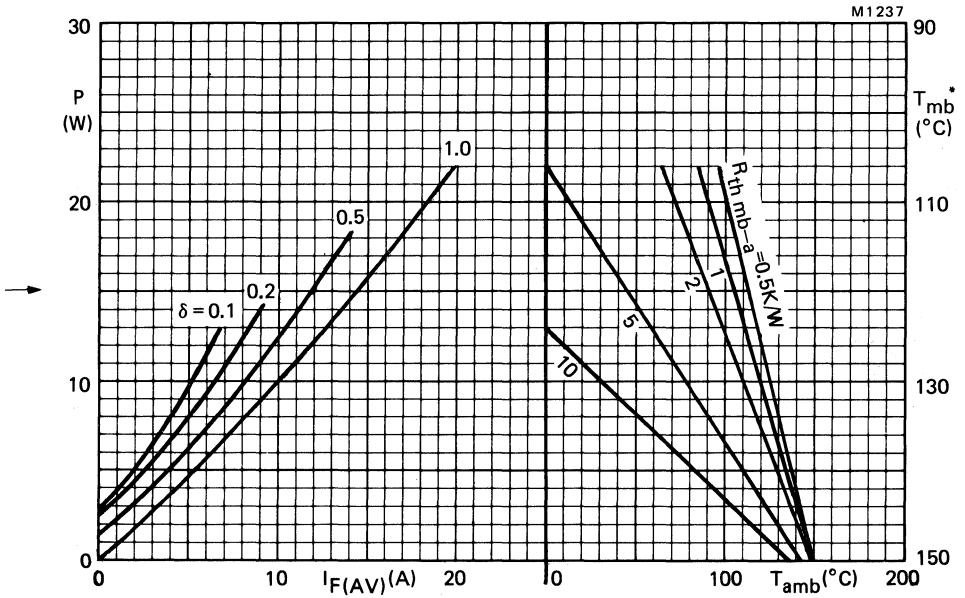
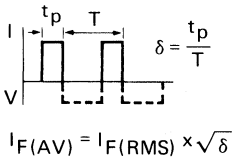


Fig.4 The right-hand part shows the relationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 100$ kHz.



* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 4.1$ K/W.

SINUSOIDAL OPERATION

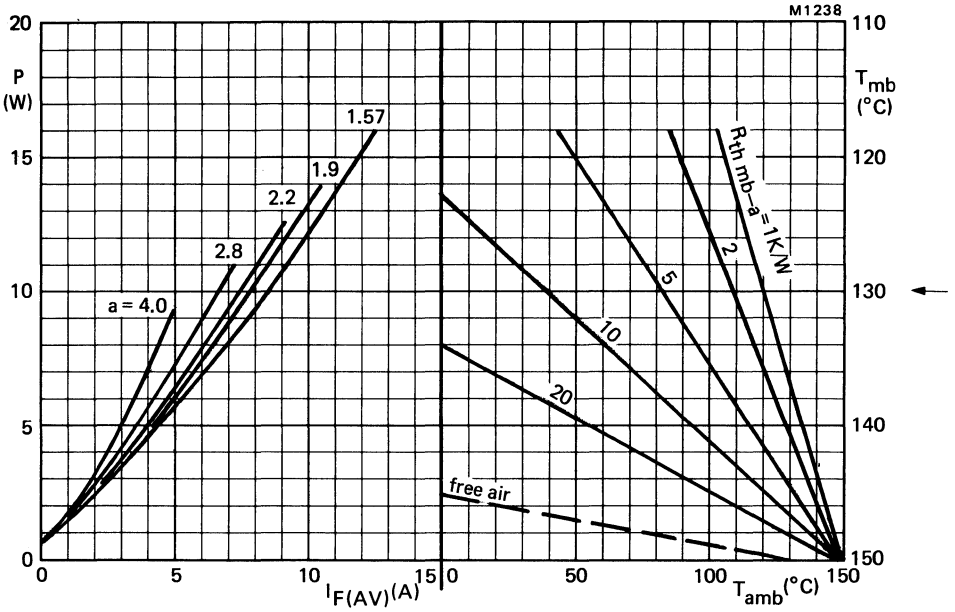


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$.

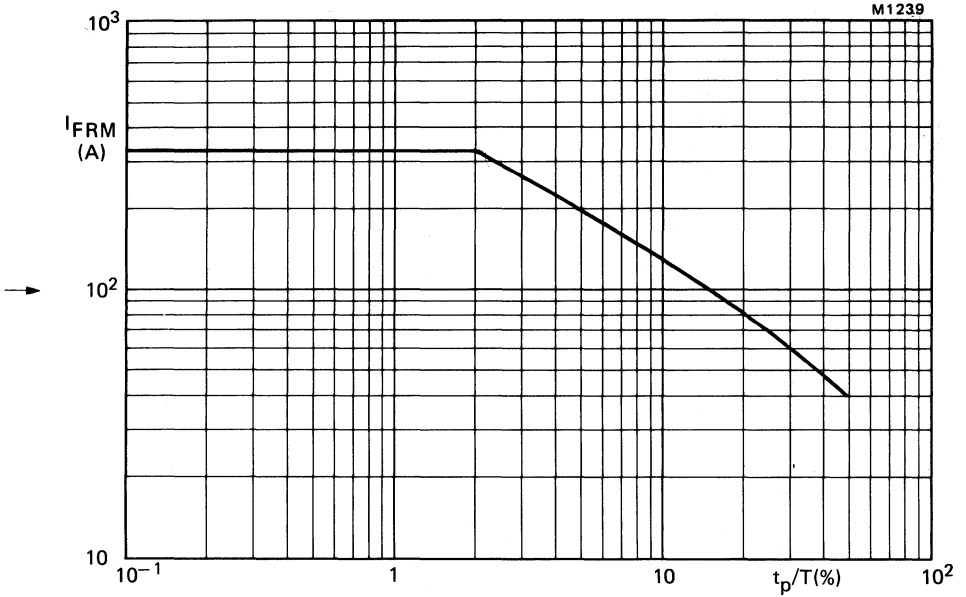
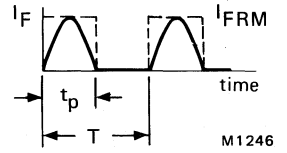
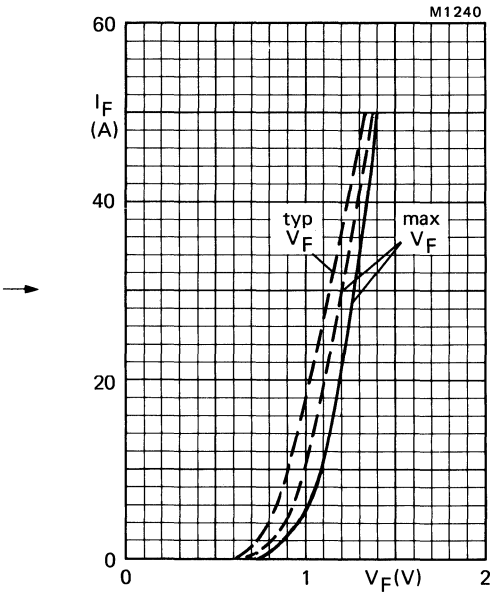


Fig.6 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.7 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$.

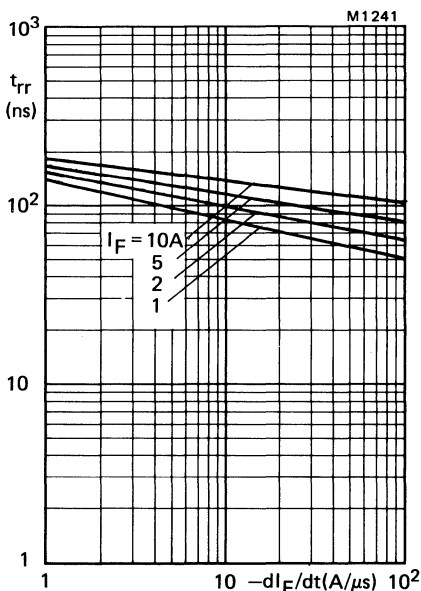


Fig.8 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$

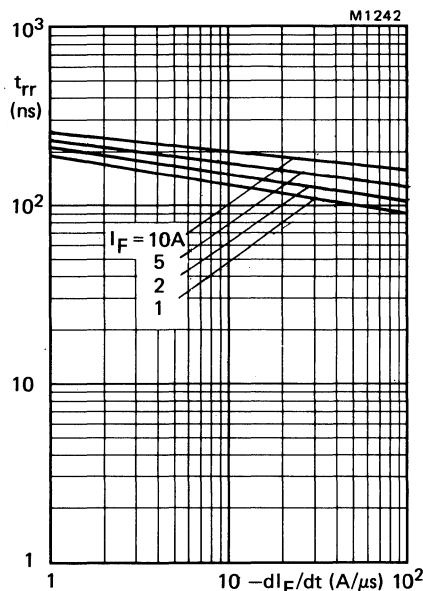


Fig.9 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

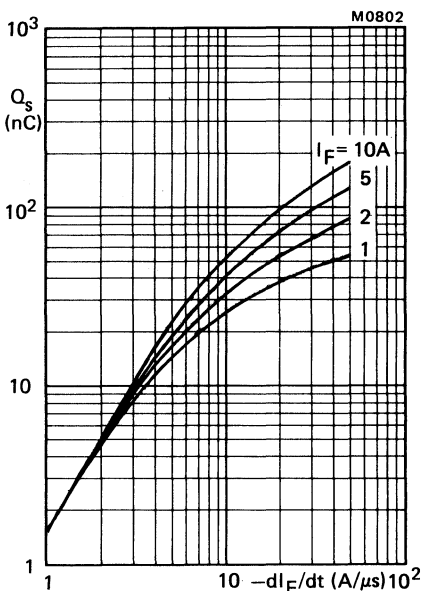


Fig.10 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$

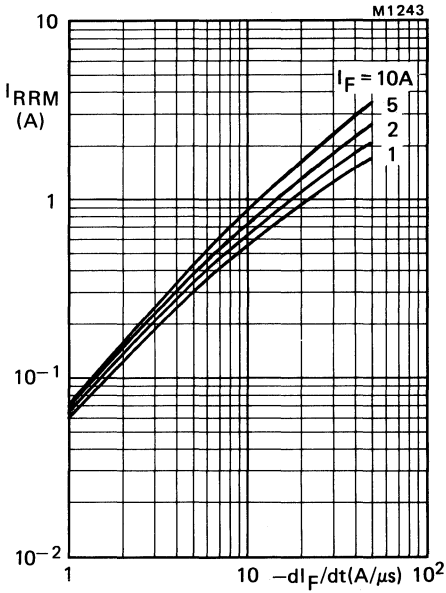


Fig.11 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$

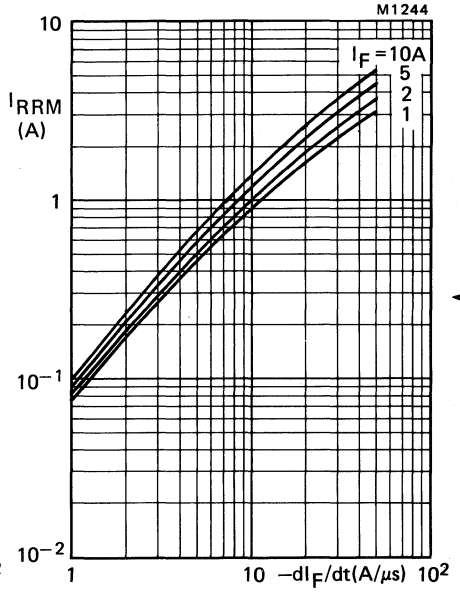


Fig.12 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

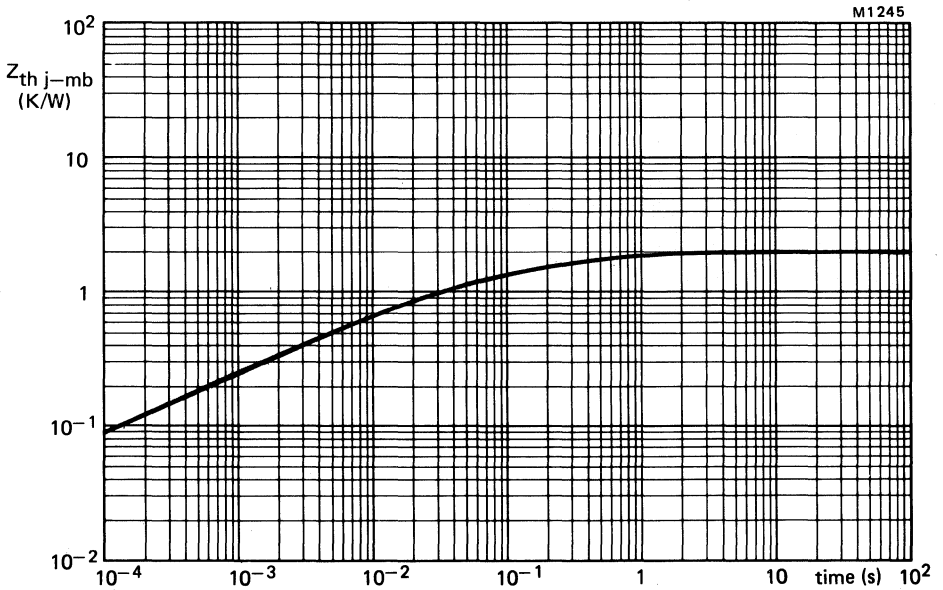


Fig.13 Transient thermal impedance.

ULTRA FAST RECOVERY RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, ultra fast reverse recovery times, very low stored charge and soft recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction and switching losses are essential. The series consists of normal polarity (cathode to stud) types.

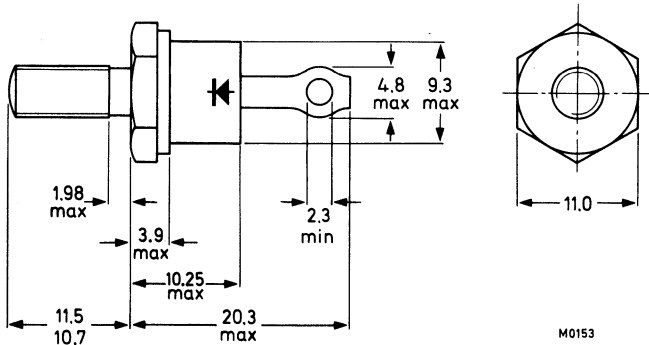
QUICK REFERENCE DATA

			BYV31-300			400	500		
			300	400	500				
Repetitive peak reverse voltage	V_{RRM}	max						V	
Average forward current	$I_F(AV)$	max.				28		A	
Forward voltage	V_F	<				1.05		V	
Reverse recovery time	t_{rr}	<				50		ns	

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4; with metric M5 stud ($\phi 5$ mm); e.g. BYV31-500
with 10-32 UNF stud ($\phi 4.83$ mm); e.g. BYV31-500U



Net mass: 7 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:

mica washer (56295a);

PTFE ring (56295b); insulating bush (56295c).

Supplied with device: 1 nut, 1 lock washer

Torque on nut: min. 0.9 Nm (9 kg cm)

max. 1.7 Nm (17 kg cm)

Nut dimensions across the flats;

M5: 8.0 mm, 10-32 UNF: 9.5 mm

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages			BYV31-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V
Crest working reverse voltage	V_{RWM}	max.	200	300	400	V
Continuous reverse voltage*	V_R	max.	200	300	400	V
Currents						
Average forward current, switching losses negligible up to 100 kHz						
square wave; $\delta = 0.5$; up to $T_{mb} = 114\text{ }^\circ\text{C}$			$I_F(AV)$	max.	28	A
up to $T_{mb} = 125\text{ }^\circ\text{C}$			$I_F(AV)$	max.	20	A
sinusoidal; up to $T_{mb} = 119\text{ }^\circ\text{C}$			$I_F(AV)$	max.	25	A
up to $T_{mb} = 125\text{ }^\circ\text{C}$			$I_F(AV)$	max.	21	A
R.M.S. forward current			$I_F(RMS)$	max.	40	A
Repetitive peak forward current						
$t_p = 20\text{ }\mu\text{s}$; $\delta = 0.02$			I_{FRM}	max.	550	A
Non-repetitive peak forward current						
half sine-wave; $T_j = 150\text{ }^\circ\text{C}$ prior to surge;						
with reapplied V_{RWMmax} ;						
$t = 10\text{ ms}$			I_{FSM}	max.	300	A
$t = 8.3\text{ ms}$			I_{FSM}	max.	360	A
$I^2 t$ for fusing ($t = 10\text{ ms}$)			$I^2 t$	max.	450	A^2s
Temperatures						
Storage temperature			T_{stg}	-55 to +150		$^\circ\text{C}$
Junction temperature			T_j	max. 150		$^\circ\text{C}$
THERMAL RESISTANCE						
From junction to mounting base			$R_{th\ j-mb}$	=	1.0	K/W
From mounting base to heatsink						
a. with heatsink compound			$R_{th\ mb-h}$	=	0.3	K/W
b. without heatsink compound			$R_{th\ mb-h}$	=	0.5	K/W

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

*To ensure thermal stability: $R_{th\ j-a} \leq 3.4\text{ K/W}$.

CHARACTERISTICS

Forward voltage

$I_F = 30 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$
 $I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

V_F	<	1.05	V*
V_F	<	1.4	V*

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$
 $T_j = 25 \text{ }^\circ\text{C}$

I_R	<	2.0	mA
I_R	<	50	μA

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovery time

t_{rr}	<	50	ns
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$I_F = 2 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 20 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovered charge

Q_s	<	75	nC
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$I_F = 10 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 50 \text{ A}/\mu\text{s}$;
 $T_j = 100 \text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	4	A
-----------	---	---	---

Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}$; $T_j = 25 \text{ }^\circ\text{C}$

V_{fr}	typ.	2.5	V
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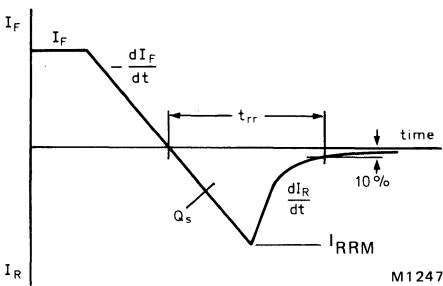


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

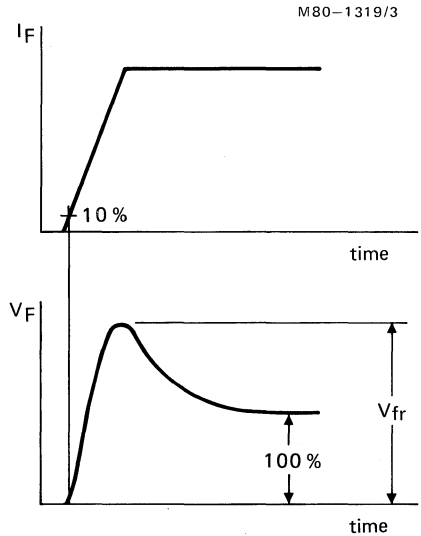


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

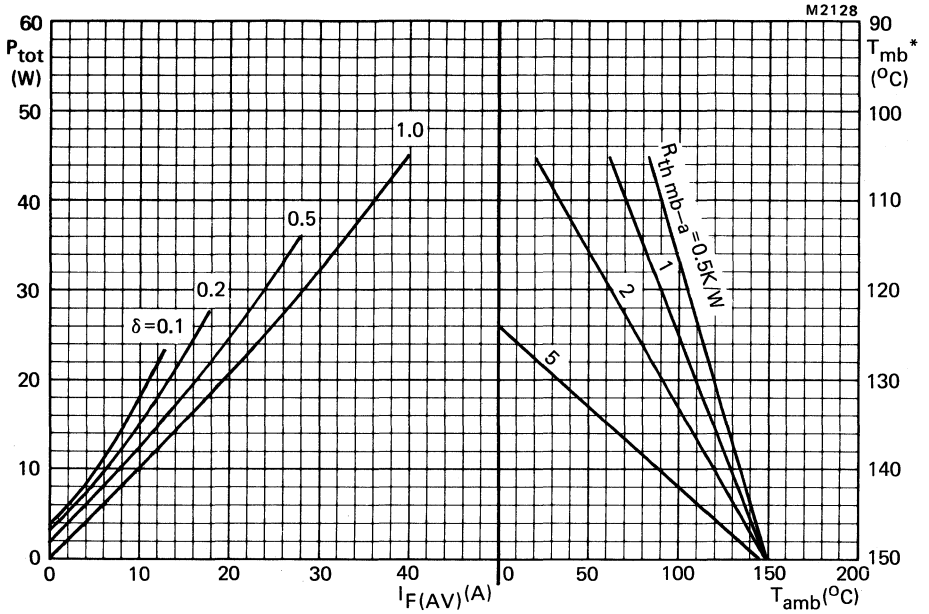
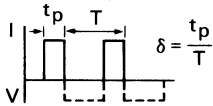


Fig.4 The right-hand part shows the relationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 100$ kHz.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

* T_{mb} scale is for comparison purposes and is correct only for $R_{th mb-a} < 2.4$ K/W.

SINUSOIDAL OPERATION

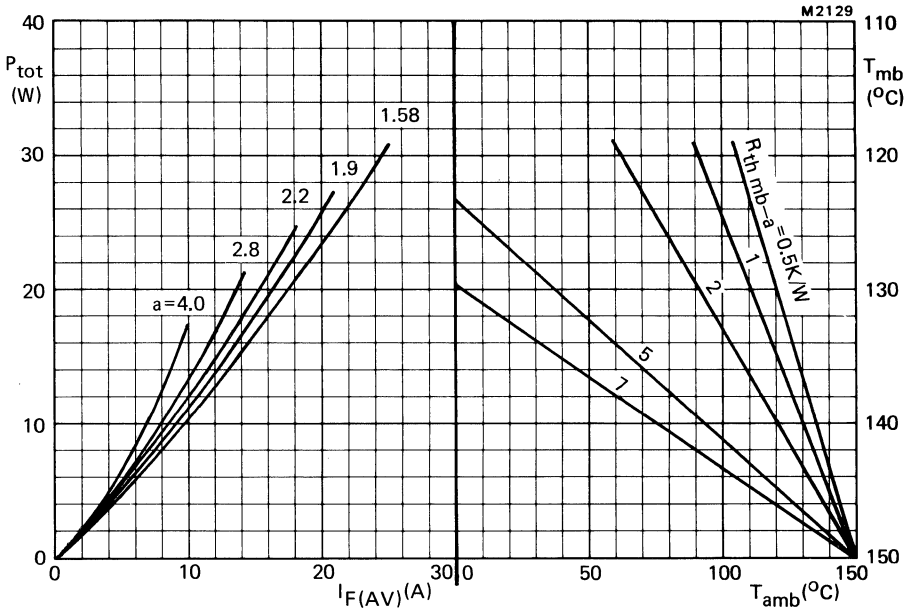


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

a = form factor = $I_F(RMS)/I_F(AV)$.

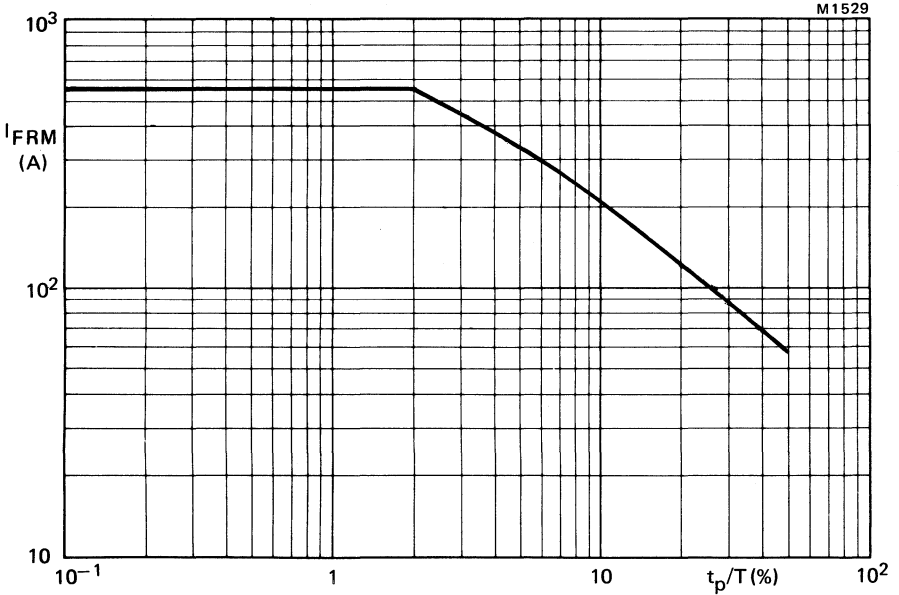


Fig.6 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 ms$.

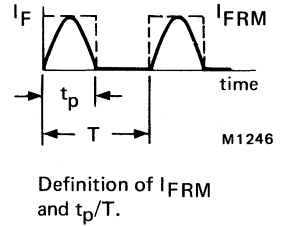
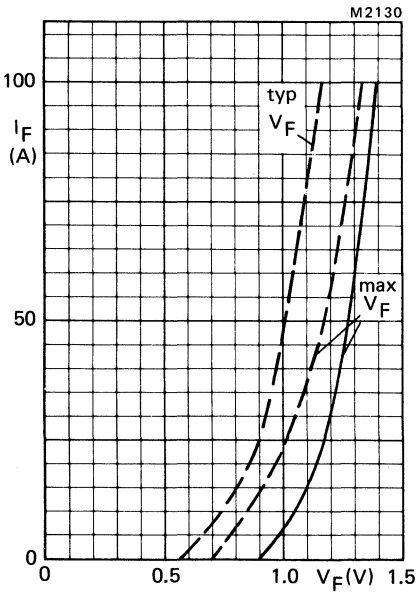


Fig.7 — $T_j = 25^\circ C$; --- $T_j = 150^\circ C$.

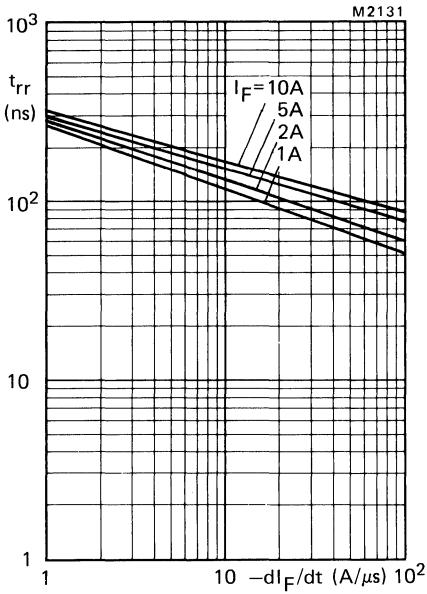


Fig.8 Maximum t_{rr} at $T_j = 25$ °C.

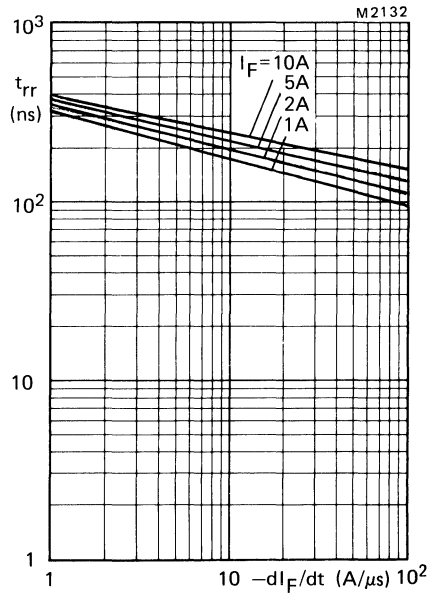


Fig.9 Maximum t_{rr} at $T_j = 100$ °C.

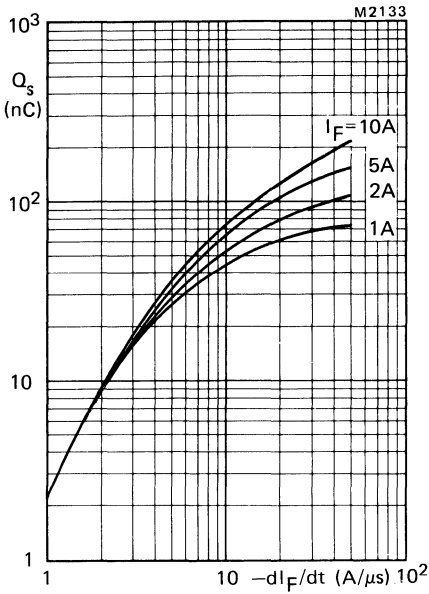


Fig.10 Maximum Q_s at $T_j = 25$ °C

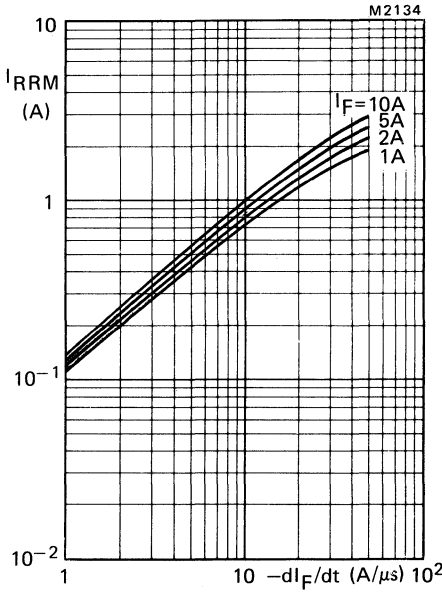


Fig.11 Maximum I_{RRM} at $T_j = 25$ °C

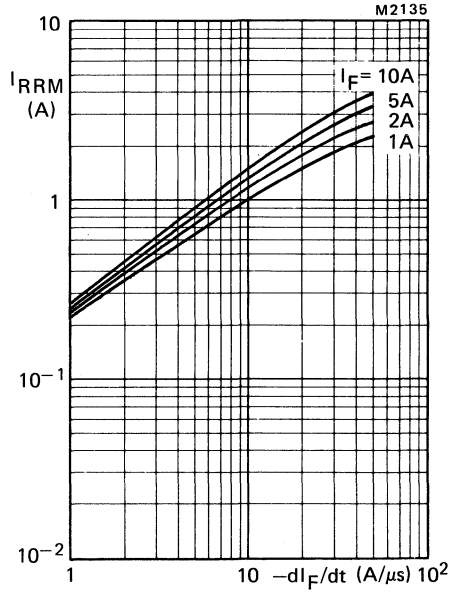


Fig.12 Maximum I_{RRM} at $T_j = 100$ °C.

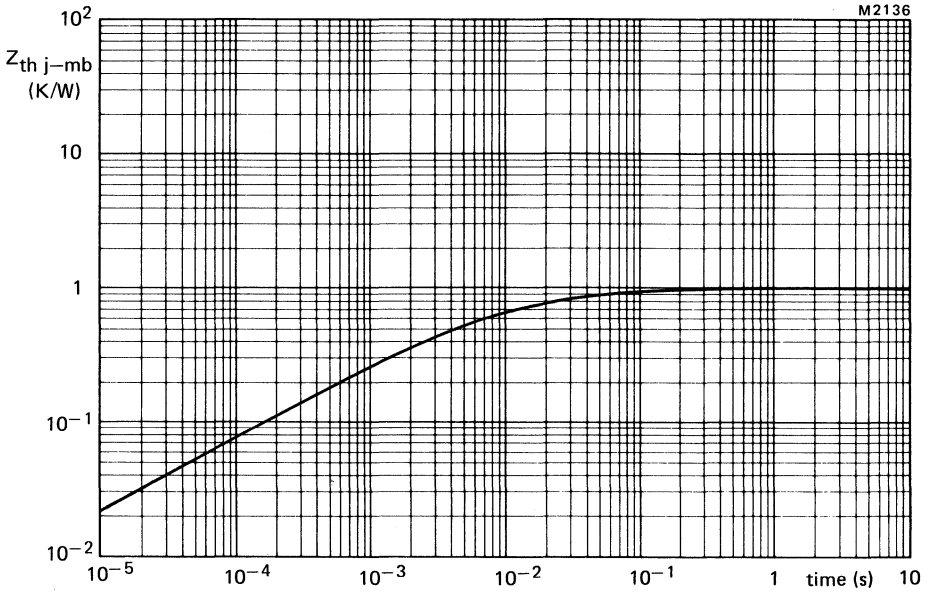


Fig.13 Transient thermal impedance

ULTRA FAST RECOVERY DOUBLE RECTIFIER DIODES



Glass-passivated, high-efficiency double rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times and soft-recovery characteristic. They are intended for use in switched mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. Their single chip (monolithic) construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common-cathode types.

QUICK REFERENCE DATA

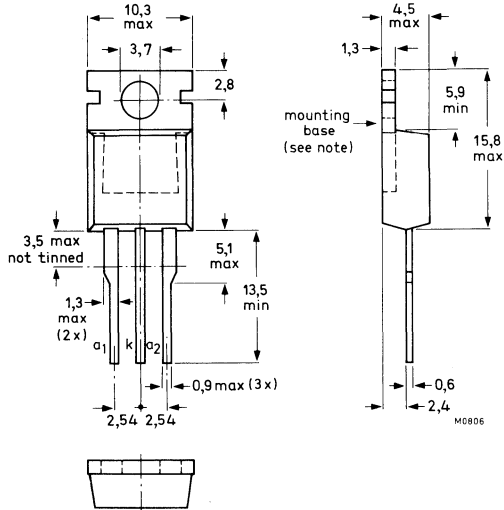
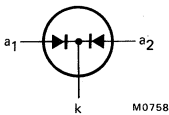
Per diode, unless otherwise stated

		BYV32-50	100	150	200		
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200	V
Output current (both diodes conducting)	I_O	max.		20			A
Forward Voltage	V_F	<		0.85			V
Reverse recovery time	t_{rr}	<		25			ns

MECHANICAL DATA

Fig.1 TO-220AB.

Dimensions in mm



Net mass: 2g

Note: the exposed metal mounting base is directly connected to the common cathode.
Accessories supplied on request: see data sheets Mounting Instructions and accessories for TO-220 envelopes.

Products approved to CECC 50 009-026 available on request.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

Voltages (per diode)		BYV32--50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage (note 1)	V_R	max. 50	100	150	200	V

→ Currents (both diodes conducting; note 2)

Output current; switching

losses negligible up to 500 kHz;

square wave; $\delta = 0.5$; up to $T_{mb} = 118^\circ\text{C}$

I_O max. 20 A

square wave; $\delta = 0.5$; up to $T_{mb} = 125^\circ\text{C}$

I_O max. 16.5 A

sinusoidal; up to $T_{mb} = 120^\circ\text{C}$

I_O max. 18 A

sinusoidal; up to $T_{mb} = 125^\circ\text{C}$

I_O max. 16 A

R.M.S. forward current

$I_{F(RMS)}$ max. 28 A

Repetitive peak forward current

$t_p = 20 \mu\text{s}$, $\delta = 0.02$ (per diode)

I_{FRM} max. 230 A

Non-repetitive peak forward current (per diode)

half sine-wave; $T_j = 150^\circ\text{C}$ prior to

surge; with reapplied V_{RWM} max

$t = 10$ ms

I_{FSM} max. 150 A

$t = 8.3$ ms

I_{FSM} max. 160 A

$I^2 t$ for fusing ($t = 10\text{ms}$; per diode)

$I^2 t$ max. 112 A^2s

Temperatures

Storage temperature

T_{stg} -40 to $+150$ $^\circ\text{C}$

Junction temperature

T_j max. 150 $^\circ\text{C}$

Notes:

- To ensure thermal stability, $R_{thj-a} < 14$ K/W.
- The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.

CHARACTERISTICS (per diode)

Forward voltage

$I_F = 5 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

V_F	<	0.85	V*
V_F	<	1.15	V*

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$

$V_R = V_{RWM \text{ max}}; T_j = 25 \text{ }^\circ\text{C}$

I_R	<	0.6	mA
I_R	<	30	μA

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s};$

$T_j = 25 \text{ }^\circ\text{C}; \text{ recovery time}$

t_{rr}	<	25	ns
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$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s};$

$T_j = 25 \text{ }^\circ\text{C}; \text{ recovered charge}$

Q_s	<	12.5	nC
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$I_F = 10 \text{ A to } V_F \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s};$

$T_j = 100 \text{ }^\circ\text{C}; \text{ peak recovery current}$

I_{RRM}	<	2	A
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Forward recovery when switched to $I_F = 1 \text{ A}$

with $dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

V_{fr}	typ.	0.9	V
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M80-1319/3

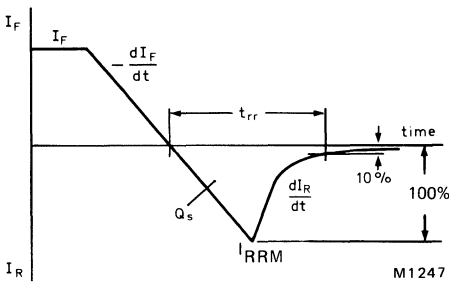


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

*Measured under pulse conditions to avoid excessive dissipation

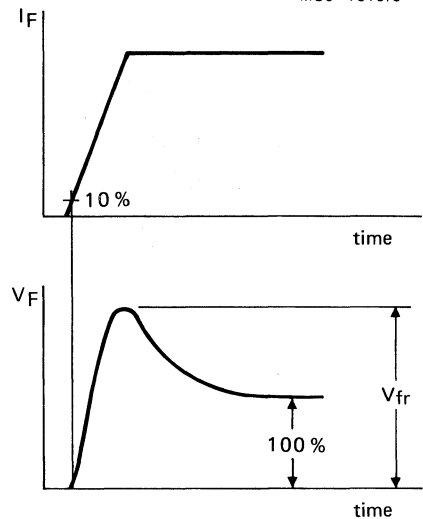


Fig.3 Definition of V_{fr} .

→ THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)	$R_{th\ j-mb}$	=	1.6	K/W
From junction to mounting base (per diode)	$R_{th\ j-mb}$	=	2.4	K/W

Influence of mounting method

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound	$R_{th\ mb-h}$	=	0.3	K/W
b. with heatsink compound and 0.06 mm maximum mica insulator	$R_{th\ mb-h}$	=	1.4	K/W
c. with heatsink compound and 0.1 mm maximum mica insulator (56369)	$R_{th\ mb-h}$	=	2.2	K/W
d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)	$R_{th\ mb-h}$	=	0.8	K/W
e. without heatsink compound	$R_{th\ mb-h}$	=	1.4	K/W

2. Free air operation

The quoted values of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

	$R_{th\ j-a}$	=	60	K/W
--	---------------	---	----	-----

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

The various components of junction temperature rise above ambient are illustrated in Fig.4:

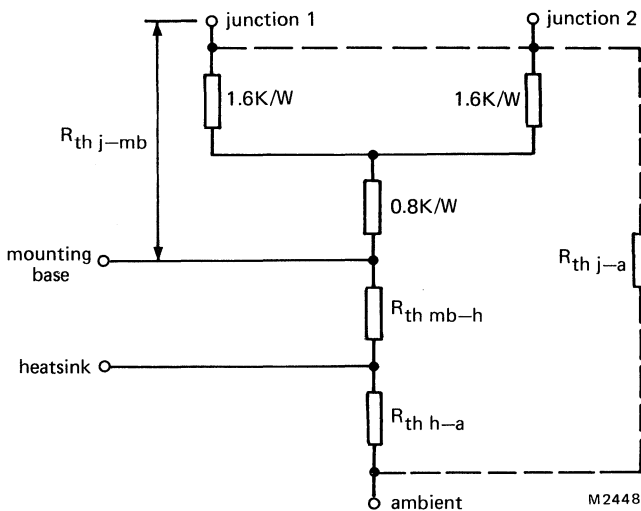


Fig.4

Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION (PER DIODE)

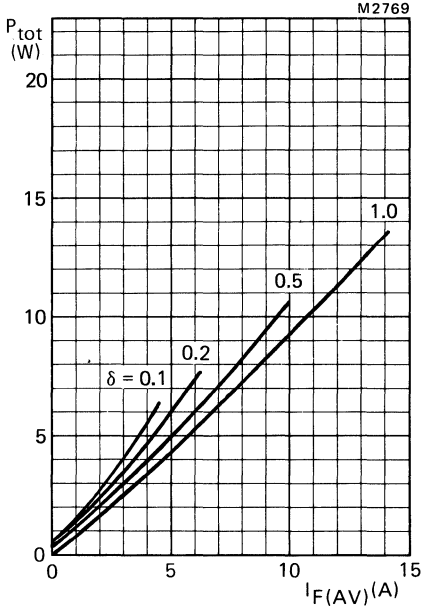
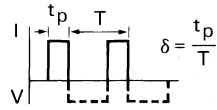


Fig. 5 Power rating per diode. The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

Power includes reverse current losses and switching losses up to $f = 500$ kHz

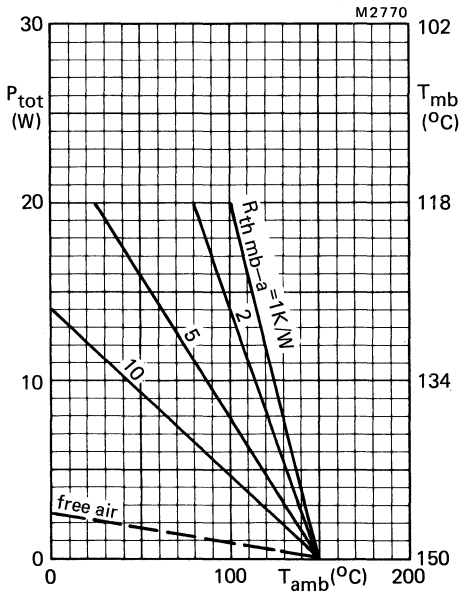


Fig.6

SINUSOIDAL OPERATION (PER DIODE)

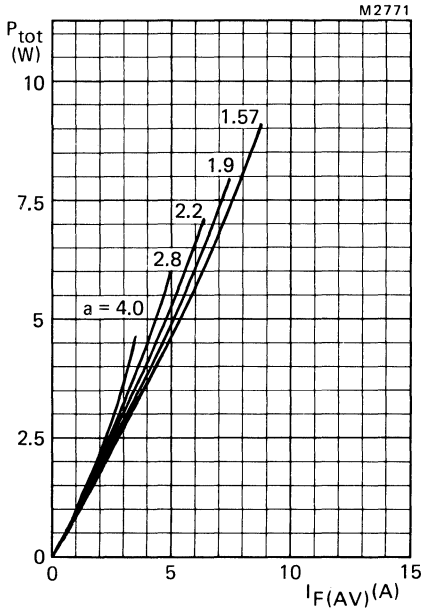


Fig.7 Power rating per diode.
The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$



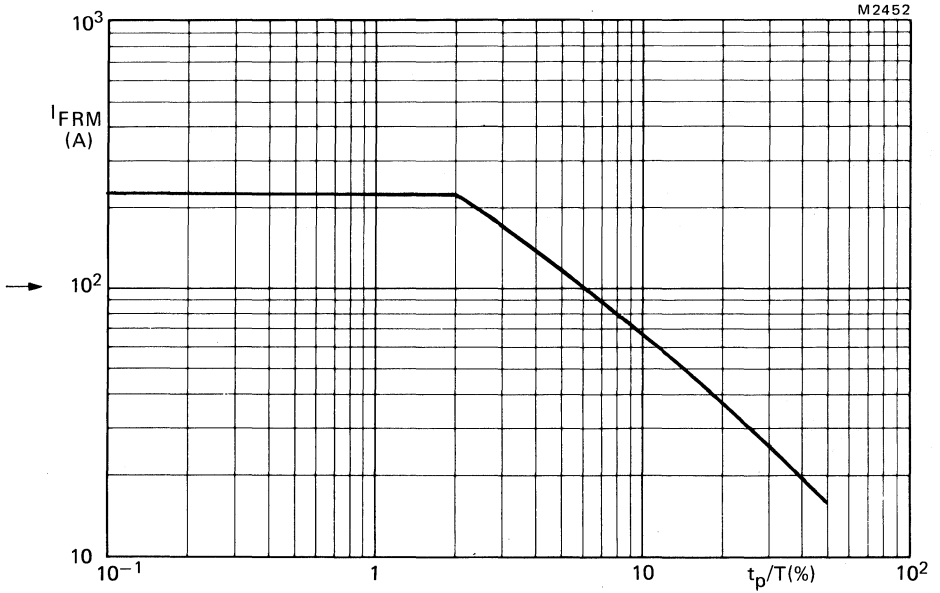


Fig.8 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 ms$; per diode.

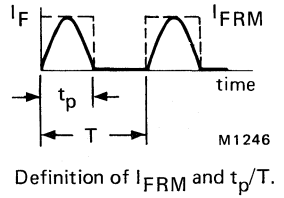
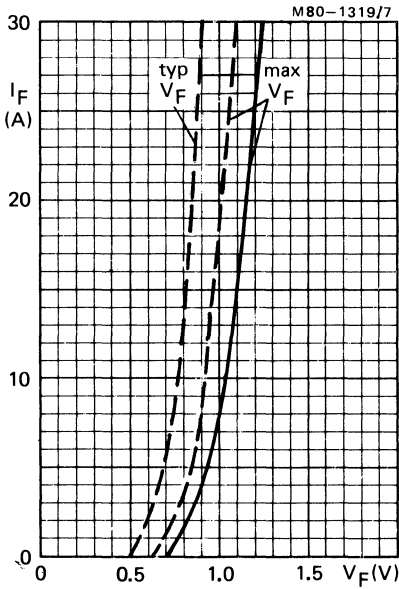


Fig.9 — $T_j = 25 \text{ }^\circ\text{C}$; --- $T_j = 100 \text{ }^\circ\text{C}$; per diode.

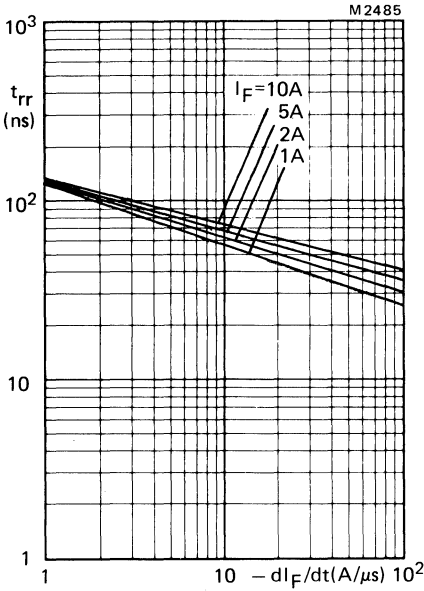


Fig.10 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$; per diode.

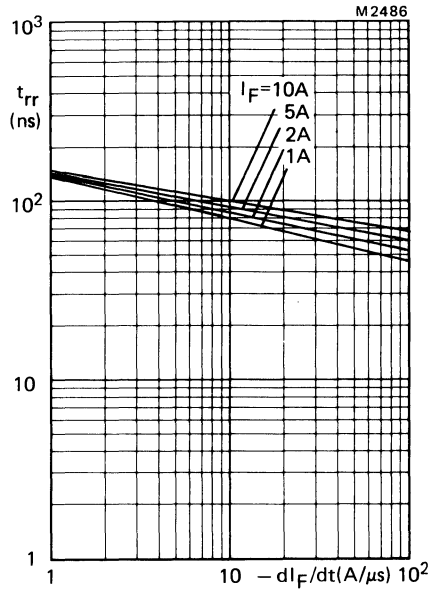


Fig.11 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$; per diode.

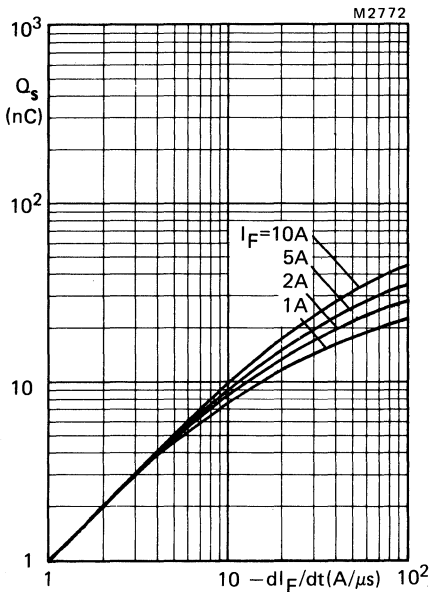


Fig.12 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$; per diode.

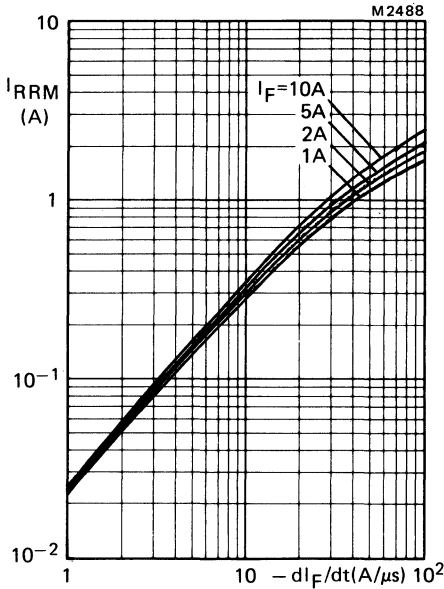


Fig.13 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$; per diode.

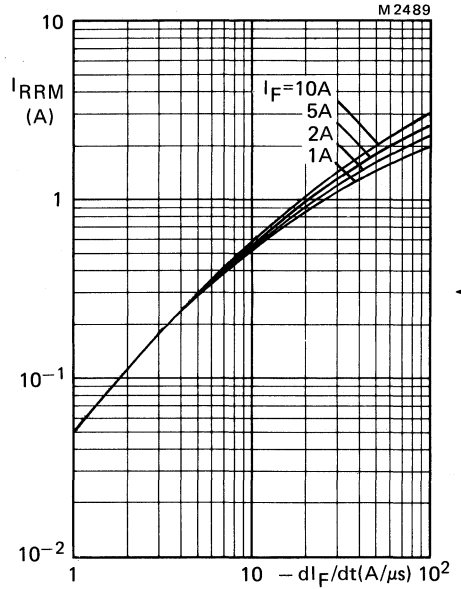


Fig.14 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$; per diode.

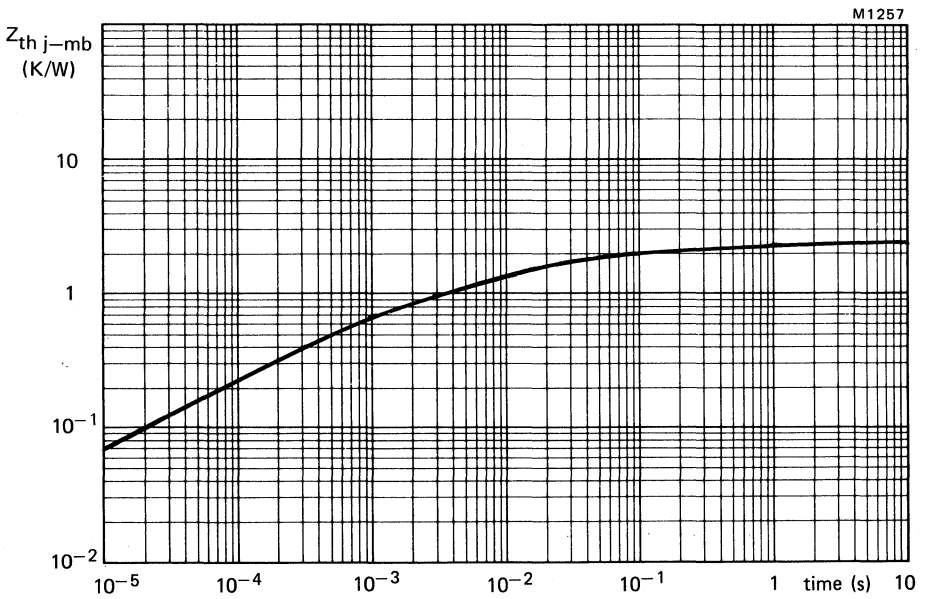


Fig.15 Transient thermal impedance; one diode conducting.

ULTRA FAST-RECOVERY ELECTRICALLY-ISOLATED DOUBLE RECTIFIER DIODES

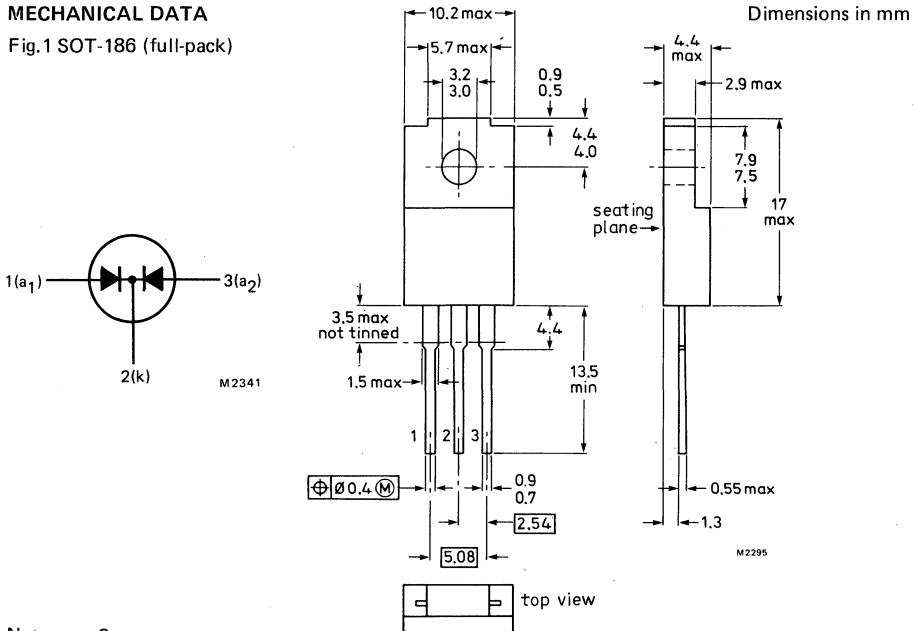
Glass-passivated, high-efficiency epitaxial double rectifier diodes in SOT-186 (full-pack) plastic envelopes, featuring low forward voltage drop, very fast reverse recovery times and soft-recovery characteristic. Their electrical isolation makes them ideal for mounting on a common heatsink alongside other components without the need for additional insulators. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction and switching losses are essential. Their single chip construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common cathode types.

QUICK REFERENCE DATA

Per diode, unless otherwise stated		BYV32F-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Output current (both diodes conducting)	I_O	max.		12		A
Forward voltage	V_F	<		0.85		V
Reverse recovery time	t_{rr}	<		25		ns

MECHANICAL DATA

Fig. 1 SOT-186 (full-pack)



Net mass: 2 g.

The seating plane is electrically isolated from all terminals.

Accessories supplied on request (see data sheets Mounting instructions for F-pack devices and Accessories for SOT-186 envelopes).

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

		BYV32F-50	100	150	200		
Voltages (per diode; see note 1)							
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max.	50	100	150	200	V
Continuous reverse voltage	V_R	max.	50	100	150	200	V
Currents (see notes 2 and 3)							
Output current, switching losses negligible up to 500 kHz							
square wave; $\delta = 0.5$; up to $T_h = 92^\circ\text{C}$	I_O	max.		12			A
sinusoidal; up to $T_h = 100^\circ\text{C}$	I_O	max.		10.6			A
R.M.S. forward current	$I_F(\text{RMS})$	max.		12			A
Repetitive peak forward current $t_p = 20 \mu\text{s}$, $\delta = 0.02$ (per diode)	I_{FRM}	max.		155			A
Non-repetitive peak forward current half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max:							
$t = 10 \text{ ms}$ (per diode)	I_{FSM}	max.		150			A
$t = 8.3 \text{ ms}$ (per diode)	I_{FSM}	max.		160			A
$I^2 t$ for fusing ($t = 10 \text{ ms}$; per diode)	$I^2 t$	max.		112			A^2s
Temperatures							
Storage temperature	T_{stg}			-40 to +150			$^\circ\text{C}$
Junction temperature	T_j	max.		150			$^\circ\text{C}$
ISOLATION							
Peak isolation voltage from all terminals to external heatsink	V_{isol}	max.		1000			V
Isolation capacitance from cathode to external heatsink (see note 4)	C_p	typ.		12			pF

Notes

1. To ensure thermal stability: $R_{th j-a} < 6.3 \text{ K/W}$ for continuous reverse voltage.
2. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
3. The quoted temperatures assume heatsink compound is used.
4. Mounted without heatsink compound and with 20 Newtons pressure on the centre of the envelope.

THERMAL RESISTANCE

From junction to external heatsink with minimum of 2 kgf (20 Newtons) pressure on the centre of the envelope,
total package:
without heatsink compound
with heatsink compound

$R_{th\ j-h}$	=	7.0	K/W
$R_{th\ j-h}$	=	5.0	K/W

Free-air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same point.

Thermal resistance from junction to ambient in free air, device mounted on a printed circuit board

$R_{th\ j-a}$	=	55	K/W
---------------	---	----	-----

CHARACTERISTICS

Forward voltage

$I_F = 5\text{ A}; T_j = 100\text{ }^\circ\text{C}$
 $I_F = 20\text{ A}; T_j = 25\text{ }^\circ\text{C}$

V_F	<	0.85	V*
V_F	<	1.15	V*

Reverse current

$V_R = V_{RWM\ max}; T_j = 100\text{ }^\circ\text{C}$
 $V_R = V_{RWM\ max}; T_j = 25\text{ }^\circ\text{C}$

I_R	<	0.6	mA
I_R	<	10	μA

Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$;
 $T_j = 25\text{ }^\circ\text{C}$; recovery time

t_{rr}	<	25	ns
----------	---	----	----

$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$;
 $T_j = 25\text{ }^\circ\text{C}$; recovered charge

Q_s	<	12.5	nC ←
-------	---	------	------

$I_F = 10\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$;
 $T_j = 100\text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	2	A ←
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Forward recovery when switched to $I_F = 1\text{ A}$ with $dI_F/dt = 10\text{ A}/\mu\text{s}$; $T_j = 25\text{ }^\circ\text{C}$

V_{fr}	typ.	1	V
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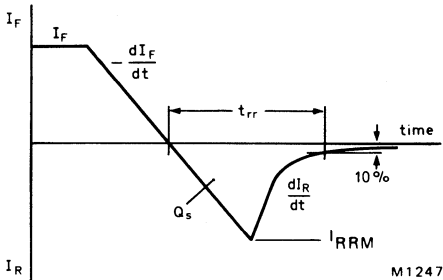


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

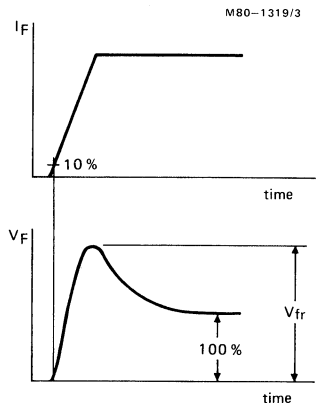


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

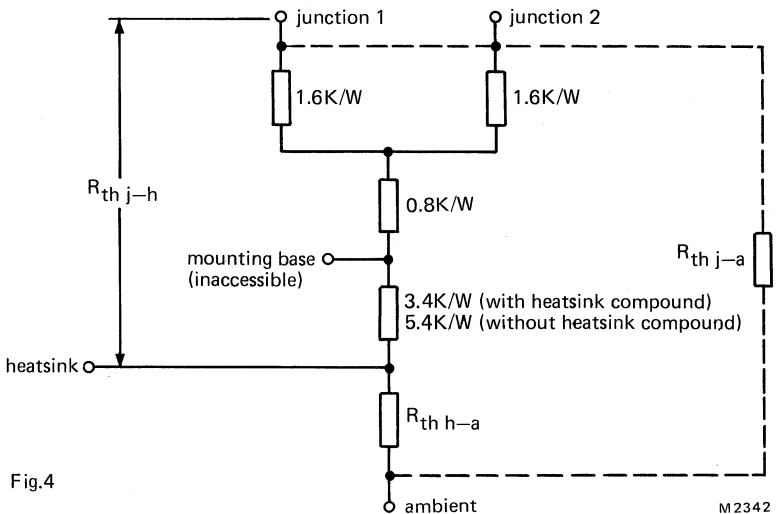
MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- 2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers a good thermal contact under the crystal area and slightly lower $R_{th\ j-h}$ values than screw mounting. The force exerted on the top of the device by the clip should be at least 2 kgf (20 Newtons) to ensure good thermal contact and must not exceed 3.5 kgf (35 Newtons) to avoid damage to the device.
4. If screw mounting is used, it should be M3 cross-recess pan head.
 - Minimum torque to ensure good thermal contact: 5.5 kgf (0.55 Nm)
 - Maximum torque to avoid damage to the device: 8.0 kgf (0.80 Nm)
5. For good thermal contact, heatsink compound should be used between baseplate and heatsink. Values of $R_{th\ j-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting.
 - It is not recommended to use rivets, since extensive damage could result to the plastic, which could destroy the insulating properties of the device.
- 7. The heatsink must have a flatness in the mounting area of 0.02 mm maximum per 10 mm. Mounting holes must be deburred.

OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated in Fig.4:



- b. Any measurement of heatsink temperature should be immediately adjacent to the device.

SQUARE-WAVE OPERATION

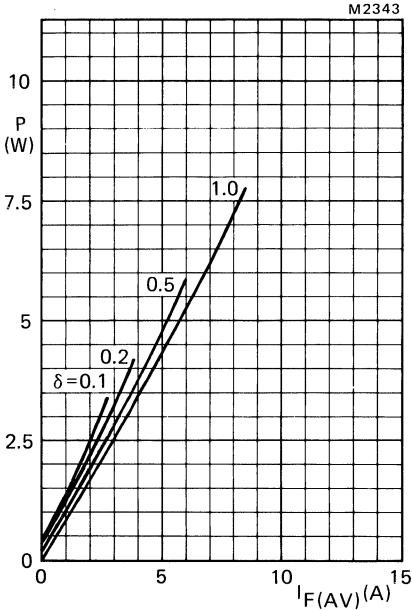


Fig.5 Power rating.

The individual power loss in each diode should first be determined from the required forward current on the $I_{F(AV)}$ axis and the appropriate duty cycle, then both added together to give a total power loss for the whole device.

Having determined this power (P), use Fig.7 (if heatsink compound is not being used) or Fig.8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.

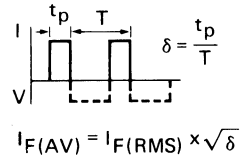


Fig.6 Power rating.

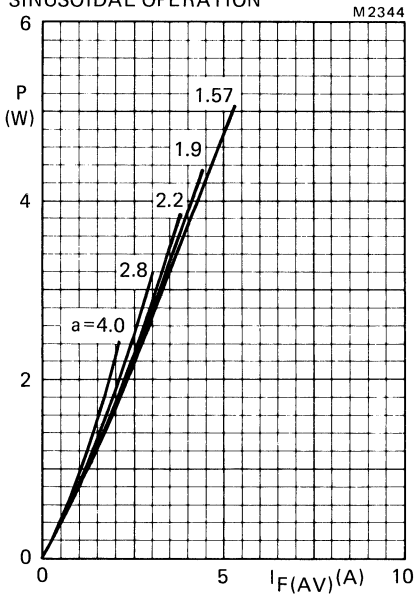
The individual power loss in each diode should first be determined from the required forward current on the $I_{F(AV)}$ axis and the appropriate form factor, then both added together to give a total power loss for the whole device.

Having determined this power (P), use Fig.7 (if heatsink compound is not being used) or Fig.8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.

a = form factor = $I_{F(RMS)}/I_{F(AV)}$

SINUSOIDAL OPERATION



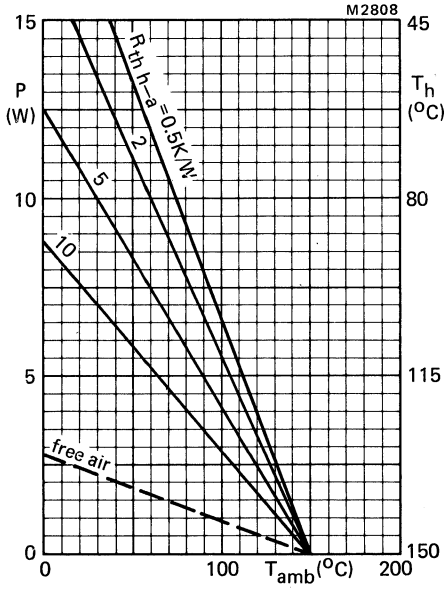


Fig.7 Heatsink rating.
Without heatsink compound.

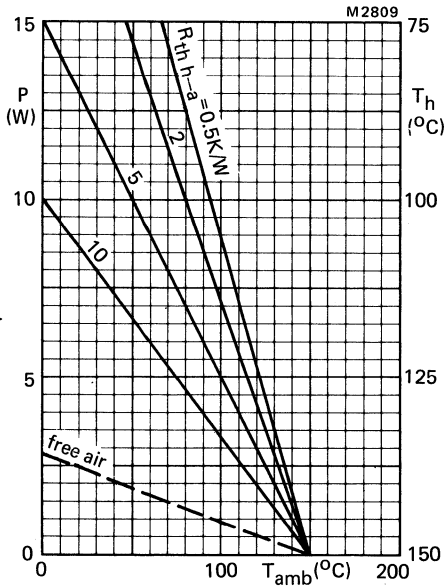


Fig.8 Heatsink rating.
With heatsink compound.

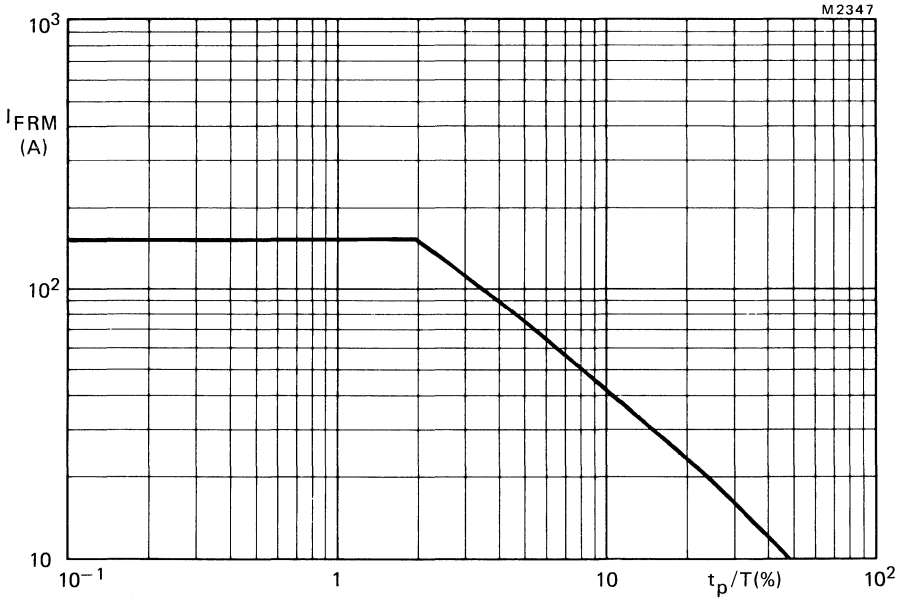
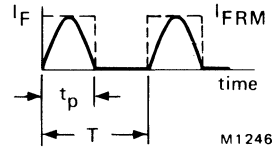
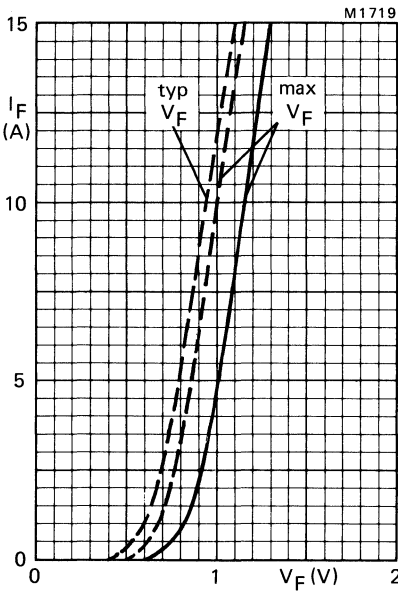


Fig.9 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T

Fig.10 — $T_j = 25^\circ\text{C}$; - - - $T_j = 150^\circ\text{C}$ per diode.

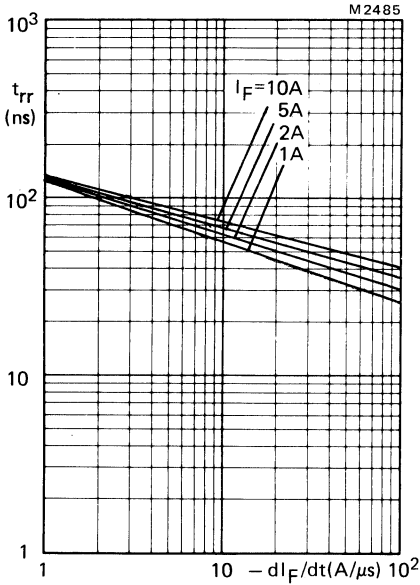


Fig.11 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

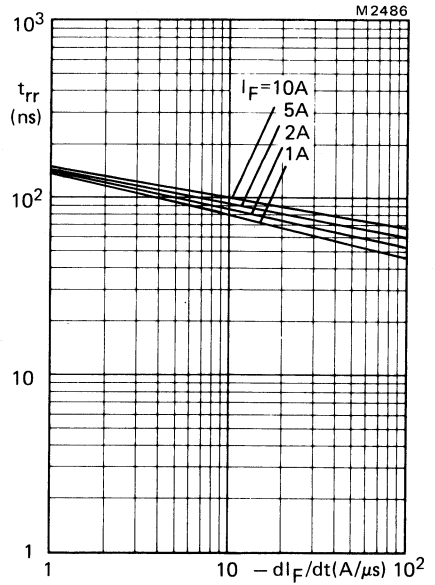


Fig.12 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

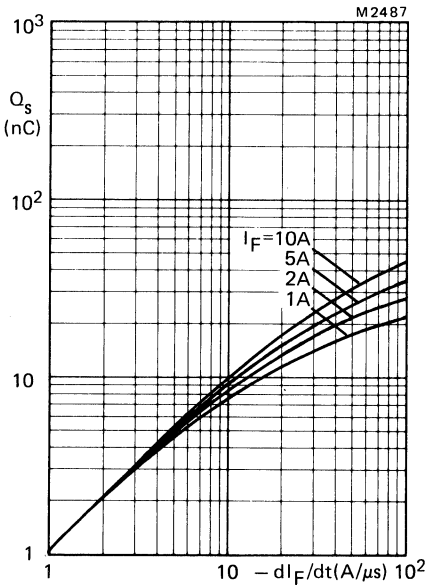


Fig.13 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

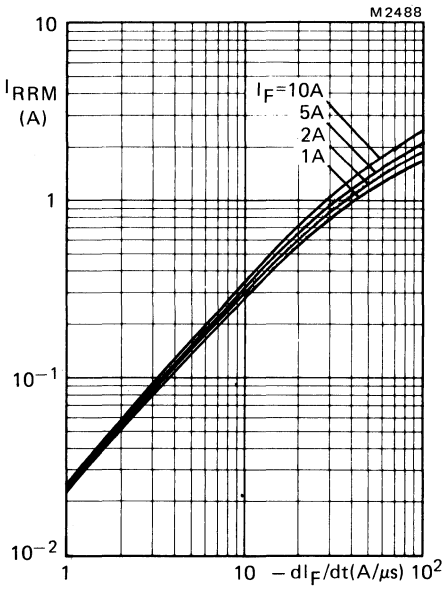


Fig.14 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$

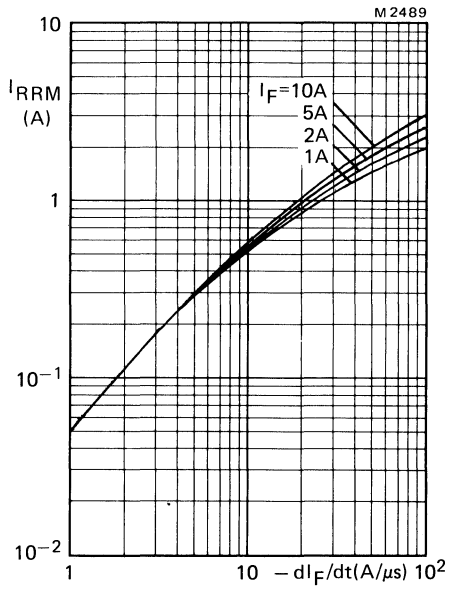


Fig.15 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$;

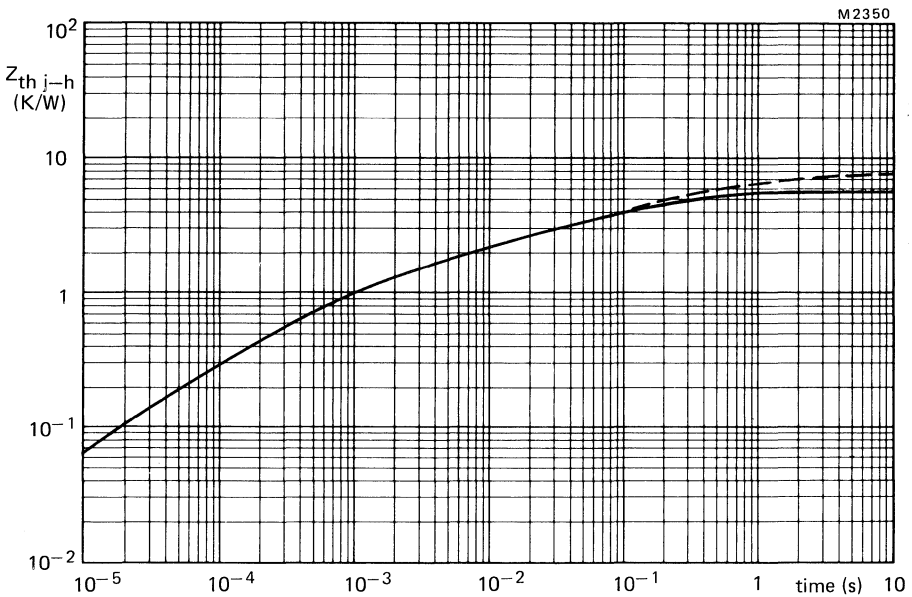


Fig.16 One diode conducting; — with heatsink compound; - - - without heatsink compound.

ULTRA FAST RECOVERY DOUBLE RECTIFIER DIODES

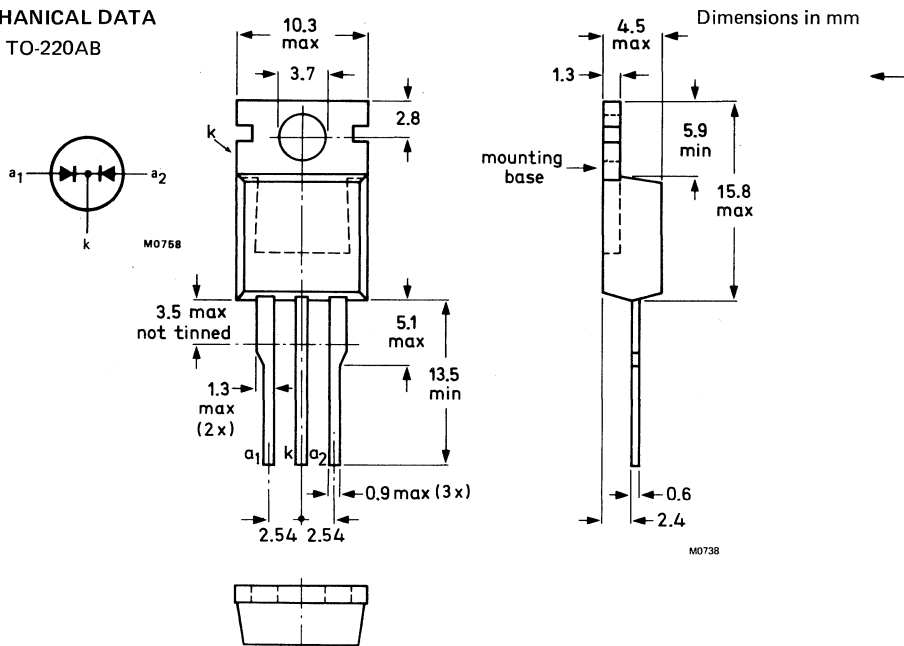
Glass-passivated, high-efficiency double rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. Their single chip (monolithic) construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common-cathode types.

QUICK REFERENCE DATA

Per diode, unless otherwise stated		BYV34-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max. 300	400	500	V
Output current (both diodes conducting)	I_O	max.	20		A
Forward voltage	V_F	<	0.93		V
Reverse recovery time	t_{rr}	<	50		ns

MECHANICAL DATA

Fig.1 TO-220AB



Net mass: 2 g

Note: the exposed metal mounting base is directly connected to the common cathode.

Accessories supplied on request: see data sheets Mounting Instructions and accessories for TO-220 envelopes.

BYV34 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

Voltages (per diode)		BYV34-300			400	500	
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	400	500	V
Crest working reverse voltage	V_{RWM}	max.	200	300	300	400	V
Continuous reverse voltage (note 1)	V_R	max.	200	300	300	400	V
Currents (both diodes conducting; note 2)							
Output current; switching							
→ losses negligible up to 200 kHz;							
square wave; $\delta = 0.5$; up to $T_{mb} = 113^\circ\text{C}$	I_O	max.		20			A
up to $T_{mb} = 125^\circ\text{C}$	I_O	max.		14			A
sinusoidal; up to $T_{mb} = 120^\circ\text{C}$	I_O	max.		17.5			A
up to $T_{mb} = 125^\circ\text{C}$	I_O	max.		14			A
→ R.M.S. forward current	$I_F(\text{RMS})$	max.		28			A
Repetitive peak forward current							
$t_p = 20 \mu\text{s}$; $\delta = 0.02$ (note 3)	I_{FRM}	max.		240			A
Non-repetitive peak forward current (per diode)							
half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge							
with re-applied V_{RWM} max							
$t = 10 \text{ ms}$	I_{FSM}	max.		120			A
$t = 8.3 \text{ ms}$	I_{FSM}	max.		150			A
$I^2 t$ for fusing ($t = 10 \text{ ms}$; per diode)	$I^2 t$	max.		72			A^2s
Temperatures							
Storage temperature	T_{stg}			-40 to +150			$^\circ\text{C}$
Junction temperature	T_j	max.		150			$^\circ\text{C}$

Notes

1. To ensure thermal stability: $R_{th j-a} < 4.5 \text{ K/W}$.
2. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.

CHARACTERISTICS (per diode)

Forward voltage

$I_F = 10 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$	$V_F < 0.93 \text{ V}^*$
$I_F = 30 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F < 1.4 \text{ V}^*$

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$	$I_R < 0.6 \text{ mA}$
$V_R = V_{RWM \text{ max}}; T_j = 25 \text{ }^\circ\text{C}$	$I_R < 50 \text{ } \mu\text{A}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$ recovery time	$t_{rr} < 50 \text{ ns}$
--	--------------------------

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$ recovered charge	$Q_s < 45 \text{ nC}$
--	-----------------------

$I_F = 10 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 100 \text{ }^\circ\text{C}$ peak recovery current	$I_{RRM} < 5.0 \text{ A}$
---	---------------------------

Forward recovery when switched to $I_F = 10 \text{ A}$
with $dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
recovery voltage

V_{fr}	typ.	2.5	V
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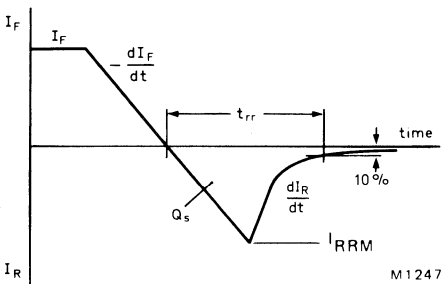


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

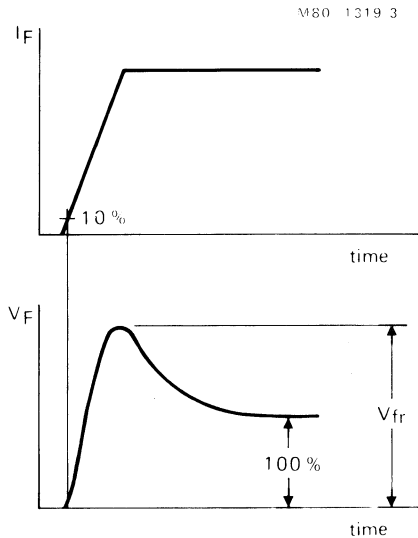


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)

$$R_{th\ j-mb} = 1.6 \text{ K/W}$$

From junction to mounting base (per diode)

$$R_{th\ j-mb} = 2.3 \text{ K/W}$$

→ Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
- Mounting by means of a spring clip is the best mounting method because it offers:
 - a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
- Rivet mounting (only possible for non-insulated mounting). Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

- The various components of junction temperature rise above ambient are illustrated in Fig.4

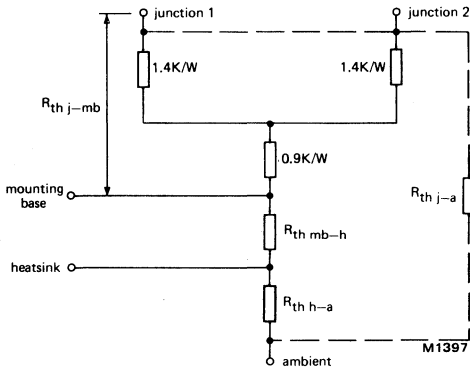


Fig.4

- Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION (PER DIODE)

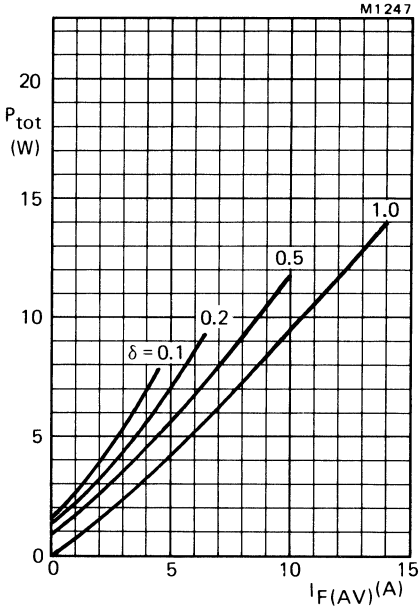


Fig.5 Power rating per diode.

The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

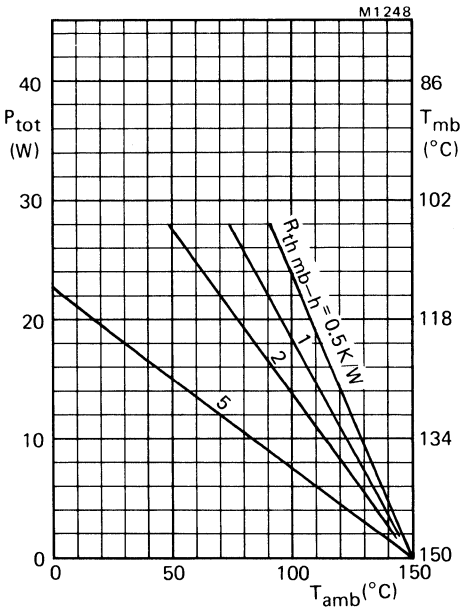
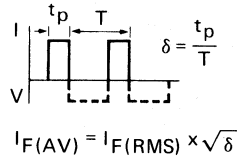


Fig.6

SINUSOIDAL OPERATION (PER DIODE)

M1249

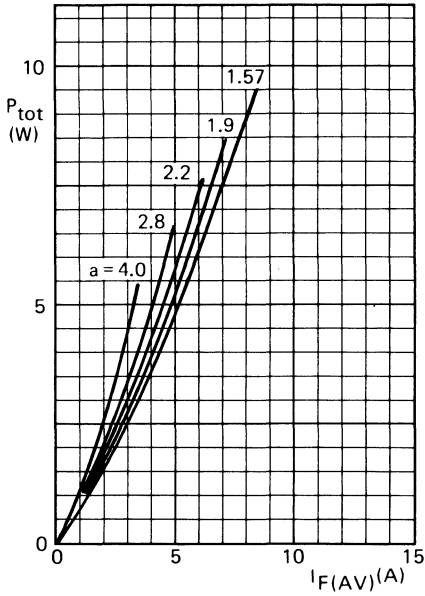


Fig.7 Power rating per diode.

The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$

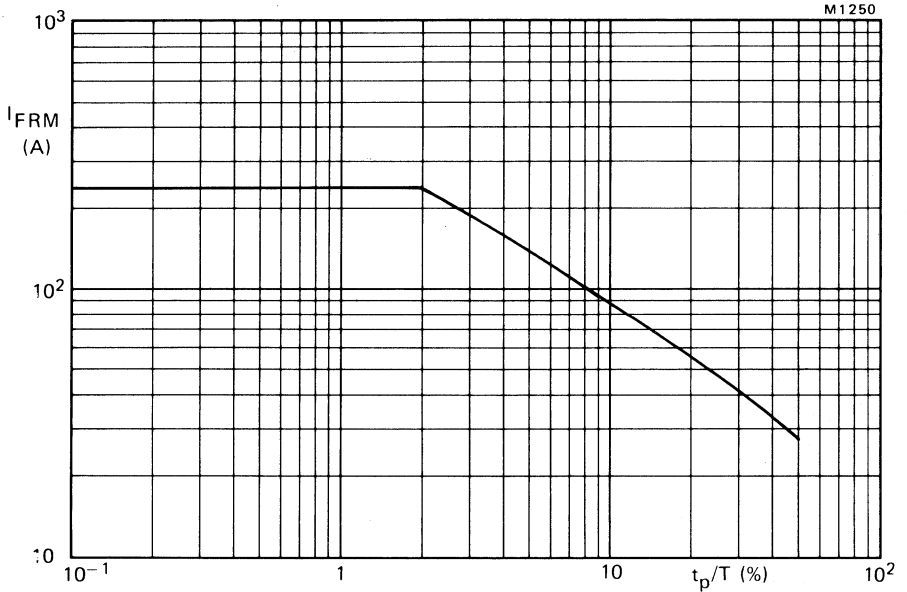
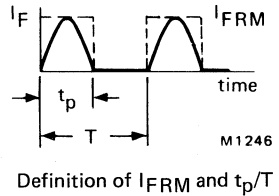
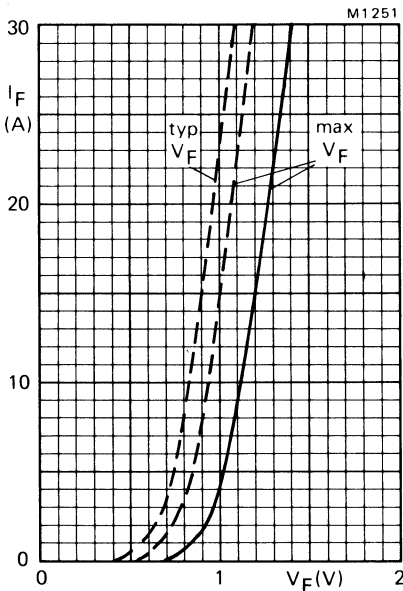


Fig.8 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu\text{s} < t_p < 1 \text{ms}$. (per diode).



Definition of I_{FRM} and t_p/T

Fig. 9 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$ (per diode).

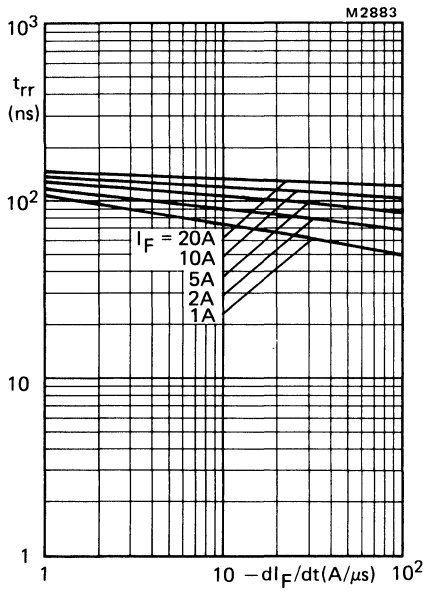


Fig.10 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.
(per diode).

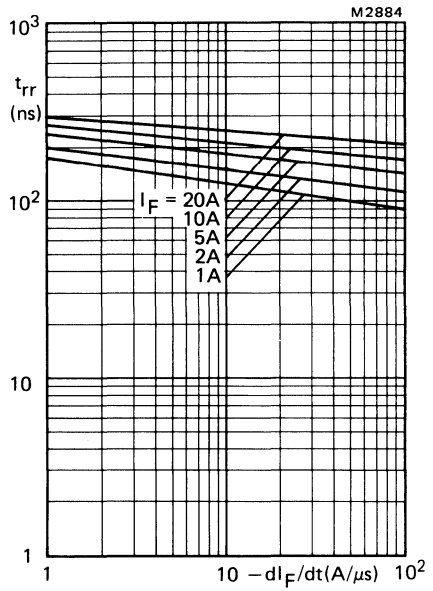


Fig.11 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.
(per diode).

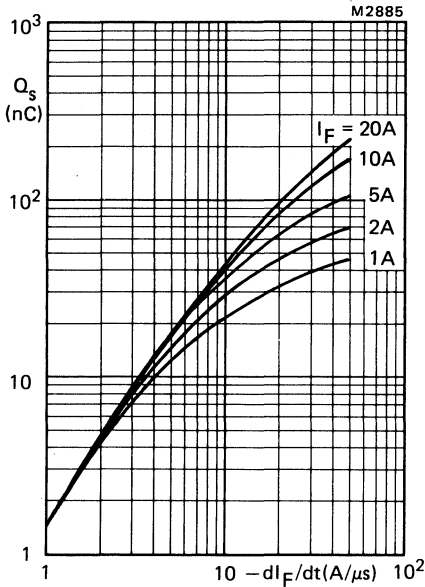


Fig.12 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.
(per diode).

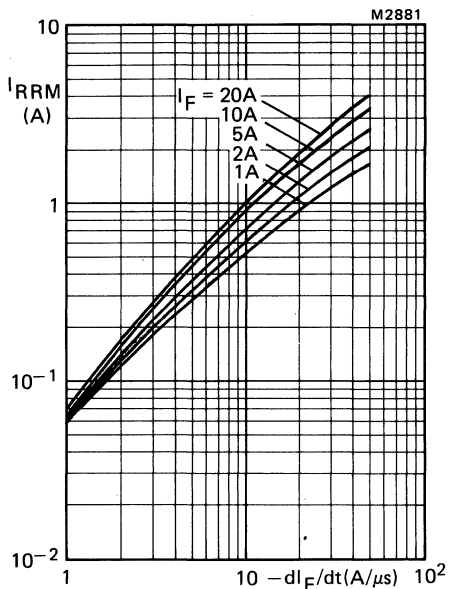


Fig.13 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.
(per diode).

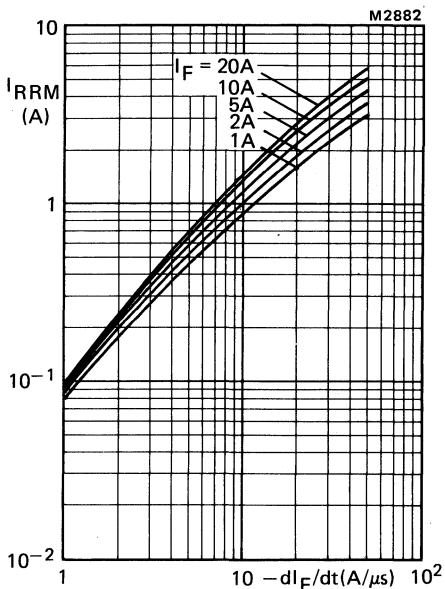


Fig.14 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.
(per diode).

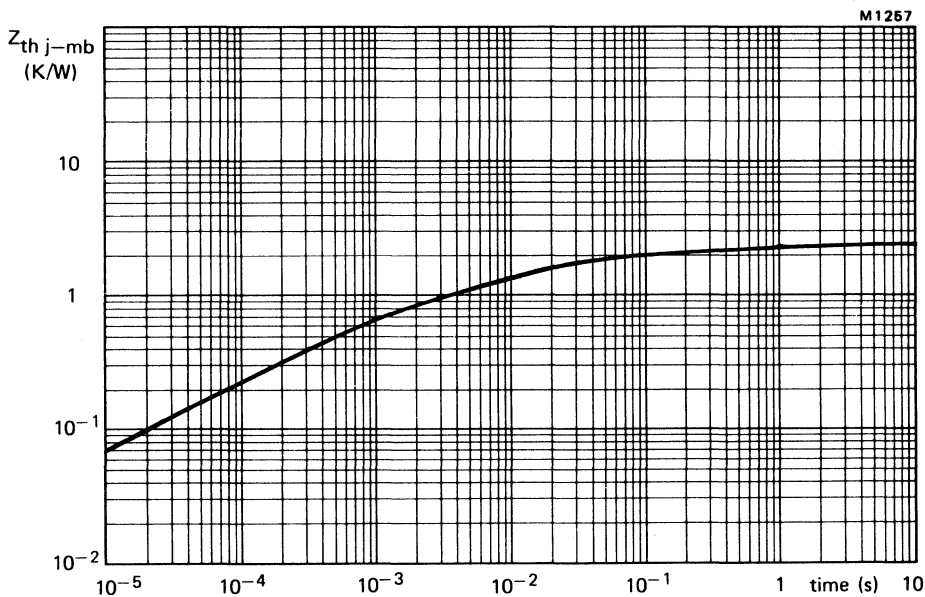


Fig.15 One diode conducting (per diode).

ULTRA FAST RECOVERY DOUBLE RECTIFIER DIODES

Glass-passivated, high-efficiency double rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. Their single chip (monolithic) construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common-cathode types.

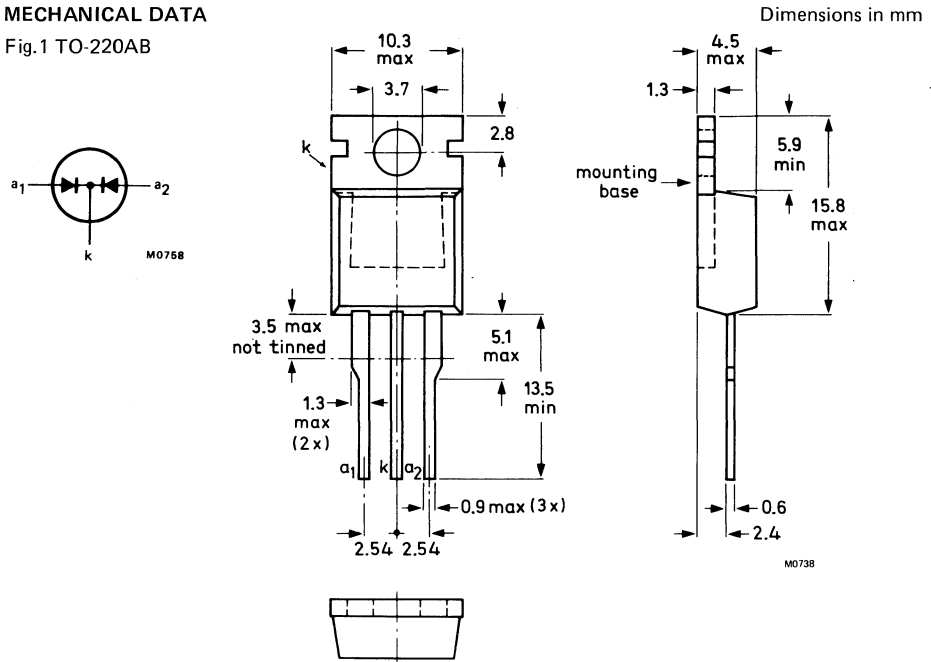
QUICK REFERENCE DATA

Per diode, unless otherwise stated

		BYV42-50				
		100	150	200		
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Output current (both diodes conducting)	I_O	max.	30			A
Forward voltage	V_F	<	0.85			V
Reverse recovery time	t_{rr}	<	28			ns

MECHANICAL DATA

Fig.1 TO-220AB



Net mass: 2 g

Note: the exposed metal mounting base is directly connected to the common-cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

BYV42 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)

		BYV42-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage	V_R	max. 50	100	150	200	V

→ Currents (both diodes conducting: note 1)

Output current; switching

losses negligible up to 500 kHz;

square wave; $\delta = 0.5$;

up to $T_{mb} = 104^\circ\text{C}$ (note 2)

I_O	max.		30		A
-------	------	--	----	--	---

R.M.S. forward current (note 2)

$I_F(\text{RMS})$	max.		43		A
-------------------	------	--	----	--	---

Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$ (per diode)

I_{FRM}	max.		320		A
-----------	------	--	-----	--	---

Non-repetitive peak forward current (per diode)

half sine-wave; $T_j = 150^\circ\text{C}$ prior to

surge; with reapplied V_{RWM} max

$t = 10 \text{ ms}$

I_{FSM}	max.		200		A
-----------	------	--	-----	--	---

$t = 8.3 \text{ ms}$

I_{FSM}	max.		220		A
-----------	------	--	-----	--	---

$I^2 t$ for fusing ($t = 10 \text{ ms}$; per diode)

$I^2 t$	max.		200		A^2s
---------	------	--	-----	--	----------------------

Temperatures

Storage temperature

T_{stg}			-40 to +150		$^\circ\text{C}$
-----------	--	--	-------------	--	------------------

Junction temperature

T_j	max.		150		$^\circ\text{C}$
-------	------	--	-----	--	------------------

Notes:

1. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
2. For output currents in excess of 20 A, connection should be made to the exposed metal mounting base.

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated

Forward voltage

$I_F = 10\text{ A}; T_j = 100\text{ }^\circ\text{C}$
 $I_F = 30\text{ A}$

$V_F < 0.85\text{ V}^*$
 $V_F < 1.15\text{ V}^*$

Reverse current

$V_R = V_{RWM\text{ max}}; T_j = 100\text{ }^\circ\text{C}$
 $V_R = V_{RWM\text{ max}}$

$I_R < 1.0\text{ mA}$
 $I_R < 100\text{ }\mu\text{A}$

Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$;
 recovery time

$t_{rr} < 28\text{ ns}$ ←

$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$;
 recovered charge

$Q_s < 15\text{ nC}$

$I_F = 10\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$;
 $T_j = 100\text{ }^\circ\text{C}$; peak recovery current

$I_{RRM} < 2.4\text{ A}$ ←

Forward recovery when switched to $I_F = 1\text{ A}$
 with $dI_F/dt = 10\text{ A}/\mu\text{s}$

V_{fr} typ. 1.0 V

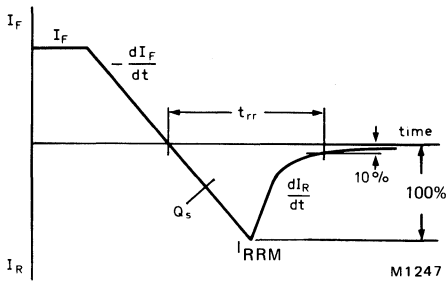


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

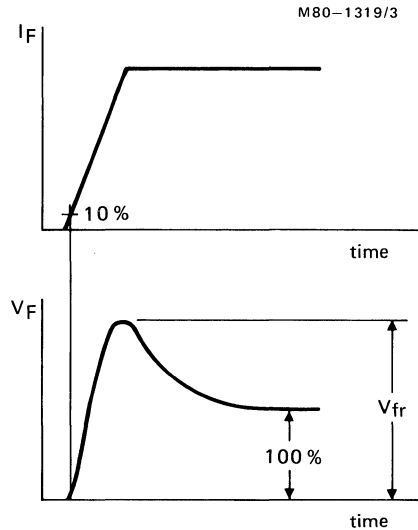


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

→ THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)

$$R_{th\ j-mb} = 1.4 \text{ K/W}$$

From junction to mounting base (per diode)

$$R_{th\ j-mb} = 2.4 \text{ K/W}$$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

The various components of junction temperature rise above ambient are illustrated in Fig.4

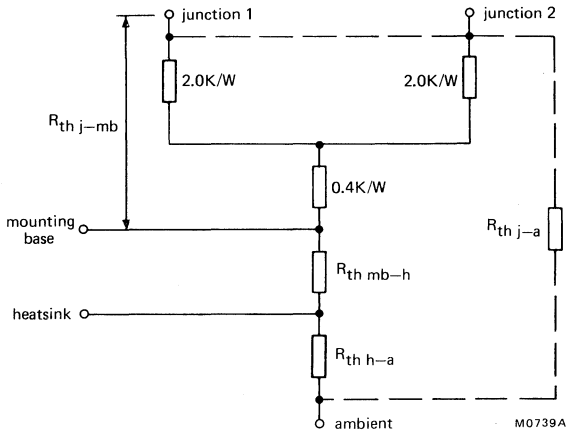


Fig. 4

Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION (PER DIODE)

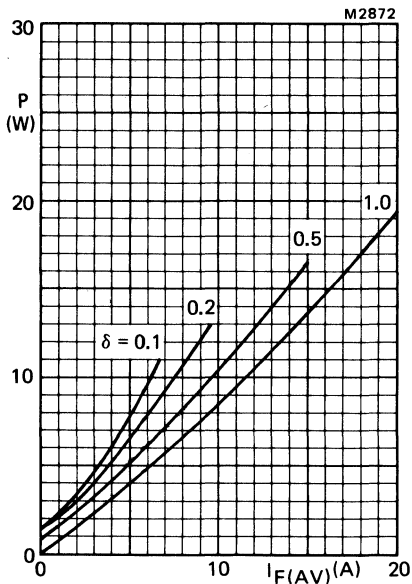
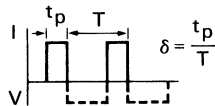


Fig.5 Power rating per diode. The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

Power includes reverse current losses and switching losses up to $f = 500$ kHz.

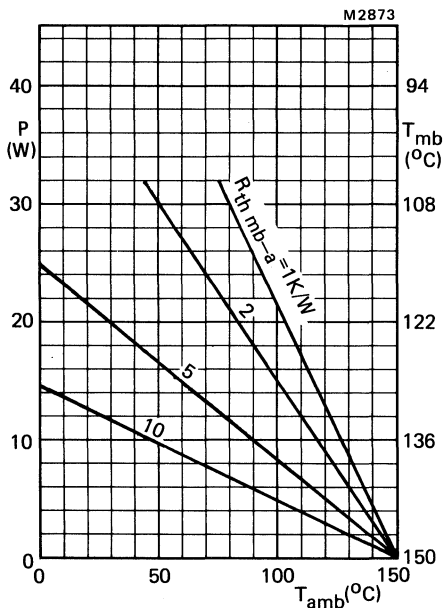


Fig.6.

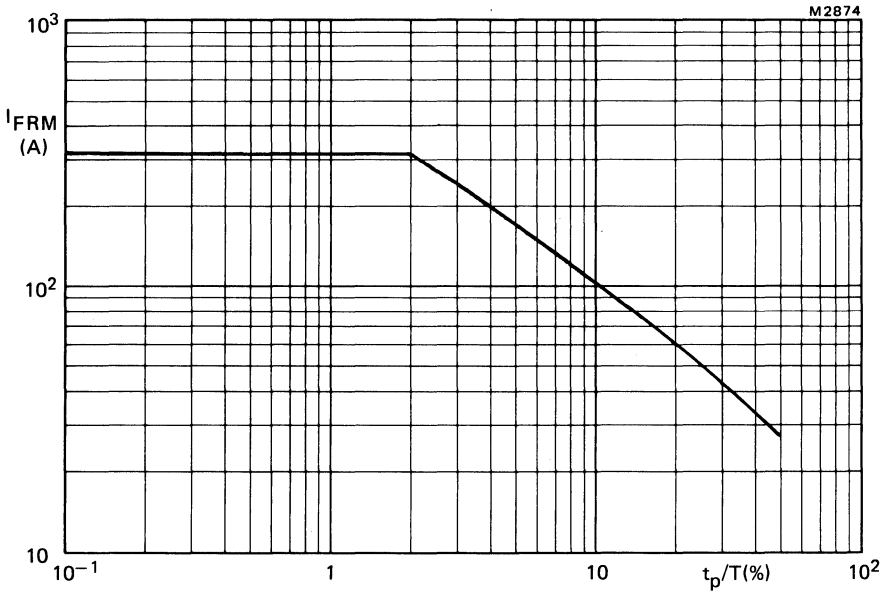


Fig.7 Maximum permissible repetitive peak forward current for square or sinusoidal currents for $1 \mu\text{s} < t_p < 1 \text{ ms}$; per diode.

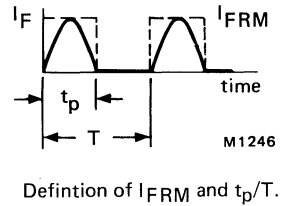
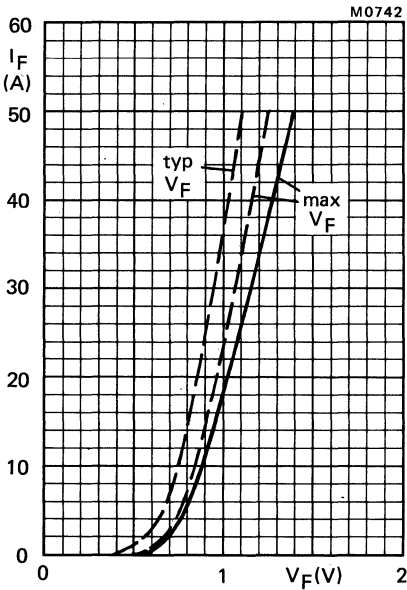


Fig.8 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 100 \text{ }^\circ\text{C}$; per diode.

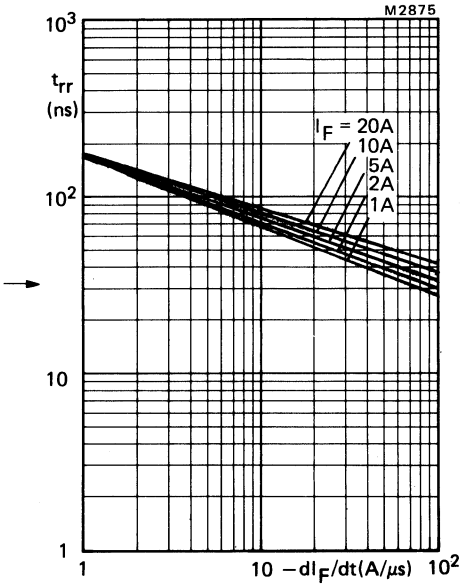


Fig.9 Maximum t_{rr} at $T_j = 25^\circ C$; per diode.

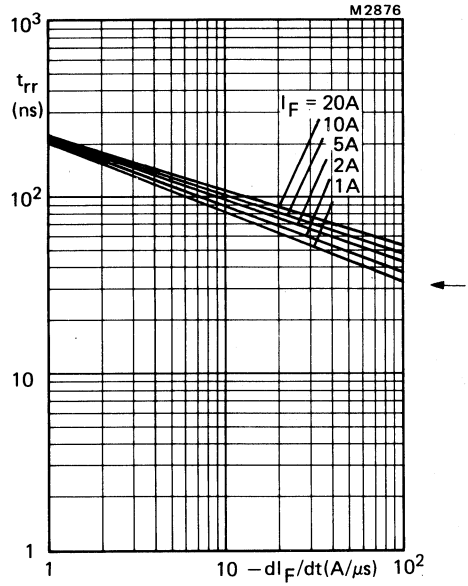


Fig.10 Maximum t_{rr} at $T_j = 100^\circ C$; per diode.

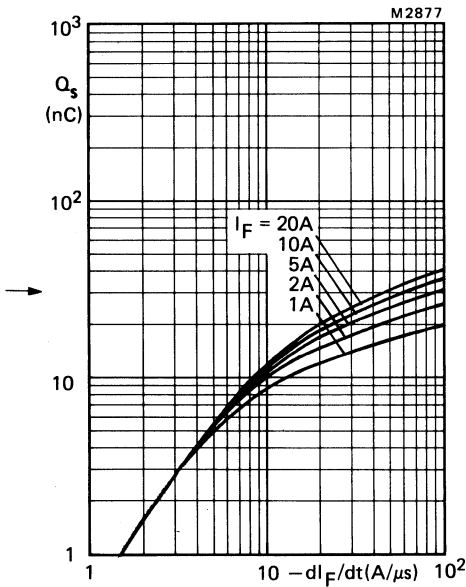


Fig.11 Maximum Q_s at $T_j = 25^\circ C$; per diode.

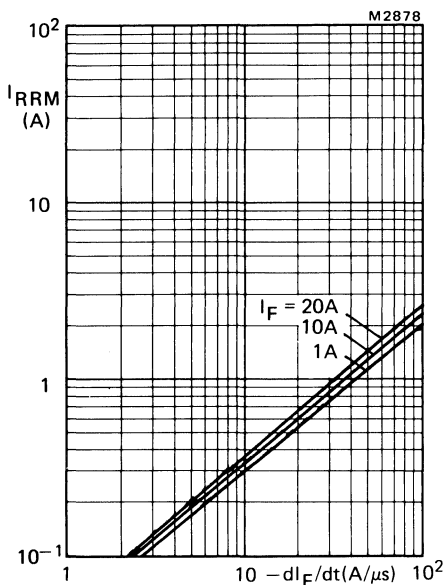


Fig.12 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$; per diode.

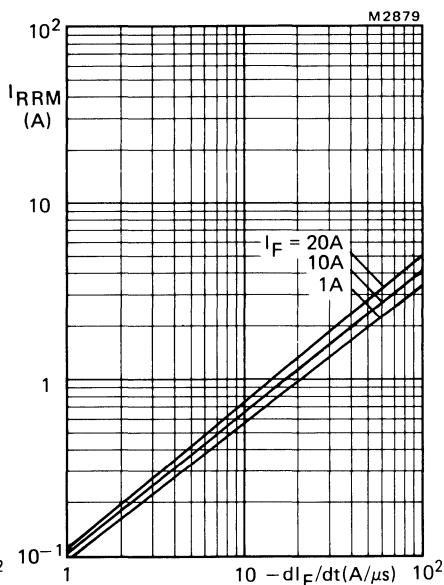


Fig.13 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$; per diode.

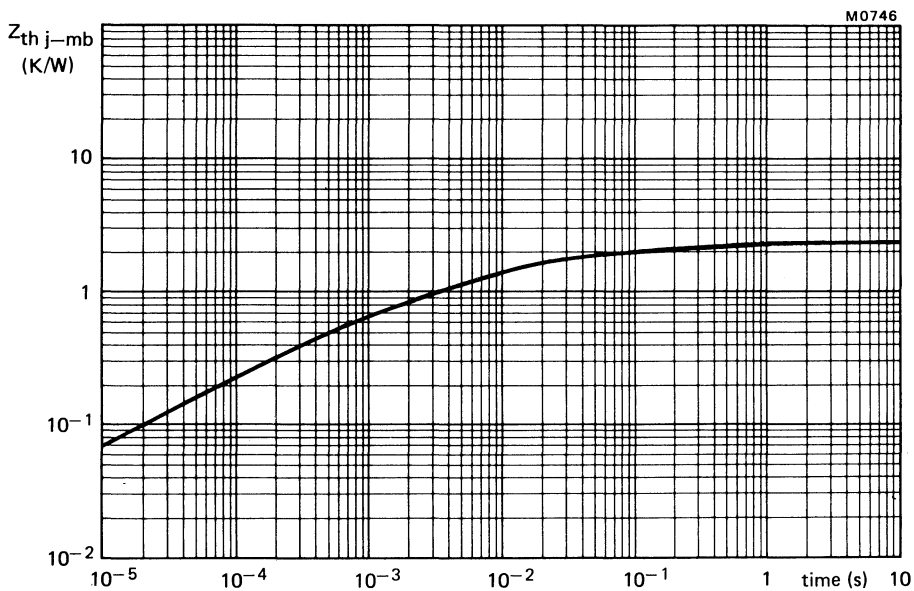


Fig.14 Transient thermal impedance; one diode conducting.

ULTRA FAST RECOVERY DOUBLE RECTIFIER DIODES

Glass-passivated, high-efficiency double rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. Their single chip (monolithic) construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common-cathode types.

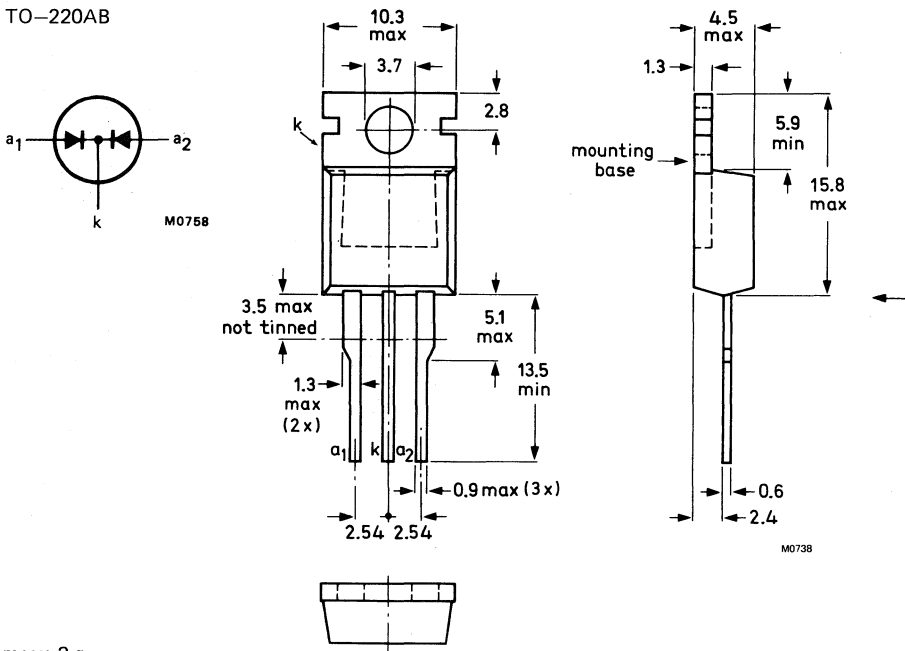
QUICK REFERENCE DATA

Per diode, unless otherwise stated		BYV44-300	400	500	V
Repetitive peak reverse voltage	V_{RRM}	max. 300	400	500	V
Output current (both diodes conducting)	I_O	max.	30		A
Forward voltage	V_F	<	1.05		V
Reverse recovery time	t_{rr}	<	50		ns

MECHANICAL DATA

Fig. TO-220AB

Dimensions in mm



Net mass: 2 g

Note: the exposed metal mounting base is directly connected to the common cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

BYV44 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)		BYV44-300			400	500	
		max.	300	400			
Repetitive peak reverse voltage	V_{RRM}	max.	300	400	500	V	
Crest working reverse voltage	V_{RWM}	max.	200	300	400	V	
Continuous reverse voltage (note 1)	V_R	max.	200	300	400	V	
→ Currents (both diodes conducting; note 2)							
Output current; switching losses							
negligible up to 200 kHz;							
square wave; $\delta = 0.5$; up to $T_{mb} = 92^\circ\text{C}$ (note 3)	I_O	max.		30		A	
sinusoidal; up to $T_{mb} = 103^\circ\text{C}$ (note 3)	I_O	max.		26		A	
R.M.S. forward current (note 3)	$I_F(\text{RMS})$	max.		43		A	
Repetitive peak forward current							
$t_p = 20 \mu\text{s}$; $\delta = 0.02$ (per diode)	I_{FRM}	max.		320		A	
Non-repetitive peak forward current (per diode)							
half sine-wave; $T_j = 150^\circ\text{C}$ prior to							
surge; with reapplied V_{RWM} max							
$t = 10 \text{ ms}$	I_{FSM}	max.		150		A	
$t = 8.3 \text{ ms}$	I_{FSM}	max.		180		A	
$I^2 t$ for fusing ($t = 10 \text{ ms}$; per diode)	$I^2 t$	max.		112		A^2s	
Temperatures							
Storage temperature	T_{stg}			-40 to +150		$^\circ\text{C}$	
Junction temperature	T_j	max.		150		$^\circ\text{C}$	

Notes:

- To ensure thermal stability: $R_{th j-a} < 9.3 \text{ K/W}$.
- The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
- For output currents in excess of 20 A, connection should be made to the exposed metal mounting base.

CHARACTERISTICS (per diode; $T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated)

Forward voltage

$I_F = 15\text{ A}; T_j = 150\text{ }^\circ\text{C}$

$V_F < 1.05\text{ V}^*$

$I_F = 50\text{ A}$

$V_F < 1.4\text{ V}^*$

Reverse current

$V_R = V_{RWM\text{ max}}; T_j = 100\text{ }^\circ\text{C}$

$I_R < 0.8\text{ mA}$

$V_R = V_{RWM\text{ max}}$

$I_R < 50\text{ }\mu\text{A}$

Reverse recovery when switched from

$I_F = 1\text{ A to } V_R \geq 30\text{ V with } -dI_F/dt = 100\text{ A}/\mu\text{s};$
recovery time

$t_{rr} < 50\text{ ns}$

$I_F = 2\text{ A to } V_R \geq 30\text{ V with } -dI_F/dt = 20\text{ A}/\mu\text{s};$
recovered charge

$Q_s < 50\text{ nC}$

$I_F = 10\text{ A to } V_R \geq 30\text{ V with } -dI_F/dt = 50\text{ A}/\mu\text{s};$
 $T_j = 100\text{ }^\circ\text{C};$ peak recovery current

$I_{RRM} < 5.2\text{ A}$

Forward recovery when switched to $I_F = 10\text{ A}$

with $dI_F/dt = 10\text{ A}/\mu\text{s};$

recovery voltage

$V_{fr}\text{ typ. } 2.5\text{ V}$

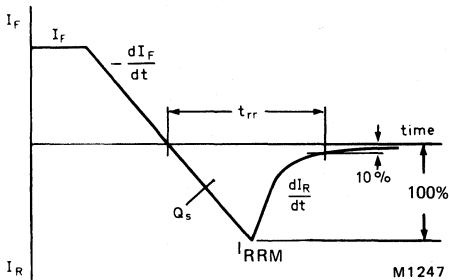


Fig.2 Definition of t_{rr} , Q_s and I_{RRM}

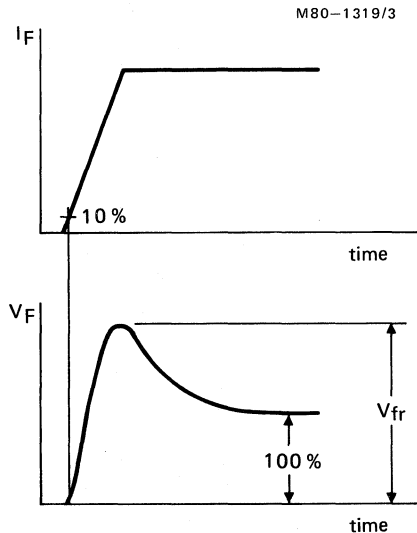


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)

$$R_{th\ j-mb} = 1.4 \text{ K/W}$$

From junction to mounting base (per diode)

$$R_{th\ j-mb} = 2.0 \text{ K/W}$$

→ Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free-air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board.

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

The various components of junction temperature rise above ambient are illustrated in Fig.4:

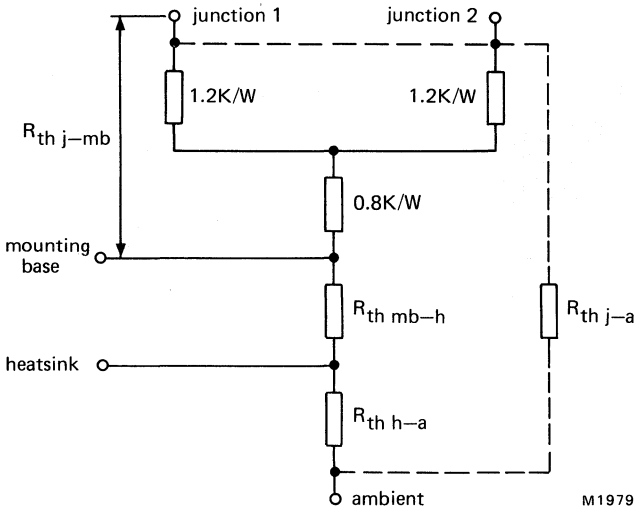


Fig.4

Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION

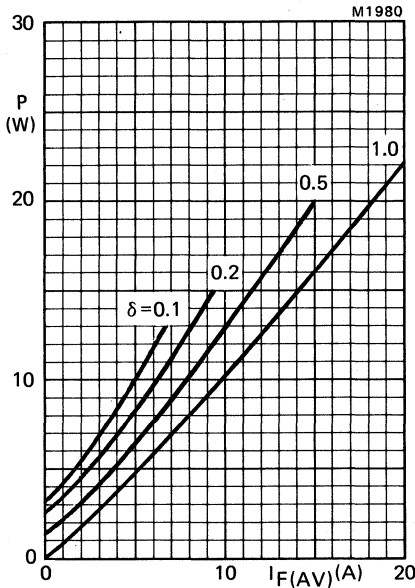
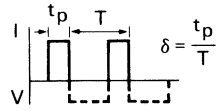


Fig.5 Power rating per diode.

The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

Power includes reverse current losses and switching losses up to $f = 100$ kHz.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

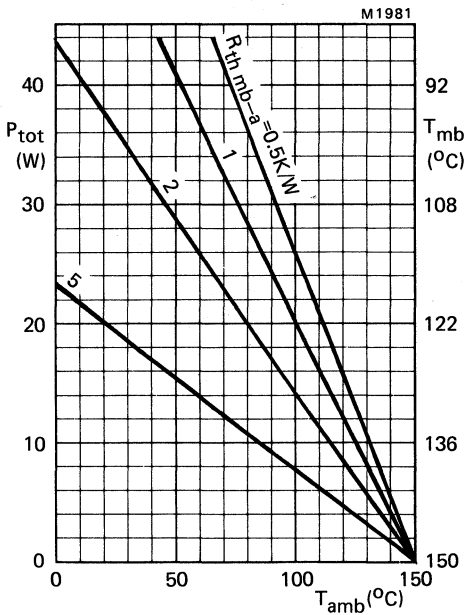


Fig.6

SINUSOIDAL OPERATION

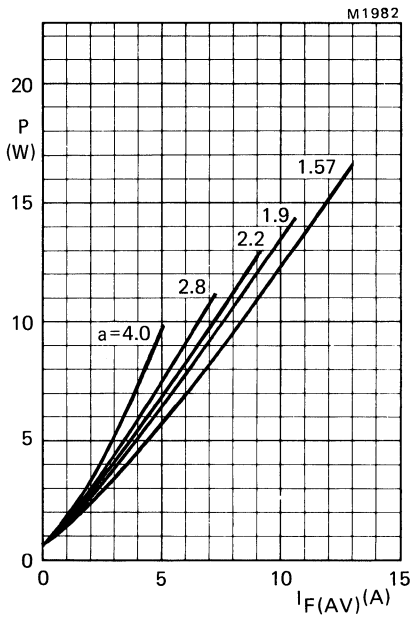


Fig.7 Power rating per diode.

The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$

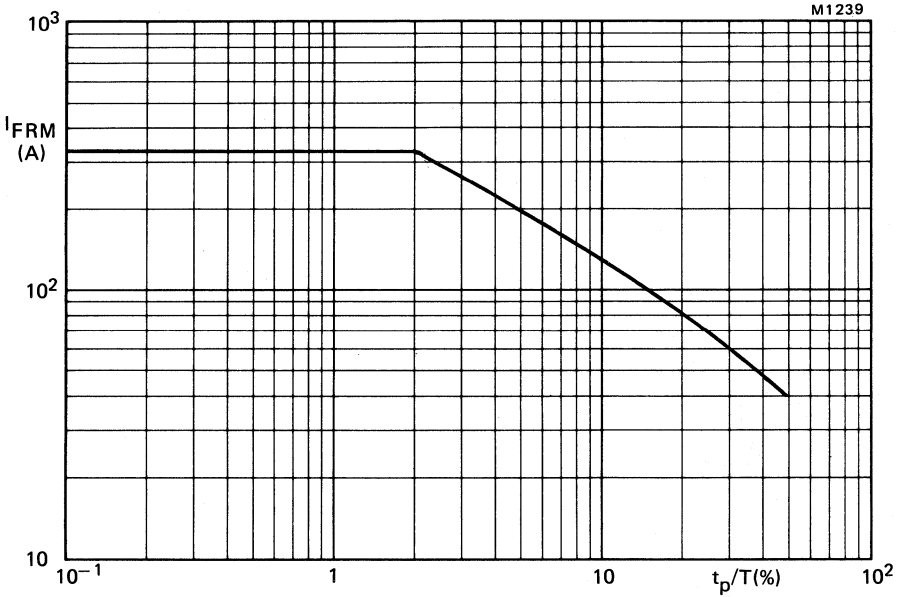


Fig.8 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.

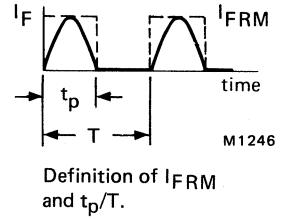
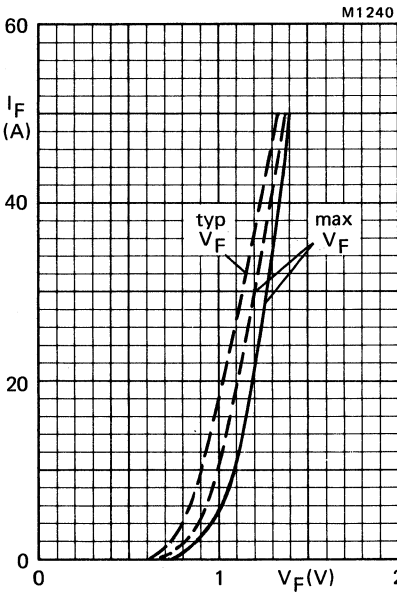


Fig.9 — $T_j = 25 \text{ }^\circ\text{C}$; --- $T_j = 150 \text{ }^\circ\text{C}$.

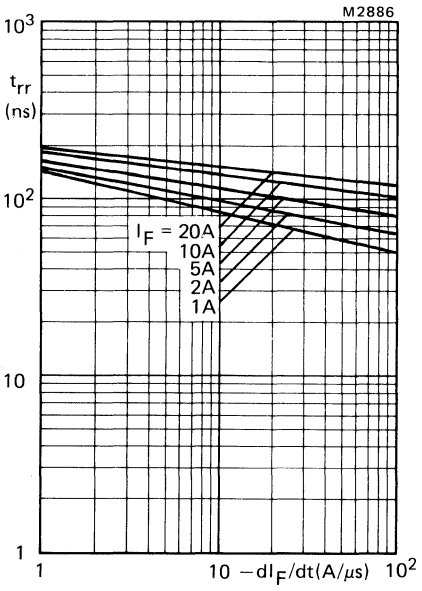


Fig.10 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

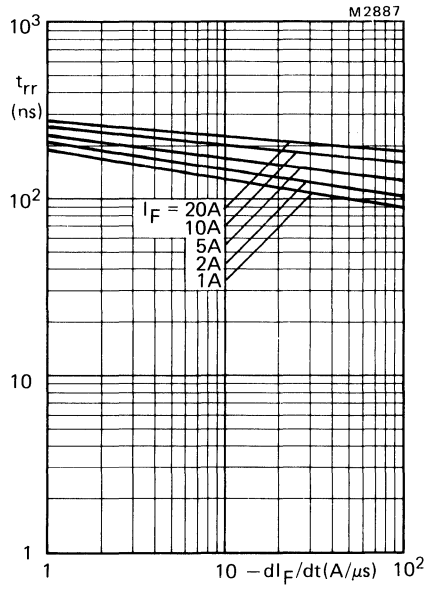


Fig.11 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

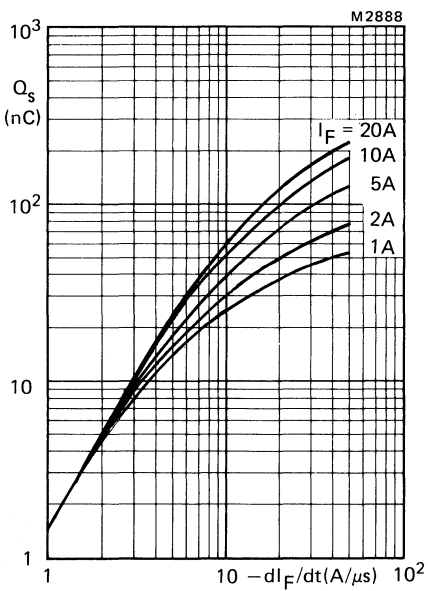


Fig.12 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

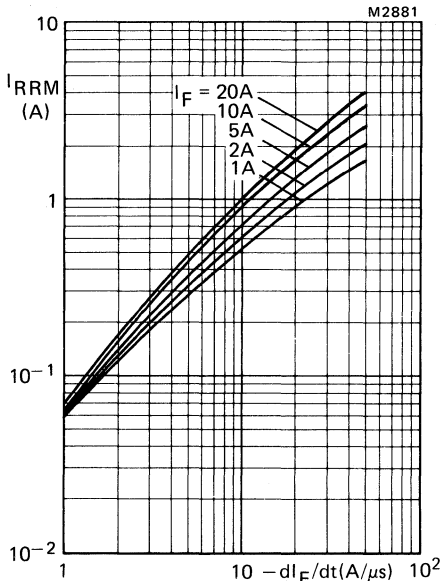


Fig.13 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

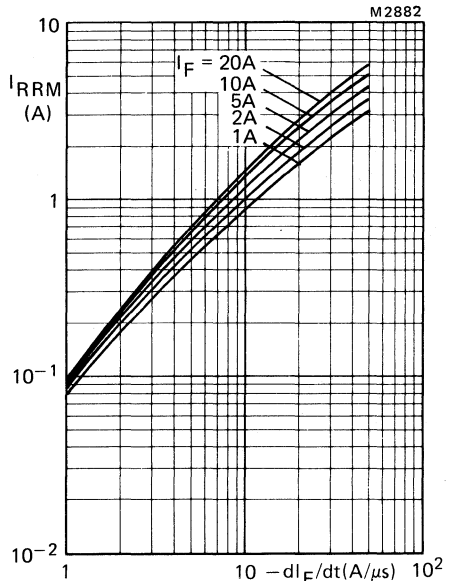


Fig.14 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

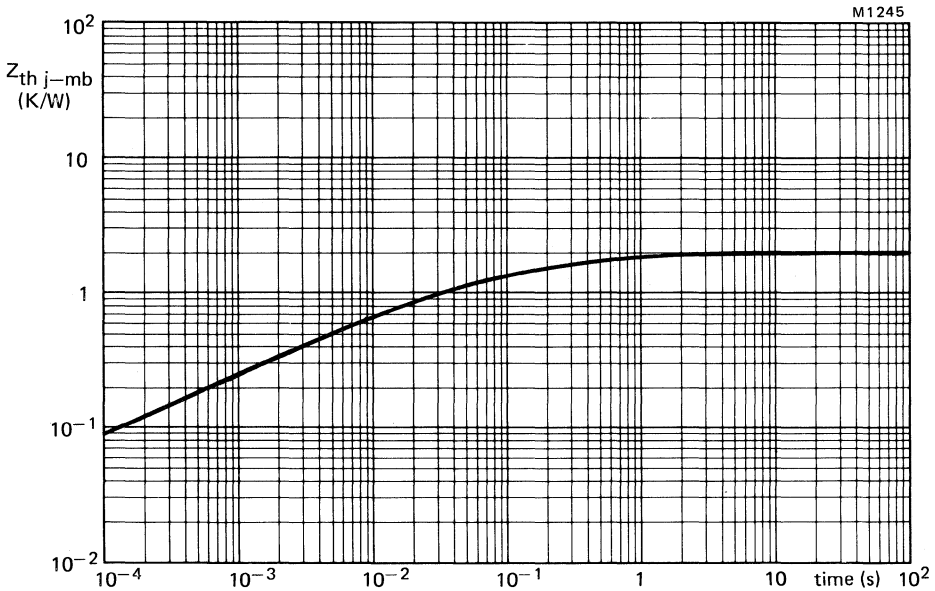


Fig.15 Transient thermal impedance (one diode conducting).

FAST SOFT-RECOVERY RECTIFIER DIODES

Glass-passivated double-diffused rectifier diodes in TO-238 envelope, featuring fast reverse recovery times with soft recovery characteristics.

They are primarily intended for use in a.c. motor control systems as an anti-parallel diode to switching devices such as GTO, ASCR, etc. They are also suitable for use in high-frequency inverters.

The envelope baseplate is electrically isolated.

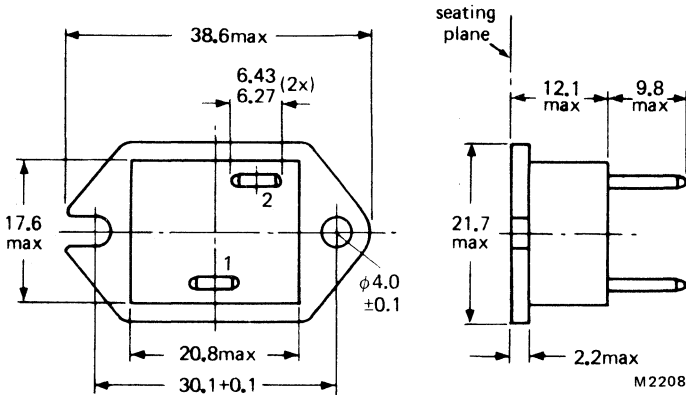
QUICK REFERENCE DATA

		BYV60-850			1000	1200
Repetitive peak reverse voltage	V_{RRM}	max.	850	1000	1200	
Average forward current	$I_F(AV)$	max.		15		A
Non-repetitive peak forward current	I_{FSM}	max.		150		A
Reverse recovery time	t_{rr}	<		0.6		μs

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-238 (2-pin)



Pin 1 = cathode (AMO 250 series)

2 = anode (AMP 250 series)

Baseplate is electrically isolated.

Net mass = 16.5 g

BYV60 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages		BYV60-850	1000	1200	
Non-repetitive peak reverse voltage	V_{RSM}	max. 1000	1100	1300	V
Repetitive peak reverse voltage	V_{RRM}	max. 850	1000	1200	V
Crest working reverse voltage	V_{RWM}	max. 600	800	1000	V
Continuous reverse voltage	V_R	max. 500	650	750	V

Currents

Average forward current assuming zero switching losses

square-wave; $\delta = 0.5$; up to $T_{mb} = 76^\circ\text{C}$
sinusoidal; up to $T_{mb} = 81^\circ\text{C}$

$I_F(AV)$	max.	15	A
$I_F(AV)$	max.	13.5	A

R.M.S. forward current

$I_F(RMS)$	max.	21	A
------------	------	----	---

Repetitive peak forward current;
 $1\ \mu\text{s} < t_p < 1\ \text{ms}; \delta \leq 0.02$

I_{FRM}	max.	300	A
-----------	------	-----	---

Non-repetitive peak forward current; $t = 10\ \text{ms}$
half sine-wave; $T_j = 125^\circ\text{C}$ prior to surge;
with reapplied $V_{RWM\ \text{max}}$

I_{FSM}	max.	150	A
-----------	------	-----	---

Temperatures

Storage temperature

T_{stg}		-40 to +125	$^\circ\text{C}$
-----------	--	-------------	------------------

Junction temperature

T_j	max.	125	$^\circ\text{C}$
-------	------	-----	------------------

THERMAL RESISTANCE

From mounting base to heatsink;
with heatsink compound

$R_{th\ mb-h}$	=	0.3	K/W
----------------	---	-----	-----

From junction to mounting base

$R_{th\ j-mb}$	=	2	K/W
----------------	---	---	-----

ISOLATION*

R.M.S. isolation voltage

V_{isol}	min.	2500	V
------------	------	------	---

*From baseplate to terminals strapped together.

CHARACTERISTICS

Forward voltage

$$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 2.45 \text{ V}^*$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C}$$

$$I_R < 1.2 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

recovered charge

$$Q_s < 2.0 \text{ } \mu\text{C}$$

recovery time

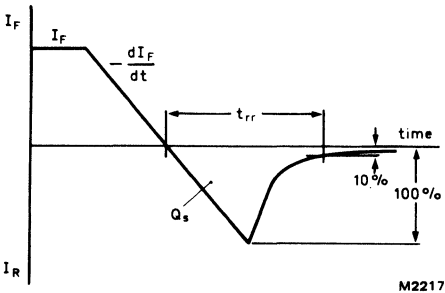
$$t_{rr} < 0.6 \text{ } \mu\text{s}$$

Forward recovery when switched to

$$I_F = 5 \text{ A with } t_r = 0.1 \text{ } \mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

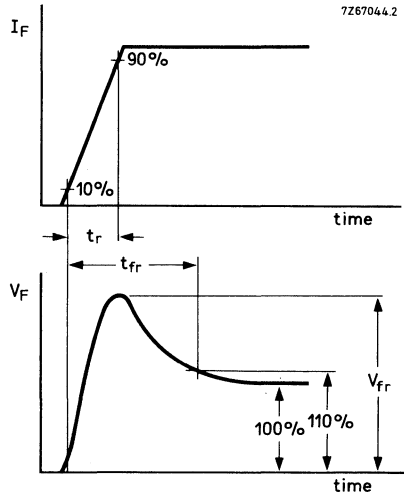
recovery time

$$t_{fr} < 1.0 \text{ } \mu\text{s}$$



M2217

Fig.2 Definition of t_{rr} and Q_s .



7267044.2

Fig.3 Definition of t_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

SINUSOIDAL OPERATION

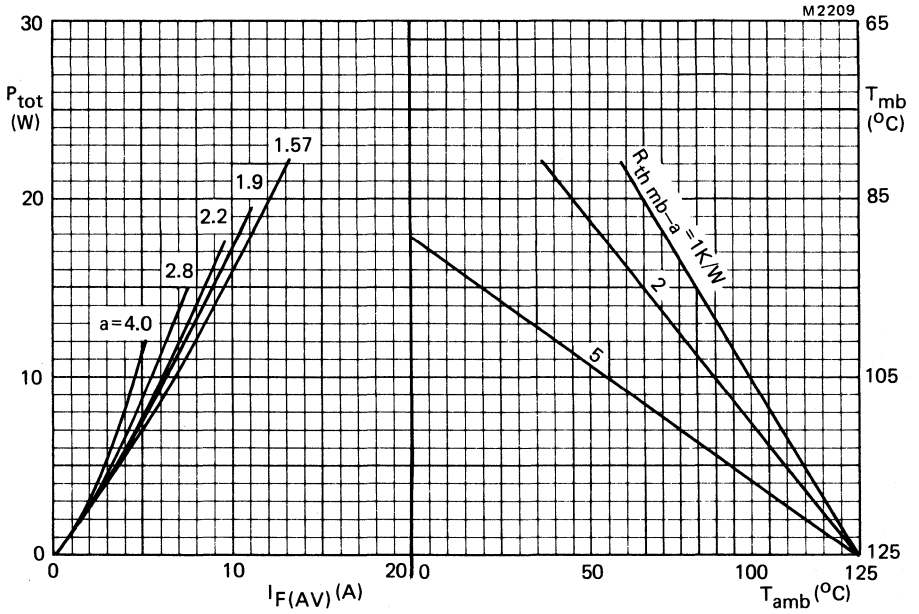


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.
 P = power including reverse current losses but excluding switching losses.
 a = form factor = $I_F(RMS)/I_F(AV)$.

SQUARE-WAVE OPERATION

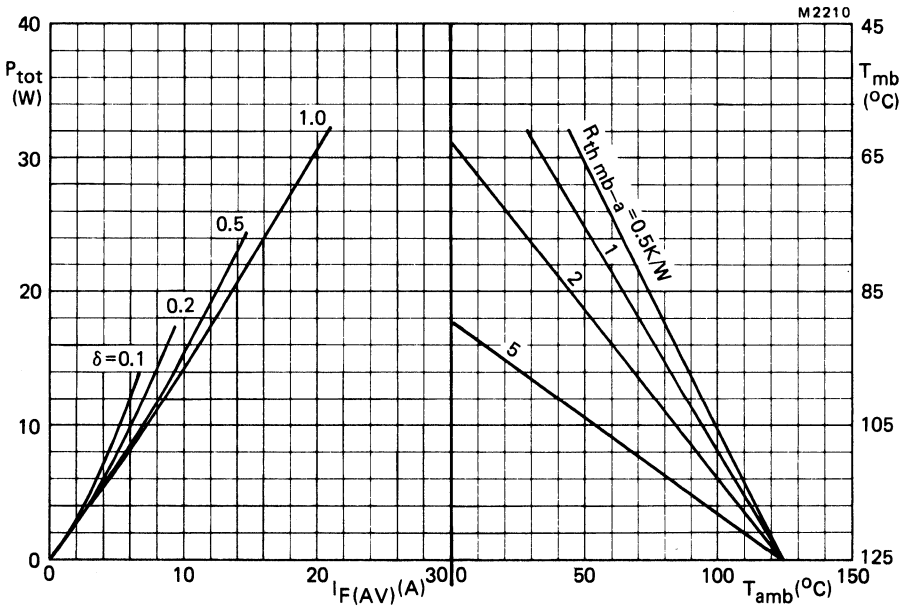
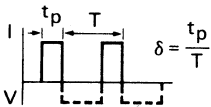


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses but excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

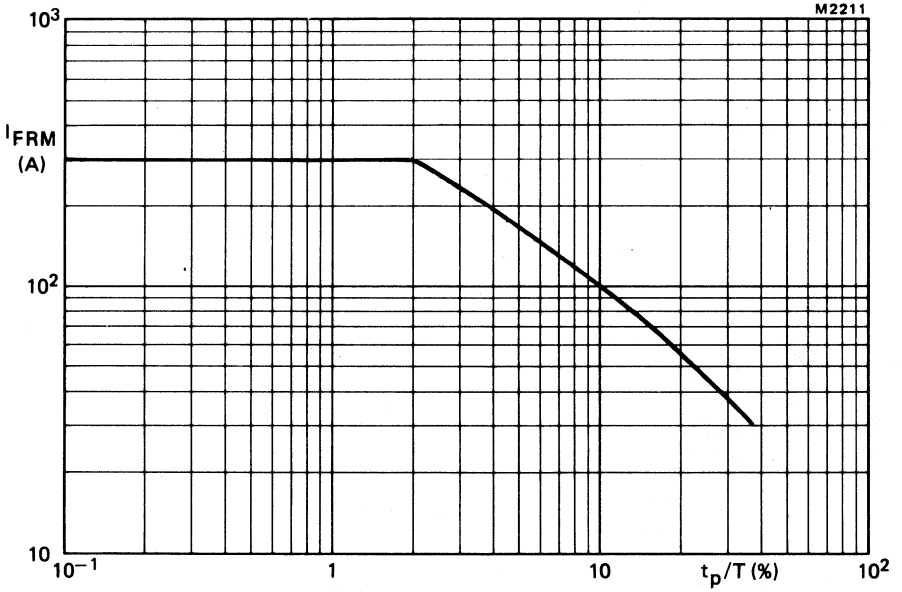


Fig.6 Maximum permissible repetitive peak forward current based on sinusoidal currents; $1 \mu s < t_p < 1$ ms.

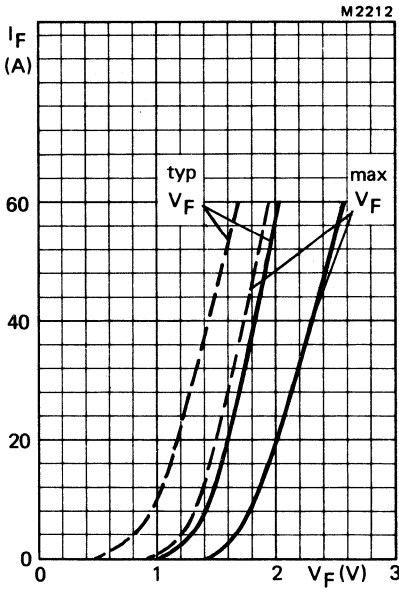


Fig.7 ——— $T_j = 25^\circ C$; - - - - $T_j = 100^\circ C$.

M1048

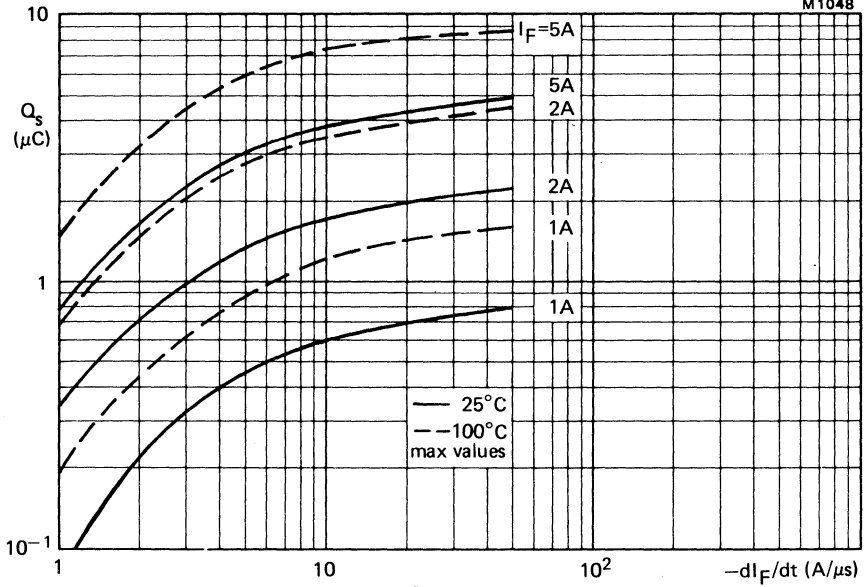


Fig.8

M1049

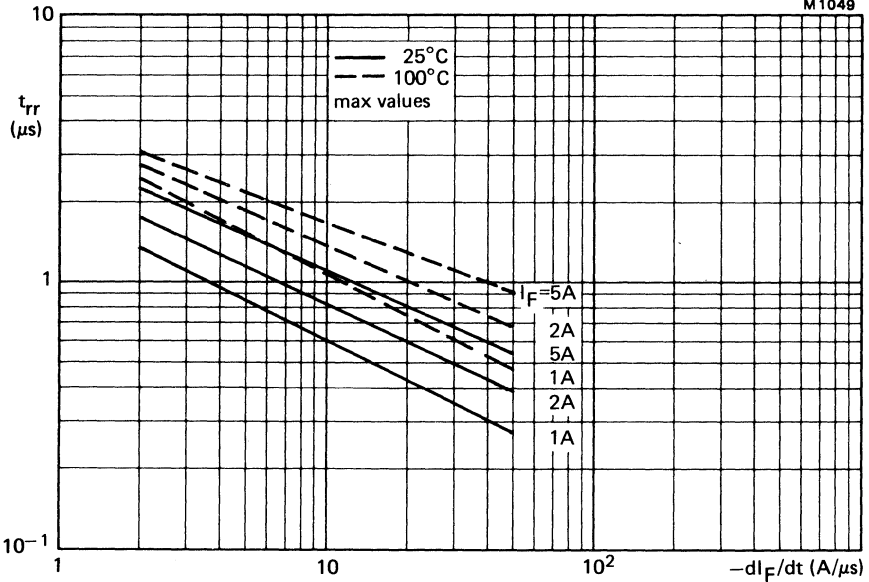


Fig.9

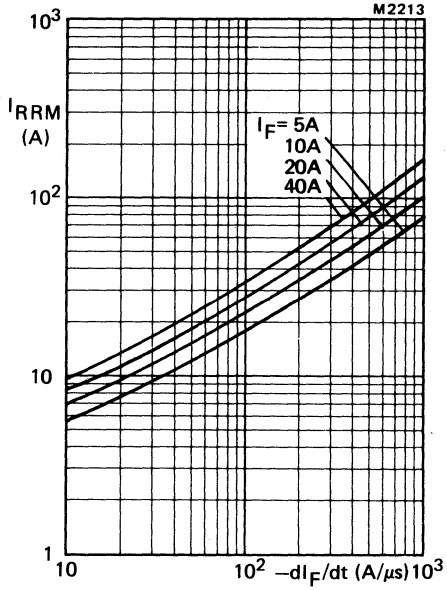


Fig.10

ULTRA FAST RECOVERY DOUBLE RECTIFIER DIODES

Glass-passivated, high-efficiency double rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse-recovery times and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. Their single chip (monolithic) construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without the need for derating. The series consists of common-cathode types.

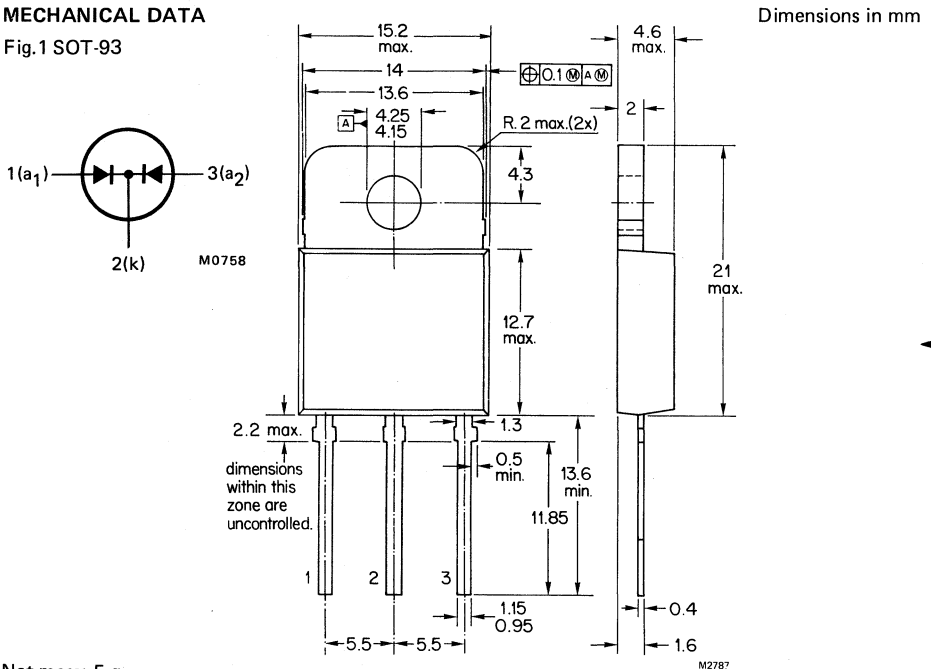
QUICK REFERENCE DATA

Per diode, unless otherwise stated

		BYV72-50				
		100	150	200		
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Output current (both diodes conducting)	I_O	max. 30				A
Forward voltage	V_F	< 0.85				V
Reverse recovery time	t_{rr}	< 28				ns

MECHANICAL DATA

Fig.1 SOT-93



Net mass: 5 g

Note: the exposed metal mounting base is directly connected to the common cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for SOT-93 envelopes.

BYV72 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)		BYV72-50	100	150	200
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200 V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200 V
Continuous reverse voltage	V_R	max. 50	100	150	200 V

→ **Currents** (both diodes conducting; note 1)

Output current; switching losses negligible up to 500 kHz; square wave; $\delta = 0.5$; up to $T_{mb} = 104^\circ\text{C}$ (note 2)	I_O	max.	30	A
R.M.S. forward current (note 2)	$I_F(\text{RMS})$	max.	43	A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$ (per diode)	I_{FRM}	max.	320	A
Non-repetitive peak forward current (per diode) half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max	I_{FSM}	max.	150	A
$t = 10 \text{ ms}$	I_{FSM}	max.	160	A
$t = 8.3 \text{ ms}$	I_{FSM}	max.	160	A
$I^2 t$ for fusing ($t = 10 \text{ ms}$; per diode)	$I^2 t$	max.	112	A^2s

Temperatures				
Storage temperature	T_{stg}		-40 to +150	$^\circ\text{C}$
Junction temperature	T_j	max.	150	$^\circ\text{C}$

Notes:

1. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
2. For output currents in excess of 20 A, connection should be made to the exposed metal mounting base.

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated

Forward voltage

$I_F = 10\text{ A}; T_j = 100\text{ }^\circ\text{C}$

$I_F = 30\text{ A}$

V_F	<	0.85	V*
V_F	<	1.15	V*

Reverse current

$V_R = V_{RWM\text{ max}}; T_j = 100\text{ }^\circ\text{C}$

$V_R = V_{RWM\text{ max}}$

I_R	<	1.0	mA
I_R	<	25	μA

Reverse recovery when switched from

$I_R = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$;
recovery time

t_{rr}	<	28	ns ←
----------	---	----	------

$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$;
recovered charge

Q_s	<	15	nC
-------	---	----	----

$I_F = 10\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$;
 $T_j = 100\text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	2.4	A ←
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Forward recovery when switched to $I_F = 1\text{ A}$
with $dI_F/dt = 10\text{ A}/\mu\text{s}$

V_{fr}	typ.	1.0	V
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M80-1319/3

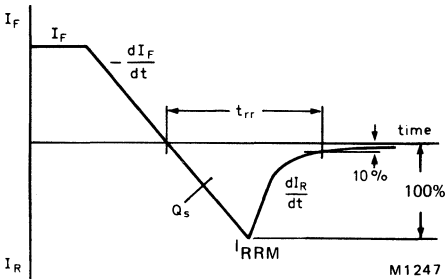


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

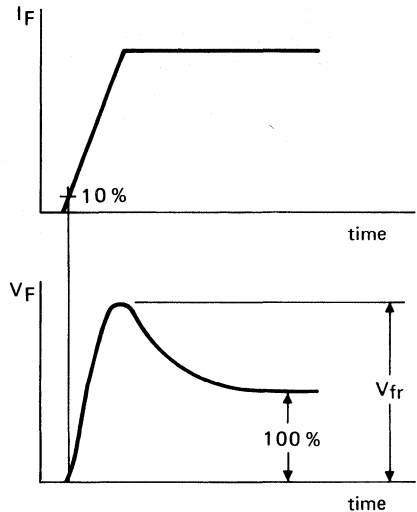


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

→ THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)	$R_{th\ j-mb}$	=	1.4	K/W
From junction to mounting base (per diode)	$R_{th\ j-mb}$	=	2.4	K/W

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound	$R_{th\ mb-h}$	=	0.2	K/W
b. with heatsink compound and 0.06 mm maximum mica insulator (56378)	$R_{th\ mb-h}$	=	1.4	K/W
c. with heatsink compound and 0.1 mm maximum mica insulator	$R_{th\ mb-h}$	=	2.2	K/W
d. with heatsink compound and 0.25 mm maximum alumina insulator	$R_{th\ mb-h}$	=	0.8	K/W
e. without heatsink compound	$R_{th\ mb-h}$	=	1.4	K/W

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$R_{th\ j-a}$	=	60	K/W
---------------	---	----	-----

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M4 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

The various components of junction temperature rise above ambient are illustrated in Fig.4

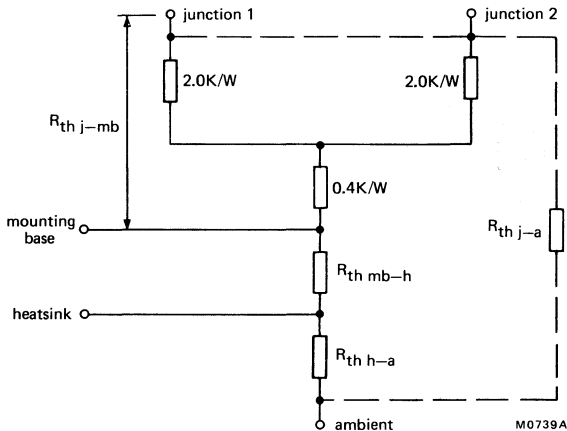


Fig.4

Any measurement of heatsink temperature should be made immediately adjacent to the device.

SQUARE-WAVE OPERATION (BOTH DIODES)

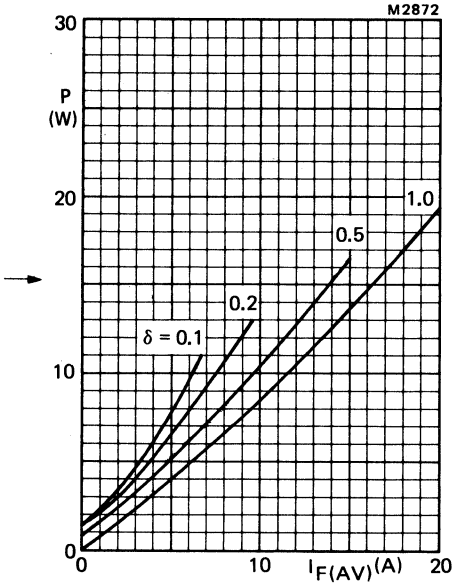
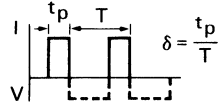


Fig.5 Power rating per diode. The individual power loss in each diode should first be determined then both added together. The resulting total power loss is then used in conjunction with Fig.6 to determine the heatsink size and corresponding maximum ambient and mounting base temperatures.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

Power includes reverse current losses and switching losses up to $f = 500$ kHz

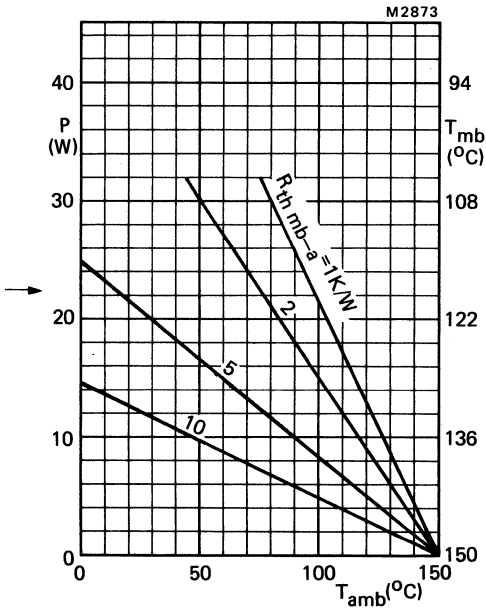


Fig.6

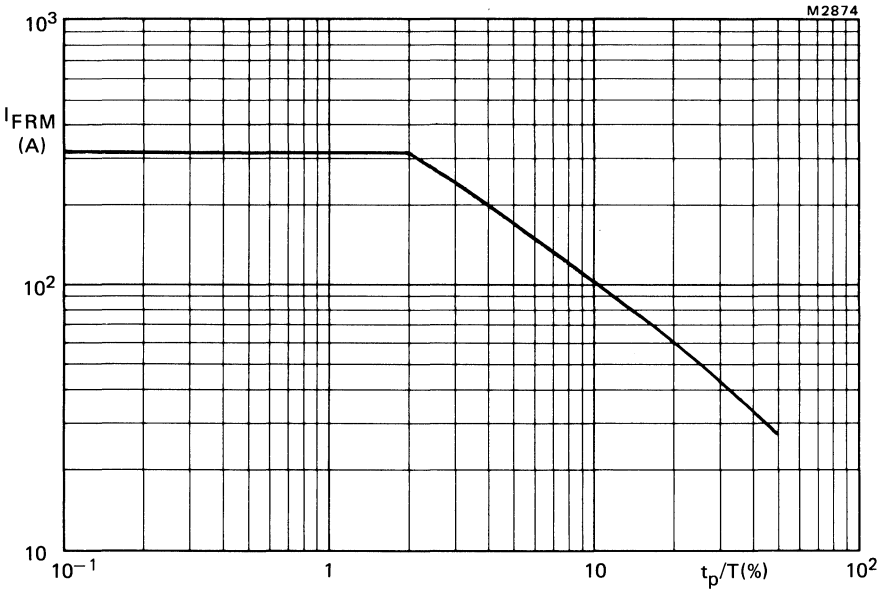
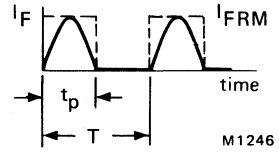
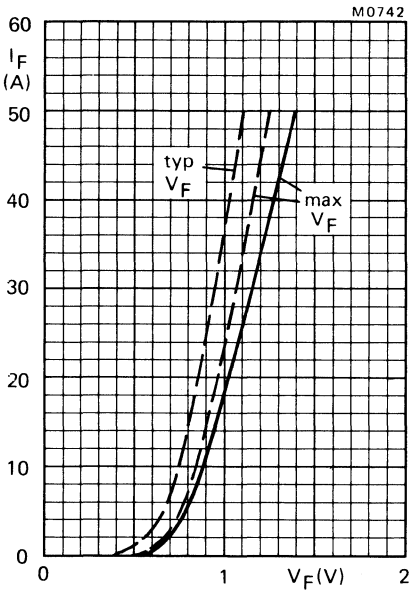


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 ms$; per diode.



Defintion of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25^\circ C$; - - - $T_j = 100^\circ C$. per diode.

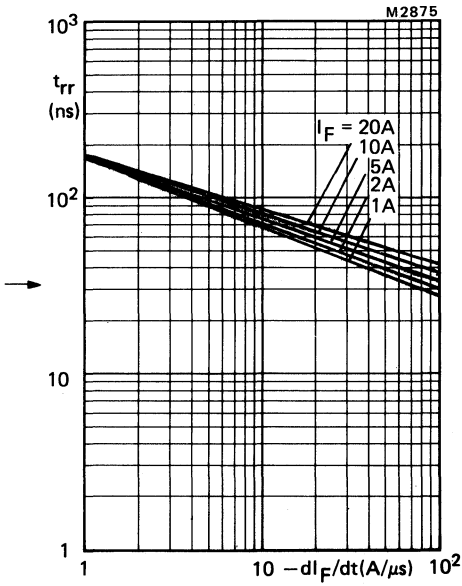


Fig.9 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$; per diode.

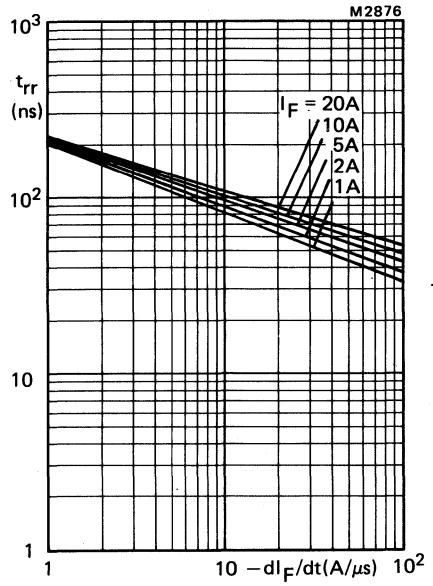


Fig.10 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$; per diode.

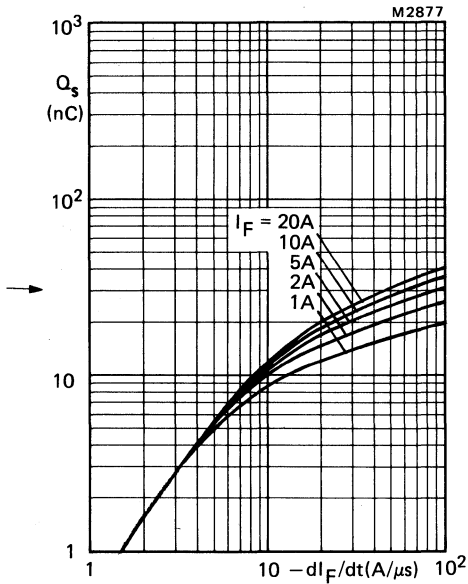


Fig.11 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$; per diode.

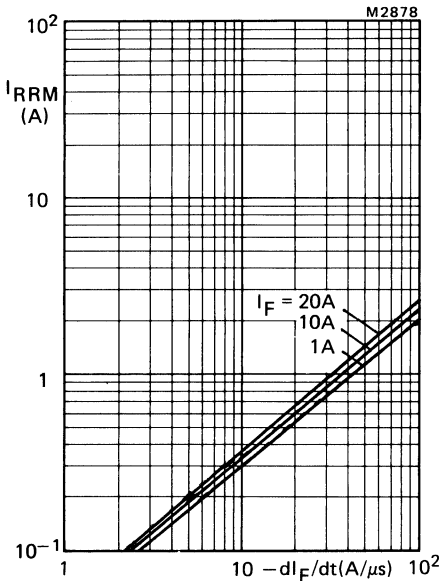


Fig.12 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$; per diode.

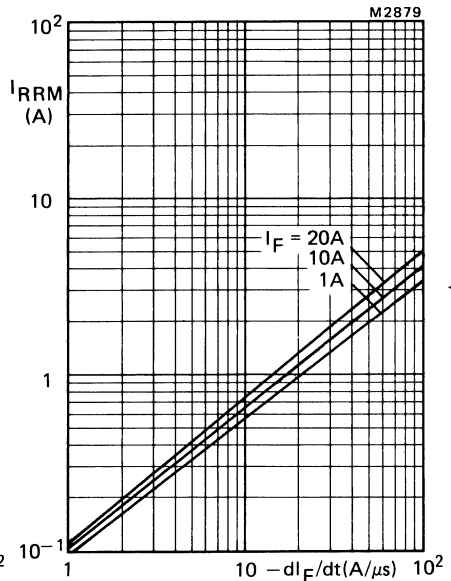


Fig.13 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$; per diode.

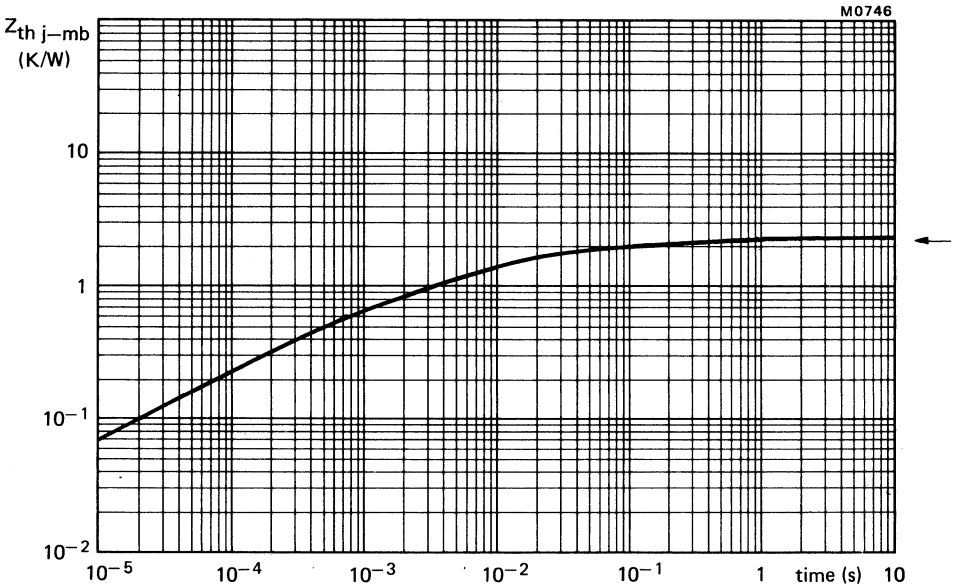


Fig.14 Transient thermal impedance; one diode conducting.

ULTRA FAST RECOVERY DOUBLE RECTIFIER DIODES

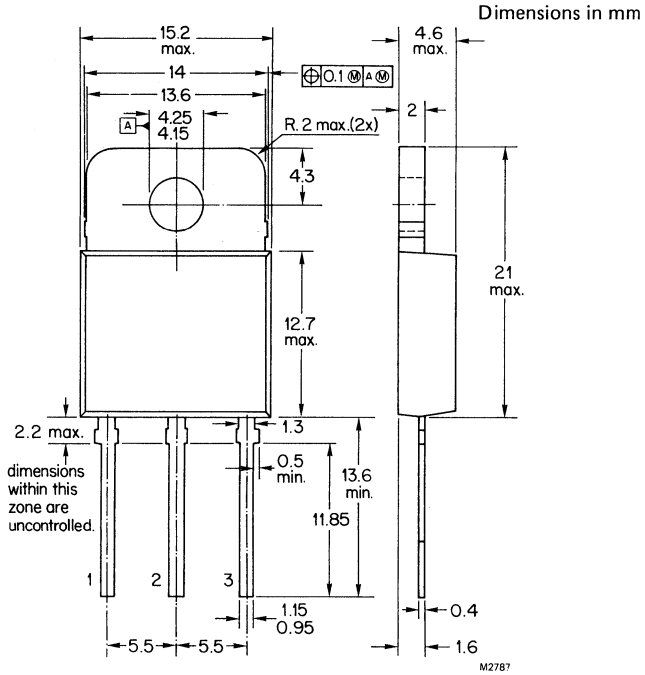
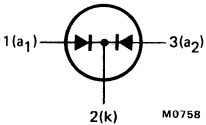
Glass-passivated, high-efficiency epitaxial double rectifier diodes in plastic envelopes which feature low forward voltage drop, very fast reverse recovery times and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where low conduction losses and switching losses are essential. Their single chip construction ensures excellent matching of the forward and switching characteristics of the two halves, allowing parallel operation without derating. The series consists of common-cathode types.

QUICK REFERENCE DATA

Per diode, unless otherwise stated		BYV74-300	400	500	V
Repetitive peak reverse voltage	V_{RRM}	max. 300	400	500	V
Output current (both diodes conducting)	I_O	max.	30		A
Forward voltage	V_F	<	1.05		V
Reverse recovery time	t_{rr}	<	50		ns

MECHANICAL DATA

Fig. 1 SOT-93



Net mass: 5 g

Note: the exposed metal mounting base is directly connected to the common-cathode.
 Accessories supplied on request: see data sheets Mounting instructions and accessories for SOT-93 envelopes.

BYV74 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)		BYV74-300	400	500	
Repetitive peak reverse voltage	V_{RRM}	max. 300	400	500	V
Crest working reverse voltage	V_{RWM}	max. 200	300	400	V
Continuous reverse voltage (note 1)	V_R	max. 200	300	400	V
Currents (both diodes conducting; note 2)					
Output current (note 3)					
square wave; $\delta = 0.5$; up to $T_{mb} = 92^\circ\text{C}$	I_O	max.	30		A
sinusoidal; up to $T_{mb} = 103^\circ\text{C}$	I_O	max.	26		A
R.M.S. forward current	$I_F(\text{RMS})$	max.	30		A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$ (note 4)	I_{FRM}	max.	320		A
Non-repetitive peak forward current					
half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max (note 4)					
$t = 10 \text{ ms}$	I_{FSM}	max.	130		A
$t = 8.3 \text{ ms}$	I_{FSM}	max.	140		A
$I^2 t$ for fusing ($t = 10 \text{ ms}$; note 4)	$I^2 t$	max.	84		A^2s
Temperatures					
Storage temperature	T_{stg}		-40 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.	150		$^\circ\text{C}$

Notes:

1. To ensure thermal stability: $R_{th j-a} < 9.3 \text{ K/W}$.
2. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
3. For output currents in excess of 20 A, connection should be made to the exposed metal mounting base.
4. Figures apply to each diode.

CHARACTERISTICS (per diode)

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated

Forward voltage

$I_F = 15\text{ A}; T_j = 150\text{ }^\circ\text{C}$

$I_F = 50\text{ A}$

V_F	<	1.05	V*
V_F	<	1.6	V*

Reverse current

$V_R = V_{RWM\text{ max}}; T_j = 100\text{ }^\circ\text{C}$

$V_R = V_{RWM\text{ max}}$

I_R	<	0.8	mA
I_R	<	50	μA

Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$;
recovery time

$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$;
recovered charge

$I_F = 10\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$;
 $T_j = 100\text{ }^\circ\text{C}$; peak recovery current

t_{rr}	<	50	ns
----------	---	----	----

Q_s	<	50	nC
-------	---	----	----

I_{RRM}	<	5.2	A
-----------	---	-----	---

Forward recovery when switched to $I_F = 10\text{ A}$

with $dI_F/dt = 10\text{ A}/\mu\text{s}$

recovery voltage

V_{fr}	typ.	2.5	V
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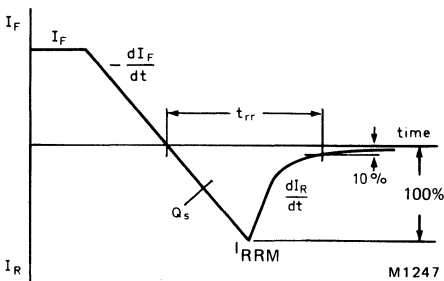


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

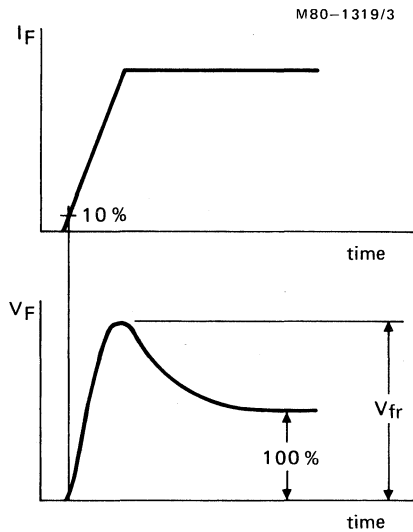


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base; total package	$R_{th\ j-mb}$	=	1.4	K/W
per diode	$R_{th\ j-mb}$	=	2.0	K/W

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound	$R_{th\ mb-h}$	=	0.2	K/W
b. with heatsink compound and 0.06 mm maximum mica insulator (56378)	$R_{th\ mb-h}$	=	1.4	K/W
c. without heatsink compound	$R_{th\ mb-h}$	=	1.4	K/W

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$R_{th\ j-a}$	=	60	K/W
---------------	---	----	-----

MOUNTING INSTRUCTIONS

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275°C ; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
- Mounting by means of a spring clip is the best mounting method because it offers:
 - a good thermal contact under the crystal area and slightly lower $R_{\text{th mb-h}}$ values than does screw mounting.
 - safe isolation for mains operation.
 However, if a screw is used, it should be M4 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{\text{th mb-h}}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
- Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

- The various components of junction temperature rise above ambient are illustrated in Fig.4.

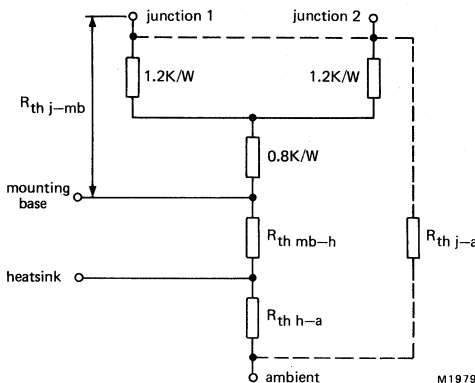


Fig. 4.

- Any measurement of heatsink temperature should be made immediately adjacent to the device.
- The method of using Figs. 5 and 6 is as follows:
Starting with the required current on the $I_F(\text{AV})$ axis, trace upwards to meet the appropriate duty cycle or form factor curve. Trace right horizontally and upwards from the required value on the T_{amb} scale. The intersection determines the $R_{\text{th mb-a}}$. The heatsink thermal resistance value ($R_{\text{th h-a}}$) can be calculated from:

$$R_{\text{th h-a}} = R_{\text{th mb-a}} - R_{\text{th mb-h}}$$

SQUARE-WAVE OPERATION

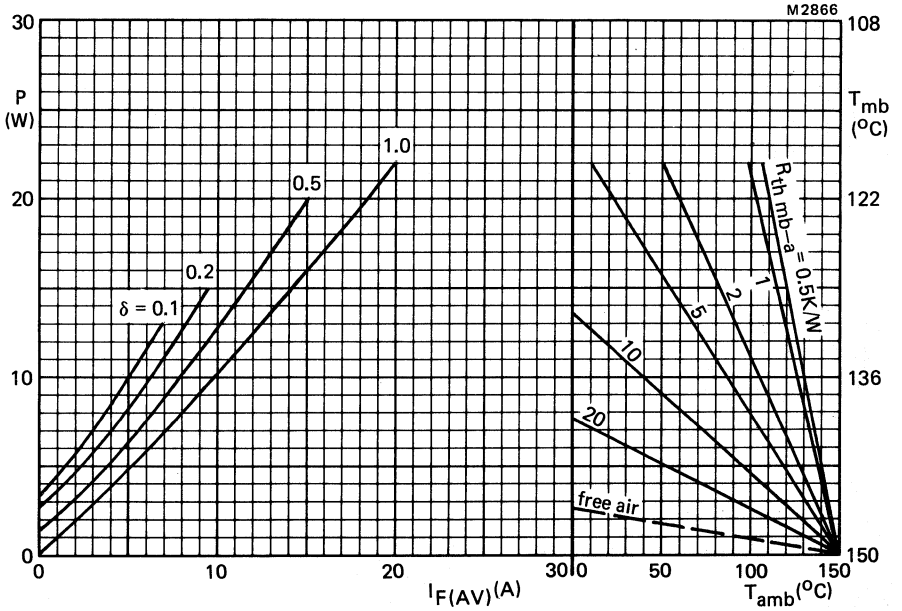
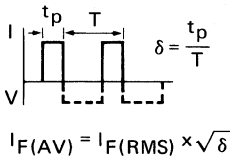


Fig.5 The right-hand part shows the relationship between the power (derived from the left-hand part) and the maximum permissible temperatures (per diode).



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

SINUSOIDAL OPERATION

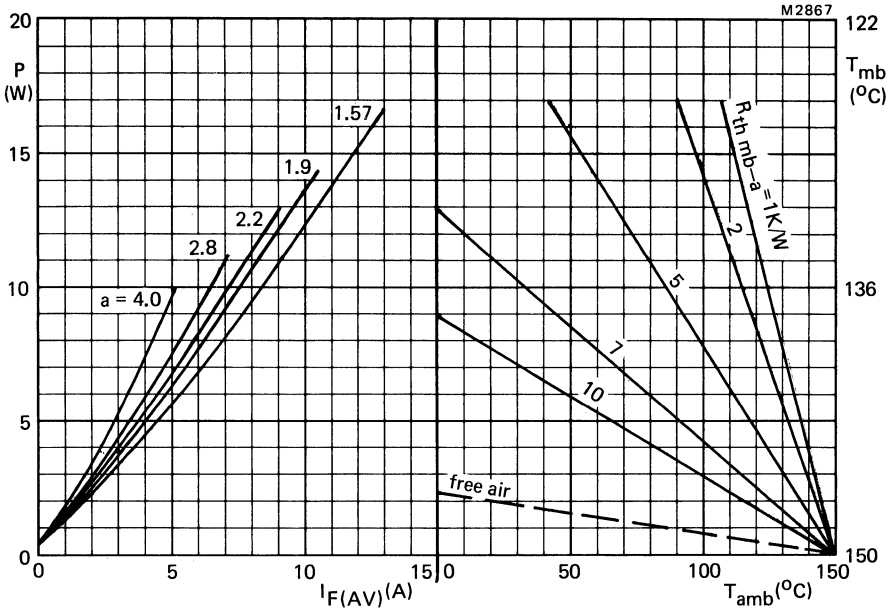


Fig.6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures (per diode).

a = form factor = $I_{F(RMS)}/I_{F(AV)}$.

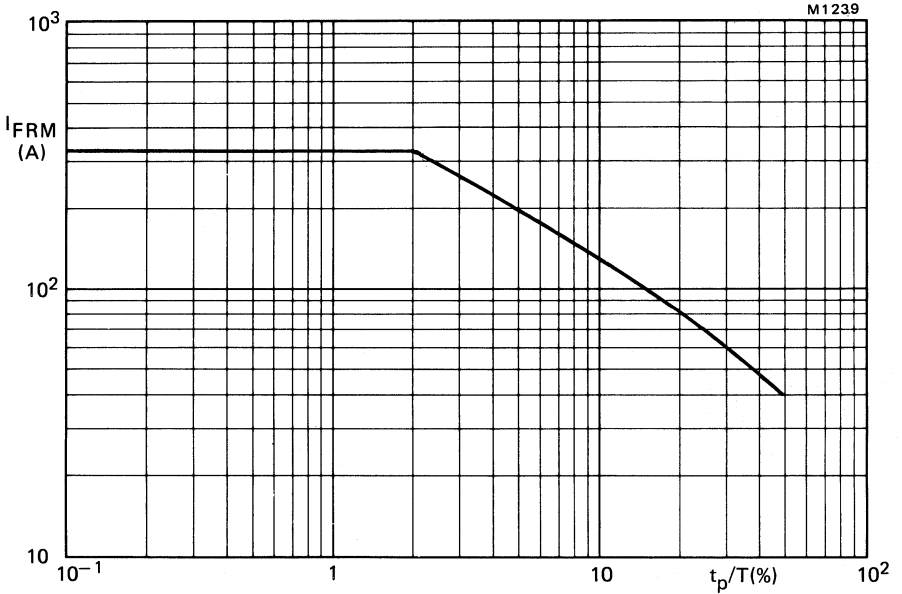
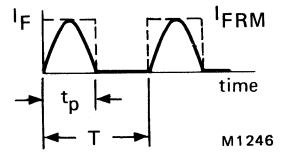
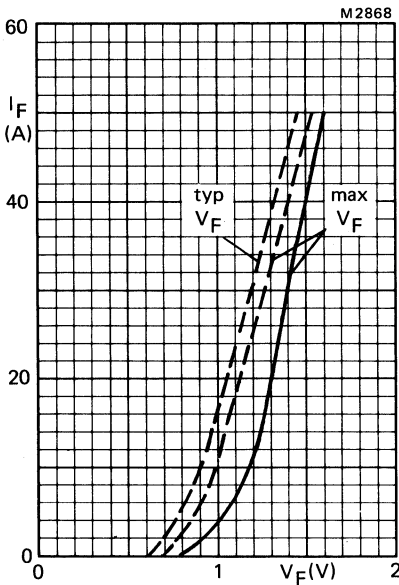


Fig.7 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$ (per diode).



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25^\circ\text{C}$; --- $T_j = 150^\circ\text{C}$ (per diode).

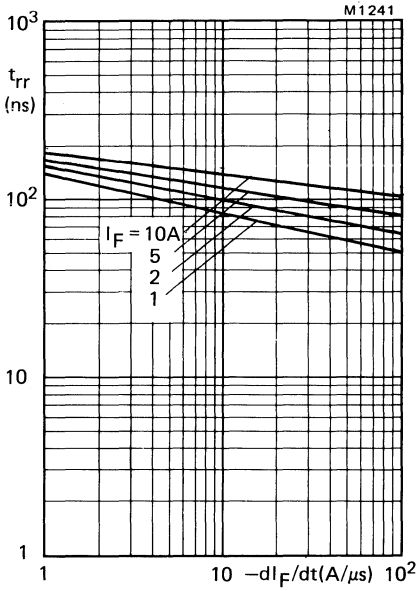


Fig.9 Maximum t_{rr} at $T_j = 25$ °C. (per diode).

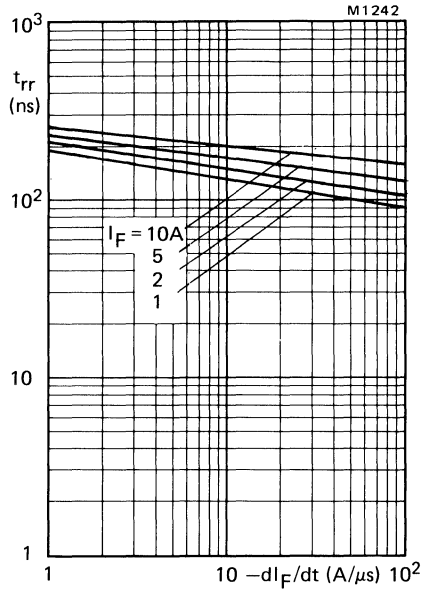


Fig.10 Maximum t_{rr} at $T_j = 100$ °C. (per diode).

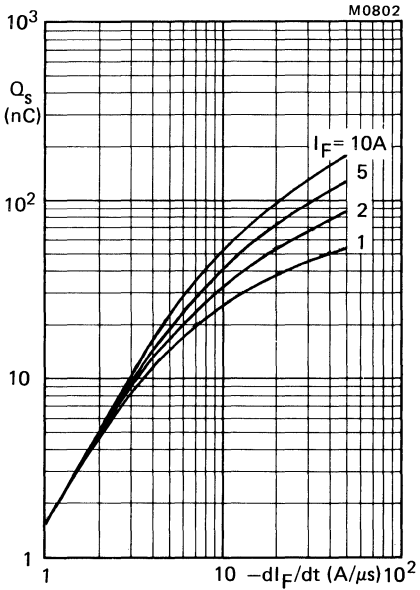


Fig.11 Maximum Q_s at $T_j = 25$ °C. (per diode).

ULTRA FAST RECOVERY RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. The series consists of normal polarity (cathode to mounting base) types.

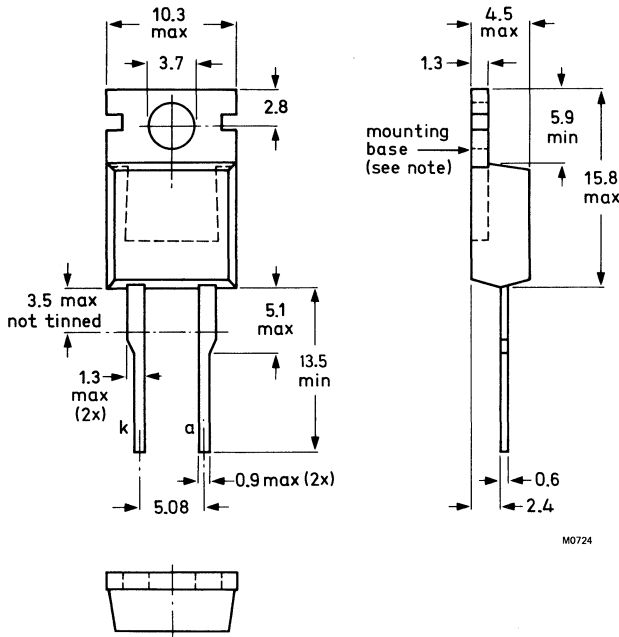
QUICK REFERENCE DATA

		BYV79-50				100	150	200
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200	V	
Average forward current	$I_{F(AV)}$	max.			14	A		
Forward voltage	V_F	<			0.85	V		
Reverse recovery time	t_{rr}	<			30	ns		←

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AC



M0724

Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

BYV79 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

		BYV79-50				
		50	100	150	200	
Voltages						
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage (note 1)	V_R	max. 50	100	150	200	V
Currents						
Average forward current; switching losses negligible up to 500 kHz; square wave; $\delta = 0.5$; up to $T_{mb} = 115^\circ\text{C}$ sinusoidal; up to $T_{mb} = 122^\circ\text{C}$						
	$I_F(AV)$	max.		14		A
	$I_F(AV)$	max.		12		A
R.M.S. forward current	$I_F(RMS)$	max.		20		A
→ Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.		420		A
→ Non-repetitive peak forward current half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max $t = 10 \text{ ms}$ $t = 8.3 \text{ ms}$	I_{FSM}	max.		180		A
	I_{FSM}	max.		200		A
→ $I^2 t$ for fusing ($t = 10 \text{ ms}$)	$I^2 t$	max.		160		A^2s
Temperatures						
Storage temperature	T_{stg}			-40 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.		150		$^\circ\text{C}$

Notes:

1. To ensure thermal stability: $R_{th j-a} \leq 8 \text{ K/W}$.

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated

Forward voltage

$I_F = 10\text{ A}; T_j = 100\text{ }^\circ\text{C}$

$I_F = 50\text{ A}$

V_F	<	0.85	V*
V_F	<	1.3	V*

Reverse current

$V_R = V_{RWM\text{ max}}; T_j = 100\text{ }^\circ\text{C}$

$V_R = V_{RWM\text{ max}}$

I_R	<	1.3	mA
I_R	<	50	μA ←

Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$;
recovery time

t_{rr}	<	30	ns ←
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$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$;
recovered charge

Q_s	<	15	nC
-------	---	----	----

$I_F = 10\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$;
 $T_j = 100\text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	4	A ←
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Forward recovery when switched to $I_F = 10\text{ A}$
with $dI_F/dt = 10\text{ A}/\mu\text{s}$

V_{fr}	typ.	1.0	V
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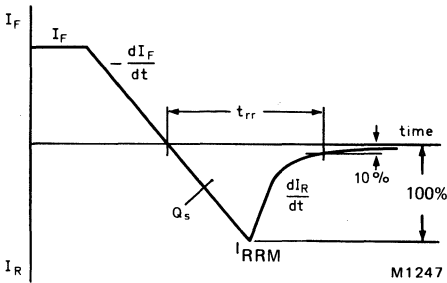


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

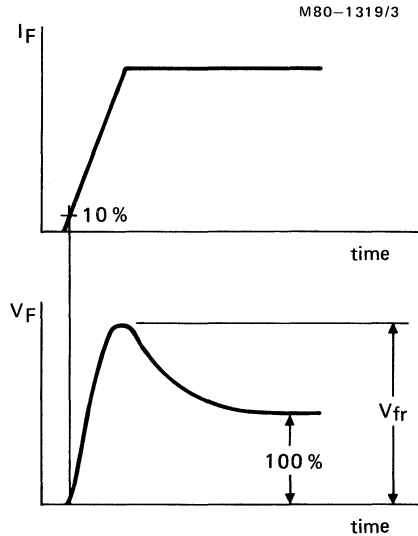


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 2 \text{ K/W}$$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275°C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
 Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

- a. The various components of junction temperature rise above ambient are illustrated in Fig.4.

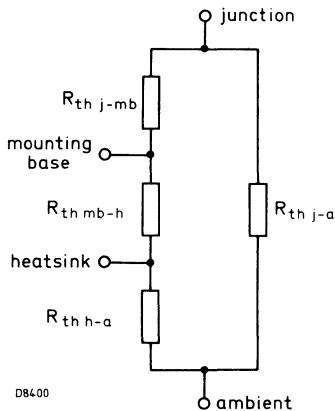


Fig. 4.

- b. Any measurement of heatsink temperature should be made immediately adjacent to the device.
- c. The method of using Figs. 5 and 6 is as follows:
 Starting with the required current on the $I_F(\Delta V)$ axis, trace upwards to meet the appropriate duty cycle or form factor curve. Trace right horizontally and upwards from the required value on the T_{amb} scale. The intersection determines the $R_{th\ mb-a}$. The heatsink thermal resistance value ($R_{th\ h-a}$) can be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

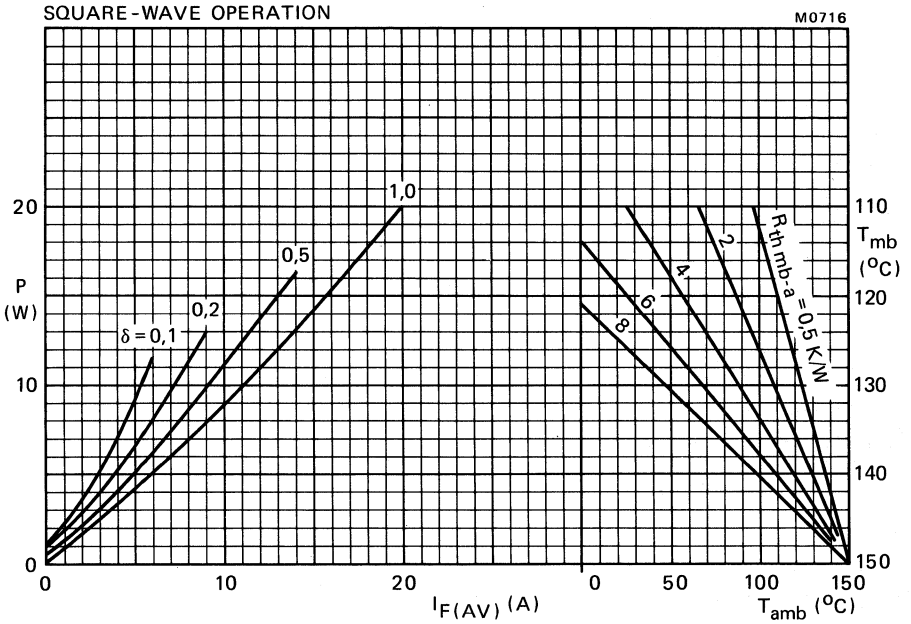
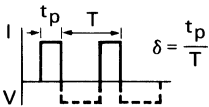


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.
 P = power including reverse current losses and switching losses up to $f = 500$ kHz.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

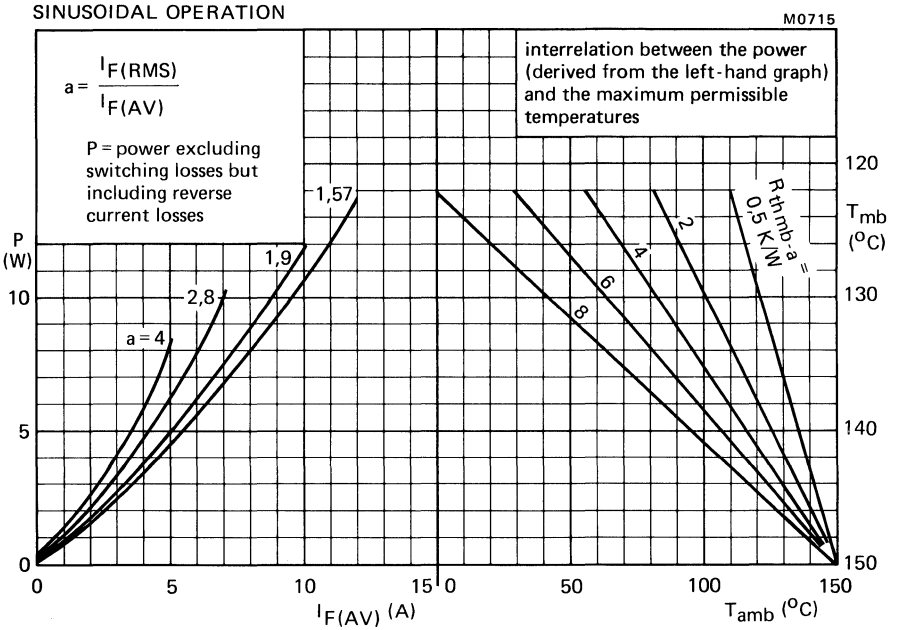


Fig.6

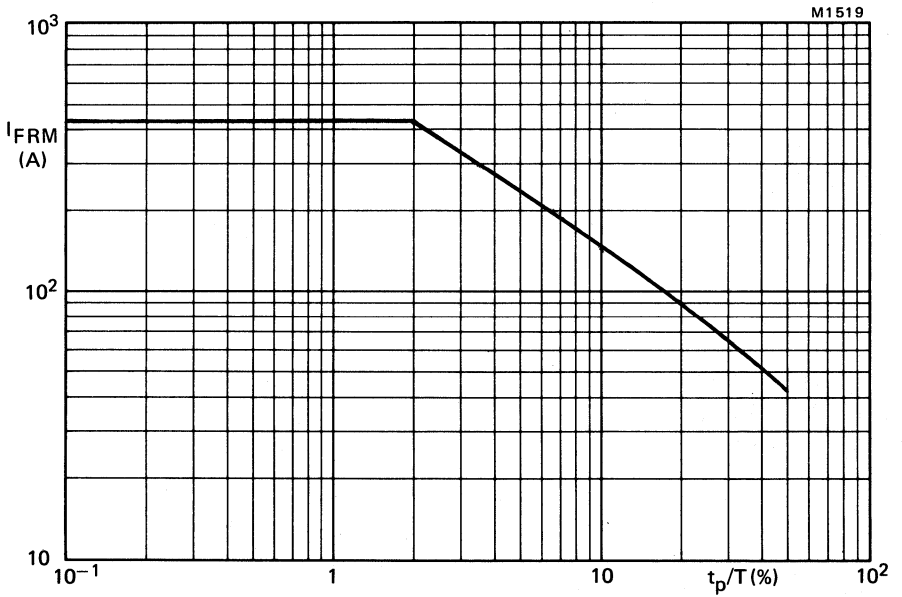
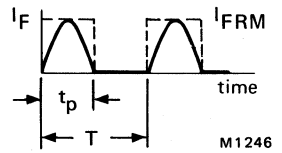
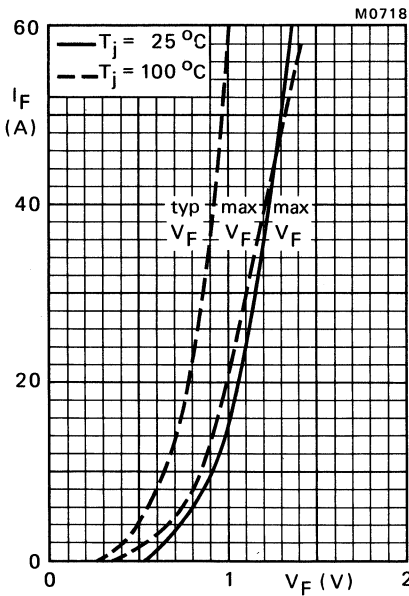


Fig.7 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 ms$.



Definition of I_{FRM} and t_p/T .

Fig.8.

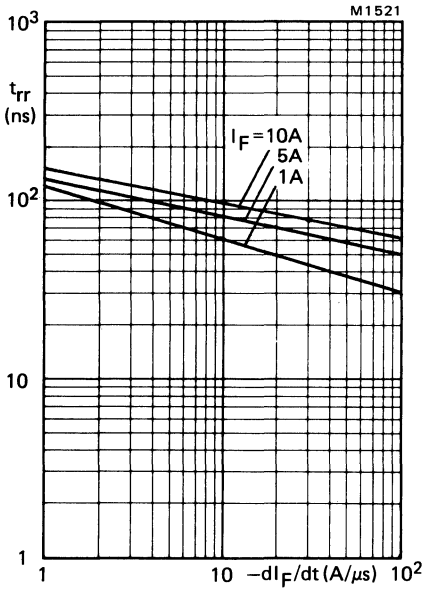


Fig.9 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

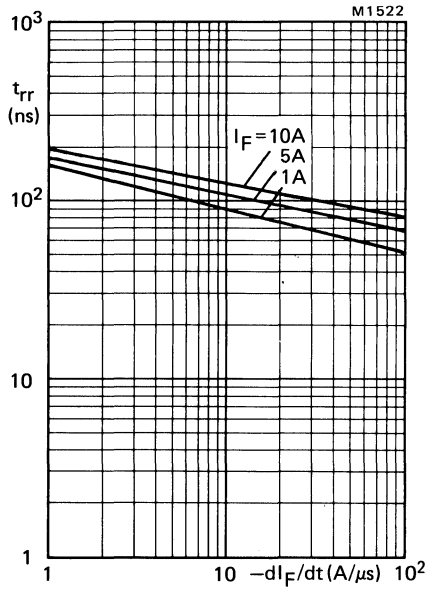


Fig.10 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

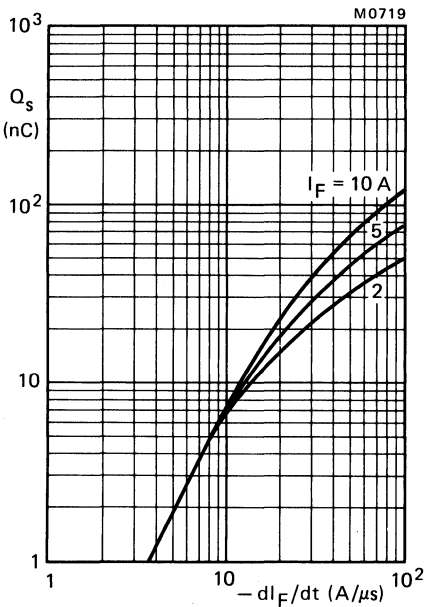


Fig.11 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

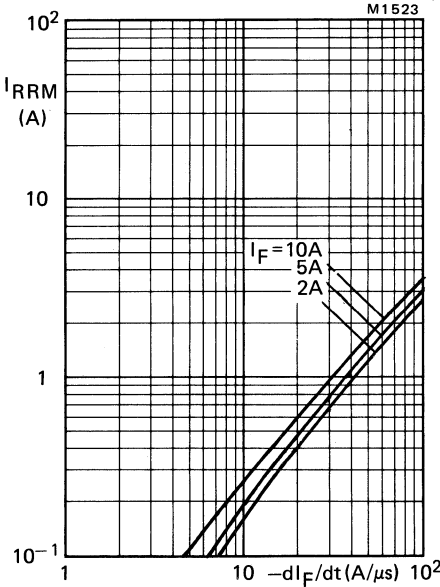


Fig.12 Maximum I_{RRM} at $T_j = 25$ °C.

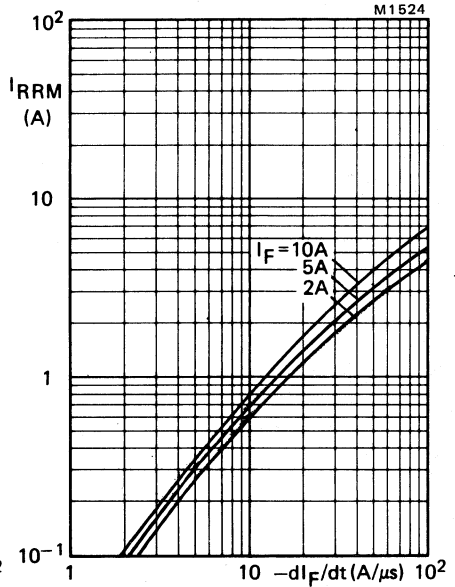


Fig.13 Maximum I_{RRM} at $T_j = 100$ °C.

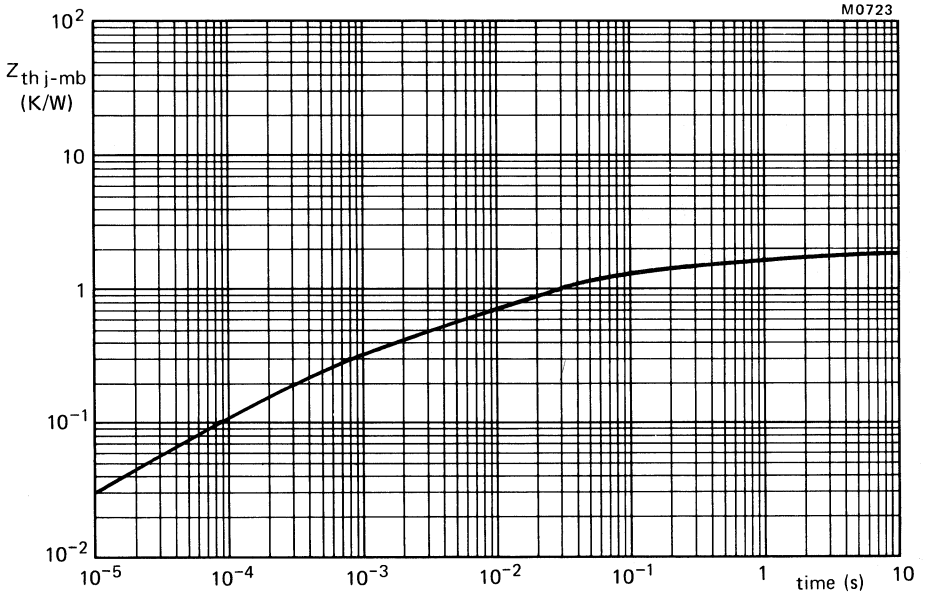


Fig.14 Transient thermal impedance.

ULTRA FAST RECOVERY RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in DO-5 metal envelopes, featuring low forward voltage drop, ultra fast reverse recovery times, very low stored charge and soft recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction and low switching losses are essential.

The series consists of normal polarity (cathode to stud) types.

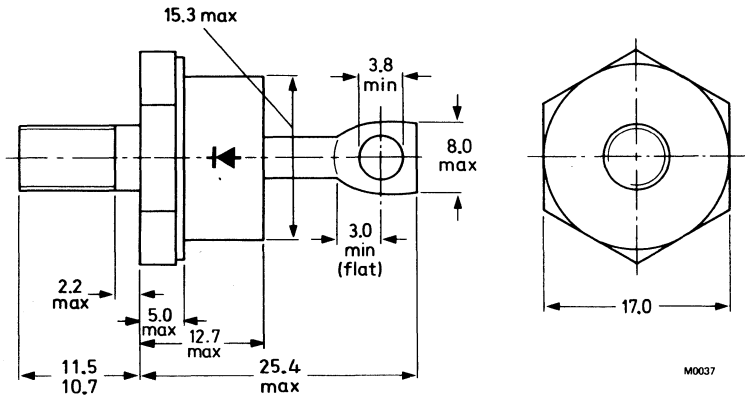
QUICK REFERENCE DATA

		BYV92-300 400 500			
Repetitive peak reverse voltage	V_{RRM}	max. 300	400	500	V
Average forward current	$I_F(AV)$	max.	35		A
Forward voltage	V_F	<	1.05		V
Reverse recovery time	t_{rr}	<	50		ns

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5: with metric M6 stud (ϕ 6 mm); e.g. BYV92-500M;
with $\frac{1}{4}$ in x 28UNF stud (ϕ 6.35 mm), e.g. BYV92-500U.



Net mass: 22 g

Diameter of clearance hole:
max. 6.5 mm

Accessories supplied on request:
56264a (mica washer),
56264b (insulating bush).

Supplied with device:
1 nut, 1 lock washer.

Torque on nut:
min. 1.7 Nm (17 kg cm);
max. 3.5 Nm (35 kg cm).

Nut dimensions across flats:
M6: 10 mm; $\frac{1}{4}$ in x 28UNF: 11.1 mm.

BYV92 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

		BYV92-300	400	500	
→ Voltages					
Repetitive peak reverse voltage	V_{RRM}	max. 300	400	500	V
Crest working reverse voltage	V_{RWM}	max. 200	300	400	V
Continuous reverse voltage*	V_R	max. 200	300	400	V
→ Currents					
Average forward current; switching losses negligible up to 100 kHz					
square wave, $\delta = 0.5$, up to $T_{mb} = 100\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	38		A
up to $T_{mb} = 125\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	21		A
sinusoidal, up to $T_{mb} = 106\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	34		A
up to $T_{mb} = 125\text{ }^\circ\text{C}$	$I_{F(AV)}$	max.	21		A
R.M.S. forward current	$I_{F(RMS)}$	max.	55		A
Repetitive peak forward current					
$t_p = 20\text{ }\mu\text{s}$, $\delta = 0.02$	I_{FRM}	max.	800		A
Non-repetitive peak forward current					
half sine-wave, $T_j = 150\text{ }^\circ\text{C}$ prior to surge					
$t = 10\text{ ms}$	I_{FSM}	max.	500		A
$t = 8.3\text{ ms}$	I_{FSM}	max.	600		A
with reapplied V_{RWM} max					
$t = 10\text{ ms}$	I_{FSM}	max.	350		A
$t = 8.3\text{ ms}$	I_{FSM}	max.	440		A
$I^2 t$ for fusing ($t = 10\text{ ms}$)	$I^2 t$	max.	610		A^2s
Temperatures					
Storage temperature	T_{stg}		-55 to +150		$^\circ\text{C}$
Junction temperature	T_j		150		$^\circ\text{C}$
THERMAL RESISTANCE					
From junction to mounting base	$R_{th\ j-mb}$	=	1.0		K/W
From mounting base to heatsink					
with heatsink compound	$R_{th\ mb-h}$	=	0.3		K/W
without heatsink compound	$R_{th\ mb-h}$	=	0.5		K/W

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it. During soldering the heat conduction to the junction should be kept to a minimum.

*To ensure thermal stability: $R_{th\ j-a} \leq 3.4\text{ K/W}$.

CHARACTERISTICS

Forward voltage

$I_F = 35 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$

$I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.05 \text{ V}^*$

$V_F < 1.4 \text{ V}^*$

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$

$T_j = 25 \text{ }^\circ\text{C}$

$I_R < 2.0 \text{ mA}$

$I_R < 50 \text{ } \mu\text{A}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s};$

$T_j = 25 \text{ }^\circ\text{C}; \text{ recovery time}$

$t_{rr} < 50 \text{ ns}$

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s};$

$T_j = 25 \text{ }^\circ\text{C}; \text{ recovered charge}$

$Q_s < 75 \text{ nC}$

$I_F = 10 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s};$

$T_j = 100 \text{ }^\circ\text{C}; \text{ peak recovery current}$

$I_{RRM} < 4 \text{ A}$

Forward recovery when switched to $I_F = 10 \text{ A}$

with $dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$V_{fr} \text{ typ. } 2.5 \text{ V}$

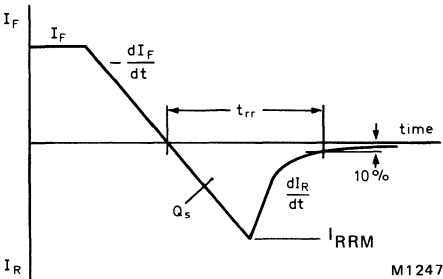


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

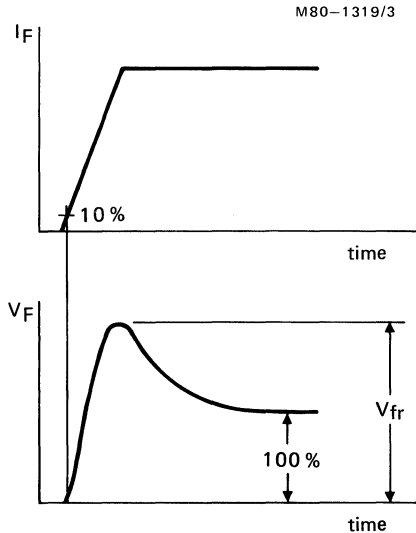


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

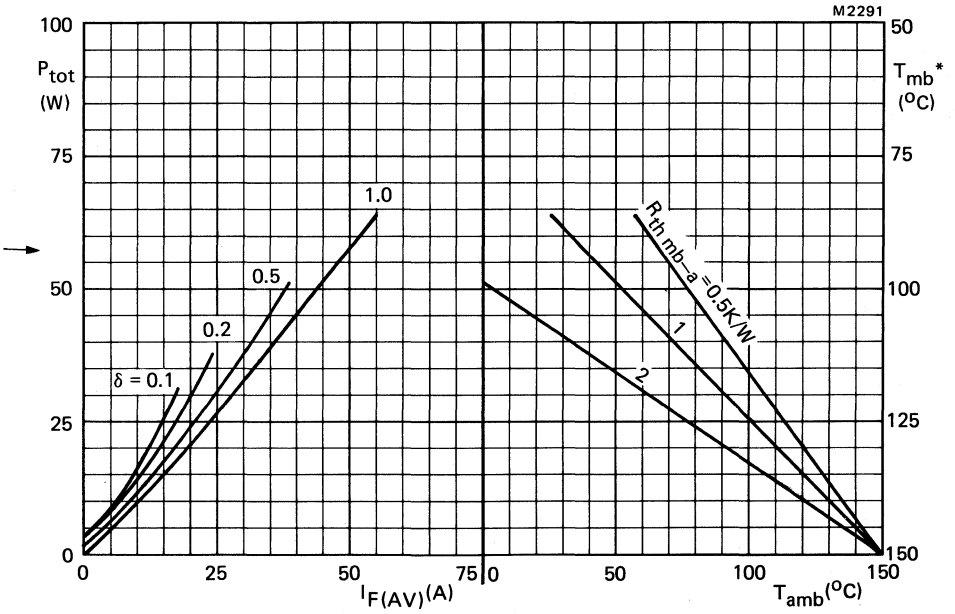
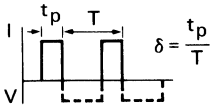


Fig.4 The right-hand part shows the relationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 100$ kHz.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

* T_{mb} scale is for comparison purposes and is correct only for $R_{th mb-a} < 2.4 K/W$.

SINUSOIDAL OPERATION

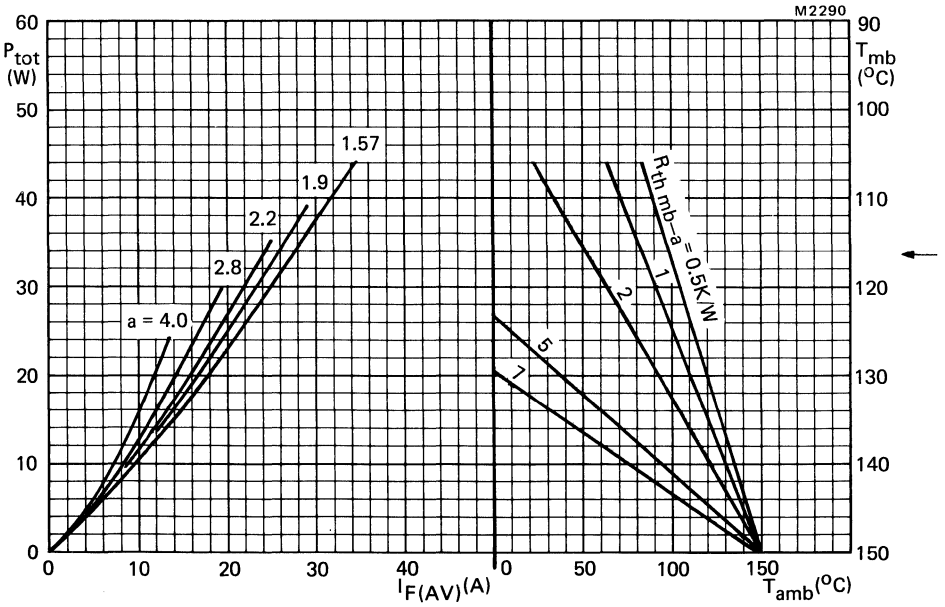


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$a = \text{form factor} = I_F(RMS)/I_F(AV)$.

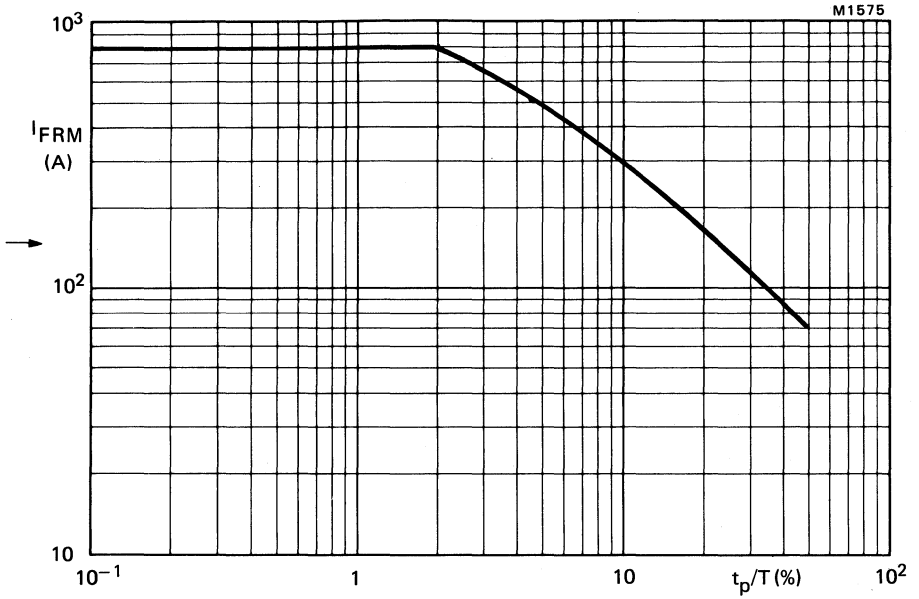
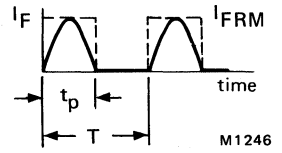
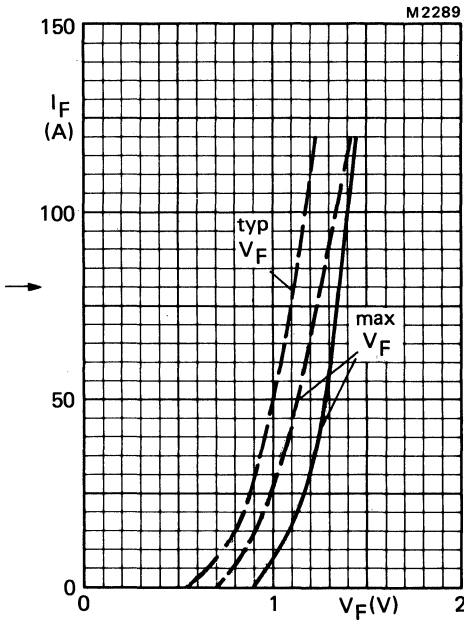


Fig.6 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.7 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$.

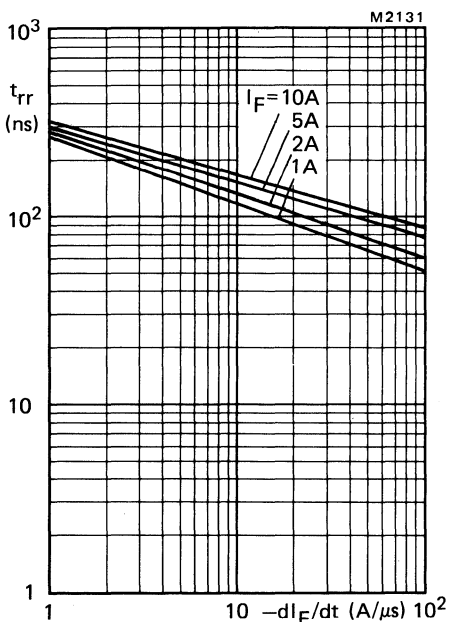


Fig.8 Maximum t_{rr} at $T_j = 25$ °C.

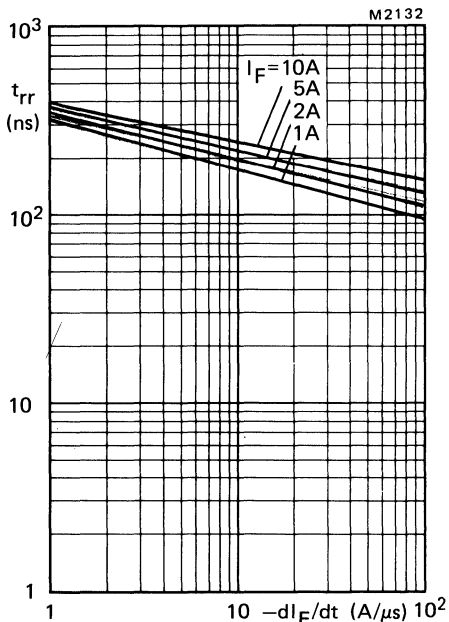


Fig.9 Maximum t_{rr} at $T_j = 100$ °C.

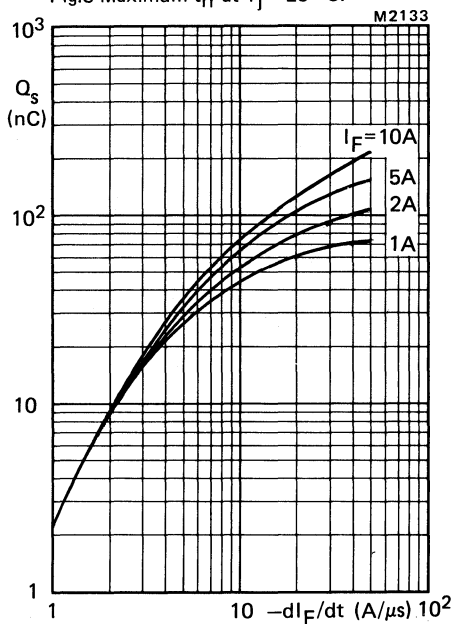


Fig.10 Maximum Q_s at $T_j = 25$ °C.

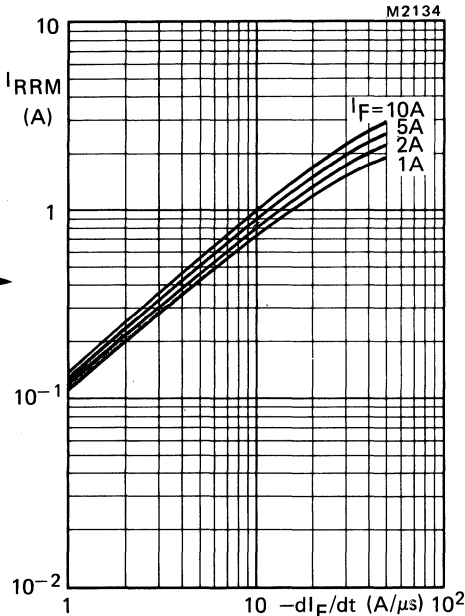


Fig.11 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

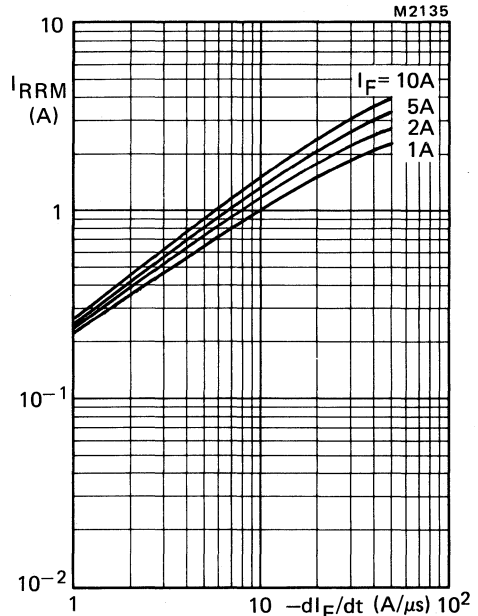


Fig.12 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

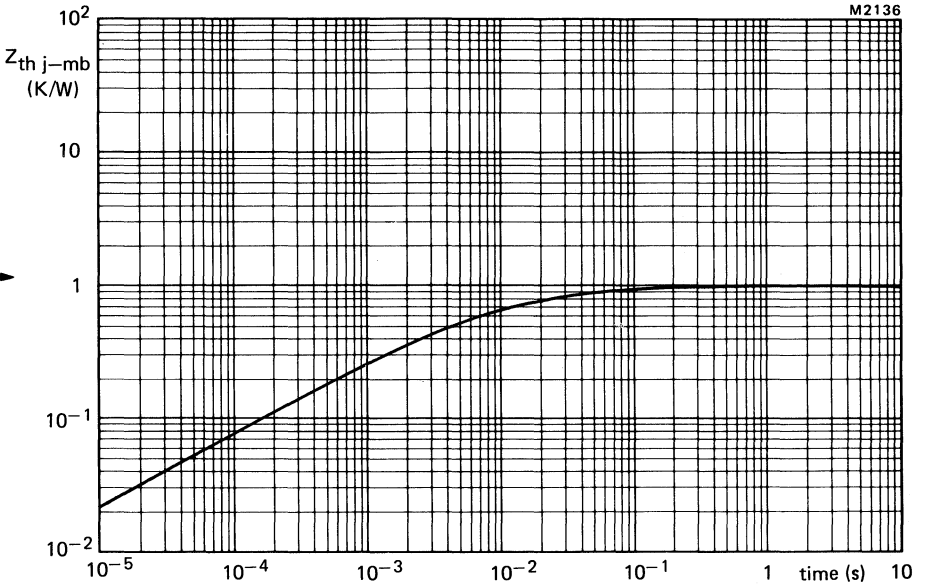


Fig.13 Transient thermal impedance.

FAST SOFT-RECOVERY RECTIFIER DIODES

Fast soft-recovery diodes in DO-5 metal envelopes especially suitable for operation as main and commutating diodes in 3-phase a.c. motor speed control inverters and in high frequency power supplies in general.

The series consists of the following types:

Normal polarity (cathode to stud): BYW25-800 and BYW25-1000.

Reverse polarity (anode to stud): BYW25-800R and BYW25-1000R.

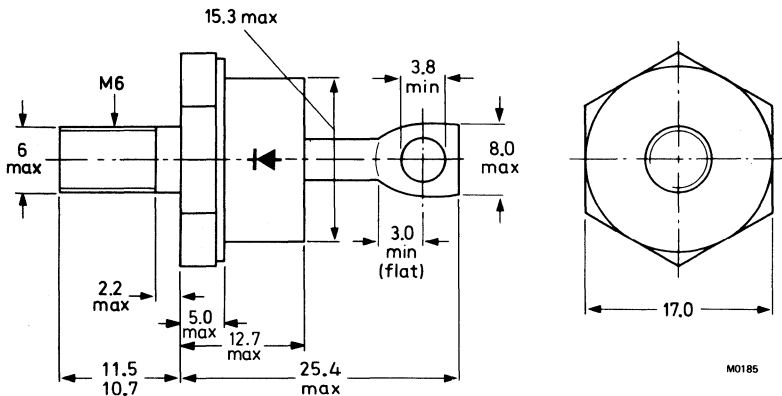
QUICK REFERENCE DATA

			BYW25-800(R)		1000(R)	
			800	1000	1000	
Repetitive peak reverse voltage	V_{RRM}	max.			1000	V
Average forward current	$I_{F(AV)}$	max.	40			A
Repetitive peak forward current	I_{FRM}	max.	600			A
Reverse recovery time	t_{rr}	<	450			ns

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5: with metric M6 stud ($\phi 6$ mm)



Net mass: 22 g

Diameter of clearance hole: max. 6.5 mm

Accessories supplied on request:

see ACCESSORIES section

The mark shown applies to normal polarity types.

Supplied with device: 1 nut, 1 lock washer

Torque on nut: min. 1.7 Nm (17 kg cm)

max. 3.5 Nm (35 kg cm)

Nut dimensions across the flats: 10 mm

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages*

		BYW25-800(R)	1000(R)	
Non-repetitive peak reverse voltage	V_{RSM}	max. 1000	1200	V
Repetitive peak reverse voltage	V_{RRM}	max. 800	1000	V
Crest working reverse voltage	V_{RWM}	max. 650	850	V
Continuous reverse voltage	V_R	max. 650	850	V

Currents

Average forward current;
switching losses negligible up to 20 kHz
sinusoidal; up to $T_{mb} = 100\text{ }^\circ\text{C}$
sinusoidal; at $T_{mb} = 125\text{ }^\circ\text{C}$

$I_{F(AV)}$	max.	40	A
$I_{F(AV)}$	max.	23	A

R.M.S. forward current

$I_{F(RMS)}$	max.	60	A
--------------	------	----	---

Repetitive peak forward current

I_{FRM}	max.	600	A
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Non-repetitive peak forward current;
 $t = 10\text{ ms}$; half sine-wave;
 $T_j = 150\text{ }^\circ\text{C}$ prior to surge

I_{FSM}	max.	550	A
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I^2t for fusing ($t = 10\text{ ms}$)

I^2t	max.	1500	A^2s
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Temperatures

Storage temperature

T_{stg}	-55 to +150	$^\circ\text{C}$
-----------	-------------	------------------

Junction temperature

T_j	max. 150	$^\circ\text{C}$
-------	----------	------------------

THERMAL RESISTANCE

From junction to mounting base

$R_{th\ j-mb}$	=	0.6	$^\circ\text{C/W}$
----------------	---	-----	--------------------

From mounting base to heatsink
with heatsink compound
without heatsink compound

$R_{th\ mb-h}$	=	0.3	$^\circ\text{C/W}$
$R_{th\ mb-h}$	=	0.5	$^\circ\text{C/W}$

*To ensure thermal stability: $R_{th\ j-a} \leq 1\text{ }^\circ\text{C/W}$ (continuous reverse voltage).

CHARACTERISTICS

Forward voltage

$I_F = 35 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1,55 \text{ V}^*$

$V_F < 2,25 \text{ V}^*$

Reverse current

$V_R = 650 \text{ V}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 7 \text{ mA}$

Reverse recovery when switched from

$I_F = 10 \text{ A to } V_R = 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 450 \text{ ns}$

$I_F = 600 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 70 \text{ A}/\mu\text{s}; T_{mb} = 85 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 1 \text{ } \mu\text{s}$

Maximum slope of the reverse recovery current

when switched from $I_F = 600 \text{ A to } V_R \geq 30 \text{ V};$

with $-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$|dI_R/dt| < 100 \text{ A}/\mu\text{s}$

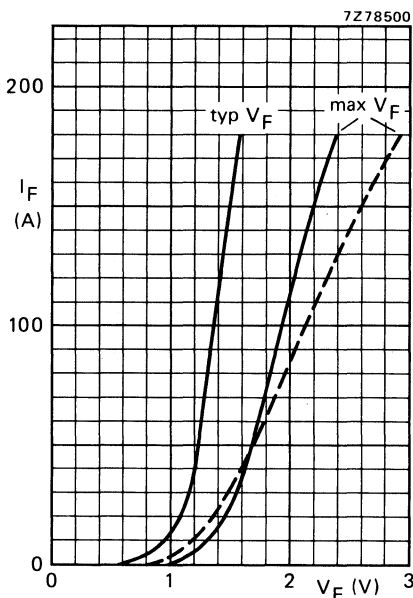


Fig. 3 — $T_j = 25 \text{ }^\circ\text{C}$; --- $T_j = 150 \text{ }^\circ\text{C}$.

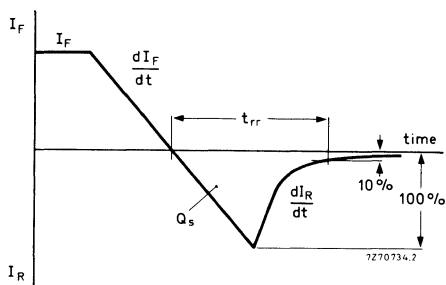


Fig. 2 Definitions of Q_s , t_{rr} and dI_R/dt .

* Measured under pulse conditions to avoid excessive dissipation.

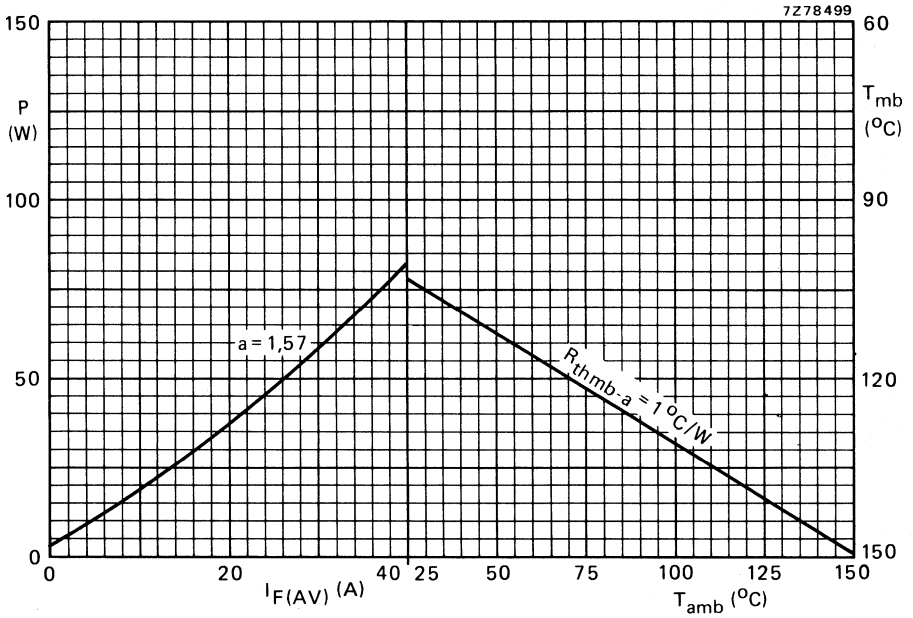


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power including reverse current losses and switching losses up to $f = 20$ kHz.

$a = I_F(RMS)/I_F(AV)$.

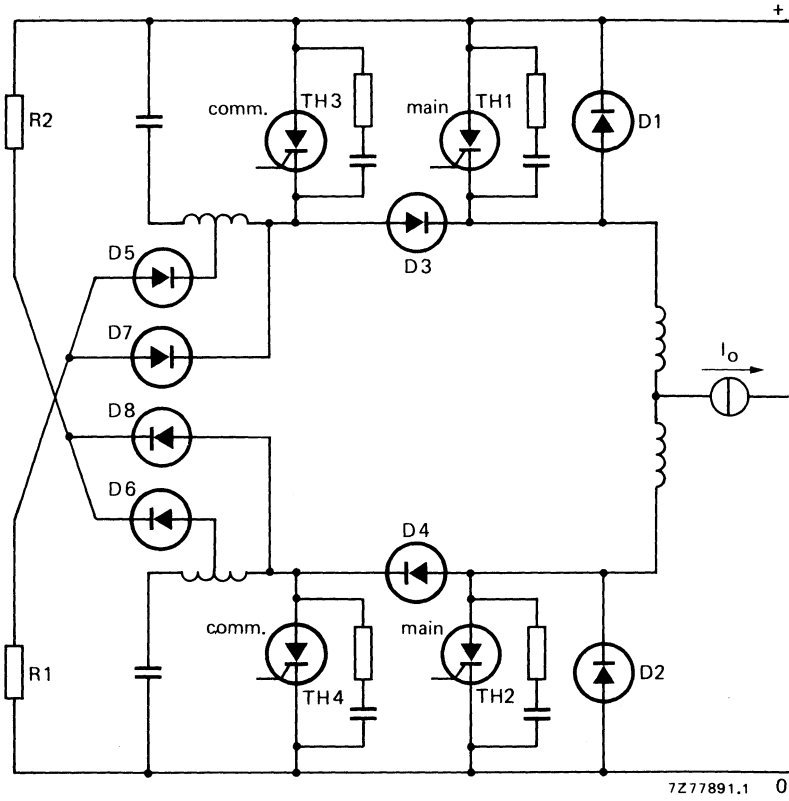


Fig. 5 One phase of a three-phase inverter for a.c. motor speed control. D1 to D4 are BYW25 types.

ULTRA FAST RECOVERY RECTIFIER DIODES



Glass-passivated, high-efficiency epitaxial rectifier diodes in plastic envelopes, featuring low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. The series consists of normal polarity (cathode to mounting base) types.

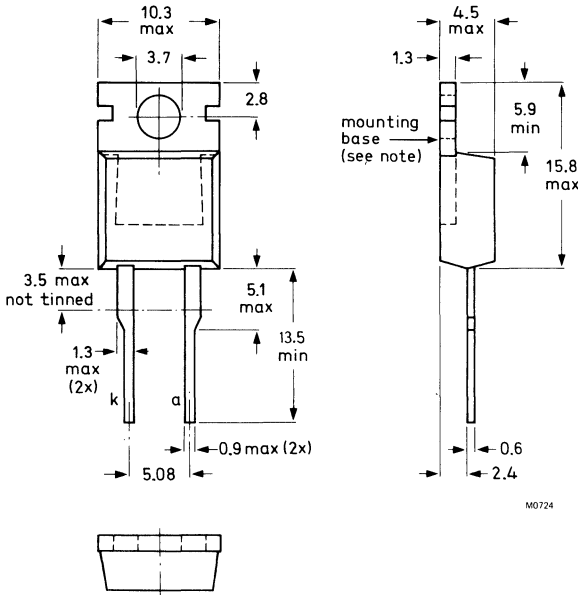
QUICK REFERENCE DATA

		BYW29-50				100				150				200			
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200	V										
Average forward current	$I_{F(AV)}$	max.			8		A										
Forward voltage	V_F	<			0.8		V										
Reverse recovery time	t_{rr}	<			25		ns										

MECHANICAL DATA

Fig.1 TO-220AC

Dimensions in mm



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

Products approved to CECC 50 009-014 available on request.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

		BYW29-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage (note 1)	V_R	max. 50	100	150	200	V

Currents

Average forward current; switching losses negligible up to 500 kHz						
→	square wave; $\delta = 0.5$; up to $T_{mb} = 125^\circ\text{C}$	$I_F(AV)$	max.	8		A
	sinusoidal; up to $T_{mb} = 125^\circ\text{C}$	$I_F(AV)$	max.	7.3		A
	R.M.S. forward current	$I_F(RMS)$	max.	11.5		A
	Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.	240		A
Non-repetitive peak forward current						
half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge;						
with reapplied V_{RWMmax} ;						
	$t = 10 \text{ ms}$	I_{FSM}	max.	80		A
	$t = 8.3 \text{ ms}$	I_{FSM}	max.	100		A
	I^2t for fusing ($t = 10 \text{ ms}$)	I^2t	max.	32		A^2s

Temperatures

Storage temperature	T_{stg}		-40 to +150	$^\circ\text{C}$
Junction temperature	T_j	max.	150	$^\circ\text{C}$

Notes:

- To ensure thermal stability: $R_{th j-a} < 11.6 \text{ K/W}$

CHARACTERISTICS

Forward voltage

$$I_F = 8 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$$

$$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 0.8 \text{ V}^*$$

$$V_F < 1.3 \text{ V}^*$$

Reverse current

$$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$$

$$T_j = 25 \text{ }^\circ\text{C}$$

$$I_R < 0.6 \text{ mA}$$

$$I_R < 10 \text{ } \mu\text{A}$$

Reverse recovery when switched from

$$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s};$$

$$T_j = 25 \text{ }^\circ\text{C}; \text{ recovery time}$$

$$t_{rr} < 25 \text{ ns}$$

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s};$$

$$T_j = 25 \text{ }^\circ\text{C}; \text{ recovered charge}$$

$$Q_s < 11 \text{ nC} \leftarrow$$

$$I_F = 10 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s};$$

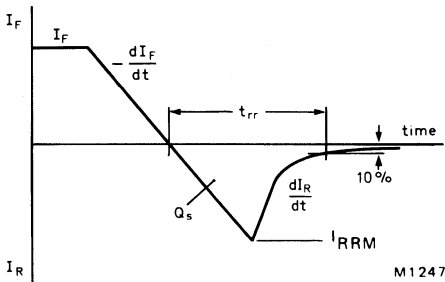
$$T_j = 100 \text{ }^\circ\text{C}; \text{ peak recovery current}$$

$$I_{RRM} < 2 \text{ A} \leftarrow$$

Forward recovery when switched to $I_F = 1 \text{ A}$

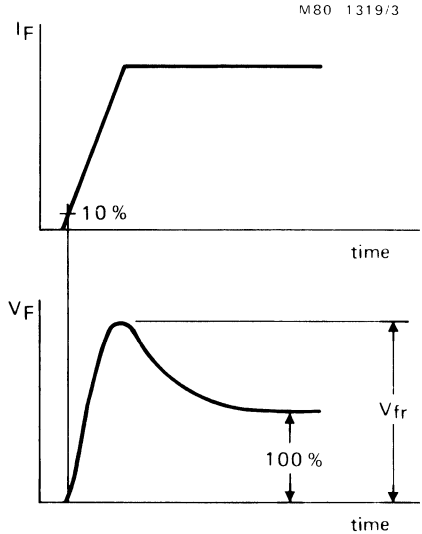
$$\text{with } dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_{fr} \text{ typ. } 0.9 \text{ V} \leftarrow$$



M1247

Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .



M80 1319/3

Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 2.7 \text{ K/W}$$

Influence of mounting method

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free-air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie-point.

Thermal resistance from junction to ambient in free air: mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

MOUNTING INSTRUCTIONS

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275°C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
- Mounting by means of a spring clip is the best mounting method because it offers:
 - a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
- Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process must **neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

- The various components of junction temperature rise above ambient are illustrated in Fig.4.

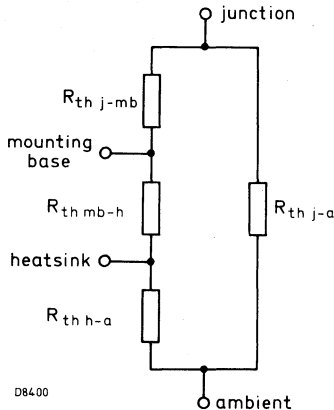


Fig. 4.

- Any measurement of heatsink temperature should be made immediately adjacent to the device.
- The method of using Figs. 5 and 6 is as follows:
Starting with the required current on the $I_F(AV)$ axis, trace upwards to meet the appropriate duty cycle or form factor curve. Trace right horizontally and upwards from the required value on the T_{amb} scale. The intersection determines the $R_{th\ mb-a}$. The heatsink thermal resistance value ($R_{th\ h-a}$) can be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

SQUARE-WAVE OPERATION

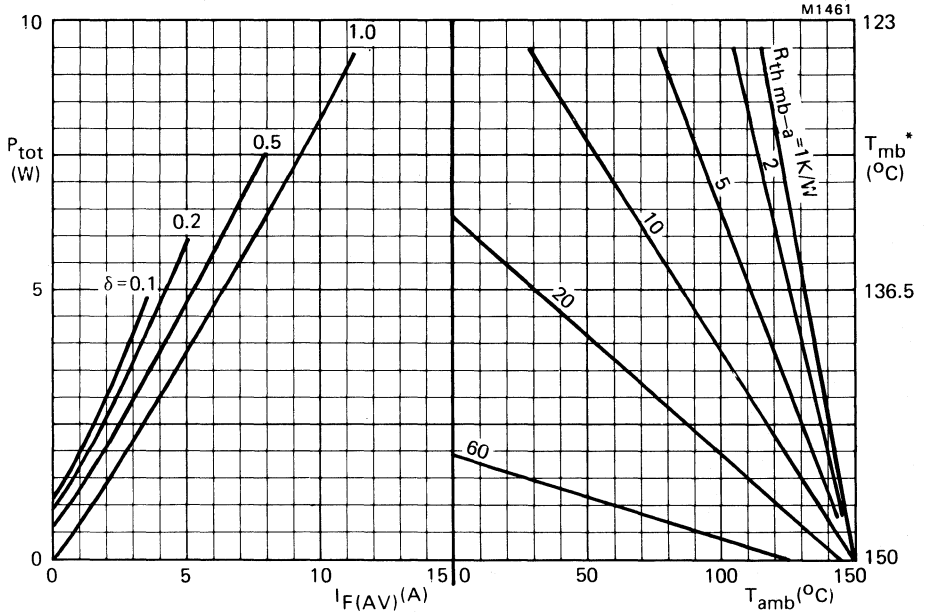
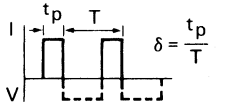


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 500$ kHz.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 8.9$ K/W.

SINUSOIDAL OPERATION

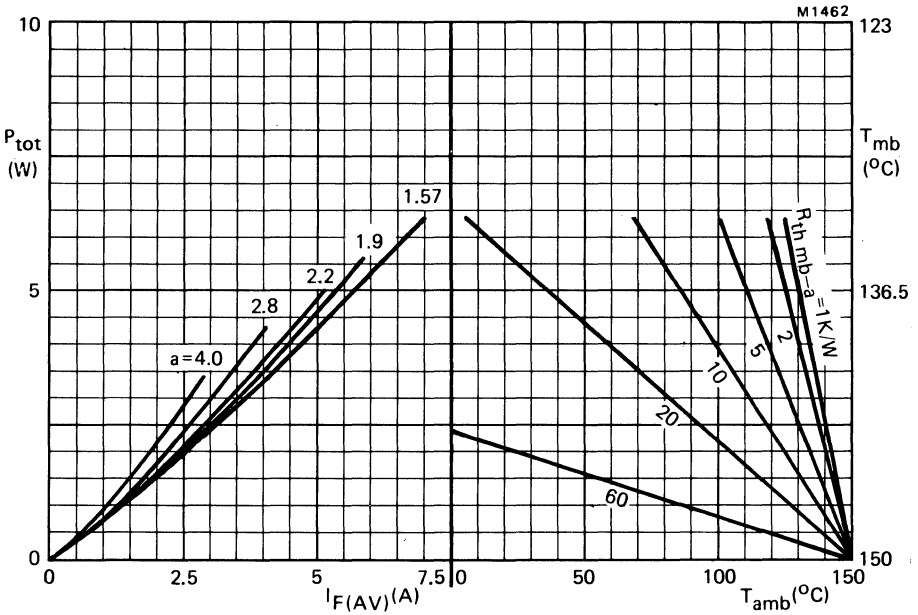


Fig.6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

Power includes reverse current losses and switching losses up to $f = 500$ kHz.

$a =$ form factor $= I_{F(RMS)}/I_{F(AV)}$.

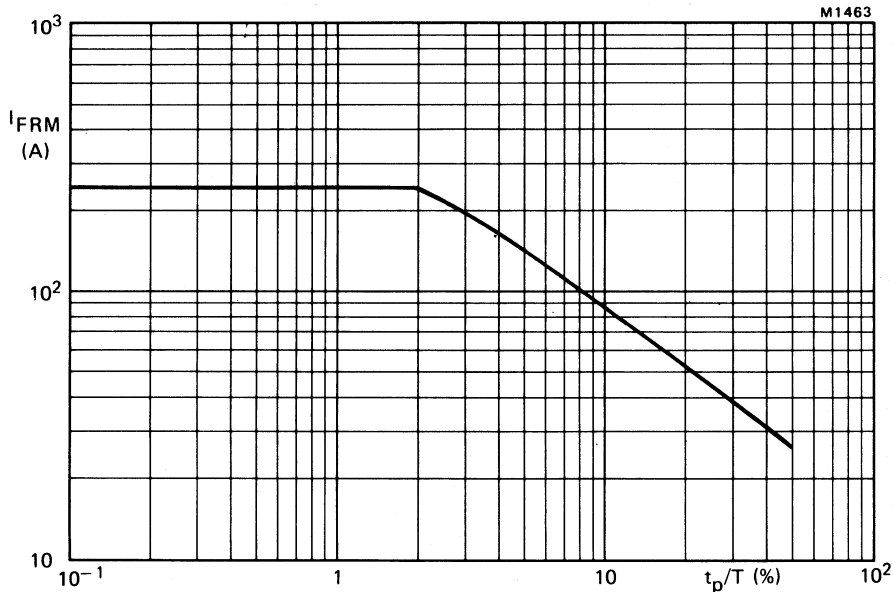
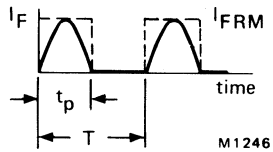
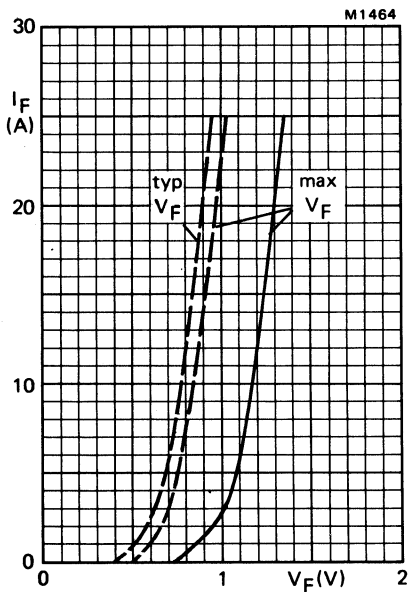


Fig.7 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1ms$.



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25^\circ C$; --- $T_j = 150^\circ C$.

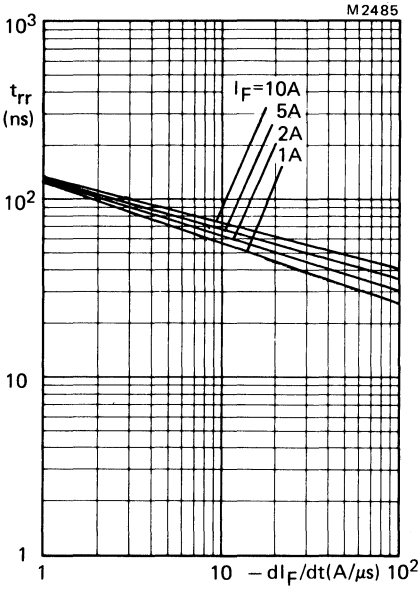


Fig.9 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

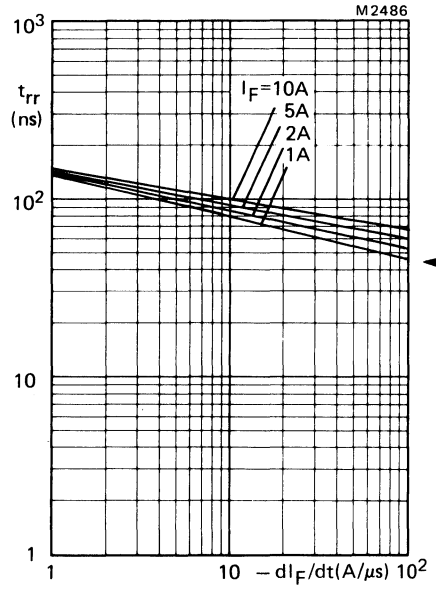


Fig.10 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

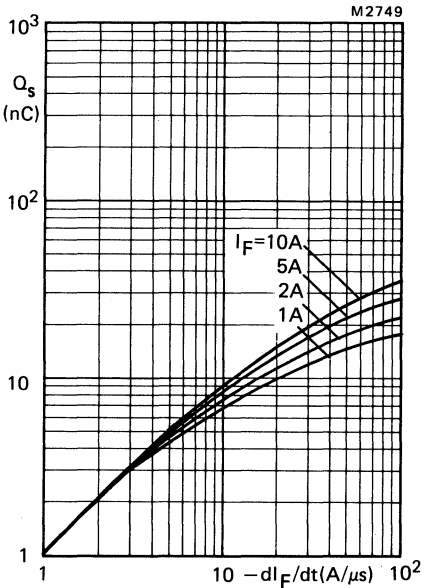


Fig.11 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

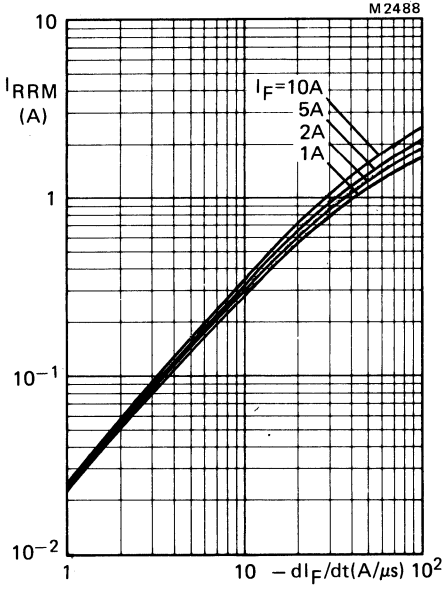


Fig.12 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

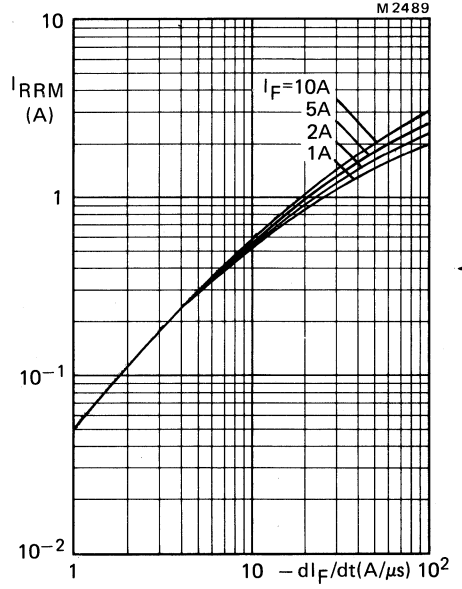


Fig.13 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

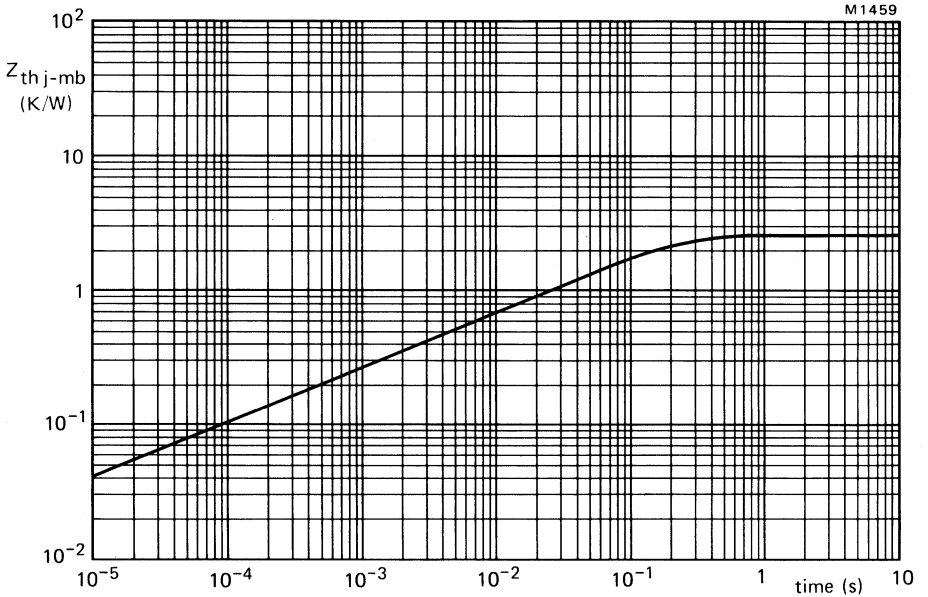


Fig.14 Transient thermal impedance.

ULTRA FAST RECOVERY, ELECTRICALLY-ISOLATED RECTIFIER DIODES

Glass-passivated, high-efficiency epitaxial rectifier diodes in SOT-186 (full-pack) envelopes, featuring low forward voltage drop, ultra fast reverse recovery times with very low stored charge and soft-recovery characteristic. Their electrical isolation makes them ideal for mounting on a common heatsink alongside other components without the need for additional insulators. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential.

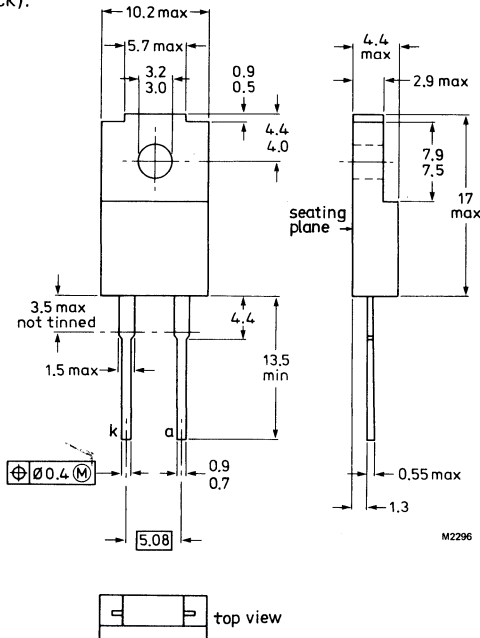
QUICK REFERENCE DATA

		BYW29F-50				
		100	150	200		
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Average forward current	$I_{F(AV)}$	max. 8				A
Forward voltage	V_F	< 0.8				V
Reverse recovery time	t_{rr}	< 25				ns

MECHANICAL DATA

Dimensions in mm

Fig.1 SOT-186 (full-pack).



Net mass: 2 g.

The seating plane is electrically isolated from all terminals.

Accessories supplied on request (see data sheets Mounting instructions for F-pack devices and Accessories for SOT-186 envelopes).

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages		BYW29F-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200 V
Crest working reverse voltage	V_{RWM}	max.	50	100	150	200 V
Continuous reverse voltage (note 1)	V_R	max.	50	100	150	200 V
Currents						
Average forward current; switching losses negligible up to 500 kHz (note 2); square wave; $\delta = 0.5$; up to $T_{mb} = 108^\circ\text{C}$						
	$I_F(AV)$	max.		8		A
	$I_F(AV)$	max.		7.3		A
R.M.S. forward current	$I_F(RMS)$	max.		11.5		A
Repetitive peak forward current $t_p = 20 \mu\text{s}$, $\delta = 0.02$						
	I_{FRM}	max.		240		A
Non-repetitive peak forward current half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max						
$t = 10 \text{ ms}$	I_{FSM}	max.		80		A
$t = 8.3 \text{ ms}$	I_{FSM}	max.		100		A
$I^2 t$ for fusing ($t = 10 \text{ ms}$)	$I^2 t$	max.		32		A^2s
Temperatures						
Storage temperature	T_{stg}		-40 to +150			$^\circ\text{C}$
Junction temperature	T_j	max.		150		$^\circ\text{C}$
ISOLATION						
Peak isolation voltage from all terminals to external heatsink						
	V_{isol}	max.		1000		V
Isolation capacitance from cathode to external heatsink (note 3)						
	C_p	typ.		12		pF

Notes:

1. To ensure thermal stability: $R_{th j-a} < 11.6 \text{ K/W}$.
2. The quoted temperatures assume heatsink compound is used.
3. Mounted without heatsink compound and 20 Newtons pressure on the centre of the envelope.

THERMAL RESISTANCE

From junction to external heatsink with minimum of 2 kgf (20 Newtons) pressure on the centre of the envelope, with heatsink compound without heatsink compound

$R_{th\ j-h}$	=	5.5	K/W
$R_{th\ j-h}$	=	7.2	K/W

Free air operation

The quoted value of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air, mounted on a printed circuit board

$R_{th\ j-a}$	=	55	K/W
---------------	---	----	-----

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated

Forward voltage

$I_F = 8\text{ A}; T_j = 150\text{ }^\circ\text{C}$
 $I_F = 20\text{ A}$

V_F	<	0.8	V*
V_F	<	1.3	V*

Reverse current

$V_R = V_{RWM\ max}; T_j = 100\text{ }^\circ\text{C}$
 $V_R = V_{RWM\ max}$

I_R	<	0.6	mA
I_R	<	10	μA

Reverse recovery when switched from

$I_F = 1\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 100\text{ A}/\mu\text{s}$;
 recovery time

t_{rr}	<	25	ns
----------	---	----	----

$I_F = 2\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 20\text{ A}/\mu\text{s}$;
 recovered charge

Q_s	<	11	nC
-------	---	----	----

$I_F = 10\text{ A}$ to $V_R \geq 30\text{ V}$ with $-dI_F/dt = 50\text{ A}/\mu\text{s}$;
 $T_j = 100\text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	2	A
-----------	---	---	---

Forward recovery when switched to $I_F = 1\text{ A}$
 with $dI_F/dt = 10\text{ A}/\mu\text{s}$

V_{fr}	typ.	0.9	V
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M80-1319/3

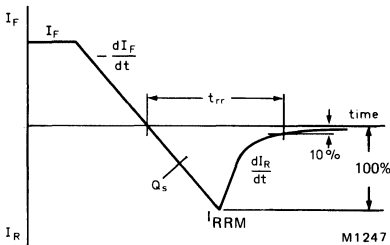


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

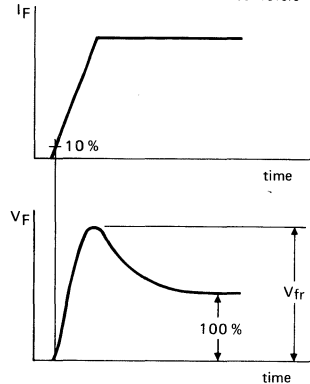


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers a good thermal contact under the crystal area and slightly lower $R_{th\ j-h}$ values than screw mounting. The force exerted on the top of the device by the clip should be at least 2 kgf (20 Newtons) to ensure good thermal contact and must not exceed 3.5 kgf (35 Newtons) to avoid damage to the device.
4. If screw mounting is used, it should be M3 cross-recess pan head.
 Minimum torque to ensure good thermal contact: 5.5 kgf (0.55 Nm)
 Maximum torque to avoid damage to the device: 8.0 kgf (0.80 Nm)
5. For good thermal contact, heatsink compound should be used between baseplate and heatsink. Values of $R_{th\ j-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting.
 It is not recommended to use rivets, since extensive damage could result to the plastic, which could destroy the insulating properties of the device.
7. The heatsink must have a flatness in the mounting area of 0.02 mm maximum per 10 mm. Mounting holes must be deburred.

OPERATING NOTES

The various components of junction temperature rise above ambient are illustrated in Fig.4.

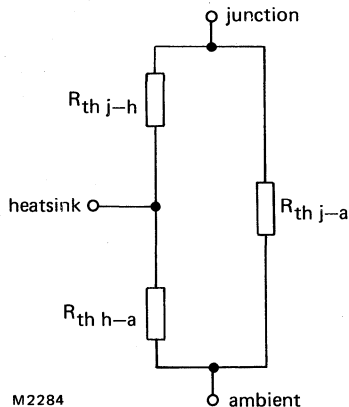


Fig.4.

Any measurement of heatsink temperature should be immediately adjacent to the device.

SQUARE-WAVE OPERATION

M2834

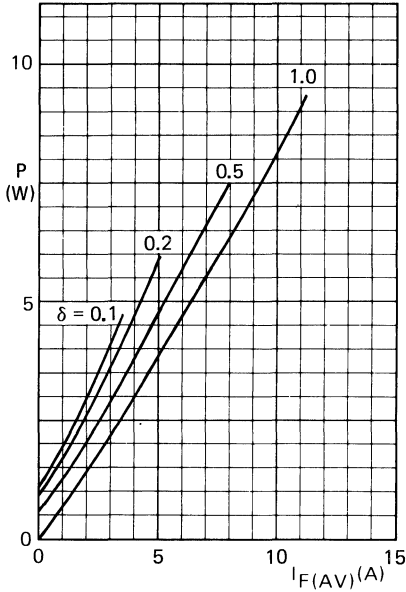
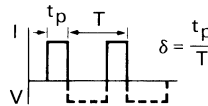


Fig.5 Power rating.

The power loss in the diode should first be determined from the required forward current on the $I_{F(AV)}$ axis and the appropriate duty cycle.

Having determined the power (P), use Fig.7 (if heatsink compound is not being used) or Fig.8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

SINUSOIDAL OPERATION

M2835

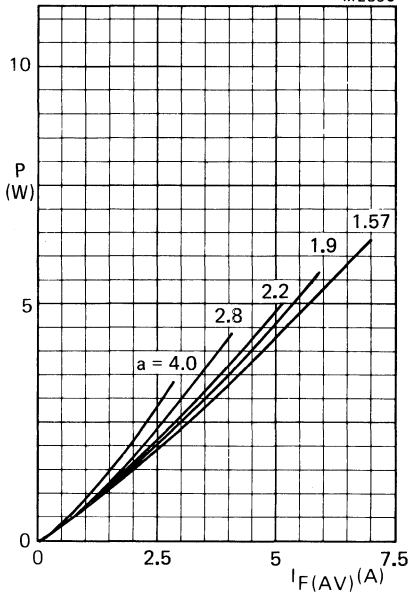


Fig.6 Power rating.

The power loss in the diode should first be determined from the required forward current on the $I_{F(AV)}$ axis and the appropriate form factor.

Having determined the power (P), use Fig.7 (if heatsink compound is not being used) or Fig.8 (if heatsink compound is being used) to determine the heatsink size and corresponding maximum ambient and heatsink temperatures.

Note: P = power including reverse current losses but excluding switching losses.

$$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$$

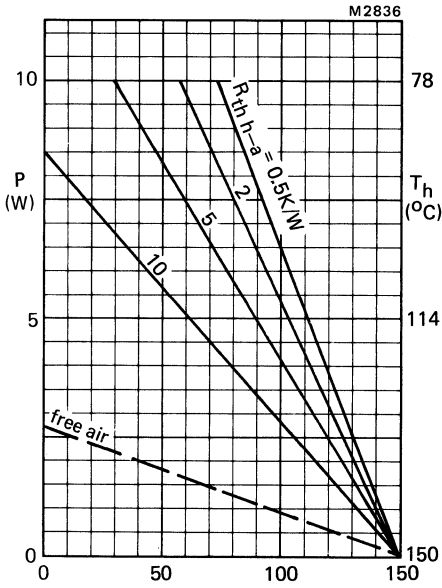


Fig.7 Heatsink rating;
without heatsink compound.

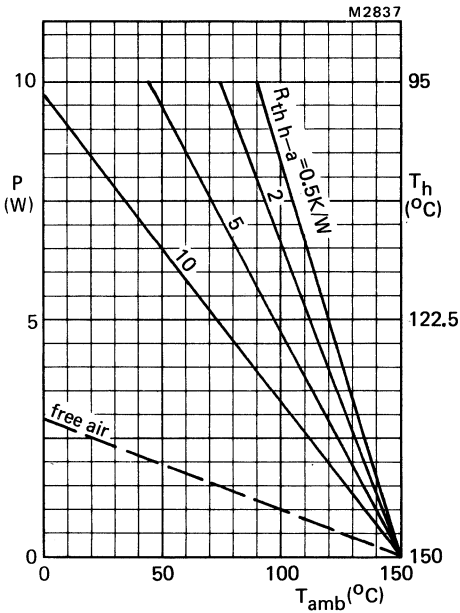


Fig.8 Heatsink rating;
with heatsink compound.

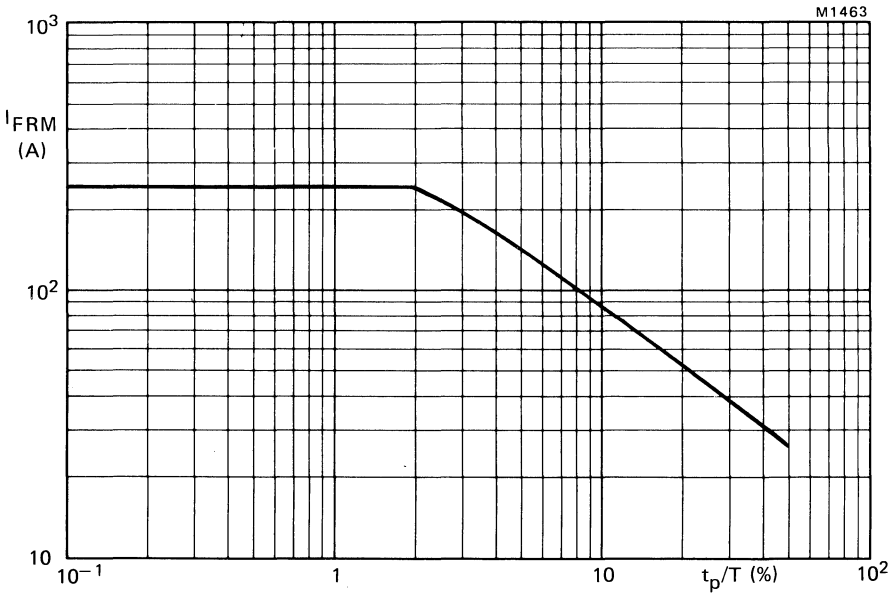
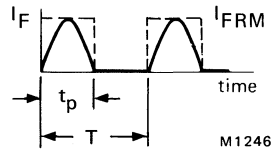
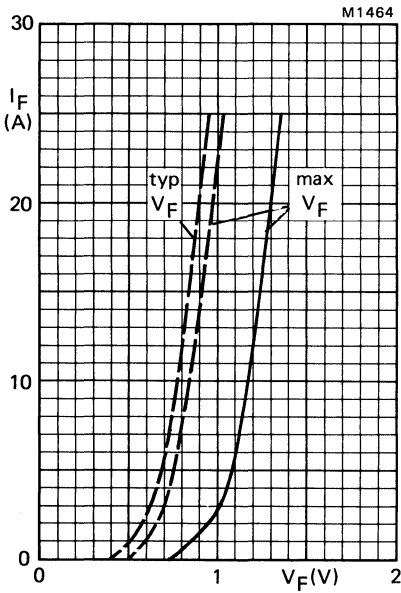


Fig.9 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 ms$.



Definition of I_{FRM} and t_p/T .

Fig.10 — $T_j = 25^\circ C$; - - - $T_j = 150^\circ C$.

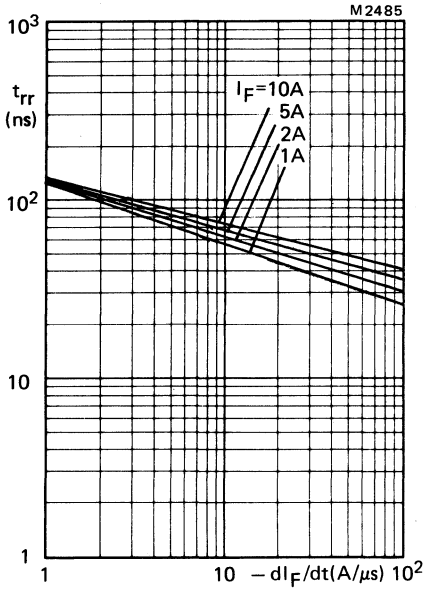


Fig.11 Maximum t_{rr} at $T_j = 25$ °C.

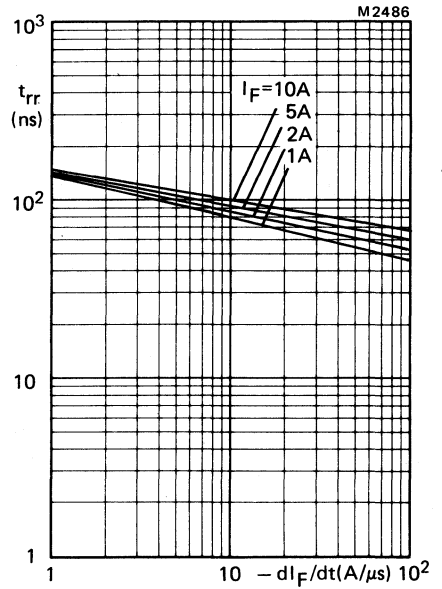


Fig.12 Maximum t_{rr} at $T_j = 100$ °C.

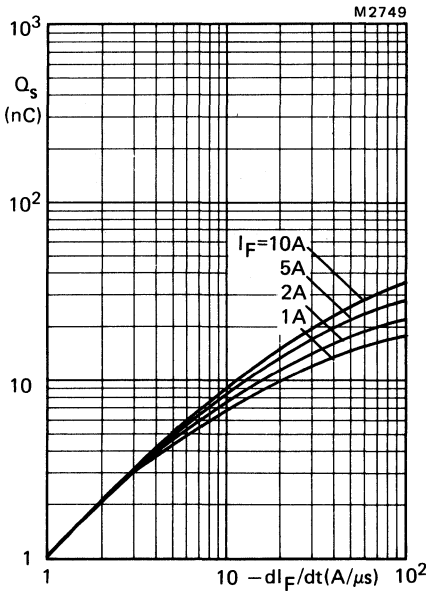


Fig.13 Maximum Q_s at $T_j = 25$ °C.

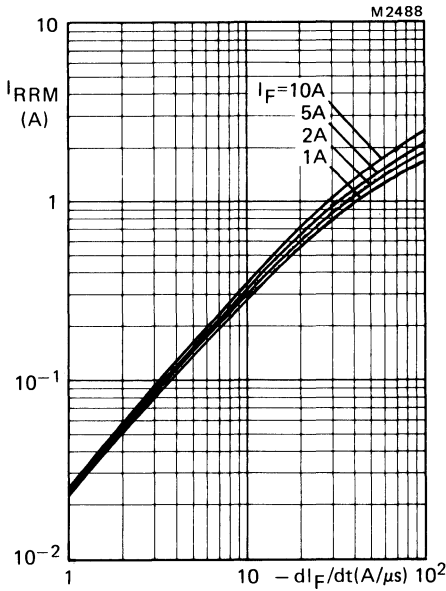


Fig.14 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

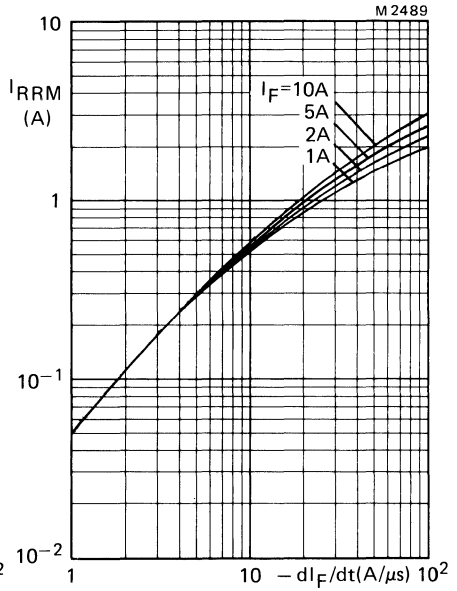


Fig.15 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

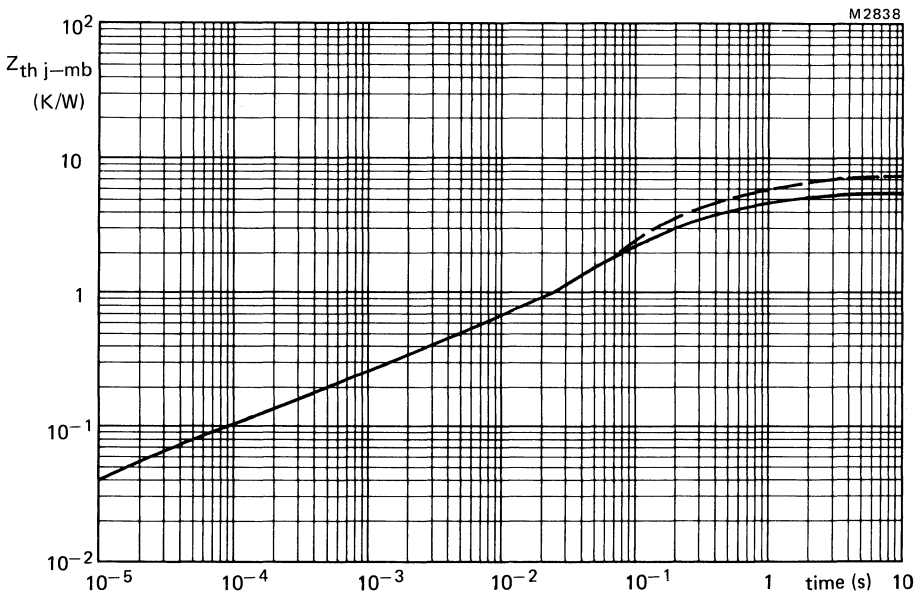


Fig.16 Transient thermal impedance: — with heatsink compound; - - - without heatsink compound.

ULTRA FAST RECOVERY RECTIFIER DIODES



Glass-passivated, high-efficiency epitaxial rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, ultra fast reverse recovery times, very low stored charge and soft recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode to stud) types.

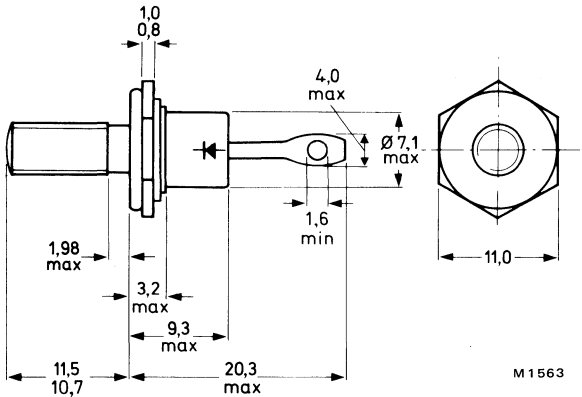
QUICK REFERENCE DATA

		BYW30-50				
		100	150	200		
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Average forward current	$I_F(AV)$	max. 14				A
Forward voltage	V_F	< 0.8				V
Reverse recovery time	t_{rr}	< 30				ns

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4: with metric M5 stud ($\phi 5$ mm); e.g. BYW30-50.
with 10-32 UNF stud ($\phi 4.83$ mm); e.g. BYW30-50U.



Net mass: 6 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:
see ACCESSORIES section.

Supplied with device: 1 nut, 1 lock washer

Torque on nut: min. 0.9 Nm (9 kg cm)
max. 1.7 Nm (17 kg cm)

Nut dimensions across the flats:
M5: 8.0 mm; 10-32 UNF: 9.5 mm.

Products approved to CECC 50 009-001, available on request.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages*		BYW30-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage	V_R	max. 50	100	150	200	V

Currents

Average forward current; switching losses negligible up to 500 kHz

square wave; $\delta = 0.5$; up to $T_{mb} = 120^\circ\text{C}$
up to $T_{mb} = 125^\circ\text{C}$

$I_F(AV)$	max.	14	A
$I_F(AV)$	max.	12	A

sinusoidal; up to $T_{mb} = 125^\circ\text{C}$

$I_F(AV)$	max.	12.5	A
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R.M.S. forward current

$I_F(RMS)$	max.	20	A
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Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$

I_{FRM}	max.	420	A
-----------	------	-----	---

Non-repetitive peak forward current

half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge;
with reapplied V_{RWMmax} ;

$t = 10 \text{ ms}$

$t = 8.3 \text{ ms}$

I_{FSM}	max.	200	A
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I_{FSM}	max.	240	A
-----------	------	-----	---

I^2t for fusing ($t = 10 \text{ ms}$)

I^2t	max.	200	A^2s
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Temperatures

Storage temperature

T_{stg}		-55 to +150	$^\circ\text{C}$
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Junction temperature

T_j	max.	150	$^\circ\text{C}$
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THERMAL RESISTANCE

From junction to mounting base

$R_{th j-mb}$	=	2.2	K/W
---------------	---	-----	--------------

From mounting base to heatsink

a. with heatsink compound

$R_{th mb-h}$	=	0.5	K/W
---------------	---	-----	--------------

b. without heatsink compound

$R_{th mb-h}$	=	0.6	K/W
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Transient thermal impedance; $t = 1 \text{ ms}$

$Z_{th j-mb}$	=	0.3	K/W
---------------	---	-----	--------------

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

*To ensure thermal stability: $R_{th j-a} \leq 5.6 \text{ K/W}$ (continuous reverse voltage).

CHARACTERISTICS

Forward voltage

$I_F = 15 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$
 $I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

V_F	<	0.8	V*
V_F	<	1.3	V*

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$
 $T_j = 25 \text{ }^\circ\text{C}$

I_R	<	1.3	mA
I_R	<	50	μA

Reverse recovery when switched from

$I_F = 1 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovery time

t_{rr}	<	30	ns
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$I_F = 2 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 20 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovered charge

Q_s	<	15	nC
-------	---	----	----

$I_F = 10 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 50 \text{ A}/\mu\text{s}$;
 $T_j = 100 \text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	4	A
-----------	---	---	---

Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}$; $T_j = 25 \text{ }^\circ\text{C}$

V_{fr}	typ.	1.0	V
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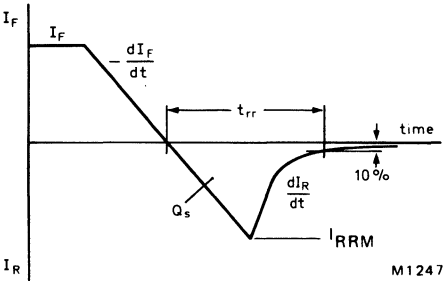


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

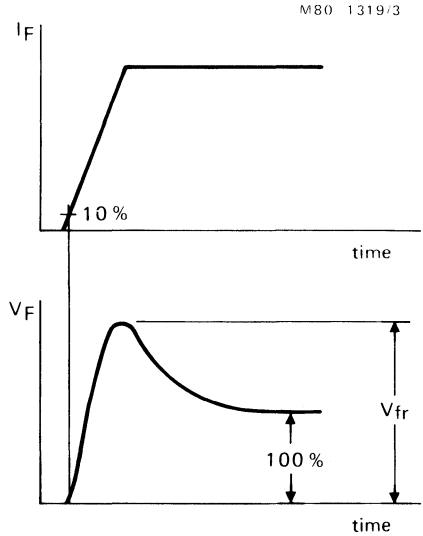


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

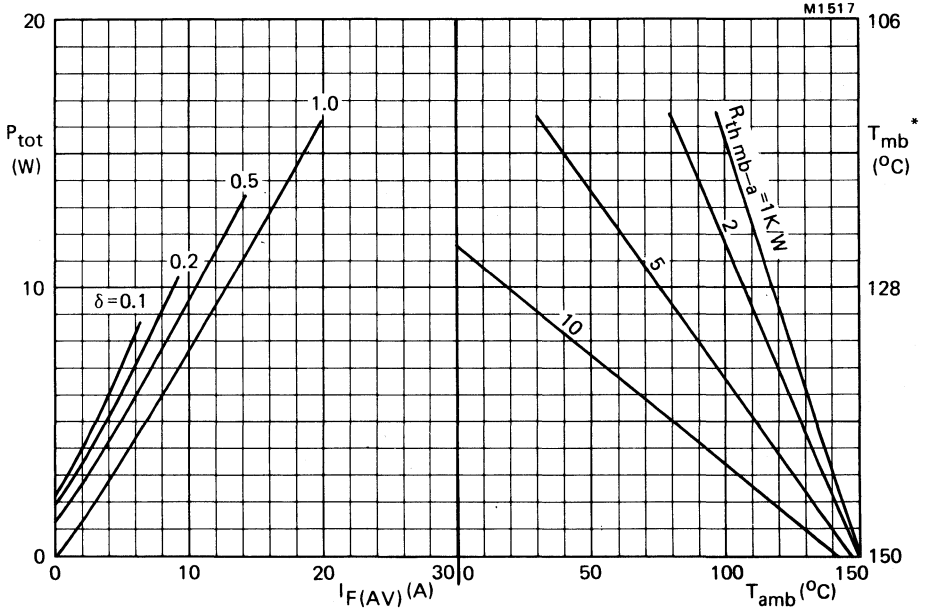
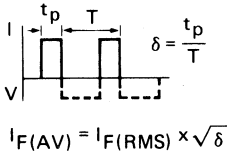


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 500$ kHz.



* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 3.1$ K/W.

SINUSOIDAL OPERATION

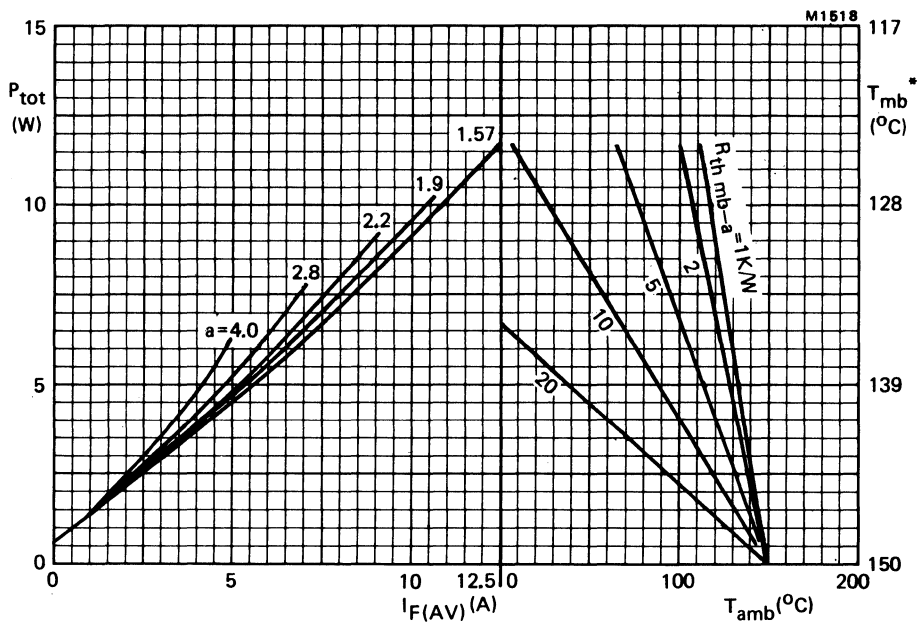


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

$a = \text{form factor} = I_F(RMS)/I_F(AV)$.

* T_{mb} scale is for comparison purposes and is correct only for $R_{th mb-a} < 17 K/W$.

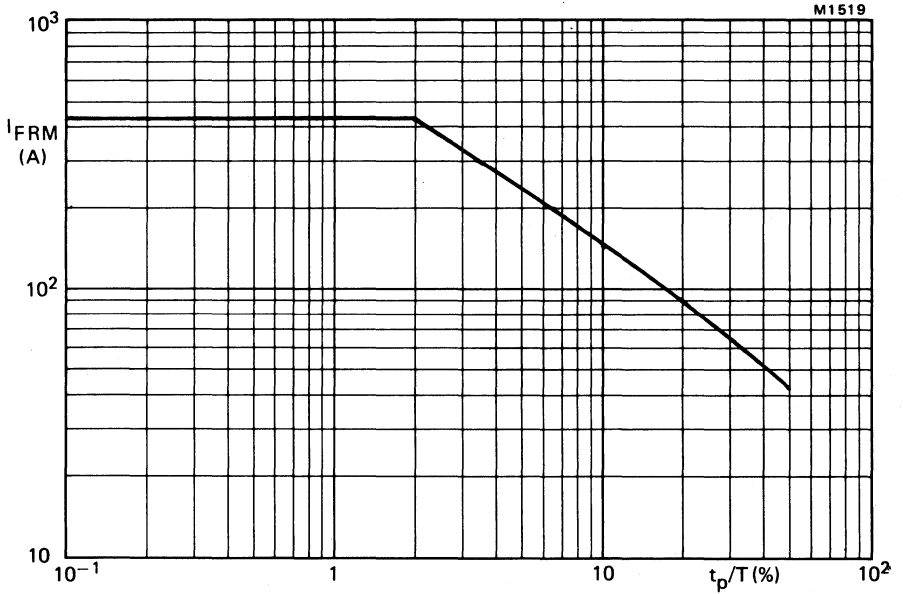
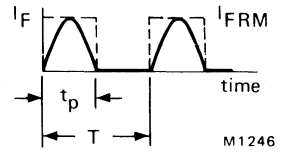
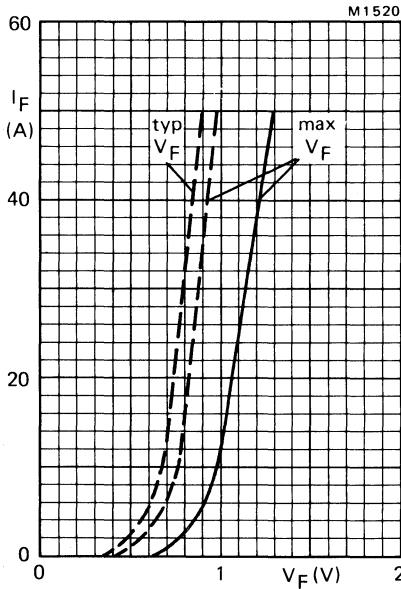


Fig.6 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.7 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$.

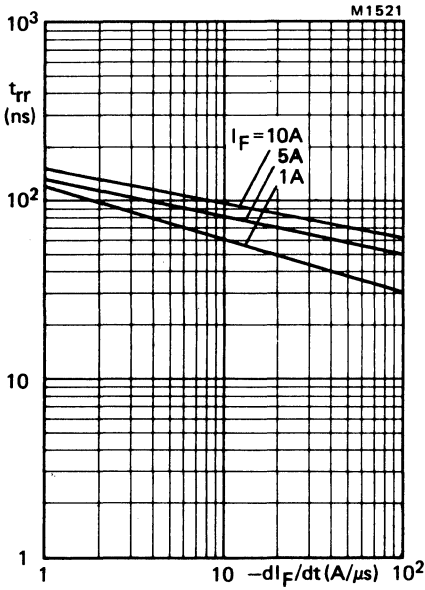


Fig.8 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

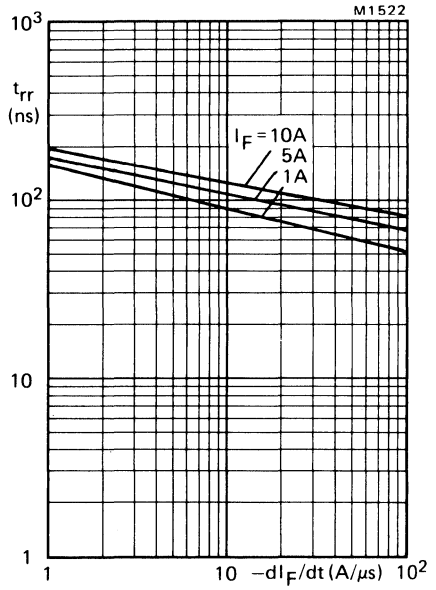


Fig.9 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

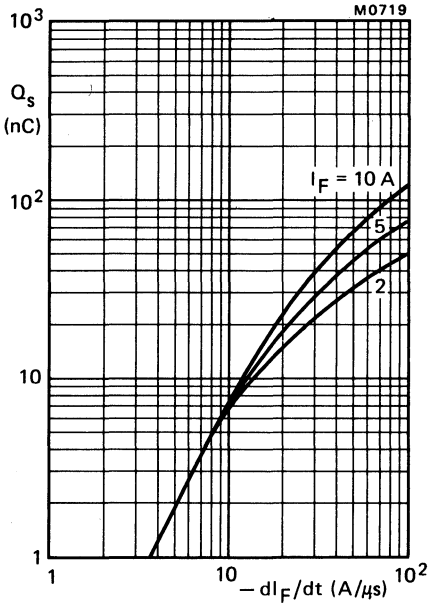


Fig.10 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

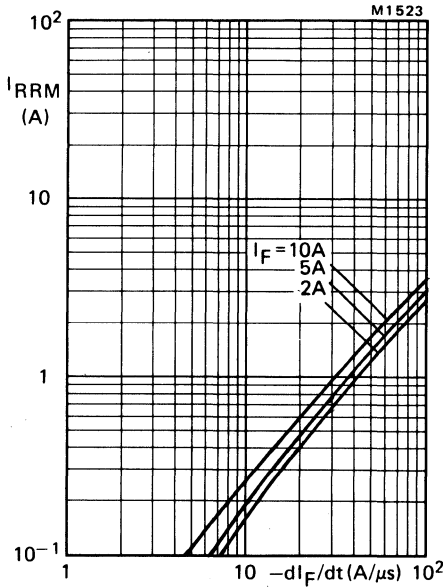


Fig.11 Maximum I_{RRM} at $T_j = 25$ °C.

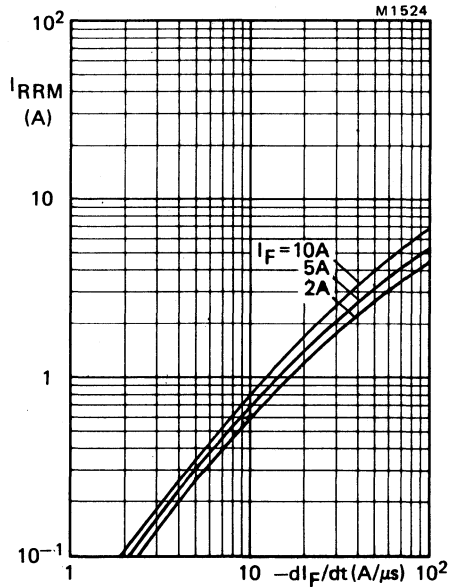


Fig.12 Maximum I_{RRM} at $T_j = 100$ °C.

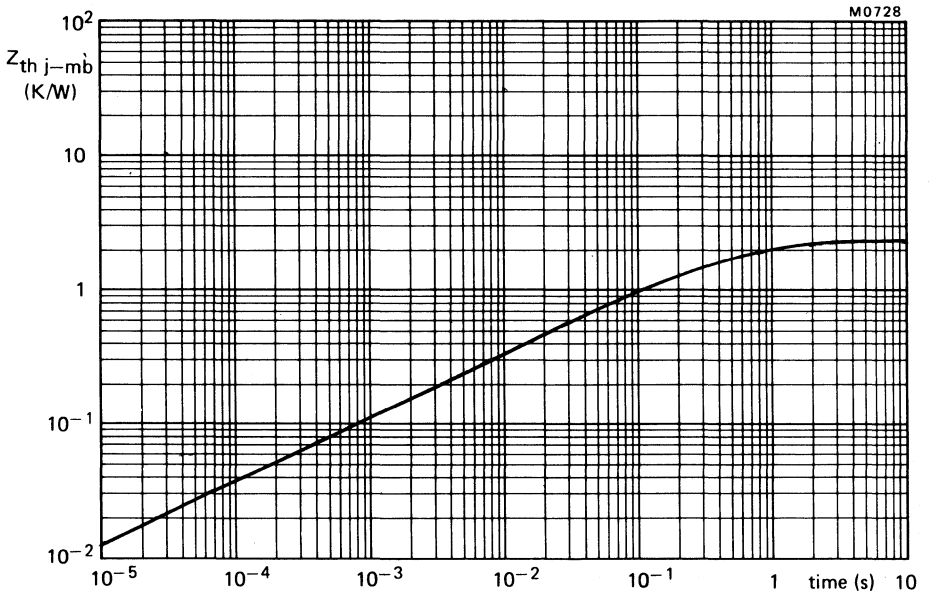


Fig.13 Transient thermal impedance.

ULTRA FAST RECOVERY RECTIFIER DIODES



Glass-passivated, high-efficiency epitaxial rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, ultra fast reverse recovery times, very low stored charge and soft recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode to stud) types.

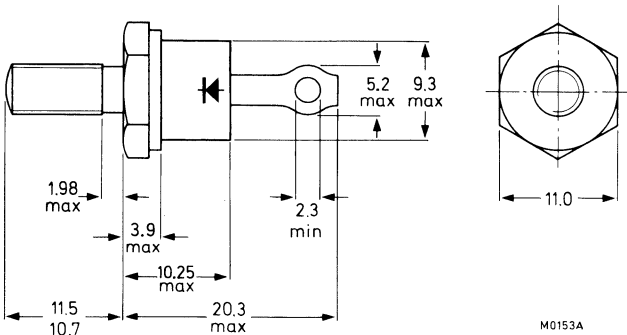
QUICK REFERENCE DATA

		BYW31-50				100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200		V	
Average forward current	$I_{F(AV)}$	max.				28		A	
Forward voltage	V_F	<				0.8		V	
Reverse recovery time	t_{rr}	<				40		ns	

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4; with metric M5 stud ($\phi 5$ mm); e.g. BYW31-50.
with 10-32 UNF stud ($\phi 4.83$ mm); e.g. BYW31-50U.



Net mass: 7 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:
see ACCESSORIES section.

Supplied with device: 1 nut, 1 lock washer

Torque on nut: min. 0.9 Nm (9 kg cm)
max. 1.7 Nm (17 kg cm)

Nut dimensions across the flats;
M5: 8.0 mm; 10-32 UNF: 9.5 mm

Products approved to CECC 50 009-002, available on request.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages		BYW31-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage*	V_R	max. 50	100	150	200	V

Currents

Average forward current; switching losses negligible up to 500 kHz

square wave; $\delta = 0.5$; up to $T_{mb} = 122^\circ\text{C}$
up to $T_{mb} = 125^\circ\text{C}$

$I_F(AV)$	max.	28	A
$I_F(AV)$	max.	26	A

sinusoidal; up to $T_{mb} = 127^\circ\text{C}$

$I_F(AV)$	max.	25	A
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R.M. S. forward current

$I_F(RMS)$	max.	40	A
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Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$

I_{FRM}	max.	550	A
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Non-repetitive peak forward current

half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge;
with reapplied V_{RWMmax} ;

$t = 10 \text{ ms}$

$t = 8.3 \text{ ms}$

I_{FSM}	max.	320	A
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I_{FSM}	max.	380	A
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$I^2 t$ for fusing ($t = 10 \text{ ms}$)

$I^2 t$	max.	500	A^2s
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Temperatures

Storage temperature

T_{stg}		-55 to +150	$^\circ\text{C}$
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Junction temperature

T_j	max.	150	$^\circ\text{C}$
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THERMAL RESISTANCE

From junction to mounting base

$R_{th j-mb}$	=	1.0	K/W
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From mounting base to heatsink

a. with heatsink compound

$R_{th mb-h}$	=	0.3	K/W
---------------	---	-----	--------------

b. without heatsink compound

$R_{th mb-h}$	=	0.5	K/W
---------------	---	-----	--------------

Transient thermal impedance: $t = 1 \text{ ms}$

$Z_{th j-mb}$	=	0.2	K/W
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MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

*To ensure thermal stability: $R_{th j-a} \leq 4.9 \text{ K/W}$ (continuous reverse voltage).

CHARACTERISTICS

Forward voltage

$I_F = 30 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$
 $I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 0.8 \text{ V}^*$
 $V_F < 1.3 \text{ V}^*$

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 100 \text{ }^\circ\text{C}$
 $T_j = 25 \text{ }^\circ\text{C}$

$I_R < 1.5 \text{ mA}$
 $I_R < 100 \text{ } \mu\text{A}$

Reverse recovery when switched from

$I_F = 1 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovery time

$t_{rr} < 40 \text{ ns}$

$I_F = 2 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 20 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovered charge

$Q_s < 20 \text{ nC}$

$I_F = 10 \text{ A}$ to $V_R \geq 30 \text{ V}$ with $-dI_F/dt = 50 \text{ A}/\mu\text{s}$;
 $T_j = 100 \text{ }^\circ\text{C}$; peak recovery current

$I_{RRM} < 4 \text{ A}$

Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}$; $T_j = 25 \text{ }^\circ\text{C}$

$V_{fr} \text{ typ. } 1 \text{ V}$

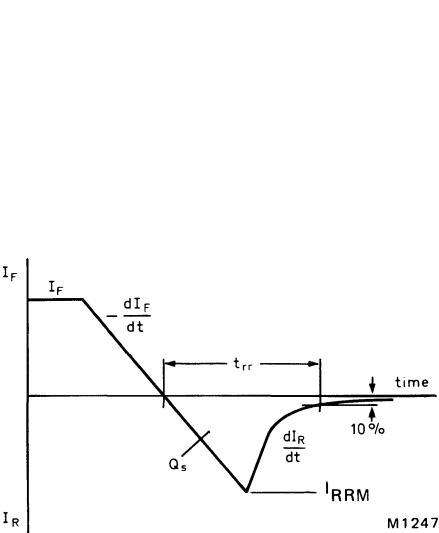


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

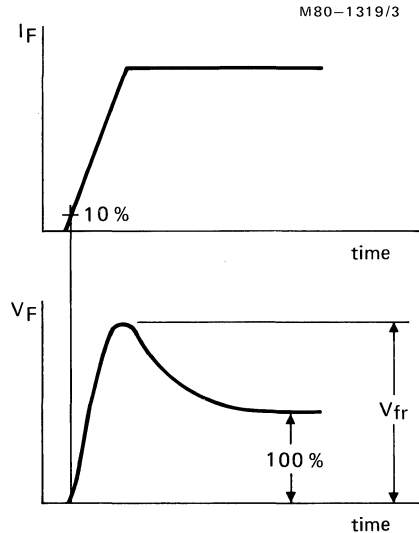


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

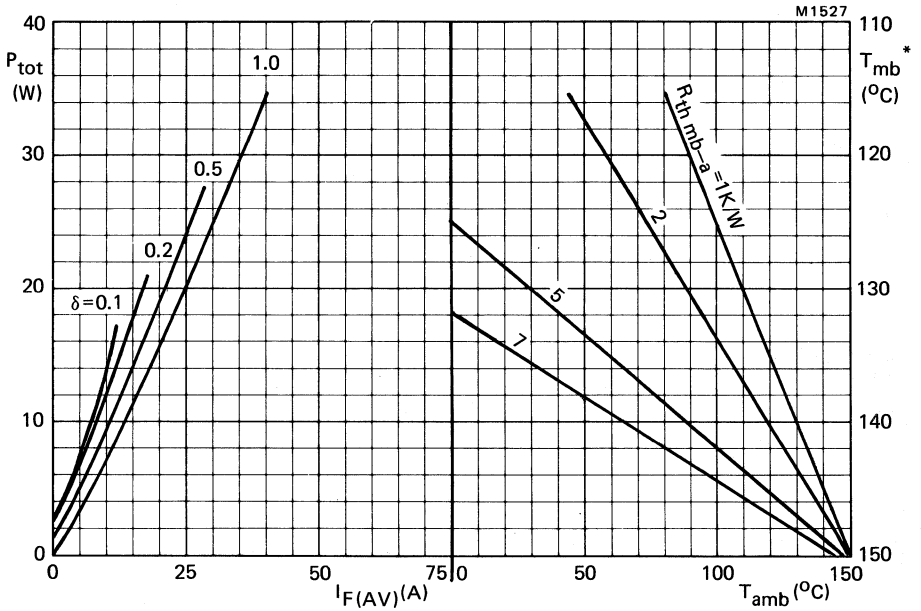
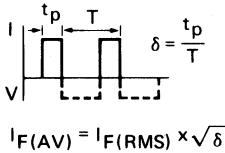


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 500$ kHz.



* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 3.6$ K/W.

SINUSOIDAL OPERATION

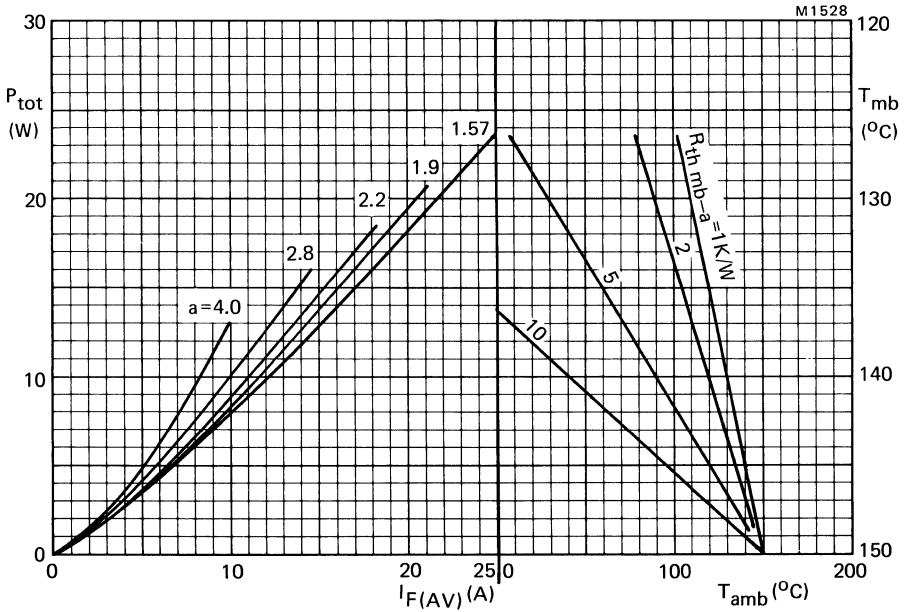


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 500$ kHz.

$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$.

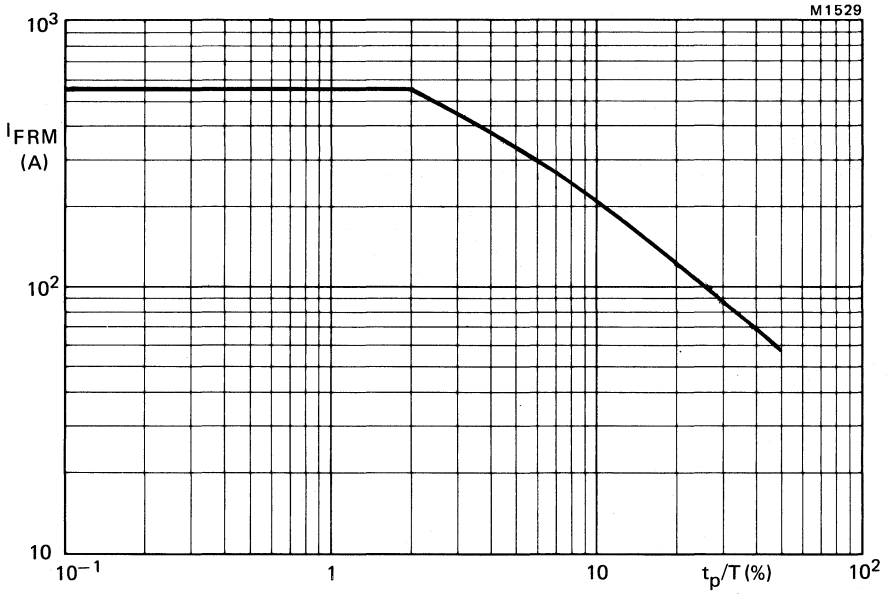
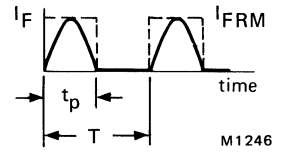
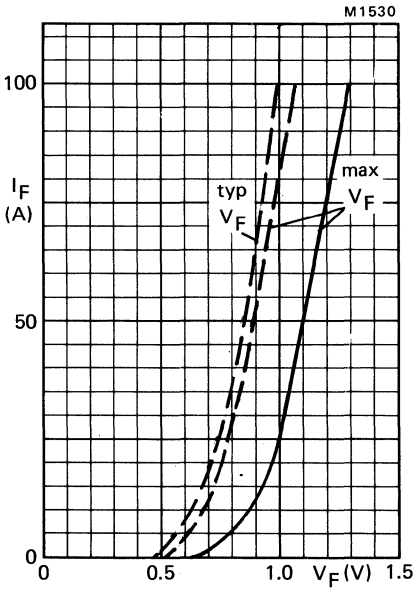


Fig.6 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 ms$.



Definition of I_{FRM} and t_p/T .

Fig.7 ——— $T_j = 25^\circ C$; - - - $T_j = 150^\circ C$.

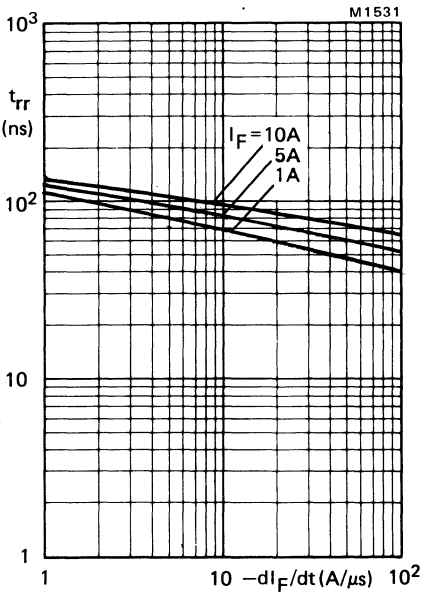


Fig.8 Maximum t_{rr} at $T_j = 25\text{ }^\circ\text{C}$.

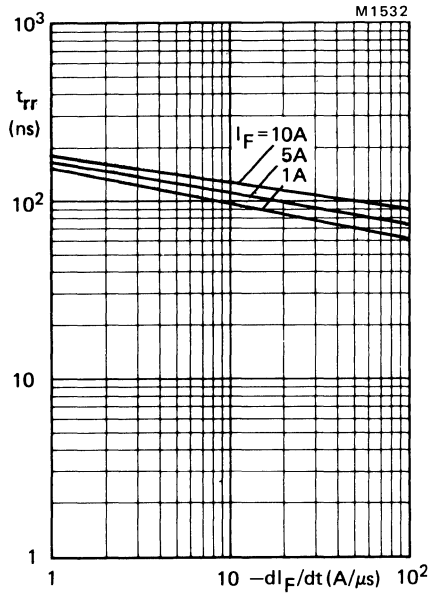


Fig.9 Maximum t_{rr} at $T_j = 100\text{ }^\circ\text{C}$.

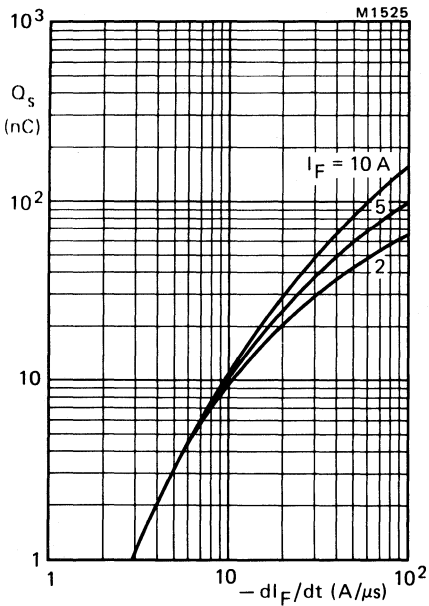


Fig.10 Maximum Q_s at $T_j = 25\text{ }^\circ\text{C}$.

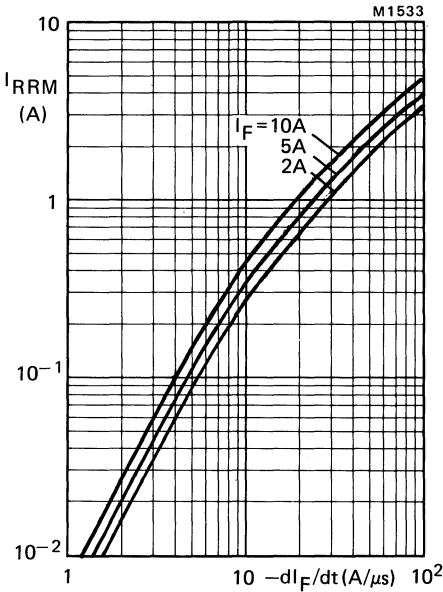


Fig.11 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

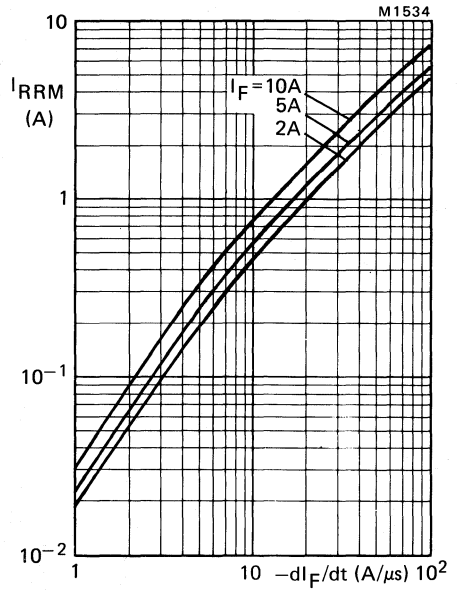


Fig.12 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

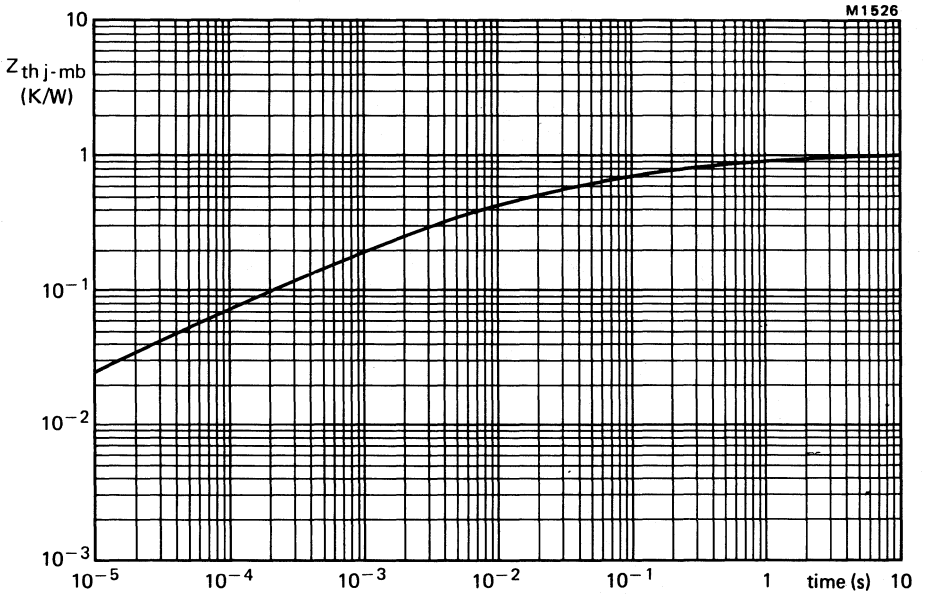


Fig.13 Transient thermal impedance.

ULTRA FAST RECOVERY RECTIFIER DIODES



Glass-passivated, high-efficiency epitaxial rectifier diodes in DO-5 metal envelopes, featuring low forward voltage drop, ultra fast reverse recovery times, very low stored charge and soft recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode to stud) types.

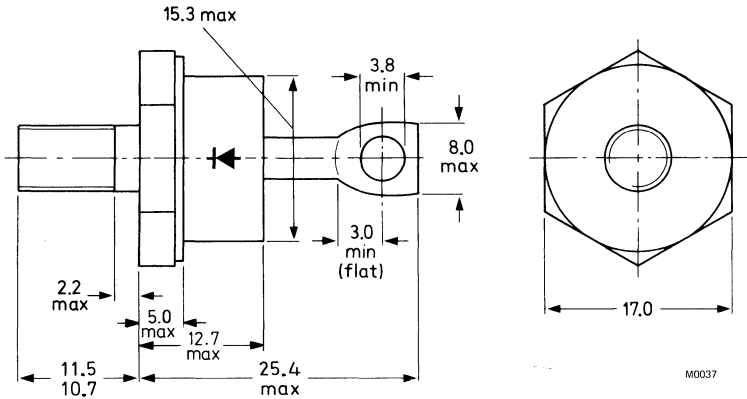
QUICK REFERENCE DATA

		BYW92-50				100				150				200			
Repetitive peak reverse voltage	V_{RRM}	max.	50	100	150	200	50	100	150	200	50	100	150	200	V		
Average forward current	$I_F(AV)$	max.					40								A		
Forward voltage	V_F	<					0.8								V		
Reverse recovery time	t_{rr}	<					40								ns		

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5: with metric M6 stud (ϕ 6 mm); e.g. BYW92-50.
with 1/4 in x 28 UNF stud (ϕ 6.35 mm); e.g. BYW92-50U.



Net mass: 22 g
Diameter of clearance hole: max. 6.5 mm
Accessories supplied on request:
see ACCESSORIES section.

Supplied with device: 1 nut. 1 lock washer
Torque on nut: min. 1.7 Nm (17 kg cm)
max. 3.5 Nm (35 kg cm)
Nut dimensions across the flats:
M6: 10 mm; 1/4 in x 28 UNF: 11.1 mm



Products approved to CECC 50 009-003, available on request.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages		BYW92-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage*	V_R	max. 50	100	150	200	V

Currents

Average forward current; switching losses negligible up to 500 kHz

square wave; $\delta = 0.5$; up to $T_{mb} = 110^\circ\text{C}$
up to $T_{mb} = 125^\circ\text{C}$

$I_F(AV)$	max.	40	A
$I_F(AV)$	max.	27	A

sinusoidal; up to $T_{mb} = 115^\circ\text{C}$
up to $T_{mb} = 125^\circ\text{C}$

$I_F(AV)$	max.	35	A
$I_F(AV)$	max.	26	A

R.M.S. forward current

$I_F(RMS)$	max.	55	A
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Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$

I_{FRM}	max.	800	A
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Non-repetitive peak forward current

half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge;

with reapplied V_{RWMmax} ;

$t = 10 \text{ ms}$

I_{FSM}	max.	500	A
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$t = 8.3 \text{ ms}$

I_{FSM}	max.	600	A
-----------	------	-----	---

$I^2 t$ for fusing ($t = 10 \text{ ms}$)

$I^2 t$	max.	1250	A^2s
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Temperatures

→ Storage temperature	T_{stg}	-55 to +150	$^\circ\text{C}$
Junction temperature	T_j	max. 150	$^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	1.0	K/W
From mounting base to heatsink				
a. with heatsink compound	$R_{th mb-h}$	=	0.3	K/W
b. without heatsink compound	$R_{th mb-h}$	=	0.5	K/W
Transient thermal impedance; $t = 1 \text{ ms}$	$Z_{th j-mb}$	=	0.2	K/W

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

*To ensure thermal stability: $R_{th j-a} \leq 4.9 \text{ K/W}$

CHARACTERISTICS

Forward voltage

$I_F = 35 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$
 $I_F = 100 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 0.8 \text{ V}^*$
 $V_F < 1.3 \text{ V}^*$

Reverse current

$V_R = V_{RRMmax}; T_j = 100 \text{ }^\circ\text{C}$
 $T_j = 25 \text{ }^\circ\text{C}$

$I_R < 2.5 \text{ mA}$
 $I_R < 100 \text{ } \mu\text{A}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 100 \text{ A}/\mu\text{s};$
 $T_j = 25 \text{ }^\circ\text{C};$ recovery time

$t_{rr} < 40 \text{ ns}$

$I_F = 2 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 20 \text{ A}/\mu\text{s};$
 $T_j = 25 \text{ }^\circ\text{C};$ recovered charge

$Q_s < 20 \text{ nC}$

$I_F = 10 \text{ A to } V_R \geq 30 \text{ V with } -dI_F/dt = 50 \text{ A}/\mu\text{s};$
 $T_j = 100 \text{ }^\circ\text{C};$ peak recovery current

$I_{RRM} < 4.5 \text{ A}$

Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

V_{fr} typ. 1.0 V

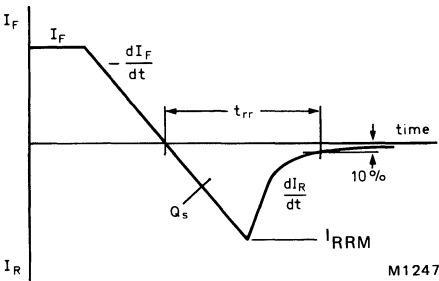


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

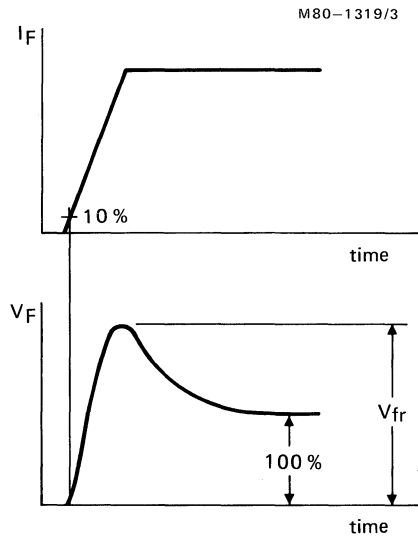


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

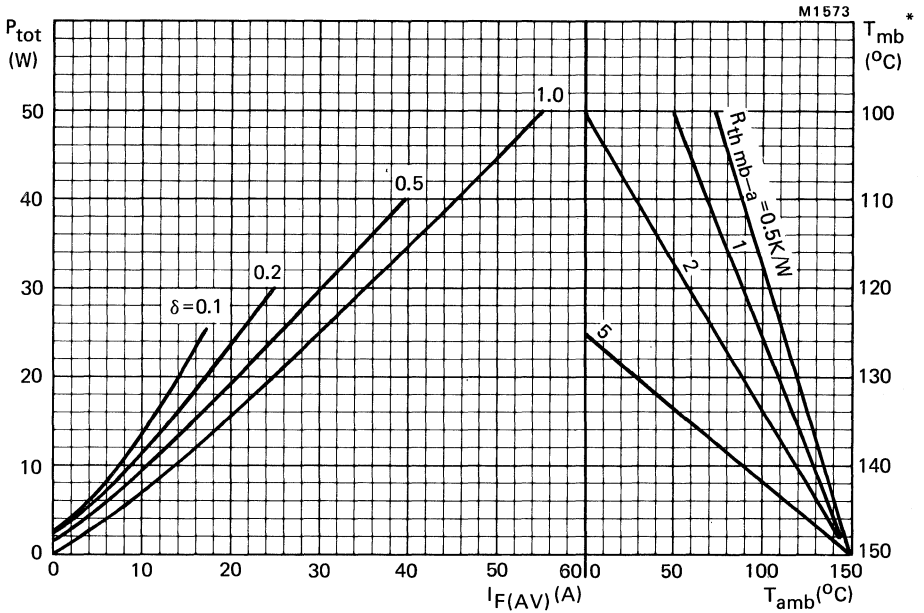
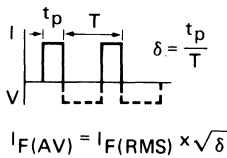


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 500$ kHz.



* T_{mb} scale is for comparison purposes and is correct only for $R_{th\ mb-a} < 3.6\ K/W$.

SINUSOIDAL OPERATION

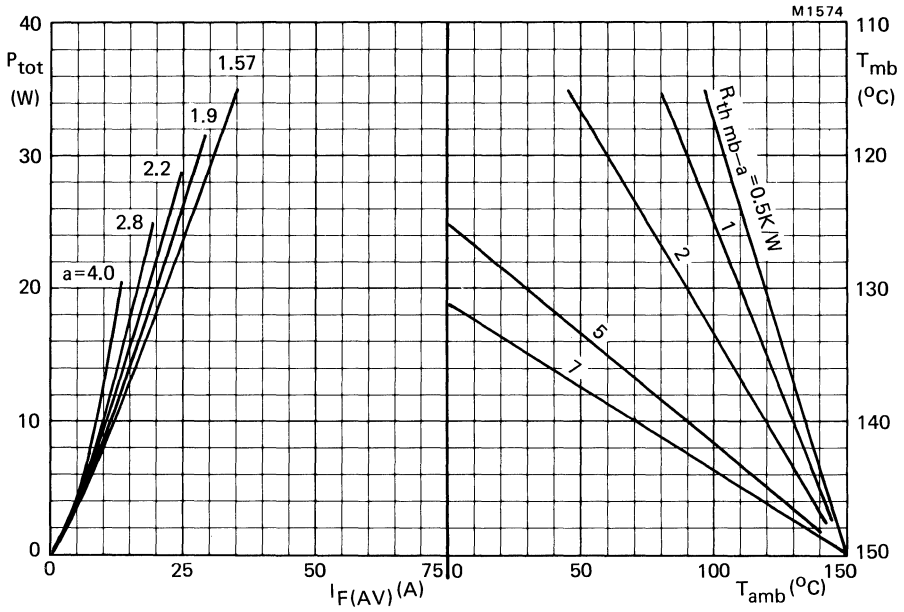


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses and switching losses up to $f = 500$ kHz.

$a = \text{form factor} = I_F(RMS) / I_F(AV)$

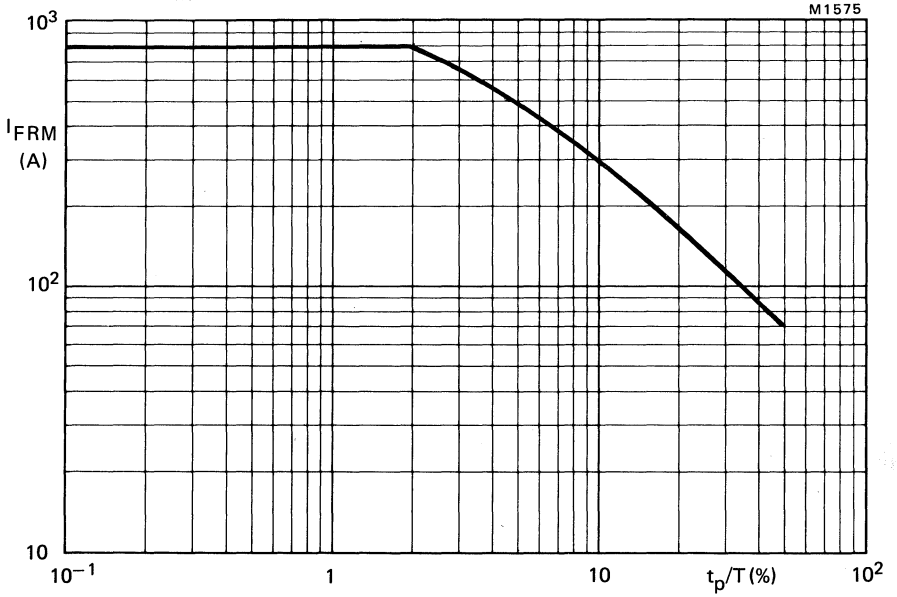
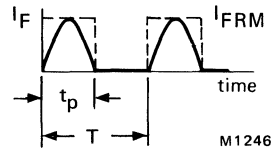
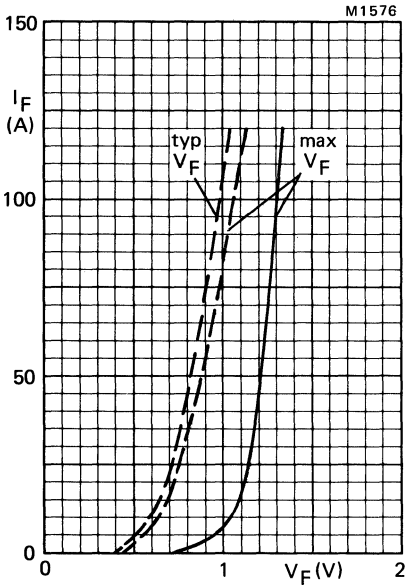


Fig.6 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.7 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$.

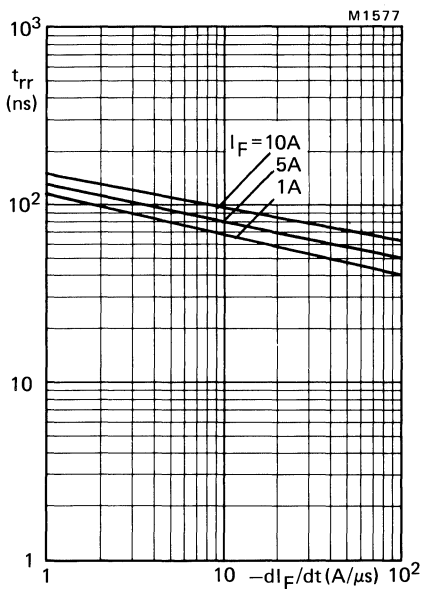


Fig.8 Maximum t_{rr} at $T_j = 25^\circ\text{C}$.

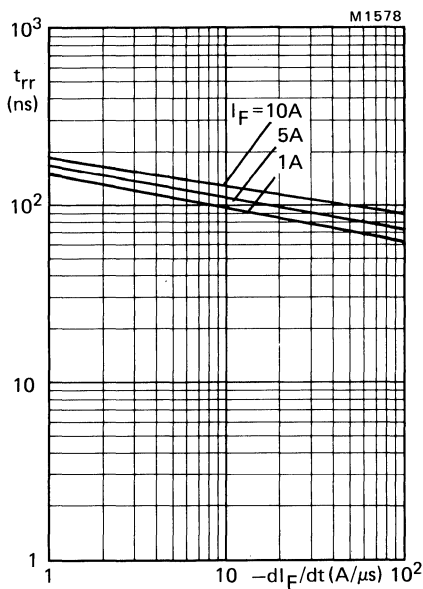


Fig.9 Maximum t_{rr} at $T_j = 100^\circ\text{C}$.

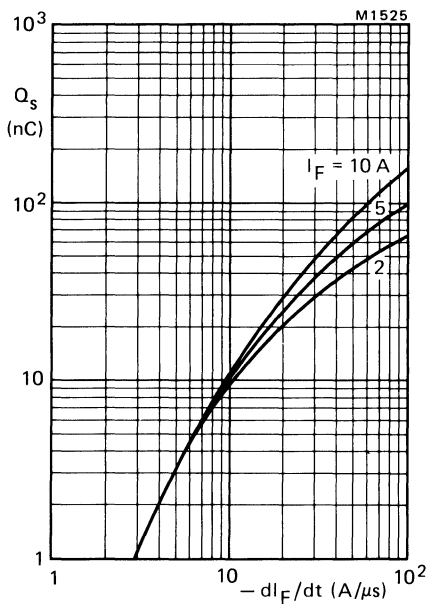


Fig.10 Maximum Q_s at $T_j = 25^\circ\text{C}$.

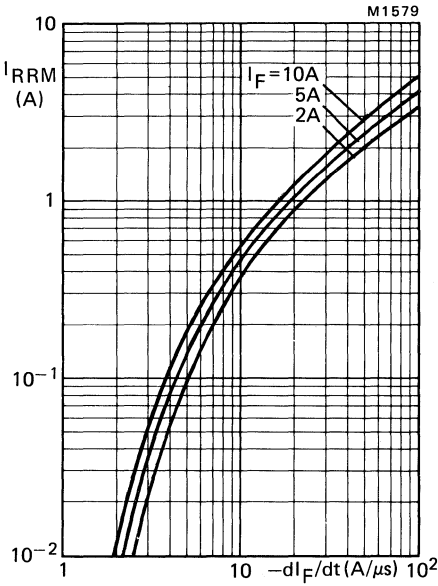


Fig.11 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

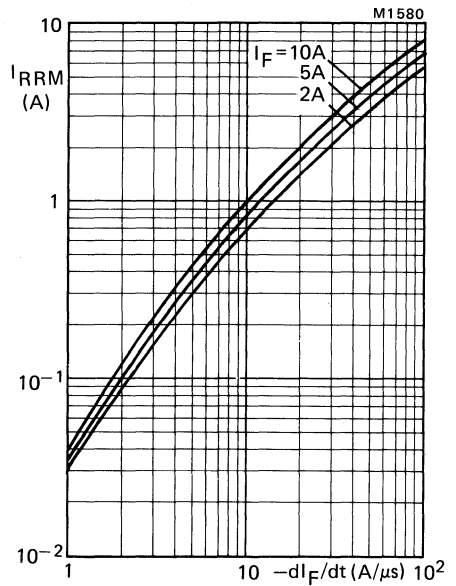


Fig.12 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

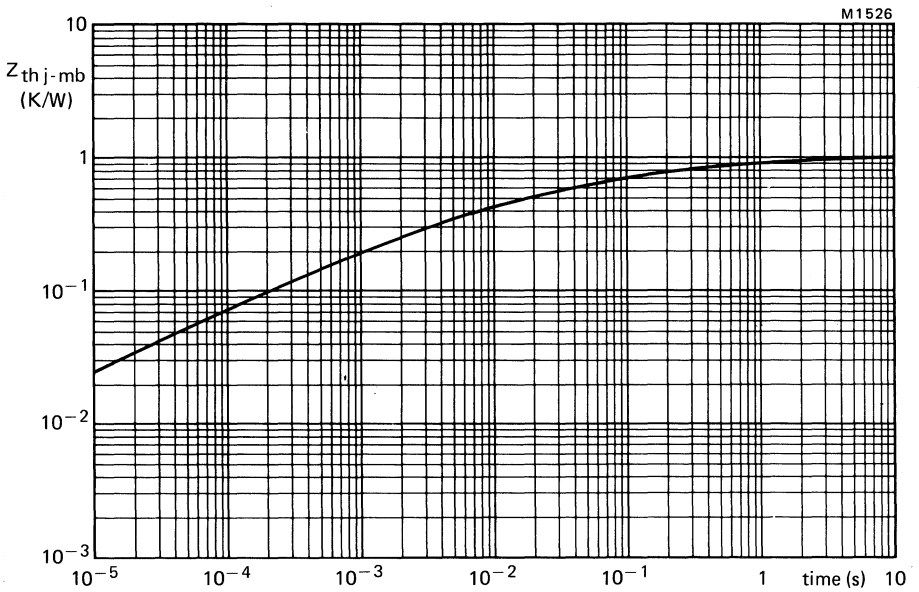


Fig.13 Transient thermal impedance.

ULTRA FAST RECOVERY RECTIFIER DIODES



Glass-passivated, high-efficiency epitaxial rectifier diodes in DO-5 metal envelopes, featuring low forward voltage drop, ultra fast reverse recovery times, very low stored charge and soft recovery characteristic. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where low conduction and switching losses are essential. The series consists of normal polarity (cathode to stud) types.

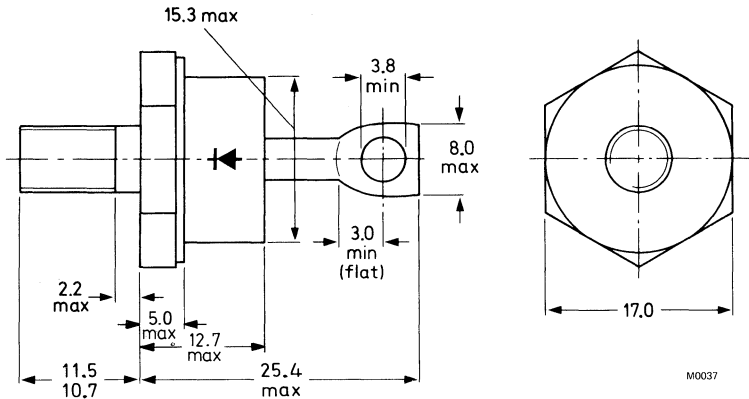
QUICK REFERENCE DATA

		BYW93-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Average forward current	$I_F(AV)$	max.		60		A
Forward voltage	V_F	<		0.8		V
Reverse recovery time	t_{rr}	<		45		ns

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5; with metric M6 stud (ϕ 6 mm): e.g. BYW93-50
with $\frac{1}{4}$ in x 28 UNF stud (ϕ 6.35 mm); e.g. BYW93-50U



Net mass: 22 g

Diameter of clearance hole: max. 6.5 mm

Accessories supplied on request:
see ACCESSORIES section.

Supplied with device: 1 nut, 1 lock washer

Torque on nut: min. 1.7 Nm (17 kg cm)
max. 3.5 Nm (35 kg cm)

Nut dimensions across the flats: M6: 10 mm,
 $\frac{1}{4}$ in x 28 UNF: 11.1 mm



Products approved to CECC 50 009-028, available on request.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages		BYW93-50	100	150	200	
Repetitive peak reverse voltage	V_{RRM}	max. 50	100	150	200	V
Crest working reverse voltage	V_{RWM}	max. 50	100	150	200	V
Continuous reverse voltage*	V_R	max. 50	100	150	200	V
Currents						
Average forward current; switching losses negligible up to 500 kHz						
square wave; $\delta = 0.5$; up to $T_{mb} = 110^\circ\text{C}$		$I_F(AV)$	max.	60		A
up to $T_{mb} = 125^\circ\text{C}$		$I_F(AV)$	max.	40		A
sinusoidal; up to $T_{mb} = 115^\circ\text{C}$		$I_F(AV)$	max.	50		A
up to $T_{mb} = 125^\circ\text{C}$		$I_F(AV)$	max.	38		A
R.M.S. forward current		$I_F(RMS)$	max.	85		A
Repetitive peak forward current						
$t_p = 20 \mu\text{s}$; $\delta = 0.02$		I_{FRM}	max.	1500		A
Non-repetitive peak forward current						
half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWMmax} ;						
$t = 10 \text{ ms}$		I_{FSM}	max.	800		A
$t = 8.3 \text{ ms}$		I_{FSM}	max.	1000		A
$I^2 t$ for fusing ($t = 10 \text{ ms}$)		$I^2 t$	max.	3200		A^2s
Temperatures						
Storage temperature		T_{stg}		-55 to +150		$^\circ\text{C}$
Junction temperature		T_j	max.	150		$^\circ\text{C}$
THERMAL RESISTANCE						
From junction to mounting base		$R_{th j-mb}$	=	0.7		K/W
From mounting base to heatsink						
a. with heatsink compound		$R_{th mb-h}$	=	0.2		K/W
b. without heatsink compound		$R_{th mb-h}$	=	0.3		K/W
Transient thermal impedance; $t = 1 \text{ ms}$		$Z_{th j-mb}$	=	0.32		K/W

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

*To ensure thermal stability: $R_{th j-a} \leq 3.0 \text{ K/W}$.

CHARACTERISTICS

Forward voltage

$I_F = 50 \text{ A}; T_j = 150 \text{ }^\circ\text{C}$
 $I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

V_F	<	0.8	V*
V_F	<	1.3	V*

Reverse current

$V_R = V_{RWM} \text{ max}; T_j = 100 \text{ }^\circ\text{C}$
 $T_j = 25 \text{ }^\circ\text{C}$

I_R	<	5	mA
I_R	<	250	μA

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 100 \text{ A}/\mu\text{s}$;
 $T_j = 25 \text{ }^\circ\text{C}$; recovery time

t_{rr}	<	45	ns
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$I_F = 2 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 20 \text{ A}/\mu\text{s}$
 $T_j = 25 \text{ }^\circ\text{C}$; recovered charge

Q_s	<	35	nC
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$I_F = 10 \text{ A to } V_R \geq 30 \text{ V}$ with $-dI_F/dt = 50 \text{ A}/\mu\text{s}$;
 $T_j = 100 \text{ }^\circ\text{C}$; peak recovery current

I_{RRM}	<	6	A
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Forward recovery when switched to $I_F = 10 \text{ A}$
 with $dI_F/dt = 10 \text{ A}/\mu\text{s}$; $T_j = 25 \text{ }^\circ\text{C}$

V_{fr}	typ.	1.0	V
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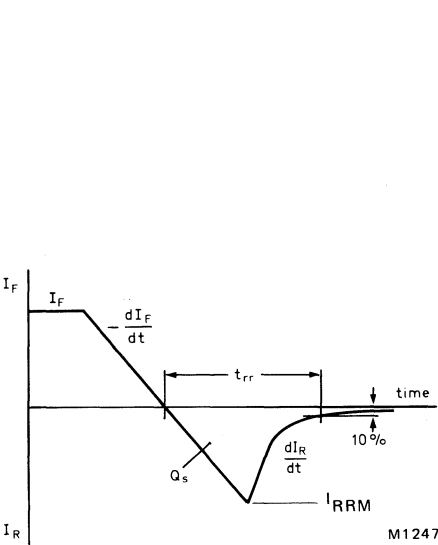


Fig.2 Definition of t_{rr} , Q_s and I_{RRM} .

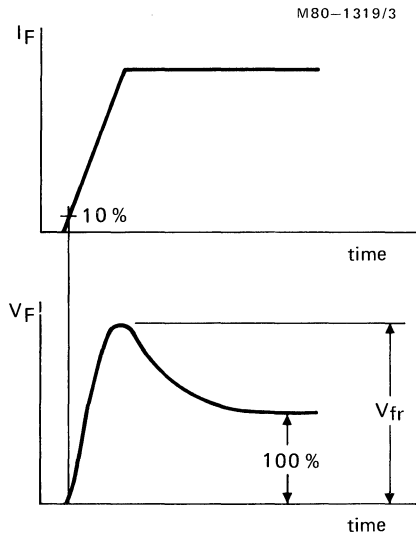


Fig.3 Definition of V_{fr} .

*Measured under pulse conditions to avoid excessive dissipation.

SQUARE-WAVE OPERATION

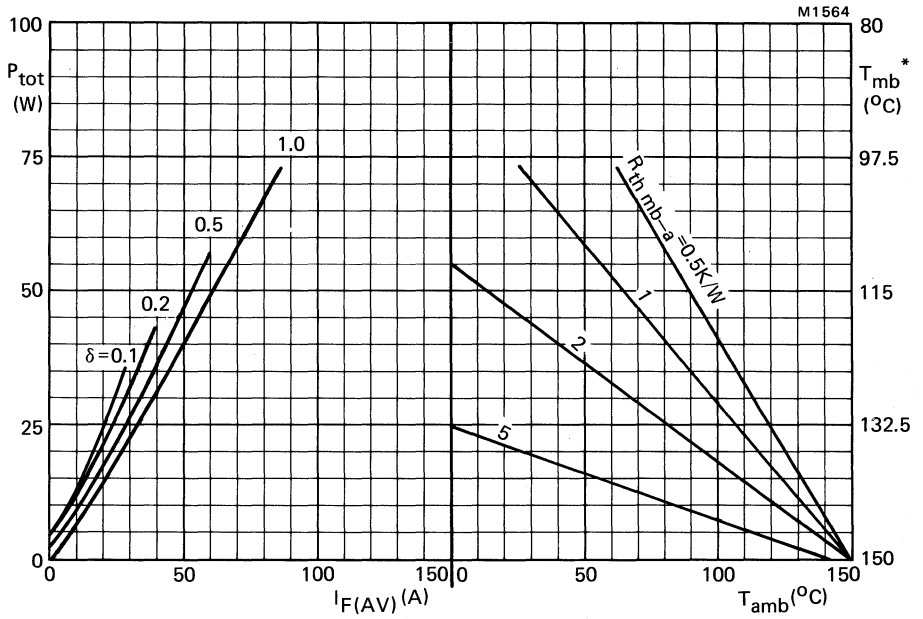
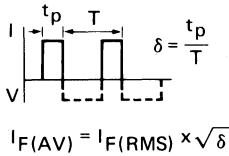


Fig.4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses.



* T_{mb} scale is for comparison purposes and is correct only for $R_{th mb-a} < 2.1 K/W$

SINUSOIDAL OPERATION

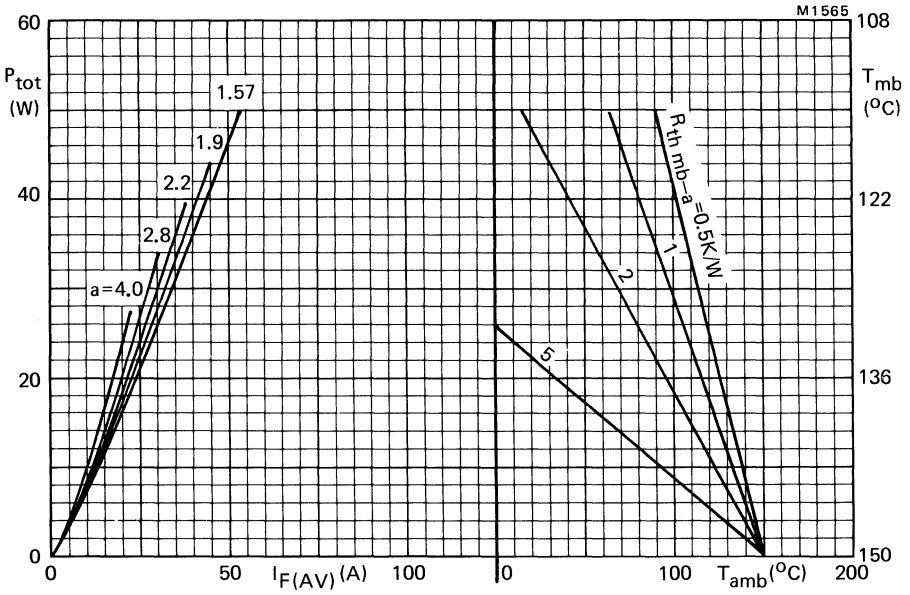


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures. Power includes reverse current losses.
 $a = \text{form factor} = I_{F(RMS)}/I_{F(AV)}$.

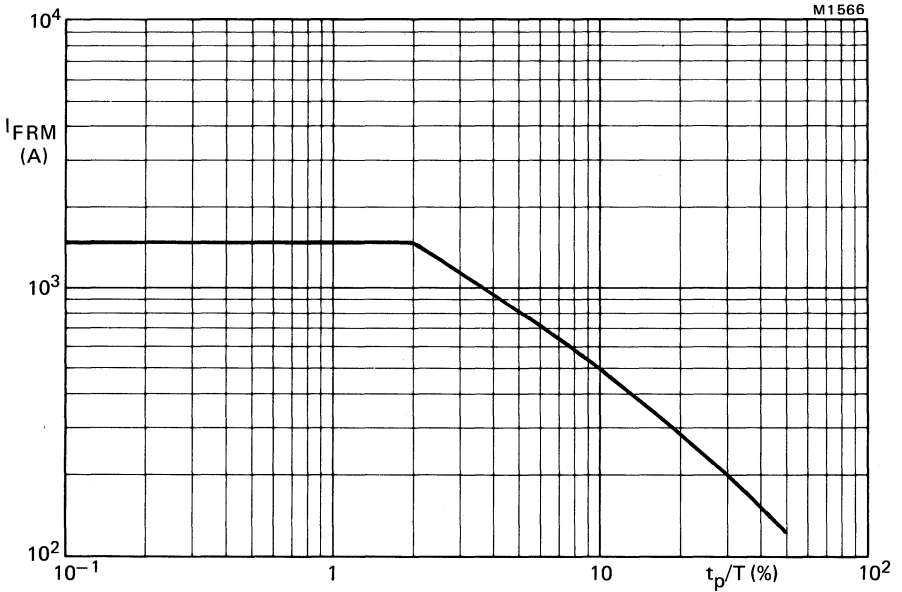
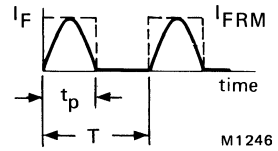
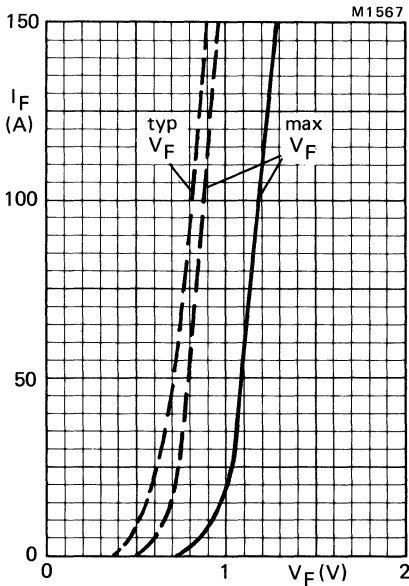


Fig.6 Maximum permissible repetitive peak forward current for square or sinusoidal currents; $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.7 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 150 \text{ }^\circ\text{C}$.

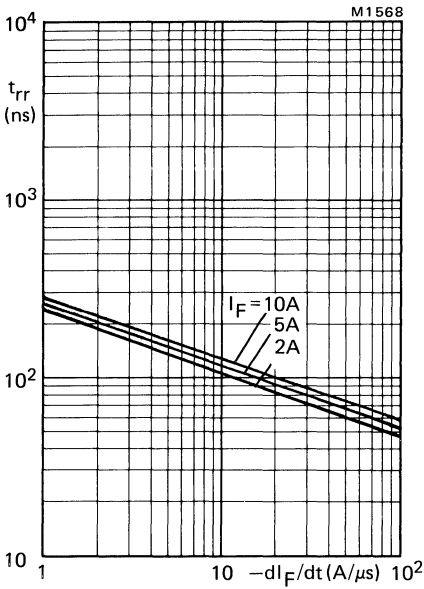


Fig.8 Maximum t_{rr} at $T_j = 25$ °C.

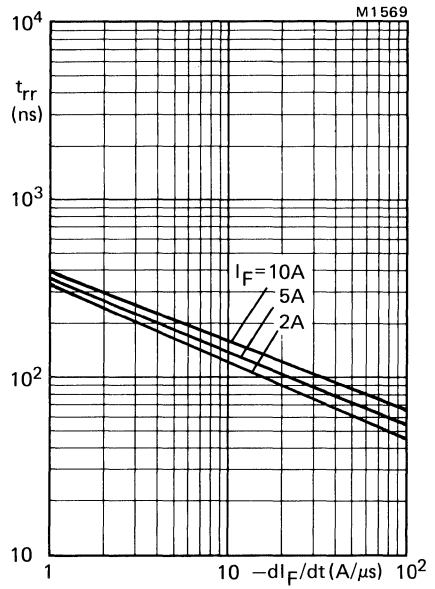


Fig.9 Maximum t_{rr} at $T_j = 100$ °C.

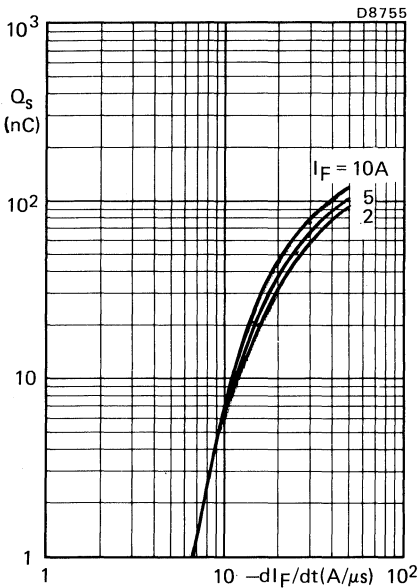


Fig.10 Maximum Q_s at $T_j = 25$ °C.

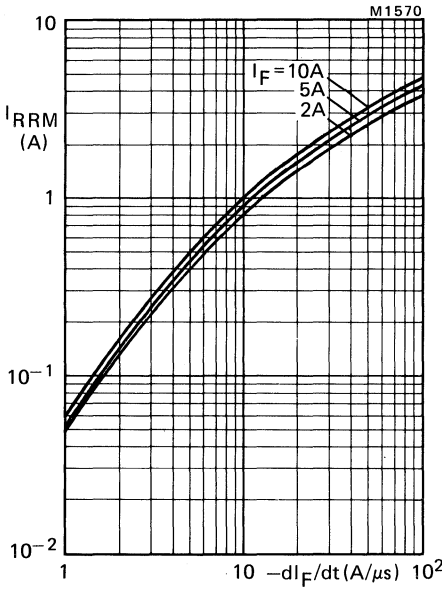


Fig.11 Maximum I_{RRM} at $T_j = 25\text{ }^\circ\text{C}$.

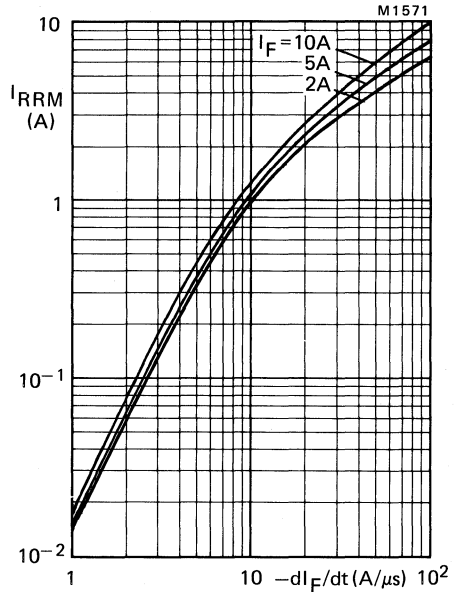


Fig.12 Maximum I_{RRM} at $T_j = 100\text{ }^\circ\text{C}$.

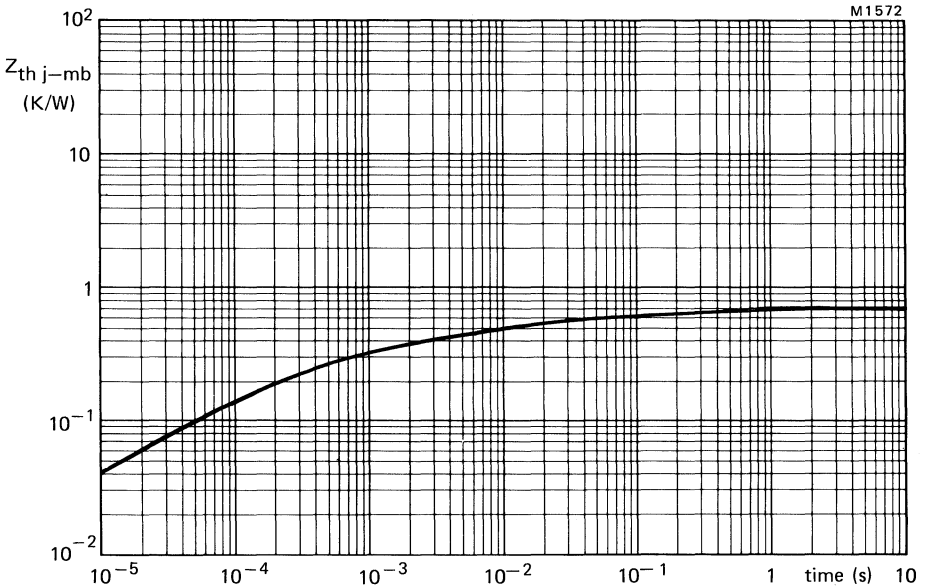


Fig.13 Transient thermal impedance.

FAST SOFT-RECOVERY RECTIFIER DIODES

● With controlled avalanche

Also available to BS9333-F002

Diffused silicon diodes in DO-4 metal envelopes, capable of absorbing transients. They are primarily intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications.

The series consists of the following types :

Normal polarity (cathode to stud): BYX30-200 to BYX30-600

Reverse polarity (anode to stud): BYX30-200R to BYX30-600R.

QUICK REFERENCE DATA

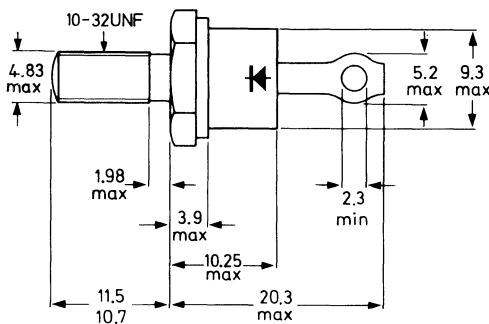
	BYX30-200(R)	300(R)	400(R)	500(R)	600(R)
Crest working reverse voltage V_{RWM}	max. 200	300	400	500	600 V
Reverse avalanche breakdown voltage $V_{(BR)R}$	> 250	375	500	625	750 V
Average forward current $I_{F(AV)}$		max.	14		A
Non-repetitive peak forward current I_{FSM}		max.	250		A
Non-repetitive peak reverse power P_{RSM}		max.	18		kW
Reverse recovery time t_{rr}		<	200		ns

MECHANICAL DATA

Dimensions in mm

DO-4; Supplied with device: 1 nut, 1 lock-washer

Nut dimensions across the flats: 9.5 mm



M0184A

Net mass: 7 g

Diameter of clearance hole: max. 5.2 mm

Accessories supplied on request:

see ACCESSORIES section

Torque on nut: min. 0.9 Nm

(9 kg cm)

max. 1.7 Nm

(17 kg cm)

The mark shown applies to the normal polarity types.

BYX30 SERIES

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC134)

<u>Voltages</u> ¹⁾		BYX30-200(R)	300(R)	400(R)	500(R)	600(R)
Crest working reverse voltage	V_{RWM}	max. 200	300	400	500	600 V
Continuous reverse voltage	V_R	max. 200	300	400	500	600 V

Currents

Average forward current (averaged over any 20 ms period) up to $T_{mb} = 100^\circ\text{C}$ at $T_{mb} = 125^\circ\text{C}$	$I_{F(AV)}$	max.	14 A
	$I_{F(AV)}$	max.	7.5 A
R. M. S. forward current	$I_{F(RMS)}$	max.	22 A
Repetitive peak forward current	I_{FRM}	max.	310 A
Non-repetitive peak forward current ($t = 10\text{ ms}$; half-sinewave) $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max.	I_{FSM}	max.	250 A
I^2t for fusing ($t = 10\text{ ms}$)	I^2t	max.	312 A ² s

Reverse power dissipation

Repetitive peak reverse power dissipation $t = 10\text{ }\mu\text{s}$ (square wave; $f = 50\text{ Hz}$) $T_j = 150^\circ\text{C}$	$PRRM$	max.	5.5 kW
Non-repetitive peak reverse power dissipation $t = 10\text{ }\mu\text{s}$ (square wave) $T_j = 25^\circ\text{C}$ prior to surge $T_j = 150^\circ\text{C}$ prior to surge	$PRSM$	max.	18 kW
	$PRSM$	max.	5.5 kW

Temperatures

Storage temperature	T_{stg}	-55 to +150	$^\circ\text{C}$
Junction temperature	T_j	max.	150 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to ambient in free air	$R_{th\ j-a}$	=	50 $^\circ\text{C/W}$
From junction to mounting base	$R_{th\ j-mb}$	=	1.3 $^\circ\text{C/W}$
From mounting base to heatsink	$R_{th\ mb-h}$	=	0.5 $^\circ\text{C/W}$

¹⁾ To ensure thermal stability: $R_{th\ j-a} < 2.5\text{ }^\circ\text{C/W}$ (continuous reverse voltage) or $< 5\text{ }^\circ\text{C/W}$ (a. c.).

For smaller heatsinks T_j max should be derated. For a. c. see page 469.

For continuous reverse voltage: if $R_{th\ j-a} = 5\text{ }^\circ\text{C/W}$, then T_j max = $135\text{ }^\circ\text{C}$.

if $R_{th\ j-a} = 10\text{ }^\circ\text{C/W}$, then T_j max = $120\text{ }^\circ\text{C}$.

CHARACTERISTICS

	BYX30-200(R)	300(R)	400(R)	500(R)	600(R)	
<u>Forward voltage</u>						
$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	$V_F < 3.2$	3.2	3.2	3.2	3.2	V ¹⁾
<u>Reverse breakdown voltage</u>						
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R} > 250$	375	500	625	750	V
	< 1050	1050	1050	1050	1050	V
<u>Reverse current</u>						
$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	$I_R < 4.0$	4.0	4.0	4.0	4.0	mA

Reverse recovery charge when switched from

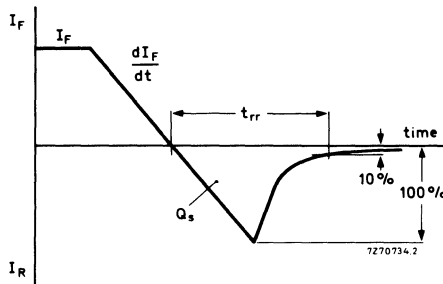
$I_F = 2 \text{ A to } V_R \geq 30 \text{ V};$
 with $-dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$Q_s <$	0.70	μC
---------	--------	---------------

Reverse recovery time when switched from

$I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$
 $-dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

$t_{rr} <$	200	ns
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OPERATING NOTES

1. Square-wave operation

When I_F has been flowing sufficiently long for the steady state to be established, there will be a charge due to minority carriers present. Before the device can block in the reverse direction this charge must be extracted. This extraction takes the form of a reverse transient (see figure above). The majority of the power dissipation due to the reverse transient occurs during fall time as the rectifier gradually becomes reverse biased, and the mean power will be proportional to the operating frequency. The mean value of this power loss can be derived from the graphs on page 474.

¹⁾ Measured under pulse conditions to avoid excessive dissipation.

OPERATING NOTES (continued)

2. Sine wave operation

Power loss in sine wave operation will be considerably less owing to the much slower rate of change of the applied voltage (and consequently lower values of I_{RRM}), so that power loss due to reverse recovery may be safely ignored for frequencies up to 20 kHz.

3. Determination of the heatsink thermal resistance

Example:

Assume a diode, used in an inverter.

frequency	f	=	20	kHz
duty cycle	δ	=	0.5	
ambient temperature	T_{amb}	=	45	°C
switched from	I_F	=	12	A
to	V_R	=	400	V
at a rate	$-\frac{dI}{dt}$	=	20	A/ μ s

At a duty cycle $\delta = 0.5$ the average forward current $I_{FAV} = 6$ A.

From the upper graph on page 469 it follows, that at $I_{FAV} = 6$ A the average forward power + average leakage power = 15 W (point A).

The additional power losses due to switching-off can be read from the nomogram on page 474 (the example being based on optimum use, i.e. $T_j = 150$ °C). Starting from $I_F = 12$ A on the horizontal scale trace upwards until the appropriate line

$-\frac{dI}{dt} = 20$ A/ μ s. From the intersection trace horizontally to the right until the line for $f = 20$ kHz. Then trace downwards to the line $V_R = 400$ V and ultimately trace horizontally to the left and on the vertical axis read the additional average power dissipation $P_{RAV} = 4$ W.

Therefore the total power dissipation $P_{tot} = 15$ W + 4 W = 19 W (point B of the upper graph on page 469). From the right hand part follows the thermal resistance required at $T_{amb} = 45$ °C.

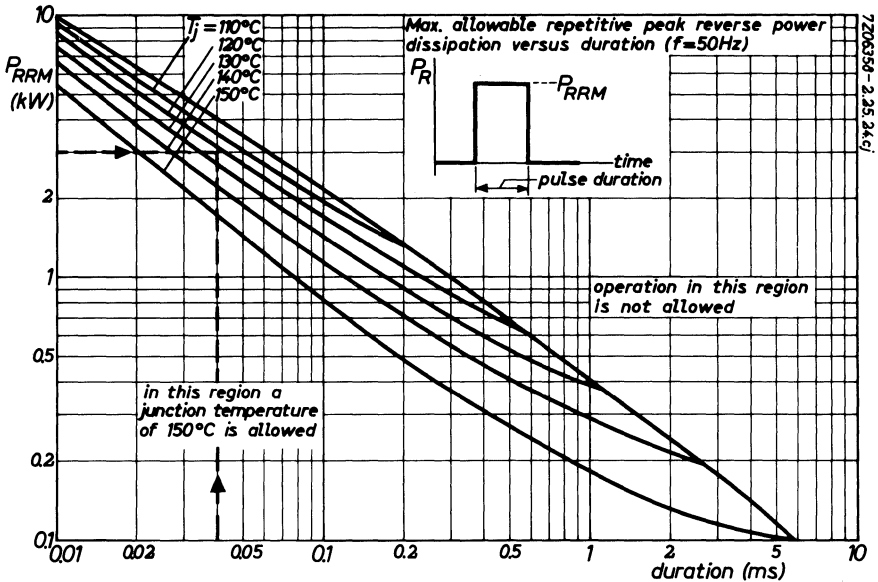
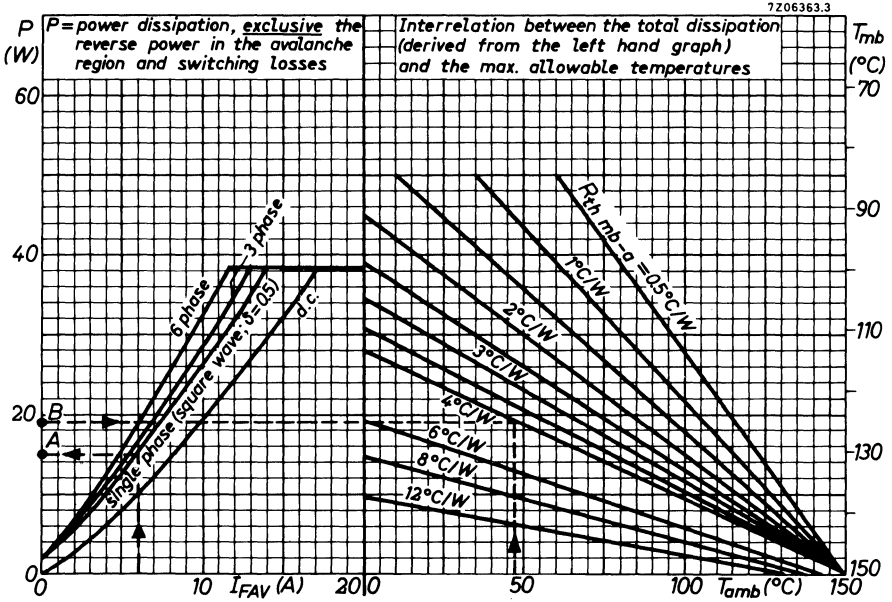
$$R_{th\ mb-a} \approx 4 \text{ °C/W}$$

The contact thermal resistance $R_{th\ mb-h} = 0.5$ °C/W.

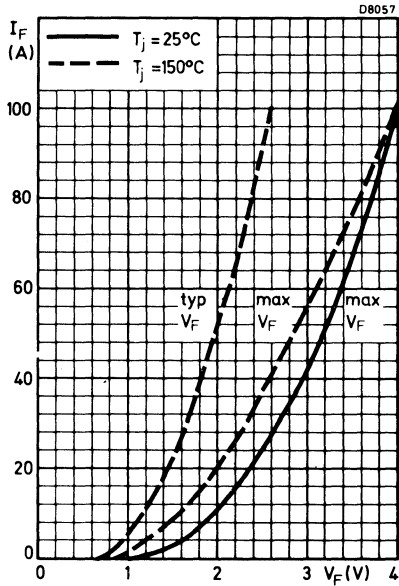
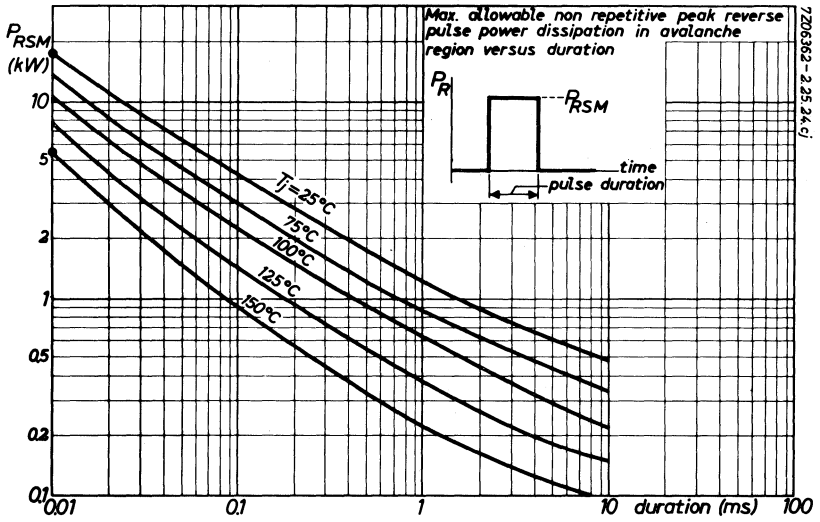
Hence the heatsink thermal resistance should be:

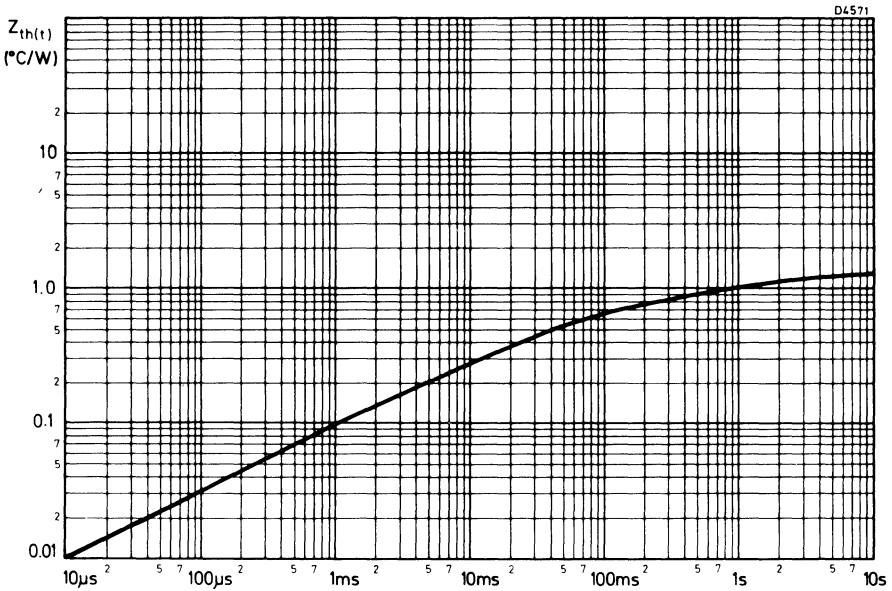
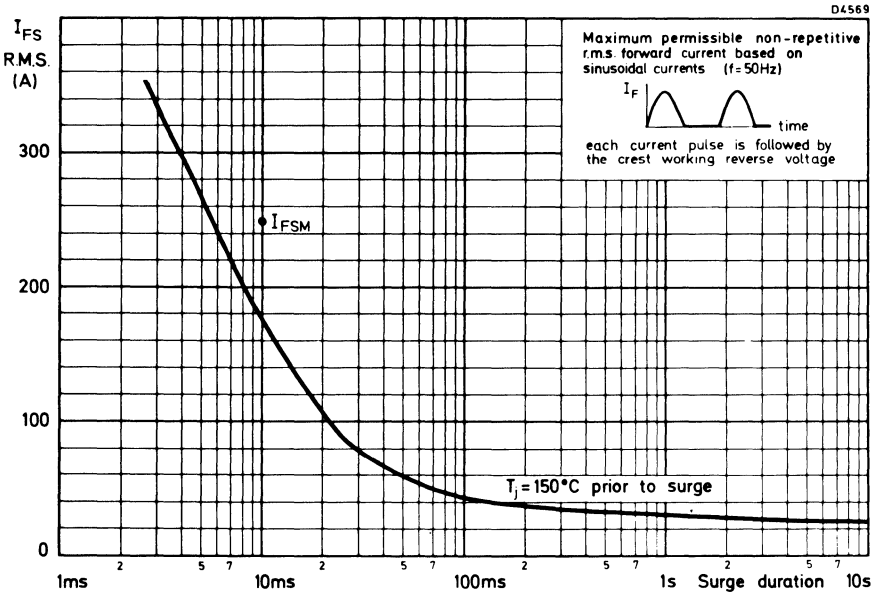
$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h} = (4 - 0.5) \text{ °C/W} = 3.5 \text{ °C/W.}$$

BYX30 SERIES

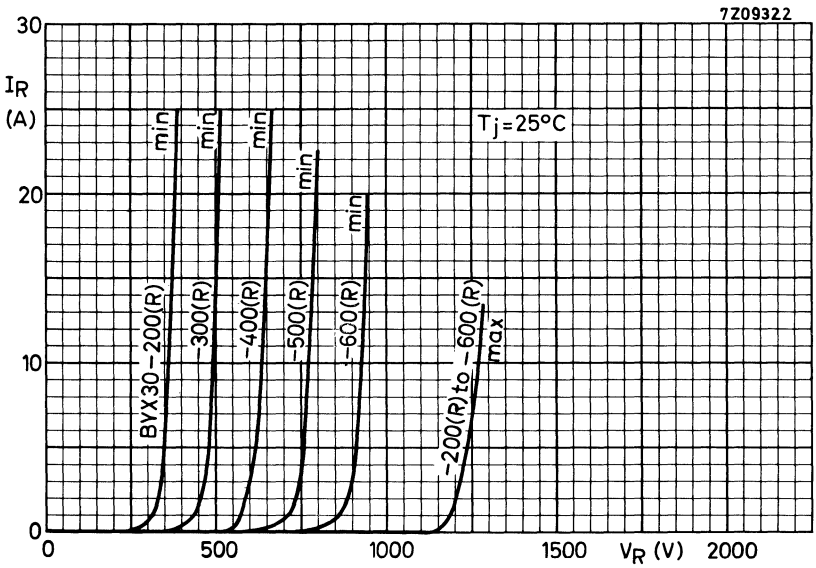
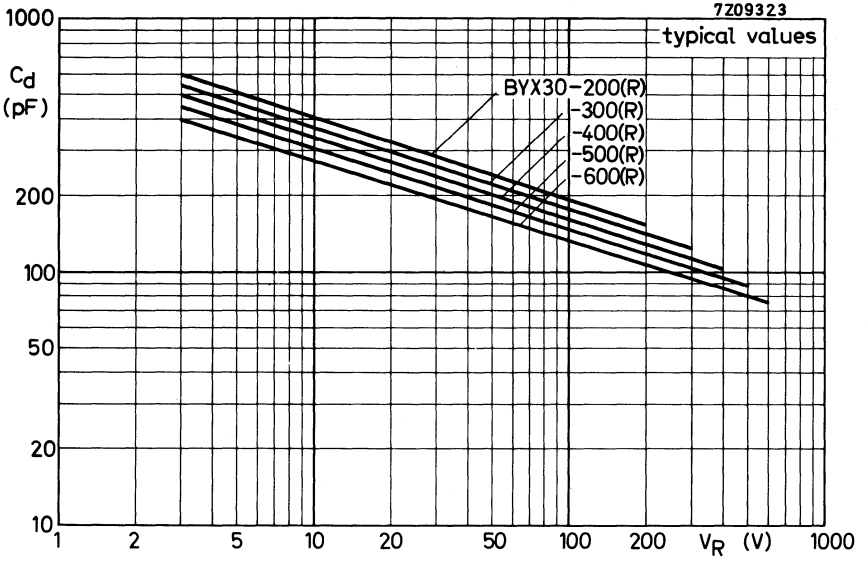


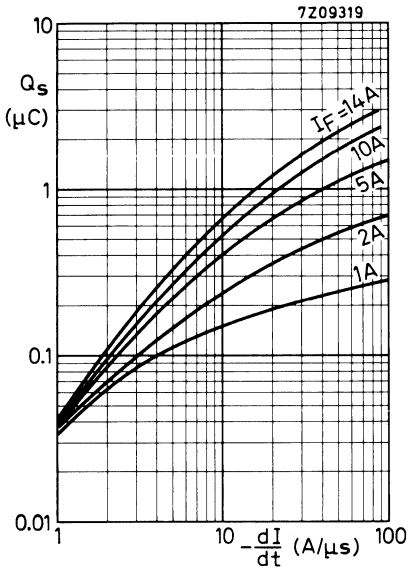
BYX30 SERIES



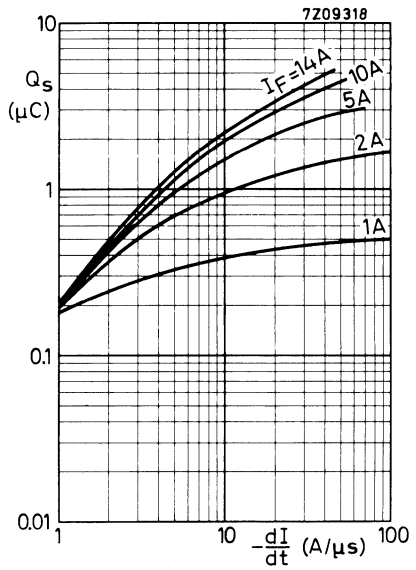


**BYX30
SERIES**

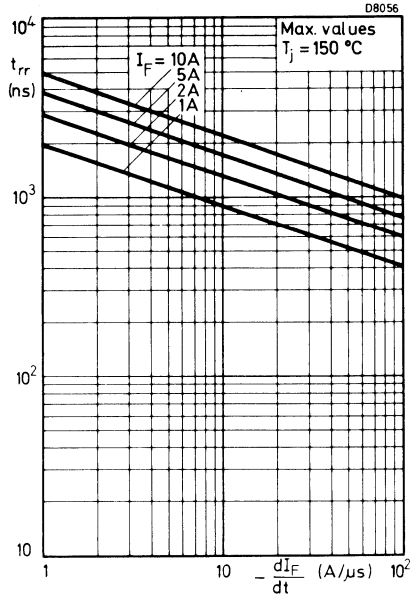
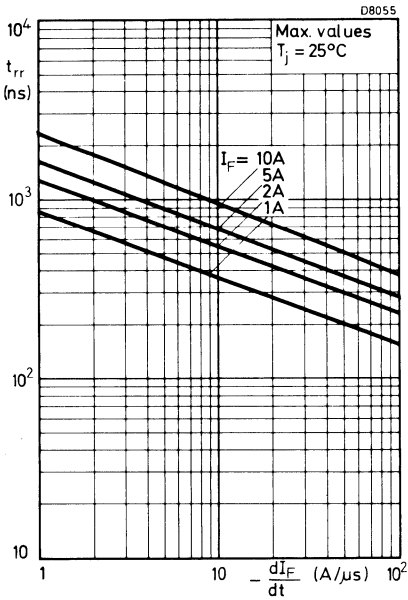




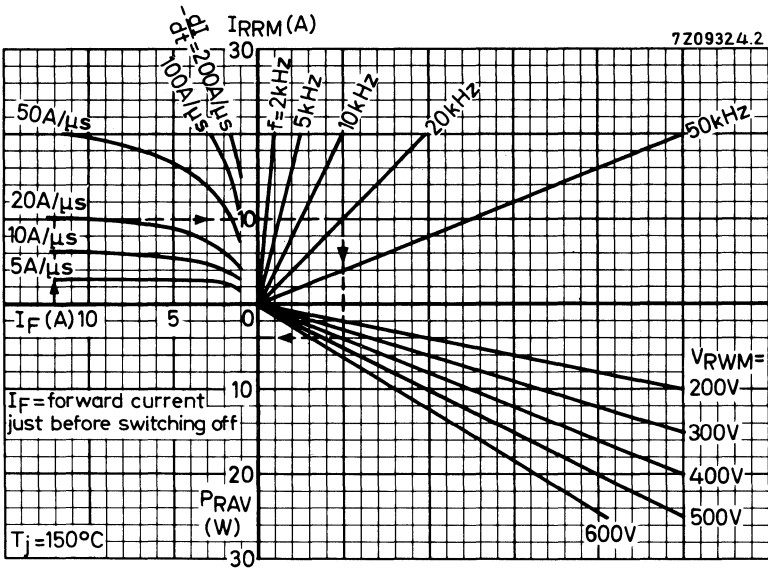
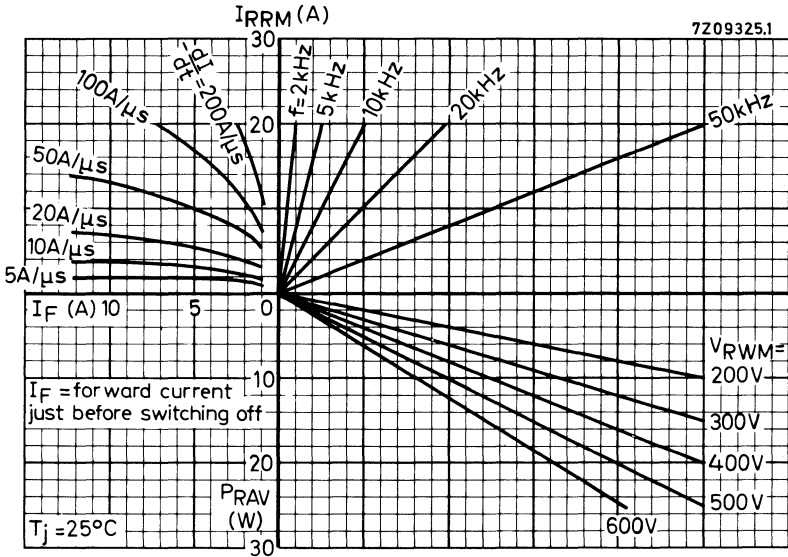
Maximum values; $T_j = 25^\circ\text{C}$; switched from I_F to $V_R \geq 30\text{ V}$.



Maximum values; $T_j = 150^\circ\text{C}$; switched from I_F to $V_R \geq 30\text{ V}$.



**BYX30
SERIES**



Nomogram: Power loss P_{RAV} due to switching only (square wave operation)

FAST SOFT-RECOVERY RECTIFIER DIODES

- With controlled avalanche

Diffused silicon diodes in DO-4 metal envelopes, capable of absorbing transients. They are primarily intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications.

The series consists of the following types:

Normal polarity (cathode to stud): BYX46-200 to BYX46-600.

Reverse polarity (anode to stud): BYX46-200R to BYX46-600R

QUICK REFERENCE DATA

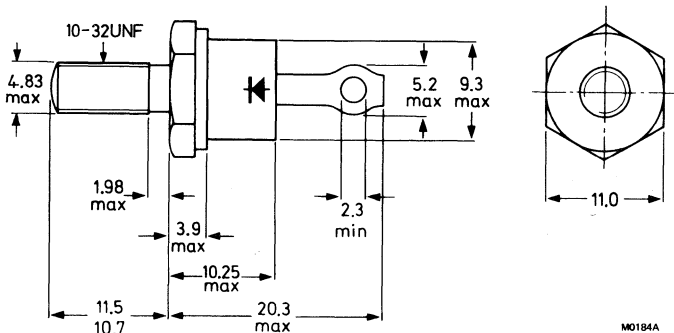
		BYX46-200(R)	300(R)	400(R)	500(R)	600(R)	
Crest working reverse voltage	V_{RWM} max.	200	300	400	500	600	V
Reverse avalanche breakdown voltage	$V_{(BR)R}$ >	250	375	500	625	750	V
Average forward current	$I_{F(AV)}$ max.				22	A	
Non-repetitive peak forward current	I_{FSM} max.				300	A	
Non-repetitive peak reverse power	P_{RSM} max.				18	kW	
Reverse recovery time	t_{rr} <				200	ns	

MECHANICAL DATA

Dimensions in mm

DO-4 Supplied with device: 1 nut, 1 lock-washer

Nut dimensions across the flats: 9,5 mm



Net mass: 7 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request:

see ACCESSORIES section

Torque on nut: min. 0,9 Nm

(9 kg cm)

max. 1,7 Nm

(17 kg cm)

The mark shown applies to the normal polarity types.

BYX46 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages *		BYX46-200(R)	300(R)	400(R)	500(R)	600(R)
Crest working reverse voltage	V_{RWM} max.	200	300	400	500	600 V
Continuous reverse voltage	V_R max.	200	300	400	500	600 V
Currents						
Average forward current (averaged over any 20 ms period)						
up to $T_{mb} = 100\text{ }^\circ\text{C}$	$I_F(AV)$ max.			22		A
at $T_{mb} = 125\text{ }^\circ\text{C}$	$I_F(AV)$ max.			15		A
R.M.S. forward current	$I_F(RMS)$ max.			35		A
Repetitive peak forward current	I_{FRM} max.			400		A
Non-repetitive peak forward current ($t = 10\text{ ms}$; half-sinewave) $T_j = 165\text{ }^\circ\text{C}$ prior to surge; with reapplied						
V_{RWMmax}	I_{FSM} max.			300		A
$I^2 t$ for fusing ($t = 10\text{ ms}$)	$I^2 t$ max.			450		$A^2 s$
Reverse power dissipation						
Repetitive peak reverse power dissipation $t = 10\text{ } \mu\text{s}$ (square wave; $f = 50\text{ Hz}$) $T_j = 100\text{ }^\circ\text{C}$						
	P_{RRM} max.			9,5		kW
Non-repetitive peak reverse power dissipation $t = 10\text{ } \mu\text{s}$ (square wave)						
$T_j = 25\text{ }^\circ\text{C}$ prior to surge	P_{RSM} max.			18		kW
$T_j = 165\text{ }^\circ\text{C}$ prior to surge	P_{RSM} max.			4		kW
Temperatures						
Storage temperature	T_{stg}			-55 to +165		$^\circ\text{C}$
Junction temperature	T_j max.			165		$^\circ\text{C}$

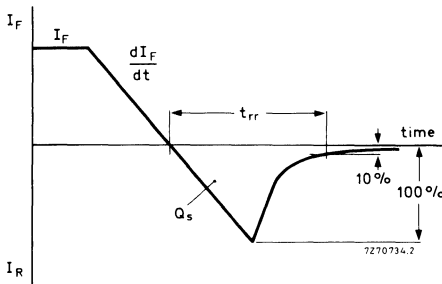
THERMAL RESISTANCE

From junction to ambient in free air	$R_{th\ j-a}$ =		50	$^\circ\text{C/W}$
From junction to mounting base	$R_{th\ j-mb}$ =		1,3	$^\circ\text{C/W}$
From mounting base to heatsink	$R_{th\ mb-h}$ =		0,5	$^\circ\text{C/W}$

* To ensure thermal stability: $R_{th\ j-a} < 2,5\text{ }^\circ\text{C/W}$ (continuous reverse voltage) or $< 5\text{ }^\circ\text{C/W}$ (a.c.). For smaller heatsinks $T_{j\ max}$ should be derated. For a.c. see page 479. For continuous reverse voltage: if $R_{th\ j-a} = 5\text{ }^\circ\text{C/W}$, then $T_{j\ max} = 135\text{ }^\circ\text{C}$; if $R_{th\ j-a} = 10\text{ }^\circ\text{C/W}$, then $T_{j\ max} = 125\text{ }^\circ\text{C}$.

CHARACTERISTICS

		BYX46-200(R)	300(R)	400(R)	500(R)	600(R)
Forward voltage $I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	V_F	<	2,0	2,0	2,0	2,0 V *
Reverse breakdown voltage $I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	>	250	375	500	625 V
		<	1050	1050	1050	1050 V
Reverse current $V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$	I_R	<	4,0	4,0	4,0	4,0 mA
Reverse recovery charge when switched from $I_F = 2 \text{ A to } V_R \geq 30 \text{ V};$ $-dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	Q_s	<		0,70		μC
Reverse recovery time when switched from $I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$ $-dI_F/dt = 50 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$	t_{rr}	<		200		ns



OPERATING NOTES

1. Square-wave operation

When I_F has been flowing sufficiently long for the steady state to be established, there will be a charge due to minority carriers present. Before the device can block in the reverse direction this charge must be extracted. This extraction takes the form of a reverse transient (see figure above). The majority of the power dissipation due to the reverse transient occurs during fall time as the rectifier gradually becomes reverse biased, and the mean power will be proportional to the operating frequency. The mean value of this power loss can be derived from the graphs on page 484.

* Measured under pulse conditions to avoid excessive dissipation.

OPERATING NOTES (continued)

2. Sine wave operation

Power loss in sine wave operation will be considerably less owing to the much slower rate of change of the applied voltage (and consequently lower values of I_{RRM}), so that power loss due to reverse recovery may be safely ignored for frequencies up to 50 kHz.

3. Determination of the heatsink thermal resistance

Example:

Assume a diode, used in an inverter.

frequency	f	=	20	kHz
duty cycle	δ	=	0.5	
ambient temperature	T_{amb}	=	40	°C
switched from	I_F	=	12	A
to	V_R	=	300	V
at a rate	$-\frac{dI}{dt}$	=	50	A/ μ s

At a duty cycle $\delta = 0.5$ the average forward current $I_{FAV} = 6$ A.

From the upper graph on page 479 it follows, that at $I_{FAV} = 6$ A the average forward power + average leakage power = 13 W (point A).

The additional power losses due to switching-off can be read from the nomogram on page 484 (the example being based on optimum use, i.e. $T_j = 165$ °C). Starting from $I_F = 12$ A on the horizontal scale trace upwards until the appropriate line

$-\frac{dI}{dt} = 50$ A/ μ s. From the intersection trace horizontally to the right until the line for $f = 20$ kHz. Then trace downwards to the line $V_R = 300$ V and ultimately trace horizontally to the left and on the vertical axis read the additional average power dissipation $P_{RAV} = 6$ W.

Therefore the total power dissipation $P_{tot} = 13$ W + 6 W = 19 W (point B of the upper graph on page 479).

From the right hand part of the upper graph on page 479 follows the thermal resistance, required at $T_{amb} = 40$ °C.

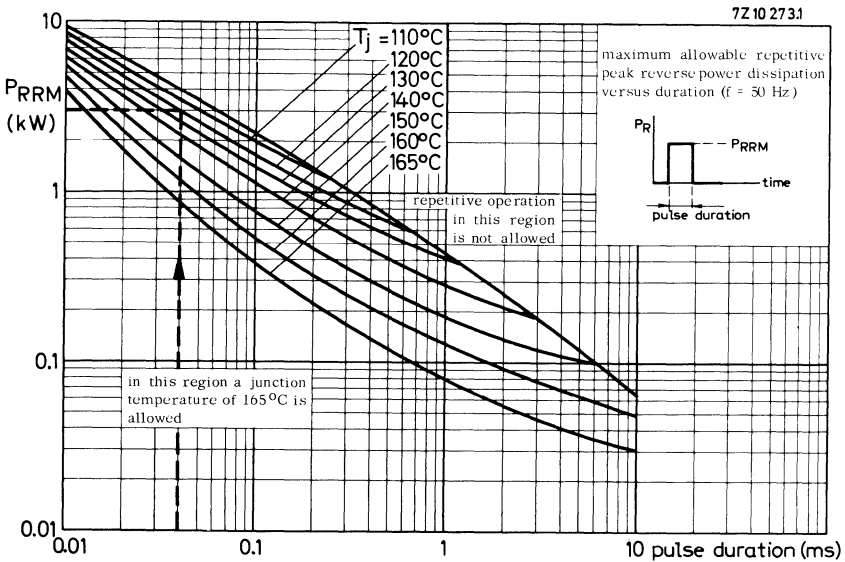
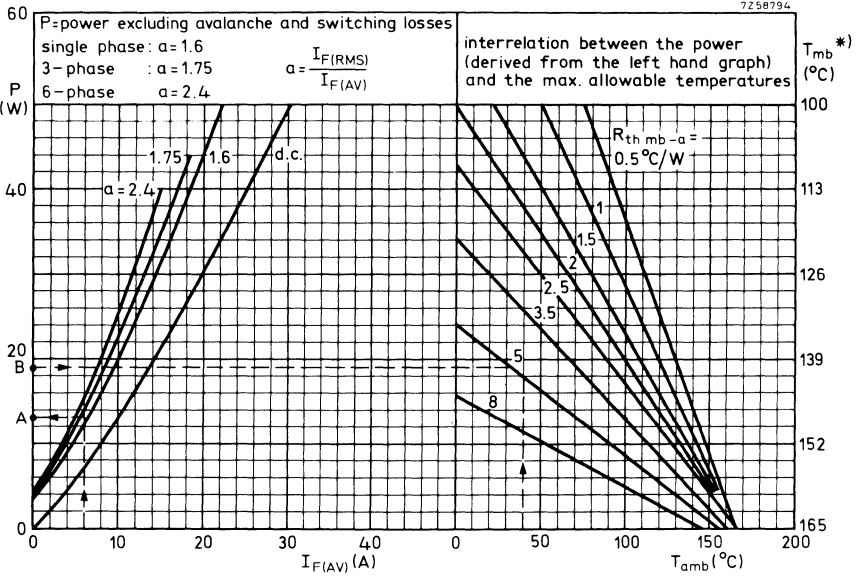
$$R_{th\ mb-a} \approx 5\text{ °C/W}$$

The contact thermal resistance $R_{th\ mb-h} = 0.5$ °C/W.

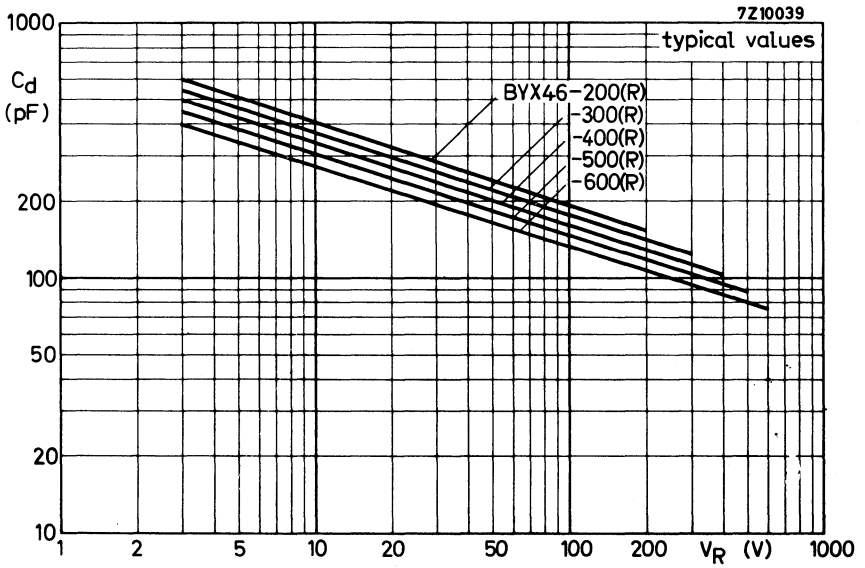
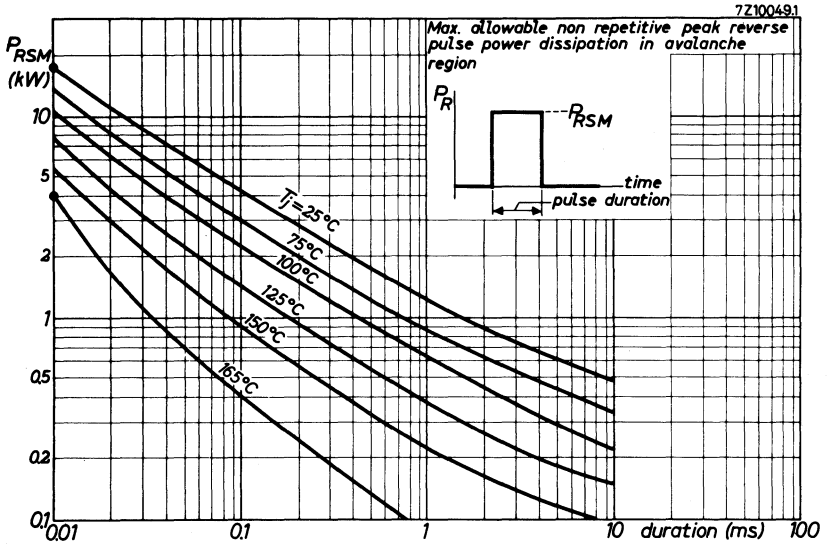
Hence the heatsink thermal resistance should be:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h} = (5 - 0.5)\text{ °C/W} = 4.5\text{ °C/W}.$$

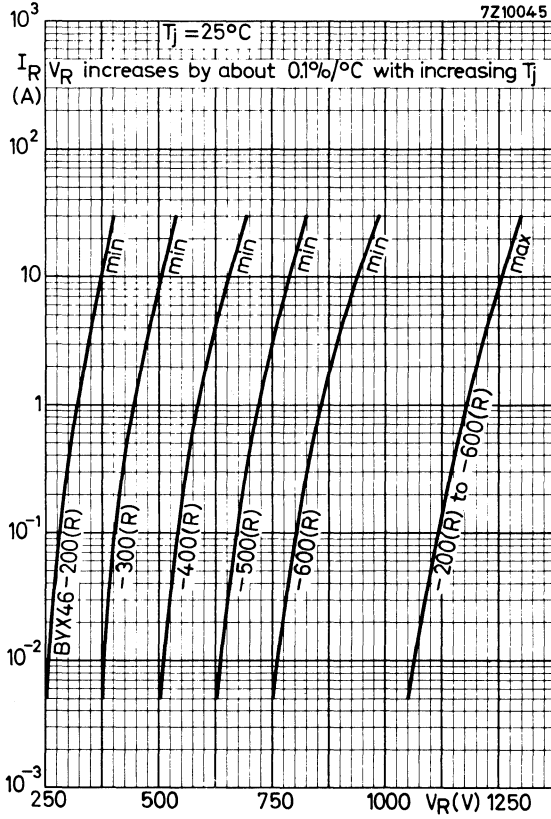
BYX 46 SERIES

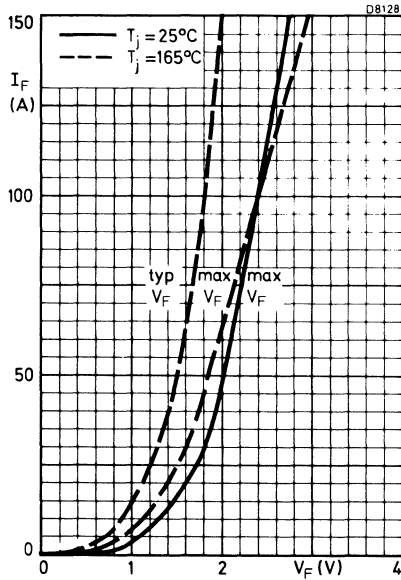
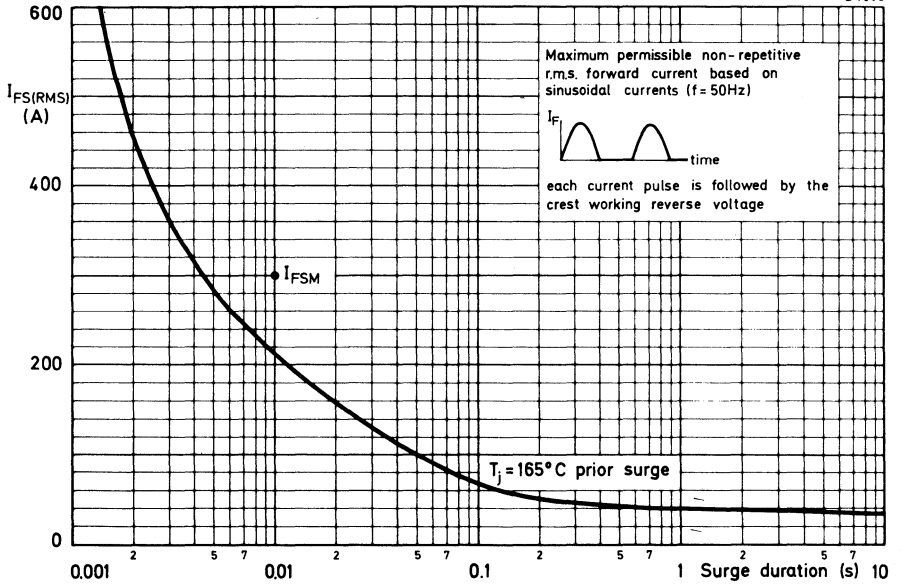


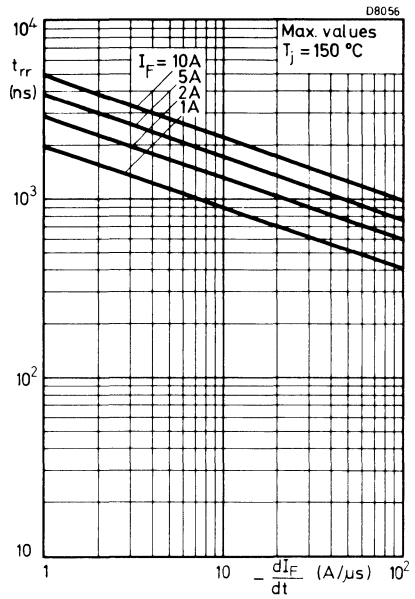
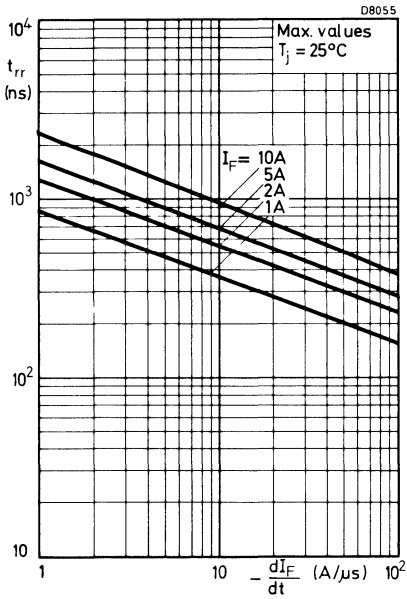
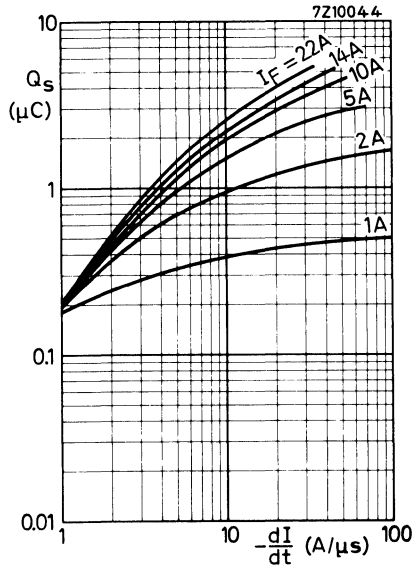
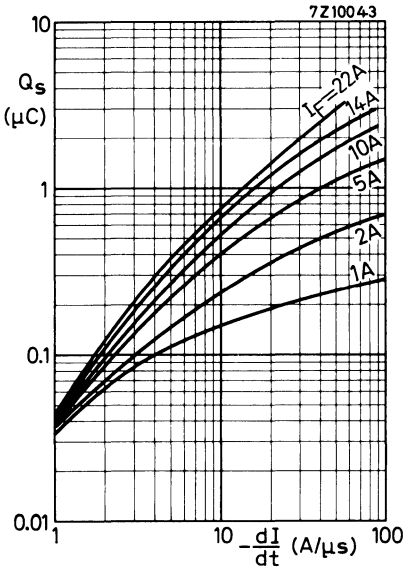
BYX46 SERIES



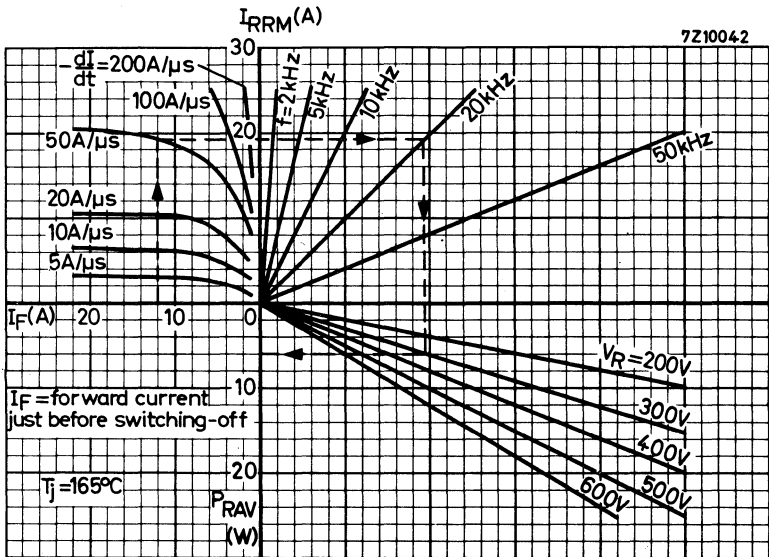
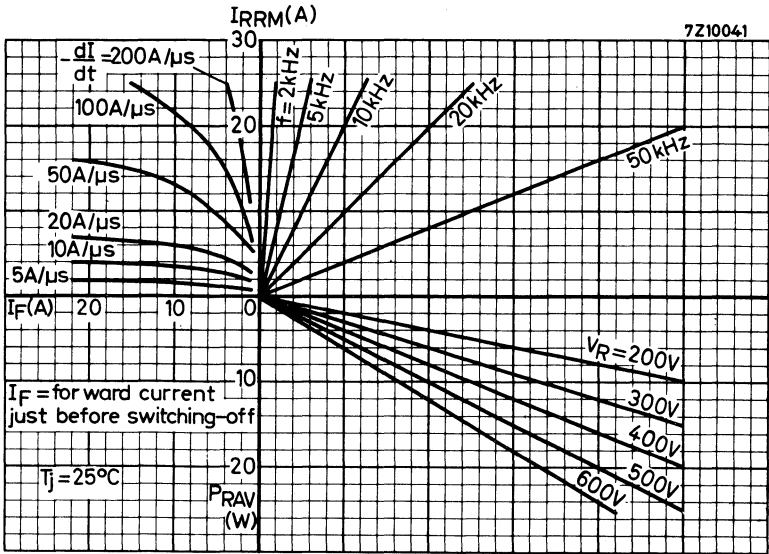
**BYX46
SERIES**



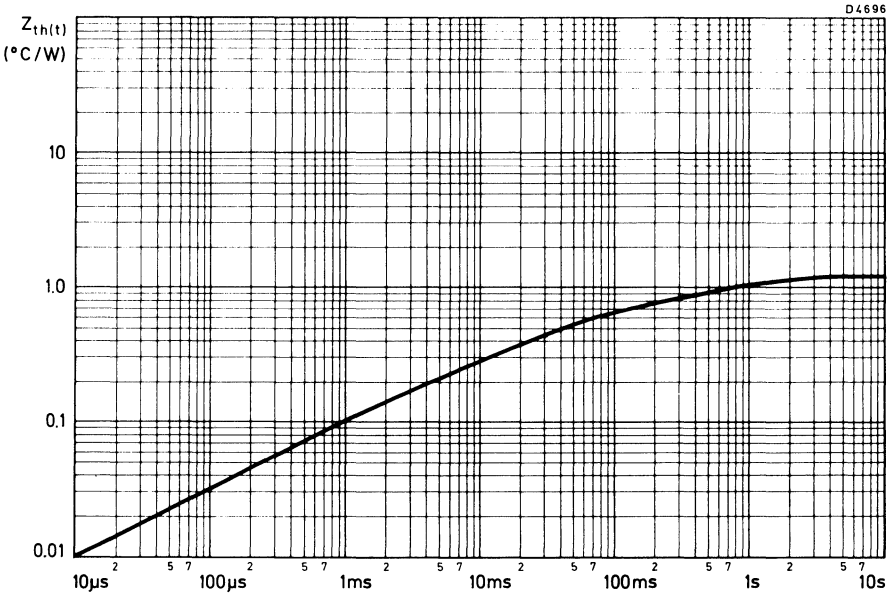




**BYX 46
SERIES**



Nomogram: Power loss P_{RAV} due to switching only (square wave operation)



FAST SOFT-RECOVERY RECTIFIER DIODES

Silicon diodes in DO-4 metal envelopes, intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications. The series consists of the following types: Normal polarity (cathode to stud): BYX50-200, 300. These devices feature non-snap-off characteristics.

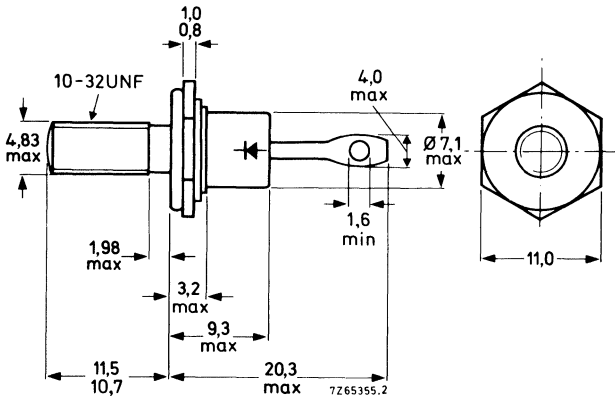
QUICK REFERENCE DATA

		BYX50-200		300	
Repetitive peak reverse voltage	V_{RRM}	max.	200	300	V
Average forward current	$I_{F(AV)}$	max.	7		A
Non-repetitive peak forward current	I_{FSM}	max.	80		A
Reverse recovery time	t_{rr}	<	100		ns

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4, Supplied with device: 1 nut, 1 lock washer
Nut dimensions across the flats: 9,5 mm



Net mass: 6 g
Diameter of clearance hole: max. 5,2 mm
Accessories supplied on request: mica washer (56295a);
PTFE ring (56295b); insulating bush (56295c).

Torque on nut: min. 0,9 Nm
(9 kg cm)
max. 1,7 Nm
(17 kg cm)

BYX50 SERIES

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC134).

→ **Voltages**

			BYX50-200	300	
Non-repetitive peak reverse voltage; $t \leq 10$ ms	V_{RSM}	max.	250	350	V
Repetitive peak reverse voltage	V_{RRM}	max.	200	300	V
Crest working reverse voltage	V_{RWM}	max.	200	300	V
Continuous reverse voltage	V_R	max.	200	300	V

Currents

Average on-state current assuming zero switching losses (averaged over any 20 ms period)

up to $T_{mb} = 103$ °C
at $T_{mb} = 125$ °C

$I_{F(AV)}$	max.	7	A
$I_{F(AV)}$	max.	4	A

R.M.S. forward current

$I_{F(RMS)}$	max.	11	A
--------------	------	----	---

Repetitive peak forward current

I_{FRM}	max.	80	A
-----------	------	----	---

Non-repetitive peak forward current
 $t = 10$ ms; $T_j = 150$ °C prior to surge
with reapplied V_{RWMmax}

I_{FSM}	max.	80	A
-----------	------	----	---

$I^2 t$ for fusing ($t = 10$ ms)

$I^2 t$	max.	32	A ² s
---------	------	----	------------------

Rate of change of commutation current

See nomogram (Fig.6)

Temperatures

Storage temperature

T_{stg}	-55 to +150	°C
-----------	-------------	----

Junction temperature

T_j	max. 150	°C
-------	----------	----

THERMAL RESISTANCE

From junction to ambient in free air

$R_{th j-a}$	=	50	K/W
--------------	---	----	-----

From junction to mounting base

$R_{th j-mb}$	=	3,5	K/W
---------------	---	-----	-----

From mounting base to heatsink

$R_{th mb-h}$	=	0,5	K/W
---------------	---	-----	-----

Transient thermal impedance; $t = 1$ ms

$Z_{th j-mb}$	=	1	K/W
---------------	---	---	-----

CHARACTERISTICS

Forward voltage

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$ $V_F < 1,95 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$ $I_R < 3 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$
 $-dI_F/dt = 100 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
 Recovery time $t_{rr} < 100 \text{ ns}$

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$
 $-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
 Recovery time $t_{rr} < 150 \text{ ns}$

$I_F = 2 \text{ A to } V_R = 30 \text{ V};$
 $-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
 Recovered charge $Q_S < 250 \text{ nC}$

$I_F = 2 \text{ A to } V_R = 50 \text{ V};$
 $-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$
 Max. slope of the reverse recovery current $|dI_R/dt| < 5 \text{ A}/\mu\text{s}$

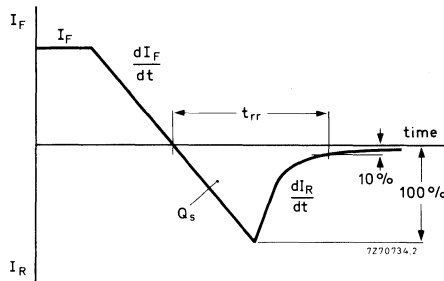


Fig.2 Definition of t_{rr} and Q_s .

* Measured under pulse conditions to avoid excessive dissipation.

BYX50 SERIES

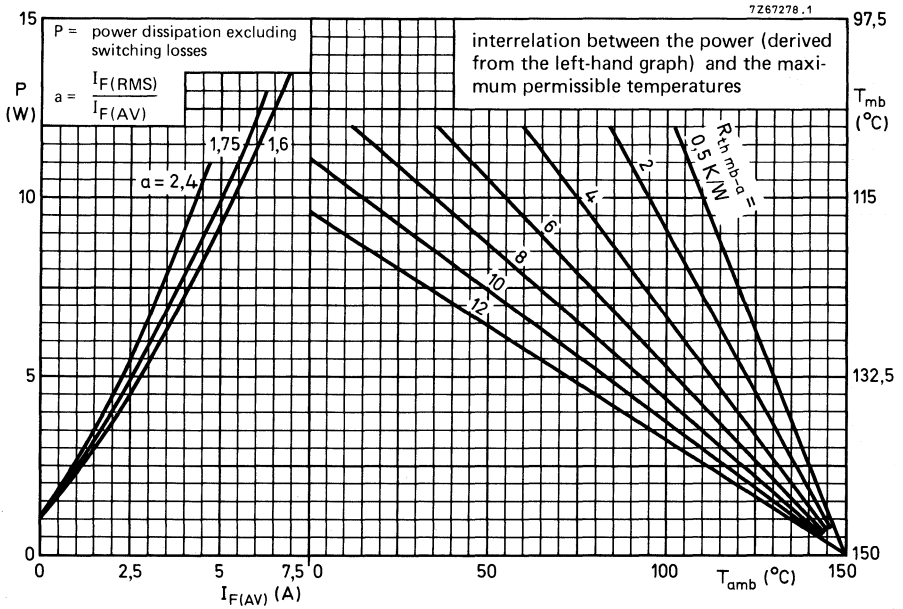


Fig.3

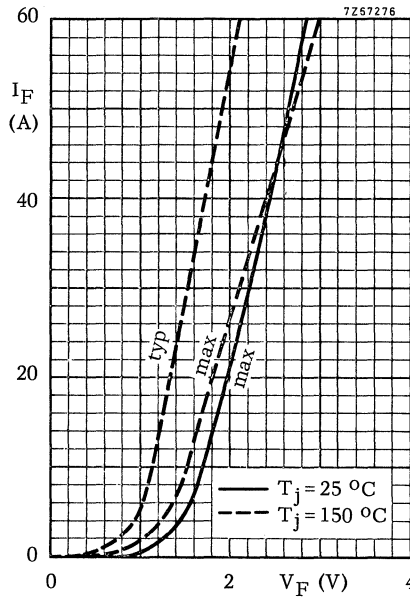


Fig.4

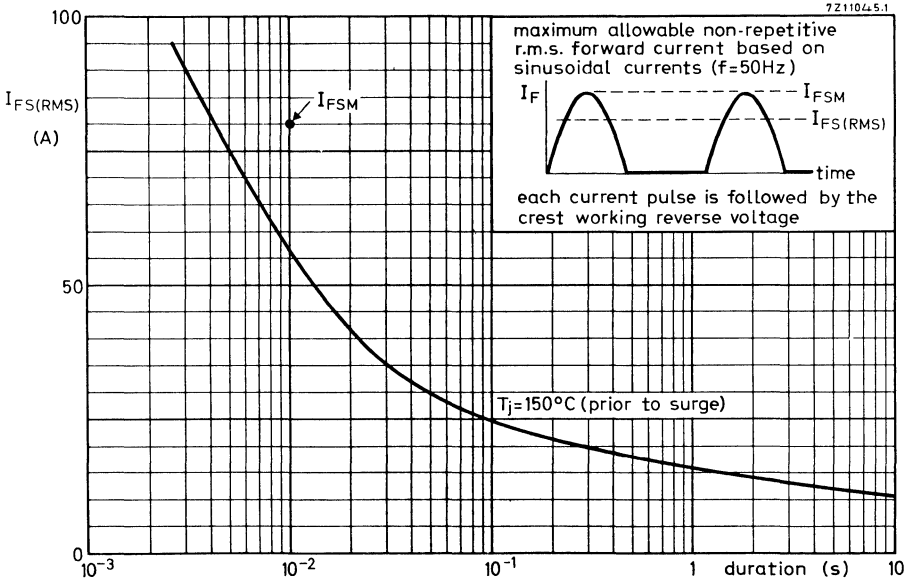


Fig.5

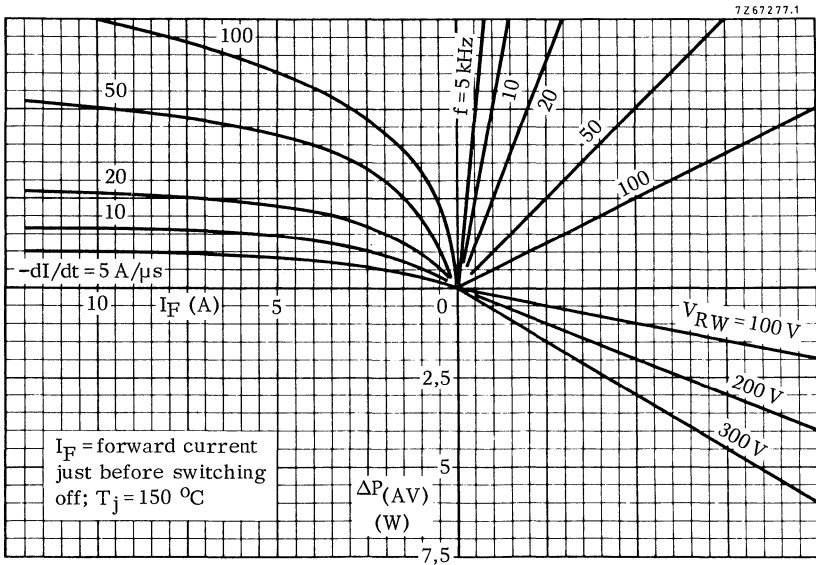


Fig.6

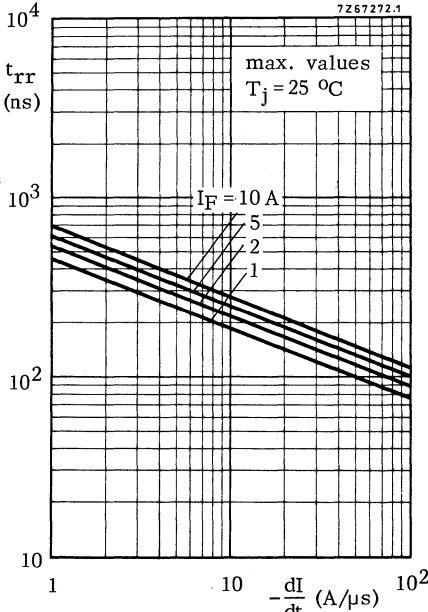


Fig.7

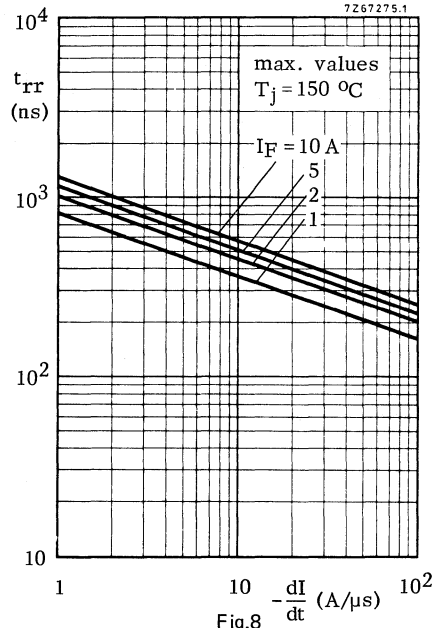


Fig.8

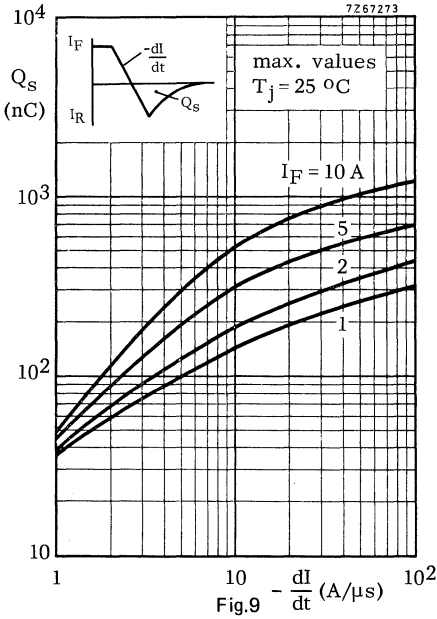


Fig.9

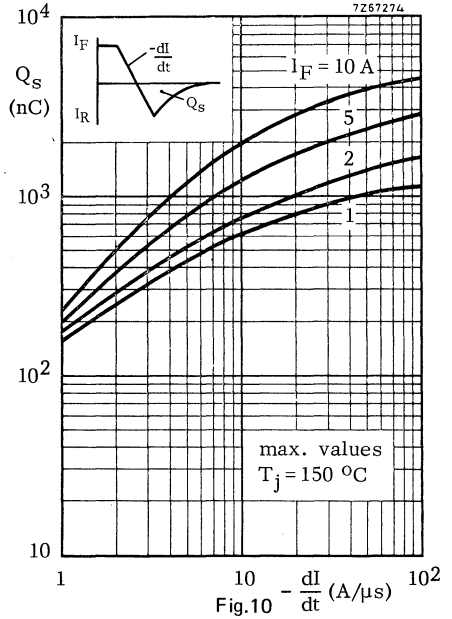


Fig.10

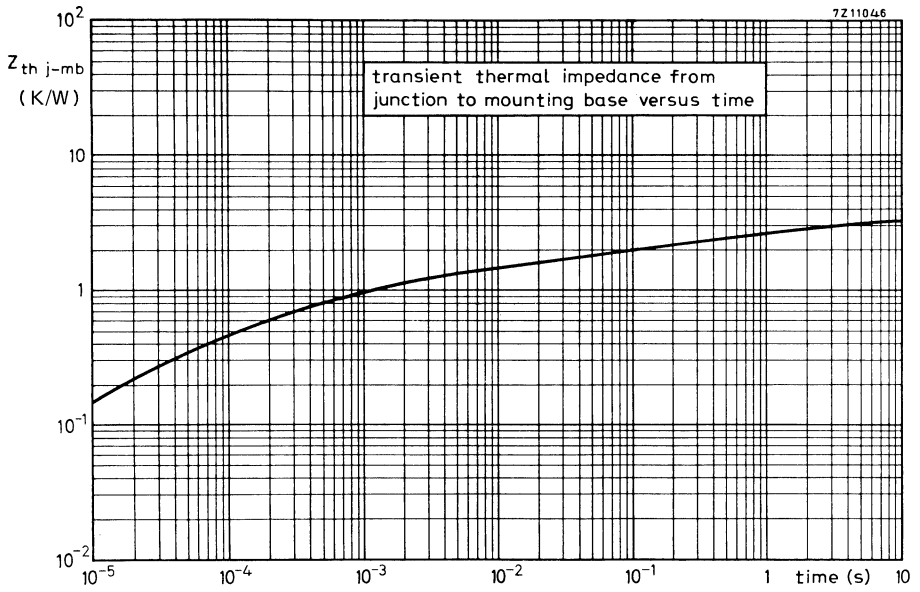


Fig.11

FAST SOFT-RECOVERY RECTIFIER DIODES

Silicon diodes, each in a DO-4 metal envelope, featuring non-snap-off characteristics, and intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): 1N3879, 1N3880, 1N3881, 1N3882 and 1N3883.

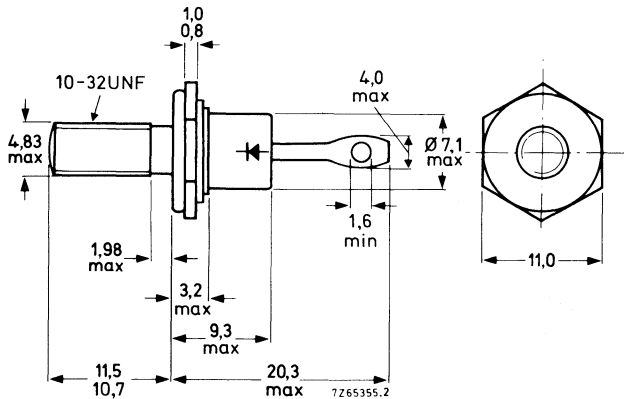
QUICK REFERENCE DATA

	1N3879	1N3880	1N3881	1N3882	1N3883
Repetitive peak reverse voltage V_{RRM} max.	50	100	200	300	400 V
Average forward current $I_F(AV)$	max.		6	A	
Non-repetitive peak forward current I_{FSM}	max.		80	A	
Reverse recovery time t_{rr}	<		200	ns	

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4, Supplied with device: 1 nut, 1 lock washer
Nut dimensions across the flats: 9.5 mm.



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request: mica washer (56295a);
PTFE ring (56295b); insulating bush (56295c).

Torque on nut: min. 0,9 Nm
(9 kg cm)
max. 1,7 Nm
(17 kg cm)

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages

	1N3879	1N3880	1N3881	1N3882	1N3883	
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM} max.	100	150	250	350	450 V
Repetitive peak reverse voltage ($\delta \leq 0,01$)	V_{RRM} max.	50	100	200	300	400 V
Crest working reverse voltage	V_{RWM} max.	50	100	200	300	400 V

Currents

Average on-state current assuming zero switching losses (averaged over any 20 ms period)

up to $T_{mb} = 100$ °C
at $T_{mb} = 125$ °C

$I_F(AV)$	max.	6	A
$I_F(AV)$	max.	3,5	A

R.M.S. forward current

$I_F(RMS)$	max.	10	A
------------	------	----	---

Repetitive peak forward current

I_{FRM}	max.	75	A
-----------	------	----	---

Non-repetitive peak forward current

$T_j = 150$ °C prior to surge;
half sine-wave with reapplied V_{RWMmax} ;
 $t = 10$ ms
 $t = 8,3$ ms

I_{FSM}	max.	75	A
I_{FSM}	max.	80	A

I^2t for fusing ($t = 10$ ms)

I^2t	max.	28	A ² s
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Temperatures

Storage temperature

T_{stg}	-65 to +175	°C
-----------	-------------	----

Operating junction temperature

T_j	max.	150	°C
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THERMAL RESISTANCE

From junction to ambient in free air

$R_{th j-a}$	=	50	K/W
--------------	---	----	-----

From junction to mounting base

$R_{th j-mb}$	=	4,4	K/W
---------------	---	-----	-----

From mounting base to heatsink

$R_{th mb-h}$	=	0,5	K/W
---------------	---	-----	-----

Transient thermal impedance; $t = 1$ ms; $\delta = 0$

$Z_{th j-mb}$	=	1	K/W
---------------	---	---	-----

CHARACTERISTICS

Forward voltage

$I_F = 6 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1,4 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 3 \text{ mA}$

Reverse recovery when switched from

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$

$-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery time

$t_{rr} < 200 \text{ ns}$

$I_F = 2 \text{ A to } V_R = 30 \text{ V};$

$-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Recovery charge

$Q_s < 250 \text{ nC}$

$I_F = 1 \text{ A to } V_R = 30 \text{ V};$

$-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$

Max. slope of the reverse recovery current

$|dI_R/dt| < 5 \text{ A}/\mu\text{s}$

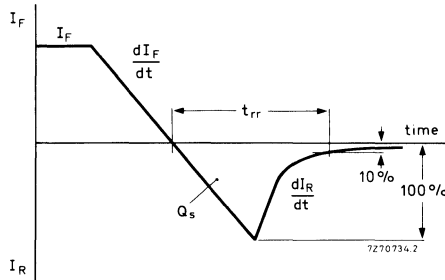


Fig.2 Definition of t_{rr} and Q_s .

*Measured under pulse conditions to avoid excessive dissipation

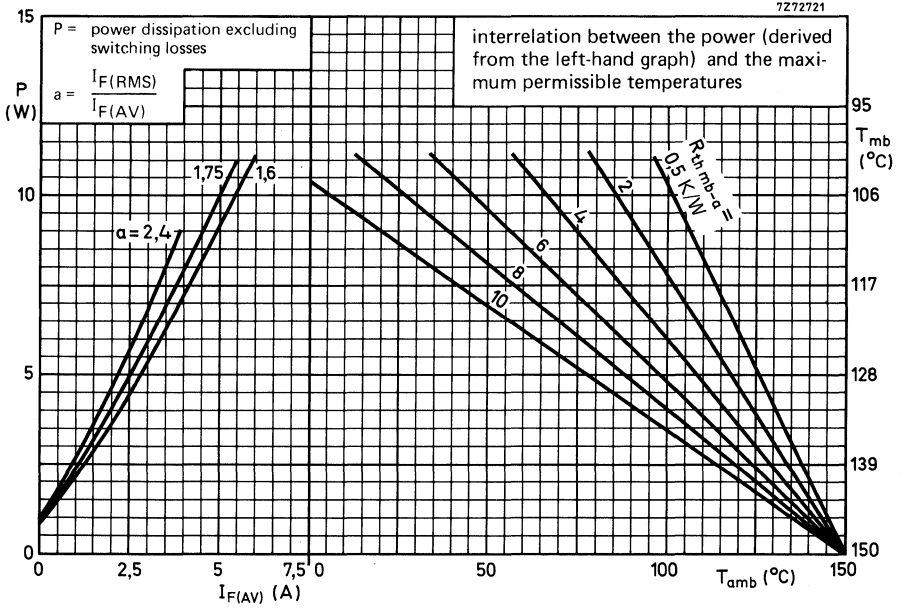


Fig.3

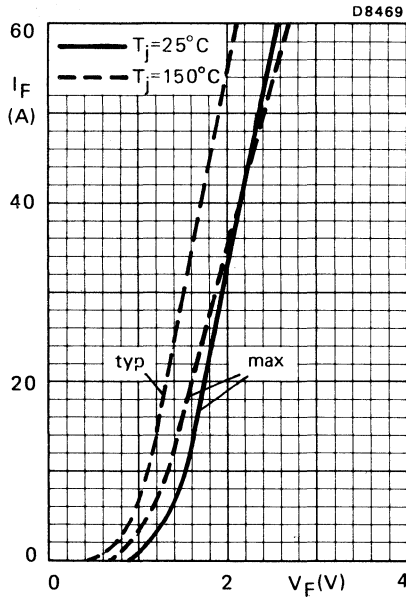


Fig.4

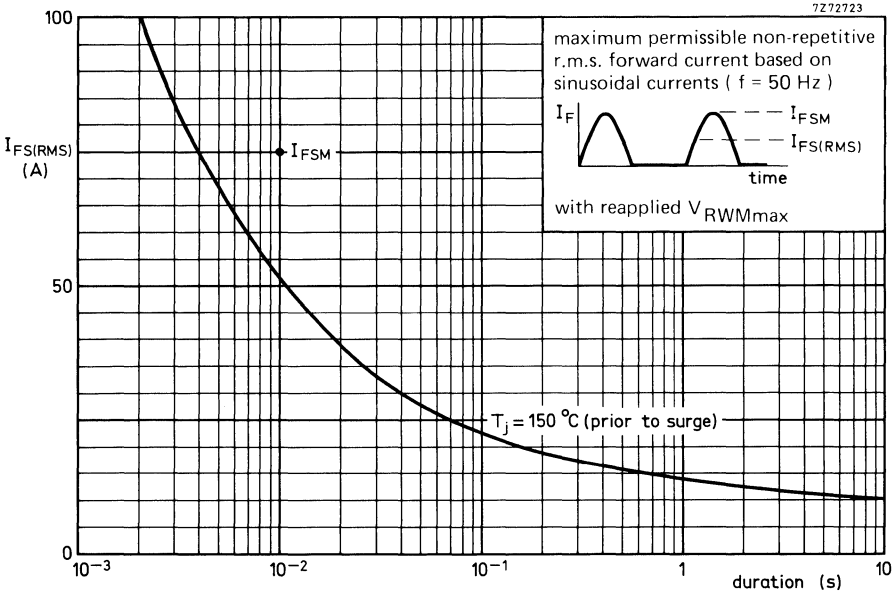


Fig.5

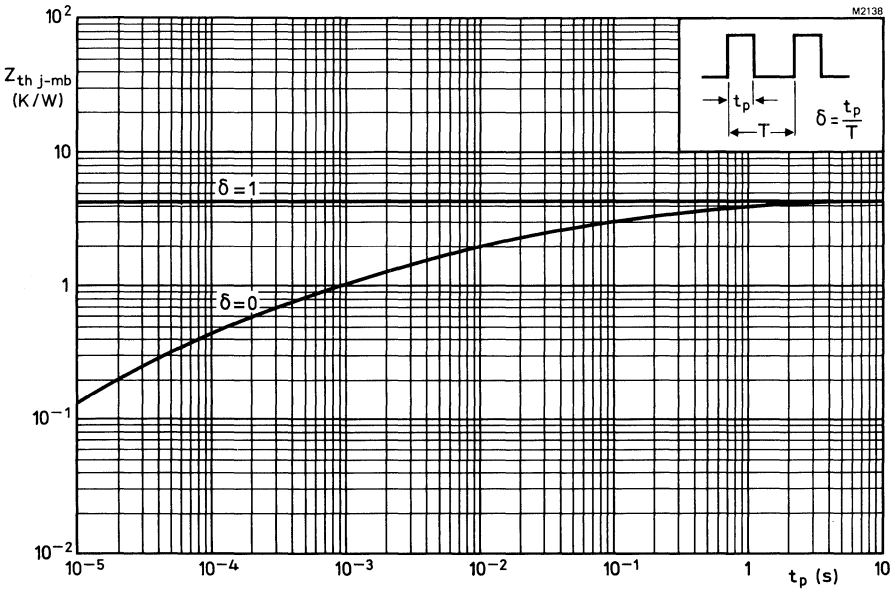


Fig.6

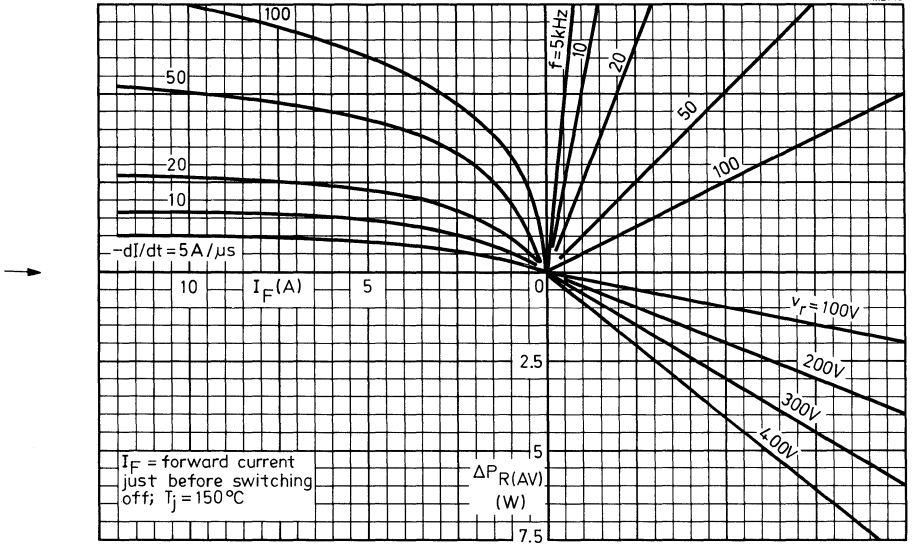
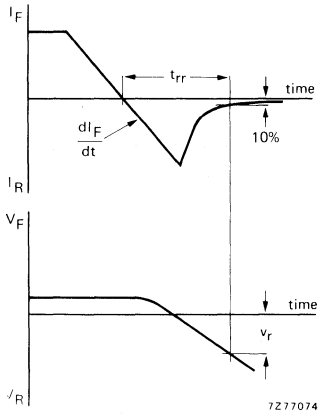


Fig.7

NOMOGRAM

Power loss $\Delta P_R(AV)$ due to switching only (to be added to steady state power losses).



7Z77074

FAST SOFT-RECOVERY RECTIFIER DIODES

Silicon diodes, each in a DO-4 metal envelope, featuring non-snap-off characteristics, and intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): 1N3889, 1N3890, 1N3891, 1N3892 and 1N3893.

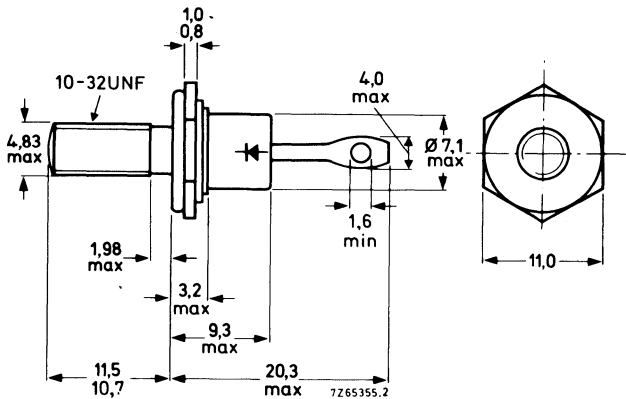
QUICK REFERENCE DATA

	1N3889	1N3890	1N3891	1N3892	1N3893	
Repetitive peak reverse voltage	V_{RRM} max.	50	100	200	300	400 V
Average forward current		$I_{F(AV)}$ max.		12	A	
Non-repetitive peak forward current		I_{FSM} max.		150	A	
Reverse recovery time		t_{rr}		< 200	ns	

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4, Supplied with device: 1 nut, 1 lock washer
Nut dimensions across the flats: 9,5 mm.



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request: mica washer (56295a);
PTFE ring (56295b); insulating bush (56295c).

Torque on nut: min. 0,9 Nm
(9 kg cm)
max. 1,7 Nm
(17 kg cm)

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC134)

→ **Voltages**

		1N3889	1N3890	1N3891	1N3892	1N3893
Non-repetitive peak reverse voltage ($t \leq 10$ ms)	V_{RSM} max.	100	150	250	350	450 V
Repetitive peak reverse voltage ($\delta \leq 0,01$)	V_{RRM} max.	50	100	200	300	400 V
Crest working reverse voltage	V_{RWM} max.	50	100	200	300	400 V

Currents

Average on-state current assuming zero switching losses (averaged over any 20 ms period)

up to $T_{mb} = 100$ °C
at $T_{mb} = 125$ °C

$I_{F(AV)}$	max.	12	A
$I_{F(AV)}$	max.	7	A

R.M.S. forward current

$I_{F(RMS)}$	max.	20	A
--------------	------	----	---

Repetitive peak forward current

I_{FRM}	max.	140	A
-----------	------	-----	---

Non-repetitive peak forward current

$T_j = 150$ °C prior to surge;
half sine-wave with reapplied V_{RWMmax} ;
 $t = 10$ ms
 $t = 8,3$ ms

I_{FSM}	max.	140	A
I_{FSM}	max.	150	A

$I^2 t$ for fusing ($t = 10$ ms)

$I^2 t$	max.	100	A ² s
---------	------	-----	------------------

Temperatures

Storage temperature

T_{stg}		-65 to +175	°C
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Operating junction temperature

T_j	max.	150	°C
-------	------	-----	----

THERMAL RESISTANCE

From junction to ambient in free air

$R_{th j-a}$	=	50	K/W
--------------	---	----	-----

From junction to mounting base

$R_{th j-mb}$	=	2,2	K/W
---------------	---	-----	-----

From mounting base to heatsink

$R_{th mb-h}$	=	0,5	K/W
---------------	---	-----	-----

Transient thermal impedance; $t = 1$ ms; $\delta = 0$

$Z_{th j-mb}$	=	0,8	K/W
---------------	---	-----	-----

CHARACTERISTICS**Forward voltage**

$$I_F = 12 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 1,4 \text{ V}^*$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$$

$$I_R < 3 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 1 \text{ A to } V_R = 30 \text{ V};$$

$$-dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovery time

$$t_{rr} < 200 \text{ ns}$$

$$I_F = 2 \text{ A to } V_R = 30 \text{ V};$$

$$-dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovery charge

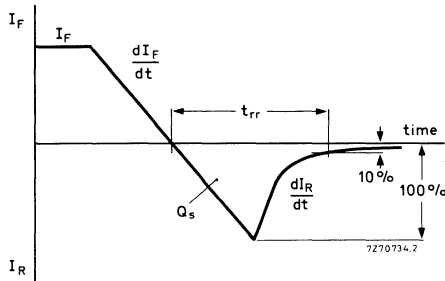
$$Q_S < 250 \text{ nC}$$

$$I_F = 1 \text{ A to } V_R = 30 \text{ V};$$

$$-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Max. slope of the reverse recovery current

$$|dI_R/dt| < 5 \text{ A}/\mu\text{s}$$

Fig.2 Definition of t_{rr} and Q_S .

* Measured under pulse conditions to avoid excessive dissipation.

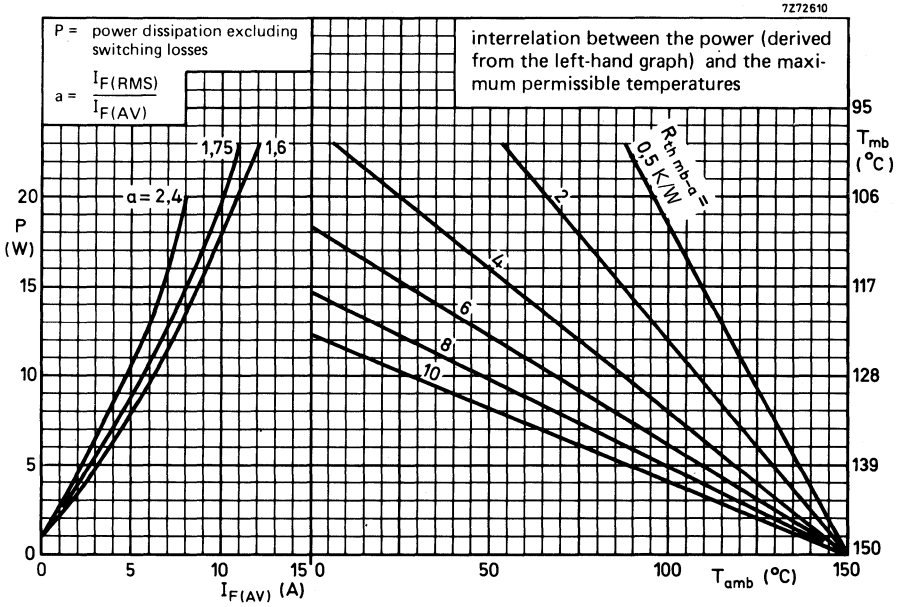


Fig.3

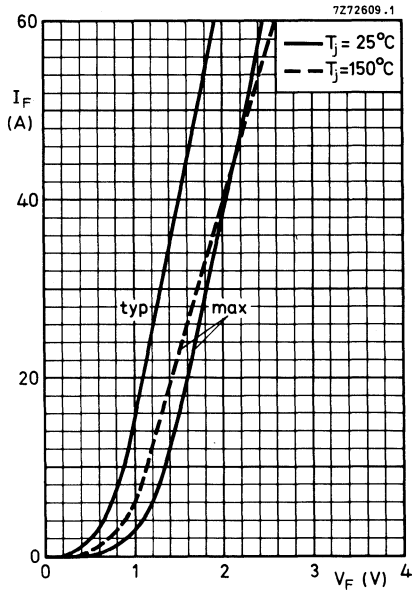


Fig.4

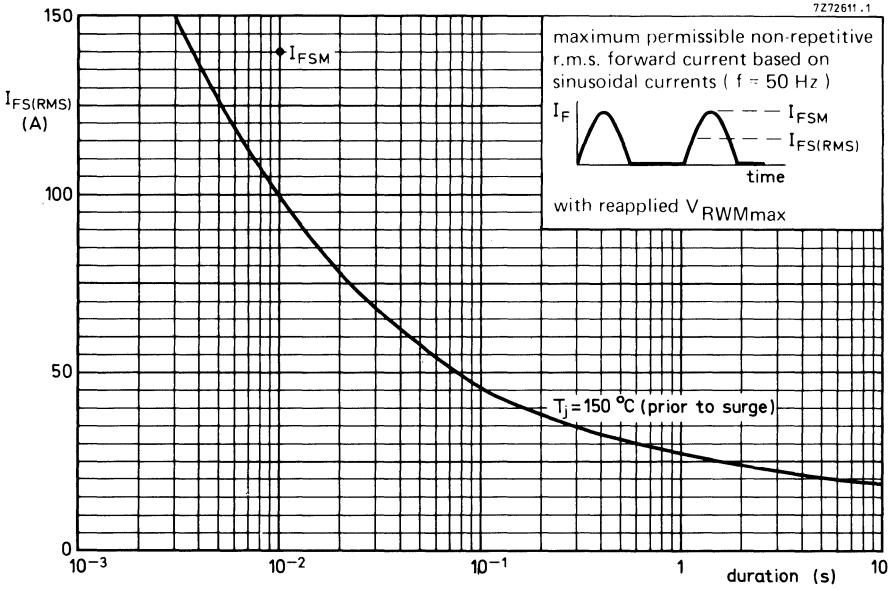


Fig.5

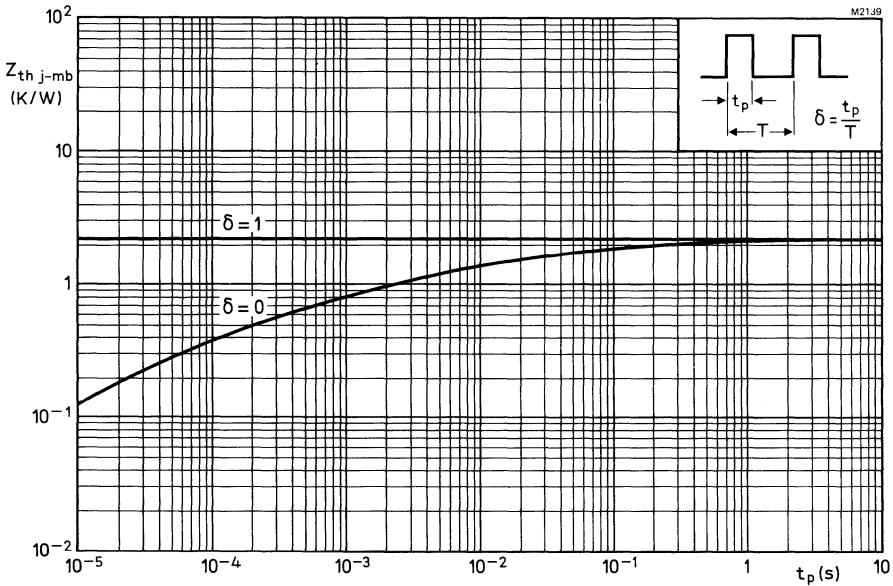


Fig.6

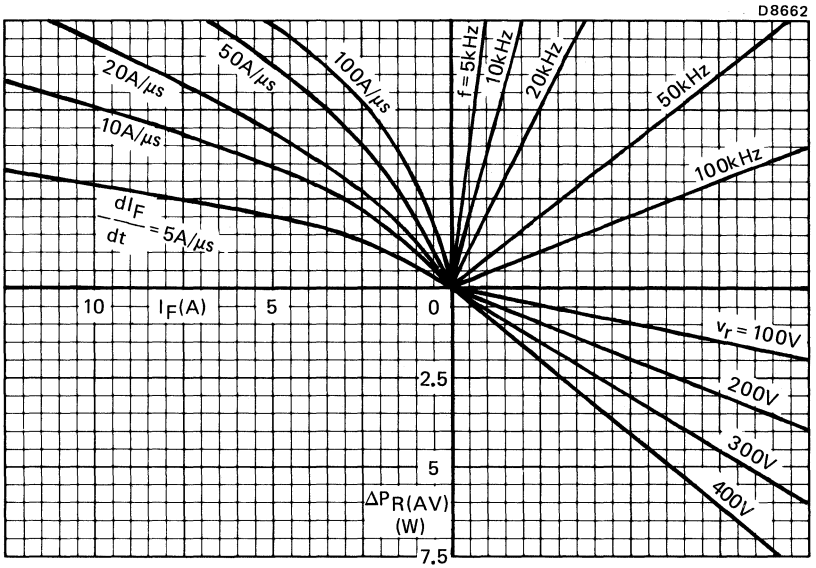
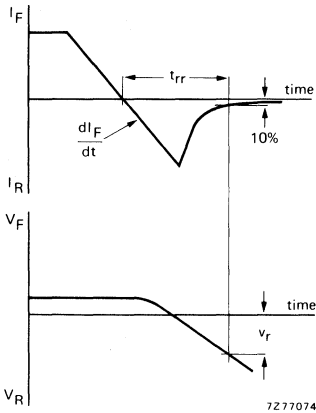


Fig.7

NOMOGRAM

Power loss $\Delta P_R(AV)$ due to switching only (to be added to steady state power losses).

I_F = forward current just before switching off; $T_j = 150^\circ C$



7277074

FAST SOFT-RECOVERY RECTIFIER DIODES

Silicon diodes in DO-5 metal envelopes, featuring non-snap-off characteristics. They are intended for use in high-frequency power supplies, thyristor inverters and multi-phase power rectifier applications. The series consists of the following types:

Normal polarity (cathode to stud): 1N3909, 1N3910, 1N3911, 1N3912, 1N3913.

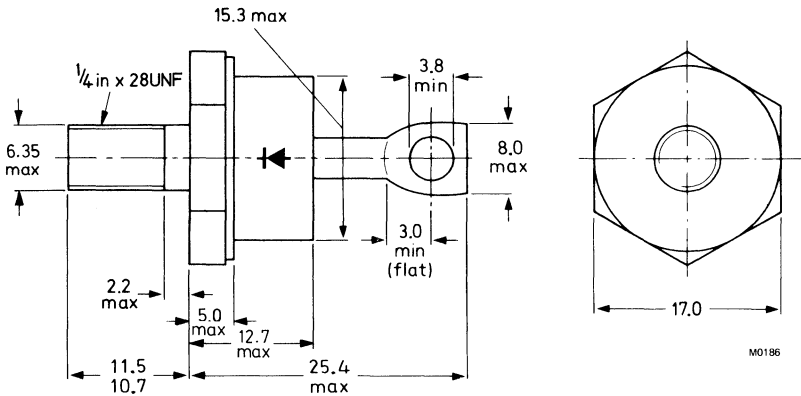
QUICK REFERENCE DATA

		1N3909	3910	3911	3912	3913	
Repetitive peak reverse voltage	V_{RRM} max.	50	100	200	300	400	V
Average forward current	$I_{F(AV)}$ max.	30					A
Non-repetitive peak forward current	I_{FSM} max.	300					A
Reverse recovery time	t_{rr} <	200					ns

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5; Supplied with device: 1 nut, 1 lock-washer
Nut dimensions across the flats: 11.1 mm



Net mass: 22 g
Diameter of clearance hole: max. 6.5 mm
Accessories supplied on request:
56264a (mica washer).
56264b (insulating bush).

Torque on nut:
min. 1.7 Nm (17 kg cm)
max. 2.5 Nm (25 kg cm)

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages

		1N3909	3910	3911	3912	3913	
Non-repetitive peak reverse voltage ($t = 10 \text{ ms}$)	V_{RSM} max.	75	200	300	400	500	V
Repetitive peak reverse voltage ($\delta \leq 0.01$)	V_{RRM} max.	50	100	200	300	400	V
Crest working voltage	V_{RWM} max.	50	100	200	300	400	V

Currents

Average on-state current assuming zero switching losses (averaged over any 20 ms period)

up to $T_{mb} = 100 \text{ }^\circ\text{C}$
at $T_{mb} = 125 \text{ }^\circ\text{C}$

$I_F(AV)$	max.	30	A
$I_F(AV)$	max.	15	A

R.M.S. forward current

$I_F(RMS)$	max.	45	A
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Repetitive peak forward current

I_{FRM}	max.	125	A
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Non-repetitive peak forward current

$T_j = 150 \text{ }^\circ\text{C}$ prior to surge;
half sine-wave with reapplied V_{RWMmax} ;
 $t = 10 \text{ ms}$
 $t = 8.3 \text{ ms}$

I_{FSM}	max.	275	A
I_{FSM}	max.	300	A

$I^2 t$ for fusing ($t = 10 \text{ ms}$)

$I^2 t$	max.	375	$A^2 s$
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Temperatures

Storage temperature

T_{stg}		-65 to 175	$^\circ\text{C}$
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Operating junction temperature

T_j	max.	150	$^\circ\text{C}$
-------	------	-----	------------------

THERMAL RESISTANCE

From junction to mounting base

$R_{th j-mb}$	=	1.0	K/W
---------------	---	-----	-----

From mounting base to heatsink with heatsink compound

$R_{th mb-h}$	=	0.3	K/W
---------------	---	-----	-----

Transient thermal impedance; $t = 1 \text{ ms}$

$Z_{th j-mb}$	=	0.2	K/W
---------------	---	-----	-----

CHARACTERISTICS

Forward voltage

$$I_F = 30 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$$

$$V_F < 1.4 \text{ V}^*$$

Reverse current

$$V_R = V_{RWMmax}; T_j = 100 \text{ }^\circ\text{C}$$

$$I_R < 10 \text{ mA}$$

Reverse recovery when switched from

$$I_F = 1 \text{ A to } V_R \geq 30 \text{ V}; -dI_F/dt = 35 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovery time

$$t_{rr} < 200 \text{ ns}$$

$$I_F = 2 \text{ A to } V_R \geq 30 \text{ V}; -dI_F/dt = 20 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

Recovered charge

$$Q_s < 250 \text{ nC}$$

Maximum slope of the reverse recovery current

$$\text{when switched from } I_F = 1 \text{ A to } V_R \geq 30 \text{ V};$$

$$-dI_F/dt = 2 \text{ A}/\mu\text{s}; T_j = 25 \text{ }^\circ\text{C}$$

$$|dI_R/dt| < 5 \text{ A}/\mu\text{s}$$

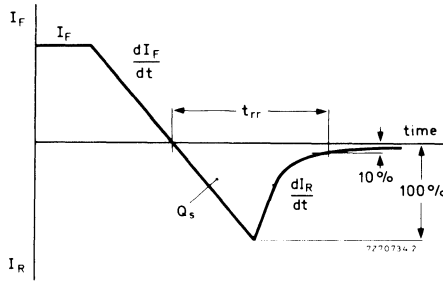


Fig. 2 Definitions of t_{rr} and Q_s .

D8403

*Measured under pulse conditions to avoid excessive dissipation.

SINUSOIDAL OPERATION

D8408

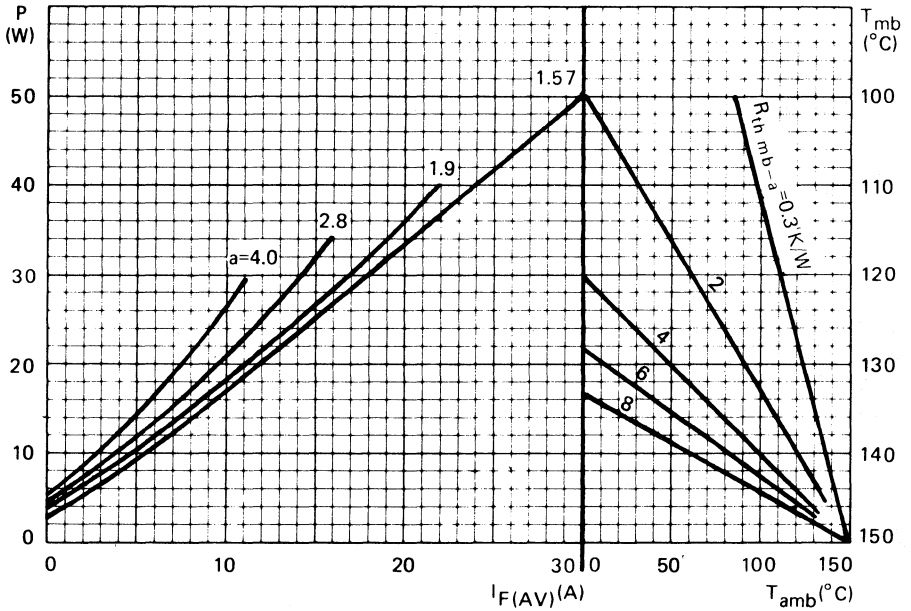


Fig. 3 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

P = power dissipation excluding switching losses.

a = form factor = I_{F(RMS)}/I_{F(AV)}.

SQUARE-WAVE OPERATION

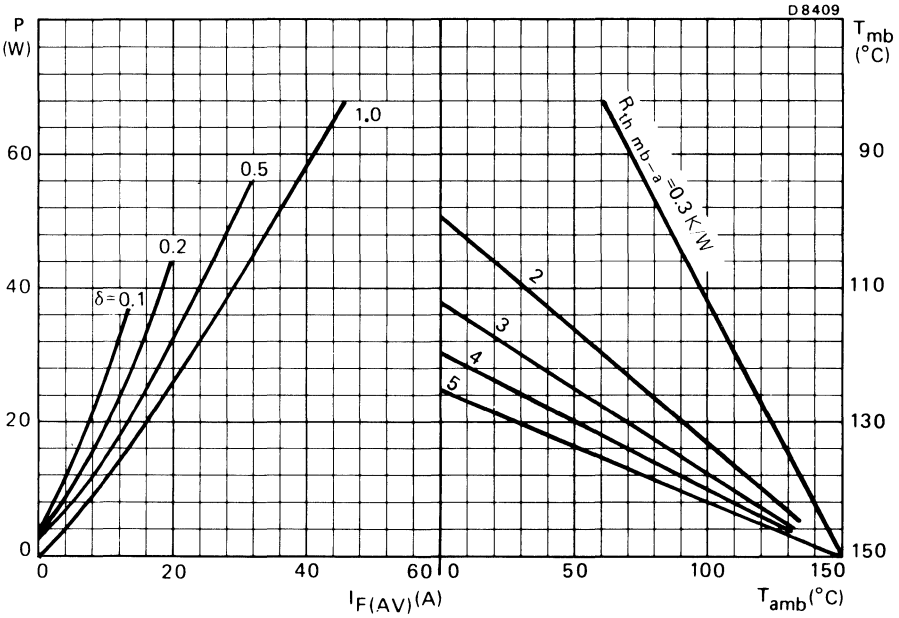
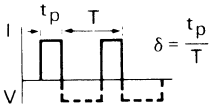


Fig. 4 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.
 P = power dissipation excluding switching losses.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

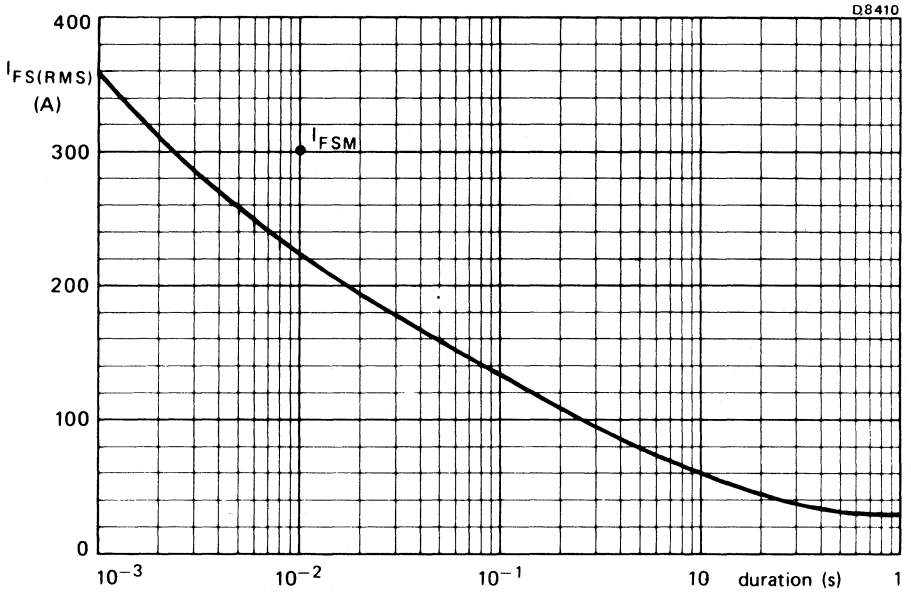
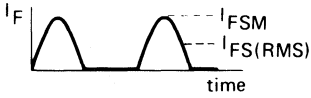


Fig.5 Maximum permissible non-repetitive r.m.s. forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 150$ °C prior to surge; with reapplied V_{RWMmax} .



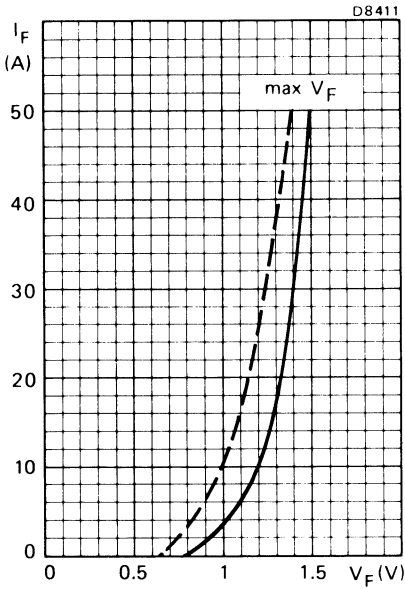


Fig. 6 — $T_j = 25\text{ }^\circ\text{C}$; --- $T_j = 150\text{ }^\circ\text{C}$

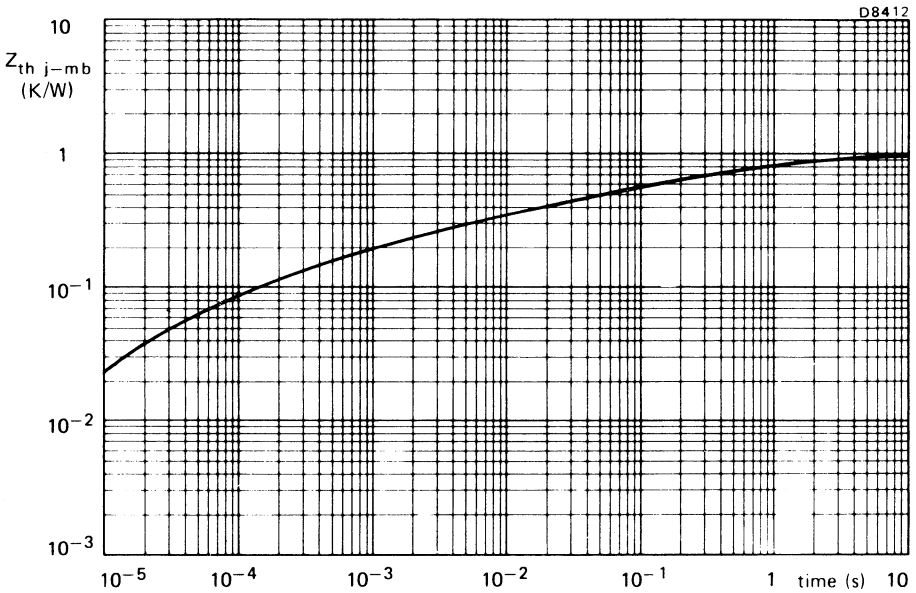


Fig. 7

SCHOTTKY RECTIFIER DIODES

SCHOTTKY-BARRIER DOUBLE RECTIFIER DIODES

High-efficiency schottky-barrier double rectifier diodes in plastic envelopes, featuring low forward voltage drop, low capacitance and absence of stored charge . They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. The single chip (monolithic) construction allows both diodes to be paralleled without the need for derating. They can also withstand reverse voltage transients. The series consists of common-cathode types. A version with guaranteed reverse surge capability, BYV18-40A, is also available.

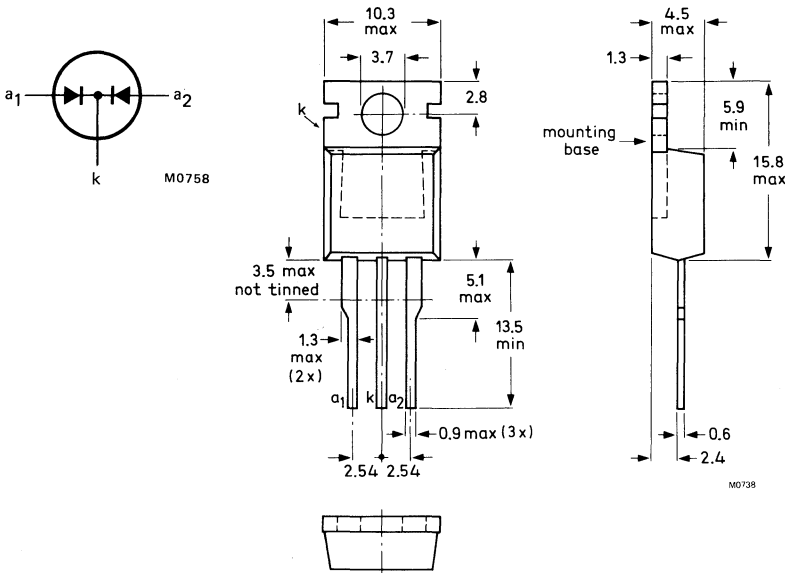
QUICK REFERENCE DATA

Per diode, unless otherwise stated			BYV18-30	35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45	V
Output current (both diodes conducting)	I_O	max.	10				A
Forward voltage	V_F	<	0.6				V
Junction temperature	T_j	<	150				°C

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AB



Net mass: 2 g

Note: the exposed metal mounting base is directly connected to the common cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)

		BYV18-30	35	40(A)	45
Repetitive peak reverse voltage	V_{RRM}	max. 30	35	40	45 V
Crest working reverse voltage (note 1)	V_{RWM}	max. 30	35	40	45 V
Continuous reverse voltage (note 1)	V_R	max. 30	35	40	45 V

Currents (both diodes conducting: note 2)

Output current:

square wave; $\delta = 0.5$;
up to $T_{mb} = 136^\circ\text{C}$ (note 3)

I_O max. 10 A

sinusoidal;

up to $T_{mb} = 137^\circ\text{C}$ (note 3)

I_O max. 8.8 A

R.M.S. forward current

$I_F(\text{RMS})$ max. 14 A

Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$ (per diode)

I_{FRM} max. 90 A

Non-repetitive peak forward current

(per diode) half sine-wave;

$T_j = 125^\circ\text{C}$ prior to surge;

with reapplied V_{RWMmax}

$t = 10 \text{ ms}$

I_{FSM} max. 100 A

$t = 8.3 \text{ ms}$

I_{FSM} max. 110 A

I^2t for fusing ($t = 10 \text{ ms}$, per diode)

I^2t max. 50 A^2s

Reverse surge current (BYV18-40A only)

$t_p = 100 \mu\text{s}$

I_{RSM} max. 0.5 A

Temperatures

Storage temperature

T_{stg} -40 to +150 $^\circ\text{C}$

Junction temperature

T_j max. 150 $^\circ\text{C}$

Notes

1. Up to $T_j = 125^\circ\text{C}$; see derating curve for higher temperature operation.
2. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
3. Assuming no reverse leakage current losses.

CHARACTERISTICS (per diode)

Forward voltage

$I_F = 5 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$

$I_F = 15 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

V_F	<	0.6	V*
V_F	<	1.05	V*

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$

I_R	<	30	mA
-------	---	----	----

Junction capacitance at $f = 1 \text{ MHz}$

$V_R = 5 \text{ V}; T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$

C_d	typ.	200	pF
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THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)

$R_{th \text{ j-mb}}$	=	1.7	K/W
-----------------------	---	-----	-----

From junction to mounting base (per diode)

$R_{th \text{ j-mb}}$	=	2.7	K/W
-----------------------	---	-----	-----

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$R_{th \text{ mb-h}}$	=	0.3	K/W
-----------------------	---	-----	-----

b. with heatsink compound and 0.06 mm maximum mica insulator

$R_{th \text{ mb-h}}$	=	1.4	K/W
-----------------------	---	-----	-----

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$R_{th \text{ mb-h}}$	=	2.2	K/W
-----------------------	---	-----	-----

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$R_{th \text{ mb-h}}$	=	0.8	K/W
-----------------------	---	-----	-----

e. without heatsink compound

$R_{th \text{ mb-h}}$	=	1.4	K/W
-----------------------	---	-----	-----

2. Free air operation

The quoted values of $R_{th \text{ j-a}}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air; mounted on a printed circuit board at any device lead length and with copper laminate on the board

$R_{th \text{ j-a}}$	=	60	K/W
----------------------	---	----	-----

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
 Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations

The various components of junction temperature rise above ambient are illustrated in Fig.2.

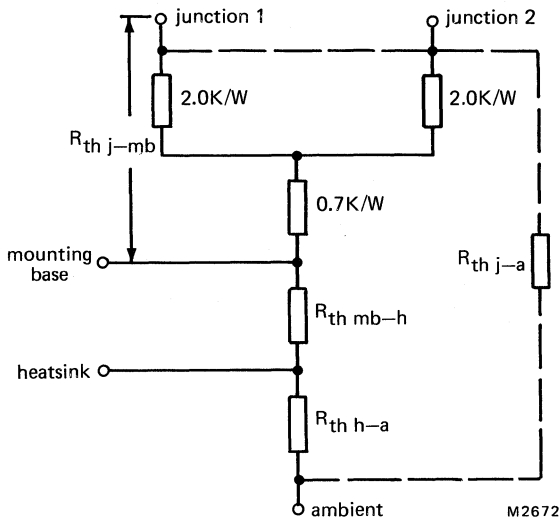


Fig.2.

OPERATING NOTES

Dissipation and heatsink calculations

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required for each half of the dual diode:

- (i) maximum operating ambient temperature
- (ii) duty cycle or form factor of forward current (δ or a)
- (iii) average forward current per diode
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R — reverse leakage dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

P_F — forward conduction dissipation

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_F + P_R} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows:

Look at each half of the dual diode separately; for each diode, starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_j max. From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis. From this calculation, $P_R = P_R$ (diode 1) + P_R (diode 2) 3).

Forward conduction dissipation (P_F) for the known average current $I_F(AV)$ and duty cycle (or form factor) for each diode is easily derived from Fig.4 (or Fig.6).

Similarly, $P_F = P_F$ (diode 1) + P_F (diode 2) 4).

Substituting equations 3) and 4) into equation 2) enables the calculation of the required heatsink.

NOTE:— If both halves of the diode are being used (as is assumed above), the value of $R_{th\ j-mb} = 1.7$ K/W. If only one half of the diode is used, follow the above procedure for one diode only, and use the value of $R_{th\ j-mb}$ of 2.7 K/W.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than 12 °C. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV18-35 and heatsink compound;

$T_{amb} = 50$ °C; δ (diode 1) = 0.5; δ (diode 2) = 0.5;

$I_F(AV)$ (diode 1) = 5 A; $I_F(AV)$ (diode 2) = 5 A;

V_{RWM} (both diodes) = 12 V; voltage grade of device = 35 V.

From data, $R_{th\ j-mb} = 1.7$ K/W and $R_{th\ mb-h} = 0.3$ K/W.

For each diode from Fig.4, it is found that $P_F = 3.5$ W;

hence total $P_F = 2 \times 3.5 = 7$ W. (from equation 4)

If desired T_j max is chosen to be 130 °C, then, from Fig.3, P_R (per diode) = 0.1 W

Therefore total $P_R = 2 \times 0.1 = 0.2$ W. (from equation 3)

Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\text{ °C} - 50\text{ °C}}{7\text{ W} + 0.2\text{ W}} - (1.7 + 0.3) = 9.1\text{ K/W}$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (1.7 + 0.3 + 9.1) \times 0.2 = 2.2\text{ °C}.$$

This is less than 12 °C, hence thermal stability is ensured.

SQUARE WAVE OPERATION (Figs.3 and 4)

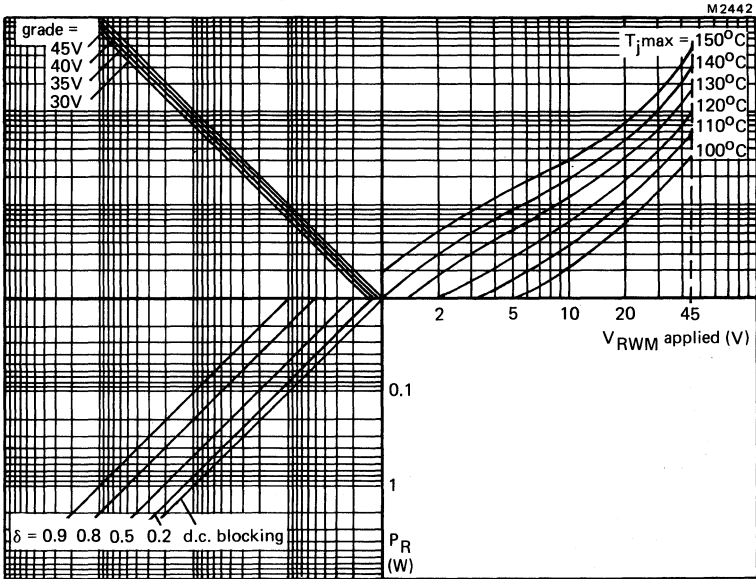


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_j \text{ max.}$, V_{RWM} applied, voltage grade and duty cycle (per diode).

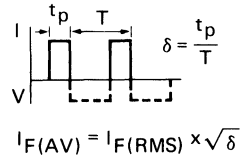
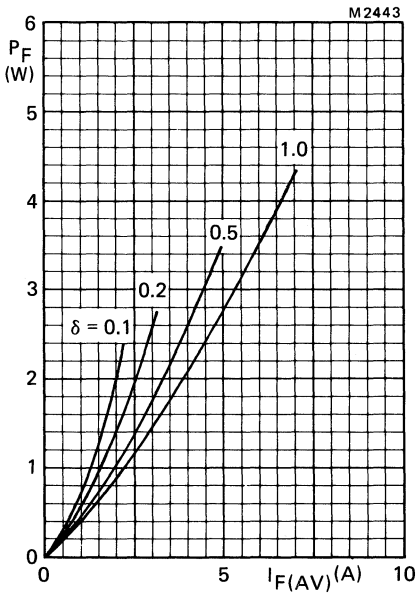


Fig.4 Forward current power rating (per diode).

SINUSOIDAL OPERATION (Figs.5 and 6)

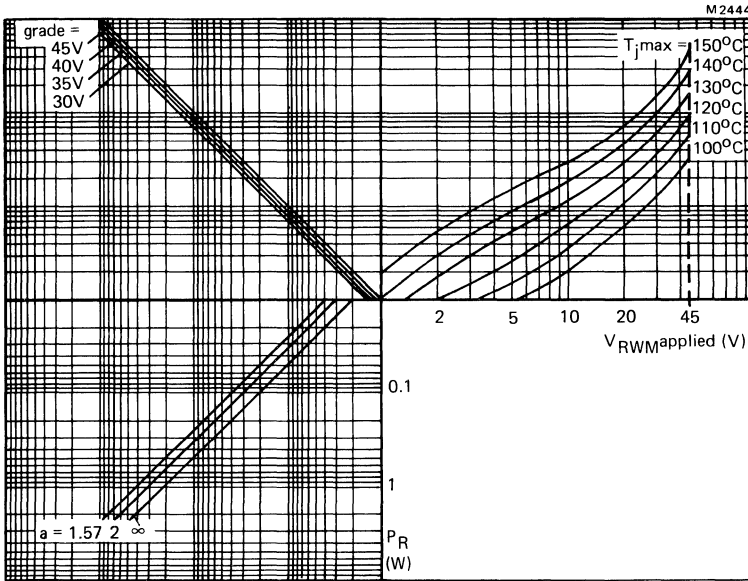


Fig.5 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_{j,max}$, $V_{RWM,applied}$, voltage grade and form factor (per diode).

$a = \text{form factor} = I_F(RMS) / I_F(AV)$

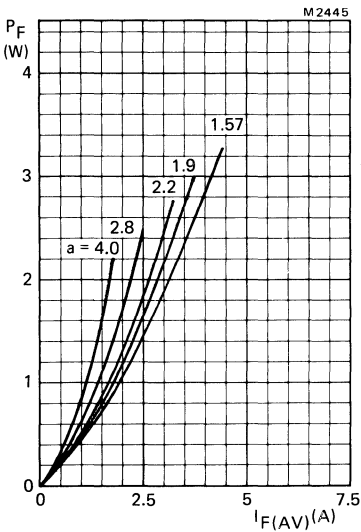


Fig.6 Forward current power rating (per diode).

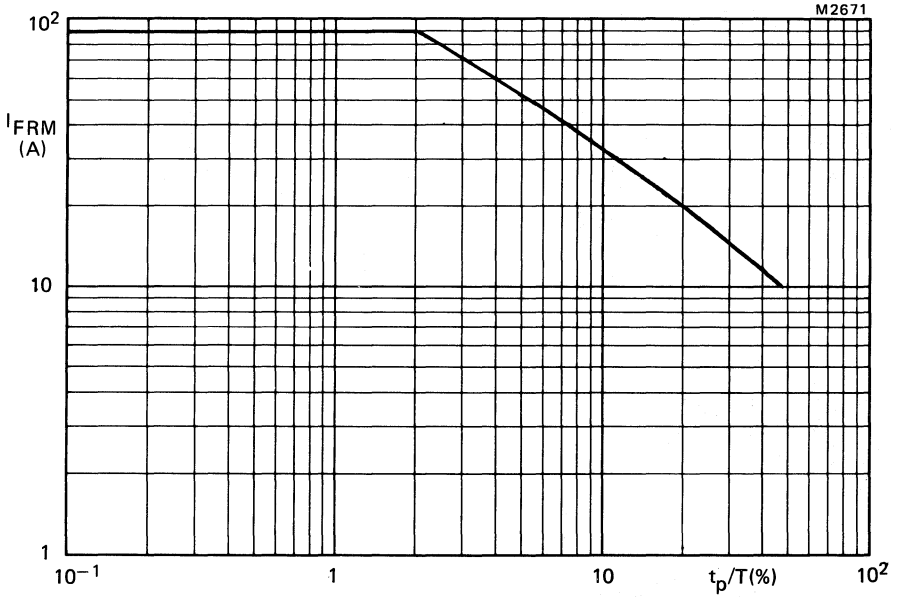
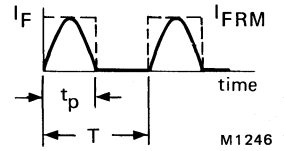
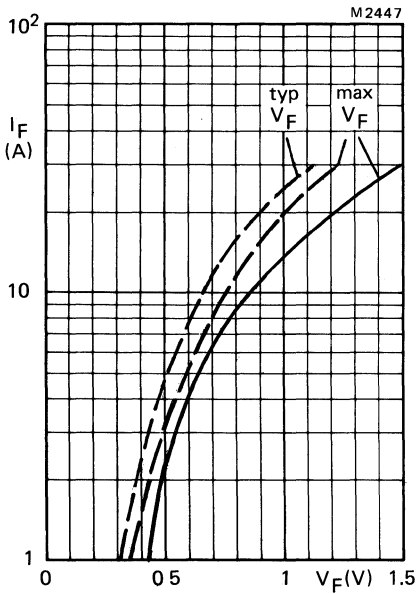


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal current for $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 100 \text{ }^\circ\text{C}$.

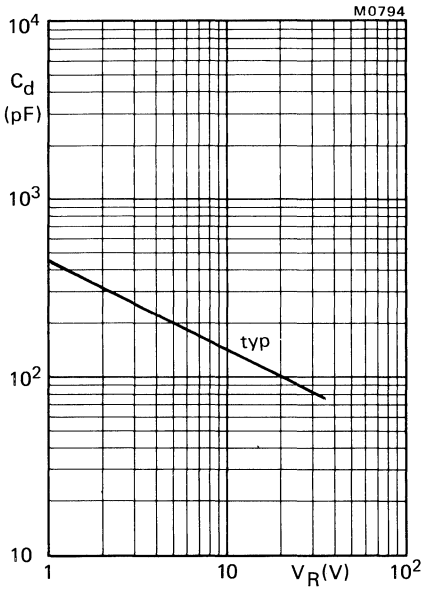


Fig.9 $f = 1$ MHz; $T_j = 25$ to 125 °C.

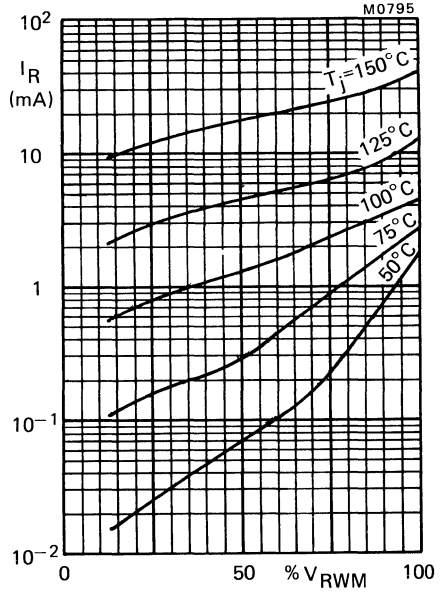


Fig.10 Typical values.

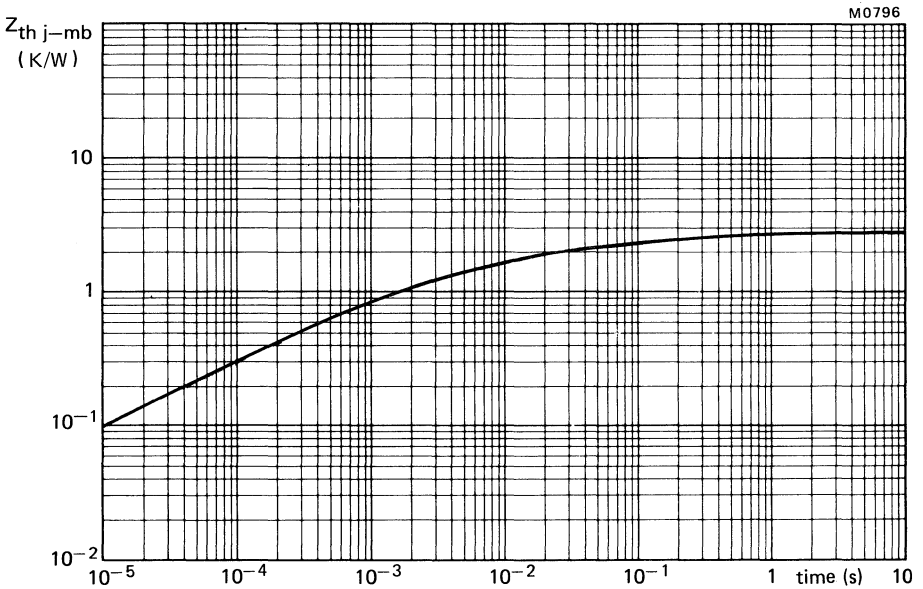


Fig.11 Transient thermal impedance (per diode).

SCHOTTKY—BARRIER RECTIFIER DIODES

High-efficiency schottky-barrier rectifier diodes in TO-220AC plastic envelopes, featuring low forward voltage drop, low capacitance, absence of stored charge, and high temperature stability. They are intended for use in low output voltage switched-mode power supplies and high-frequency circuits in general, where low conduction losses and switching losses are important. They can also withstand reverse voltage transients. The series consists of normal polarity (cathode to mounting base) types. A version with guaranteed reverse surge capability, BYV19-40A, is also available.

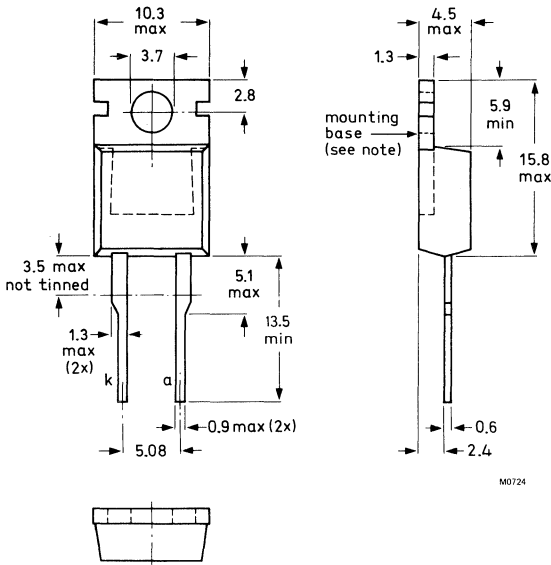
QUICK REFERENCE DATA

		BYV19-30				35	40(A)	45		
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45			V	
Average forward current	$I_F(AV)$	max.				10			A	
Forward voltage	V_F	<				0.6			V	
Junction temperature	T_j	max.				150			°C	

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AC



Note: The exposed metal mounting base is directly connected to cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

BYV19 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134).

		BYV19-30				35	40(A)	45	
→ Voltages									
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45		V	
Crest working reverse voltage (note 1)	V_{RWM}	max.	30	35	40	45		V	
Continuous reverse voltage (note 1)	V_R	max.	30	35	40	45		V	
→ Currents									
Average forward current square wave; $\delta = 0.5$; up to $T_{mb} = 124\text{ }^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.			10			A	
sinusoidal; up to $T_{mb} = 124\text{ }^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.			9			A	
R.M.S. forward current	$I_{F(RMS)}$	max.			14			A	
Repetitive peak forward current $t_p = 20\text{ }\mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.			170			A	
Non-repetitive peak forward current half sine-wave; $T_j = 125\text{ }^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max; $t = 10\text{ ms}$	I_{FSM}	max.			150			A	
$t = 8.3\text{ ms}$	I_{FSM}	max.			165			A	
I^2t for fusing ($t = 10\text{ ms}$)	I^2t	max.			112			A^2s	
Reverse surge current (BYV19-40A only) $t_p = 100\text{ }\mu\text{s}$	I_{RSM}	max.			0.5			A	
Temperatures									
Storage temperature	T_{stg}				-40 to +150			$^\circ\text{C}$	
Junction temperature	T_j	max.			150			$^\circ\text{C}$	
CHARACTERISTICS									
Forward voltage									
$I_F = 5\text{ A}$; $T_j = 100\text{ }^\circ\text{C}$ (note 3)	V_F	<			0.6			V	
$I_F = 20\text{ A}$; $T_j = 25\text{ }^\circ\text{C}$ (note 3)	V_F	<			1.10			V	
Reverse current									
$V_R = V_{RWMmax}$; $T_j = 125\text{ }^\circ\text{C}$	I_R	<			30			mA	
Junction capacitance at $f = 1\text{ MHz}$									
$V_R = 5\text{ V}$; $T_j = 25\text{ to }125\text{ }^\circ\text{C}$	C_d	typ.			200			pF	

Notes:

- Up to $T_j = 125\text{ }^\circ\text{C}$; see derating curve for higher temperature operation.
- Assuming no reverse leakage current losses.
- Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 2.7 \text{ K/W}$$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.3 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted values of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air; mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

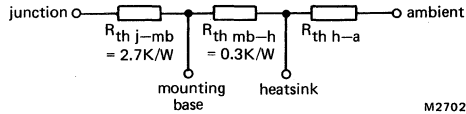
MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

→ OPERATING NOTES

Dissipation and Heatsink Calculations

The various components of junction temperature rise above ambient are shown below:



M2702 Fig.2

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required:

- (i) maximum operating ambient temperature
- (ii) duty cycle or form factor of forward current (δ or a)
- (iii) average forward current
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R – reverse leakage dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

P_F – forward conduction dissipation

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_R + P_F} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows: Starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis.

Forward conduction dissipation (P_F) for the known average current $I_{F(AV)}$ and duty cycle (or form factor) is easily derived from Fig.4 (or Fig.6).

Substituting the values of P_R and P_F into equation 2) enables the calculation of the required heatsink.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than $12\text{ }^\circ\text{C}$. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV19-35 and heatsink compound;

$T_{amb} = 50\text{ }^\circ\text{C}$; $\delta = 0.5$; $I_{F(AV)} = 8\text{ A}$

$V_{RWM} = 12\text{ V}$; voltage grade of device = 35 V

From data, $R_{th\ j-mb} = 2.7\text{ K/W}$ and $R_{th\ mb-h} = 0.3\text{ K/W}$.

From Fig.4, it is found that $P_F = 7\text{ W}$

If the desired T_{jmax} is chosen to be $130\text{ }^\circ\text{C}$, then from Fig.3, $P_R = 0.1\text{ W}$

Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\text{ }^\circ\text{C} - 50\text{ }^\circ\text{C}}{7\text{ W} + 0.1\text{ W}} - (2.7 + 0.3) = 8.3\text{ K/W}$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (2.7 + 0.3 + 8.3) \times 0.1 = 1.1\text{ }^\circ\text{C}.$$

This is less than $12\text{ }^\circ\text{C}$, hence thermal stability is ensured.

SQUARE WAVE OPERATION (Figs.3 and 4)

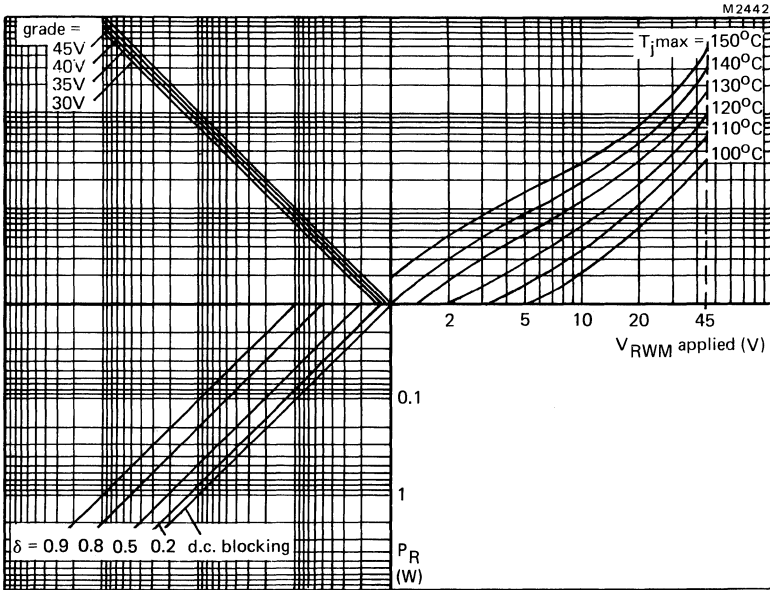


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_j \text{ max.}$, V_{RWM} applied, voltage grade and duty cycle.

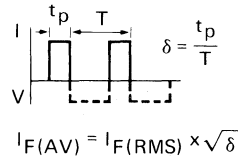
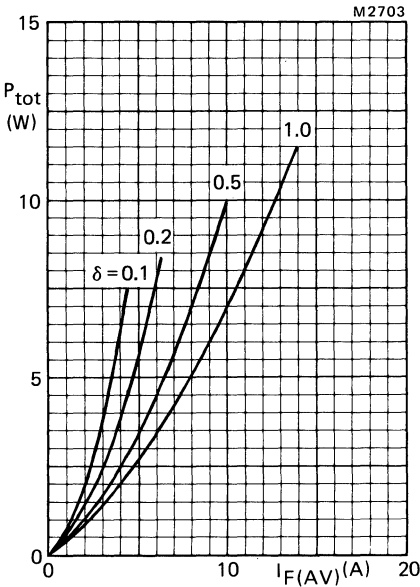


Fig.4 Forward current power rating.

SINUSOIDAL OPERATION (Figs.5 and 6)

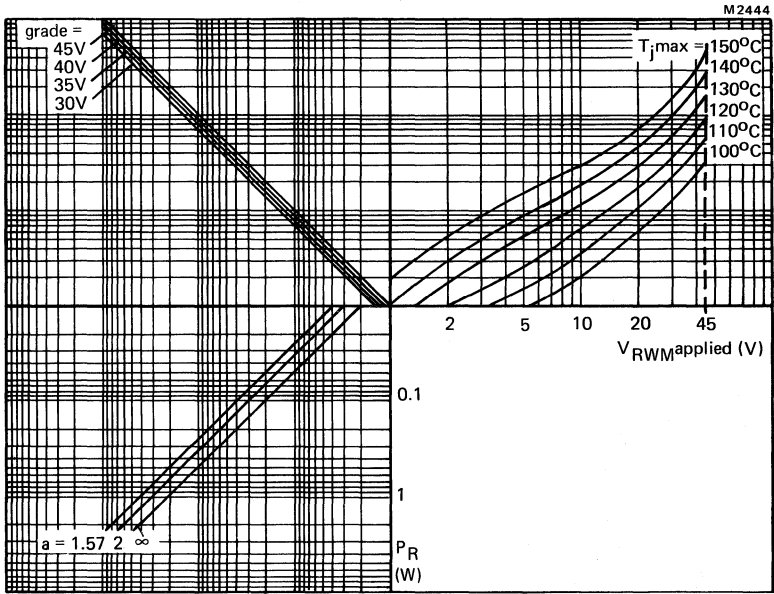


Fig.5 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_j \text{ max.}$, V_{RWM} applied, voltage grade and form factor.

$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$

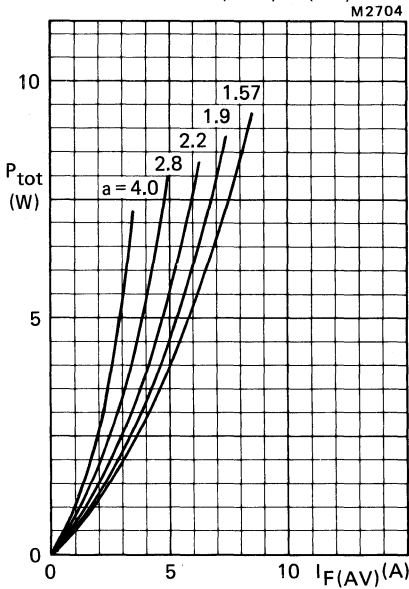


Fig.6 Forward current power rating.

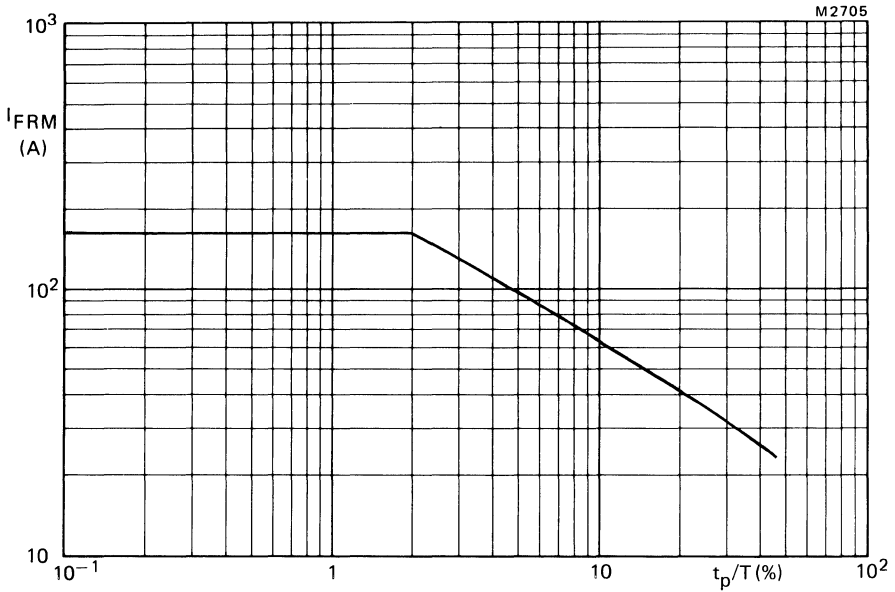


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1$ ms.

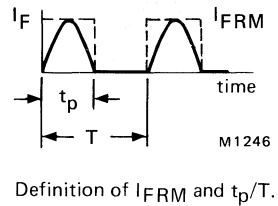
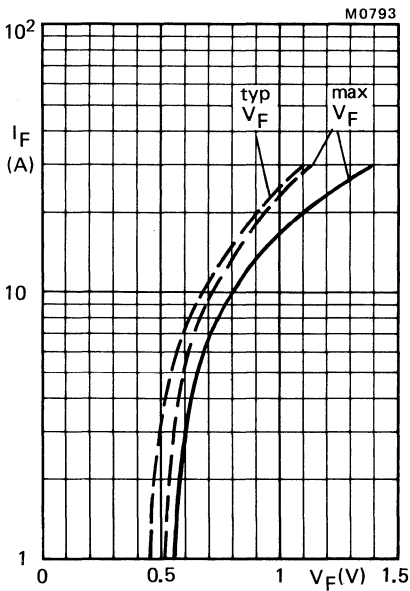


Fig.8 — $T_j = 25^\circ C$; - - - $T_j = 100^\circ C$.

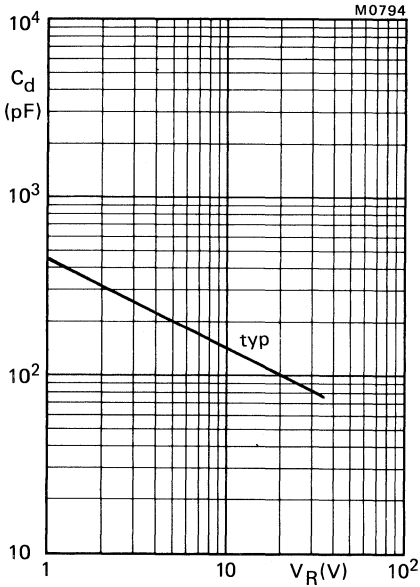


Fig.9 $f = 1$ MHz, $T_j = 25$ to 125 °C.

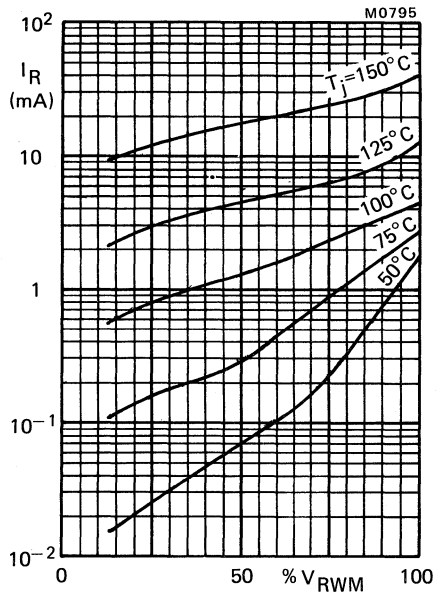


Fig.10 Typical values.

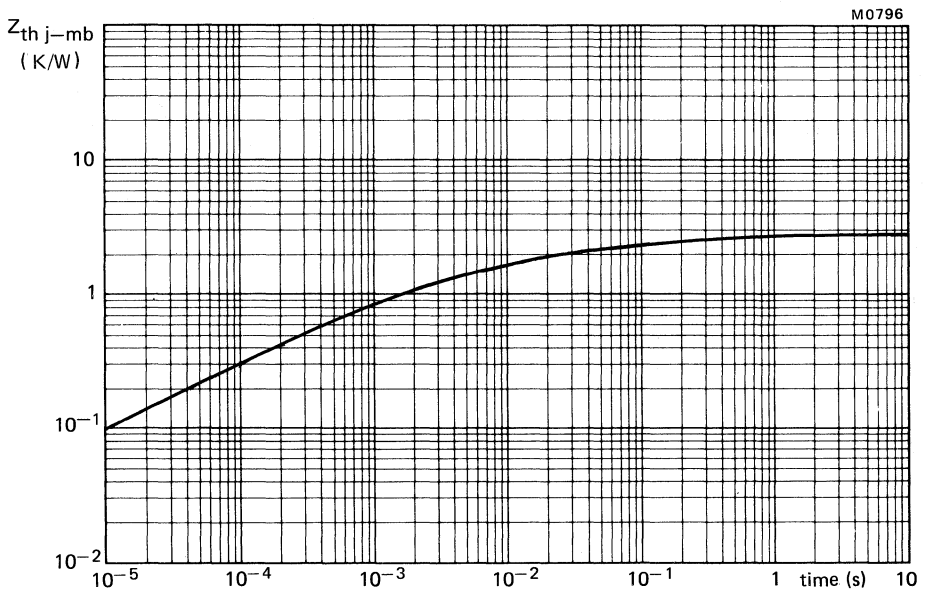


Fig.11 Transient thermal impedance.

SCHOTTKY -BARRIER RECTIFIER DIODES



High-efficiency schottky-barrier rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, low capacitance, absence of stored charge and high temperature stability. They are intended for use in low output voltage switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and zero switching losses are important. They can also withstand reverse voltage transients. The series consists of normal polarity (cathode to stud) types. A version with guaranteed reverse surge capability, BYV20-40A, is also available.

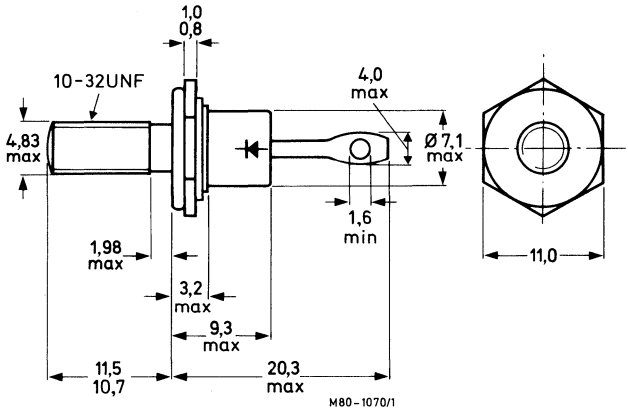
QUICK REFERENCE DATA

		BYV20-30	35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max. 30	35	40	45	V
Average forward current	$I_{F(AV)}$	max.	15			A
Forward voltage	V_F	<	0.6			V
Junction temperature	T_j	max.	150			°C

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4 with 10-32 UNF stud ($\phi 4.83$ mm) as standard.
Metric M5 stud ($\phi 5$ mm) is available on request, eg. BYV20-30M.



Net mass: 6 g

Diameter of clearance hole: 5.2 mm

Accessories supplied on request:
56295a (mica washer); 56295b (PTFE ring);
56295c (insulating bush).

Supplied with device: 1 nut, 1 lock washer.
Torque on nut:
min. 0.9 Nm (9 kg cm),
max. 1.7 Nm (17 kg cm).
Nut dimensions across the flats:
10-32 UNF, 9.5 mm; M5, 8.0 mm.

Products approved to CECC 50 009-033 available on request.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

		BYV20-30	35	40(A)	45	
Non-repetitive peak reverse voltage	V_{RSM}	max. 36	42	48	54	V
Repetitive peak reverse voltage (note 1)	V_{RRM}	max. 30	35	40	45	V
Crest working reverse voltage	V_{RWM}	max. 30	35	40	45	V
Continuous reverse voltage	V_R	max. 30	35	40	45	V

→ Currents

Average forward current square wave; $\delta = 0.5$; up to $T_{mb} = 121\text{ }^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.	15		A
sinusoidal; up to $T_{mb} = 124\text{ }^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.	12.5		A
R.M.S. forward current	$I_{F(RMS)}$	max.	21		A
Repetitive peak forward current $t_p = 20\text{ }\mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.	260		A
Non-repetitive peak forward current half sine-wave; $T_j = 125\text{ }^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max; $t = 10\text{ ms}$	I_{FSM}	max.	300		A
$t = 8.3\text{ ms}$	I_{FSM}	max.	330		A
I^2t for fusing ($t = 10\text{ ms}$)	I^2t	max.	450		A^2s
Reverse surge current (BYV20-40A only) $t_p = 100\text{ }\mu\text{s}$	I_{RSM}	max.	1.0		A

Temperatures

Storage temperature	T_{stg}		-55 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.	150		$^\circ\text{C}$

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering, the heat conduction to the junction should be kept to a minimum.

Notes:

1. For $t_p = 200\text{ ns}$ a 20% increase in V_{RRM} is allowed.
2. Assuming no reverse leakage current losses.

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	2.2	K/W
From mounting base to heatsink with heatsink compound	$R_{th\ mb-h}$	=	0.5	K/W
Transient thermal impedance; $t = 1\ ms$	$Z_{th\ j-mb}$	=	0.85	K/W ←

CHARACTERISTICS

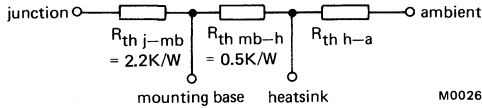
Forward voltage				
$I_F = 15\ A; T_j = 100\ ^\circ C$	V_F	<	0.6	V*
$I_F = 40\ A; T_j = 25\ ^\circ C$	V_F	<	1.0	V*
Rate of rise of reverse voltage				
$V_R = V_{RWMmax}$	$\frac{dV_R}{dt}$	<	1500	V/ μs ←
Reverse current				
$V_R = V_{RWMmax}; T_j = 125\ ^\circ C$	I_R	<	70	mA
Capacitance at $f = 1\ MHz$				
$V_R = 5\ V; T_j = 25\ to\ 125\ ^\circ C$	C_d	typ.	520	pF

*Measured under pulse conditions to avoid excessive dissipation.

→ OPERATING NOTES

Dissipation and Heatsink Calculations

The various components of junction temperature rise above ambient are shown below:



m0026 Fig.2

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required:

- (i) maximum operating ambient temperature
- (ii) duty cycle or form factor of forward current (δ or a)
- (iii) average forward current
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R — reverse leakage dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

P_F — forward conduction dissipation

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_R + P_F} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows: Starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis.

Forward conduction dissipation (P_F) for the known average current $I_{F(AV)}$ and duty cycle (or form factor) is easily derived from Fig.4 (or Fig.6).

Substituting the values of P_R and P_F into equation 2) enables the calculation of the required heatsink.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than 12 °C. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV20-35 and heatsink compound;
 $T_{amb} = 50\text{ °C}$; $\delta = 0.5$; $I_{F(AV)} = 12\text{ A}$
 $V_{RWM} = 12\text{ V}$; voltage grade of device = 35 V
 From data, $R_{th\ j-mb} = 2.2\text{ K/W}$ and $R_{th\ mb-h} = 0.5\text{ K/W}$.
 From Fig.4, it is found that $P_F = 9.2\text{ W}$
 If the desired T_{jmax} is chosen to be 130 °C, then from Fig.3, $P_R = 0.3\text{ W}$
 Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\text{ °C} - 50\text{ °C}}{9.2\text{ W} + 0.3\text{ W}} - (2.2 + 0.5) = 5.7\text{ K/W}$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (2.2 + 0.5 + 5.7) \times 0.3 = 2.5\text{ °C}.$$

This is less than 12 °C, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs.3 and 4)

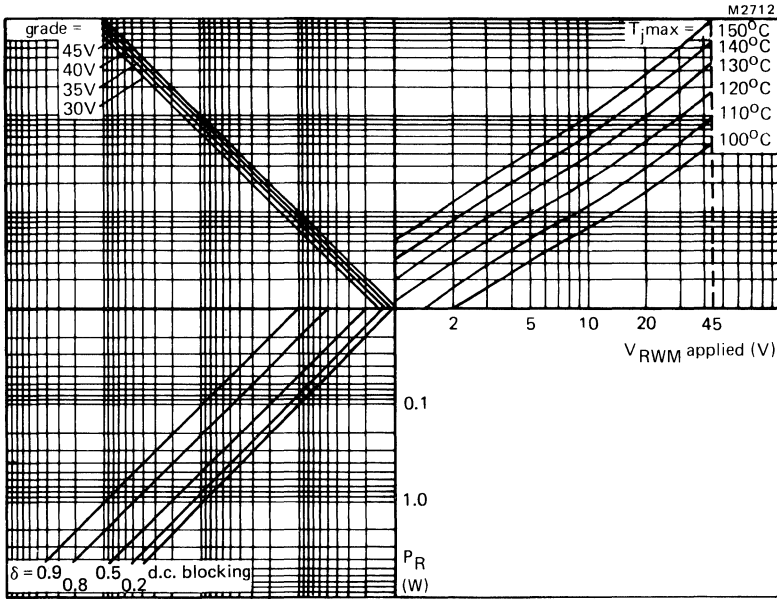
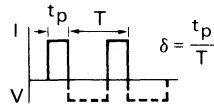
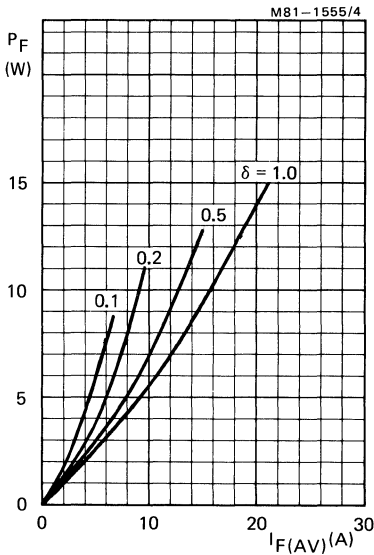


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_j \text{ max.}$, V_{RWM} applied, voltage grade and duty cycle.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

Fig.4.

SINE-WAVE OPERATION (Figs.5 and 6)

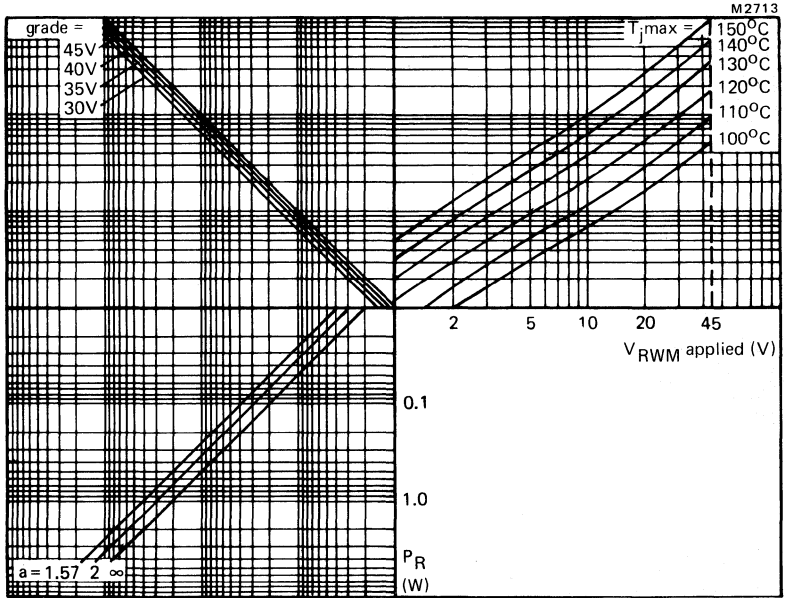


Fig.5 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_j, \text{max.}$, V_{RWM} applied, voltage grade and form factor.

$a = \text{form factor} = I_F(\text{RMS})/I_F(\text{AV})$

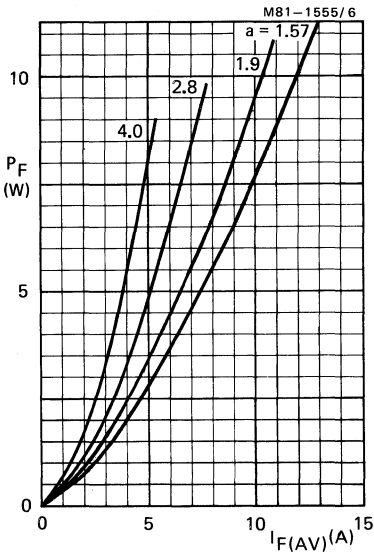


Fig.6.

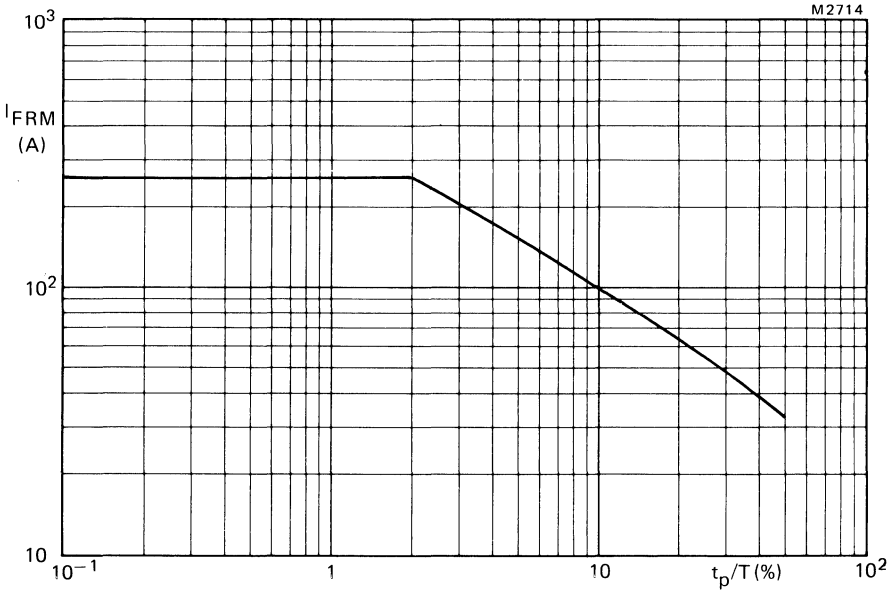


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 ms$.

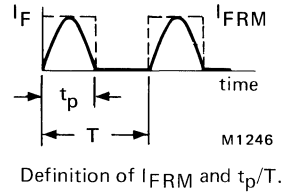
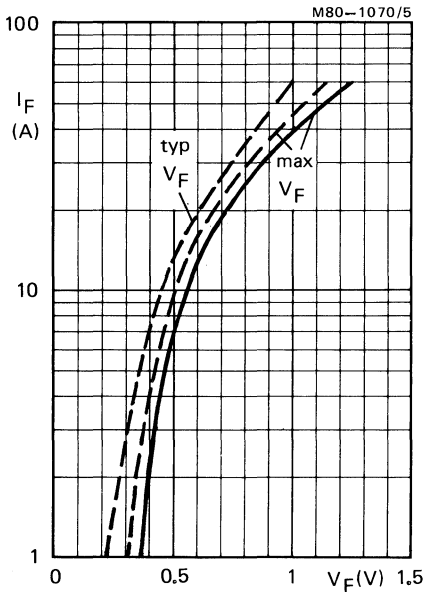


Fig.8 — $T_j = 25^\circ C$; - - - $T_j = 100^\circ C$.

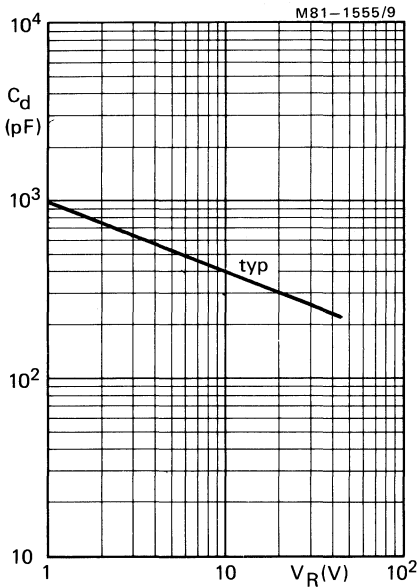


Fig.9 $f = 1$ MHz; $T_j = 25$ to 125 °C.

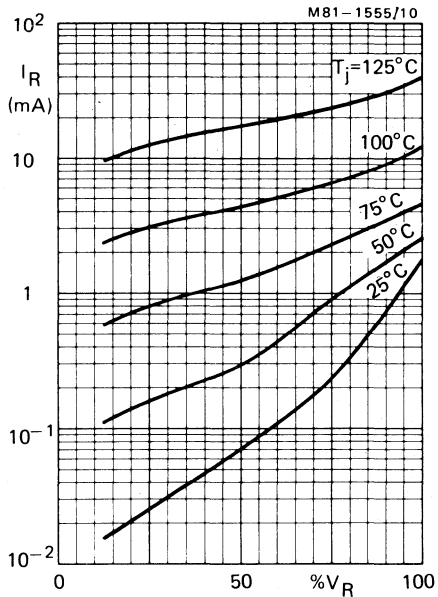


Fig.10 Typical values.

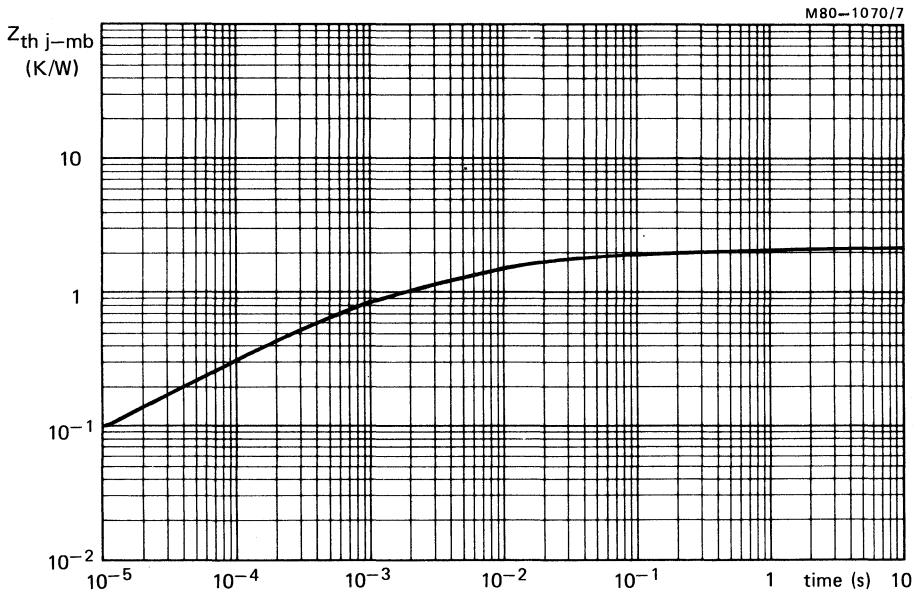


Fig.11 Transient thermal impedance.

SCHOTTKY-BARRIER RECTIFIER DIODES



High-efficiency schottky-barrier rectifier diodes in DO-4 metal envelopes, featuring low forward voltage drop, low capacitance, absence of stored charge and high temperature stability. They are intended for use in low output voltage switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and zero switching losses are important. They can also withstand reverse voltage transients. The series consists of normal polarity (cathode to stud) types. A version with guaranteed reverse surge capability, BYV21-40A, is also available.

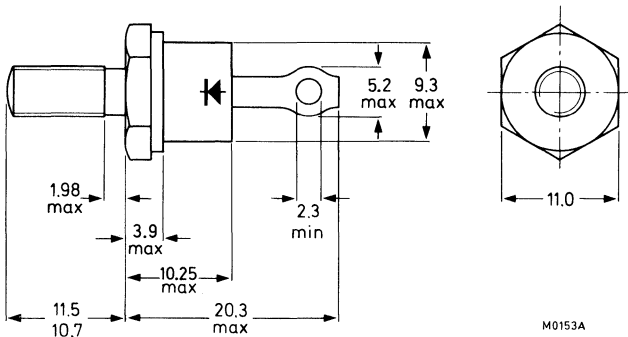
QUICK REFERENCE DATA

			BYV21-30	35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45	V
Average forward current	$I_{F(AV)}$	max.	30				A
Forward voltage	V_F	<	0.55				V
Junction temperature	T_j	max.	150				°C

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-4 with 10-32 UNF stud ($\phi 4.83$ mm) as standard.
Metric M5 stud ($\phi 5$ mm) is available on request, e.g. BYV21-30M.



Net mass: 7 g

Diameter of clearance hole: 5.2 mm

Accessories supplied on request:

- 56295a (mica washer),
- 56295b (PTFE ring),
- 56295c (insulating bush).

Supplied with device: 1 nut, 1 lock washer.

Torque on nut:

- min. 0.9 Nm (9 kg cm),
- max. 1.7 Nm (17 kg cm).

Nut dimensions across the flats:

- 10-32 UNF, 9.5 mm; M5, 8.0 mm.

Products approved to CECC 50 009-018 available on request.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Voltages

		BYV21-30	35	40(A)	45	
Non-repetitive peak reverse voltage	V_{RSM}	max. 36	42	48	54	V
Repetitive peak reverse voltage (note 1)	V_{RRM}	max. 30	35	40	45	V
Crest working reverse voltage	V_{RWM}	max. 30	35	40	45	V
Continuous reverse voltage	V_R	max. 30	35	40	45	V

→ Currents

Average forward current; switching losses negligible square wave; $\delta = 0.5$; up to $T_{mb} = 124^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.		30		A
sinusoidal; up to $T_{mb} = 125^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.		27		A
R.M.S. forward current	$I_{F(RMS)}$	max.		42.5		A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.		500		A
Non-repetitive peak forward current half sine-wave; $T_j = 125^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max; $t = 10 \text{ ms}$	I_{FSM}	max.		600		A
$t = 8.3 \text{ ms}$	I_{FSM}	max.		650		A
$I^2 t$ for fusing ($t = 10 \text{ ms}$)	$I^2 t$	max.		1800		A^2s
Reverse surge current (BYV21-40A only) $t_p = 100 \mu\text{s}$	I_{RSM}	max.		1.0		A

Temperatures

Storage temperature	T_{stg}			-55 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.		150		$^\circ\text{C}$

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering, the heat conduction to the junction should be kept to a minimum.

Notes:

1. For $t_p = 200 \text{ ns}$ a 20% increase in V_{RRM} is allowed.
2. Assuming no reverse leakage current losses.

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	1	K/W
From mounting base to heatsink with heatsink compound	$R_{th\ mb-h}$	=	0.3	K/W
without heatsink compound	$R_{th\ mb-h}$	=	0.5	K/W
Transient thermal impedance; $t = 1\ ms$	$Z_{th\ j-mb}$	=	0.15	K/W

CHARACTERISTICS

Forward voltage

$I_F = 30\ A; T_j = 100\ ^\circ C$	V_F	<	0.55	V*
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$I_F = 80\ A; T_j = 25\ ^\circ C$	V_F	<	0.88	V*
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Rate of rise of reverse voltage

$V_R = V_{RWMmax}$	$\frac{dV_R}{dt}$	<	1500	V/ μs
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Reverse current

$V_R = V_{RWMmax}; T_j = 125\ ^\circ C$	I_R	<	150	mA
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Capacitance at $f = 1\ MHz$

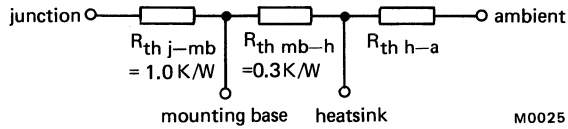
$V_R = 5\ V; T_j = 25\ to\ 125\ ^\circ C$	C_d	typ.	1150	pF
---	-------	------	------	----

*Measured under pulse conditions to avoid excessive dissipation.

→ OPERATING NOTES

Dissipation and heatsink calculations

The various components of junction temperature rise above ambient are shown below:



m0025 Fig.2

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required:

- (i) maximum operating ambient temperature
- (ii) duty-cycle or form-factor of forward current (δ or a)
- (iii) average forward current
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R – reverse leakage dissipation

P_F – forward conduction dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1)$$

From the above, it can be seen that:

$$R_{th\ h-a} = \frac{T_{j\ max} - T_{amb}}{P_R + P_F} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2)$$

values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal resistance.

P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows:

Starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis.

Forward conduction dissipation (P_F) for the known average current $I_F(AV)$ and duty cycle (or form factor) is easily derived from Fig.4 (or Fig.6).

Substituting the values of P_R and P_F into equation 2) enables the calculation of the required heatsink. To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than $12\ ^\circ C$. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV21-35 and heatsink compound;

$T_{amb} = 30\ ^\circ C$; $\delta = 0.5$; $I_F(AV) = 20\ A$; $V_{RWM} = 12\ V$; voltage grade of device = $35\ V$.

From data, $R_{th\ j-mb} = 1.0\ K/W$ and $R_{th\ mb-h} = 0.3\ K/W$.

From Fig.4, it is found that $P_F = 14\ W$

If desired T_{jmax} is chosen to be $120\ ^\circ C$, then, from Fig.3, $P_R = 0.35\ W$

Using equation 2) we have:

$$R_{th\ h-a} = \frac{120\ ^\circ C - 30\ ^\circ C}{14\ W + 0.35\ W} - (1.0 + 0.3) = 5\ K/W$$

To check for thermal stability: $(R_{th\ j-a}) \times P_R = (1.0 + 0.3 + 5) \times 0.35 = 2.2\ ^\circ C$.

This is less than $12\ ^\circ C$, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs.3 and 4)

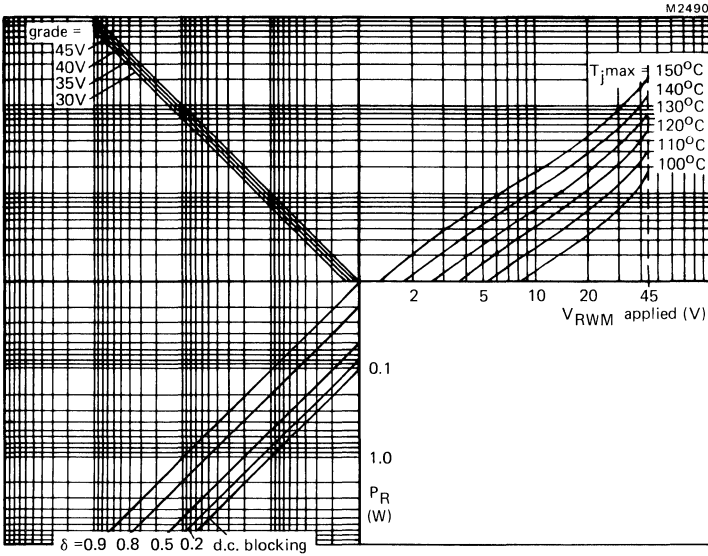


Fig.3 Maximum permissible junction temperature as a function of crest working reverse voltage and duty cycle of forward conduction.

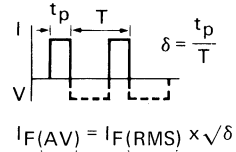
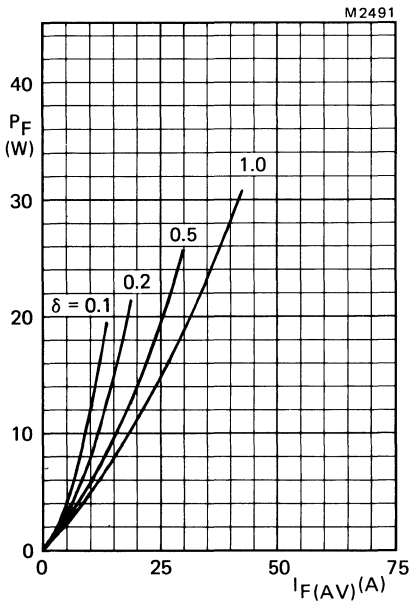


Fig.4

SINE-WAVE OPERATION (Figs.5 and 6)

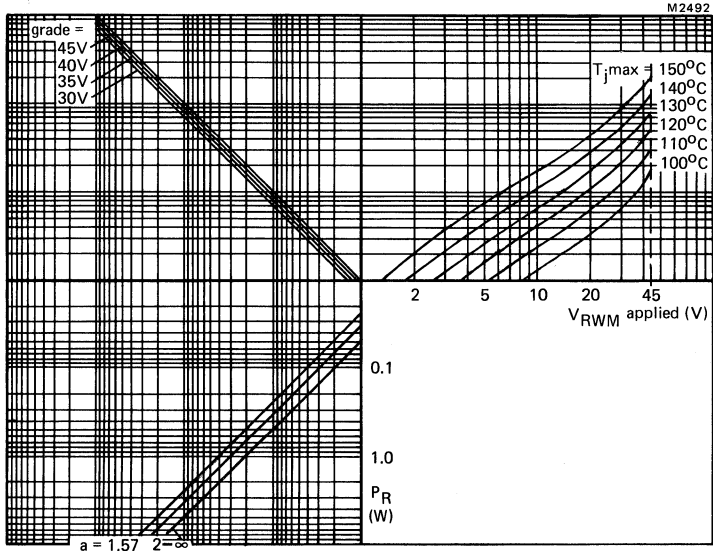


Fig.5 Maximum permissible junction temperature as a function of crest working reverse voltage and form factor of forward conduction.

$a = \text{form factor} = I_F(\text{RMS})/I_F(\text{AV})$.

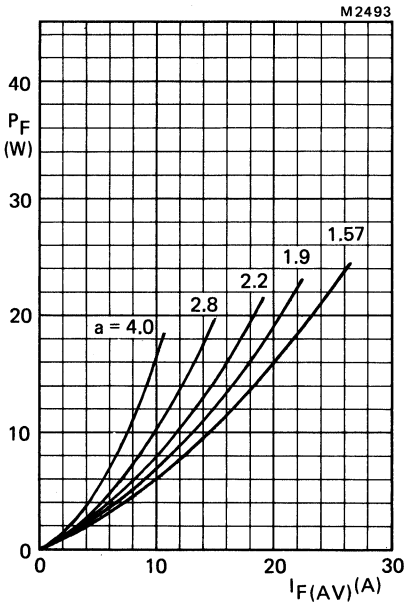


Fig.6

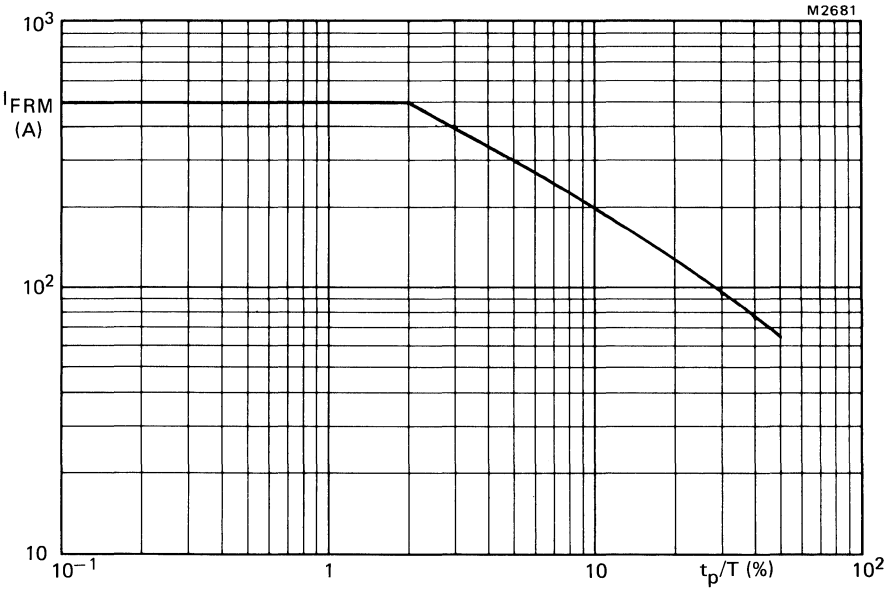
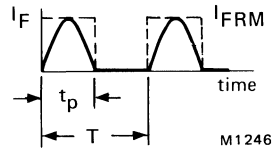
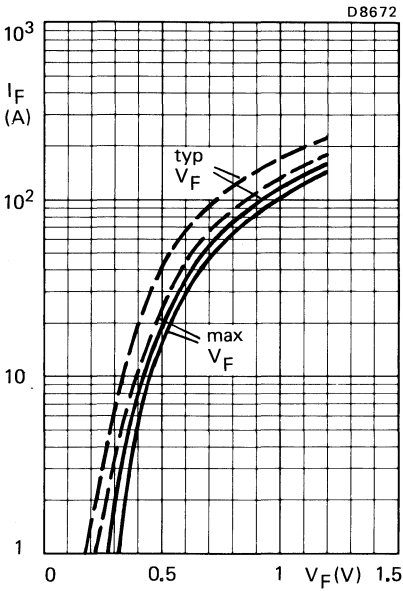


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu\text{s} < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25^\circ\text{C}$; - - - $T_j = 100^\circ\text{C}$.

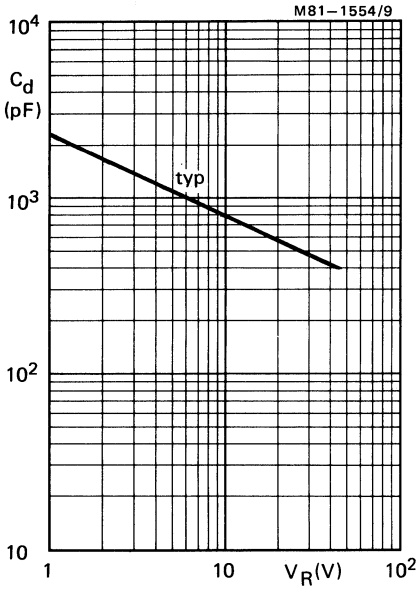


Fig.9 $f = 1 \text{ MHz}$; $T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$

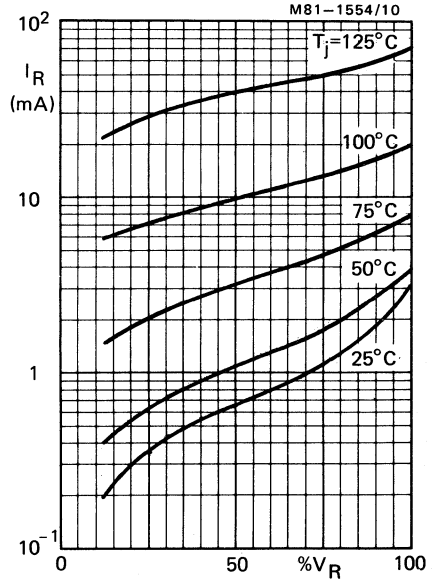


Fig.10 Typical values

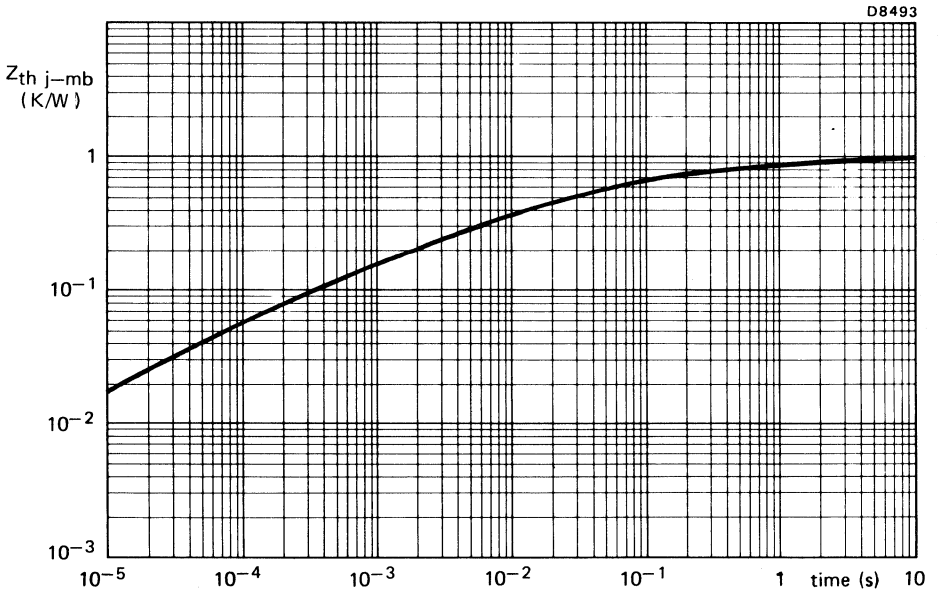


Fig.11

SCHOTTKY-BARRIER RECTIFIER DIODES



High-efficiency schottky-barrier rectifier diodes in DO-5 metal envelopes, featuring low forward voltage drop, low capacitance, absence of stored charge and high temperature stability. They are intended for use in low output voltage switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and zero switching losses are important. They can also withstand reverse voltage transients. The series consists of normal polarity (cathode to stud) types. A version with guaranteed reverse surge capability, BYV22-40A, is also available.

QUICK REFERENCE DATA

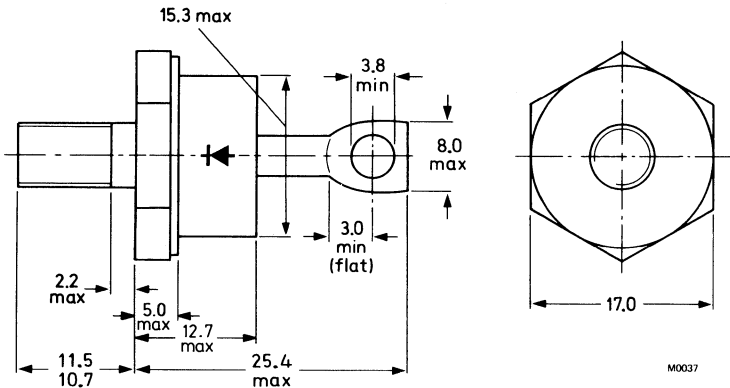
				BYV22-30	35	40(A)	45		
Repetitive peak reverse voltage	V_{RRM}	max.		30	35	40	45		V
Average forward current	$I_F(AV)$	max.				60			A
Forward voltage	V_F	<				0.55			V
Junction temperature	T_j	max.				150			°C

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5 with 1/4" x 28 UNF stud (φ6.35 mm)

Types with metric M6 stud (φ6 mm) are available on request; e.g. BYV22-30M.



Net mass: 22 g

Diameter of clearance hole: 6.5 mm

Accessories supplied on request:

56264a (mica washer)

56264b (insulating bush).

Products approved to CECC 50 009-034 available on request

Supplied with device: 1 nut, 1 lock washer

Torque on nut:

min. 1.7 Nm (17 kg cm),

max. 3.5 Nm (35 kg cm),

Nut dimensions across the flats

1/4" x 28 UNF, 11.1 mm; M6, 10 mm.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

		BYV22-30	35	40(A)	45	
Non-repetitive peak reverse voltage	V_{RSM}	max. 36	42	48	54	V
Repetitive peak reverse voltage (note 1)	V_{RRM}	max. 30	35	40	45	V
Crest working reverse voltage	V_{RWM}	max. 30	35	40	45	V
Continuous reverse voltage	V_R	max. 30	35	40	45	V

→ Currents

Average forward current square wave; $\delta = 0.5$; up to $T_{mb} = 124^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.		60		A
sinusoidal; up to $T_{mb} = 127^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.		50		A
R.M.S. forward current	$I_{F(RMS)}$	max.		85		A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.		1100		A
Non-repetitive peak forward current half sine-wave; $T_j = 125^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max $t = 10$ ms	I_{FSM}	max.		1000		A
$t = 8.3$ ms	I_{FSM}	max.		1100		A
$I^2 t$ for fusing ($t = 10$ ms)	$I^2 t$	max.		5000		A^2s
Reverse surge current (BYV22-40A only) $t_p = 100 \mu\text{s}$	I_{RSM}	max.		2.0		A

Temperatures

Storage temperature	T_{stg}			-55 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.		150		$^\circ\text{C}$

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering, the heat conduction to the junction should be kept to a minimum.

Notes:

1. For $t_p = 200$ ns a 20% increase in V_{RRM} is allowed.
2. Assuming no reverse leakage current losses.

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	0.6	K/W
From mounting base to heatsink with heatsink compound without heatsink compound	$R_{th\ mb-h}$	=	0.3	K/W
	$R_{th\ mb-h}$	=	0.5	K/W
Transient thermal impedance; $t = 1\ ms$	$Z_{th\ j-mb}$	=	0.072	K/W

CHARACTERISTICS

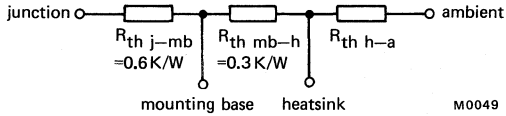
Forward voltage				
$I_F = 50\ A; T_j = 100\ ^\circ C$	V_F	<	0.55	V*
$I_F = 150\ A; T_j = 25\ ^\circ C$	V_F	<	0.9	V*
Rate of rise of reverse voltage				
$V_R = V_{RWMmax}$	$\frac{dV_R}{dt}$	<	1500	V/ μs
Reverse current				
$V_R = V_{RWMmax}; T_j = 125\ ^\circ C$	I_R	<	250	mA
Capacitance at $f = 1\ MHz$				
$V_R = 5\ V; T_j = 25\ to\ 125\ ^\circ C$	C_d	typ.	2100	pF

*Measured under pulse conditions to avoid excessive dissipation.

→ OPERATING NOTES

Dissipation and Heatsink Calculations

The various components of junction temperature rise above ambient are shown below:



Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required:

- (i) maximum operating ambient temperature
- (ii) duty cycle or form factor of forward current (δ or a)
- (iii) average forward current
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R – reverse leakage dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

P_F – forward conduction dissipation

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_R + P_F} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows: Starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis.

Forward conduction dissipation (P_F) for the known average current $I_{F(AV)}$ and duty cycle (or form factor) is easily derived from Fig.4 (or Fig.6).

Substituting the values of P_R and P_F into equation 2) enables the calculation of the required heatsink.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than 12 °C. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV22-35 and heatsink compound;
 $T_{amb} = 40\ ^\circ C$; $\delta = 0.5$; $I_{F(AV)} = 30\ A$
 $V_{RWM} = 12\ V$; voltage grade of device = 35 V
 From data, $R_{th\ j-mb} = 0.6\ K/W$ and $R_{th\ mb-h} = 0.3\ K/W$.
 From Fig.4, it is found that $P_F = 18\ W$
 If the desired T_{jmax} is chosen to be 130 °C, then from Fig.3, $P_R = 0.9\ W$
 Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\ ^\circ C - 40\ ^\circ C}{18\ W + 0.9\ W} - (0.6 + 0.3) = 3.9\ K/W$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (0.6 + 0.3 + 3.9) \times 0.9 = 4.3\ ^\circ C.$$

This is less than 12 °C, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs.3 and 4)

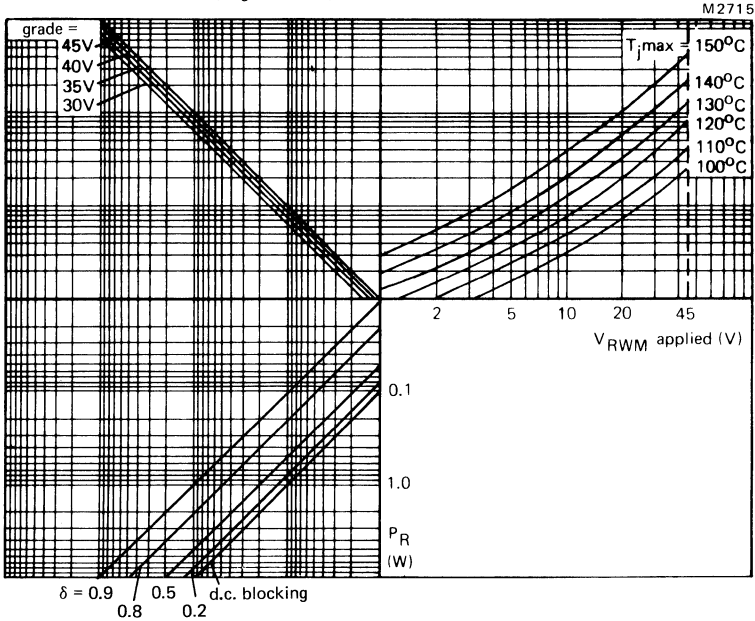


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given T_j max., V_{RWM} applied, voltage grade and duty cycle.

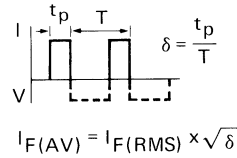
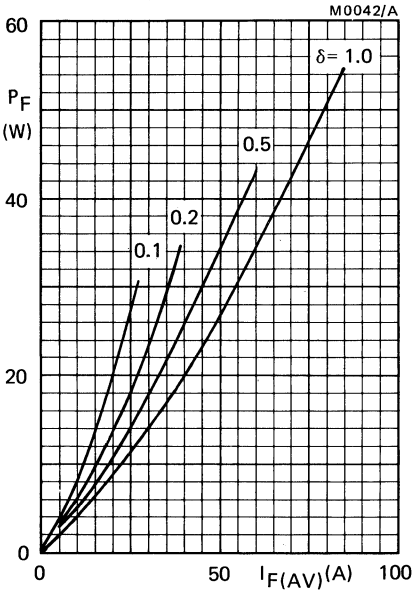


Fig.4.

SINE-WAVE OPERATION (Figs.5 and 6)

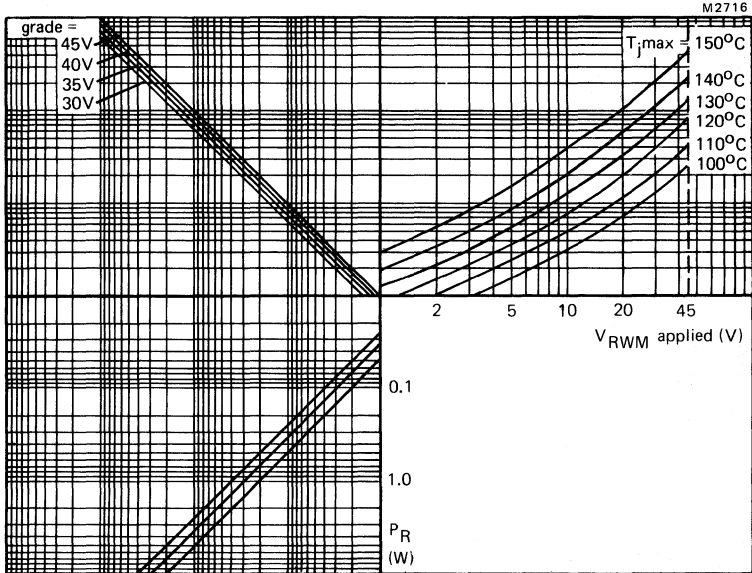


Fig.5 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_{j,max}$, V_{RWM} applied, voltage grade and form factor.

$a = \text{form factor} = I_{F(RMS)} / I_{F(AV)}$

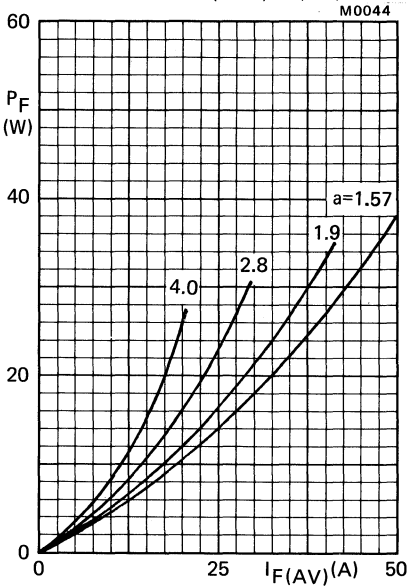


Fig.6.

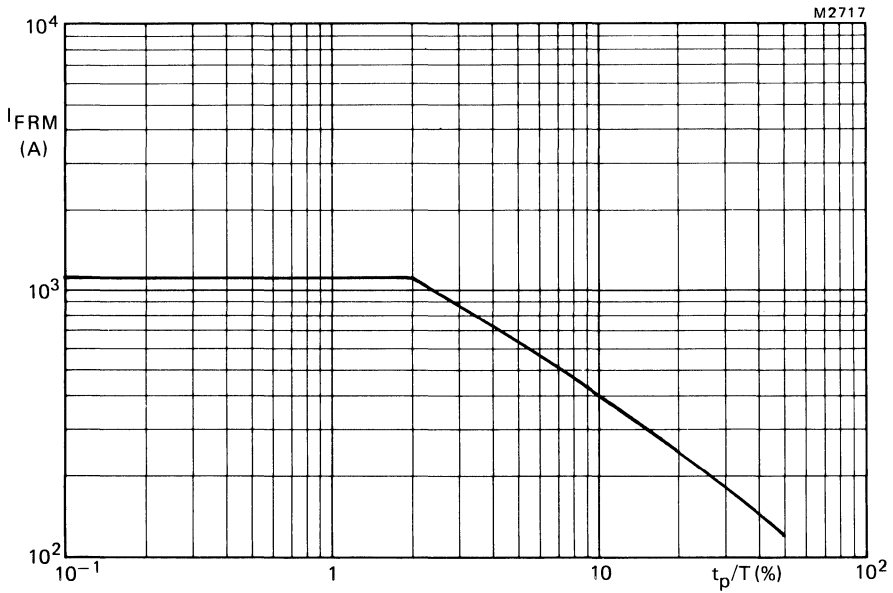


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1$ ms.

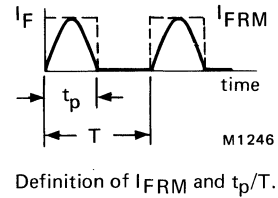
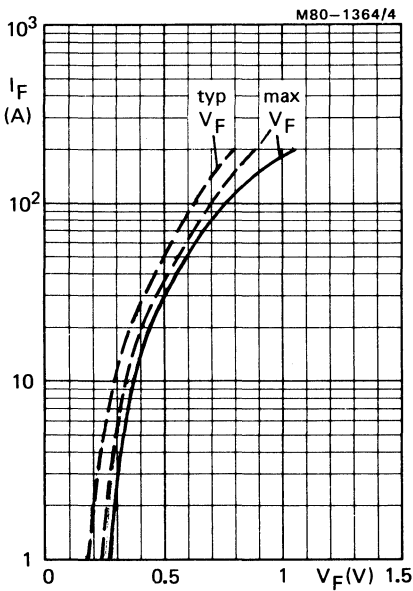


Fig.8 — $T_j = 25^\circ C$; - - - $T_j = 100^\circ C$.

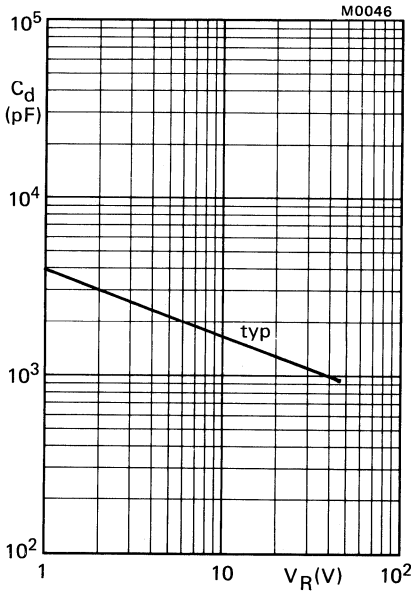


Fig.9 $f = 1 \text{ MHz}$; $T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$.

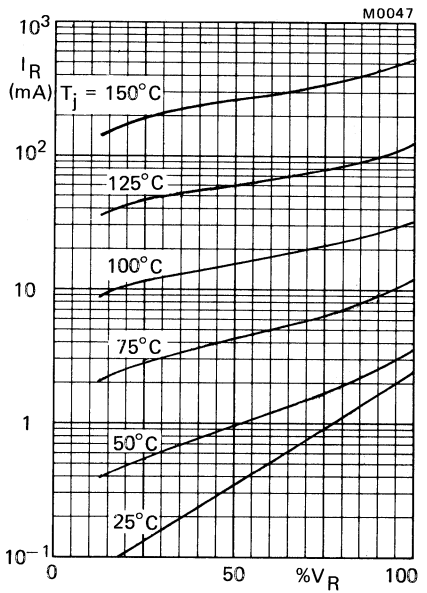


Fig.10 Typical values.

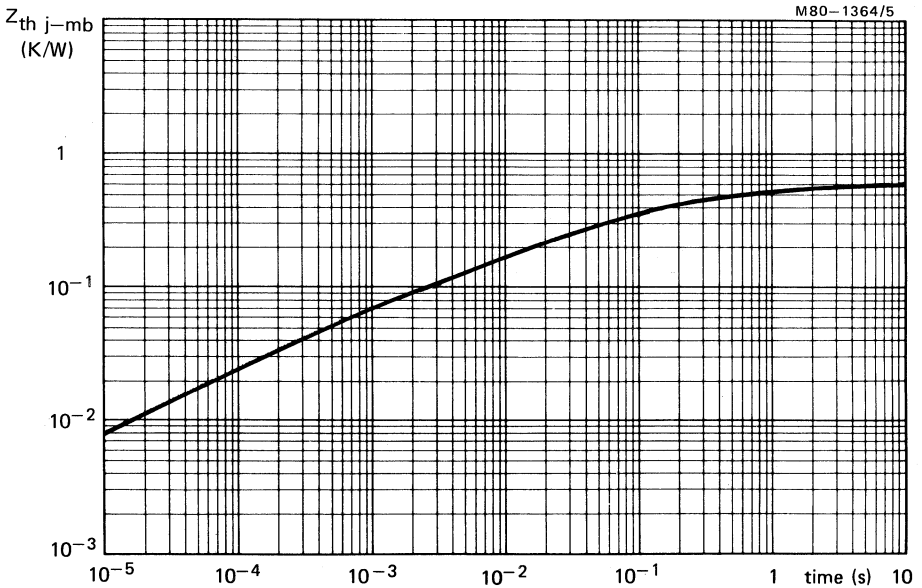


Fig.11 Transient thermal impedance.

SCHOTTKY-BARRIER RECTIFIER DIODES



High-efficiency schottky-barrier rectifier diodes in DO-5 metal envelopes, featuring low forward voltage drop, low capacitance, absence of stored charge and high temperature stability. They are intended for use in low output voltage switched-mode power supplies and high-frequency circuits in general, where low conduction losses and switching losses are important. They can also withstand reverse voltage transients. The series consists of normal polarity (cathode to stud) types. A version with guaranteed reverse surge capability, BYV23-40A, is also available.

QUICK REFERENCE DATA

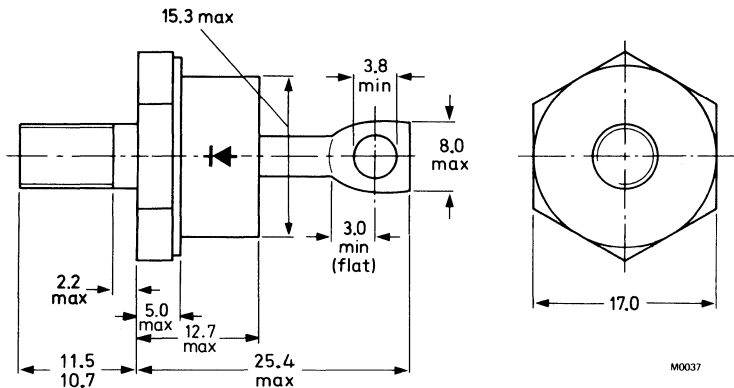
		BYV23-30				35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45		V	
Average forward current	$I_{F(AV)}$	max.			80			A	
Forward voltage	V_F	<			0.55			V	
Junction temperature	T_j	max.			150			°C	

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5 with 1/4" x 28 UNF stud (φ6.35 mm)

Types with metric M6 stud (φ6 mm) are available on request; e.g. BYV23-30M.



Net mass: 22 g

Diameter of clearance hole: 6.5 mm

Accessories supplied on request:

- 56264a (mica washer),
- 56264b (insulating bush).

Supplied with device: 1 nut, 1 lock washer

Torque on nut:

- min. 1.7 Nm (17 kg cm),
- max. 3.5 Nm (35 kg cm).

Nut dimensions across the flats:

1/4" x 28 UNF, 11.1 mm; M6, 10 mm.

Products approved to CECC 50 009-036 available on request

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages

		BYV23-30	35	40(A)	45	
Non-repetitive peak reverse voltage	V_{RSM}	max. 36	42	48	54	V
Repetitive peak reverse voltage (note 1)	V_{RRM}	max. 30	35	40	45	V
Crest working reverse voltage	V_{RWM}	max. 30	35	40	45	V
Continuous reverse voltage	V_R	max. 30	35	40	45	V

→ Currents

Average forward current square wave; $\delta = 0.5$; up to $T_{mb} = 115^\circ\text{C}$ (note 2)	$I_F(AV)$	max.	80		A
sinusoidal; up to $T_{mb} = 116^\circ\text{C}$ (note 2)	$I_F(AV)$	max.	70		A
R.M.S. forward current	$I_F(RMS)$	max.	113		A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.	1500		A
Non-repetitive peak forward current half sine-wave; $T_j = 125^\circ\text{C}$ prior to surge; with reapplied V_{RWMmax}					
$t = 10 \text{ ms}$	I_{FSM}	max.	1500		A
$t = 8.3 \text{ ms}$	I_{FSM}	max.	1650		A
$I^2 t$ for fusing ($t = 10 \text{ ms}$)	$I^2 t$	max.	11250		A^2s
Reverse surge current (BYV23-40A only) $t_p = 100 \mu\text{s}$	I_{RSM}	max.	2.0		A

Temperatures

Storage temperature	T_{stg}		-55 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.	150		$^\circ\text{C}$

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering, the heat conduction to the junction should be kept to a minimum.

Notes:

1. For $t_p = 200 \text{ ns}$ a 20% increase in V_{RRM} is allowed.
2. Assuming no reverse leakage current losses.

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	0.6	K/W
From mounting base to heatsink with heatsink compound	$R_{th\ mb-h}$	=	0.3	K/W
without heatsink compound	$R_{th\ mb-h}$	=	0.5	K/W
Transient thermal impedance; $t = 1\ ms$	$Z_{th\ j-mb}$	=	0.07	K/W

CHARACTERISTICS

Forward voltage

$I_F = 70\ A; T_j = 100\ ^\circ C$	V_F	<	0.55	V*
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$I_F = 200\ A; T_j = 25\ ^\circ C$	V_F	<	0.95	V*
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Rate of rise of reverse voltage

$V_R = V_{RWMmax}$	$\frac{dV_R}{dt}$	<	1500	V/ μs
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Reverse current

$V_R = V_{RWMmax}; T_j = 125\ ^\circ C$	I_R	<	350	mA
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Capacitance at $f = 1\ MHz$

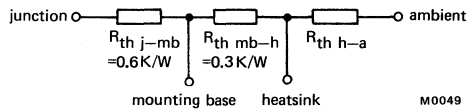
$V_R = 5\ V; T_j = 25\ to\ 125\ ^\circ C$	C_d	typ.	2500	pF
---	-------	------	------	----

*Measured under pulse conditions to avoid excessive dissipation.

→ OPERATING NOTES

Dissipation and Heatsink Calculations

The various components of junction temperature rise above ambient are shown below:



M0049 Fig.2

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required:

- (i) maximum operating ambient temperature
- (ii) duty cycle or form factor of forward current (δ or a)
- (iii) average forward current
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R – reverse leakage dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

P_F – forward conduction dissipation

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_R + P_F} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows: Starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis.

Forward conduction dissipation (P_F) for the known average current $I_F(AV)$ and duty cycle (or form factor) is easily derived from Fig.4 (or Fig.6).

Substituting the values of P_R and P_F into equation 2) enables the calculation of the required heatsink.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than $12\text{ }^\circ\text{C}$. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV23-35 and heatsink compound;
 $T_{amb} = 40\text{ }^\circ\text{C}$; $\delta = 0.5$; $I_F(AV) = 50\text{ A}$
 $V_{RWM} = 12\text{ V}$; voltage grade of device = 35 V
 From data, $R_{th\ j-mb} = 0.6\text{ K/W}$ and $R_{th\ mb-h} = 0.3\text{ K/W}$.
 From Fig.4, it is found that $P_F = 35\text{ W}$
 If the desired T_{jmax} is chosen to be $140\text{ }^\circ\text{C}$, then from Fig.3, $P_R = 2.4\text{ W}$
 Using equation 2) we have:

$$R_{th\ h-a} = \frac{140\text{ }^\circ\text{C} - 40\text{ }^\circ\text{C}}{35\text{ W} + 2.4\text{ W}} - (0.6 + 0.3) = 1.8\text{ K/W}$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (0.6 + 0.3 + 1.8) \times 2.4 = 6.5\text{ }^\circ\text{C}.$$

This is less than $12\text{ }^\circ\text{C}$, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs.3 and 4)

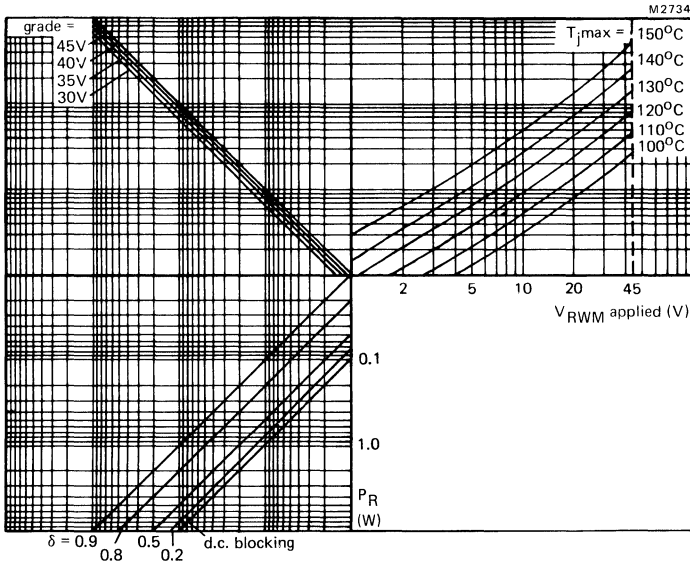
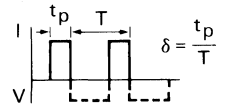
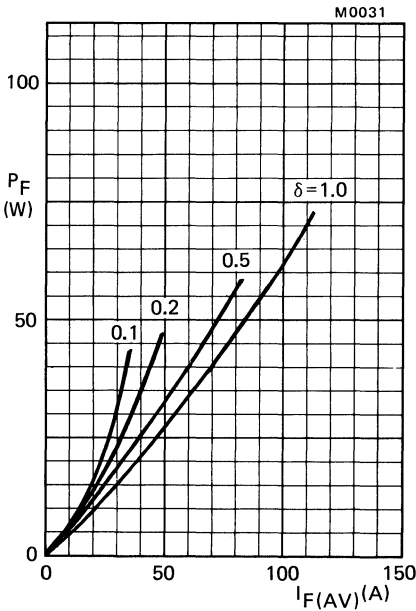


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_{j,max}$, V_{RWM} applied, voltage grade and duty cycle.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

Fig.4

SINE-WAVE OPERATION (Figs.5 and 6)

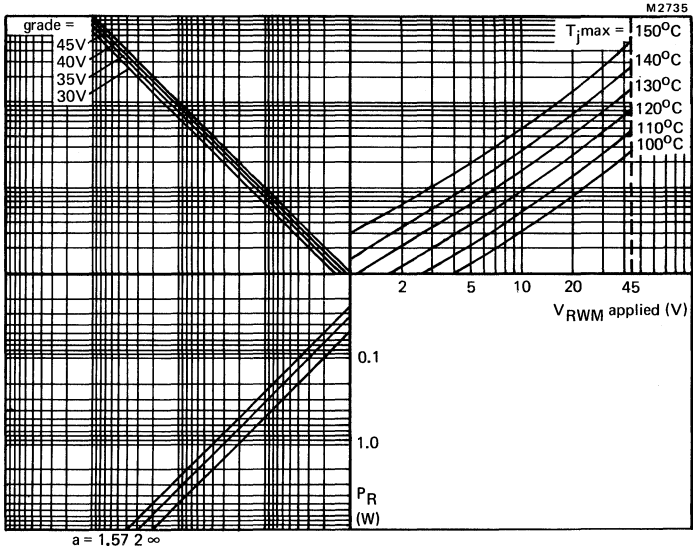


Fig.5 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given T_{jmax} , V_{RWM} applied, voltage grade and form factor.

$a =$ form factor = $I_{F(RMS)}/I_{F(AV)}$.

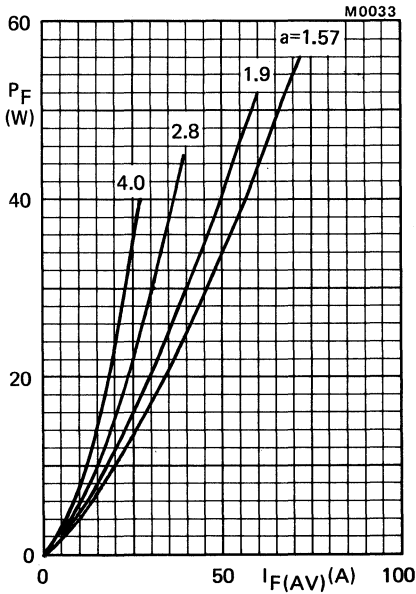


Fig.6

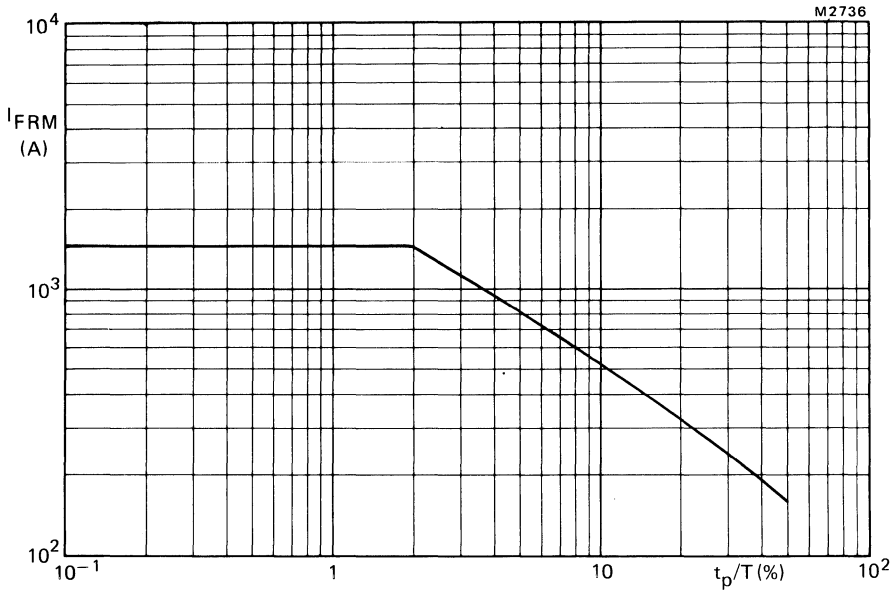
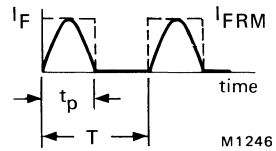
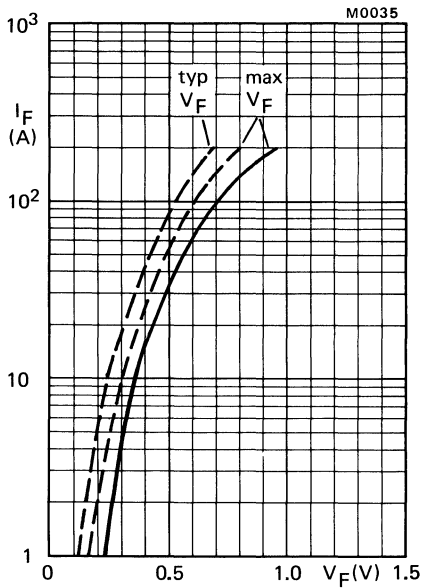


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal current for $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 100 \text{ }^\circ\text{C}$.

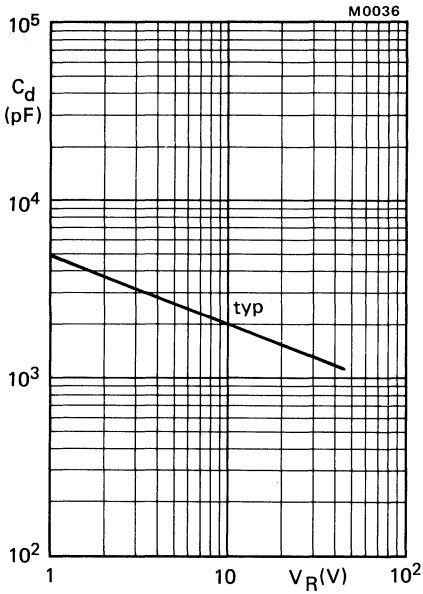


Fig.9 $f = 1$ MHz; $T_j = 25$ to 125 °C.

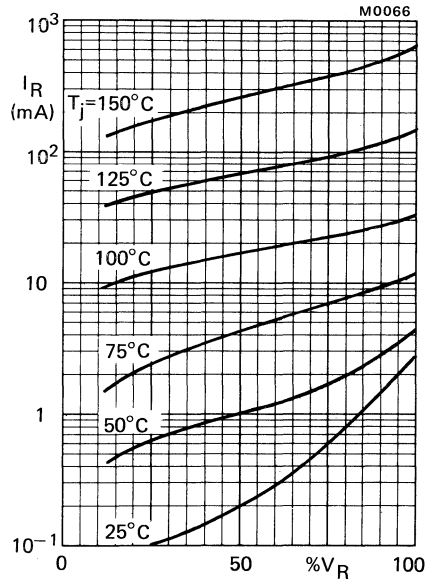


Fig.10 Typical values.

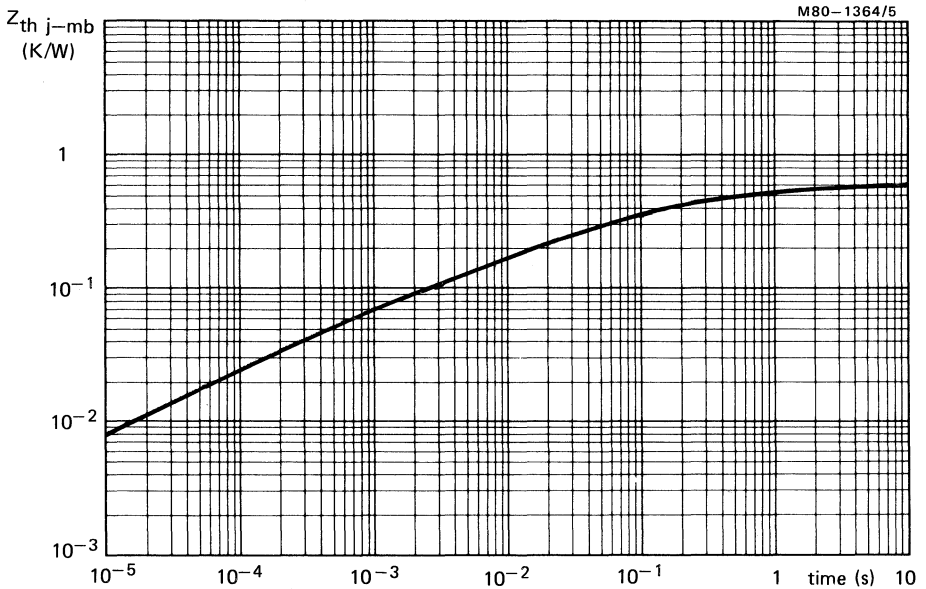


Fig.11 Transient thermal impedance.

SCHOTTKY-BARRIER DOUBLE RECTIFIER DIODES

High-efficiency schottky-barrier double rectifier diodes in plastic envelopes, featuring low forward voltage drop, low capacitance and absence of stored charge. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and low switching losses are essential. The single chip (monolithic) construction allows both diodes to be paralleled without the need for derating. They can also withstand reverse voltage transients. The series consists of common-cathode types. A version with guaranteed reverse surge capability, BYV33-40A, is also available.

QUICK REFERENCE DATA

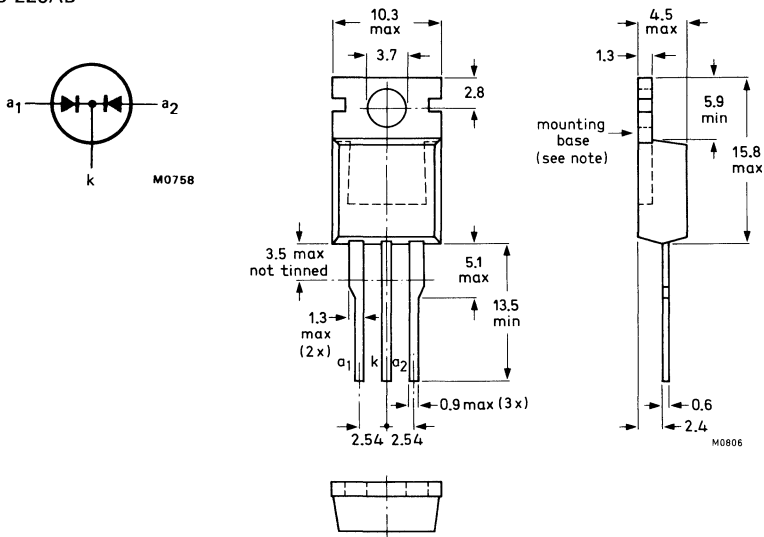
Per diode, unless otherwise stated

		BYV33-30				35				40(A)				45				
Repetitive peak reverse voltage	V_{RRM} max.	30				35				40				45				V
Average forward current (both diodes conducting)	$I_F(AV)$ max.									20								A
Forward voltage	V_F <									0.6								V
Junction temperature	T_j max.									150								°C

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AB



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)

		BYV33-30	35	40(A)	45
Repetitive peak reverse voltage	V_{RRM}	max. 30	35	40	45 V
Crest working reverse voltage (note 1)	V_{RWM}	max. 30	35	40	45 V
Continuous reverse voltage (note 1)	V_R	max. 30	35	40	45 V

→ Currents (both diodes conducting; note 2)

Output current:

square-wave; $\delta = 0.5$;

up to $T_{mb} = 122^\circ\text{C}$ (note 3)

I_O max. 20 A

sinusoidal;

up to $T_{mb} = 124^\circ\text{C}$ (note 3)

I_O max. 18 A

R.M.S. forward current

$I_F(\text{RMS})$ max. 28 A

Repetitive peak forward current

$t_p = 20 \mu\text{s}$, $\delta = 0.02$ (per diode)

I_{FRM} max. 200 A

Non-repetitive peak forward current (per diode)

half sine-wave; $T_j = 125^\circ\text{C}$ prior to

surge; with reapplied V_{RWMmax}

$t = 10 \text{ ms}$

I_{FSM} max. 200 A

$t = 8.3 \text{ ms}$

I_{FSM} max. 220 A

$I^2 t$ for fusing ($t = 10 \text{ ms}$; per diode)

$I^2 t$ max. 200 A^2s

Reverse surge current (BYV33-40A only)

$t_p = 100 \mu\text{s}$

I_{RSM} max. 0.5 A

Temperatures

Storage temperature

T_{stg} -40 to +150 $^\circ\text{C}$

Junction temperature

T_j max. 150 $^\circ\text{C}$

Notes:

1. Up to $T_j = 125^\circ\text{C}$; see derating curve for higher temperature operation.
2. The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
3. Assuming no reverse leakage current losses.

CHARACTERISTICS (per diode)

Forward voltage

$I_F = 7 \text{ A}; T_j = 100 \text{ }^\circ\text{C}$

$V_F < 0.6 \text{ V}^*$

$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 1.0 \text{ V}^*$

Reverse current

$V_R = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 40 \text{ mA} \leftarrow$

Junction capacitance at $f = 1 \text{ MHz}$

$V_R = 5 \text{ V}; T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$

$C_d \text{ typ. } 300 \text{ pF}$

THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)

$R_{th \text{ j-mb}} = 1.6 \text{ K/W}$

From junction to mounting base (per diode)

$R_{th \text{ j-mb}} = 2.6 \text{ K/W}$

Influence of mounting method

1. Heatsink mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$R_{th \text{ mb-h}} = 0.2 \text{ K/W}$

b. with heatsink compound and 0.06 mm maximum mica insulator

$R_{th \text{ mb-h}} = 1.4 \text{ K/W}$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$R_{th \text{ mb-h}} = 2.2 \text{ K/W}$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$R_{th \text{ mb-h}} = 0.8 \text{ K/W}$

e. without heatsink compound

$R_{th \text{ mb-h}} = 1.4 \text{ K/W}$

2. Free air operation

The quoted values of $R_{th \text{ j-a}}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air; mounted on a printed circuit board at any device lead length and with copper laminate on the board

$R_{th \text{ j-a}} = 60 \text{ K/W}$

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
 Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations.

The various components of junction temperature rise above ambient are illustrated in Fig.2.

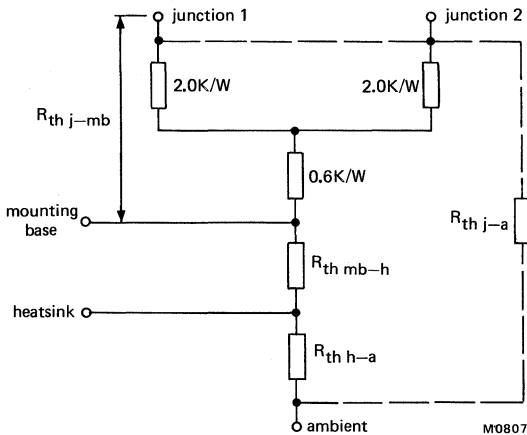


Fig.2.

OPERATING NOTES

Dissipation and heatsink calculations (continued)

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required for each half of the dual diode:

- (i) maximum operating ambient temperature
- (ii) duty cycle or form factor of forward current (δ or a)
- (iii) average forward current per diode
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R — reverse leakage dissipation

P_F — forward conduction dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_F + P_R} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows: Look at each half of the dual diode separately; for each diode, starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis. From this calculation, $P_R = P_R$ (diode 1) + P_R (diode 2) 3). Forward conduction dissipation (P_F) for the known average current $I_F(AV)$ and duty cycle (or form factor) for each diode is easily derived from Fig.4 (or Fig.6). Similarly, $P_F = P_F$ (diode 1) + P_F (diode 2) 4). Substituting equations 3) and 4) into equation 2) enables the calculation of the required heatsink.

NOTE:— If both halves of the diode are being used (as is assumed above), the value of $R_{th\ j-mb} = 1.6$ K/W. If only one half of the diode is used, follow the above procedure for one diode only, and use the value of $R_{th\ j-mb}$ of 2.6 K/W.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than 12 °C. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV33-35 and heatsink compound;

- $T_{amb} = 50$ °C; δ (diode 1) = 0.5; δ (diode 2) = 0.5;
- $I_F(AV)$ (diode 1) = 7 A; $I_F(AV)$ (diode 2) = 7 A;
- V_{RWM} (both diodes) = 12 V; voltage grade of device = 35 V.
- From data, $R_{th\ j-mb} = 1.6$ K/W and $R_{th\ mb-h} = 0.2$ K/W.
- For each diode from Fig.4, it is found that $P_F = 5.5$ W;
- hence total $P_F = 2 \times 5.5 = 11$ W. (from equation 4)
- If the desired $T_{j\ max}$ is chosen to be 130 °C, then, from Fig.3, P_R (per diode) = 0.17W
- Therefore total $P_R = 2 \times 0.17 = 0.34$ W. (from equation 3)
- Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\ ^\circ C - 50\ ^\circ C}{11\ W + 0.34\ W} - (1.6 + 0.2) = 5.3\ K/W$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (1.6 + 0.2 + 5.3) \times 0.34 = 2.4\ ^\circ C.$$

This is less than 12 °C, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs.3 and 4)

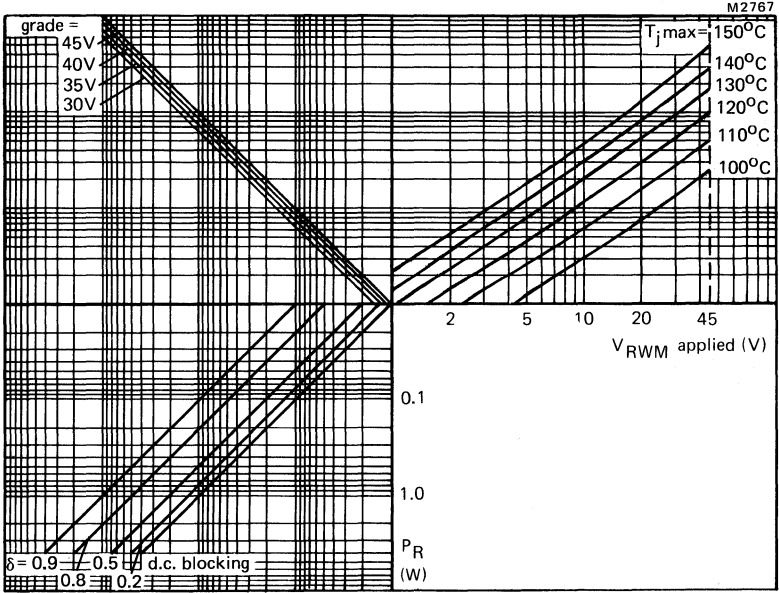


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_j \text{ max}$., V_{RWM} applied, voltage grade and duty cycle (per diode).

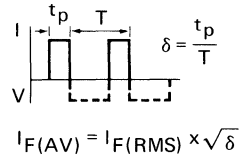
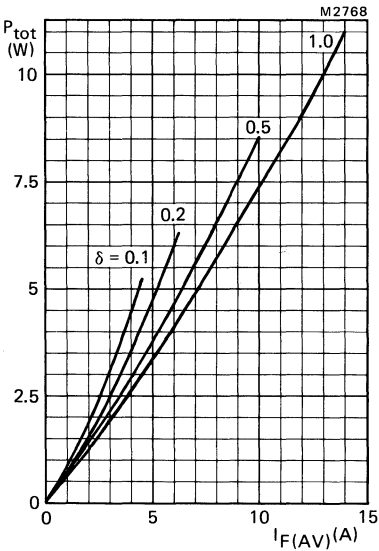


Fig.4.

SINE-WAVE OPERATION (Figs.5 and 6)

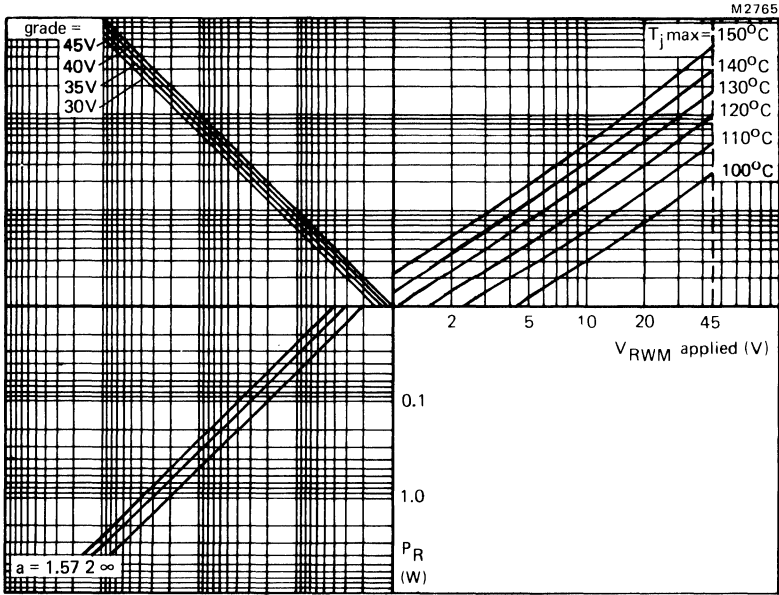


Fig.5 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_{j\max}$, V_{RWM} applied, voltage grade and form factor (per diode).

$a = \text{form factor} = I_{F(RMS)} / I_F(AV)$

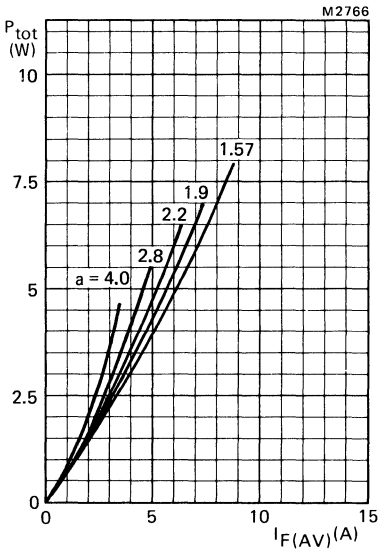


Fig.6.

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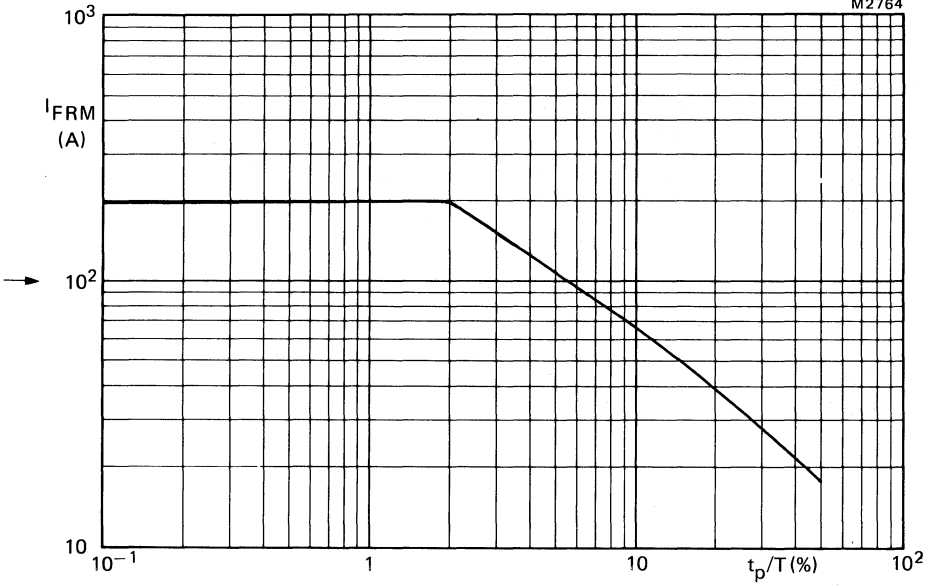
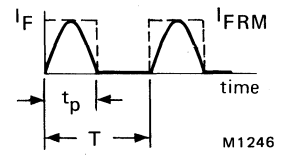
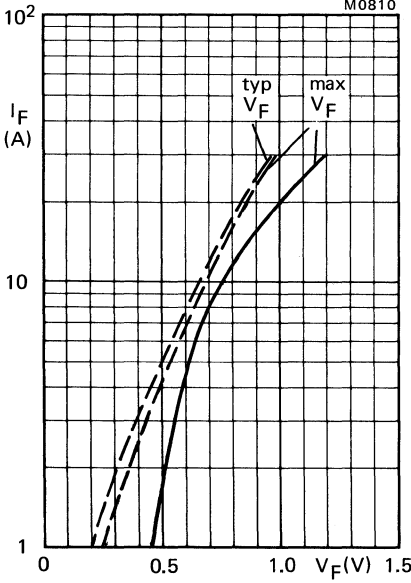


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 ms$.

M0810



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25^\circ C$; - - - $T_j = 100^\circ C$; per diode.

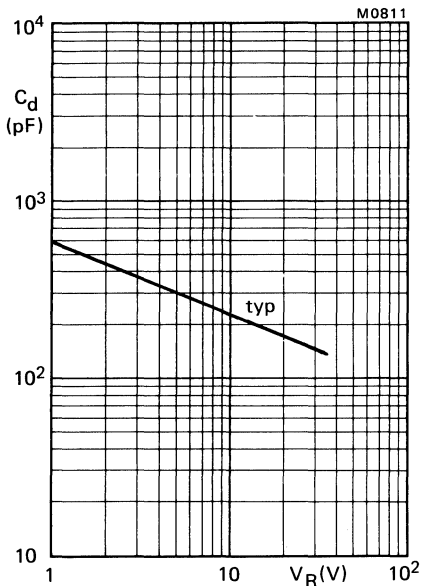


Fig.9 $f = 1 \text{ MHz}$; $T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$; per diode.

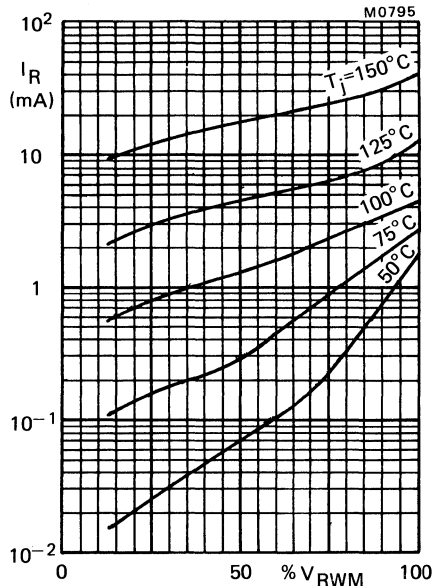


Fig.10 Typical values; per diode.

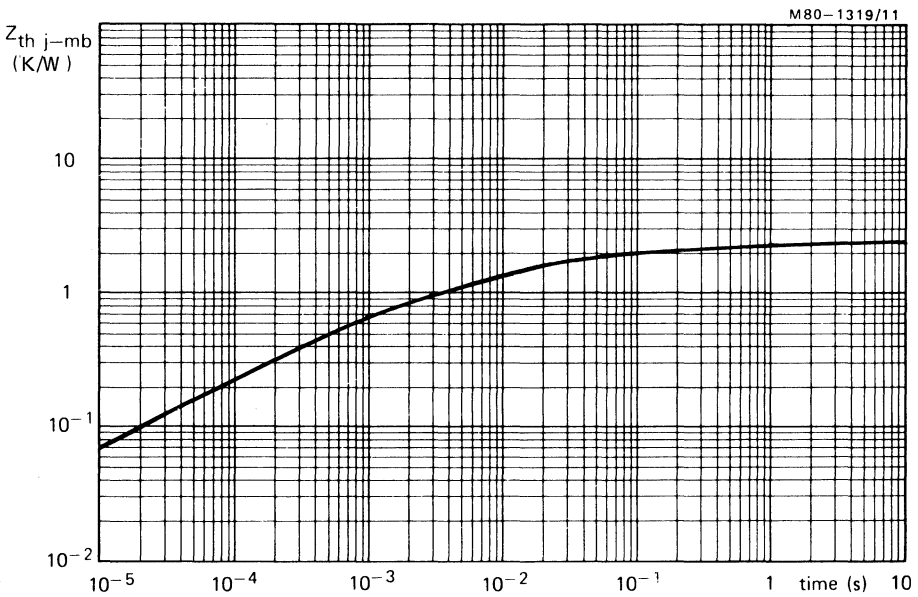


Fig.11 Transient thermal impedance; one diode conducting.

SCHOTTKY-BARRIER, ELECTRICALLY-ISOLATED DOUBLE RECTIFIER DIODES

High-efficiency schottky-barrier double rectifier diodes in SOT-186 (full-pack) plastic envelopes, featuring very low forward voltage drop, low capacitance and absence of stored charge. Their electrical isolation makes them ideal for mounting on a common heatsink alongside other components without the need for additional insulators. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where low conduction losses and absence of stored charge are essential. The single chip (monolithic) construction allows both diodes to be paralleled without the need for derating. The series consists of common-cathode types. A version with guaranteed reverse surge capability, BYV33F-40A is available.

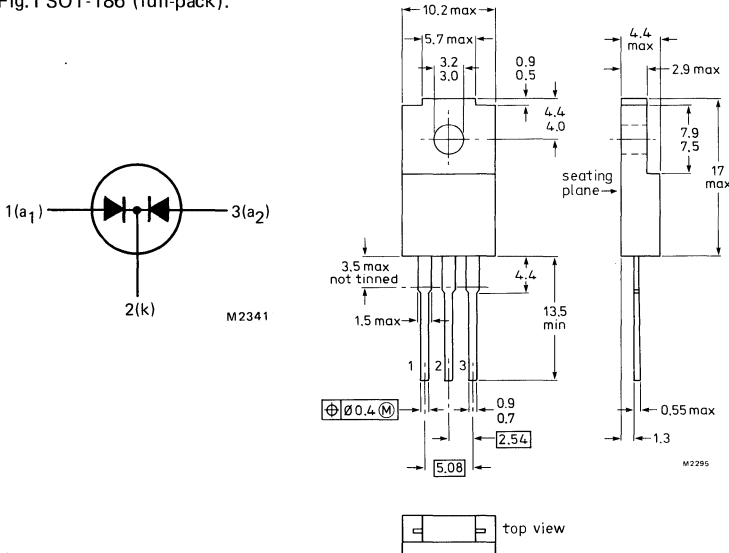
QUICK REFERENCE DATA

Per diode, unless otherwise stated		BYV33F-30	35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45 V
Output current (both diodes conducting)	I_O	max.	20			A
Forward voltage	V_F	<	0.6			V
Junction temperature	T_j	<	150			°C

MECHANICAL DATA

Dimensions in mm

Fig.1 SOT-186 (full-pack).



Net mass: 2 g.

The seating plane is electrically isolated from all terminals.

Accessories supplied on request (see data sheets Mounting instructions for F-pack devices and Accessories for SOT-186 envelopes).

BYV33F SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)		BYV33F-30				
			35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45 V
Crest working reverse voltage (note 1)	V_{RWM}	max.	30	35	40	45 V
Continuous reverse voltage (note 1)	V_R	max.	30	35	40	45 V

Currents (both diodes conducting; notes 2 and 4)

Output current:

square wave; $\delta = 0.5$; up to $T_h = 65^\circ\text{C}$ (note 3)	I_O	max.		20	A
sinusoidal; up to $T_h = 71^\circ\text{C}$ (note 3)	I_O	max.		18	A
R.M.S. forward current	$I_F(\text{RMS})$	max.		28	A
Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$ (per diode)	I_{FRM}	max.		200	A
Non-repetitive peak forward current (per diode) half sine-wave; $T_j = 150^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max	I_{FSM}	max.		150	A
$t = 10 \text{ ms}$	I_{FSM}	max.		165	A
$t = 8.3 \text{ ms}$	$I^2 t$	max.		112	A^2s
Reverse surge current (BYV33F-40A only) $t_p = 100 \mu\text{s}$	I_{RSM}	max.		0.5	A

Temperatures

Storage temperature	T_{stg}		-40 to +150	$^\circ\text{C}$
Junction temperature	T_j	max.	150	$^\circ\text{C}$

ISOLATION

Peak isolation voltage from all terminals to external heatsink	V_{isol}	max.	1000	V
Isolation capacitance from centre lead to external heatsink (note 5)	C_p	typ.	12	pF

Notes:

- Up to $T_j = 125^\circ\text{C}$; see derating curve for higher temperature operation.
- The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
- Assuming no reverse leakage current losses.
- The quoted temperatures assume heatsink compound is used.
- Mounted without heatsink compound and 20 Newtons pressure on the centre of the envelope.

CHARACTERISTICS (per diode) $T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated

Forward voltage

 $I_F = 7\text{ A}; T_j = 100\text{ }^\circ\text{C}$ $V_F < 0.6\text{ V}^*$ $I_F = 20\text{ A}$ $V_F < 1.0\text{ V}^*$

Reverse current

 $V_R = V_{RWM\text{ max}}; T_j = 125\text{ }^\circ\text{C}$ $I_R < 40\text{ mA}$ Junction capacitance at $f = 1\text{ MHz}$ $V_R = 5\text{ V}; T_j = 25\text{ }^\circ\text{C}$ to $125\text{ }^\circ\text{C}$ C_j typ. 300 pF**THERMAL RESISTANCE**

From junction to external heatsink with minimum of 2 kgf (20 Newtons) pressure on the centre of the envelope:

a. both diodes conducting:

with heatsink compound

 $R_{th\ j-h} = 5.0\text{ K/W}$

without heatsink compound

 $R_{th\ j-h} = 7.0\text{ K/W}$

b. per diode:

with heatsink compound

 $R_{th\ j-h} = 6.0\text{ K/W}$

without heatsink compound

 $R_{th\ j-h} = 8.0\text{ K/W}$ **Free air operation**

The quoted value of $R_{th\ j-h}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient

in free air, mounted on a printed circuit board

 $R_{th\ j-a} = 55\text{ K/W}$

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers a good thermal contact under the crystal area and slightly lower $R_{th\ j-h}$ values than screw mounting. The force exerted on the top of the device by the clip should be at least 2 kgf (20 Newtons) to ensure good thermal contact and must not exceed 3.5 kgf (35 Newtons) to avoid damage to the device.
4. If screw mounting is used, it should be M3 cross-recess pan head.

Minimum torque to ensure good thermal contact:	5.5 kgf (0.55 Nm)
Maximum torque to avoid damage to the device:	8.0 kgf (0.80 Nm)
5. For good thermal contact, heatsink compound should be used between baseplate and heatsink. Values of $R_{th\ j-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting. It is not recommended to use rivets, since extensive damage could result to the plastic, which could destroy the insulating properties of the device.
7. The heatsink must have a flatness in the mounting area of 0.02 mm maximum per 10 mm. Mounting holes must be deburred.

OPERATING NOTES

The various components of junction temperature rise above ambient are illustrated in Fig.2.

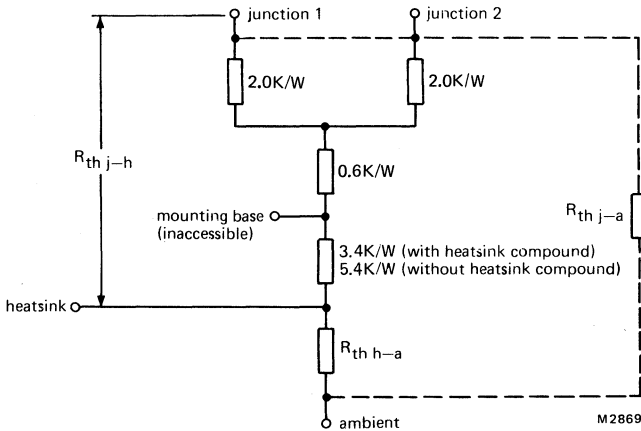


Fig.2.

Any measurement of heatsink temperature should be immediately adjacent to the device.

OPERATING NOTES

Dissipation and heatsink calculations (continued)

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required for each half of the dual diode:

- (i) maximum operating ambient temperature
- (ii) duty cycle or form factor of forward current (δ or a)
- (iii) average forward current per diode
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R – reverse leakage dissipation

P_F – forward conduction dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_F + P_R} - (R_{th\ j-h}) \dots\dots\dots 2).$$

The value of $R_{th\ j-h}$ can be found under Thermal Resistance and will depend upon whether or not heatsink compound is used. P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows:

Look at each half of the dual diode separately; for each diode, starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis. From this calculation, $P_R = P_R$ (diode 1) + P_R (diode 2) 3).

Forward conduction dissipation (P_F) for the known average current $I_F(AV)$ and duty cycle (or form factor) for each diode is easily derived from Fig.4 (or Fig.6).

Similarly, $P_F = P_F$ (diode 1) + P_F (diode 2) 4).

Substituting equations 3) and 4) into equation 2) enables the calculation of the required heatsink.

NOTE:— If both halves of the diode are being used (as is assumed above), the value of $R_{th\ j-h} = 5\text{ K/W}$ (with heatsink compound) or 7 K/W (without heatsink compound).

If only one half of the diode is used, follow the above procedure for one diode only, and use the value of $R_{th\ j-h}$ of 6 K/W (with heatsink compound) or 8 K/W (without heatsink compound).

To ensure thermal stability, $(R_{th\ j-h} + R_{th\ h-a}) \times P_R$ must be less than $12\text{ }^\circ\text{C}$. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ j-a}$ improved) to enable this criterion to be met.

EXAMPLE: square wave operation, using BYV33F–35 and heatsink compound;

$T_{amb} = 40\text{ }^\circ\text{C}$; δ (diode 1) = 0.5; δ (diode 2) = 0.5;

$I_F(AV)$ (diode 1) = 7 A; $I_F(AV)$ (diode 2) = 7 A;

V_{RWM} (both diodes) = 12 V; voltage grade of device = 35 V.

From data, $R_{th\ j-h} = 5\text{ K/W}$.

For each diode from Fig.4, it is found that $P_F = 5.5\text{ W}$;

hence total $P_F = 2 \times 5.5 = 11\text{ W}$. (from equation 4)

If the desired T_{jmax} is chosen to be $130\text{ }^\circ\text{C}$, then, from Fig.3, P_R (per diode) = 0.17 W.

Therefore total $P_R = 2 \times 0.17 = 0.34\text{ W}$. (from equation 3)

Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\text{ }^\circ\text{C} - 40\text{ }^\circ\text{C}}{11\text{ W} + 0.34\text{ W}} - (5.0) = 2.9\text{ K/W}$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (5.0 + 2.9) \times 0.34 = 2.69\text{ }^\circ\text{C}.$$

This is less than $12\text{ }^\circ\text{C}$, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs.3 and 4)

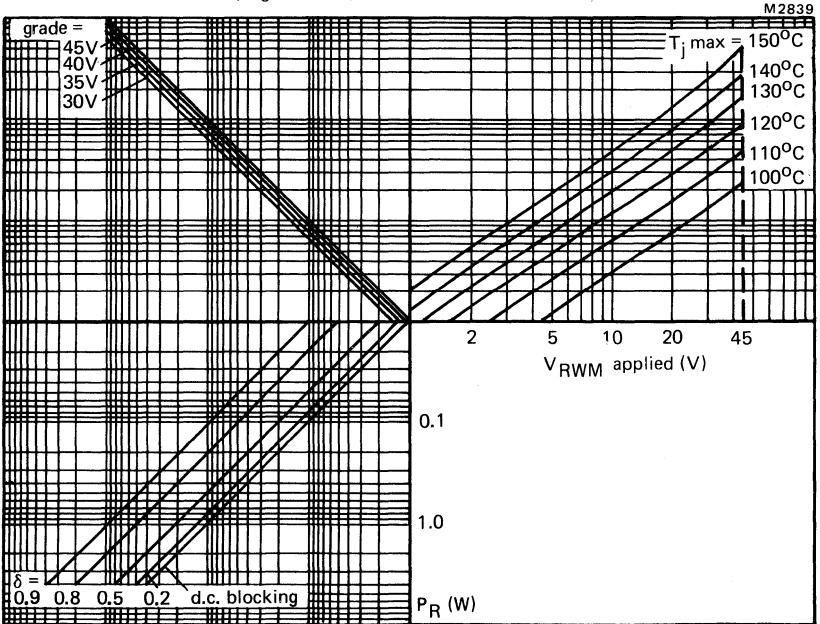


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given T_{jmax} ., V_{RWM} applied, voltage grade and duty cycle (per diode).

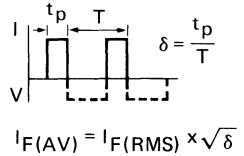
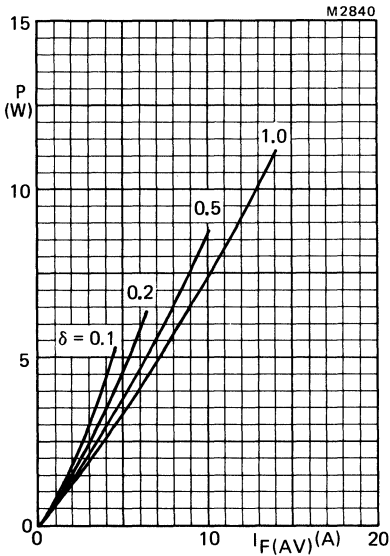


Fig.4.

SINE-WAVE OPERATION (Figs.5 and 6)

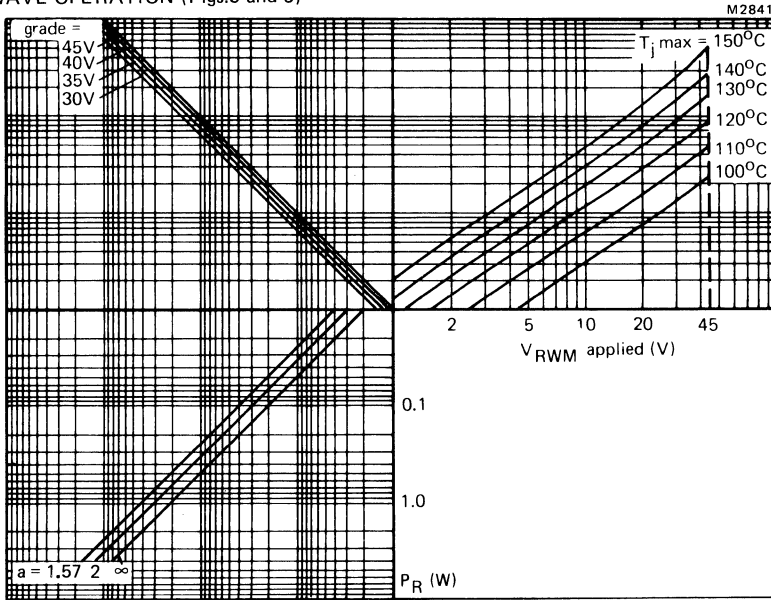


Fig.5 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_{j\text{max}}$, V_{RWM} applied, voltage grade and form factor (per diode).

$a = \text{form factor} = I_{F(\text{RMS})}/I_{F(\text{AV})}$.

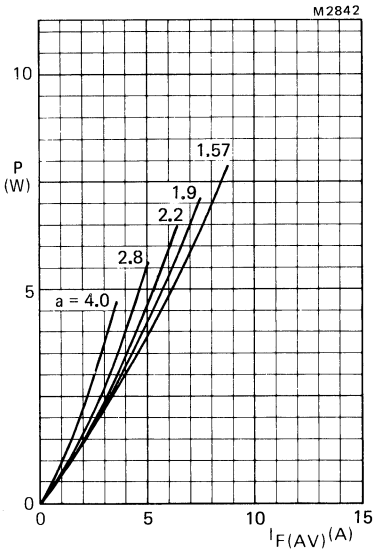


Fig.6.

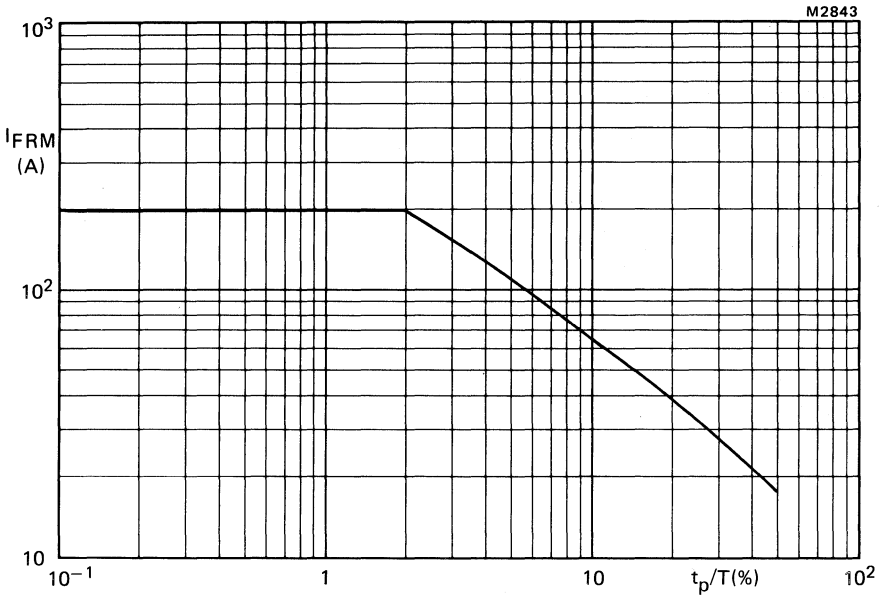
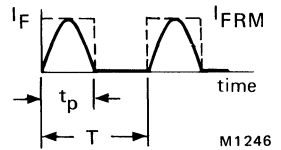
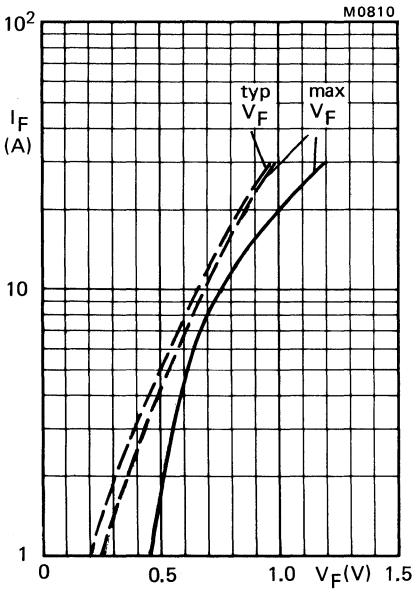


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 \text{ ms}$, per diode.



Definition of I_{FRM} and t_p/T .

Fig.8 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 100 \text{ }^\circ\text{C}$; per diode.

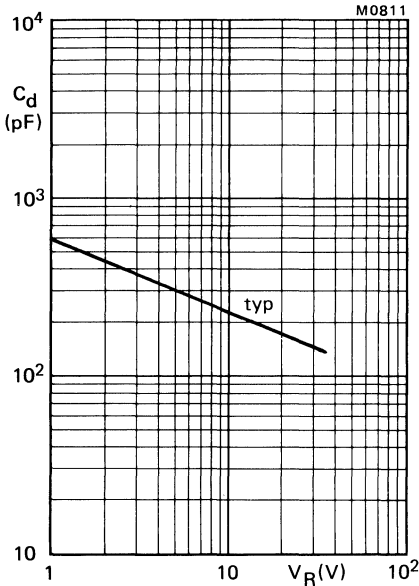


Fig.9 $f = 1 \text{ MHz}$; $T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$; per diode.

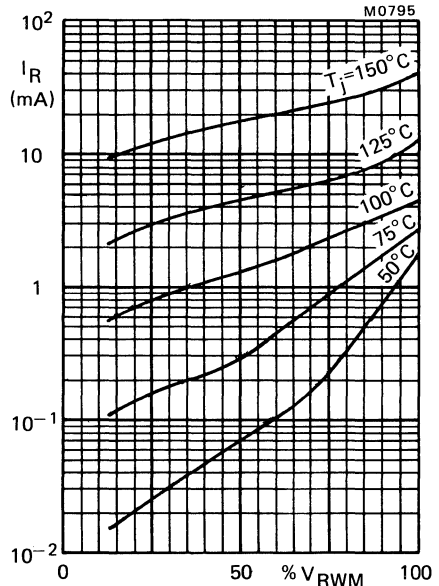


Fig.10 Typical values; per diode.

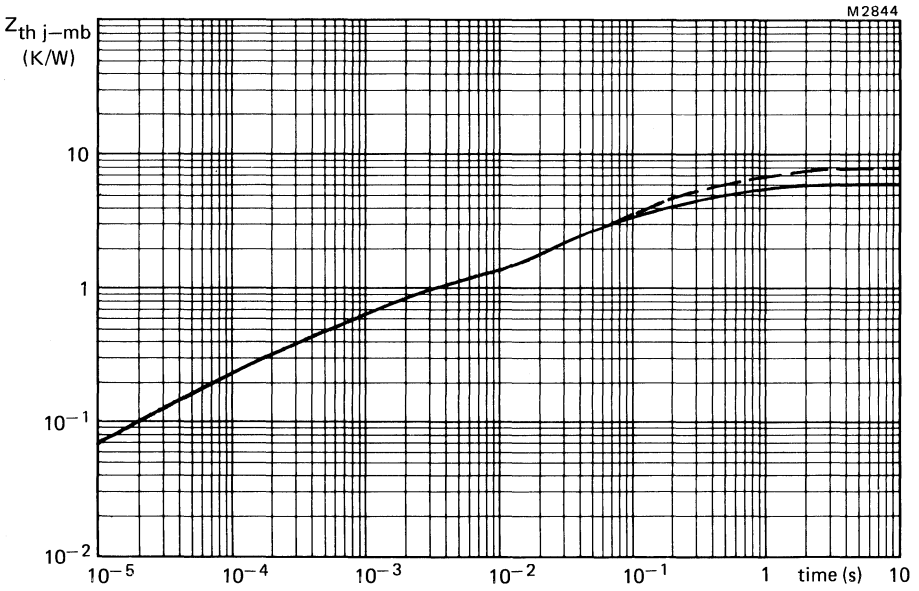


Fig.11 Transient thermal impedance; one diode conducting; — with heatsink compound; - - - without heatsink compound.

SCHOTTKY-BARRIER RECTIFIER DIODES

High-efficiency schottky-barrier rectifier diodes in TO-220 plastic envelopes, featuring low forward voltage drop, low capacitance, absence of stored charge, and high temperature stability. They are intended for use in low output voltage switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and switching losses are important. They can also withstand reverse voltage transients. The series consists of normal polarity (cathode to mounting-base) types. A version with guaranteed reverse surge capability, BYV39-40A; is also available.

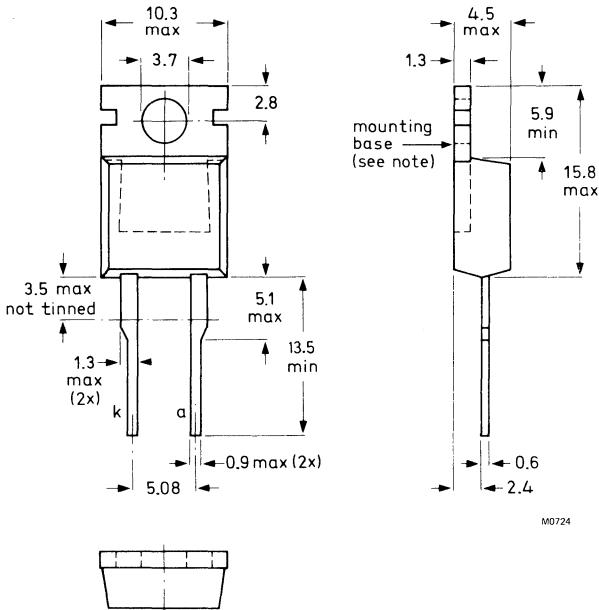
QUICK REFERENCE DATA

		BYV39-30				35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45		V	
Average forward current	$I_{F(AV)}$	max.			16			A	
Forward voltage	V_F	<			0.6			V	
Junction temperature	T_j	max.			150			°C	

MECHANICAL DATA

Fig.1 TO-220AC

Dimensions in mm



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to the cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

BYV39 SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

		BYV39—						
		30	35	40(A)	45			
→	Voltages							
	Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45	V
	Crest working reverse voltage (note 1)	V_{RWM}	max.	30	35	40	45	V
	Continuous reverse voltage (note 1)	V_R	max.	30	35	40	45	V
→	Currents							
	Average forward current square wave; $\delta = 0.5$; up to $T_{mb} = 119^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.			16		A
	sinusoidal; up to $T_{mb} = 124^\circ\text{C}$ (note 2)	$I_{F(AV)}$	max.			12.5		A
	R.M.S. forward current	$I_{F(RMS)}$	max.			22		A
	Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$	I_{FRM}	max.			260		A
	Non-repetitive peak forward current half sine-wave; $T_j = 125^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max							
	$t = 10 \text{ ms}$	I_{FSM}	max.			150		A
	$t = 8.3 \text{ ms}$	I_{FSM}	max.			165		A
	$I^2 t$ for fusing ($t = 10 \text{ ms}$)	$I^2 t$	max.			112		A^2s
	Reverse surge current (BYV39–40A only) $t_p = 100 \mu\text{s}$	I_{RSM}	max.			1.0		A
	Temperatures							
	Storage temperature	T_{stg}				–40 to +150		$^\circ\text{C}$
	Junction temperature	T_j	max.			150		$^\circ\text{C}$
	CHARACTERISTICS							
	Forward voltage							
	$I_F = 15 \text{ A}$; $T_j = 100^\circ\text{C}$ (note 3)	V_F	<			0.6		V
	$I_F = 40 \text{ A}$; $T_j = 25^\circ\text{C}$ (note 3)	V_F	<			1.0		V
	Reverse current							
→	$V_R = V_{RWM}$ max; $T_j = 125^\circ\text{C}$	I_R	<			55		mA
	Junction capacitance at $f = 1 \text{ MHz}$ $V_R = 5 \text{ V}$; $T_j = 25$ to 125°C	C_d	typ.			520		pF

Notes:

1. Up to $T_j = 125^\circ\text{C}$; see derating curve for higher temperature operation.
2. Assuming no reverse leakage current losses.
3. Measured under pulse conditions to avoid excessive dissipation.

THERMAL RESISTANCE

From junction to mounting base

$$R_{th\ j-mb} = 2.2 \text{ K/W}$$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$$R_{th\ mb-h} = 0.5 \text{ K/W}$$

b. with heatsink compound and 0.06 mm maximum mica insulator

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$$R_{th\ mb-h} = 2.2 \text{ K/W}$$

d. with heatsink compound and 0.25 mm maximum alumina insulator (56367)

$$R_{th\ mb-h} = 0.8 \text{ K/W}$$

e. without heatsink compound

$$R_{th\ mb-h} = 1.4 \text{ K/W}$$

2. Free air operation

The quoted values of $R_{th\ j-a}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air; mounted on a printed circuit board at any device lead length and with copper laminate on the board

$$R_{th\ j-a} = 60 \text{ K/W}$$

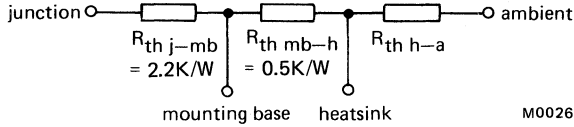
MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

→ OPERATING NOTES

Dissipation and Heatsink Calculations

The various components of junction temperature rise above ambient are shown below:



m0026 Fig.2

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required:

- (i) maximum operating ambient temperature
- (ii) duty cycle or form factor of forward current (δ or a)
- (iii) average forward current
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R – reverse leakage dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

P_F – forward conduction dissipation

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_R + P_F} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 for square-wave operation (and Figs.5 and 6 for sine-wave) as follows: Starting at the V_{RWM} axis of Fig.3 (or Fig.5), and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ) or form factor (a). From this point trace right and read the actual reverse power dissipation on the P_R axis.

Forward conduction dissipation (P_F) for the known average current $I_{F(AV)}$ and duty cycle (or form factor) is easily derived from Fig.4 (or Fig.6).

Substituting the values of P_R and P_F into equation 2) enables the calculation of the required heatsink.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than 12 °C. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV39-35 and heatsink compound;
 $T_{amb} = 50\text{ °C}$; $\delta = 0.5$; $I_{F(AV)} = 12\text{ A}$
 $V_{RWM} = 12\text{ V}$; voltage grade of device = 35 V
 From data, $R_{th\ j-mb} = 2.2\text{ K/W}$ and $R_{th\ mb-h} = 0.5\text{ K/W}$.
 From Fig.4, it is found that $P_F = 9.2\text{ W}$
 If the desired T_{jmax} is chosen to be 130 °C, then from Fig.3, $P_R = 0.23\text{ W}$
 Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\text{ °C} - 50\text{ °C}}{9.2\text{ W} + 0.23\text{ W}} - (2.2 + 0.5) = 5.8\text{ K/W}$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (2.2 + 0.5 + 5.8) \times 0.23 = 2\text{ °C}.$$

This is less than 12 °C, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs 3 and 4)

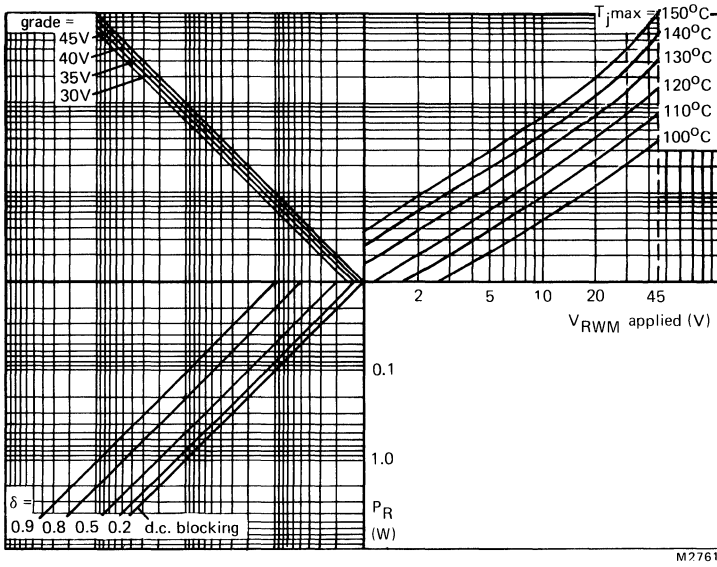
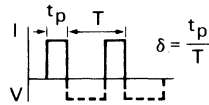
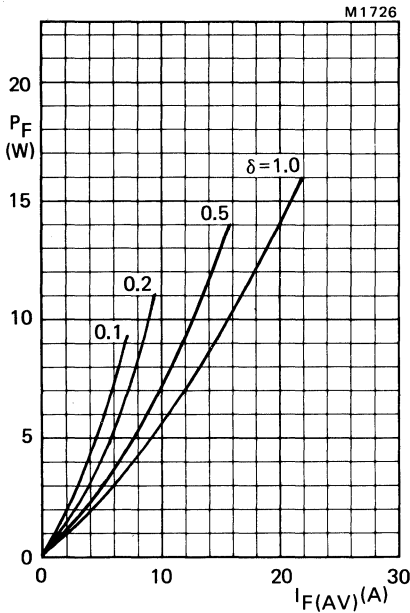


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given $T_{j,max}$., V_{RWM} applied, voltage grade and duty cycle.



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

Fig.4

SINUSOIDAL OPERATION (Figs.5 and 6)

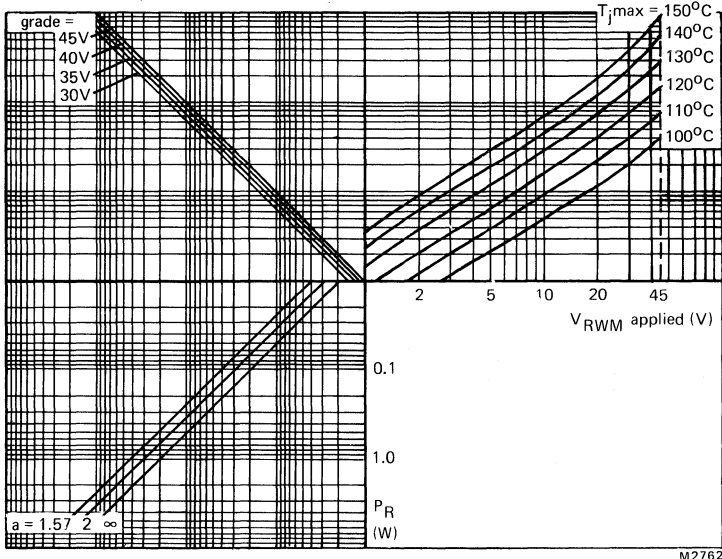


Fig.5 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given T_{jmax} ., V_{RWM} applied, voltage grade and form factor.

a = form factor = $I_F(RMS)/I_F(AV)$

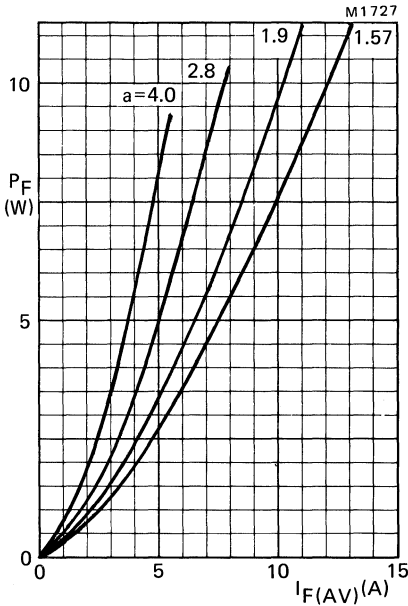


Fig.6

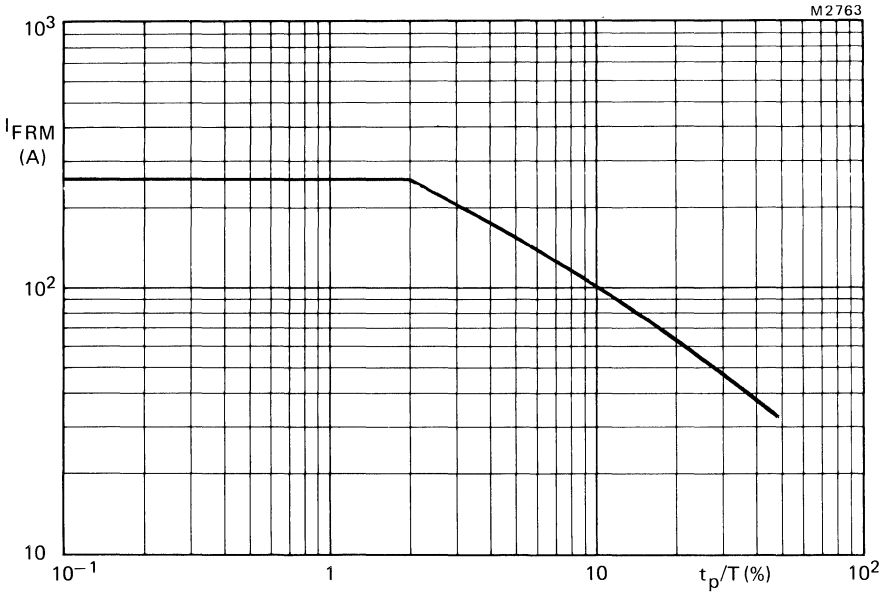


Fig.7 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 \text{ ms}$.

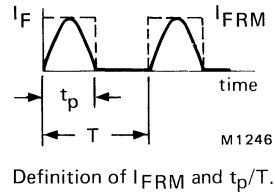
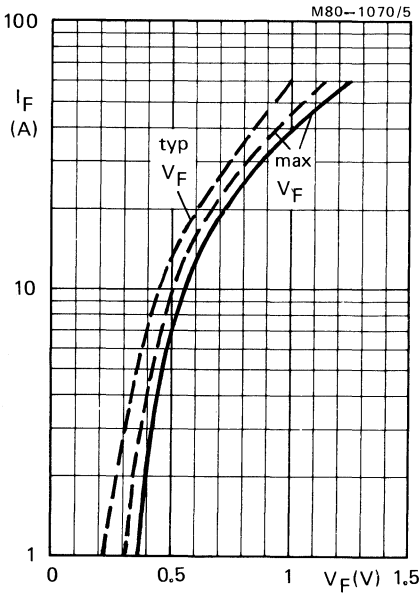


Fig.8 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 100 \text{ }^\circ\text{C}$

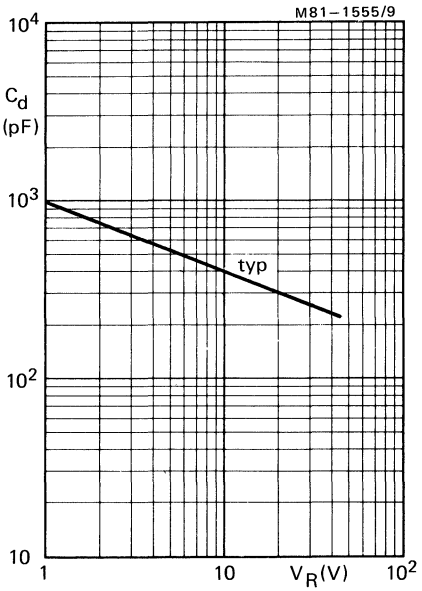


Fig.9 $f = 1$ MHz; $T_j = 25$ to 125 °C

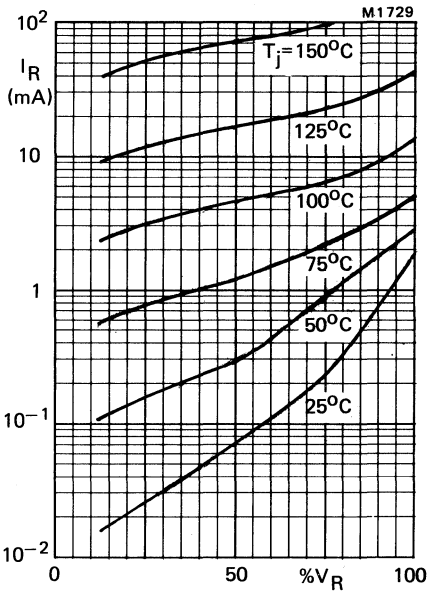


Fig.10 Typical values

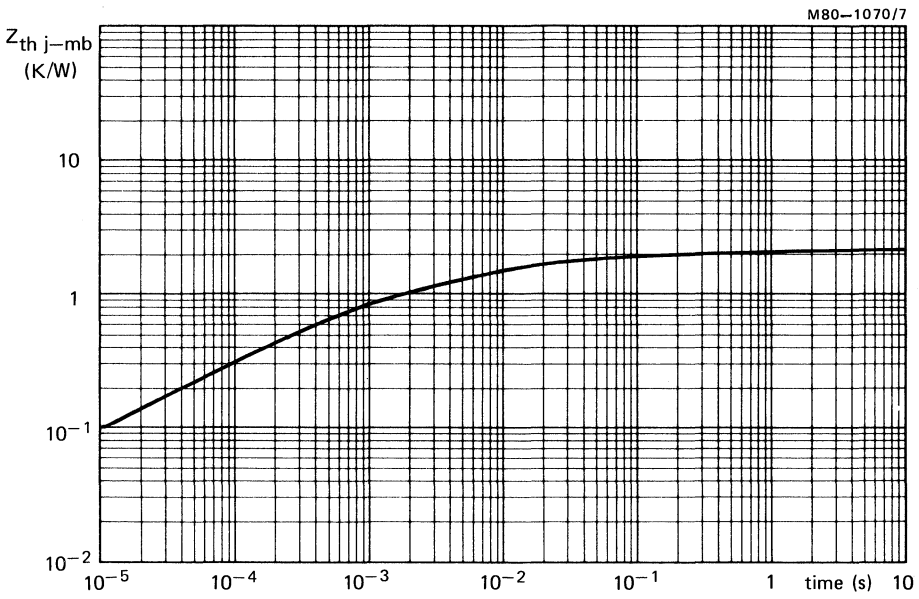


Fig.11 Transient thermal impedance

SCHOTTKY—BARRIER DOUBLE RECTIFIER DIODES

High-efficiency schottky-barrier double rectifier diodes in plastic envelopes, featuring low forward voltage drop, low capacitance and absence of stored charge. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and zero switching losses are essential. Their single chip (monolithic) construction allows both diodes to be paralleled without the need for derating. They can also withstand reverse voltage transients. The series consists of common-cathode types. A version with guaranteed reverse surge capability, BYV43-40A, is also available.

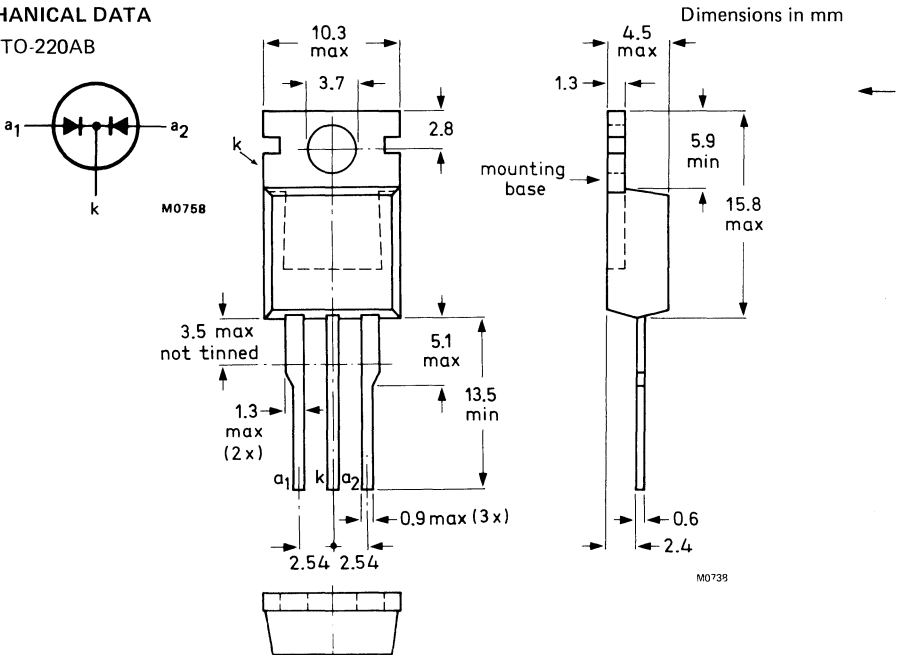
QUICK REFERENCE DATA

Per diode, unless otherwise stated

			BYV43-30	35	40(A)	45
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45
Output current (both diodes conducting)	I_O	max.				30
Forward voltage	V_F	<				0.6
Junction temperature	T_j	<				150
						V
						A
						V
						°C

MECHANICAL DATA

Fig.1 TO-220AB



Net mass: 2g

Note: the exposed metal mounting base is directly connected to the common cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

→ Voltages (per diode)		BYV43— 30	35	40(A)	45	V
Repetitive peak reverse voltage	V_{RRM}	max. 30	35	40	45	V
Crest working reverse voltage (note 1)	V_{RWM}	max. 30	35	40	45	V
Continuous reverse voltage (note 1)	V_R	max. 30	35	40	45	V
→ Currents (both diodes conducting: note 2)						
Output current: square wave; $\delta = 0.5$; up to $T_{mb} = 112^\circ\text{C}$ (note 3)						
R.M.S. forward current	I_O	max.		30		A
Repetitive peak forward current $t_p = 20\ \mu\text{s}$, $\delta = 0.02$ (per diode)	I_{FRM}	max.		250		A
Non-repetitive peak forward current (per diode) half sine-wave; $T_j = 125^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max						
$t = 10\ \text{ms}$	I_{FSM}	max.		200		A
$t = 8.3\ \text{ms}$	I_{FSM}	max.		220		A
$I^2 t$ for fusing ($t = 10\ \text{ms}$, per diode)	$I^2 t$	max.		200		$\text{A}^2\ \text{s}$
Reverse surge current (BYV43—40A only) $t_p = 100\ \mu\text{s}$						
	I_{RSM}	max.		0.5		A
Temperatures						
Storage temperature	T_{stg}			-40 to +150		$^\circ\text{C}$
Junction temperature	T_j	max.		150		$^\circ\text{C}$

Notes:

- Up to $T_j = 125^\circ\text{C}$; see derating curve for higher temperature operation.
- The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
- Assuming no reverse leakage current losses.

CHARACTERISTICS (per diode)

Forward voltage

$I_F = 15 \text{ A}; T_j = 125 \text{ }^\circ\text{C}$

$V_F < 0.6 \text{ V}^*$

$I_F = 30 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 0.87 \text{ V}^*$

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 100 \text{ mA} \leftarrow$

Junction capacitance at $f = 1 \text{ MHz}$

$V_R = 5 \text{ V}; T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$

$C_d \text{ typ. } 500 \text{ pF}$

THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)

$R_{th \text{ j-mb}} = 1.4 \text{ K/W}$

From junction to mounting base (per diode)

$R_{th \text{ j-mb}} = 2.3 \text{ K/W}$

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$R_{th \text{ mb-h}} = 0.2 \text{ K/W}$

b. with heatsink compound and 0.06mm maximum mica insulator

$R_{th \text{ mb-h}} = 1.4 \text{ K/W}$

c. with heatsink compound and 0.1 mm maximum mica insulator (56369)

$R_{th \text{ mb-h}} = 2.2 \text{ K/W}$

d. with heatsink compound and 0.25mm maximum alumina insulator (56367)

$R_{th \text{ mb-h}} = 0.8 \text{ K/W}$

e. without heatsink compound

$R_{th \text{ mb-h}} = 1.4 \text{ K/W}$

2. Free air operation

The quoted values of $R_{th \text{ j-a}}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air; mounted on a printed circuit board at any device lead length and with copper laminate on the board

$R_{th \text{ j-a}} = 60 \text{ K/W}$

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
 Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations.

The various components of junction temperature rise above ambient are illustrated in Fig.2.

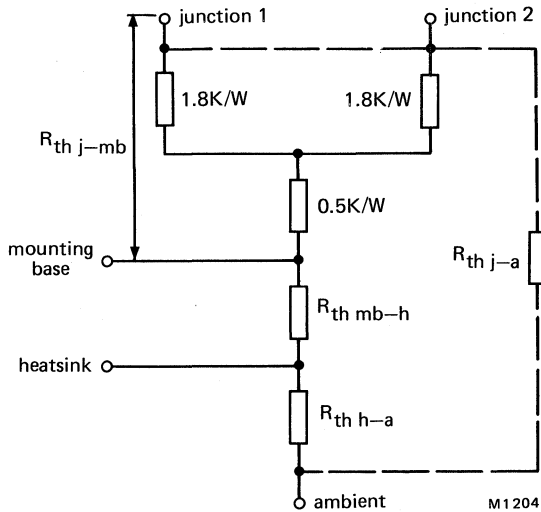


Fig.2.

OPERATING NOTES

Dissipation and heatsink calculations (continued)

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required for each half of the dual diode:

- (i) maximum operating ambient temperature
- (ii) duty cycle of forward current (δ)
- (iii) average forward current per diode
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R — reverse leakage dissipation

P_F — forward conduction dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_F + P_R} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 as follows:

Look at each half of the dual diode separately; for each diode, starting at the V_{RWM} axis of Fig.3, and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ). From this point trace right and read the actual reverse power dissipation on the P_R axis.

From this calculation, $P_R = P_R$ (diode 1) + P_R (diode 2) 3).

Forward conduction dissipation (P_F) for the known average current $I_{F(AV)}$ and duty cycle for each diode is easily derived from Fig.4.

Similarly, $P_F = P_F$ (diode 1) + P_F (diode 2) 4).

Substituting equations 3) and 4) into equation 2) enables the calculation of the required heatsink.

NOTE:— If both halves of the diode are being used (as is assumed above), the value of $R_{th\ j-mb} = 1.4\ K/W$. If only one half of the diode is used, follow the above procedure for one diode only, and use the value of $R_{th\ j-mb}$ of $2.3\ K/W$.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than $12\ ^\circ C$. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV43-35 and heatsink compound;

$T_{amb} = 50\ ^\circ C$; δ (diode 1) = 0.5; δ (diode 2) = 0.5;

$I_{F(AV)}$ (diode 1) = 12 A; $I_{F(AV)}$ (diode 2) = 12 A;

V_{RWM} (both diodes) = 12 V; voltage grade of device = 35 V.

From data, $R_{th\ j-mb} = 1.4\ K/W$ and $R_{th\ mb-h} = 0.2\ K/W$.

For each diode from Fig.4, it is found that $P_F = 9.3\ W$;

hence total $P_F = 2 \times 9.3 = 18.6\ W$. (from equation 4)

If the desired T_{jmax} is chosen to be $130\ ^\circ C$, then, from Fig.3, P_R (per diode) = $0.44\ W$

Therefore total $P_R = 2 \times 0.44 = 0.88\ W$. (from equation 3)

Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\ ^\circ C - 50\ ^\circ C}{18.6\ W + 0.88\ W} - (1.4 + 0.2) = 2.5\ K/W$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (1.4 + 0.2 + 2.5) \times 0.88 = 3.6\ ^\circ C.$$

This is less than $12\ ^\circ C$, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Fig.s 3 and 4)

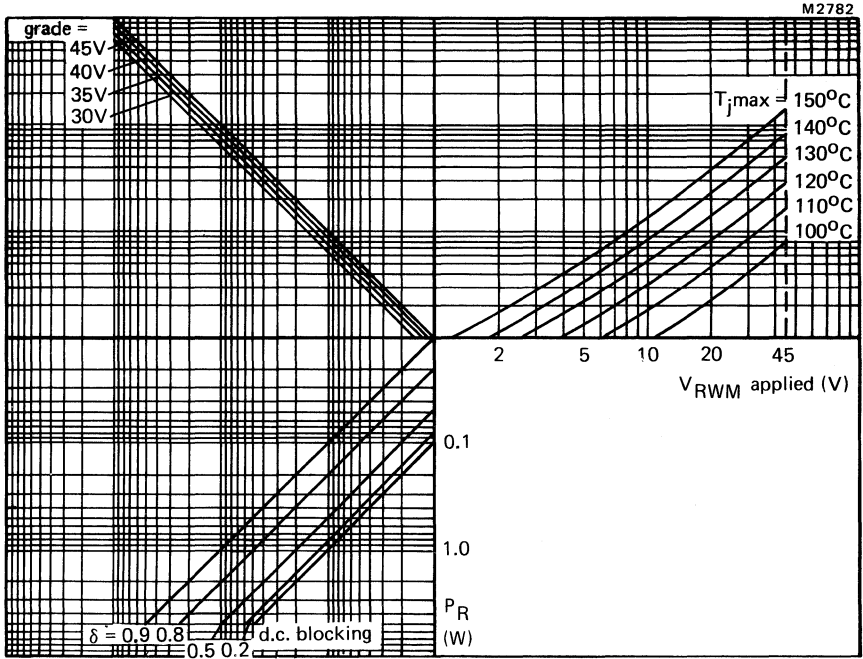


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given T_{jmax} , V_{RWM} applied, voltage grade and duty cycle (per diode).

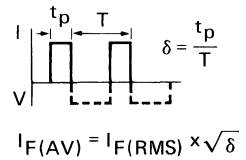
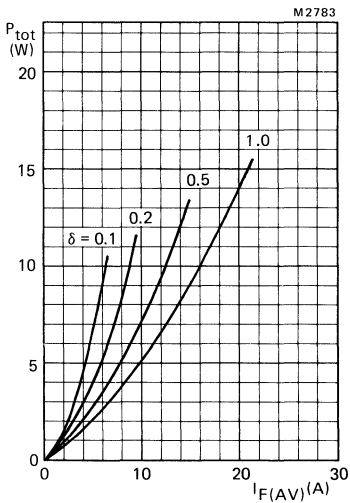


Fig.4.

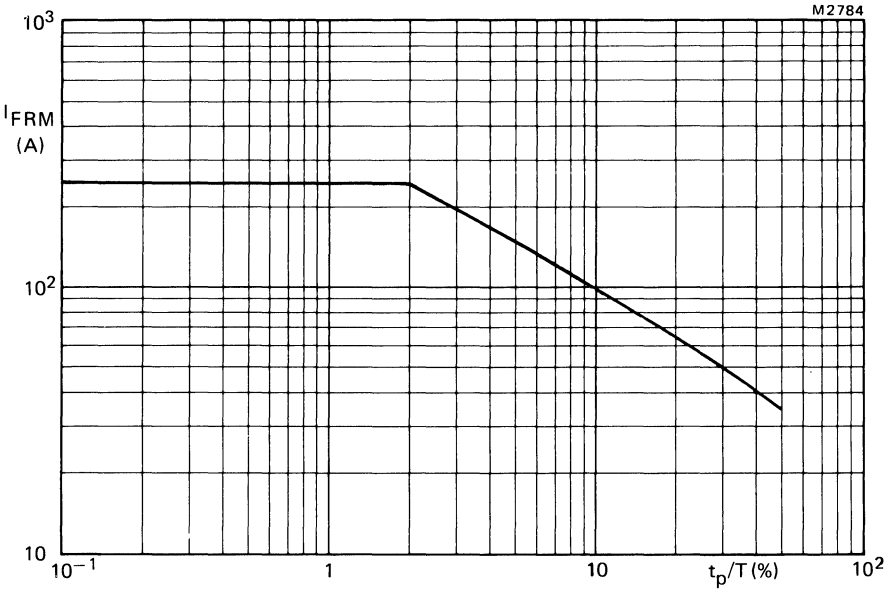
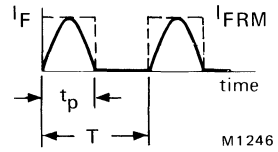
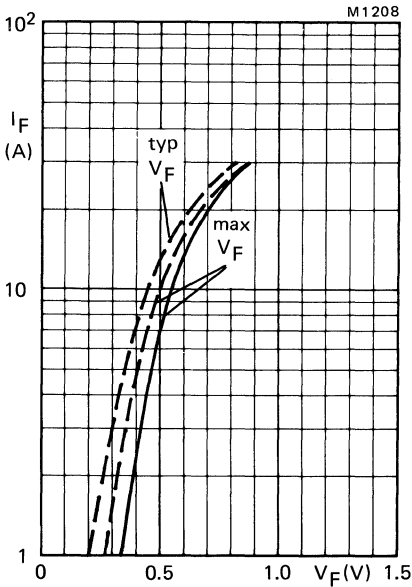


Fig.5 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 ms$.



Definition of I_{FRM} and t_p/T .

Fig.6 — $T_j = 25^\circ C$; --- $T_j = 125^\circ C$; per diode.

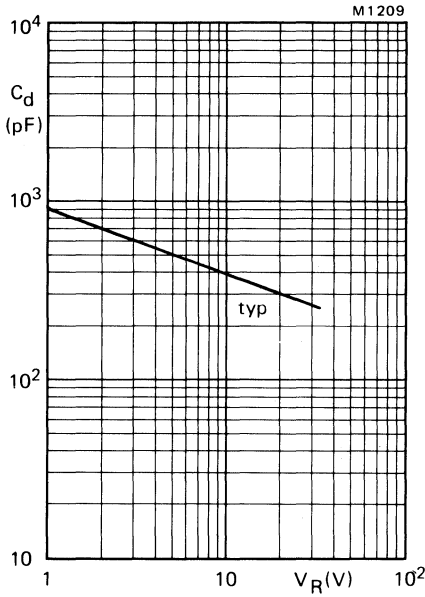


Fig.7 $f = 1$ MHz; $T_j = 25$ to 125 °C; per diode.

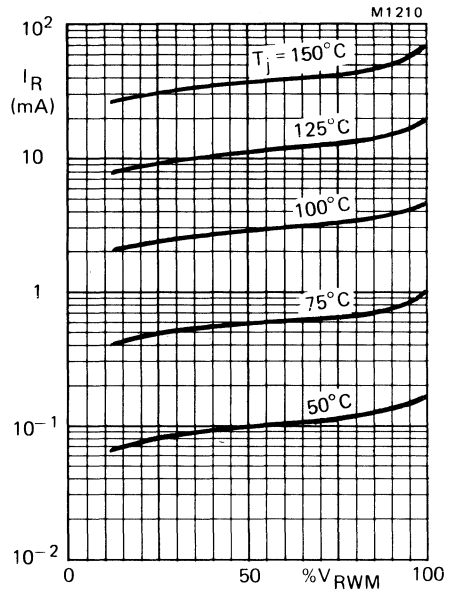


Fig.8 Typical values; per diode.

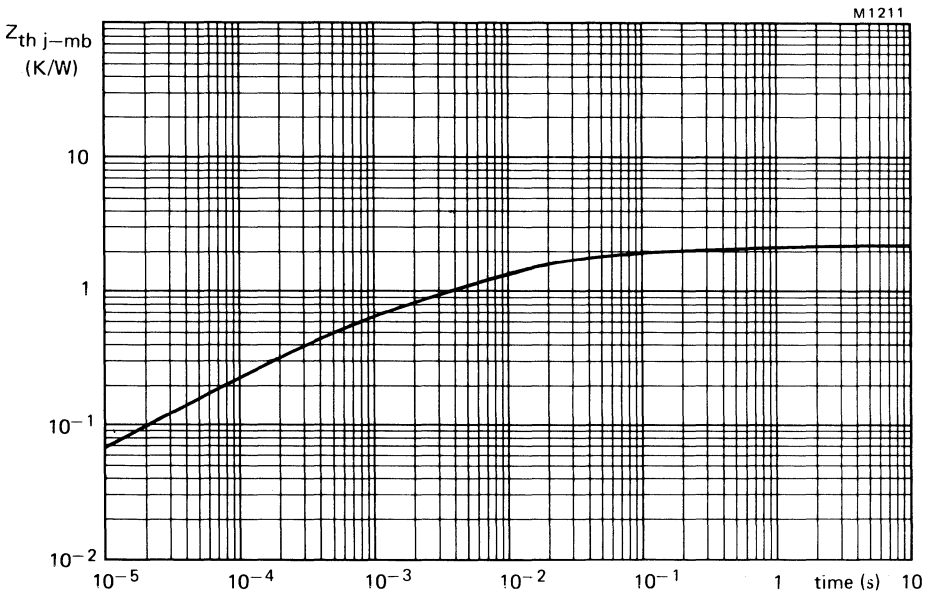


Fig.9 Transient thermal impedance; one diode conducting.

SCHOTTKY-BARRIER, ELECTRICALLY-ISOLATED DOUBLE RECTIFIER DIODES

High-efficiency schottky-barrier double rectifier diodes in SOT-186 (full-pack) plastic envelopes, featuring very low forward voltage drop, low capacitance and absence of stored charge. Their electrical isolation makes them ideal for mounting on a common heatsink alongside other components without the need for additional insulators. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where low conduction losses and absence of stored charge are essential. The single chip (monolithic) construction allows both diodes to be paralleled without the need for derating. The series consists of common-cathode types. A version with guaranteed reverse surge capability, BYV43F-40A is available.

QUICK REFERENCE DATA

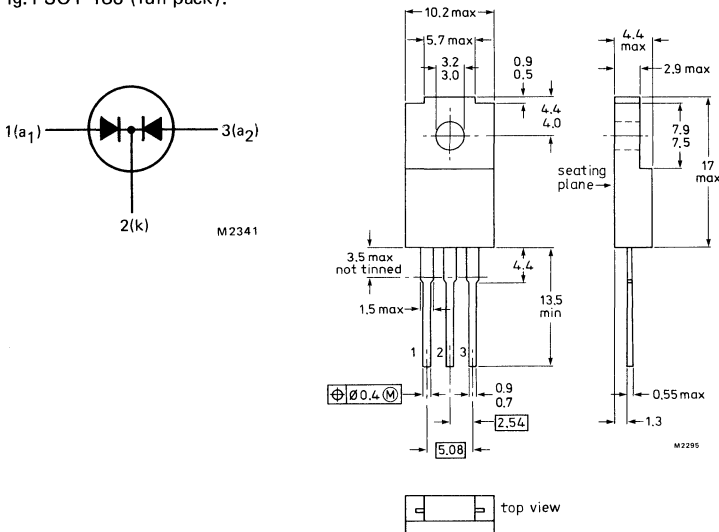
Per diode, unless otherwise stated

		BYV43F-30	35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max. 30	35	40	45	V
Output current (both diodes conducting)	I_O	max.		26		A
Forward voltage	V_F	<		0.6		V
Junction temperature	T_j	<		150		°C

MECHANICAL DATA

Dimensions in mm

Fig.1 SOT-186 (full-pack).



Net mass: 2 g.

The seating plane is electrically isolated from all terminals.

Accessories supplied on request (see data sheets Mounting instructions for F-pack devices and Accessories for SOT-186 envelopes).

BYV43F SERIES

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Voltages (per diode)

		BYV43F-30	35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max.	30	35	40	45 V
Crest working reverse voltage (note 1)	V_{RWM}	max.	30	35	40	45 V
Continuous reverse voltage (note 1)	V_R	max.	30	35	40	45 V

Currents (both diodes conducting; notes 2, 4)

Output current:

square wave; $\delta = 0.5$; up to

$T_h = 49^\circ\text{C}$ (note 3)

I_O max. 26 A

R.M.S. forward current

$I_F(\text{RMS})$ max. 37 A

Repetitive peak forward current

$t_p = 20 \mu\text{s}$; $\delta = 0.02$ (per diode)

I_{FRM} max. 250 A

Non-repetitive peak forward current (per diode)

half sine-wave; $T_j = 150^\circ\text{C}$ prior to

surge; with reapplied V_{RWM} max

$t = 10 \text{ ms}$

I_{FSM} max. 200 A

$t = 8.3 \text{ ms}$

I_{FSM} max. 220 A

$I^2 t$ for fusing ($t = 10 \text{ ms}$, per diode)

$I^2 t$ max. 200 A^2s

Reverse surge current (BYV43F-40A only)

$t_p = 100 \mu\text{s}$

I_{RSM} max. 0.5 A

Temperatures

Storage temperature

T_{stg} -40 to +150 $^\circ\text{C}$

Junction temperature

T_j max. 150 $^\circ\text{C}$

ISOLATION

Peak isolation voltage from all terminals to external heatsink

V_{isol} max. 1000 V

Isolation capacitance from centre lead to external heatsink (note 5)

C_p typ. 12 pF

Notes:

- Up to $T_j = 125^\circ\text{C}$; see derating curve for higher temperature operation.
- The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
- Assuming no reverse leakage current losses.
- The quoted temperatures assume heatsink compound is used.
- Mounted without heatsink compound and 20 Newtons pressure on the centre of the envelope.

CHARACTERISTICS (per diode) $T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated

Forward voltage

 $I_F = 15\text{ A}; T_j = 125\text{ }^\circ\text{C}$ $V_F < 0.6\text{ V}^*$ $I_F = 30\text{ A}$ $V_F < 0.87\text{ V}^*$

Reverse current

 $V_R = V_{RWM\text{ max}}; T_j = 125\text{ }^\circ\text{C}$ $I_R < 100\text{ mA}$ Junction capacitance at $f = 1\text{ MHz}$ $V_R = 5\text{ V}; T_j = 25\text{ }^\circ\text{C}$ to $125\text{ }^\circ\text{C}$ $C_j \text{ typ. } 500\text{ pF}$ **THERMAL RESISTANCE**

From junction to external heatsink with minimum of 2 kgf (20 Newtons) pressure on the centre of the envelope:

a. both diodes conducting:

with heatsink compound

 $R_{th\ j-h} = 4.8\text{ K/W}$

without heatsink compound

 $R_{th\ j-h} = 6.8\text{ K/W}$

b. per diode:

with heatsink compound

 $R_{th\ j-h} = 5.7\text{ K/W}$

without heatsink compound

 $R_{th\ j-h} = 7.7\text{ K/W}$ **Free air operation**

The quoted value of $R_{th\ j-h}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient

in free air, mounted on a printed circuit board

 $R_{th\ j-a} = 55\text{ K/W}$

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers a good thermal contact under the crystal area and slightly lower $R_{th\ j-h}$ values than screw mounting. The force exerted on the top of the device by the clip should be at least 2 kgf (20 Newtons) to ensure good thermal contact and must not exceed 3.5 kgf (35 Newtons) to avoid damage to the device.
4. If screw mounting is used, it should be M3 cross-recess pan head.

Minimum torque to ensure good thermal contact:	5.5 kgf (0.55 Nm)
Maximum torque to avoid damage to the device:	8.0 kgf (0.80 Nm)
5. For good thermal contact, heatsink compound should be used between baseplate and heatsink. Values of $R_{th\ j-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting.

It is not recommended to use rivets, since extensive damage could result to the plastic, which could destroy the insulating properties of the device.
7. The heatsink must have a flatness in the mounting area of 0.02 mm maximum per 10 mm. Mounting holes must be deburred.

OPERATING NOTES

The various components of junction temperature rise above ambient are illustrated in Fig.2.

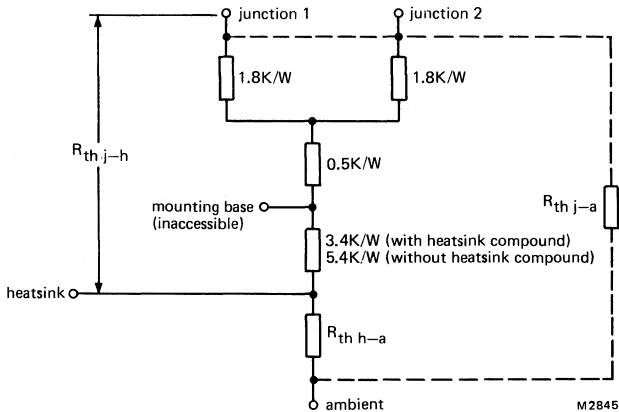


Fig.2.

Any measurement of heatsink temperature should be immediately adjacent to the device.

OPERATING NOTES

Dissipation and heatsink calculations (continued)

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required for each half of the dual diode:

- (i) maximum operating ambient temperature
- (ii) duty cycle of forward current (δ)
- (iii) average forward current per diode
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R — reverse leakage dissipation

P_F — forward conduction dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_F + P_R} - (R_{th\ j-h}) \dots\dots\dots 2).$$

The value of $R_{th\ j-h}$ can be found under Thermal Resistance and will depend upon whether or not heatsink compound is used. P_R and P_F are derived from Figs.3 and 4 as follows:

Look at each half of the dual diode separately; for each diode, starting at the V_{RWM} axis of Fig.3, and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ). From this point trace right and read the actual reverse power dissipation on the P_R axis. From this calculation, $P_R = P_R$ (diode 1) + P_R (diode 2) $\dots\dots\dots 3).$

Forward conduction dissipation (P_F) for the known average current $I_F(AV)$ and duty cycle for each diode is easily derived from Fig.4.

Similarly, $P_F = P_F$ (diode 1) + P_F (diode 2) $\dots\dots\dots 4).$

Substituting equations 3) and 4) into equation 2) enables the calculation of the required heatsink.

NOTE:— If both halves of the diode are being used (as is assumed above), the value of $R_{th\ j-h} = 4.8\ K/W$ (with heatsink compound) or $6.8\ K/W$ (without heatsink compound).

If only one half of the diode is used, follow the above procedure for one diode only, and use the value of $R_{th\ j-h}$ of $5.7\ K/W$ (with heatsink compound) or $7.7\ K/W$ (without heatsink compound).

To ensure thermal stability, $(R_{th\ j-h} + R_{th\ h-a}) \times P_R$ must be less than $12\ ^\circ C$. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ j-a}$ improved) to enable this criterion to be met.

EXAMPLE: square wave operation, using BYV43F-35 and heatsink compound;

$T_{amb} = 40\ ^\circ C$; δ (diode 1) = 0.5; δ (diode 2) = 0.5;

$I_F(AV)$ (diode 1) = 9 A; $I_F(AV)$ (diode 2) = 9 A;

V_{RWM} (both diodes) = 12 V; voltage grade of device = 35 V.

From data, $R_{th\ j-h} = 4.8\ K/W$.

For each diode from Fig.4, it is found that $P_F = 6\ W$;

hence total $P_F = 2 \times 6 = 12\ W$. (from equation 4)

If the desired T_{jmax} is chosen to be $130\ ^\circ C$, then, from Fig.3, P_R (per diode) = $0.44\ W$.

Therefore total $P_R = 2 \times 0.44 = 0.88\ W$. (from equation 3)

Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\ ^\circ C - 40\ ^\circ C}{12\ W + 0.88\ W} - (4.8) = 2.2\ K/W$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (4.8 + 2.2) \times 0.88 = 6.16\ ^\circ C.$$

This is less than $12\ ^\circ C$, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs.3 and 4)

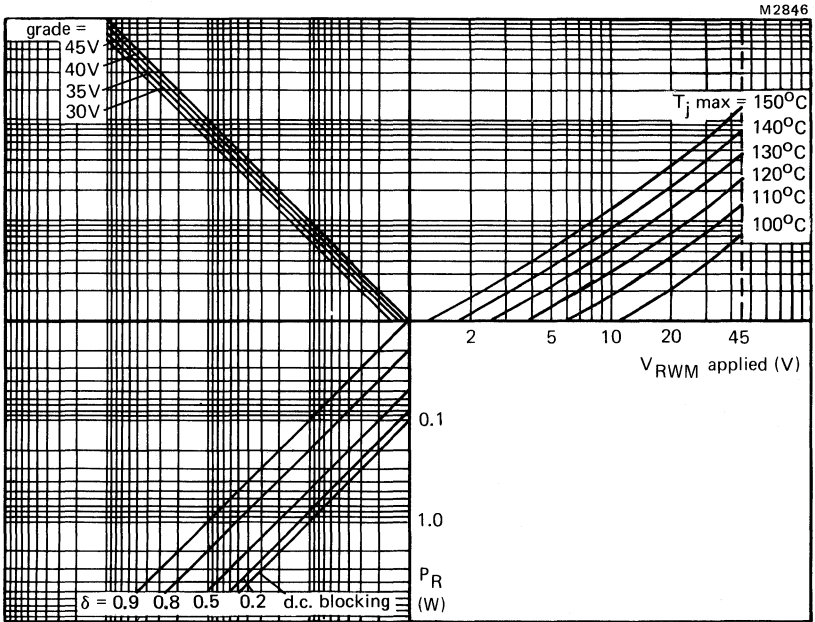


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given T_{jmax} ., V_{RWM} applied, voltage grade and duty cycle (per diode).

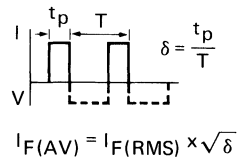
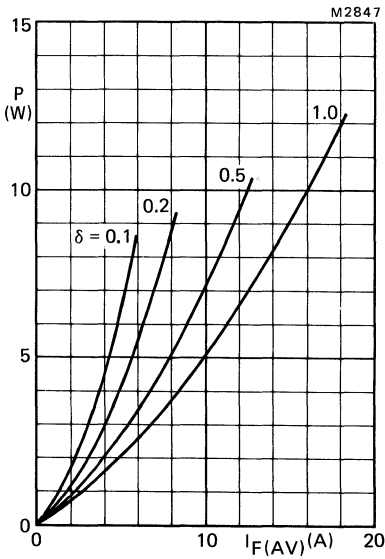


Fig.4(per diode)

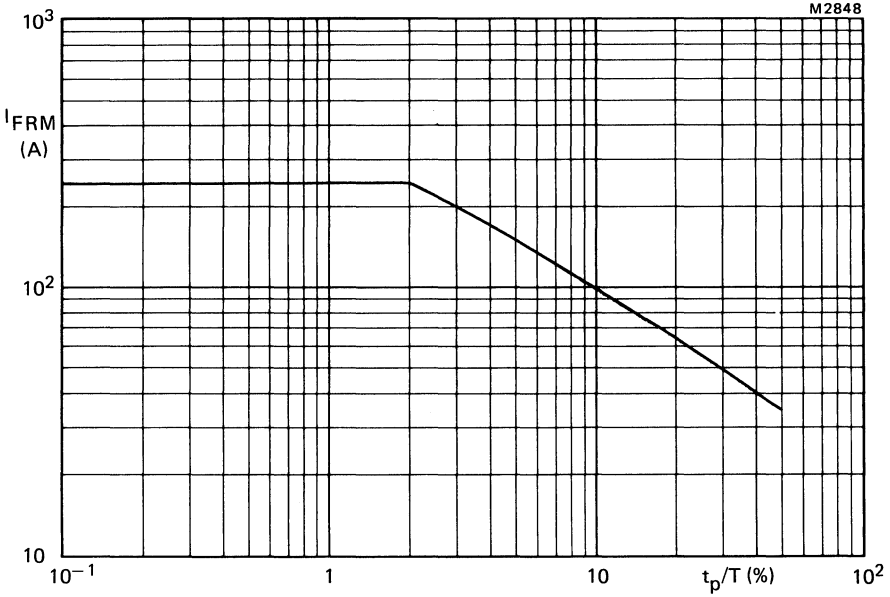


Fig.5 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 ms$, per diode.

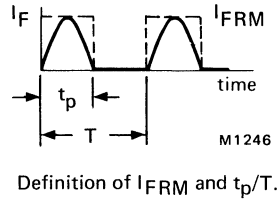
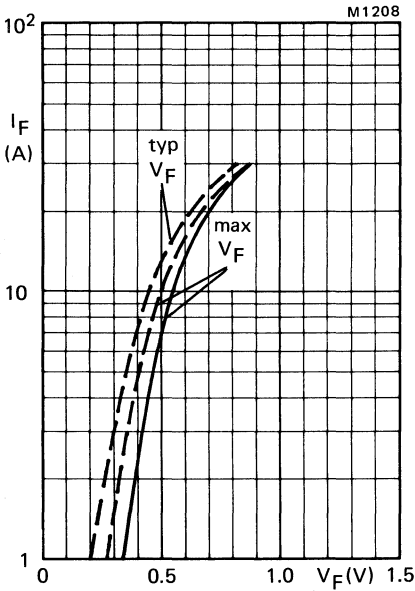


Fig.6 — $T_j = 25^\circ C$; --- $T_j = 125^\circ C$; per diode.

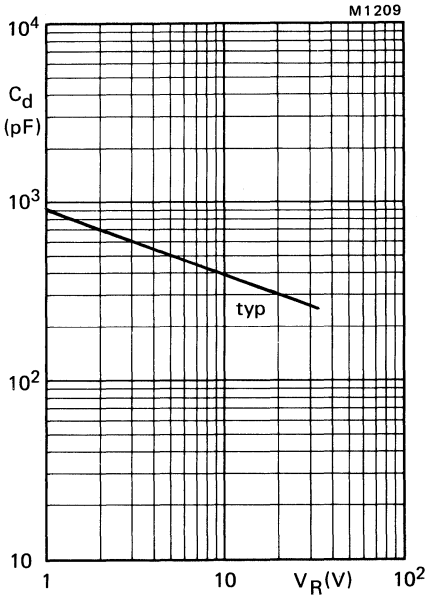


Fig.7 $f = 1$ MHz; $T_j = 25$ to 125 °C; per diode.

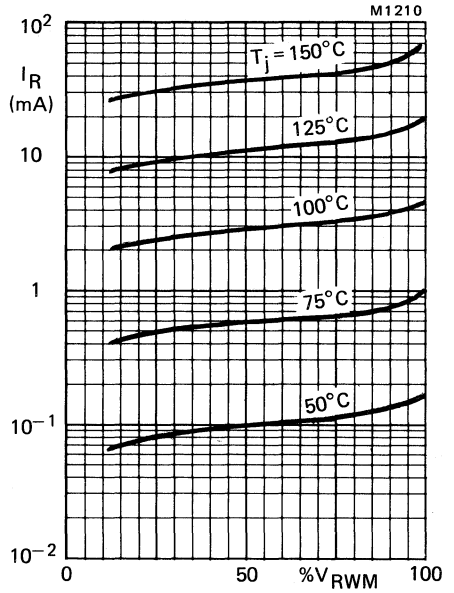


Fig.8 Typical values; per diode.

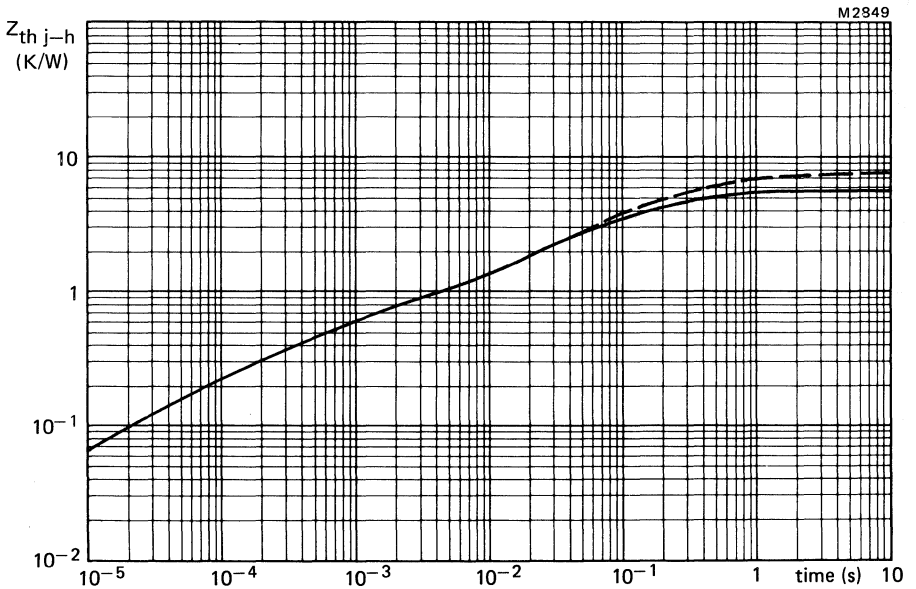


Fig.9 Transient thermal impedance; one diode conducting; — with heatsink compound; - - - without heatsink compound.

SCHOTTKY-BARRIER DOUBLE RECTIFIER DIODES

High-efficiency schottky-barrier double rectifier diodes in plastic envelopes featuring low forward voltage drop, low capacitance and absence of stored charge. They are intended for use in switched-mode power supplies and high-frequency circuits in general, where both low conduction losses and zero switching losses are essential. Their single chip (monolithic) construction allows both diodes to be paralleled without the need for derating. They can also withstand reverse voltage transients. The series consists of common-cathode types. A version with guaranteed reverse surge capability, BYV73-40A, is also available.

QUICK REFERENCE DATA

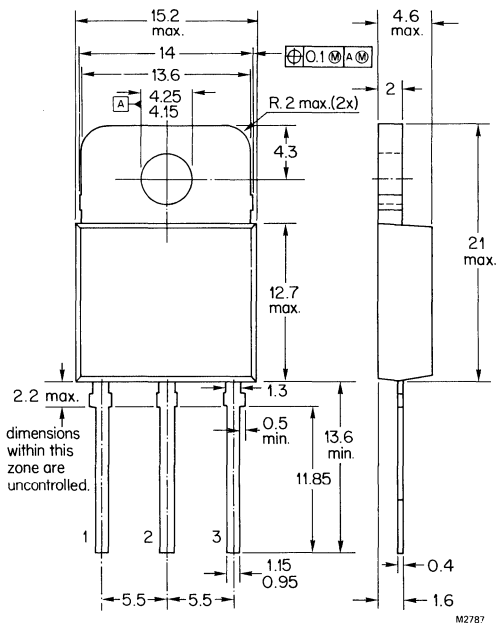
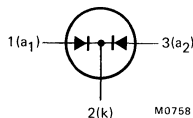
Per diode, unless otherwise stated

		BYV73-30	35	40(A)	45	
Repetitive peak reverse voltage	V_{RRM}	max. 30	35	40	45	V
Output current (both diodes conducting)	I_O	max. 30			A	←
Forward voltage	V_F	< 0.6			V	
Junction temperature	T_j	< 150			°C	

MECHANICAL DATA

Dimensions in mm

Fig.1 SOT-93



Net mass: 5 g

Note: the exposed metal mounting base is directly connected to the common cathode.

Accessories supplied on request: see data sheets Mounting instructions and accessories for SOT-93 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

		BYV73-30	35	40(A)	45		
→	Voltages (per diode)						
	Repetitive peak reverse voltage	V_{RRM}	max. 30	35	40	45	V
	Crest working reverse voltage (note 1)	V_{RWM}	max. 30	35	40	45	V
	Continuous voltage (note 1)	V_R	max. 30	35	40	45	V
→	Currents (both diodes conducting; note 2)						
	Output current: square wave; $\delta = 0.5$; up to $T_{mb} = 112^\circ\text{C}$ (note 3)	I_O	max.		30		A
	R.M.S. forward current	$I_F(\text{RMS})$	max.		40		A
	Repetitive peak forward current $t_p = 20 \mu\text{s}$; $\delta = 0.02$ (per diode)	I_{FRM}	max.		250		A
	Non-repetitive peak forward current (per diode) half sine-wave; $T_j = 125^\circ\text{C}$ prior to surge; with reapplied V_{RWM} max:						
	$t = 10 \text{ ms}$	I_{FSM}	max.		150		A
	$t = 8.3 \text{ ms}$	I_{FSM}	max.		165		A
	$I^2 t$ for fusing ($t = 10 \text{ ms}$, per diode)	$I^2 t$	max.		112		A^2s
	Reverse surge current (BYV73-40A only) $t_p = 100 \mu\text{s}$	I_{RSM}	max.		0.5		A
	Temperatures						
	Storage temperature	T_{stg}			-40 to +150		$^\circ\text{C}$
	Junction temperature	T_j	max.		150		$^\circ\text{C}$

Notes:

- Up to $T_j = 125^\circ\text{C}$; see derating curve for higher temperature operation.
- The limits for both diodes apply whether both diodes conduct simultaneously or on alternate half cycles.
- Assuming no reverse leakage current losses.

CHARACTERISTICS (per diode)

Forward voltage

$I_F = 15 \text{ A}; T_j = 125 \text{ }^\circ\text{C}$

$V_F < 0.6 \text{ V}^*$ ←

$I_F = 30 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$

$V_F < 0.87 \text{ V}^*$ ←

Reverse current

$V_R = V_{RWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$

$I_R < 100 \text{ mA}$

Junction capacitance at $f = 1 \text{ MHz}$

$V_R = 5 \text{ V}; T_j = 25 \text{ to } 125 \text{ }^\circ\text{C}$

$C_d \text{ typ. } 500 \text{ pF}$

THERMAL RESISTANCE

From junction to mounting base (both diodes conducting)

$R_{th \text{ j-mb}} = 1.4 \text{ K/W}$

From junction to mounting base (per diode)

$R_{th \text{ j-mb}} = 2.4 \text{ K/W}$

Influence of mounting method ←

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound

$R_{th \text{ mb-h}} = 0.2 \text{ K/W}$

b. with heatsink compound and 0.06 mm maximum mica insulator (56378)

$R_{th \text{ mb-h}} = 1.4 \text{ K/W}$

c. with heatsink compound and 0.1 mm maximum mica insulator

$R_{th \text{ mb-h}} = 2.2 \text{ K/W}$

d. with heatsink compound and 0.25 mm maximum alumina insulator

$R_{th \text{ mb-h}} = 0.8 \text{ K/W}$

e. without heatsink compound

$R_{th \text{ mb-h}} = 1.4 \text{ K/W}$

2. Free air operation

The quoted values of $R_{th \text{ j-a}}$ should be used only when no leads of other dissipating components run to the same tie point.

Thermal resistance from junction to ambient in free air; mounted on a printed circuit board at any device lead length and with copper laminate on the board

$R_{th \text{ j-a}} = 60 \text{ K/W}$

*Measured under pulse conditions to avoid excessive dissipation.

MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; the heat source must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The bend radius must be no less than 1.0 mm.
3. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than does screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M4 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
4. For good thermal contact, heatsink compound should be used between mounting base and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
5. Rivet mounting (only possible for non-insulated mounting).
 Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink calculations.

The various components of junction temperature rise above ambient are illustrated in Fig.2.

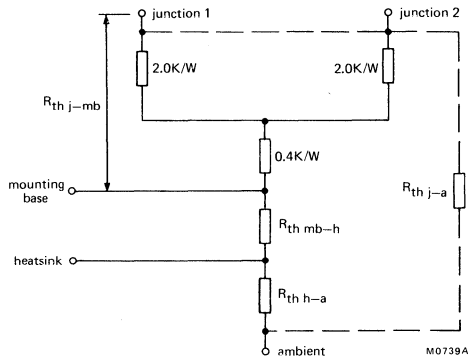


Fig.2.

OPERATING NOTES

Dissipation and heatsink calculations (continued)

Overall thermal resistance, $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$

To choose a suitable heatsink, the following information is required for each half of the dual diode:

- (i) maximum operating ambient temperature
- (ii) duty cycle of forward current (δ)
- (iii) average forward current per diode
- (iv) crest working reverse voltage (V_{RWM})

The total power dissipation in the diode has two components:

P_R — reverse leakage dissipation

P_F — forward conduction dissipation

$$P_{tot} = P_R + P_F \dots\dots\dots 1).$$

From the above it can be seen that:

$$R_{th\ h-a} = \frac{T_{jmax} - T_{amb}}{P_F + P_R} - (R_{th\ j-mb} + R_{th\ mb-h}) \dots\dots\dots 2).$$

Values for $R_{th\ j-mb}$ and $R_{th\ mb-h}$ can be found under Thermal Resistance. P_R and P_F are derived from Figs.3 and 4 as follows:

Look at each half of the dual diode separately; for each diode, starting at the V_{RWM} axis of Fig.3, and from a knowledge of the required V_{RWM} , trace upwards to meet the curve that matches the required T_{jmax} . From this point trace horizontally left until the curve of the voltage grade of the device being used is met. From this point trace downwards to meet the required duty cycle (δ). From this point trace right and read the actual reverse power dissipation on the P_R axis.

From this calculation, $P_R = P_R$ (diode 1) + P_R (diode 2) 3).

Forward conduction dissipation (P_F) for the known average current $I_{F(AV)}$ and duty cycle for each diode is easily derived from Fig.4.

Similarly, $P_F = P_F$ (diode 1) + P_F (diode 2) 4).

Substituting equations 3) and 4) into equation 2) enables the calculation of the required heatsink.

NOTE:— If both halves of the diode are being used (as is assumed above), the value of $R_{th\ j-mb} = 1.4$ K/W. If only one half of the diode is used, follow the above procedure for one diode only, and use the value of $R_{th\ j-mb}$ of 2.4 K/W.

To ensure thermal stability, $(R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}) \times P_R$ must be less than 12 °C. If the calculated value of $R_{th\ h-a}$ does not permit this, then it must be reduced (heatsink size increased or $R_{th\ mb-h}$ improved) to enable this criterion to be met.

EXAMPLE: square-wave operation, using BYV73-35 and heatsink compound;

$T_{amb} = 50$ °C; δ (diode 1) = 0.5; δ (diode 2) = 0.5;
 $I_{F(AV)}$ (diode 1) = 12 A; $I_{F(AV)}$ (diode 2) = 12 A;
 V_{RWM} (both diodes) = 12 V; voltage grade of device = 35 V.

From data, $R_{th\ j-mb} = 1.4$ K/W and $R_{th\ mb-h} = 0.2$ K/W.

For each diode from Fig.4, it is found that $P_F = 9.3$ W;

hence total $P_F = 2 \times 9.3 = 18.6$ W. (from equation 4)

If the desired $T_{j\ max}$ is chosen to be 130 °C, then, from Fig.3, P_R (per diode) = 0.44W

Therefore total $P_R = 2 \times 0.44 = 0.88$ W. (from equation 3)

Using equation 2) we have:

$$R_{th\ h-a} = \frac{130\ ^\circ\text{C} - 50\ ^\circ\text{C}}{18.6\ \text{W} + 0.88\ \text{W}} - (1.4 + 0.2) = 2.5\ \text{K/W}$$

To check for thermal stability:

$$(R_{th\ j-a}) \times P_R = (1.4 + 0.2 + 2.5) \times 0.88 = 3.6\ ^\circ\text{C}.$$

This is less than 12 °C, hence thermal stability is ensured.

SQUARE-WAVE OPERATION (Figs.3 and 4)

M2797

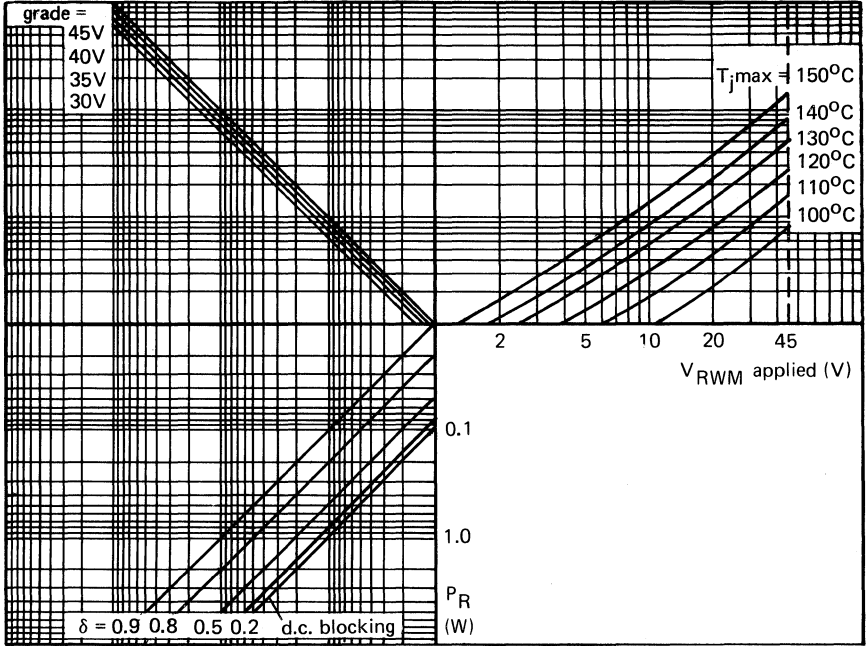
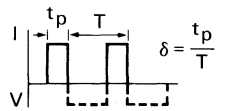
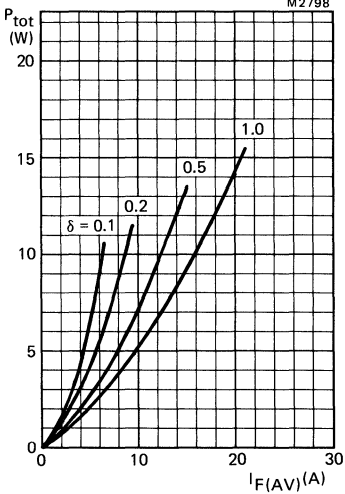


Fig.3 NOMOGRAM: for calculation of P_R (reverse leakage power dissipation) for a given T_{jmax} , V_{RWM} applied, voltage grade and duty cycle (per diode).

M2798



$$I_{F(AV)} = I_{F(RMS)} \times \sqrt{\delta}$$

Fig.4

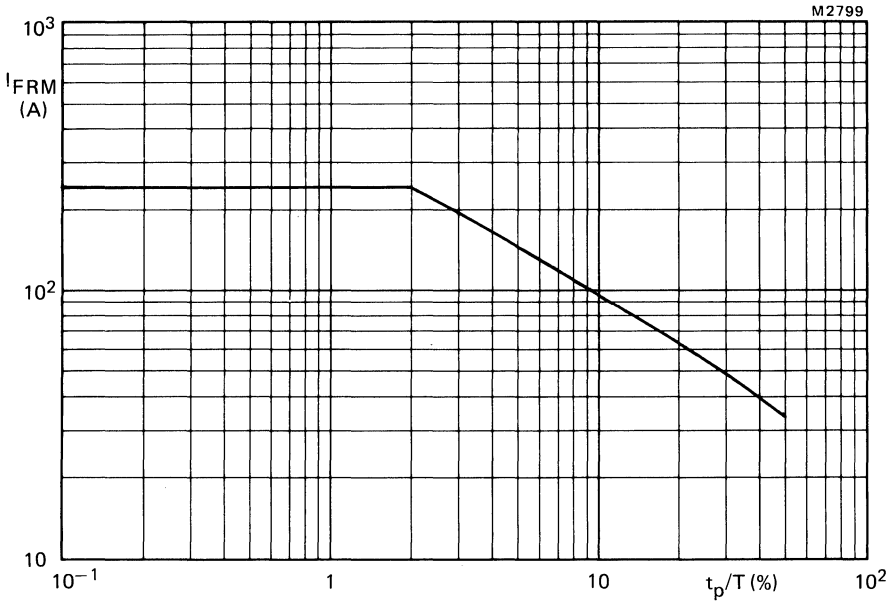
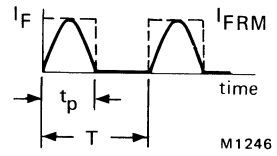
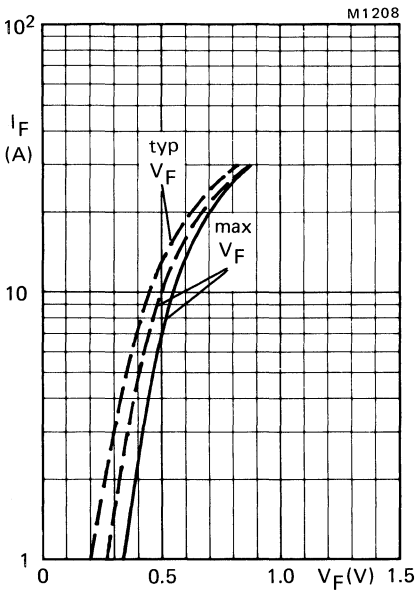


Fig.5 Maximum permissible repetitive peak forward current for either square or sinusoidal currents for $1 \mu s < t_p < 1 \text{ ms}$.



Definition of I_{FRM} and t_p/T .

Fig.6 — $T_j = 25 \text{ }^\circ\text{C}$; - - - $T_j = 125 \text{ }^\circ\text{C}$; per diode.

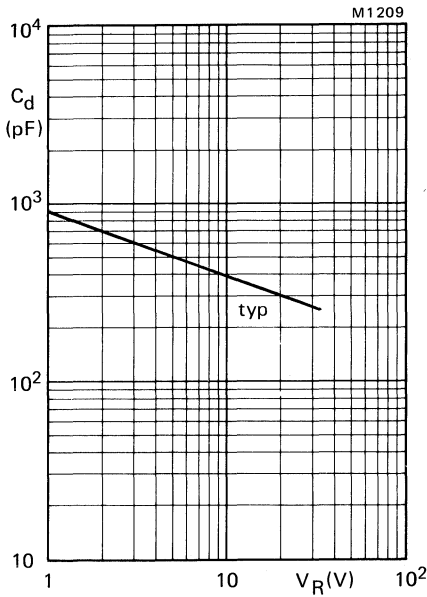


Fig.7 $f = 1$ MHz; $T_j = 25$ to 125 °C; per diode.

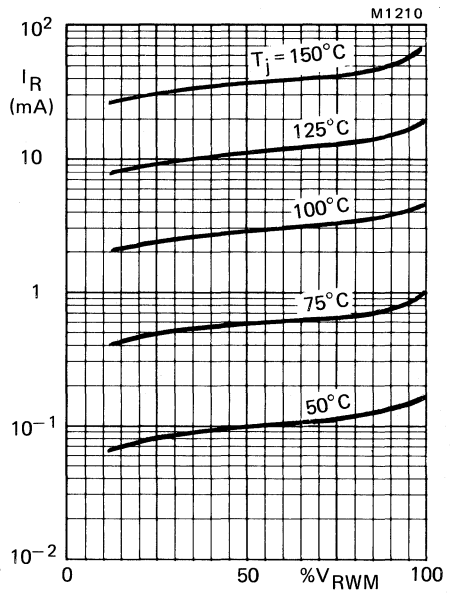


Fig.8 Typical values; per diode.

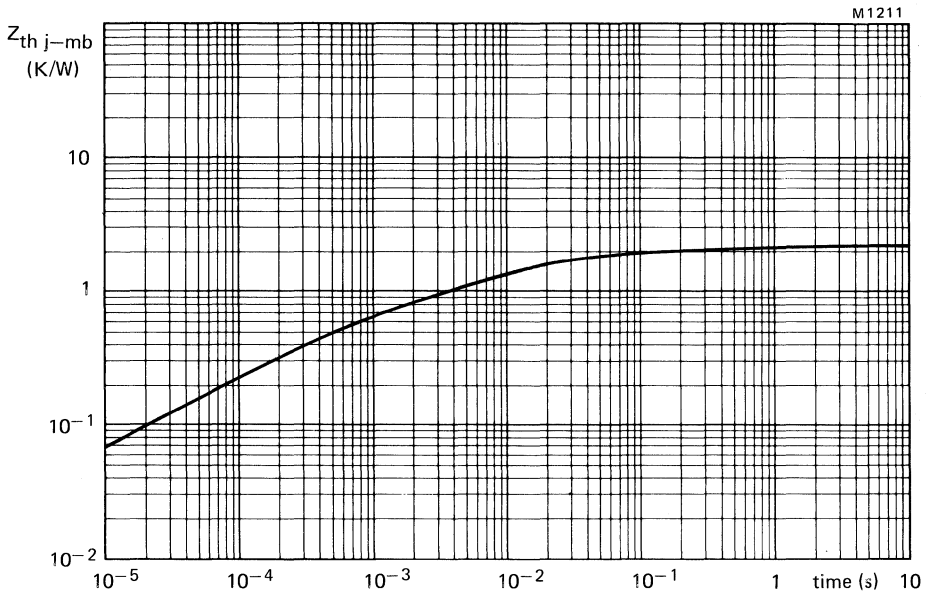


Fig.9 Transient thermal impedance; one diode conducting.

SCHOTTKY—BARRIER RECTIFIER DIODE

High-efficiency rectifier diode in a DO-5 metal envelope, featuring low forward voltage drop, low capacitance, absence of stored charge and high temperature stability. It is intended for use in low output voltage switched-mode power supplies and high-frequency circuits in general, where low conduction and switching losses are important. It can also withstand reverse voltage transients. The diode is of normal polarity (cathode to stud).

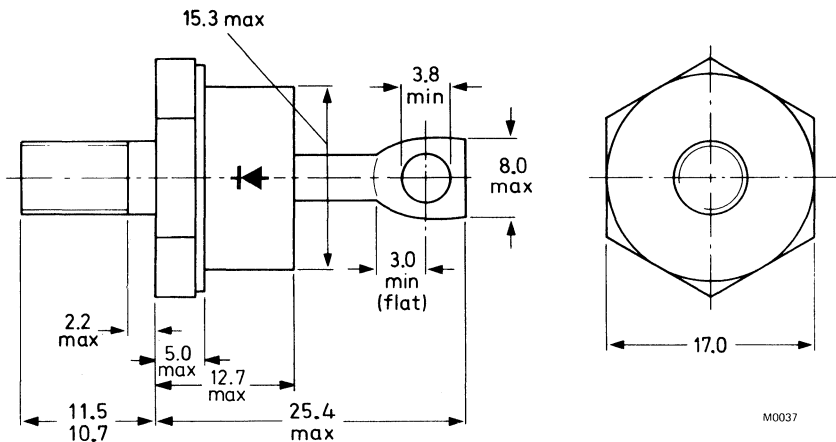
QUICK REFERENCE DATA

Repetitive peak reverse voltage	V_{RRM}	max.	45	V
Average forward current	$I_F(AV)$	max.	60	A
Forward voltage	V_F	<	0.6	V
Junction temperature	T_j	max.	150	°C

MECHANICAL DATA

Dimensions in mm

Fig.1 DO-5 with 1/4" x 28 UNF stud ($\phi 6.35$ mm)



Net mass: 22 g

Diameter of clearance hole: 6.5 mm

Accessories supplied on request:
see ACCESSORIES section

Supplied with device: 1 nut, 1 lock washer.

Torque on nut:

min. 1.7 Nm (17 kg cm),
max. 3.5 Nm (35 kg cm).

Nut dimensions across the flats:
1/4" x 28 UNF, 11.1 mm

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC134)

Voltages

Repetitive peak reverse voltage	V_{RRM}	max.	45	V
Crest working reverse voltage	V_{RWM}	max.	35	V
Continuous reverse voltage	V_R	max.	35	V

Currents

Average forward current; switching losses negligible square-wave; $\delta = 0.5$; up to $T_{mb} = 90$ °C.	$I_F(AV)$	max.	60	A
R.M.S. forward current	$I_F(RMS)$	max.	85	A
Non-repetitive peak forward current $t = 10$ ms; half sine-wave; $T_j = 125$ °C prior to surge; with reapplied V_{RWMmax}	I_{FSM}	max.	700	A
$I^2 t$ for fusing ($t = 10$ ms)	$I^2 t$	max.	2450	A ² s

Temperatures

Storage temperature	T_{stg}	-55 to +150	°C
Junction temperature	T_j	max. 150	°C

THERMAL RESISTANCE

From junction to mounting base	$R_{th j-mb}$	=	1	°C/W
From mounting base to heatsink with heatsink compound	$R_{th mb-h}$	=	0.3	°C/W
without heatsink compound	$R_{th mb-h}$	=	0.5	°C/W
Transient thermal impedance; $t = 1$ ms	$Z_{th j-mb}$	=	0.15	°C/W

CHARACTERISTICS

Forward voltage				
$I_F = 60$ A; $T_j = 125$ °C	V_F	<	0.6	V*
$I_F = 120$ A; $T_j = 125$ °C	V_F	<	0.84	V*
Rate of rise of reverse voltage	$\frac{dV_R}{dt}$	<	1500	V/ μ s
$V_R = V_{RWMmax}$				
Reverse current				
$V_R = V_{RWMmax}$; $T_j = 125$ °C	I_R	<	200	mA
Capacitance at $f = 1$ MHz				
$V_R = 5$ V; $T_j = 25$ to 125 °C	C_d	typ.	2100	pF

MOUNTING INSTRUCTIONS

The top connector should be neither bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

*Measured under pulse conditions to avoid excessive dissipation.

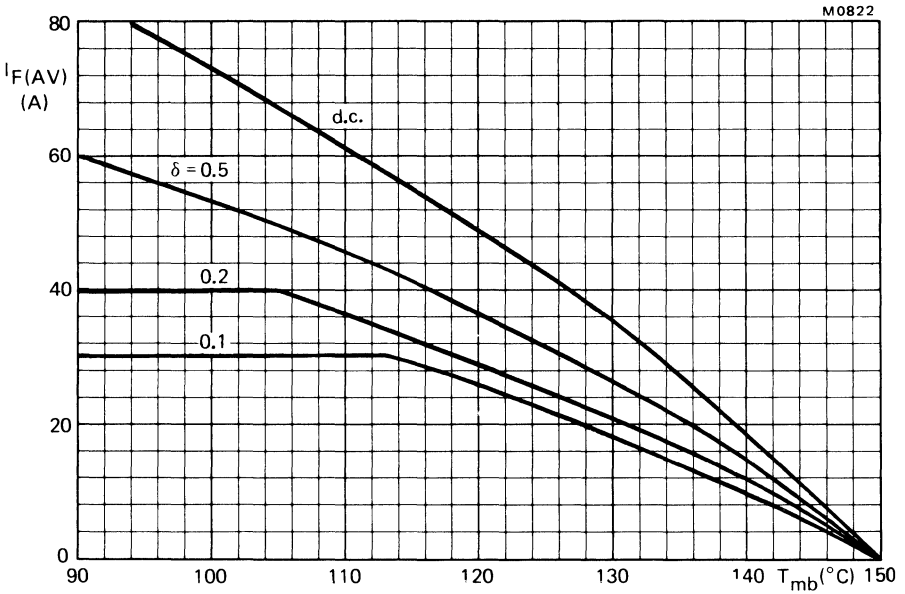
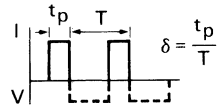
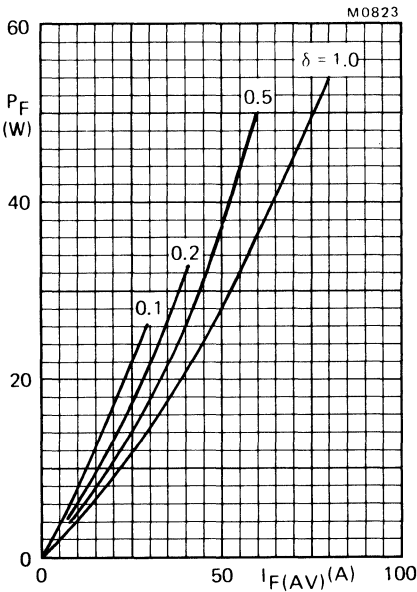


Fig.2 Maximum permissible average forward current versus mounting-base temperature at $V_{RWM} = 35$ V.



$$I_F(AV) = I_F(RMS) \times \sqrt{\delta}$$

Fig.3 Forward power dissipation versus average forward current.

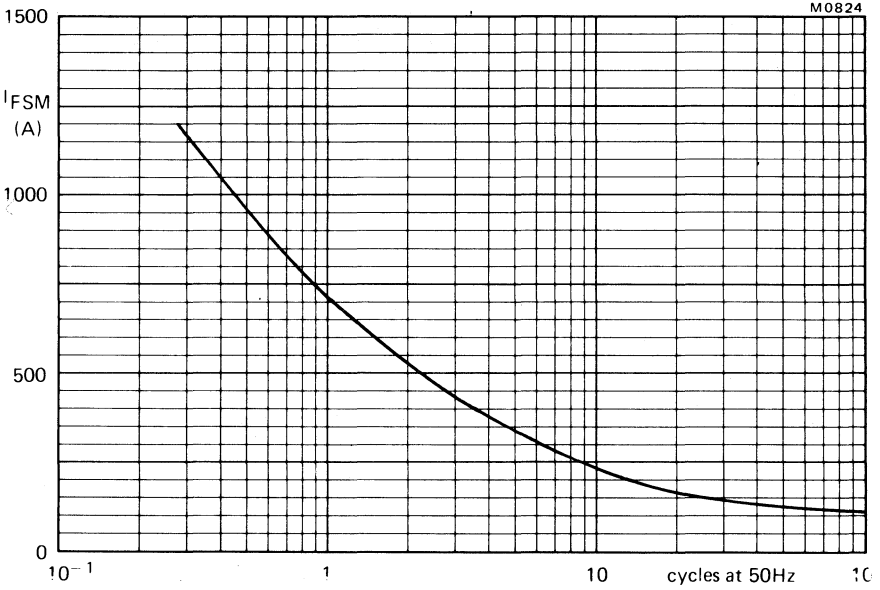


Fig.4 Maximum permissible non-repetitive peak forward current based on sinusoidal currents ($f = 50$ Hz); $T_j = 125$ °C prior to surge; with reapplied V_{RWMmax} .

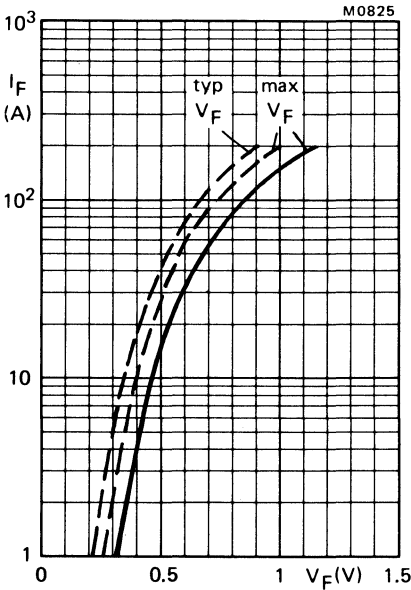


Fig.5 — $T_j = 25$ °C; - - - $T_j = 125$ °C

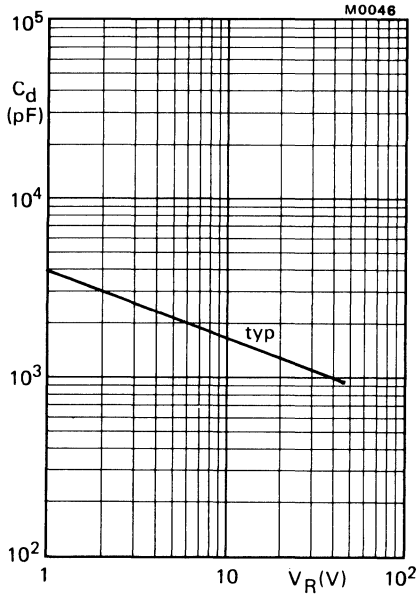


Fig.6 $f = 1$ MHz; $T_j = 25$ to 125 °C

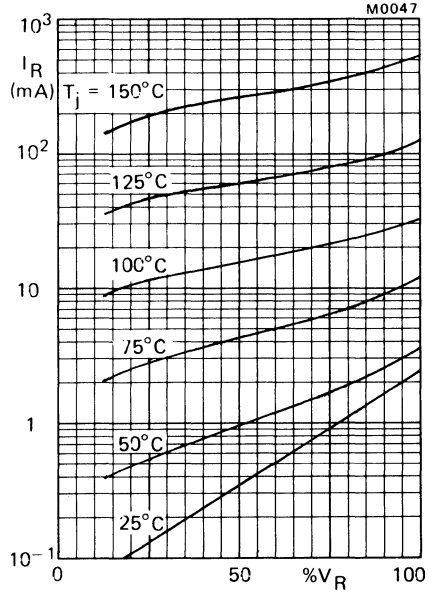


Fig.7 Typical values

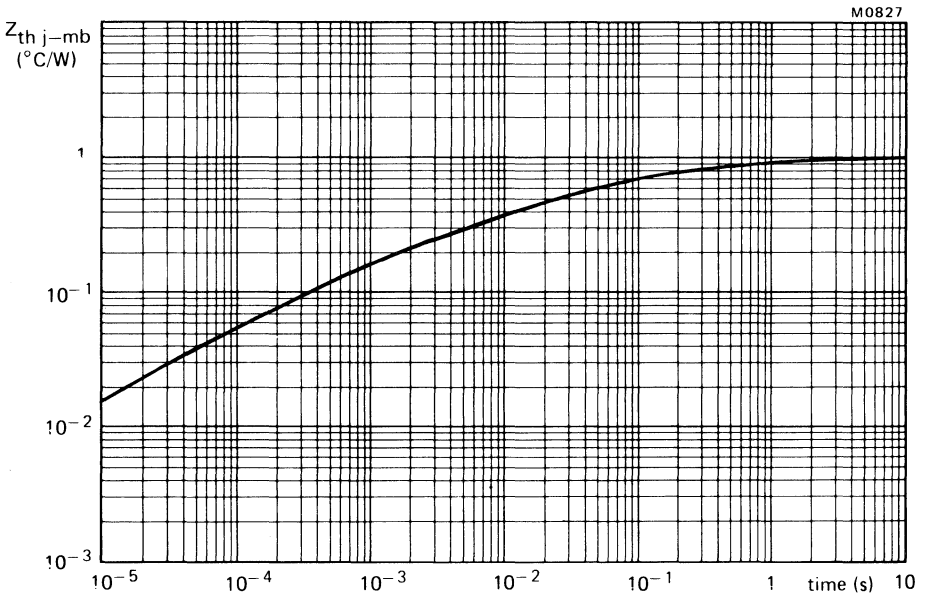


Fig.8

BREAKOVER DIODES

BREAKOVER DIODES

A range of glass-passivated bidirectional breakover diodes in the TO-220AC outline, available in a $\pm 12\%$ tolerance series of nominal breakover voltage. Their controlled breakover voltage and peak current handling capability together with the high holding current make them suitable for transient overvoltage protection in applications such as telephony equipment or other data transmission lines, and remote instrumentation lines.

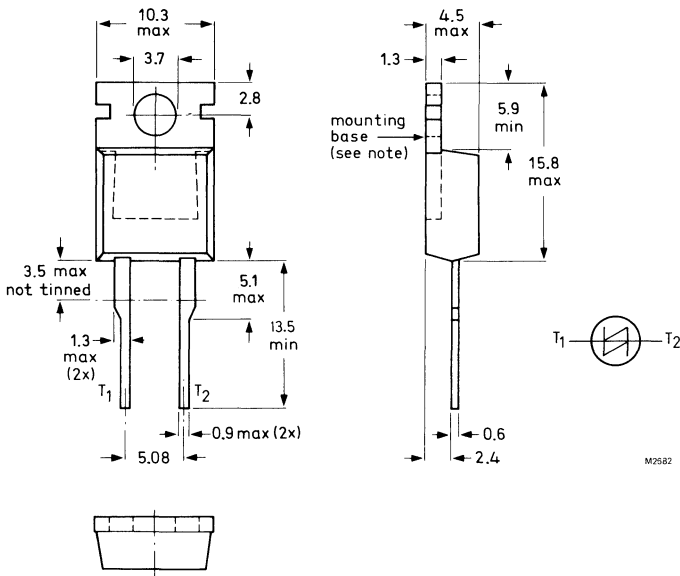
QUICK REFERENCE DATA

		BR210-100 to 280		
Breakover voltage	V_{BO}	nom.	100 to 280	V
Holding current	I_H	>	150	mA
Transient peak current (10/320 μ s impulse)	I_{TRM}	max.	40	A

MECHANICAL DATA

Dimensions in mm

Fig. 1 TO-220AC



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to terminal T₁.

Accessories supplied on request: see data sheet Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Currents

(in either direction)

Transient peak current (8/20 μ s impulse)	I_{TRM1}	max.	150	A
Transient peak current (10/320 μ s impulse) equivalent to 10/700 μ s 1.6 kV voltage impulse (CCITT K17); (see Fig.3)	I_{TRM2}	max.	40	A
Average on-state current (averaged over any 20 ms period); up to $T_{mb} = 75\text{ }^{\circ}\text{C}$	$I_{T(AV)}$	max.	5	A
R.M.S. a.c. on-state current	$I_{T(RMS)}$	max.	8	A
Non-repetitive peak on-state current; $T_j = 100\text{ }^{\circ}\text{C}$ prior to surge; $t = 10\text{ ms}$; half sine-wave	I_{TSM}	max.	40	A
$I^2 t$ for fusing ($t = 10\text{ ms}$)	$I^2 t$	max.	8	A^2s
Rate of rise of on-state current after V_{BO} turn-on ($t_p = 10\text{ }\mu\text{s}$)	di/dt	max.	50	$\text{A}/\mu\text{s}$

Temperatures

Storage temperature	T_{stg}		-40 to +150	$^{\circ}\text{C}$
Operating temperature (off-state)	T_j	max.	125	$^{\circ}\text{C}$
Overload temperature (on-state)	T_{vj}	max.	150	$^{\circ}\text{C}$

THERMAL RESISTANCEFrom junction to ambient in free air
mounted on a printed circuit board
at any lead length

$$R_{th\ j-amb} = 60\ \text{K/W}$$

From junction to mounting base

One line conducting

bidirectional operation

$$R_{th\ j-mb} = 2.0\ \text{K/W}$$

unidirectional operation

$$R_{th\ j-mb} = 2.4\ \text{K/W}$$

Both lines conducting

bidirectional operation

$$R_{th\ j-mb} = 1.5\ \text{K/W}$$

Transient thermal impedance ($t = 1\text{ ms}$)

$$Z_{th\ j-mb} = 0.3\ \text{K/W}$$

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated; each line to centre lead.

Voltages and currents (in either direction)

On-state voltage (note 1)

$I_{TM} = 10\text{ A}$	V_{TM}	<	2.5	V
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Avalanche voltage V_{BR} ; ($I_{BR} = 10\text{ mA}$), and

Breakover voltage V_{BO} ; ($I = I_S$):

(100 μs pulsed)

	V_{BR} min.	V_{BO} max.	
BR210 -100	88	112	V
-120	105	135	V
-140	123	157	V
-160	140	180	V
-180	158	202	V
-200	176	224	V
-220	193	247	V
-240	211	269	V
-260	228	292	V
-280	246	314	V

Temperature coefficient of V_{BR}

S_{br}	typ.	+0.1	%/K
----------	------	------	-----

Holding current (note 2)

$T_j = 25\text{ }^\circ\text{C}$

$T_j = 70\text{ }^\circ\text{C}$

I_H	>	150	mA
I_H	>	100	mA

Switching current (note 3)

(100 μs pulsed)

I_S	>	10	mA
I_S	typ.	200	mA
I_S	<	500	mA

Off-state current; $V_D = 85\% V_{BRmin}$ (note 4)

$T_j = 70\text{ }^\circ\text{C}$

$T_j = 125\text{ }^\circ\text{C}$

I_D	<	50	μA
I_D	<	250	μA

Linear rate of rise of off-state voltage

that will not trigger any device;

$T_j = 70\text{ }^\circ\text{C}$; $V_{DM} = 85\% V_{BRmin}$

dV_D/dt	<	2000	V/ μs
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Off-state capacitance

$V_D = 0$; $f = 1\text{ kHz to } 1\text{ MHz}$

C_j	<	350	pF
-------	---	-----	----

Notes:

1. Measured under pulsed conditions to avoid excessive dissipation.
2. Defined as the minimum current which the device can conduct before switching back to the off-state.
3. Defined as the maximum instantaneous current that the device can sustain in the avalanche breakdown state before it switches to a low voltage.
4. I.e., at maximum recommended d.c. stand-off voltage.

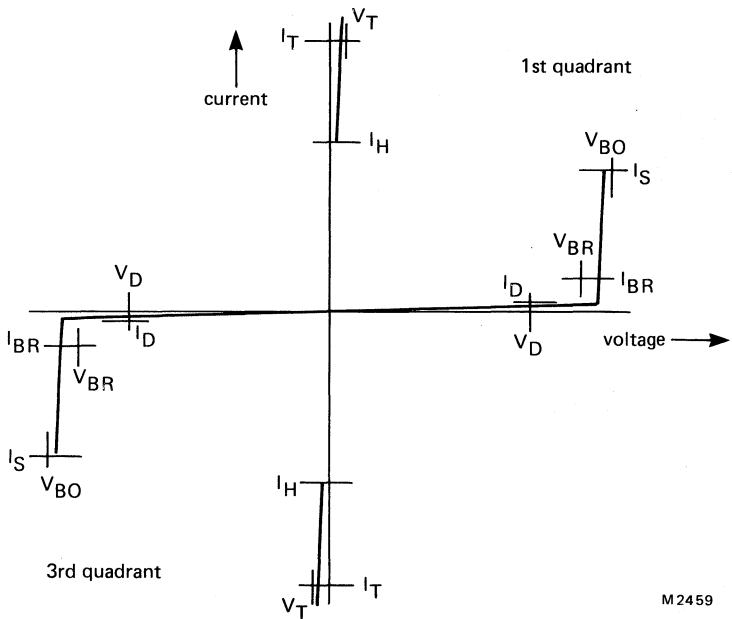


Fig.2 Breakover diode characteristics.

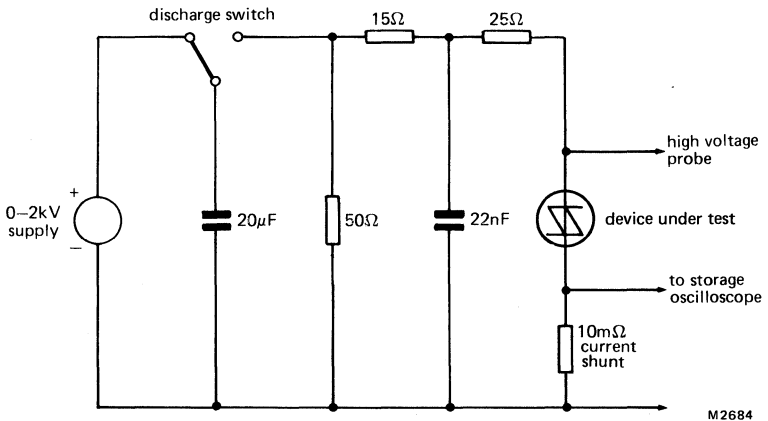


Fig.3 Test circuit for high voltage impulse (I_{TRM2})
(according to CCITT vol IX-Rec. K17)

Notes:

The 10/700 μ s Impulse Waveform is defined for the voltage across the test fixture when the device under test is replaced with an open circuit. Clearly, once a breakover device has switched on to a low voltage, the current waveform will have a shorter fall-time, since the 15 Ω + 25 Ω output impedance becomes effectively in parallel with the 50 Ω .

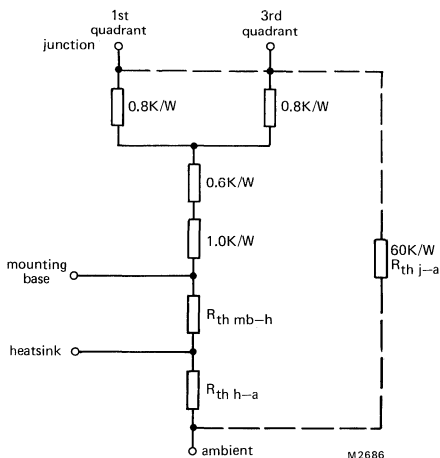
MOUNTING INSTRUCTIONS

1. The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
2. The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending. The leads can be bent, twisted or straightened by 90° maximum. The minimum bending radius is 1 mm.
3. It is recommended that the circuit connection be made to T₁, rather than direct to the heatsink.
4. Mounting by means of a spring clip is the best mounting method because it offers:
 - a. a good thermal contact under the crystal area and slightly lower R_{th mb-h} values than the screw mounting.
 - b. safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
5. For good thermal contact heatsink compound should be used between base-plate and heatsink. Values of R_{th mb-h} given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.
6. Rivet mounting (only possible for non-insulated mounting).
Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.
7. The heatsink must have a flatness in the mounting area of 0.02 mm maximum per 10 mm. Mounting holes must be deburred.

OPERATING NOTES

Dissipation and heatsink considerations:

- a. The various components of junction temperature rise above ambient are illustrated below:



- b. Any measurement of heatsink temperature should be made immediately adjacent to the device.

OPERATING NOTES (cont.)

c. The method of using Fig.5 is:

Start with the expected r.m.s. current, trace upwards to meet the dissipation curve. Trace horizontally to the right, and upwards from the appropriate value on the T_{amb} scale. The intersection determines the required $R_{th\ mb-a}$. The heatsink thermal resistance value ($R_{th\ h-a}$) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- d. As noted, Fig.5 applies for mains contact operation for use with low resistance loads (i.e. $R_L < 200\ \Omega$), and does not include any dissipation due to avalanche conduction prior to breakover. If mains contact conditions are expected with higher resistance loads (R_L typ. $1\ k\Omega$), then avalanche dissipation will be significant and must be taken into account. In certain circumstances, such avalanche dissipation could be excessive. The calculations of avalanche dissipation will depend on the particular application, but the temperature dependence of switching current, and breakdown voltage should be also taken into account.
- e. For many applications in which the device is intended for transient overvoltage protection only, the device will not normally be mounted on a heatsink, since the free air rating will be adequate to cope with non-repetitive transients.

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound	$R_{th\ mb-h}$	=	0.3	K/W
b. with heatsink compound and 0.06 mm maximum mica insulator	$R_{th\ mb-h}$	=	1.4	K/W
c. with heatsink compound and 0.1 mm max. mica insulator (56369)	$R_{th\ mb-h}$	=	2.2	K/W
d. with heatsink compound and 0.25 mm max. alumina insulator (56367)	$R_{th\ mb-h}$	=	0.8	K/W
e. without heatsink compound	$R_{th\ mb-h}$	=	1.4	K/W

FULLWAVE CONDUCTION (MAINS CONTACT)

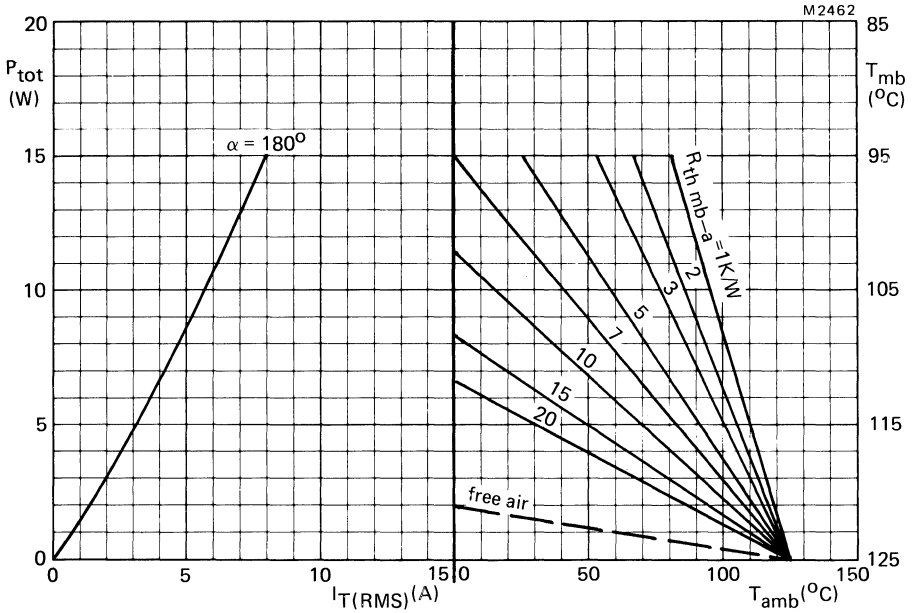
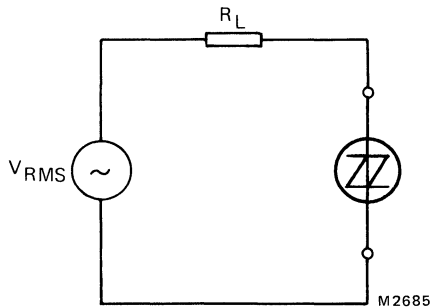


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

α = conduction angle.

This figure applies for a low resistance load. It does not include any avalanche dissipation.



OVERLOAD OPERATION

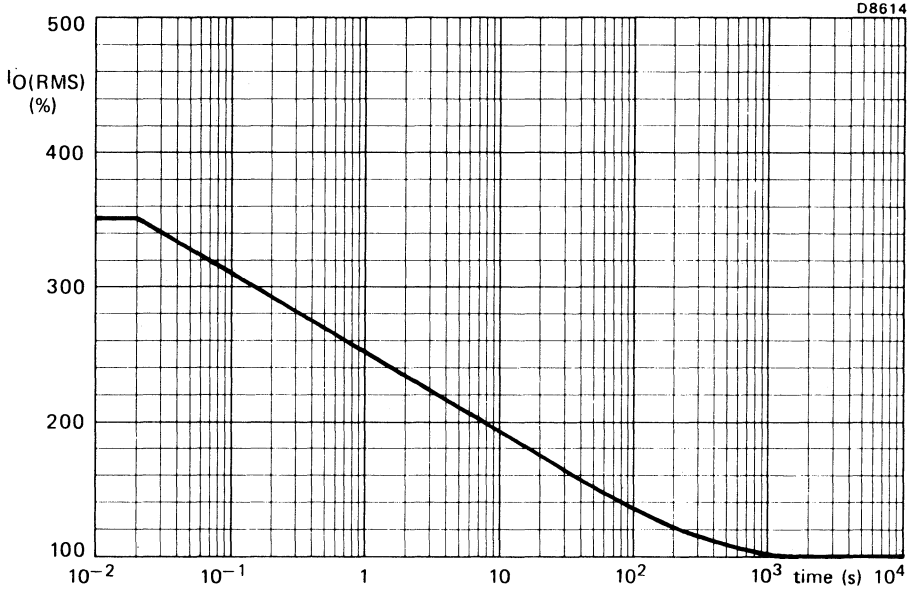


Fig.6 Maximum permissible duration of steady overload (provided that T_{mb} does not exceed $120\text{ }^{\circ}\text{C}$ during and after overload) expressed as a percentage of the steady state r.m.s. rated current. For high r.m.s. overload currents precautions should be taken so that the temperature of the terminals does not exceed $125\text{ }^{\circ}\text{C}$. During these overload conditions the BOD may lose control. Therefore the overload should be terminated by a separate protection device.

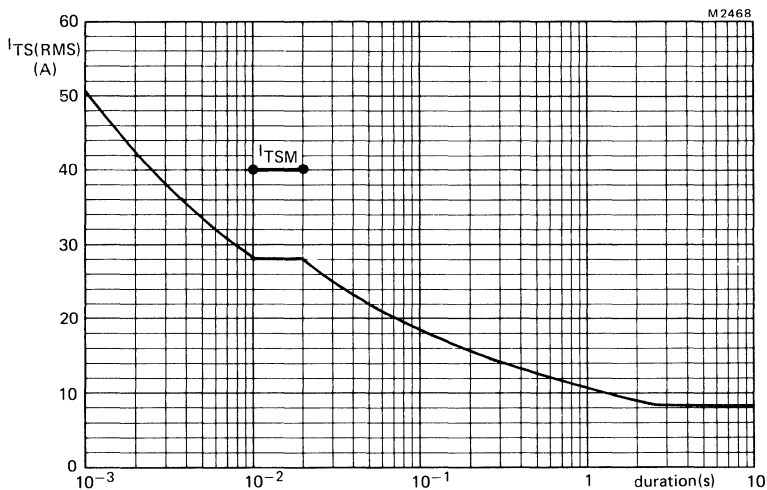


Fig.7 Maximum permissible non-repetitive r.m.s. on-state current based on sinusoidal currents ($f = 50$ Hz), $T_j = 125$ °C prior to surge.

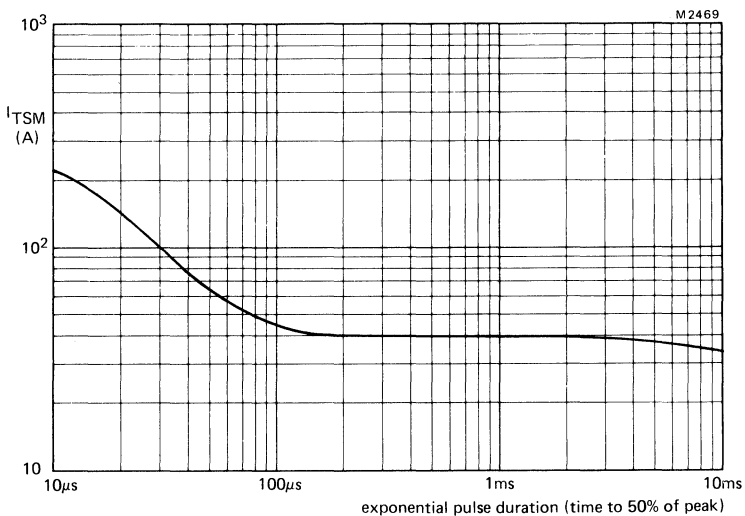
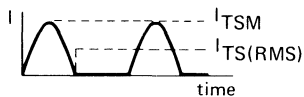


Fig.8 Maximum non-repetitive exponential waveform Impulse Current rating as a function of pulse duration.

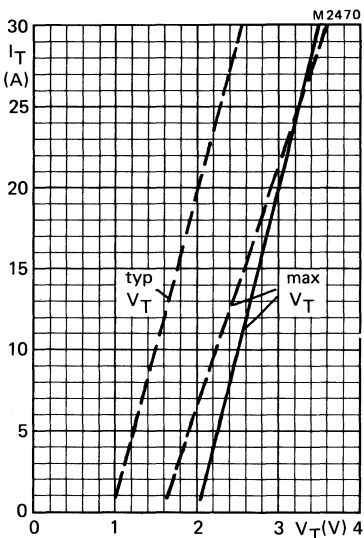


Fig.9 On-state voltage as a function of on-state current. (200 μs pulsed condition to avoid excessive dissipation)
 — $T_j = 25$, - - - $T_j = 125^\circ\text{C}$.

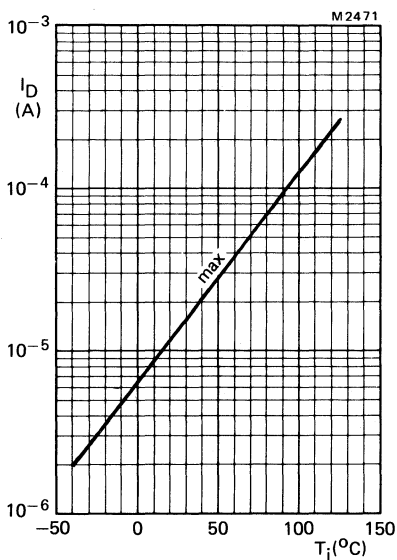


Fig.10 Maximum off-state current as a function of temperature.

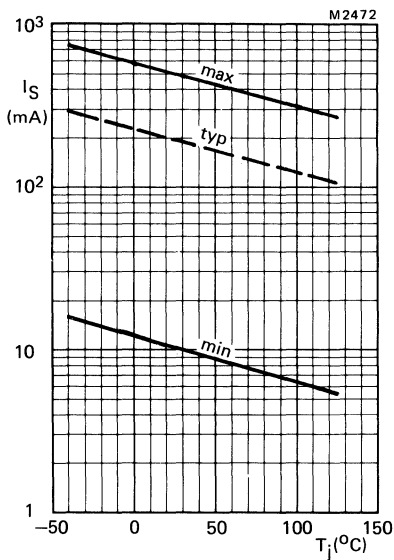


Fig.11 Switching current as a function of temperature; — $T_j = 25^\circ\text{C}$;
 - - - $T_j = 125^\circ\text{C}$.

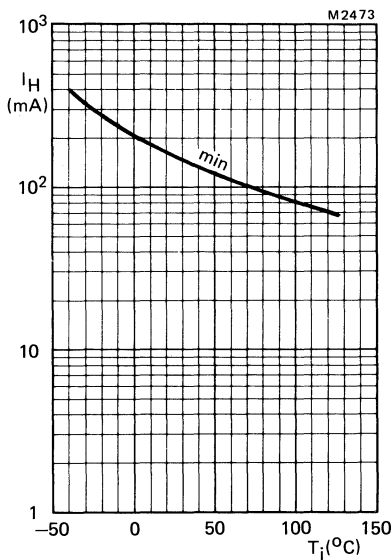


Fig.12 Minimum holding current as a function of temperature.

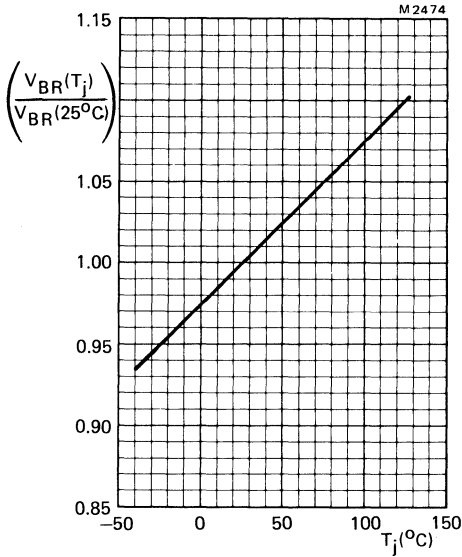


Fig.13 Normalised avalanche voltage as a function of temperature.
 Note: this figure may also be used to derive normalised V_{BO} .

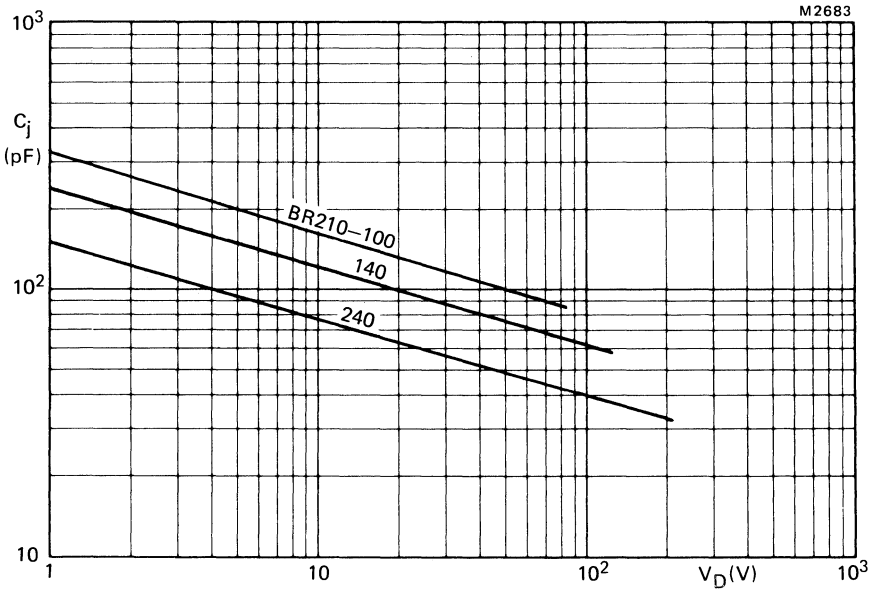


Fig.14 Typical junction capacitance as a function of off-state voltage; $T_j = 25^\circ\text{C}$; $f = 1\text{ MHz}$.

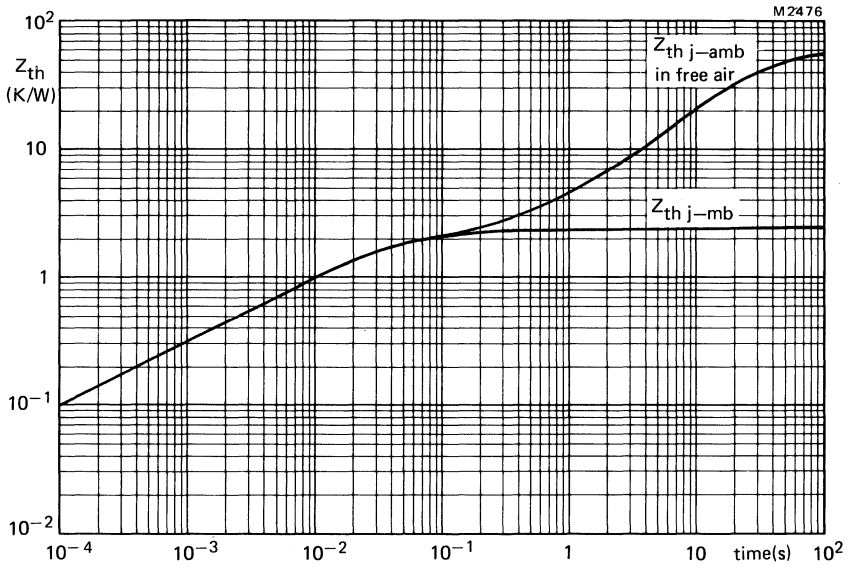


Fig.15 Transient thermal impedance as a function of time (rectangular pulse duration).

DEVELOPMENT DATA

This data sheet contains advance information and specifications are subject to change without notice.

BR216

DUAL ASYMMETRICAL BREAKOVER DIODE

The BR216 is a monolithic dual asymmetrical 65 V breakover diode in the TO-220AB outline. Each half of the device conducts normally in one direction, but in the other direction it acts as a breakover diode.

The controlled break over voltage and peak current handling capability together with high holding current make it suitable for two-line to earth transient overvoltage protection in applications such as telephony equipment and remote instrumentation lines.

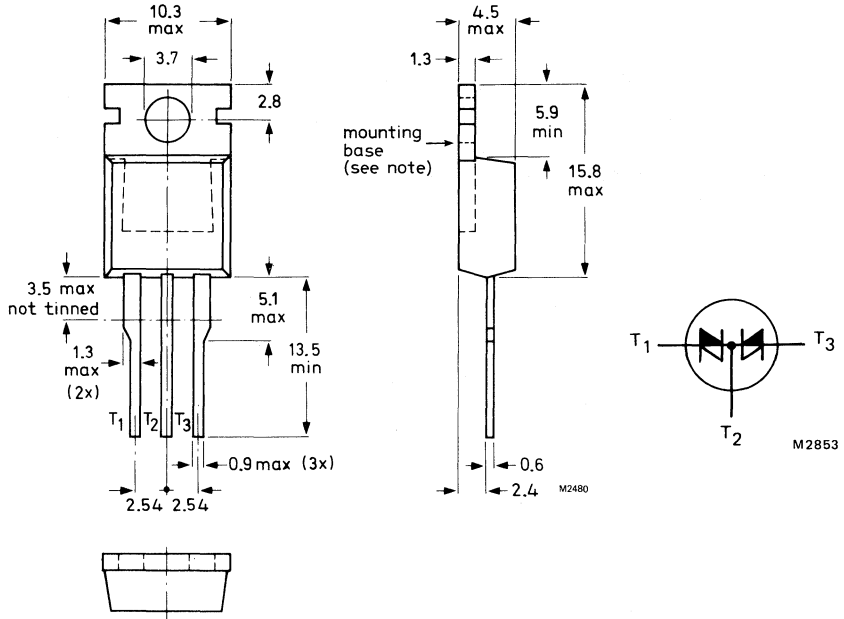
QUICK REFERENCE DATA

Breakover voltage per line	$V(BO)$	<	78	V
Breakdown voltage per line	$V(BR)$	>	58	V
Holding current	I_H	>	150	mA
Transient peak current (10/320 μ s impulse)	I_{TRM}	max.	40	A

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AB; centre lead connected to tab.



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to terminal T₂.

Accessories supplied on request: see data sheet Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Currents

Transient peak current (8/20 μ s impulse)	I_{TRM1}/I_{FRM1}	max.	150	A
Transient peak current (10/320 μ s impulse) equivalent to 10/700 μ s 1.6 kV voltage impulse (CCITT K17)	I_{TRM2}/I_{FRM2}	max.	40	A
Average on-state current	$I_T(AV)$	max.	5	A
Average forward current (averaged over any 20 ms period); up to $T_{mb} = 75^\circ\text{C}$	$I_F(AV)$	max.	5	A
R.M.S. a.c. on-state current	$I_T(RMS)$	max.	8	A
Non-repetitive peak current; $T_j = 100^\circ\text{C}$ prior to surge; $t = 10$ ms; half sine-wave	I_{TSM}/I_{FSM}	max.	40	A
$I^2 t$ for fusing ($t = 10$ ms)	$I^2 t$	max.	8	A^2s
Rate of rise of on-state current after V(BO) turn-on ($t_p = 10$ μ s)	di_T/dt	max.	50	$\text{A}/\mu\text{s}$

Temperatures

Storage temperature	T_{stg}		-40 to +150	$^\circ\text{C}$
Operating temperature (off-state)	T_j	max.	125	$^\circ\text{C}$
Overload temperature (on-state)	T_{vj}	max.	150	$^\circ\text{C}$

THERMAL RESISTANCE

From junction to ambient in free air mounted on a printed circuit board at any lead length	$R_{th j-amb}$	=	60	K/W
From junction to mounting base				
One line conducting				
bidirectional operation	$R_{th j-mb}$	=	4.0	K/W
unidirectional operation	$R_{th j-mb}$	=	5.0	K/W
Both lines conducting				
bidirectional operation	$R_{th j-mb}$	=	3.0	K/W
Transient thermal impedance ($t = 1$ ms)	$Z_{th j-mb}$	=	1.0	K/W

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated; each line to centre lead.

On-state voltage (note 1)

$I_{TM} = 5\text{ A}$ $V_{TM} < 3.0\text{ V}$

Forward voltage (note 1)

$I_{FM} = 5\text{ A}$ $V_{FM} < 3.0\text{ V}$

Avalanche voltage

$I_{(BR)} = 10\text{ mA}$ $V_{(BR)} > 58\text{ V}$

Breakover voltage

$100\text{ }\mu\text{s}$ pulsed; $I = I_S$ $V_{(BO)} < 78\text{ V}$

Temperature coefficient of $V_{(BR)}$

$S_{(br)}$ typ. $+0.1\text{ } \%/K$

Holding current (note 2)

$T_j = 25\text{ }^\circ\text{C}$ $I_H > 150\text{ mA}$

$T_j = 70\text{ }^\circ\text{C}$ $I_H > 100\text{ mA}$

Switching current (note 3)

$I_S > 10\text{ mA}$

I_S typ. 400 mA

$I_S < 830\text{ mA}$

Off-state current; $V_D = 50\text{ V}$ (note 4)

$T_j = 70\text{ }^\circ\text{C}$ $I_D < 0.5\text{ mA}$

$T_j = 125\text{ }^\circ\text{C}$ $I_D < 5.0\text{ mA}$

Linear rate of rise of off-state voltage
that will not trigger any device;

$T_j = 70\text{ }^\circ\text{C}$; $V_{DM} = 50\text{ V}$ $dV_D/dt < 2000\text{ V}/\mu\text{s}$

Off-state capacitance

$V_D = 0$; $f = 1\text{ kHz}$ to 1 MHz $C_j < 500\text{ pF}$

Notes:

1. Measured under pulsed conditions to avoid excessive dissipation.
2. Defined as the minimum current which the device can conduct before switching back to the off-state.
3. Defined as the maximum instantaneous current that the device can sustain in the avalanche breakdown state before it switches to a low voltage.
4. I.e., at maximum recommended d.c. stand-off voltage.

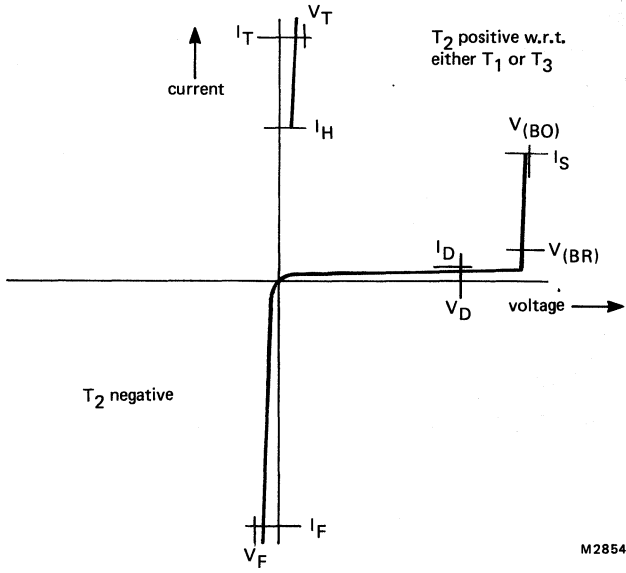


Fig.2 Breakover diode characteristics.

DUAL BREAKOVER DIODES

The BR220 is a range of monolithic diffusion-isolated glass-passivated dual bidirectional breakover diodes in the TO-220AB outline, available in a $\pm 12\%$ tolerance series of nominal breakover voltage. Their controlled breakover voltage and peak current handling capability together with high holding current make them suitable for transient two-line to earth overvoltage protection in applications such as telephony equipment or other data transmission lines, and remote instrumentation lines.

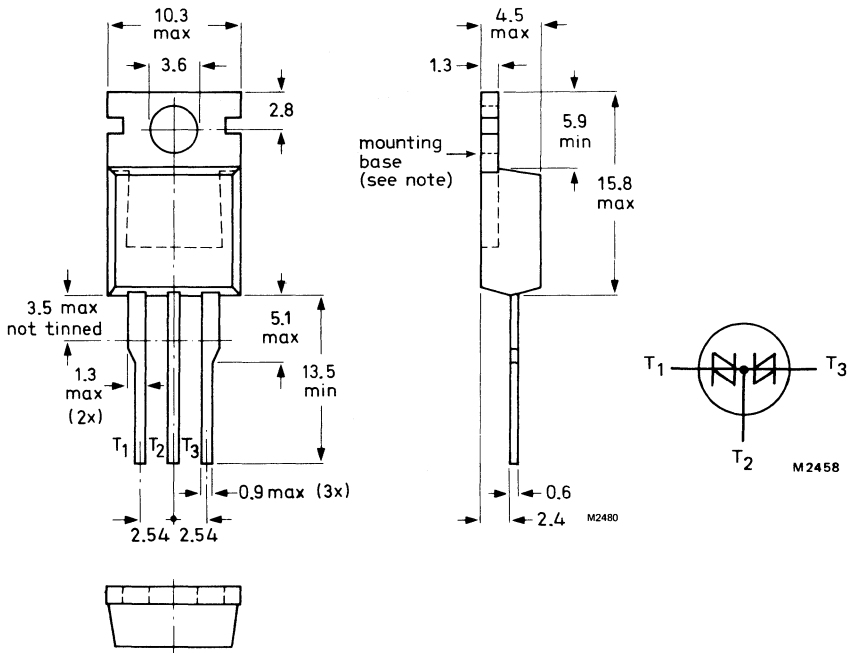
QUICK REFERENCE DATA

		BR220— 100 to 280		
Breakover voltage per line	V_{BO}	nom.	100 to 280	V
Holding current	I_H	>	150	mA
Transient peak current (10/320 μ s impulse)	I_{TRM}	max.	40	A

MECHANICAL DATA

Dimensions in mm

Fig.1 TO-220AB; centre lead connected to tab.



Net mass: 2 g

Note: The exposed metal mounting base is directly connected to terminal T₂.

Accessories supplied on request: see data sheet Mounting instructions and accessories for TO-220 envelopes.

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134).

Currents

(Individually for each line in either direction)

Transient peak current (8/20 μ s impulse)	I_{TRM1}	max.	150	A
Transient peak current (10/320 μ s impulse) equivalent to 10/700 μ s 1.6 kV voltage impulse (CCITT K17); (see Fig.3)	I_{TRM2}	max.	40	A
Average on-state current (averaged over any 20 ms period); up to $T_{mb} = 75^\circ\text{C}$	$I_{T(AV)}$	max.	5	A
R.M.S. a.c. on-state current	$I_{T(RMS)}$	max.	8	A
Non-repetitive peak on-state current; $T_j = 100^\circ\text{C}$ prior to surge; $t = 10$ ms; half sine-wave	I_{TSM}	max.	40	A
$I^2 t$ for fusing ($t = 10$ ms)	$I^2 t$	max.	8	A^2s
Rate of rise of on-state current after V_{BO} turn-on ($t_p = 10 \mu\text{s}$)	di/dt	max.	50	$\text{A}/\mu\text{s}$

Temperatures

Storage temperature	T_{stg}		-40 to +150	$^\circ\text{C}$
Operating temperature (off-state)	T_j	max.	125	$^\circ\text{C}$
Overload temperature (on-state)	T_{vj}	max.	150	$^\circ\text{C}$

THERMAL RESISTANCEFrom junction to ambient in free air
mounted on a printed circuit board
at any lead length

$$R_{th\ j-amb} = 60 \text{ K/W}$$

From junction to mounting base

One line conducting

bidirectional operation

$$R_{th\ j-mb} = 2.0 \text{ K/W}$$

unidirectional operation

$$R_{th\ j-mb} = 2.4 \text{ K/W}$$

Both lines conducting

bidirectional operation

$$R_{th\ j-mb} = 1.5 \text{ K/W}$$

Transient thermal impedance ($t = 1$ ms)

$$Z_{th\ j-mb} = 0.3 \text{ K/W}$$

CHARACTERISTICS

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise stated; each line to centre lead.

Voltages and currents (in either direction)

On-state voltage (note 1)

$I_{TM} = 10\text{ A}$ $V_{TM} < 2.5\text{ V}$

Avalanche voltage V_{BR} ; ($I_{BR} = 10\text{ mA}$), and

Breakover voltage V_{BO} ; ($I = I_S$):

(100 μs pulsed)	V_{BR} min.	V_{BO} max.	
BR220 -100	88	112	V
-120	105	135	V
-140	123	157	V
-160	140	180	V
-180	158	202	V
-200	176	224	V
-220	193	247	V
-240	211	269	V
-260	228	292	V
-280	246	314	V

Temperature coefficient of V_{BR} S_{br} typ. +0.1 %/K

Holding current (note 2)

$T_j = 25\text{ }^\circ\text{C}$ $I_H > 150\text{ mA}$

$T_j = 70\text{ }^\circ\text{C}$ $I_H > 100\text{ mA}$

Switching current (note 3)

(100 μs pulsed) $I_S > 10\text{ mA}$

I_S typ. 200 mA

$I_S < 500\text{ mA}$

Off-state current; $V_D = 85\% V_{BRmin}$ (note 4)

$T_j = 70\text{ }^\circ\text{C}$ $I_D < 50\text{ }\mu\text{A}$

$T_j = 125\text{ }^\circ\text{C}$ $I_D < 250\text{ }\mu\text{A}$

Linear rate of rise of off-state voltage

that will not trigger any device;

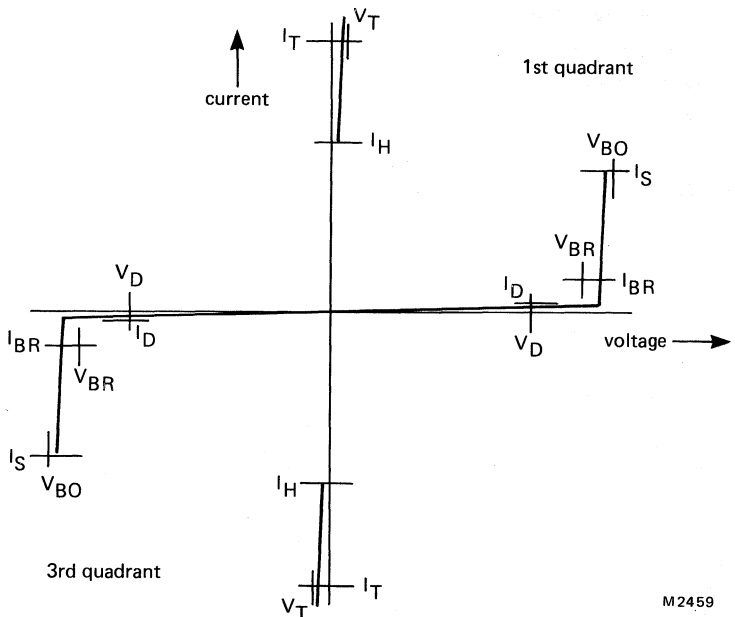
$T_j = 70\text{ }^\circ\text{C}$; $V_{DM} = 85\% V_{BRmin}$ $dV_D/dt < 2000\text{ V}/\mu\text{s}$

Off-state capacitance

$V_D = 0$; $f = 1\text{ kHz to } 1\text{ MHz}$ $C_j < 350\text{ pF}$

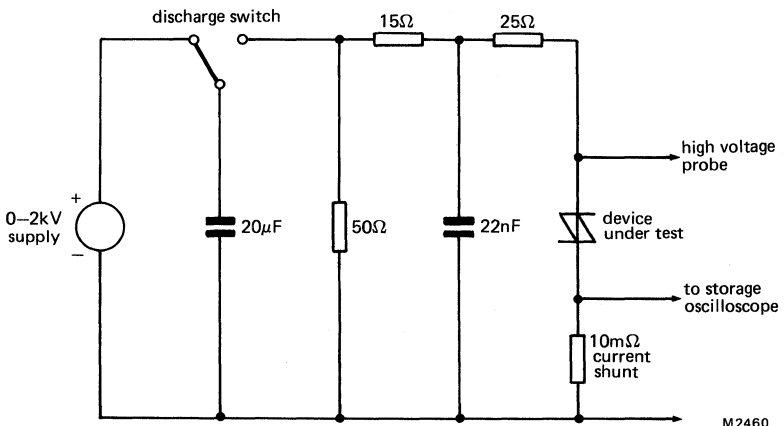
Notes:

1. Measured under pulsed conditions to avoid excessive dissipation.
2. Defined as the minimum current which the device can conduct before switching back to the off-state.
3. Defined as the maximum instantaneous current that the device can sustain in the avalanche breakdown state before it switches to a low voltage.
4. I.e., at maximum recommended d.c. stand-off voltage.



M2459

Fig.2 Breakover diode characteristics.



M2460

Fig.3 Test circuit for high voltage impulse (I_{TRM2})
(according to CCITT vol IX-Rec. K17)

Notes:

The 10/700 µs Impulse Waveform is defined for the voltage across the test fixture when the device under test is replaced with an open circuit. Clearly, once a breakover device has switched on to a low voltage, the current waveform will have a shorter fall-time, since the $15\Omega + 25\Omega$ output impedance becomes effectively in parallel with the 50Ω .

MOUNTING INSTRUCTIONS

- The device may be soldered directly into the circuit, but the maximum permissible temperature of the soldering iron or bath is 275 °C; it must not be in contact with the joint for more than 5 seconds. Soldered joints must be at least 4.7 mm from the seal.
- The leads should not be bent less than 2.4 mm from the seal, and should be supported during bending.
- It is recommended that the circuit connection be made to the centre tag, rather than direct to the heatsink.
- Mounting by means of a spring clip is the best mounting method because it offers:
 - a good thermal contact under the crystal area and slightly lower $R_{th\ mb-h}$ values than the screw mounting.
 - safe isolation for mains operation.
 However, if a screw is used, it should be M3 cross-recess pan head. Care should be taken to avoid damage to the plastic body.
- For good thermal contact heatsink compound should be used between base-plate and heatsink. Values of $R_{th\ mb-h}$ given for mounting with heatsink compound refer to the use of a metallic-oxide loaded compound. Ordinary silicone grease is not recommended.
- Rivet mounting (only possible for non-insulated mounting).

Devices may be rivetted to flat heatsinks; such a process **must neither** deform the mounting tab, **nor** enlarge the mounting hole.

OPERATING NOTES

Dissipation and heatsink considerations:

- The various components of junction temperature rise above ambient are illustrated below:

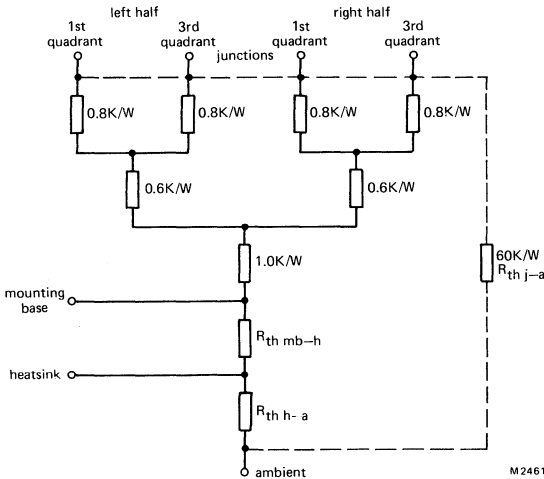


Fig.4.

- Any measurement of heatsink temperature should be made immediately adjacent to the device.

OPERATING NOTES (cont.)

- c. The method of using the following figures is:

Start with the expected r.m.s. current, trace upwards to meet the dissipation curve. Trace horizontally to the right, and upwards from the appropriate value on the T_{amb} scale. The intersection determines the required $R_{th\ mb-a}$. The heatsink thermal resistance value ($R_{th\ h-a}$) can now be calculated from:

$$R_{th\ h-a} = R_{th\ mb-a} - R_{th\ mb-h}$$

- d. As noted, the figures apply for mains contact operation for use with low resistance loads (i.e. $R_L < 200\ \Omega$), and do not include any dissipation due to avalanche conduction prior to breakover. If mains contact conditions are expected with higher resistance loads (R_L typ. $1\ k\Omega$), then avalanche dissipation will be significant and must be taken into account. In certain circumstances, such avalanche dissipation could be excessive. The calculations of avalanche dissipation will depend on the particular application, but the temperature dependence of switching current, and breakdown voltage should be also taken into account.
- e. For many applications in which the device is intended for transient overvoltage protection only, the device will not normally be mounted on a heatsink, since the free air rating will be adequate to cope with non-repetitive transients.

Influence of mounting method

1. Heatsink-mounted with clip (see mounting instructions)

Thermal resistance from mounting base to heatsink

a. with heatsink compound	$R_{th\ mb-h}$	=	0.3	K/W
b. with heatsink compound and 0.06 mm maximum mica insulator	$R_{th\ mb-h}$	=	1.4	K/W
c. with heatsink compound and 0.1 mm max. mica insulator (56369)	$R_{th\ mb-h}$	=	2.2	K/W
d. with heatsink compound and 0.25 mm max. alumina insulator (56367)	$R_{th\ mb-h}$	=	0.8	K/W
e. without heatsink compound	$R_{th\ mb-h}$	=	1.4	K/W

FULLWAVE CONDUCTION (MAINS CONTACT)

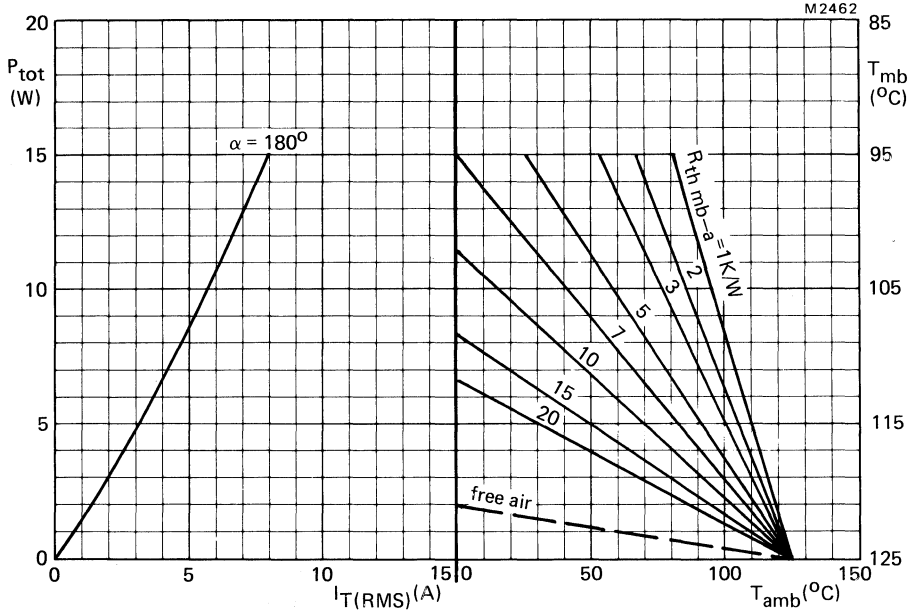
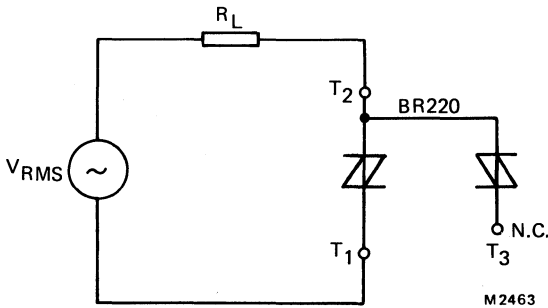


Fig.5 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

α = conduction angle.

This figure applies for one half of the device alone conducting for a low resistance load. It does not include any avalanche dissipation.



FULLWAVE CONDUCTION (MAINS CONTACT)

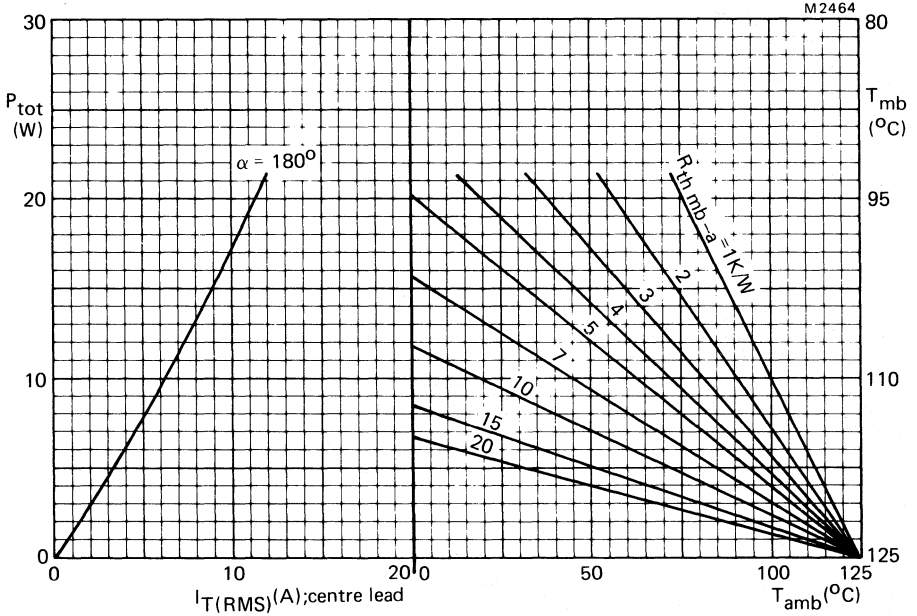
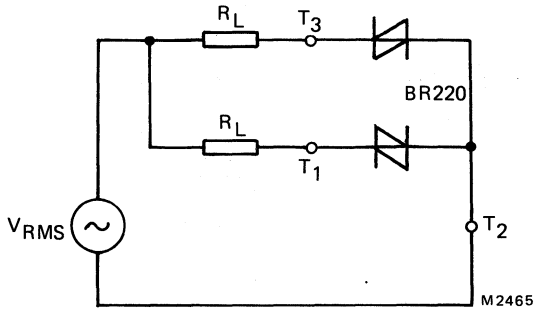


Fig.6 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

α = conduction angle.

This figure applies for both halves of the device conducting on separate loads in PARALLEL configuration. This applies for low resistive loads, and does not include avalanche dissipation.



FULLWAVE CONDUCTION (MAINS CONTACT)

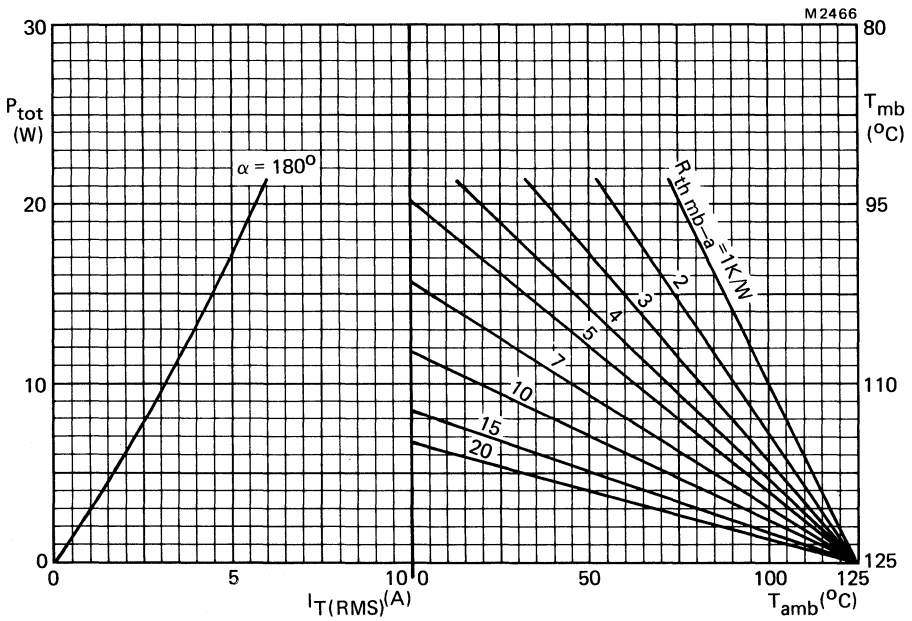
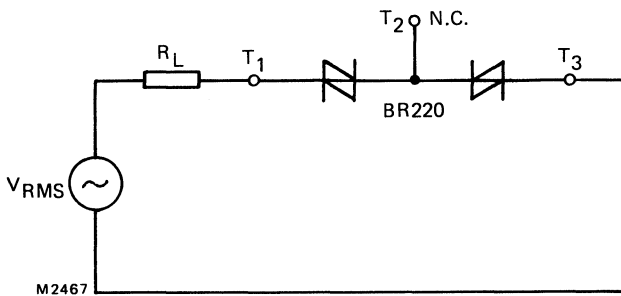


Fig.7 The right-hand part shows the interrelationship between the power (derived from the left-hand part) and the maximum permissible temperatures.

α = conduction angle.

This figure applies for both halves of the device conducting in SERIES configuration. This applies for low resistance loads, and does not include avalanche dissipation.



OVERLOAD OPERATION

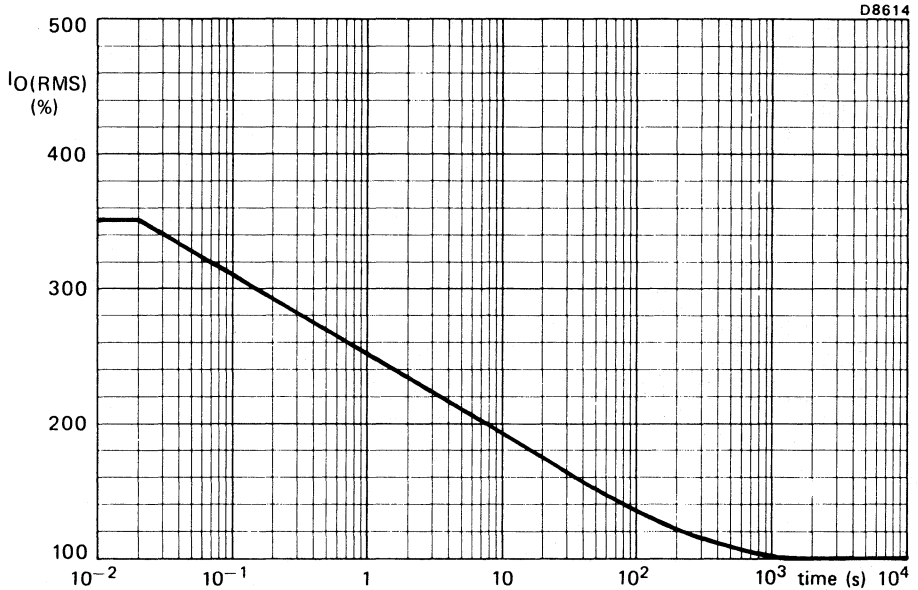


Fig.8 Maximum permissible duration of steady overload (provided that T_{mb} does not exceed 120°C during and after overload) expressed as a percentage of the steady state r.m.s. rated current. For high r.m.s. overload currents precautions should be taken so that the temperature of the terminals does not exceed 125°C . During these overload conditions the BOD may lose control. Therefore the overload should be terminated by a separate protection device.

This figure applies to one half of the dual device conducting.

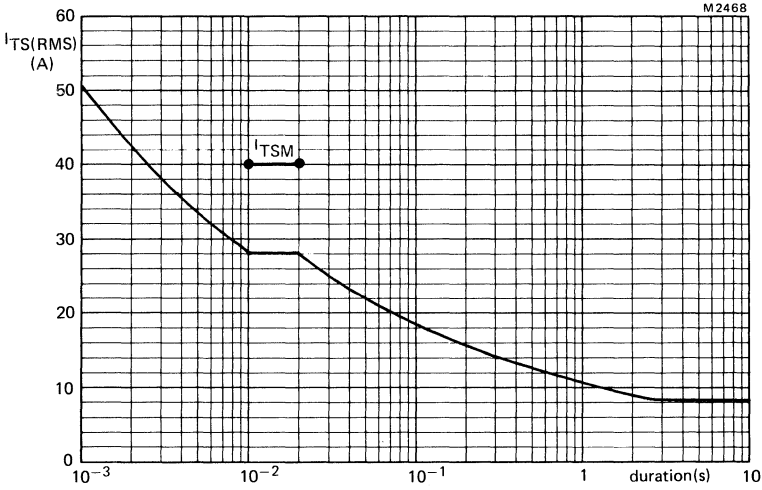


Fig.9 Maximum permissible non-repetitive r.m.s. on-state current based on sinusoidal currents ($f = 50$ Hz), $T_j = 125$ °C prior to surge.

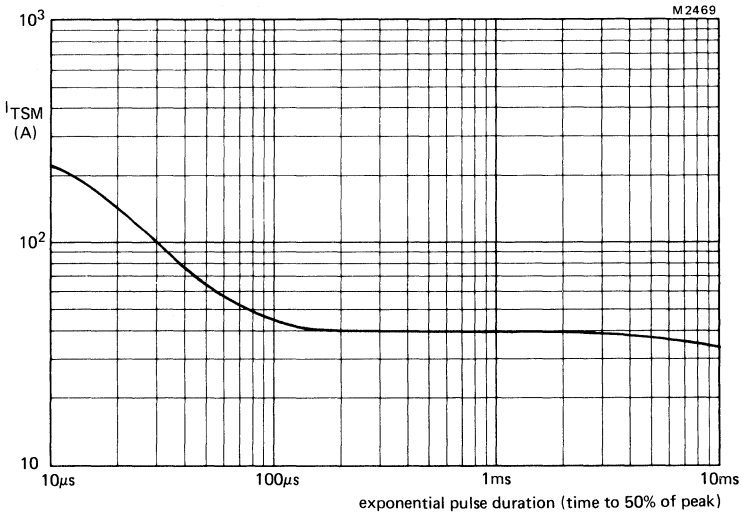
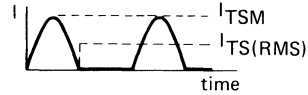


Fig.10 Maximum non-repetitive exponential waveform Impulse Current rating as a function of pulse duration.

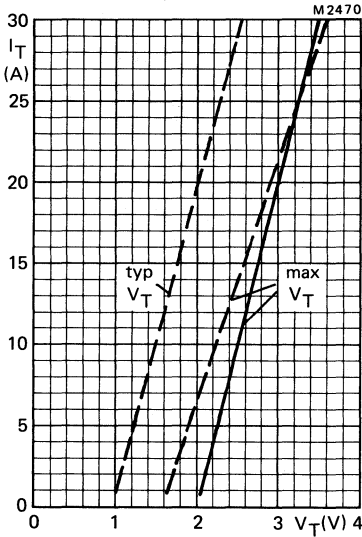


Fig.11 On-state voltage as a function of on-state current. (200 μs pulsed condition to avoid excessive dissipation)
 — $T_j = 25^\circ\text{C}$, - - - $T_j = 125^\circ\text{C}$.

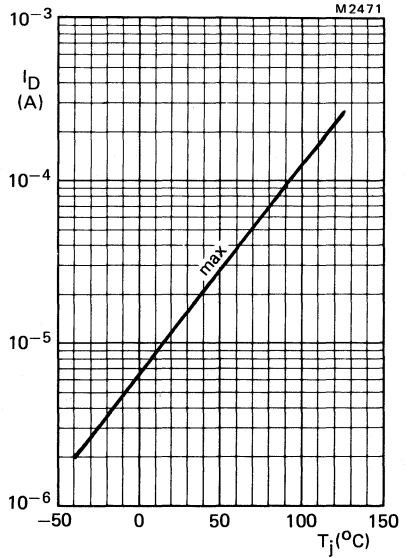


Fig.12 Maximum off-state current as a function of temperature.

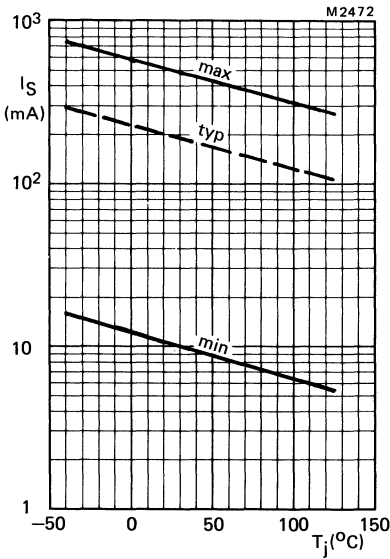


Fig.13 Switching current as a function of temperature; — $T_j = 25^\circ\text{C}$;
 - - - $T_j = 125^\circ\text{C}$.

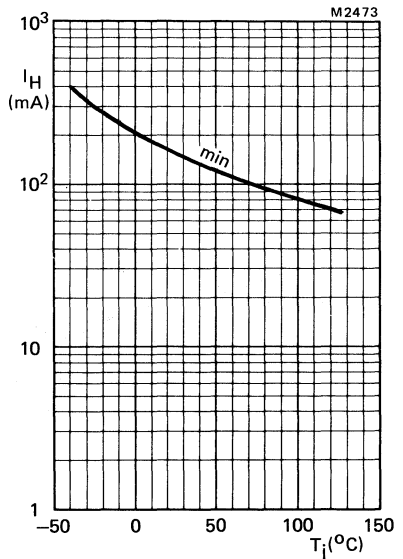


Fig.14 Minimum holding current as a function of temperature.

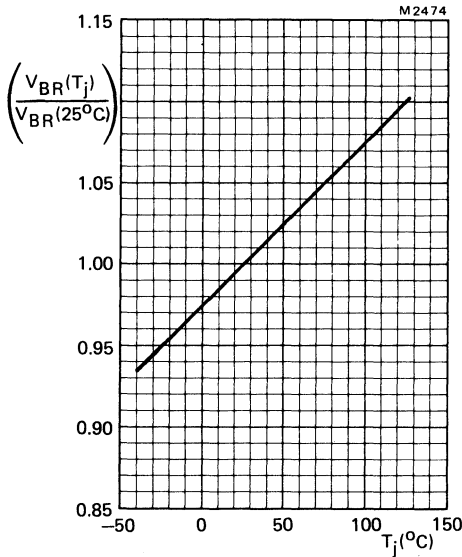


Fig.15 Normalised avalanche breakdown voltage as a function of temperature.
 Note: this figure may also be used to derive normalised V_{BO} .

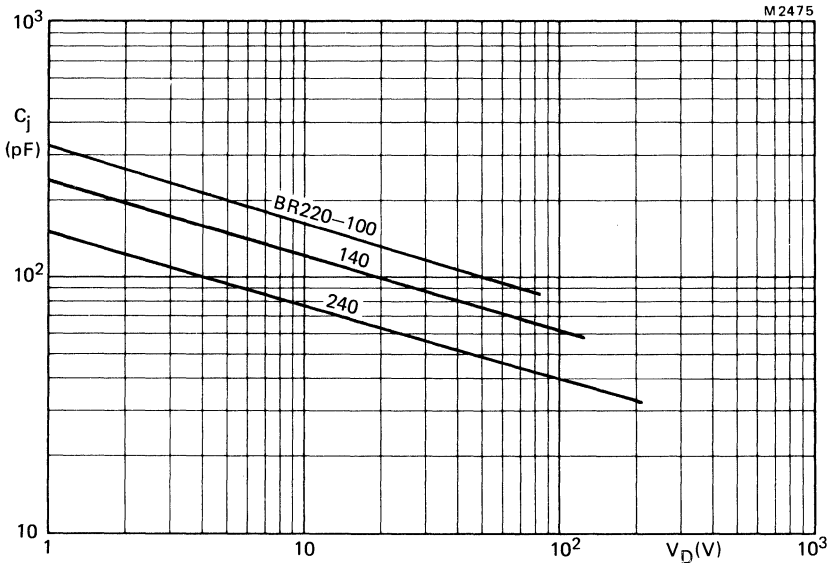


Fig.16 Typical junction capacitance as a function of off-state voltage; $T_j = 25^\circ\text{C}$; $f = 1\text{ MHz}$.

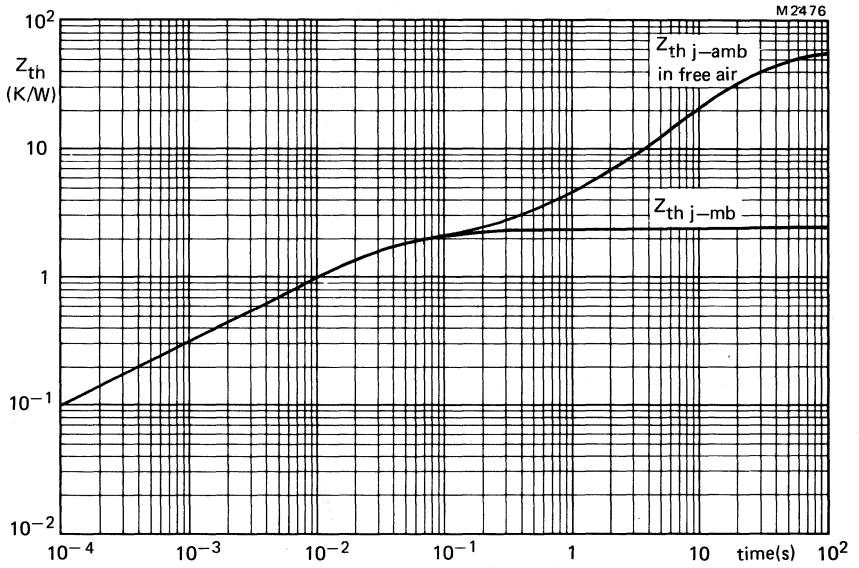


Fig.17 Transient thermal impedance as a function of time (rectangular pulse duration).

REGULATOR DIODES

TRANSIENT SUPPRESSOR DIODES

A range of diffused silicon diodes in a DO-30 metal envelope intended for use in the protection of the electrical and electronic equipment against voltage transients.

The series consists of the following types:

Normal polarity (cathode to stud): BZW86-7V5 to 56

Reverse polarity (anode to stud) : BZW86-7V5R to 56R

QUICK REFERENCE DATA

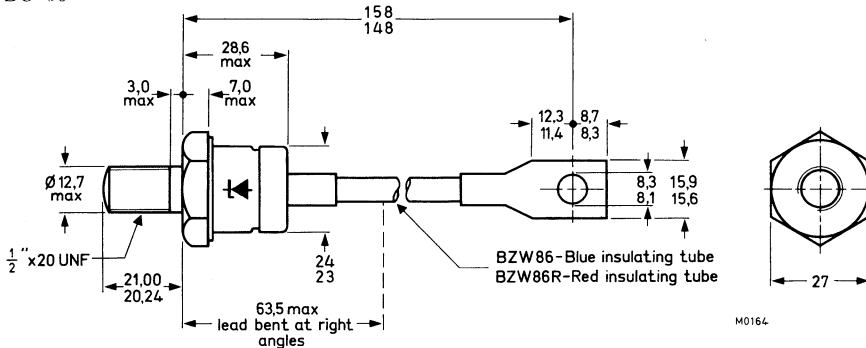
Stand-off voltage (15% range) *	V_R	7,5 to 56	V
Reverse breakdown voltage	$V_{(BR)R}$	9,4 to 64	V
Non-repetitive peak reverse power dissipation; exponential pulse	P_{RSM} max.	25	kW

* The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.

MECHANICAL DATA

Dimensions in mm

DO-30



Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 19 mm

Diameter of clearance hole: max. 13 mm

Net weight: 123 g

The mark shown applies to the normal polarity types.

Torque on nut: min. 9 Nm
(90 kgcm)
max. 17,5 Nm
(175 kgcm)

BZW86

SERIES

RATINGS Limiting values in accordance with the Absolute Maximum System (IEC134)

Stand-off voltage * V_R equal to type number suffix

Currents

Non-repetitive peak reverse current

$T_j = 25\text{ }^\circ\text{C}$ prior to surge

$t_p = 10\text{ }\mu\text{s}$; square pulse

BZW86-9V1(R)

I_{RSM} max. 3700 A

BZW86-27(R)

I_{RSM} max. 1200 A

BZW86-56(R)

I_{RSM} max. 700 A

$t_p = 1\text{ ms}$; exponential pulse

BZW86-9V1(R)

I_{RSM} max. 1200 A

BZW86-27(R)

I_{RSM} max. 400 A

BZW86-56(R)

I_{RSM} max. 250 A

Power dissipation

Repetitive peak reverse power dissipation

$T_{mb} = 65\text{ }^\circ\text{C}$; $f = 50\text{ Hz}$; $t_p = 10\text{ }\mu\text{s}$ (square

pulse; see also graphs on page 664)

P_{RRM} max. 50 kW

Non-repetitive peak reverse power dissipation

$T_j = 25\text{ }^\circ\text{C}$ prior to surge; **exponential**

pulse; see also graph on page 663

$t_p = 100\text{ }\mu\text{s}$

P_{RSM} max. 60 kW

$t_p = 1\text{ ms}$

P_{RSM} max. 25 kW

Temperatures

Storage temperature

T_{stg} -55 to +175 $^\circ\text{C}$

Junction temperature

T_j max. 175 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base

$R_{th\ j-mb} = 0,3\text{ }^\circ\text{C/W}$

From mounting base to heatsink

$R_{th\ mb-h} = 0,1\text{ }^\circ\text{C/W}$

CHARACTERISTICS

Forward voltage

$I_F = 500\text{ A}$ at $T_j = 25\text{ }^\circ\text{C}$

$V_F < 1,5\text{ V}^{**}$

* The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.

** Measured under pulse condition.

CHARACTERISTICS (continued)

	Clamping voltages (exp.pulse) at $T_j = 25^\circ\text{C}$ prior to surge; $t_p = 500 \mu\text{s}$ $V_{(CL)R}$ (V)			Reverse breakdown voltage at $T_j = 25^\circ\text{C}$ $V_{(BR)R}$ (V)	
	typ.	max.		min.	
BZW86 -7V5(R)	12	14		8,5	
-8V2(R)	13	15,5	} $I_R = 1000 \text{ A}$	9,4	} $I_R = 10 \text{ A}$
-9V1(R)	14	17		10,4	
-10(R)	15,5	18,5		11,4	
-11(R)	17	20		12,4	
-12(R)	18,5	22		13,8	
-13(R)	20	24		15,3	
-15(R)	23	27	} $I_R = 500 \text{ A}$	16,8	} $I_R = 5 \text{ A}$
-16(R)	27	32		18,8	
-18(R)	31	36		20,8	
-20(R)	34	40		22,8	
-22(R)	37	43		25,1	
-24(R)	40	47		28	
-27(R)	44	52	} $I_R = 250 \text{ A}$	31	} $I_R = 2 \text{ A}$
-30(R)	47	55		34	
-33(R)	51	60		37	
-36(R)	55	65		40	
-39(R)	60	70		44	
-43(R)	66	77		48	
-47(R)	72	84	52		
-51(R)	78	92	58		
-56(R)	85	102	64		

The maximum clamping voltage is the maximum reverse voltage which appear across the diode at the specified pulse duration and junction temperature.

See curves on pages 666 and 667 for square pulses and pages 668 and 669 for exponential pulses.

CHARACTERISTICS (continued)

$T_j = 25\text{ }^\circ\text{C}$ unless otherwise specified

Peak reverse current

V_{RM} = recommended stand-off voltage $I_{RM} < 2\text{ mA}$

Temperature coefficient of clamping voltage S typ. +0, 1 %/°C

OPERATING NOTES

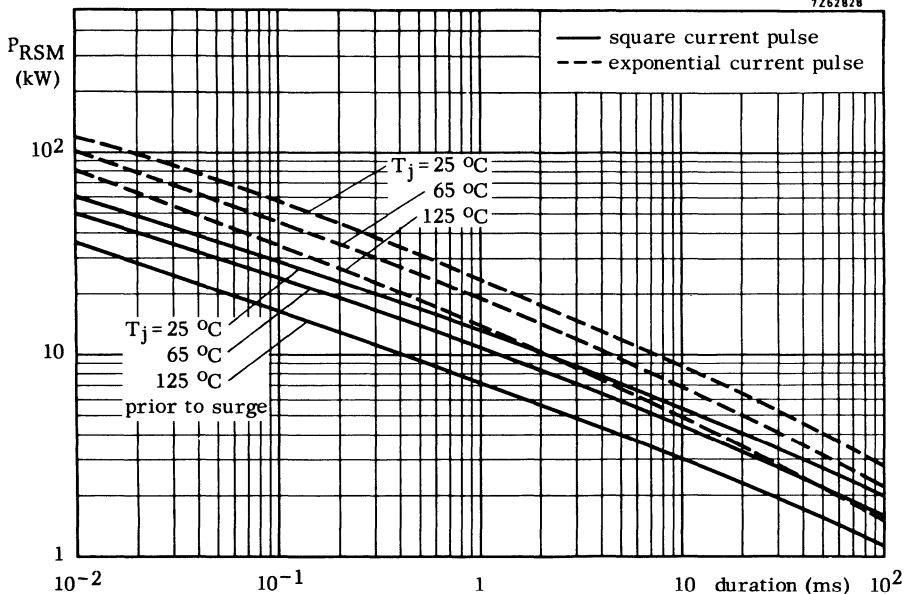
Heatsink considerations

- (a) For non-repetitive transients, the device may be used without a heatsink for pulses up to 10 ms in duration.
- (b) For repetitive transients which fall within the permitted operating range shown in the curves on page 664 the required heatsink is found as follows:

$$R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a} = \frac{T_{j\ max} - T_{amb}}{P_s + \delta \cdot P_{RRM}}$$

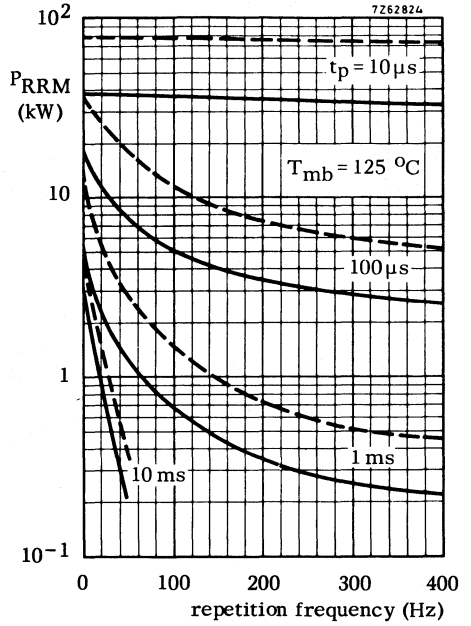
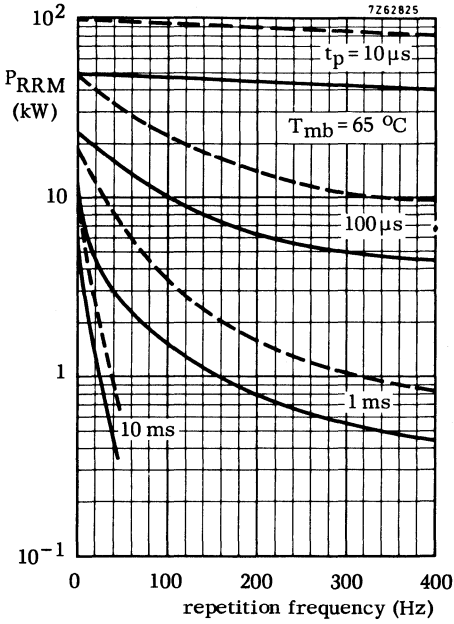
- where $T_{j\ max} = 175\text{ }^\circ\text{C}$
- T_{amb} = ambient temperature
- P_s = any steady state dissipation excluding that in pulses
- δ = duty factor (t_p/T)
- $R_{th\ j-mb} = 0,3\text{ }^\circ\text{C/W}$
- $R_{th\ mb-h} = 0,1\text{ }^\circ\text{C/W}$
- thus $R_{th\ h-a}$ can be found.

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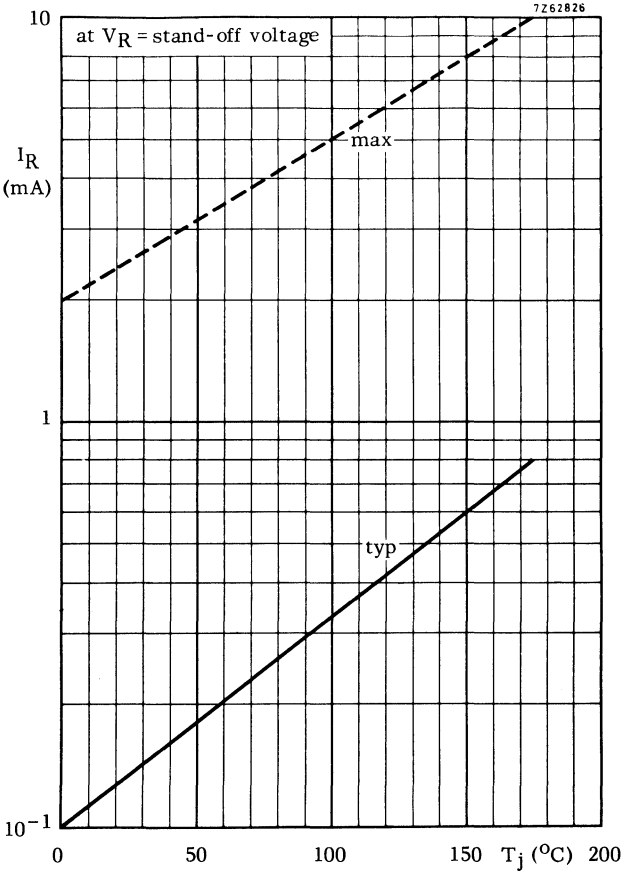
Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that the energy content does not continue beyond twice this time.

BZW86
SERIES

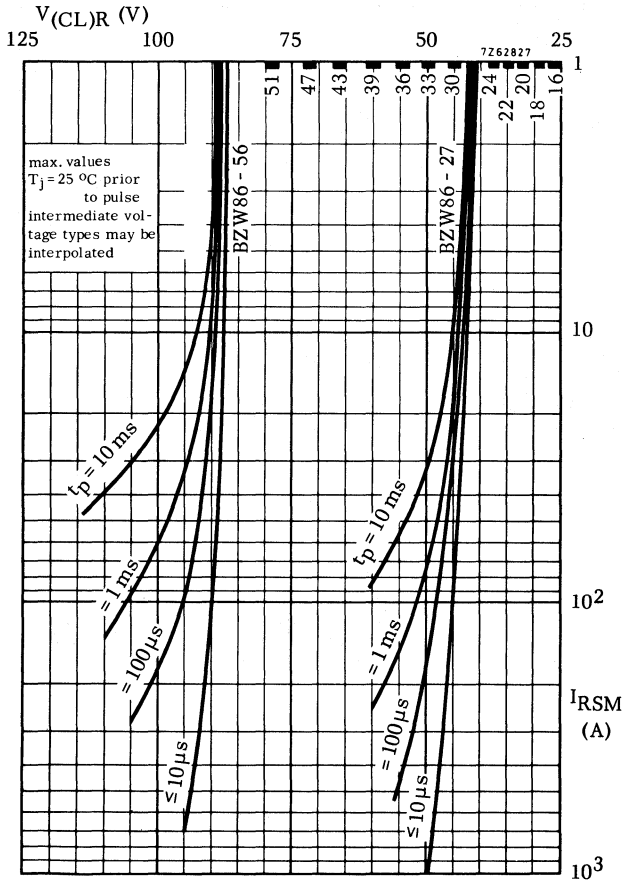


- square current pulses
- - - exponential current pulses

BZW86
SERIES

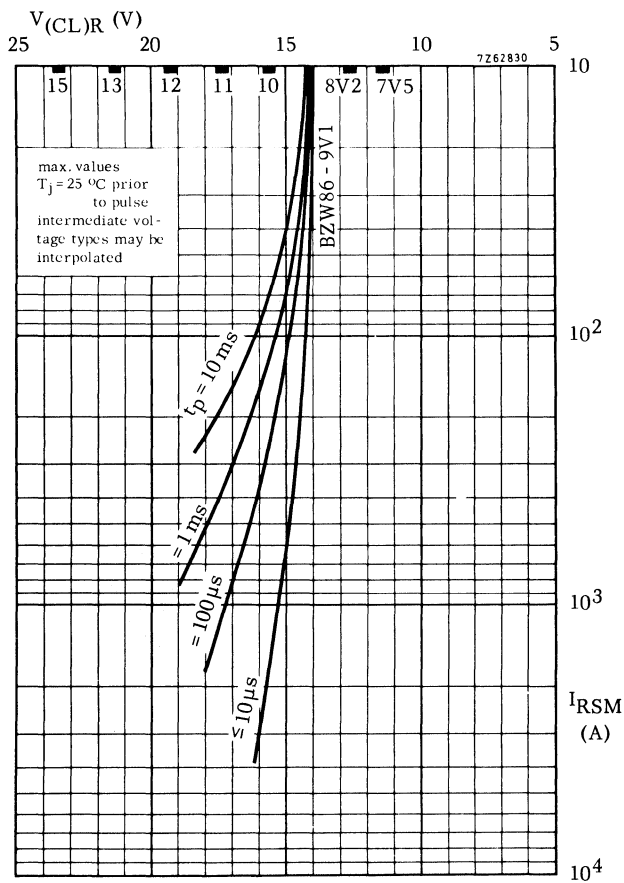


BZW86
SERIES



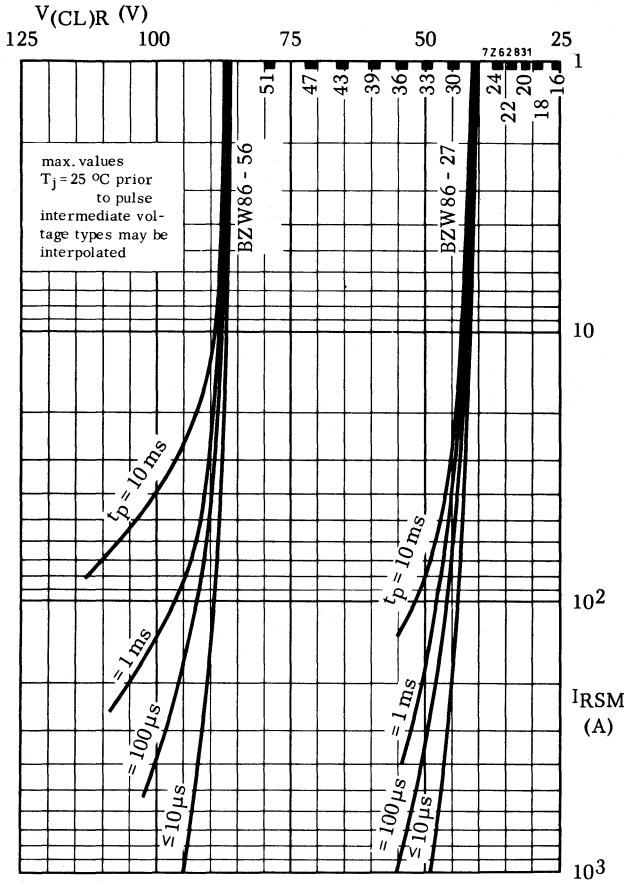
square pulses

BZW86 SERIES

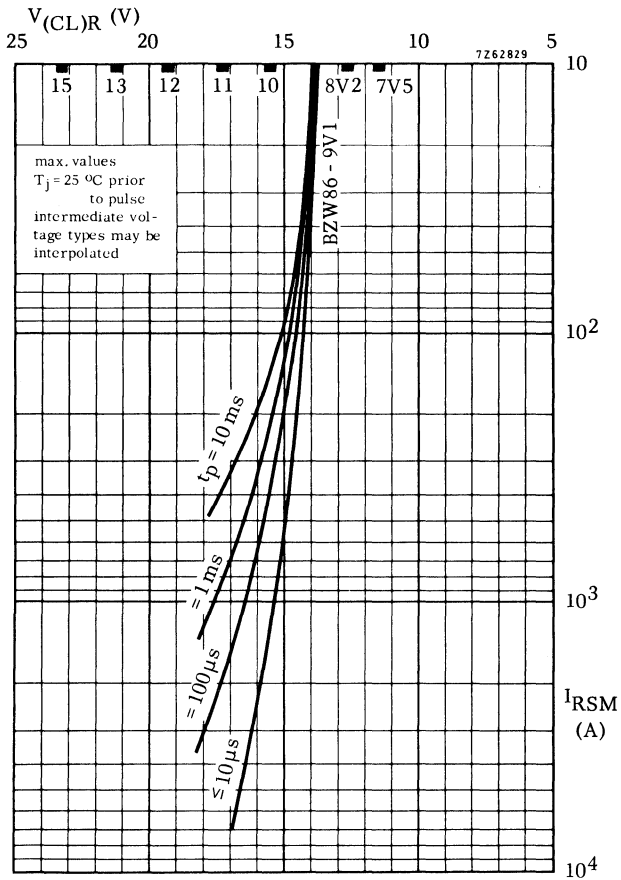


square pulses

BZW86
SERIES



exponential pulses



exponential pulses

REGULATOR DIODES



A range of diffused silicon diodes in plastic envelopes, intended for use as voltage regulator and transient suppressor diodes in medium power regulators and transient suppression circuits.

The series consists of the following types: BZX70-C7V5 to BZX70-C75.

QUICK REFERENCE DATA

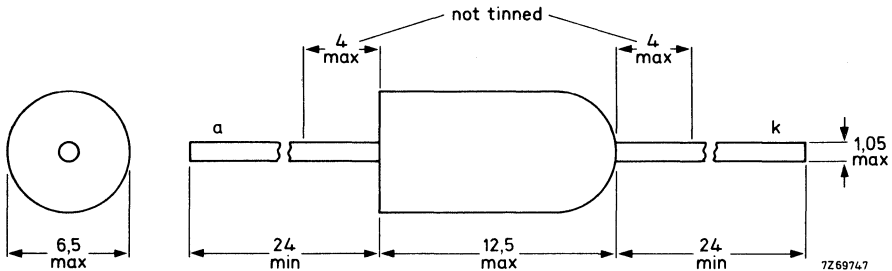
			voltage regulator		transient suppressor	
Working voltage (5% range)	V_Z	nom.	7,5 to 75	—	—	V
Stand-off voltage	V_R		—	5,6 to 56	—	V
Total power dissipation	P_{tot}	max.	2,5	—	—	W
Non-repetitive peak reverse power dissipation	P_{RSM}	max.	—	700	—	W

MECHANICAL DATA

Dimensions in mm

Fig. 1 SOD-18.

The rounded end indicates the cathode.



RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Peak working current	I_{ZM}	max.	5 A
Average forward current (averaged over any 20 ms period)	$I_F(AV)$	max.	1 A
Non-repetitive peak reverse current $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse); BZX70-C7V5 to BZX70-C75	I_{RSM}	max.	44 to 6 A
Total power dissipation at $T_{amb} = 25\text{ }^\circ\text{C}$; with 10 mm tie-points; Fig. 5	P_{tot}	max.	2,5 W
Non-repetitive peak reverse power dissipation $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse)	P_{RSM}	max.	700 W
Storage temperature	T_{stg}		-55 to + 150 $^\circ\text{C}$
Junction temperature	T_j	max.	150 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to ambient in free air see Figs 4 and 5

CHARACTERISTICS

Forward voltage $I_F = 1\text{ A}$; $T_{amb} = 25\text{ }^\circ\text{C}$	V_F	<	1,5 V
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OPERATION AS A VOLTAGE REGULATOR (see page 4)

Dissipation and heatsink considerations

a. Steady-state conditions

The maximum permissible steady-state dissipation $P_{s \max}$ is given by the relationship

$$P_{s \max} = \frac{T_{j \max} - T_{\text{amb}}}{R_{\text{th } j-a}}$$

where: $T_{j \max}$ is the maximum permissible operating junction temperature T_{amb} is the ambient temperature $R_{\text{th } j-a}$ is the total thermal resistance from junction to ambient

b. Pulse conditions (see Fig. 2)

The maximum permissible pulse power $P_{p \max}$ is given by the formula

$$P_{p \max} = \frac{(T_{j \max} - T_{\text{amb}}) - (P_s \cdot R_{\text{th } t})}{R_{\text{th } t}}$$

where: P_s is any steady-state dissipation excluding that in pulses $R_{\text{th } t}$ is the effective transient thermal resistance of the device between junction and ambient.It is a function of the pulse duration t_p and duty factor δ . δ is the duty factor (t_p/T)

The steady-state power P_s when biased in the zener direction at a given zener current can be found from Fig. 3. With the additional pulse power dissipation $P_{p \max}$ calculated from the above expression, the total peak zener power dissipation $P_{\text{tot}} = P_{\text{ZRM}} = P_s + P_p$. From Fig. 3 the corresponding maximum repetitive peak zener current at P_{tot} can now be read. This repetitive peak zener current is subject to the absolute maximum rating. For pulse durations longer than the temperature stabilization time of the diode t_{stab} , the maximum permissible repetitive peak dissipation P_{ZRM} is equal to the steady-state power P_s . The temperature stabilization time for the BZX70 is 100 seconds (see Figs 17 and 18).

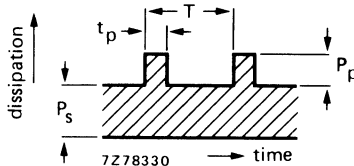


Fig. 2.

NOTES WHEN OPERATING AS A TRANSIENT SUPPRESSOR (see page 675)

1. Recommended stand-off voltage is defined as being the maximum reverse voltage to be applied without causing conduction in the avalanche mode or significant reverse dissipation.
2. Maximum clamping voltage is the maximum reverse avalanche breakdown voltage which will appear across the diode at the specified pulse duration and junction temperature. For square pulses see Figs 19 and 20, for exponential pulses see Figs 21 and 22.
3. Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that energy content does not continue beyond twice this time.

BZX70 SERIES

CHARACTERISTICS – WHEN USED AS VOLTAGE REGULATOR DIODES; $T_{amb} = 25\text{ }^{\circ}\text{C}$

BZX70...	working voltage $*V_Z$ V		differential resistance $*r_Z$ Ω		temperature coefficient $*S_Z$ mV/ $^{\circ}\text{C}$	test I_Z mA	reverse current ^{at} I_R μA	reverse voltage V_R V
	min.	max.	typ.	max.	typ.		max.	
C7V5	7.0	7.9	0.45	3.5	3.0	50	50	2.0
C8V2	7.7	8.7	0.45	3.5	4.0	50	20	5.6
C9V1	8.5	9.6	0.55	4.0	5.5	50	10	6.2
C10	9.4	10.6	0.75	4.0	7.0	50	10	6.8
C11	10.4	11.6	0.8	4.5	7.5	50	10	7.5
C12	11.4	12.7	0.85	5.0	8.0	50	10	8.2
C13	12.4	14.1	0.9	6.0	8.5	50	10	9.1
C15	13.8	15.6	1.0	8.0	10	50	10	10
C16	15.3	17.1	2.4	9.0	11	20	10	11
C18	16.8	19.1	2.5	11	12	20	10	12
C20	18.8	21.2	2.8	12	14	20	10	13
C22	20.8	23.3	3.0	13	16	20	10	15
C24	22.7	25.9	3.4	14	18	20	10	16
C27	25.1	28.9	3.8	18	20	20	10	18
C30	28	32	4.5	22	25	20	10	20
C33	31	35	5.0	25	30	20	10	22
C36	34	38	5.5	30	32	20	10	24
C39	37	41	12	35	35	10	10	27
C43	40	46	13	40	40	10	10	30
C47	44	50	14	50	45	10	10	33
C51	48	54	15	55	50	10	10	36
C56	52	60	17	63	55	10	10	39
C62	58	66	18	75	60	10	10	43
C68	64	72	18	90	65	10	10	47
C75	70	79	20	100	70	10	10	51

*At test I_Z : measured using a pulse method with $t_p \leq 100\text{ }\mu\text{s}$ and $\delta \leq 0.001$ so that the values correspond to a T_j of approximately $25\text{ }^{\circ}\text{C}$.

CHARACTERISTICS – WHEN USED AS TRANSIENT SUPPRESSOR DIODES; $T_{amb} = 25\text{ }^{\circ}\text{C}$

clamping voltage at $t_p = 500\text{ }\mu\text{s}$ exp. pulse $V_{(CL)R}$ V		non-repetitive peak reverse current I_{RSM} A	reverse current at recommended stand-off voltage I_R mA		V_R V	BZX70-...
typ.	max.		max.			
9	10	20	0.5	5.6		C7V5
10	11.2	20	0.5	6.2		C8V2
11	12.5	20	0.5	6.8		C9V1
12	14	20	0.1	7.5		C10
13.5	15.5	20	0.1	8.2		C11
15	17.5	20	0.1	9.1		C12
17	19	20	0.1	10		C13
19	21	20	0.1	11		C15
21	23	20	0.1	12		C16
23	26	20	0.1	13		C18
22	26	10	0.1	15		C20
25	29	10	0.1	16		C22
28	33	10	0.1	18		C24
32	38	10	0.1	20		C27
36	43	10	0.1	22		C30
41	48	10	0.1	24		C33
47	54	10	0.1	27		C36
44	52	5	0.1	30		C39
49	58	5	0.1	33		C43
56	65	5	0.1	36		C47
63	72	5	0.1	39		C51
71	82	5	0.1	43		C56
80	93	5	0.1	47		C62
89	104	5	0.1	51		C68
98	116	5	0.1	56		C75

SOLDERING AND MOUNTING INSTRUCTIONS

1. When using a soldering iron, diodes may be soldered directly into the circuit, but heat conducted to the junction should be kept to a minimum.
2. Diodes may be dip-soldered at a solder temperature of 245 °C for a maximum soldering time of 5 seconds. The case temperature during dip-soldering must not at any time exceed the maximum storage temperature. These recommendations apply to a diode with the anode end mounted flush on a printed-circuit board having punched-through holes. For mounting the anode end onto a printed-circuit board, the diode must be spaced at least 5 mm from the underside of the printed-circuit board having punched-through holes, or 5 mm from the top of the printed circuit board having plated-through holes.
3. Care should be taken not to bend the leads nearer than 1,5 mm from the seal; exert no axial pull when bending.

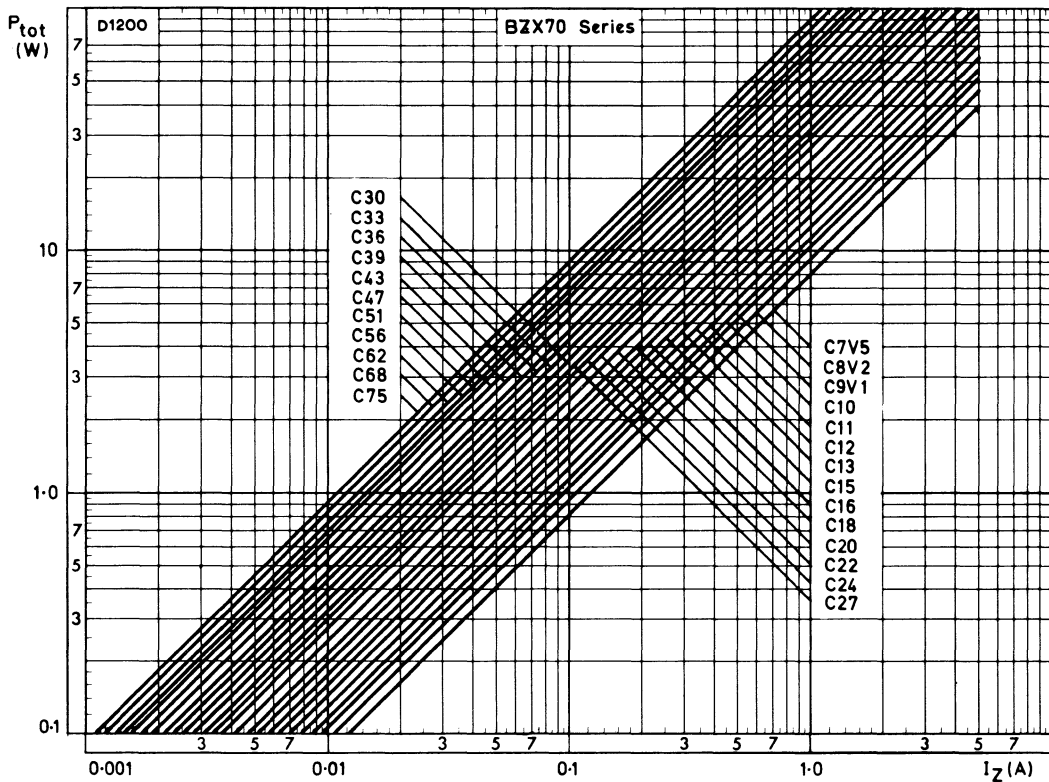


Fig. 3 Maximum permissible repetitive peak dissipation ($P_{tot} = P_{ZRM}$).

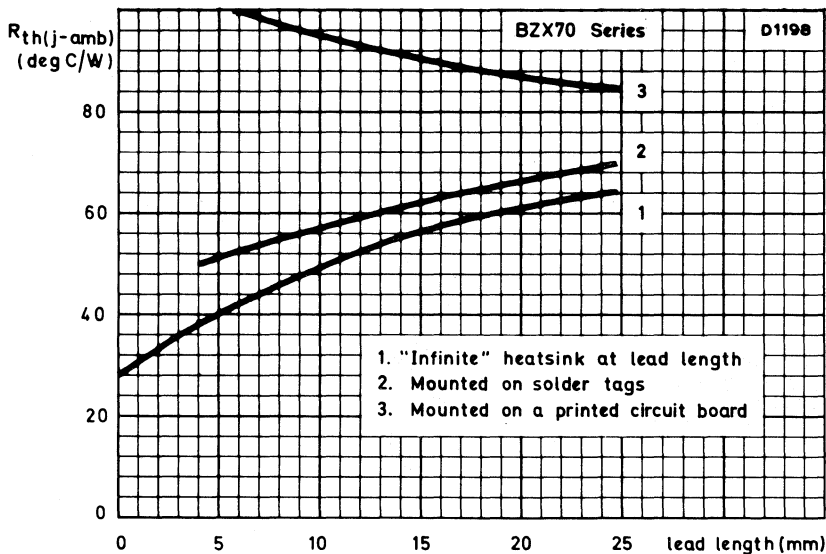


Fig. 4 Thermal resistance as a function of lead length under various mounting conditions.

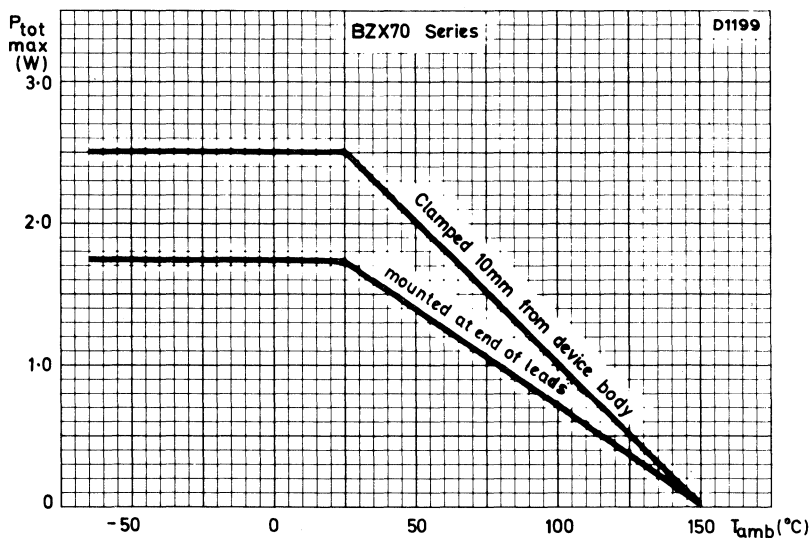


Fig. 5 Maximum permissible power dissipation; the top curve is for mounting method 1 from Fig. 4 at 10 mm lead length.

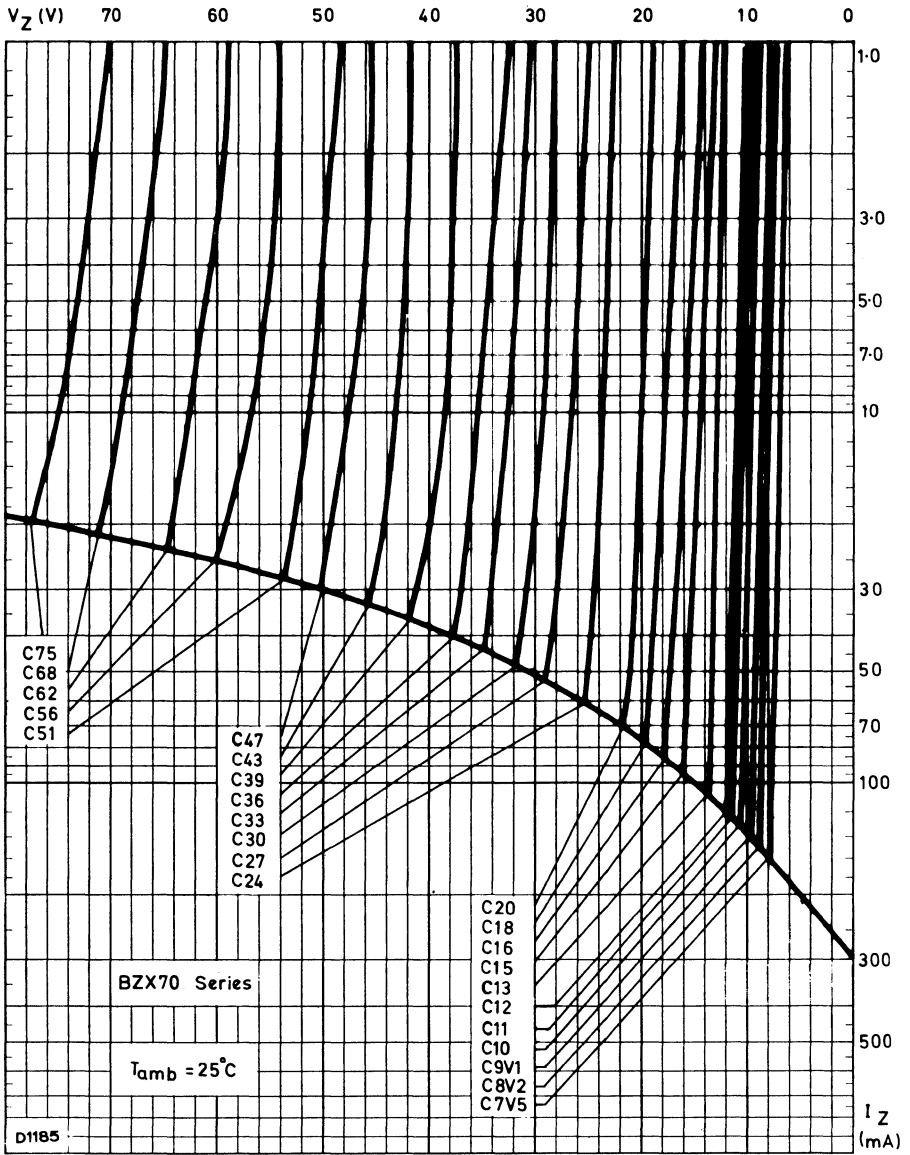


Fig. 6 Typical static zener characteristics.

BZX70 SERIES

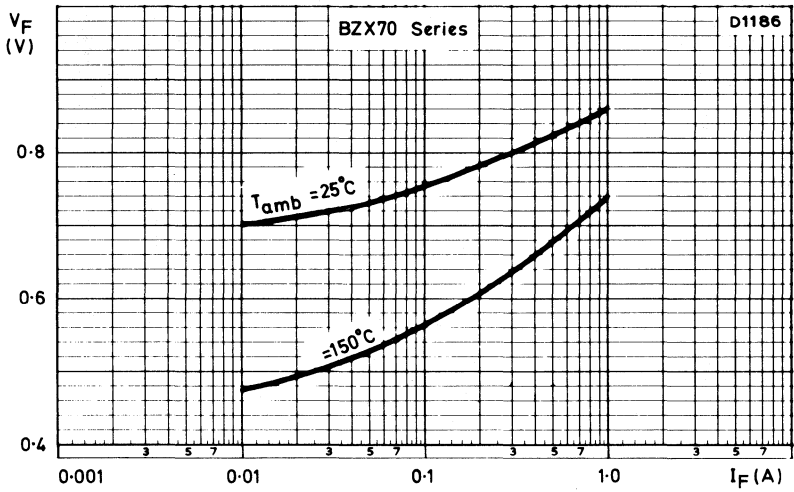


Fig. 7.

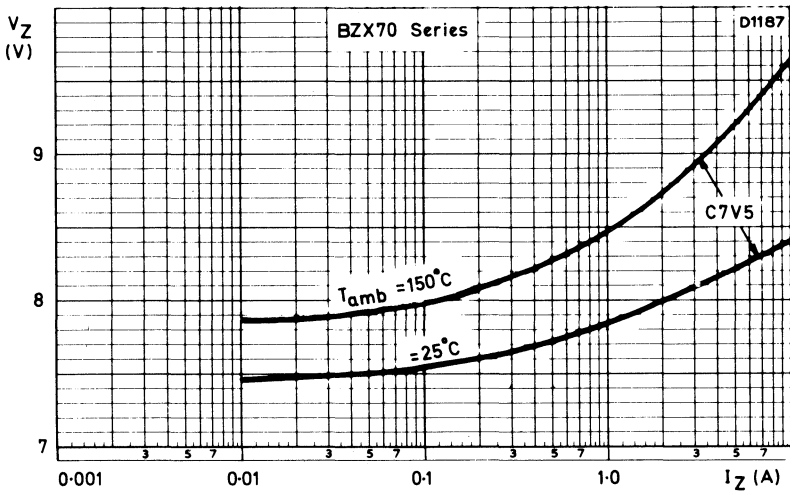


Fig. 8 Typical dynamic zener characteristics for BZX70-C7V5.

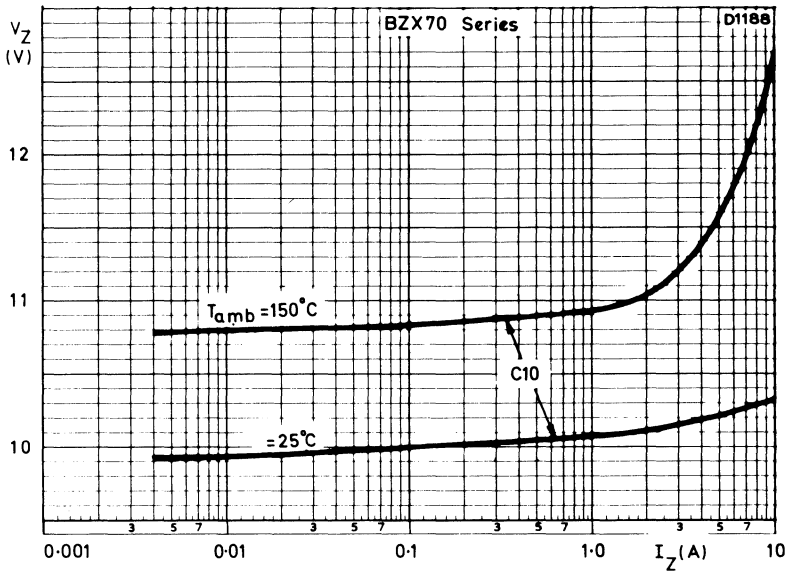


Fig. 9 Typical dynamic zener characteristics for BZX70-C10.

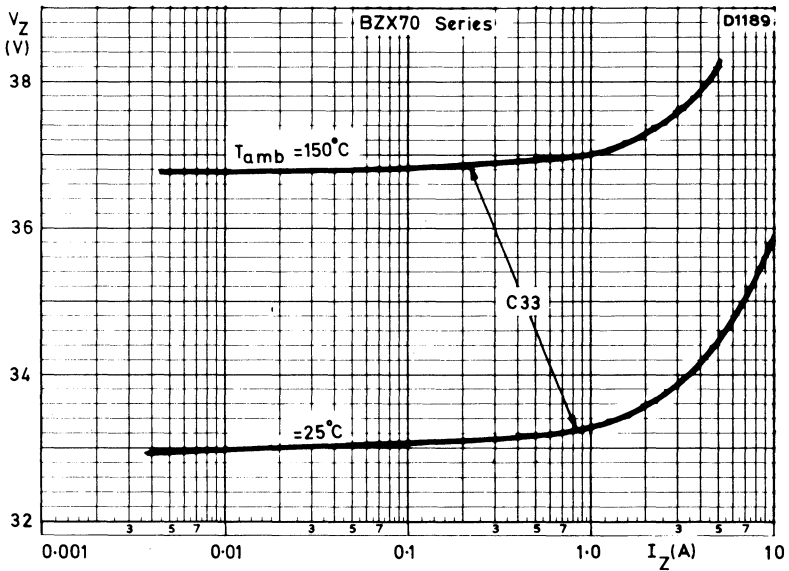


Fig. 10 Typical dynamic zener characteristics for BZX70-C33.

BZX70 SERIES

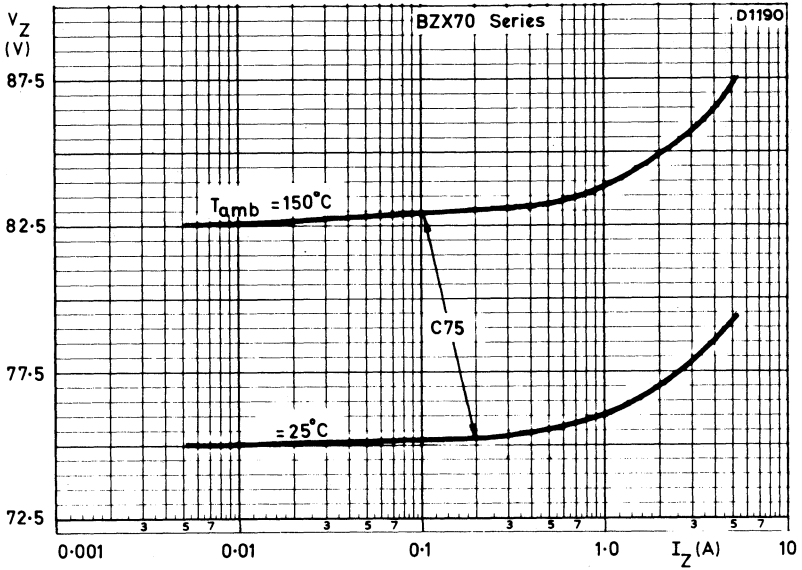


Fig. 11 Typical dynamic zener characteristics for BZX70-C75.

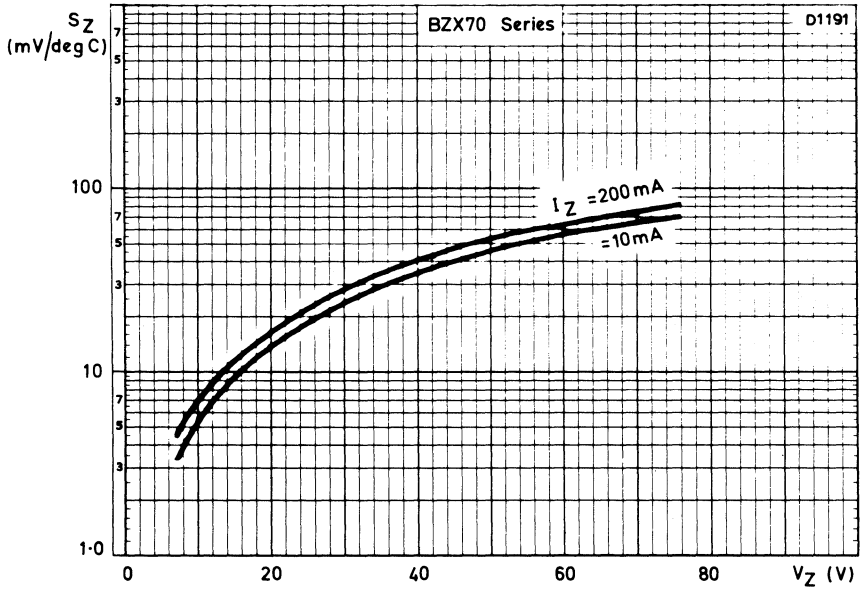


Fig. 12.

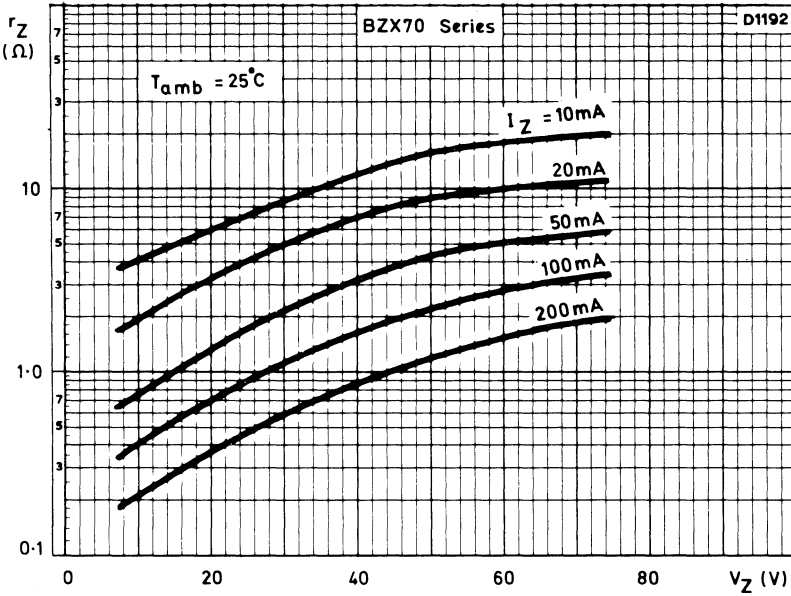


Fig. 13.

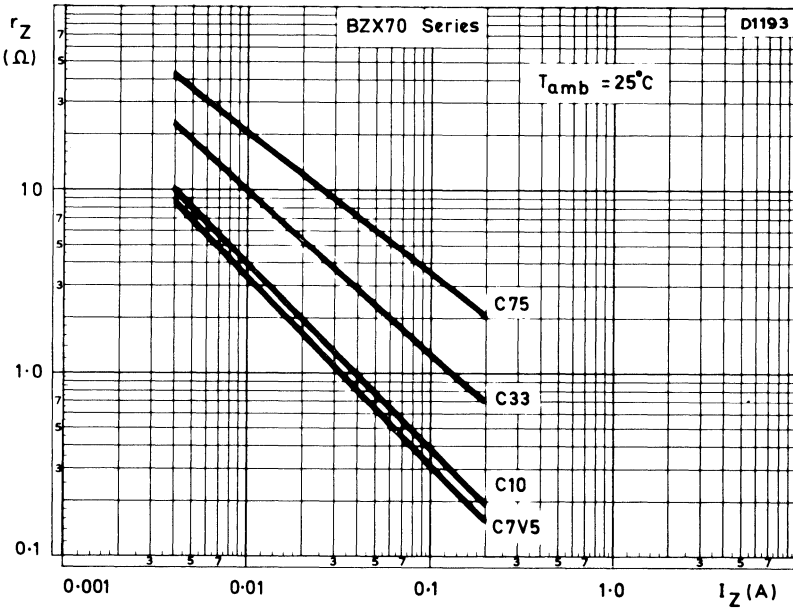


Fig. 14.

BZX70 SERIES

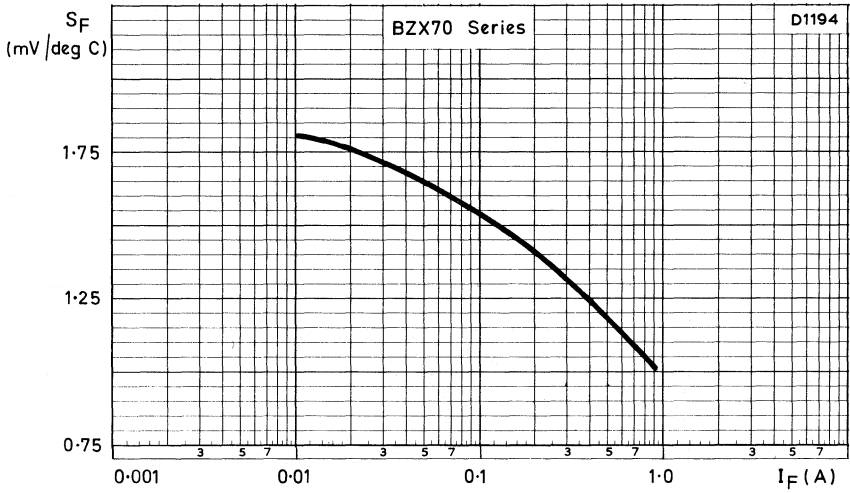


Fig. 15 Typical values.

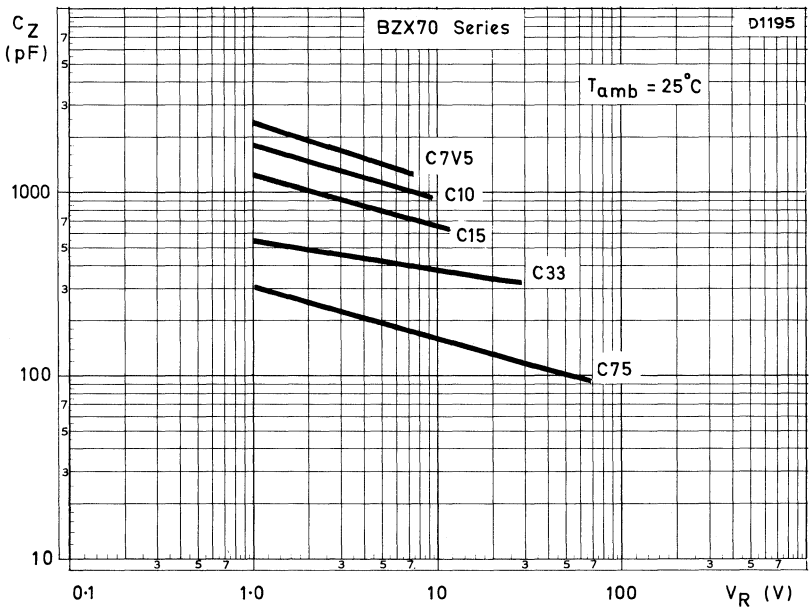


Fig. 16 Typical values.

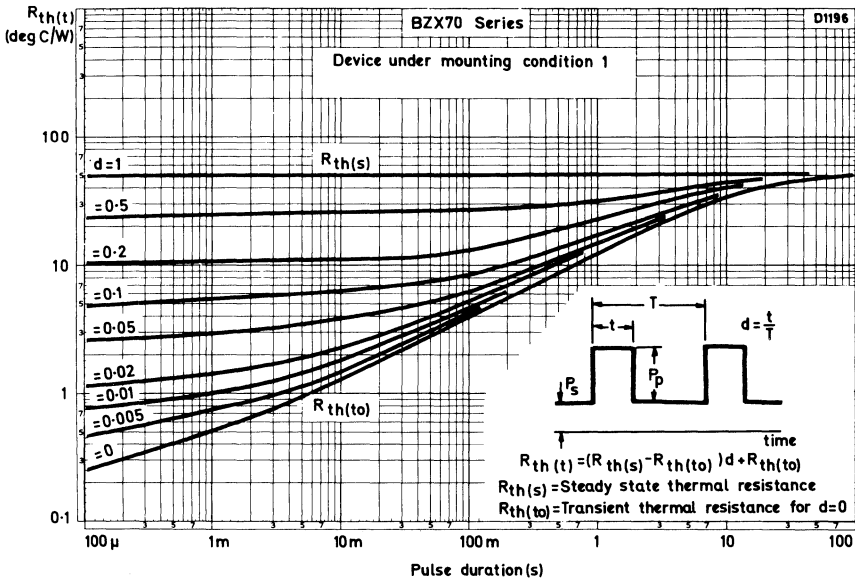


Fig. 17 Device under mounting condition 1 (infinite heatsink); see Fig. 4.

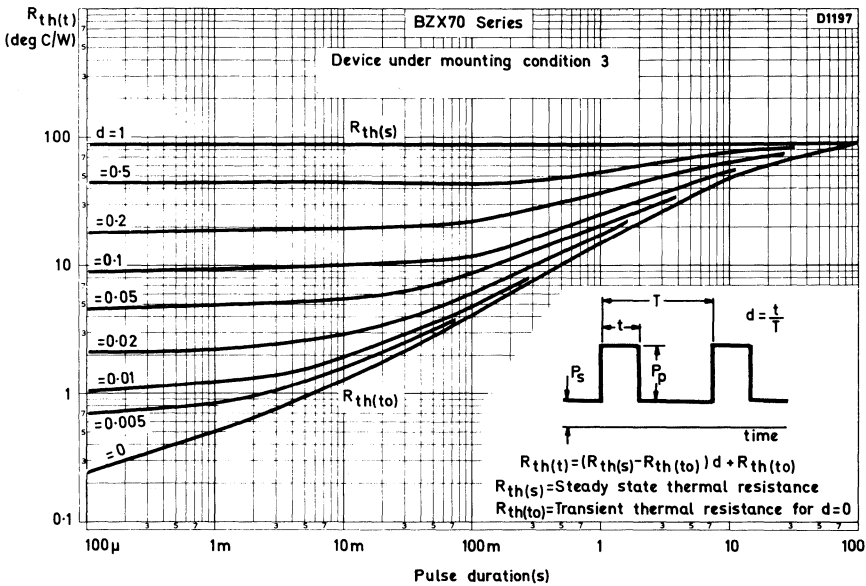


Fig. 18 Device under mounting method 3 (mounted on a printed-circuit board); see Fig. 4.

BZX70 SERIES

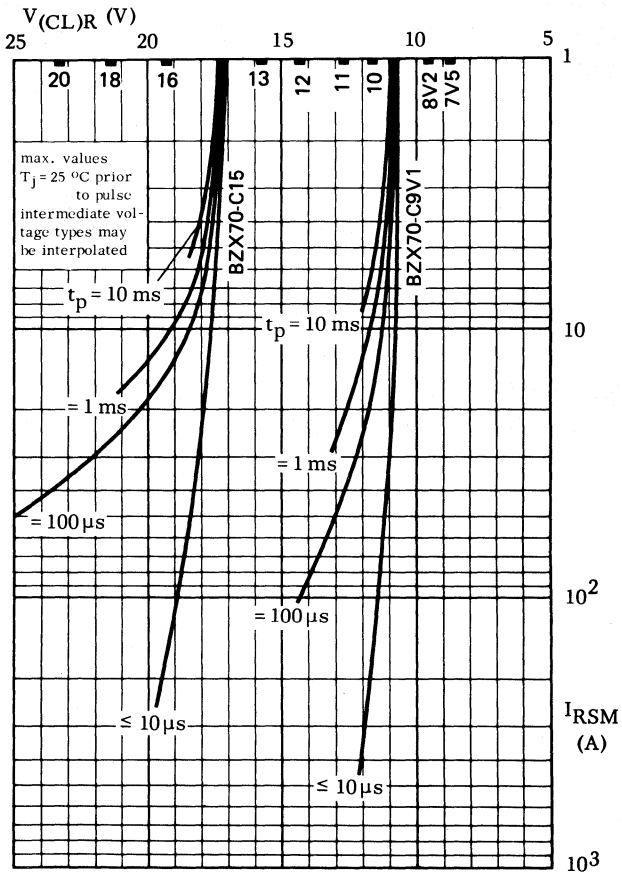


Fig. 19 Square pulses.

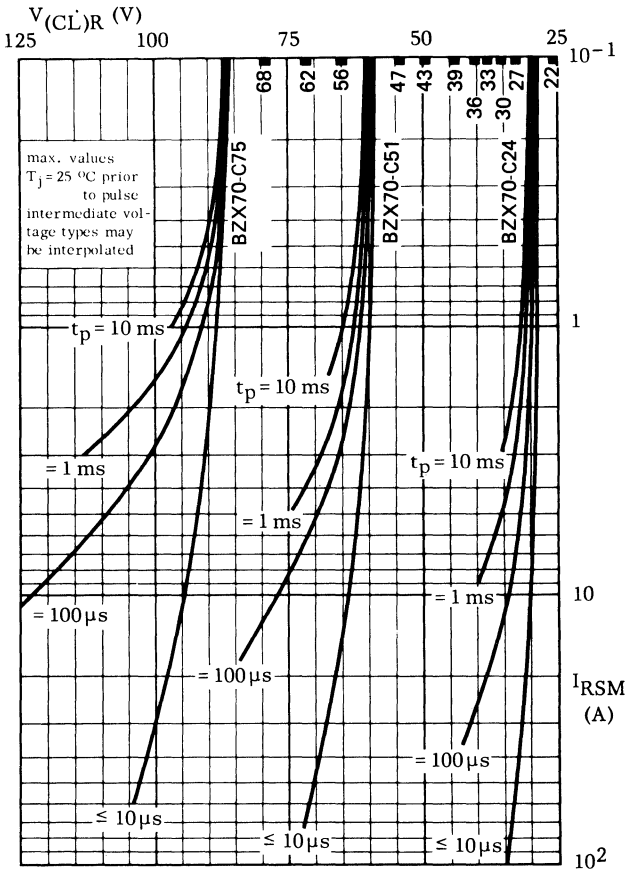


Fig. 20 Square pulses.

BZX70 SERIES

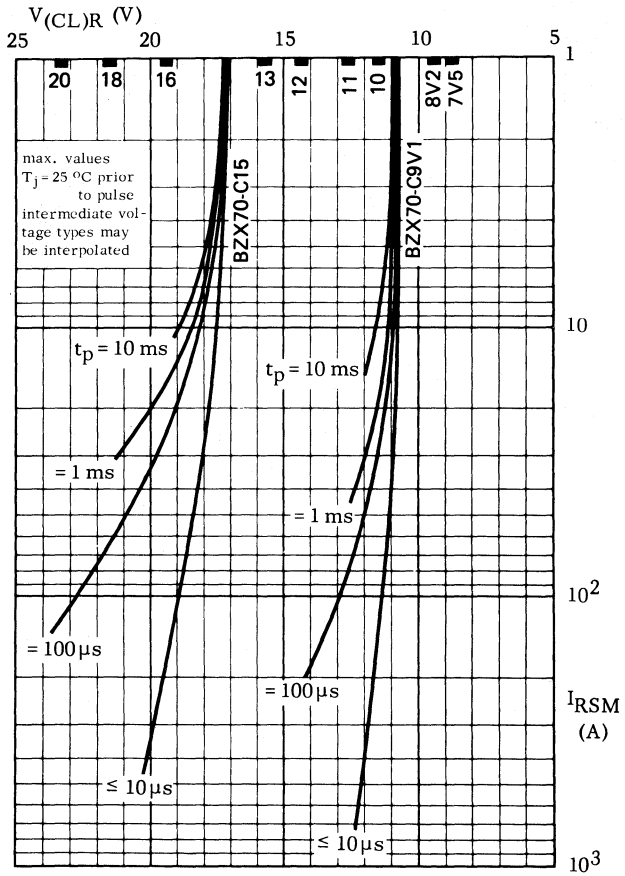


Fig. 21 Exponential pulses.

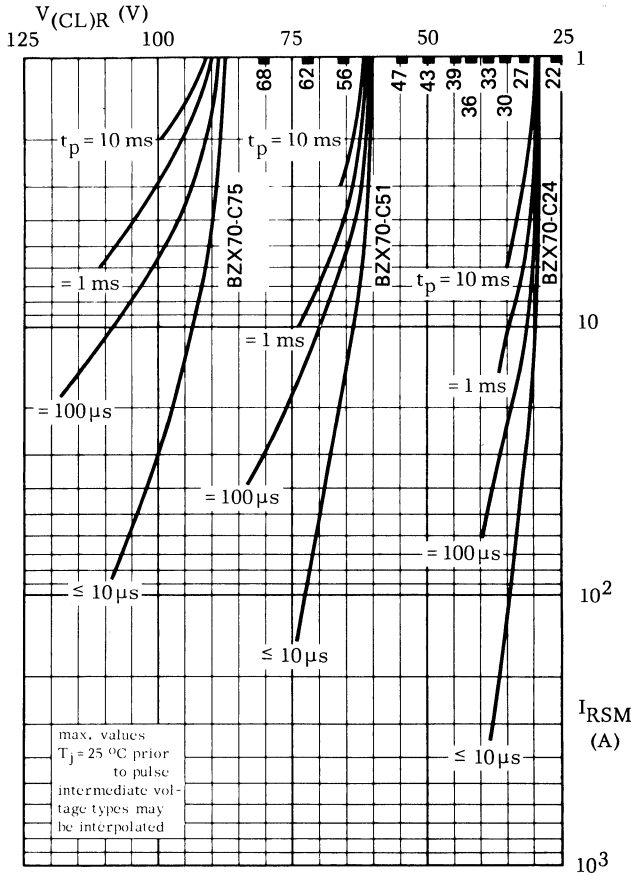


Fig. 22 Exponential pulses.

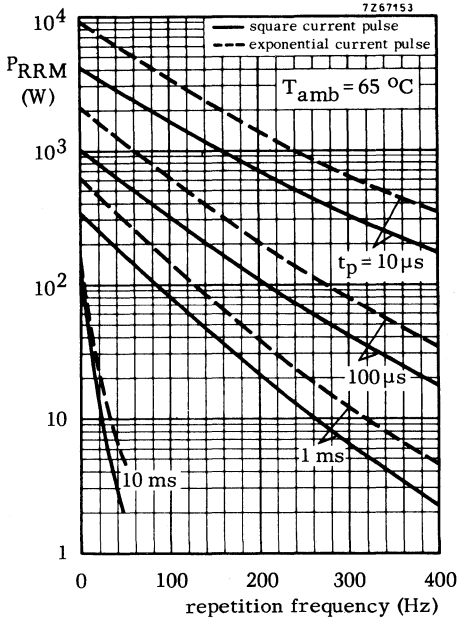


Fig. 23.

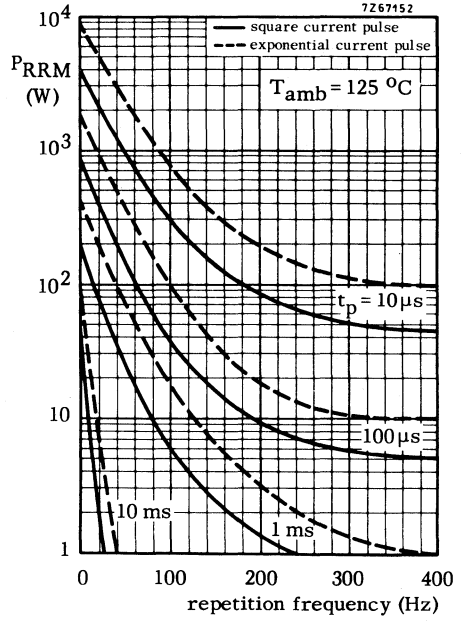


Fig. 24.

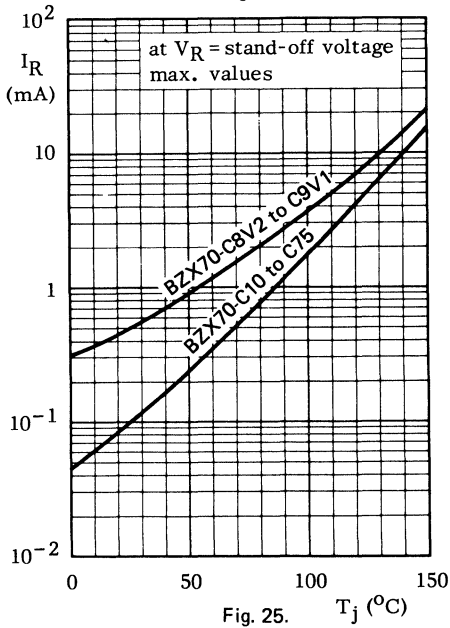


Fig. 25.

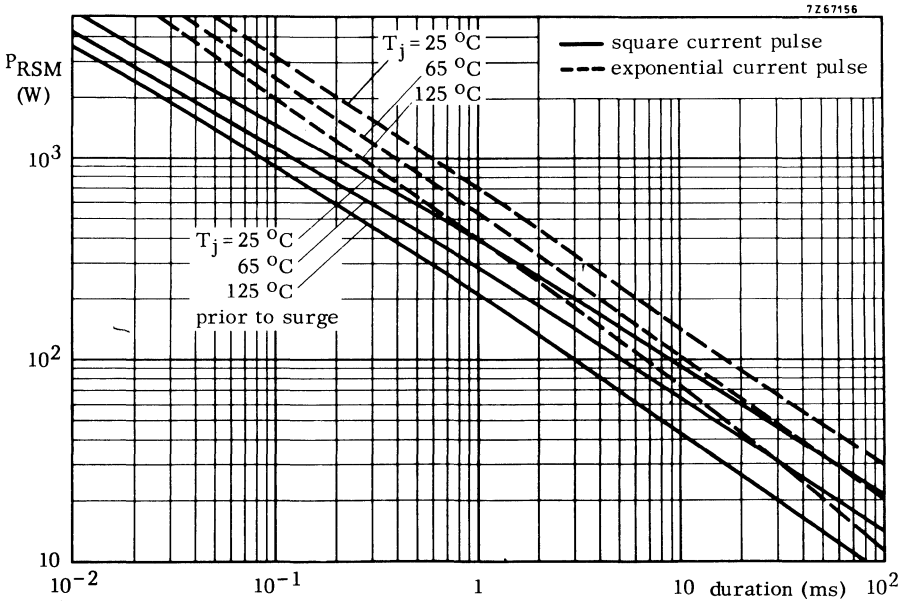


Fig. 26.

REGULATOR DIODES

Also available to BS9305-F052

A range of diffused silicon diodes in DO-5 metal envelopes, intended for use as voltage regulator and transient suppressor diodes in power stabilization and transient suppression circuits.

The series consists of the following types:

Normal polarity (cathode to stud): BZY91-C7V5 to BZY91-C75.

Reverse polarity (anode to stud): BZY91-C7V5R to BZY91-C75R.

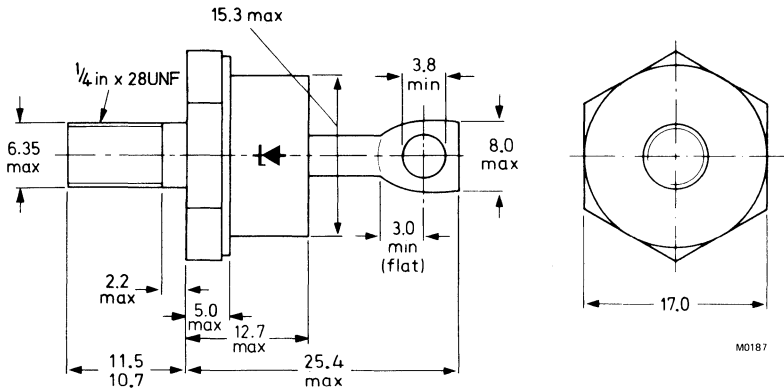
QUICK REFERENCE DATA

		voltage regulator		transient suppressor	
Working voltage (5% range)	V_Z nom.	7,5 to 75	—	V	
Stand-off voltage	V_R	—	5,6 to 56	V	
Total power dissipation	P_{tot} max.	100	—	W	
Non-repetitive peak reverse power dissipation	$PRSM$ max.	—	9,5	kW	

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-5.



Net mass: 22 g

Diameter of clearance hole: max. 6,5 mm

Accessories supplied on request:
see ACCESSORIES section

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 11,1 mm

Torque on nut: min. 1,7 Nm (17 kg cm)
max. 3,5 Nm (35 kg cm)

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Peak working current	I_{ZM}	max.	400 A
Average forward current (averaged over any 20 ms period)	$I_F(AV)$	max.	20 A
Non-repetitive peak reverse current $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse); BZY91-C7V5(R) to BZY91-C75(R)	I_{RSM}	max.	1000 to 85 A
Total power dissipation up to $T_{mb} = 25\text{ }^\circ\text{C}$ at $T_{mb} = 65\text{ }^\circ\text{C}$	P_{tot}	max.	100 W
	P_{tot}	max.	75 W
Non-repetitive peak reverse power dissipation $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse)	P_{RSM}	max.	9,5 kW
Storage temperature	T_{stg}		-55 to + 175 $^\circ\text{C}$
Junction temperature	T_j	max.	175 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	1,5 $^\circ\text{C/W}$
From mounting base to heatsink	$R_{th\ mb-h}$	=	0,2 $^\circ\text{C/W}$

CHARACTERISTICS

Forward voltage $I_F = 10\text{ A}$; $T_{mb} = 25\text{ }^\circ\text{C}$	V_F	<	1,5 V
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OPERATION AS A VOLTAGE REGULATOR (see page 696)

Dissipation and heatsink considerations

a. Steady-state conditions

The maximum permissible steady-state dissipation $P_{s\ max}$ is given by the relationship

$$P_{s\ max} = \frac{T_{j\ max} - T_{amb}}{R_{th\ j-a}}$$

where: $T_{j\ max}$ is the maximum permissible operating junction temperature

T_{amb} is the ambient temperature

$R_{th\ j-a}$ is the total thermal resistance from junction to ambient

$$R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$$

$R_{th\ mb-h}$ is the thermal resistance from mounting base to heatsink, that is, 0,2 $^\circ\text{C/W}$.

$R_{th\ h-a}$ is the thermal resistance of the heatsink.

b. Pulse conditions (see Fig. 2)

The heating effect of repetitive power pulses can be found from the curves in Figs 5 and 6 which are given for operation as a transient suppressor at 50 Hz and 400 Hz respectively. This value ΔT is in addition to the mean heating effect. The value of ΔT found from the curves for the particular operating condition should be added to the known value for ambient temperature used in calculating the required heatsink.

The value of the peak power for a given peak zener current is found from the curves in Figs 3 and 4.

Regulator diodes

The required heatsink is calculated as follows:

$$R_{th\ j-a} = \frac{T_{j\ max} - T_{amb} - \Delta T}{P_s + \delta \cdot P_p}$$

- where: $T_{j\ max} = 175\ ^\circ C$
- T_{amb} = ambient temperature
- ΔT = from Fig. 5 or 6
- P_s = any steady-state dissipation excluding that in pulses
- P_p = peak pulse power
- δ = duty factor (t_p/T)
- $R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a} = 1,5 + 0,2 + R_{th\ h-a}\ ^\circ C/W.$

Thus $R_{th\ h-a}$ can be found.

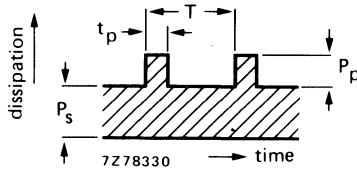


Fig. 2.

OPERATION AS A TRANSIENT SUPPRESSOR (see page 697)

Heatsink considerations

- a. For non-repetitive transients, the device may be used without a heatsink for pulses up to 10 ms in duration.
- b. For repetitive transients which fall within the permitted operating range shown in Figs 26 and 27 the required heatsink is found as follows:

$$R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a} = \frac{T_{j\ max} - T_{amb}}{P_s + \delta \cdot P_{RRM}}$$

- where: $T_{j\ max} = 175\ ^\circ C$
- T_{amb} = ambient temperature
- P_s = any steady-state dissipation excluding that in pulses
- δ = duty factor (t_p/T)
- $R_{th\ j-mb} = 1,5\ ^\circ C/W$
- $R_{th\ mb-h} = 0,2\ ^\circ C/W$

Thus $R_{th\ h-a}$ can be found.

Notes

- 1. The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.
- 2. The maximum clamping voltage is the maximum reverse voltage which appears across the diode at the specified pulse duration and junction temperature. For square pulses see Figs 22 and 23, for exponential pulses see Figs 24 and 25.
- 3. Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that the energy content does not continue beyond twice this time.
- 4. Surge suppressor diodes are extremely fast in clamping, switching on in less than 5 ns.

BZY91 SERIES

CHARACTERISTICS – WHEN USED AS VOLTAGE REGULATOR DIODES; $T_{mb} = 25\text{ }^{\circ}\text{C}$

BZY91-...	working voltage *V _Z V		differential resistance *r _Z Ω	temperature coefficient *S _Z %/ $^{\circ}\text{C}$	test I _Z A	reverse current I _R mA	reverse voltage V _R V
	min.	max.	max.	typ.		max.	
C7V5(R)	7.0	7.9	0.2	0.09	5.0	5.0	2.0
C8V2(R)	7.7	8.7	0.3	0.09	5.0	5.0	5.6
C9V1(R)	8.5	9.6	0.4	0.07	2.0	5.0	6.2
C10(R)	9.4	10.6	0.4	0.07	2.0	1.0	6.8
C11(R)	10.4	11.6	0.4	0.07	2.0	1.0	7.5
C12(R)	11.4	12.7	0.5	0.07	2.0	1.0	8.2
C13(R)	12.4	14.1	0.5	0.07	2.0	1.0	9.1
C15(R)	13.8	15.6	0.6	0.075	2.0	1.0	10
C16(R)	15.3	17.1	0.6	0.075	2.0	1.0	11
C18(R)	16.8	19.1	0.7	0.075	2.0	1.0	12
C20(R)	18.8	21.2	0.8	0.075	1.0	1.0	13
C22(R)	20.8	23.3	0.8	0.075	1.0	1.0	15
C24(R)	22.7	25.9	0.9	0.08	1.0	1.0	16
C27(R)	25.1	28.9	1.0	0.082	1.0	1.0	18
C30(R)	28	32	1.1	0.085	1.0	1.0	20
C33(R)	31	35	1.2	0.088	1.0	1.0	22
C36(R)	34	38	1.3	0.09	1.0	1.0	24
C39(R)	37	41	1.4	0.09	0.5	1.0	27
C43(R)	40	46	1.5	0.092	0.5	1.0	30
C47(R)	44	50	1.7	0.093	0.5	1.0	33
C51(R)	48	54	1.8	0.093	0.5	1.0	36
C56(R)	52	60	2.0	0.094	0.5	1.0	39
C62(R)	58	66	2.2	0.094	0.5	1.0	43
C68(R)	64	72	2.4	0.094	0.5	1.0	47
C75(R)	70	79	2.6	0.095	0.5	1.0	51

*At test I_Z; measured using a pulse method with $t_p \leq 100\ \mu\text{s}$ and $\delta \leq 0.001$ so that the values correspond to a T_j of approximately $25\text{ }^{\circ}\text{C}$.

CHARACTERISTICS – WHEN USED AS TRANSIENT SUPPRESSOR DIODES; $T_{mb} = 25\text{ }^{\circ}\text{C}$

clamping voltage at $t_p = 500\ \mu\text{s}$ exp. pulse $V_{(CL)R}$ V		non-repetitive peak reverse current I_{RSM} A	reverse current at recommended stand-off voltage I_R mA		BZY91...
typ.	max.		max.	V_R V	
—	—	—	—	—	C7V5(R)
9.5	10.5	150	20	6.2	C8V2(R)
10	11	150	20	6.8	C9V1(R)
11	12.5	150	5	7.5	C10(R)
12	13.5	150	5	8.2	C11(R)
13	15	150	5	9.1	C12(R)
14.5	17	150	5	10	C13(R)
16	19	150	5	11	C15(R)
17.5	22	150	5	12	C16(R)
19	26	150	5	13	C18(R)
22	28	100	5	15	C20(R)
24	31	100	5	16	C22(R)
26	34	100	5	18	C24(R)
28	37	100	5	20	C27(R)
31	40	100	5	22	C30(R)
34	44	100	5	24	C33(R)
38	48	100	5	27	C36(R)
40	52	50	5	30	C39(R)
44	56	50	10	33	C43(R)
49	61	50	10	36	C47(R)
54	66	50	10	39	C51(R)
60	72	50	10	43	C56(R)
66	79	50	10	47	C62(R)
72	87	50	10	51	C68(R)
79	97	50	10	56	C75(R)

MOUNTING INSTRUCTIONS

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

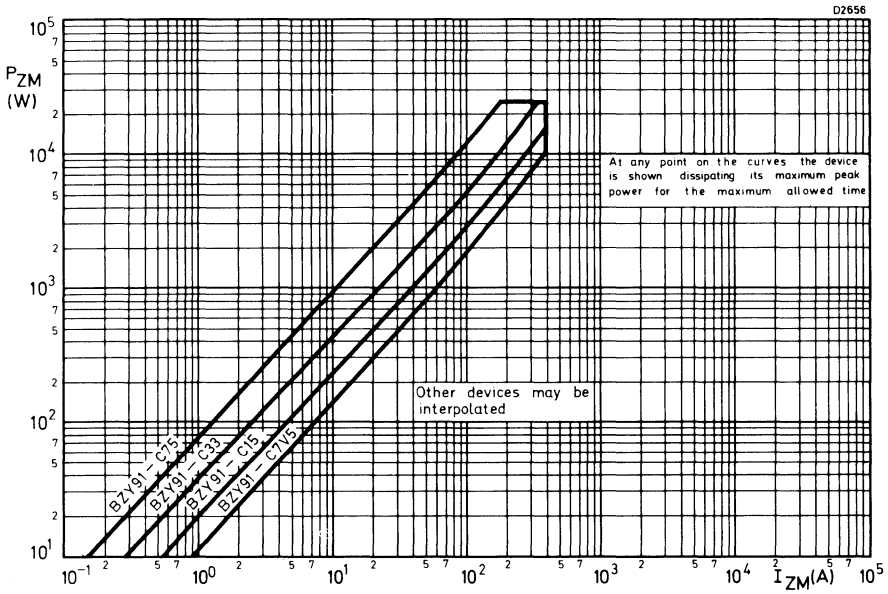


Fig. 3.

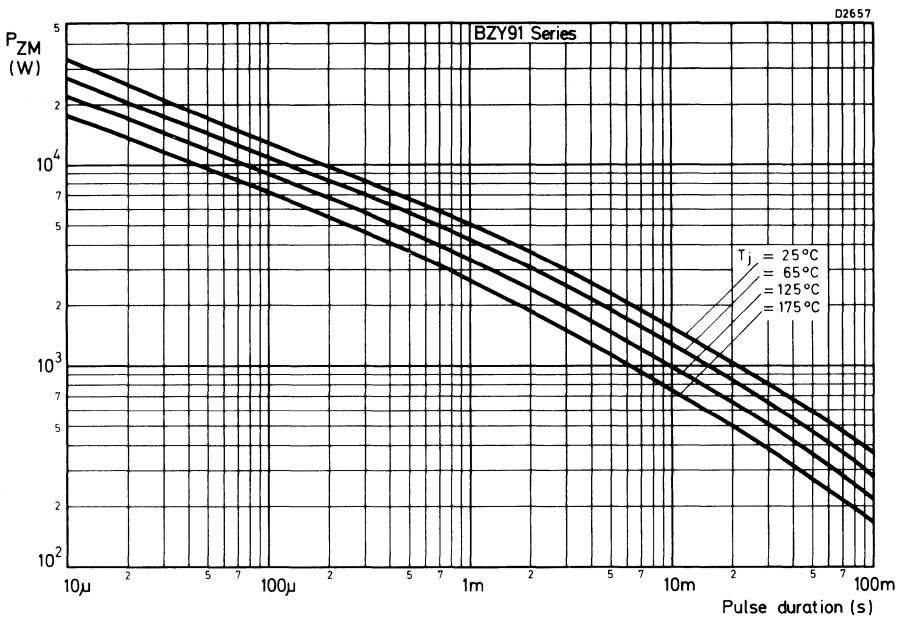


Fig. 4.

BZY91 SERIES

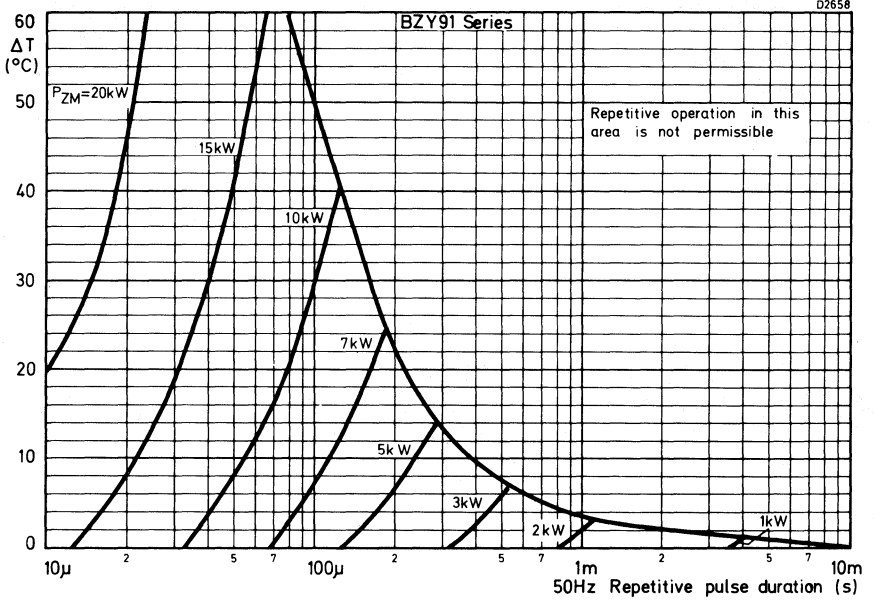


Fig. 5.

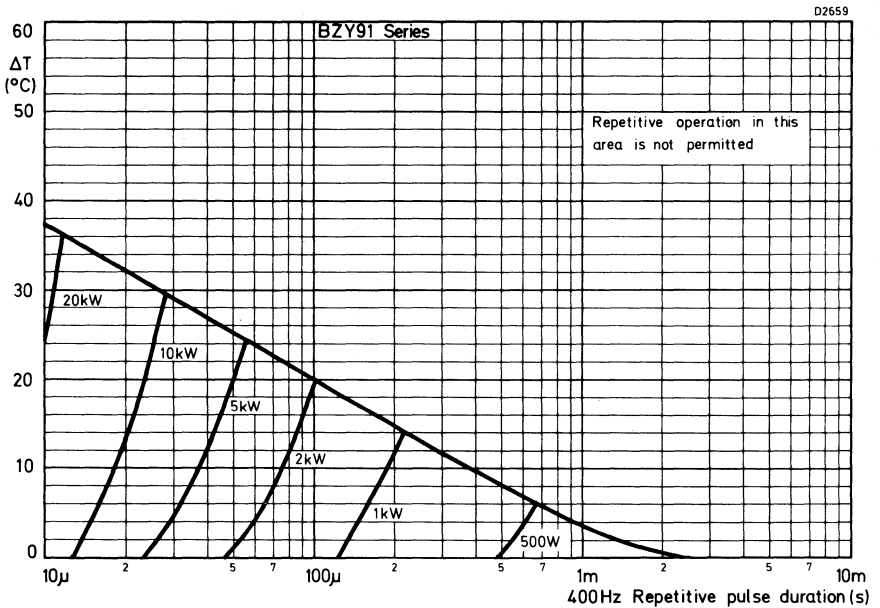


Fig. 6.

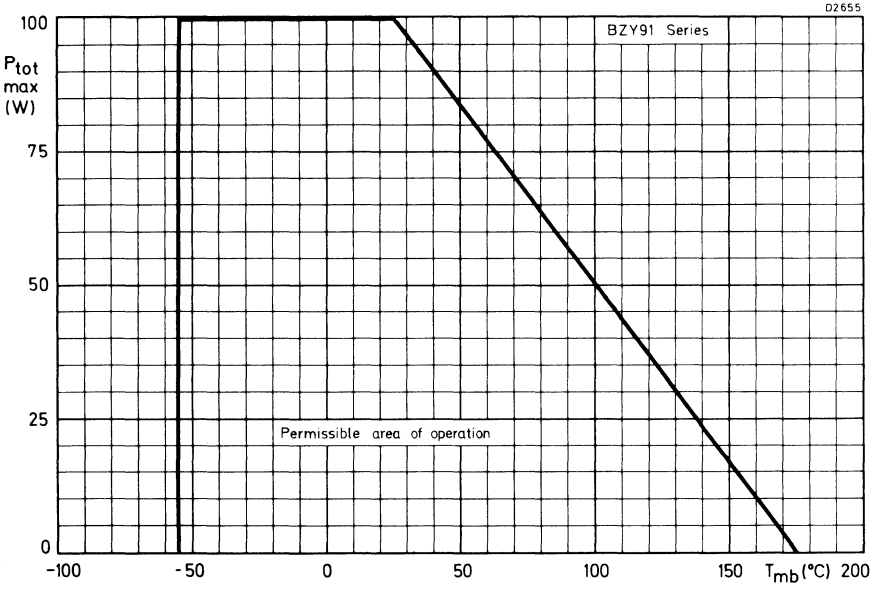


Fig. 7.

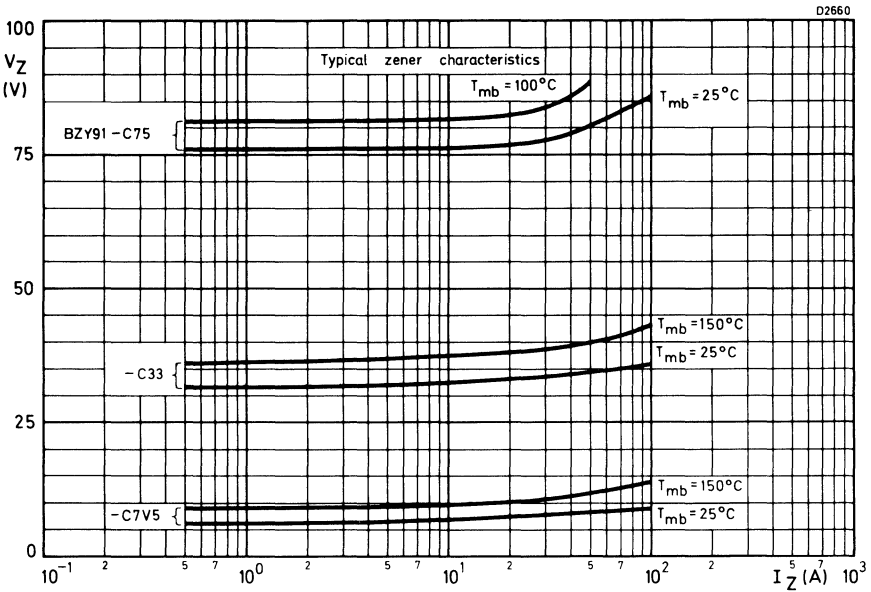


Fig. 8 Typical dynamic zener characteristics.

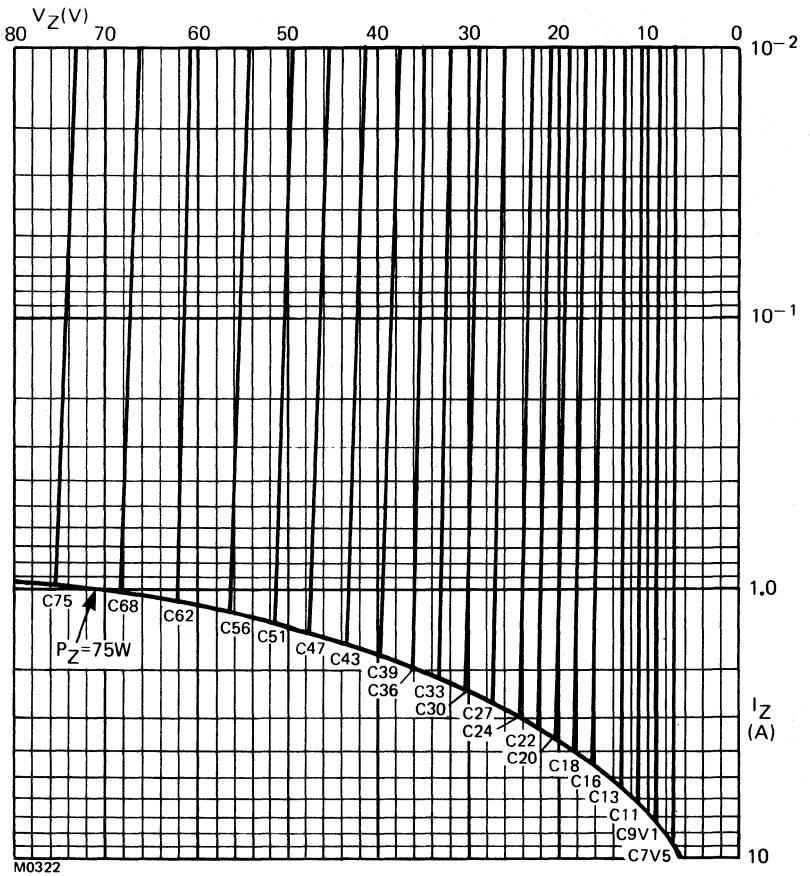


Fig.9 Typical static zener characteristics, $T_{mb} = 25\text{ }^\circ\text{C}$

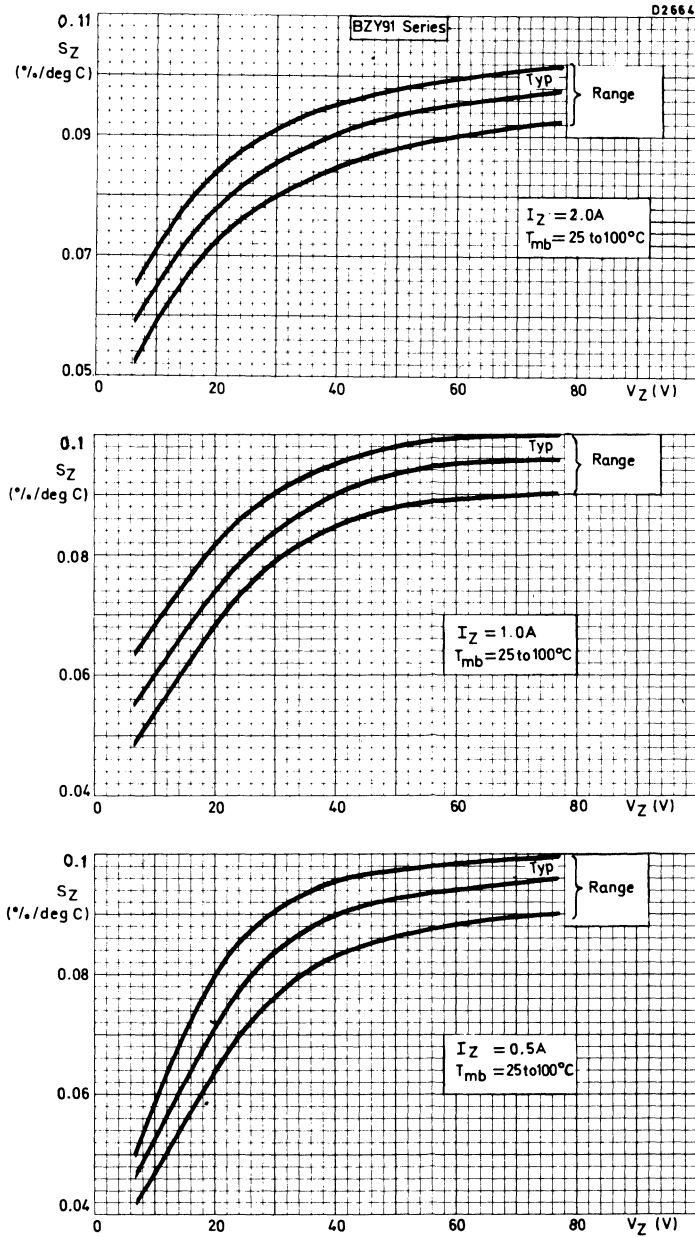


Fig. 10.

BZY91 SERIES

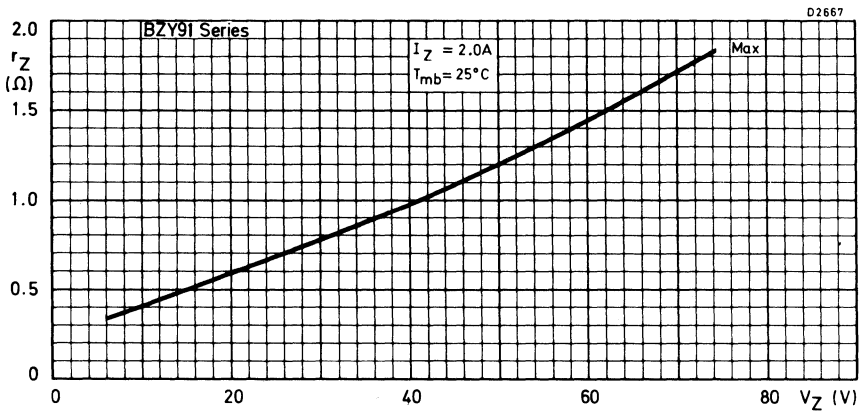
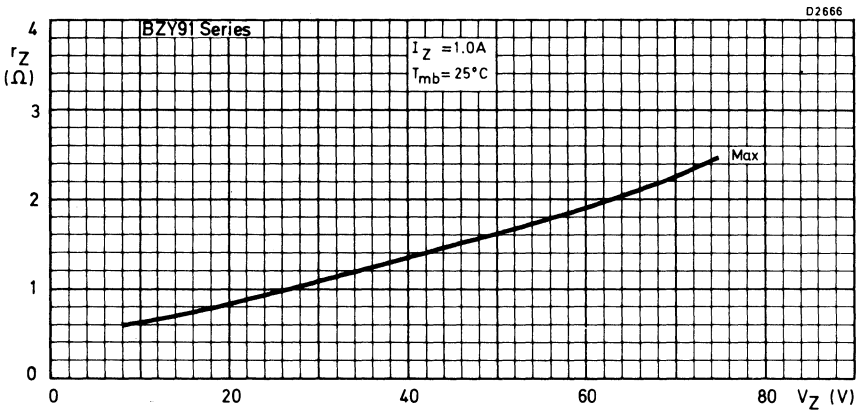
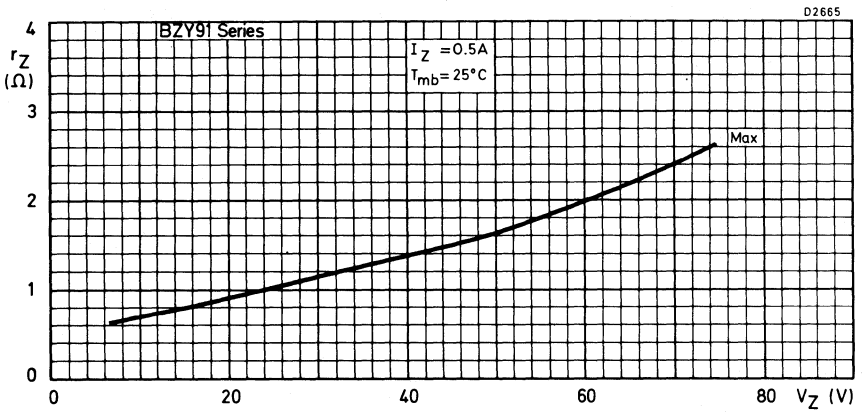


Fig. 11.

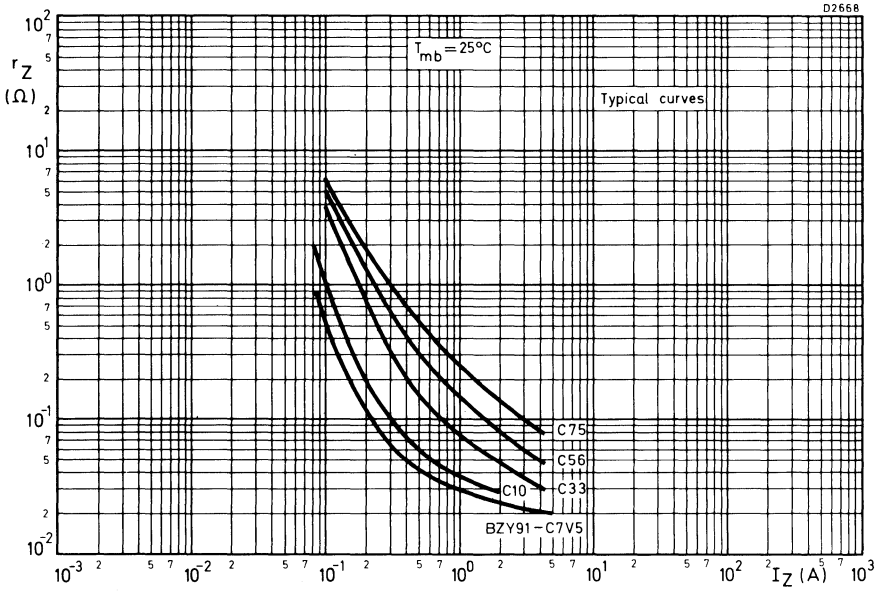


Fig. 12.

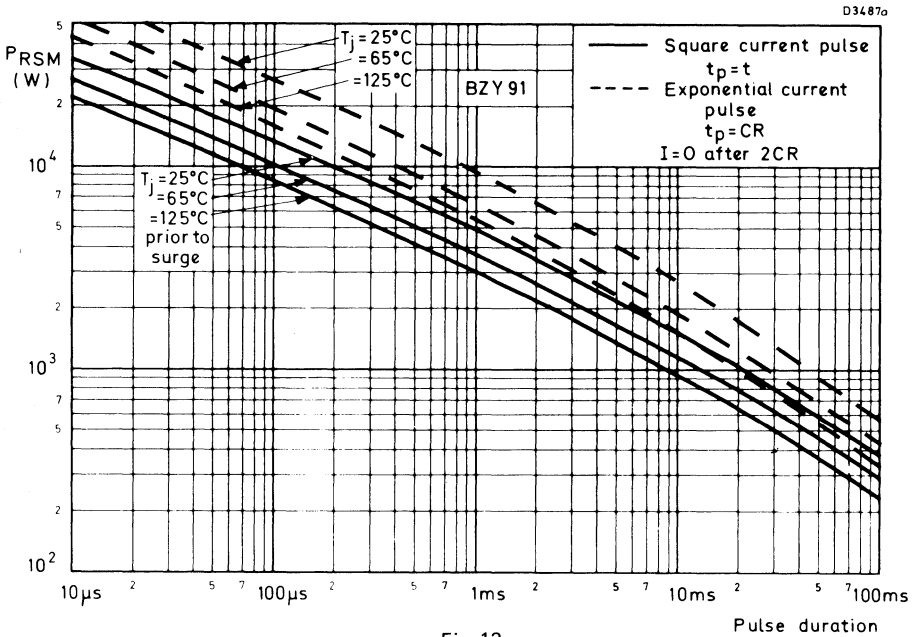


Fig. 13.

BZY91 SERIES

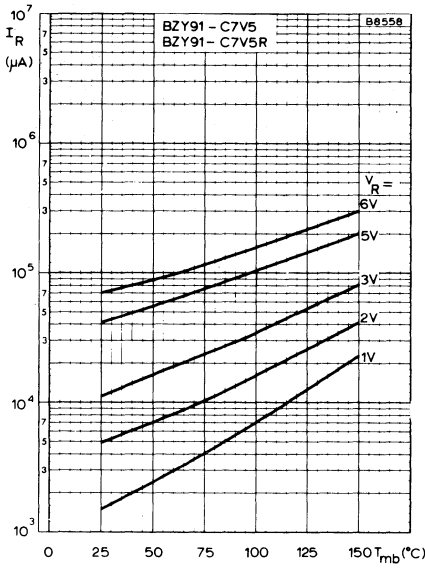


Fig. 14.

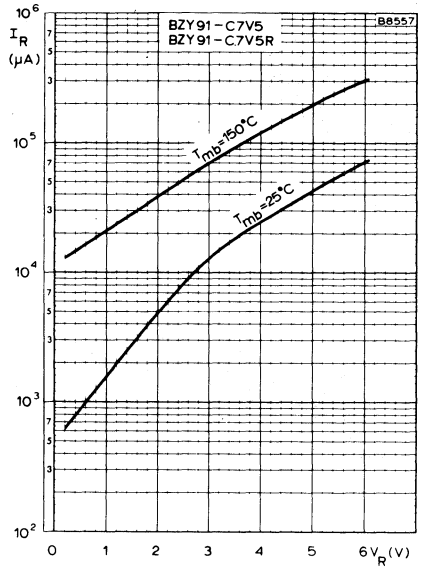


Fig. 15.

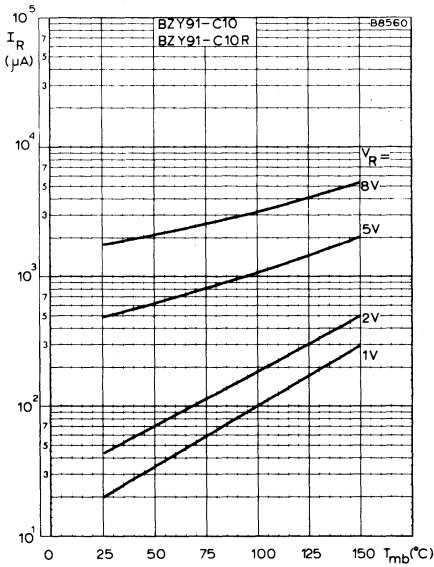


Fig. 16.

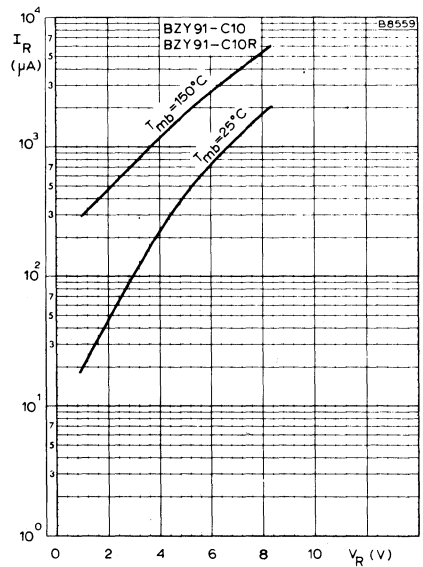


Fig. 17.

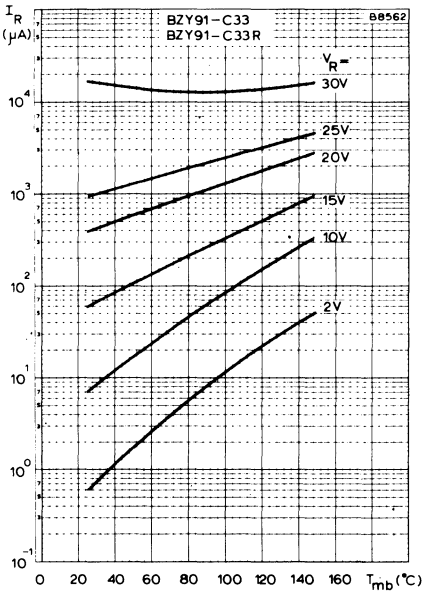


Fig. 18.

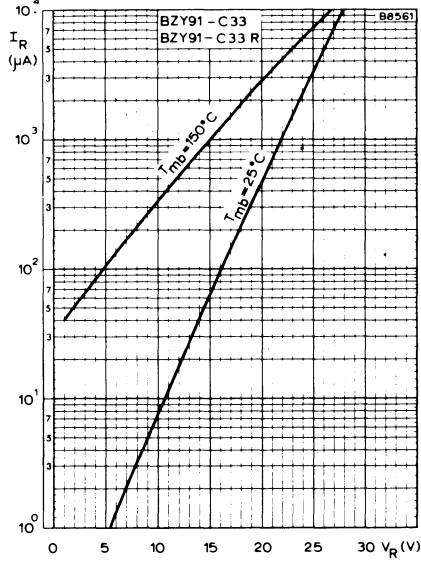


Fig. 19.

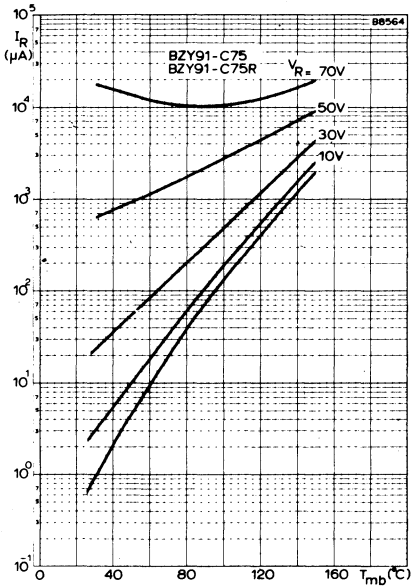


Fig. 20.

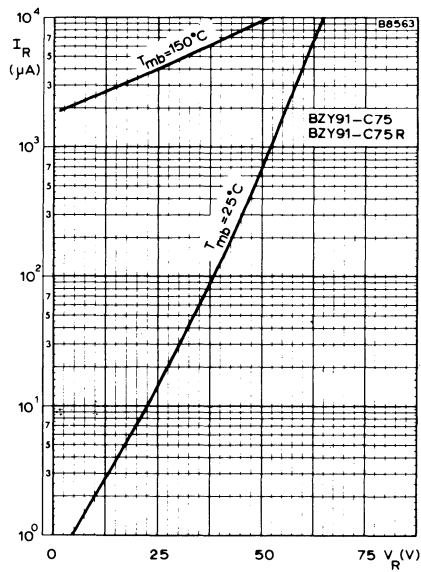
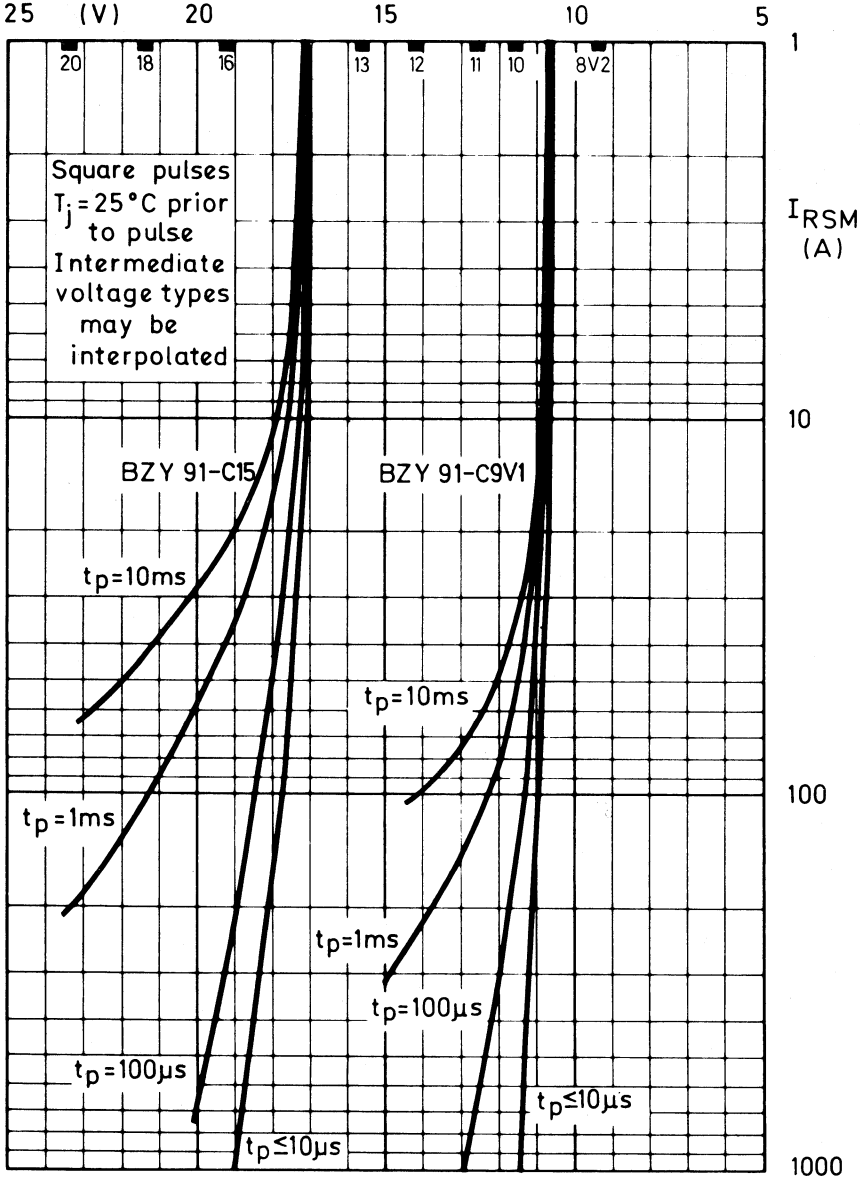


Fig. 21.

BZY91 SERIES

$V_{(CL)R}^{max}$

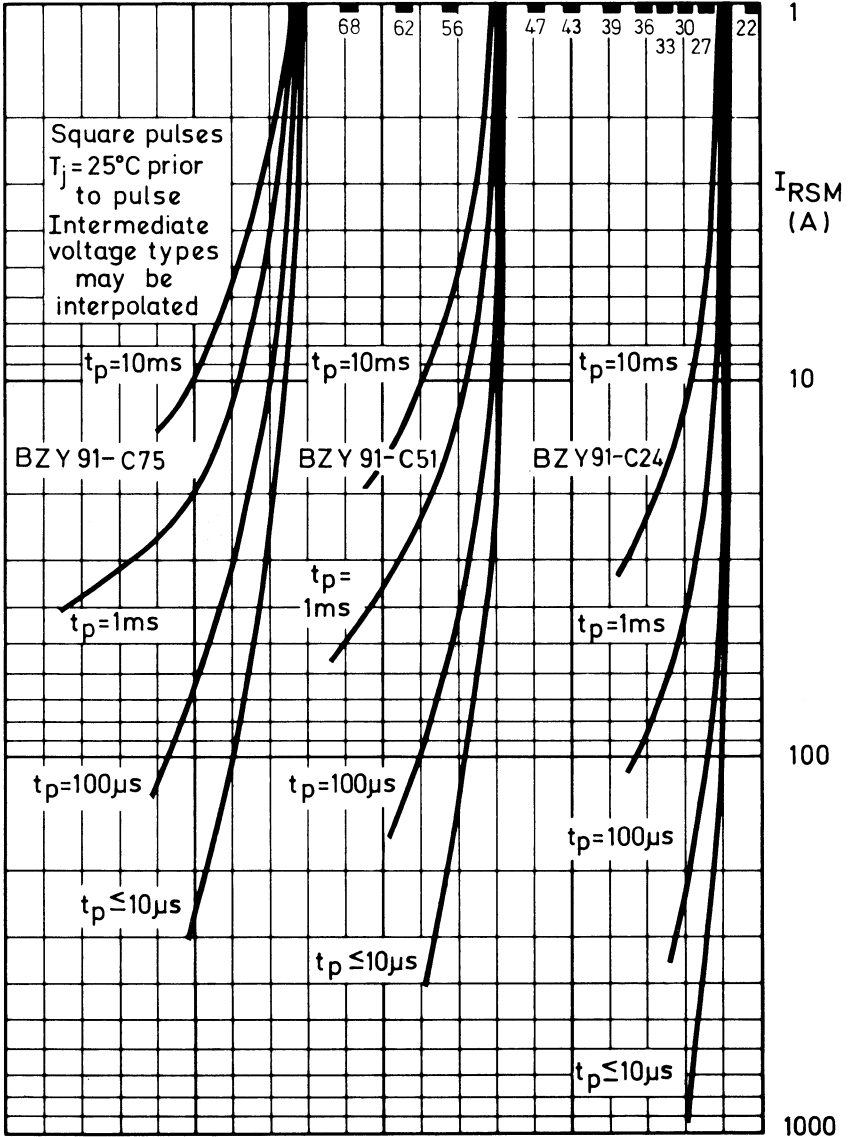


D8027

Fig. 22.

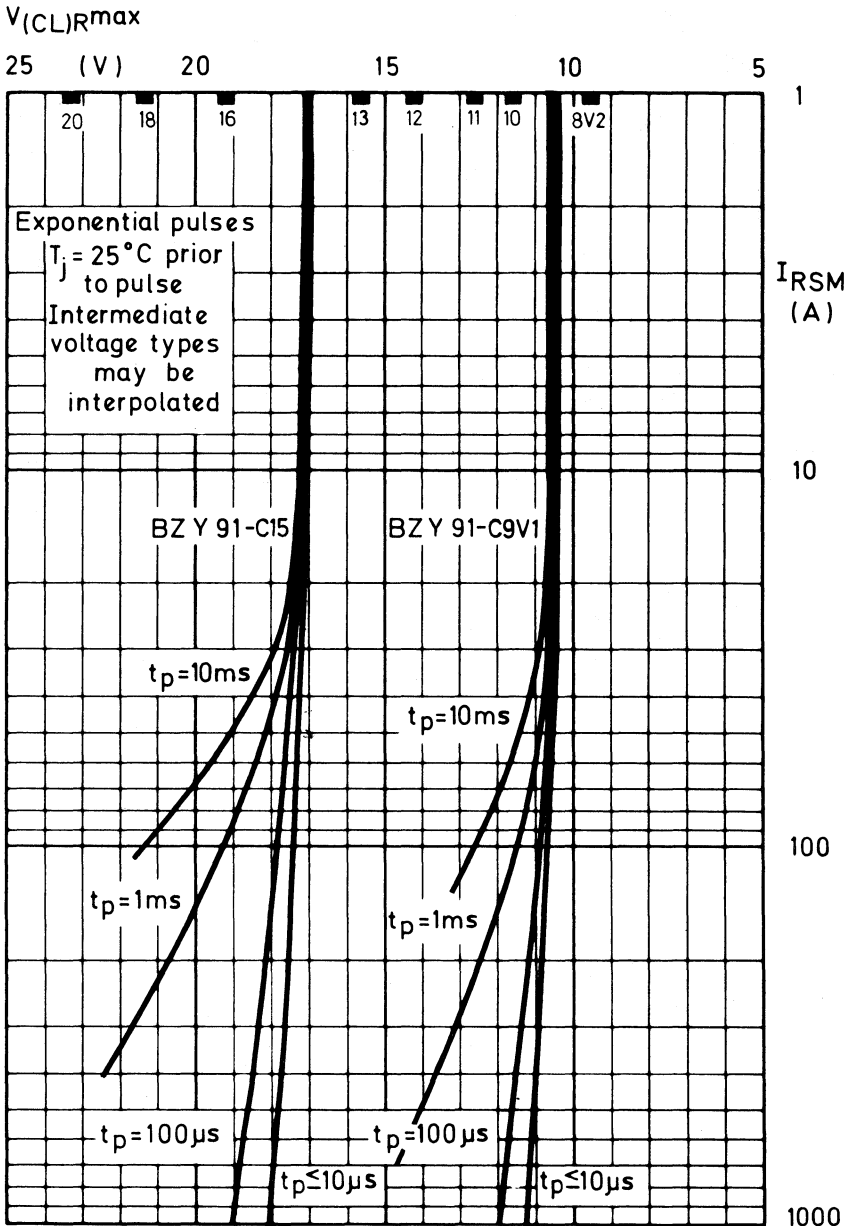
$V_{(CL)R}^{max}$

125 (V) 100 75 50 25



D8028

Fig. 23.



D8029

Fig. 24.

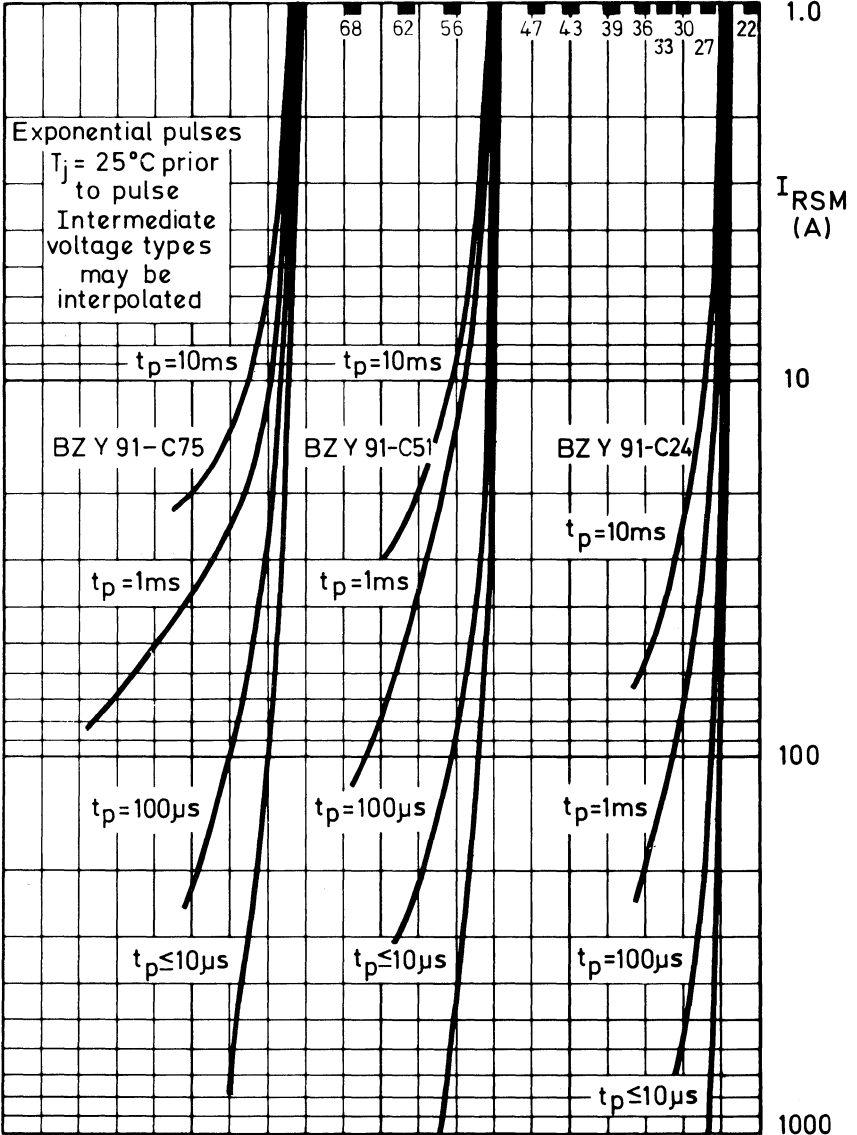
$V_{(CL)Rmax}$

125 (V) 100

75

50

25



D8030

Fig. 25.

D3485

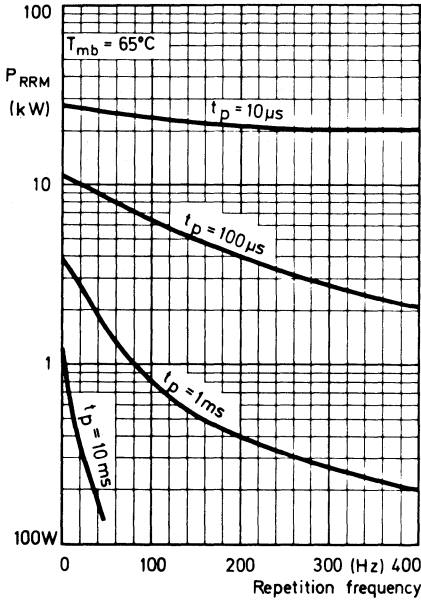


Fig. 26.

D3486

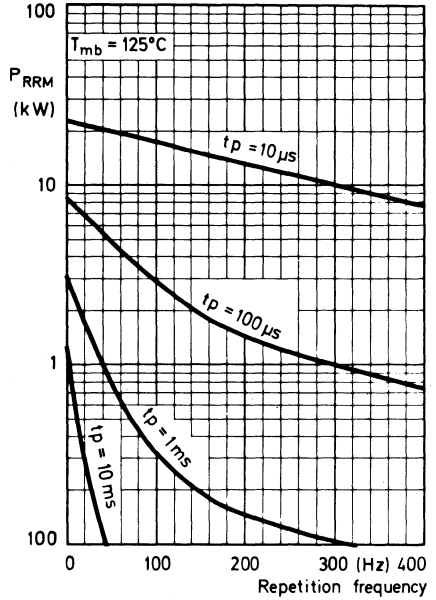


Fig. 27.

D8031

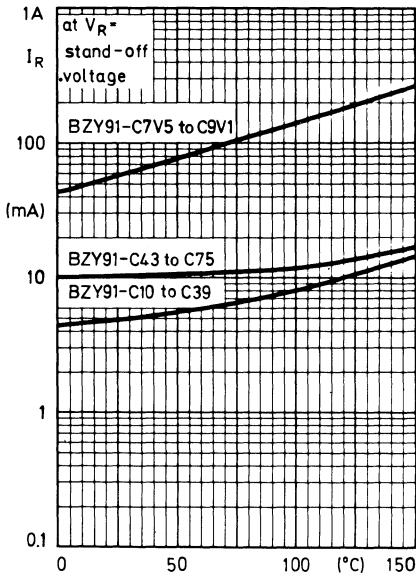


Fig. 28.

REGULATOR DIODES

Also available to BS9305-F051

A range of diffused silicon diodes in DO-4 metal envelopes, intended for use as voltage regulator and transient suppressor diodes in power stabilization and transient suppression circuits.

The series consists of the following types:

Normal polarity (cathode to stud): BZY93-C7V5 to BZY93-C75.

Reverse polarity (anode to stud): BZY93-C7V5R to BZY93-C75R.

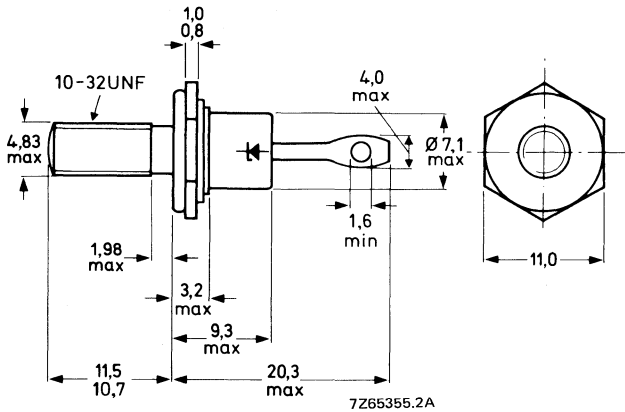
QUICK REFERENCE DATA

			voltage regulator		transient suppressor	
Working voltage (5% range)	V_Z	nom.	7,5 to 75	—	V	V
Stand-off voltage	V_R		—	5,6 to 56	V	V
Total power dissipation	P_{tot}	max.	20	—	W	W
Non-repetitive peak reverse power dissipation	P_{RSM}	max.	—	700	W	W

MECHANICAL DATA

Dimensions in mm

Fig. 1 DO-4.



Net mass: 6 g

Diameter of clearance hole: max. 5,2 mm

Accessories supplied on request:
see ACCESSORIES section

Supplied with device: 1 nut, 1 lock washer

Nut dimensions across the flats: 9,5 mm

Torque on nut: min. 0,9 Nm (9 kg cm)
max. 1,7 Nm (17 kg cm)

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

Peak working current	I_{ZM}	max.	20 A
Average forward current (averaged over any 20 ms period)	$I_F(AV)$	max.	5 A
Non-repetitive peak reverse current $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse); BZY93-C7V5(R) to BZY93-C75(R)	I_{RSM}	max.	55 to 6 A
Total power dissipation up to $T_{mb} = 75\text{ }^\circ\text{C}$	P_{tot}	max.	20 W
Non-repetitive peak reverse power dissipation $T_j = 25\text{ }^\circ\text{C}$ prior to surge; $t_p = 1\text{ ms}$ (exponential pulse)	P_{RSM}	max.	700 W
Storage temperature	T_{stg}		-55 to + 175 $^\circ\text{C}$
Junction temperature	T_j	max.	175 $^\circ\text{C}$

THERMAL RESISTANCE

From junction to mounting base	$R_{th\ j-mb}$	=	5 $^\circ\text{C/W}$
From junction to ambient	$R_{th\ j-a}$	=	50 $^\circ\text{C/W}$
From mounting base to heatsink (minimum torque: 0,9 Nm)	$R_{th\ mb-h}$	=	0,6 $^\circ\text{C/W}$

CHARACTERISTICS

Forward voltage $I_F = 5\text{ A}$; $T_{mb} = 25\text{ }^\circ\text{C}$	V_F	<	1,5 V
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OPERATION AS A VOLTAGE REGULATOR (see page 716)

Dissipation and heatsink considerations

a. Steady-state conditions

The maximum permissible steady-state dissipation $P_{s\ max}$ is given by the relationship

$$P_{s\ max} = \frac{T_{j\ max} - T_{amb}}{R_{th\ j-a}}$$

where: $T_{j\ max}$ is the maximum permissible operating junction temperature

T_{amb} is the ambient temperature

$R_{th\ j-a}$ is the total thermal resistance from junction to ambient

$$R_{th\ j-a} = R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a}$$

$R_{th\ mb-h}$ is the thermal resistance from mounting base to heatsink, that is, 0,6 $^\circ\text{C/W}$.

$R_{th\ h-a}$ is the thermal resistance of the heatsink.

b. Pulse conditions (see Fig. 2)

The maximum permissible pulse power $P_{p\ max}$ is given by the formula

$$P_{p\ max} = \frac{(T_{j\ max} - T_{amb}) - (P_s \cdot R_{th\ j-a})}{R_{th\ t} + \delta \cdot R_{th\ mb-a}}$$

where: P_s is any steady-state dissipation excluding that in pulses

$R_{th\ t}$ is the effective transient thermal resistance of the device between junction and mounting base. It is a function of the pulse duration t_p and duty factor δ .

δ is duty factor (t_p/T)

$R_{th\ mb-a}$ is the total thermal resistance between the mounting base and ambient

($R_{th\ mb-a} = R_{th\ mb-h} + R_{th\ h-a}$).

The steady-state power P_s when biased in the zener direction at a given zener current can be found from Fig. 14. With the additional pulse power dissipation $P_{p\ max}$ calculated from the above expression, the total peak zener power dissipation $P_{tot} = P_{ZRM} = P_s + P_p$. From Fig. 14 the corresponding maximum repetitive peak zener current at P_{ZRM} can now be read. This repetitive peak zener current is subject to the absolute maximum rating. For pulse durations larger than the temperature stabilization time of the diode t_{stab} , the maximum permissible repetitive peak dissipation P_{ZRM} is equal to the steady-state power P_s . The temperature stabilization time for the BZY93 is 5 seconds (see Fig. 9).

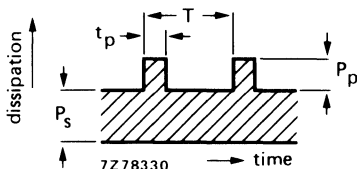


Fig. 2.

OPERATION AS A TRANSIENT SUPPRESSOR (see page 717)

Heatsink considerations

- For non-repetitive transients, the device may be used without a heatsink for pulses up to 10 ms in duration.
- For repetitive transients which fall within the permitted operating range shown in Figs 19 and 20 the required heatsink is found as follows:

$$R_{th\ j-mb} + R_{th\ mb-h} + R_{th\ h-a} = \frac{T_{j\ max} - T_{amb}}{P_s + \delta \cdot P_{RRM}}$$

where: $T_{j\ max} = 175\ ^\circ\text{C}$

T_{amb} = ambient temperature

P_s = any steady-state dissipation excluding that in pulses

δ = duty factor (t_p/T)

$R_{th\ j-mb} = 5\ ^\circ\text{C/W}$

$R_{th\ mb-h} = 0,6\ ^\circ\text{C/W}$

Thus $R_{th\ h-a}$ can be found.

Notes

- The stand-off voltage is the maximum reverse voltage recommended for continuous operation; at this value non-conduction is ensured.
- The maximum clamping voltage is the maximum reverse voltage which appears across the diode at the specified pulse duration and junction temperature. For square pulses see Figs 15 and 16, for exponential pulses see Figs 17 and 18.
- Duration of an exponential pulse is defined as the time taken for the pulse to fall to 37% of its initial value. It is assumed that the energy content does not continue beyond twice this time.
- Surge suppressor diodes are extremely fast in clamping, switching on in less than 5 ns.

BZY93 SERIES

CHARACTERISTICS – WHEN USED AS VOLTAGE REGULATOR DIODES; $T_{mb} = 25\text{ }^{\circ}\text{C}$

BZY93...	working voltage *V_Z V		differential resistance *r_Z Ω		temperature coefficient *S_Z mV/ $^{\circ}\text{C}$	test I_Z A	reverse current I_R μA	reverse voltage at V_R V
	min.	max.	typ.	max.	typ.		max.	
C7V5(R)	7.0	7.9	0.04	0.3	3.0	2.0	100	2.0
C8V2(R)	7.7	8.7	0.05	0.3	4.0	2.0	100	5.6
C9V1(R)	8.5	9.6	0.07	0.5	5.0	1.0	50	6.2
C10(R)	9.4	10.6	0.07	0.5	7.0	1.0	50	6.8
C11(R)	10.4	11.6	0.08	1.0	7.5	1.0	50	7.5
C12(R)	11.4	12.7	0.08	1.0	8.0	1.0	50	8.2
C13(R)	12.4	14.1	0.08	1.0	8.5	1.0	50	9.1
C15(R)	13.8	15.6	0.10	1.2	10	1.0	50	10
C16(R)	15.3	17.1	0.18	1.2	11	0.5	50	11
C18(R)	16.8	19.1	0.2	1.5	12	0.5	50	12
C20(R)	18.8	21.2	0.2	1.5	14	0.5	50	13
C22(R)	20.8	23.3	0.21	1.8	16	0.5	50	15
C24(R)	22.7	25.9	0.22	2.0	18	0.5	50	16
C27(R)	25.1	28.9	0.25	2.0	21	0.5	50	18
C30(R)	28	32	0.3	2.5	25	0.5	50	20
C33(R)	31	35	0.32	3.0	30	0.5	50	22
C36(R)	34	38	0.75	4.0	32	0.2	50	24
C39(R)	37	41	0.85	5.0	35	0.2	50	27
C43(R)	40	46	0.90	6.5	40	0.2	50	30
C47(R)	44	50	1.0	7.0	45	0.2	50	33
C51(R)	48	54	1.2	7.5	50	0.2	50	36
C56(R)	52	60	1.3	8.0	55	0.2	50	39
C62(R)	58	66	1.5	9.0	60	0.2	50	43
C68(R)	64	72	1.8	10	65	0.2	50	47
C75(R)	70	79	2.0	10.5	70	0.2	50	51

*At test I_Z ; measured using a pulse method with $t_p \leq 100\ \mu\text{s}$ and $\delta \leq 0.001$ so that the values correspond to a T_j of approximately $25\text{ }^{\circ}\text{C}$.

CHARACTERISTICS – WHEN USED AS TRANSIENT SUPPRESSOR DIODES; $T_{mb} = 25\text{ }^{\circ}\text{C}$

clamping voltage at $t_p = 500\text{ }\mu\text{s}$ exp. pulse $V_{(CL)R}$ V		non-repetitive peak reverse current I_{RSM} A	reverse current at recommended stand-off voltage I_R mA		V_R V	BZY93...
typ.	max.		max.			
8	9.2	20	0.5		5.6	C7V5(R)
9	10.2	20	0.5		6.2	C8V2(R)
10	11.5	20	0.5		6.8	C9V1(R)
11	12.5	20	0.1		7.5	C10(R)
12.3	14	20	0.1		8.2	C11(R)
14	16	20	0.1		9.1	C12(R)
15.3	17.5	20	0.1		10	C13(R)
17	19.5	20	0.1		11	C15(R)
19.3	22	20	0.1		12	C16(R)
21	24	20	0.1		13	C18(R)
23	27	10	0.1		15	C20(R)
26	30	10	0.1		16	C22(R)
29	34	10	0.1		18	C24(R)
33	39	10	0.1		20	C27(R)
38	44	10	0.1		22	C30(R)
42	50	10	0.1		24	C33(R)
47	56	10	0.1		27	C36(R)
40	47	5	0.1		30	C39(R)
45	52	5	0.1		33	C43(R)
51	59	5	0.1		36	C47(R)
57	66	5	0.1		39	C51(R)
64	75	5	0.1		43	C56(R)
73	85	5	0.1		47	C62(R)
81	94	5	0.1		51	C68(R)
90	105	5	0.1		56	C75(R)

BZY93 SERIES

MOUNTING INSTRUCTIONS

The top connector should neither be bent nor twisted; it should be soldered into the circuit so that there is no strain on it.

During soldering the heat conduction to the junction should be kept to a minimum.

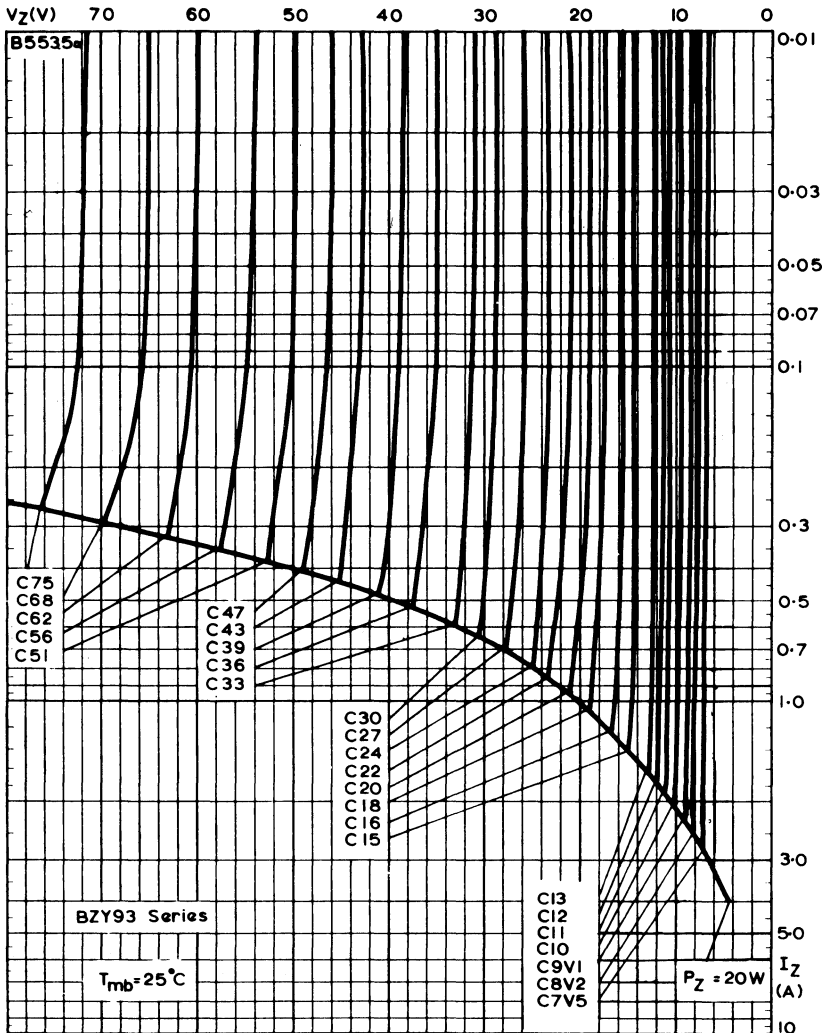


Fig. 3 Typical static zener characteristics.

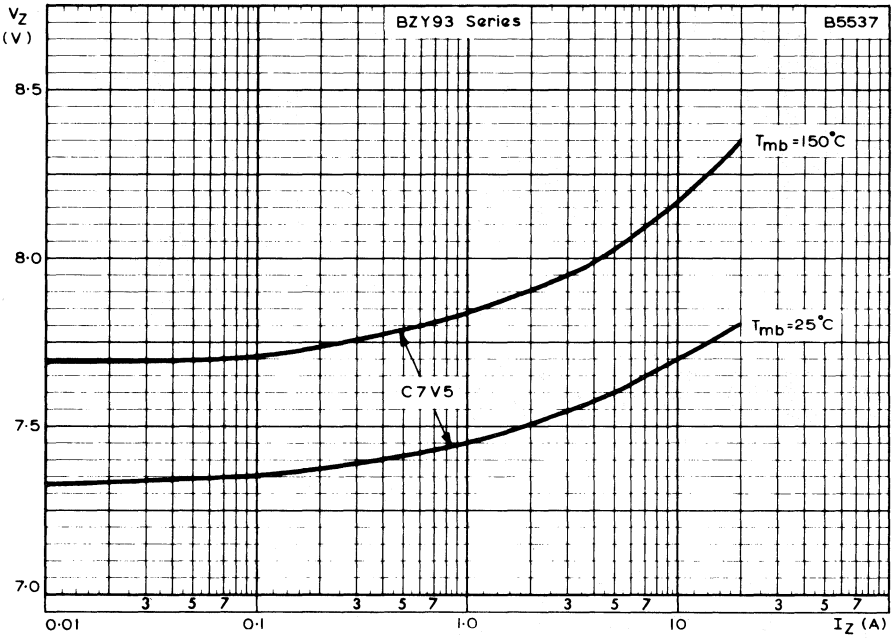


Fig. 4 Typical dynamic zener characteristics for BZY93-C7V5.

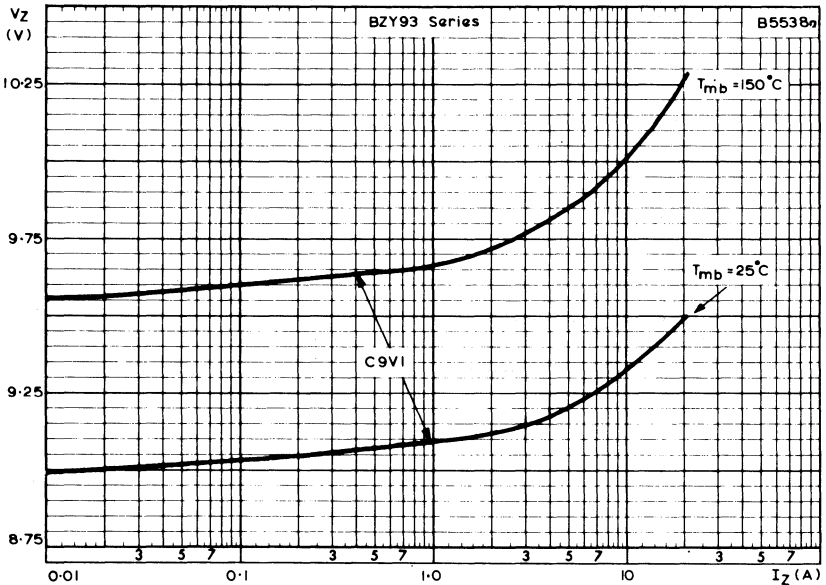


Fig. 5 Typical dynamic zener characteristics for BZY93-C9V1.

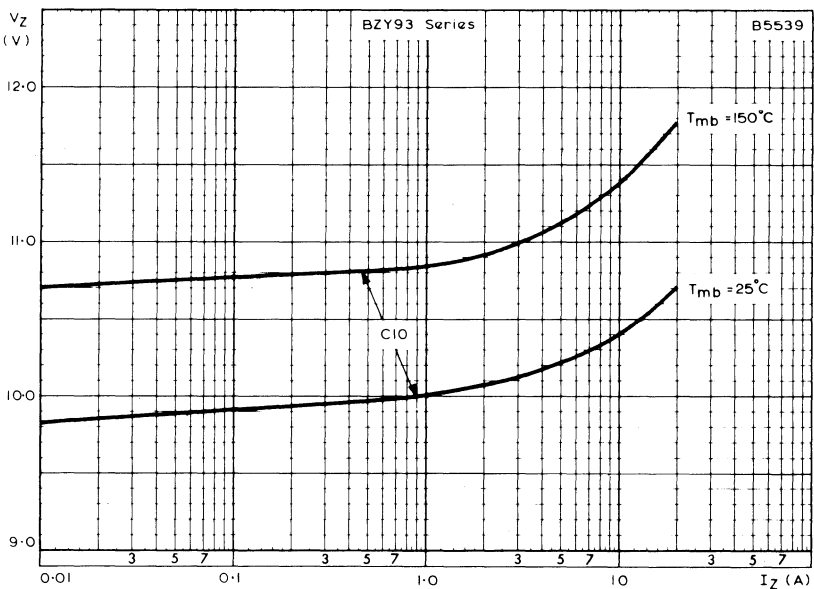


Fig. 6 Typical dynamic zener characteristics for BZY93-C10.

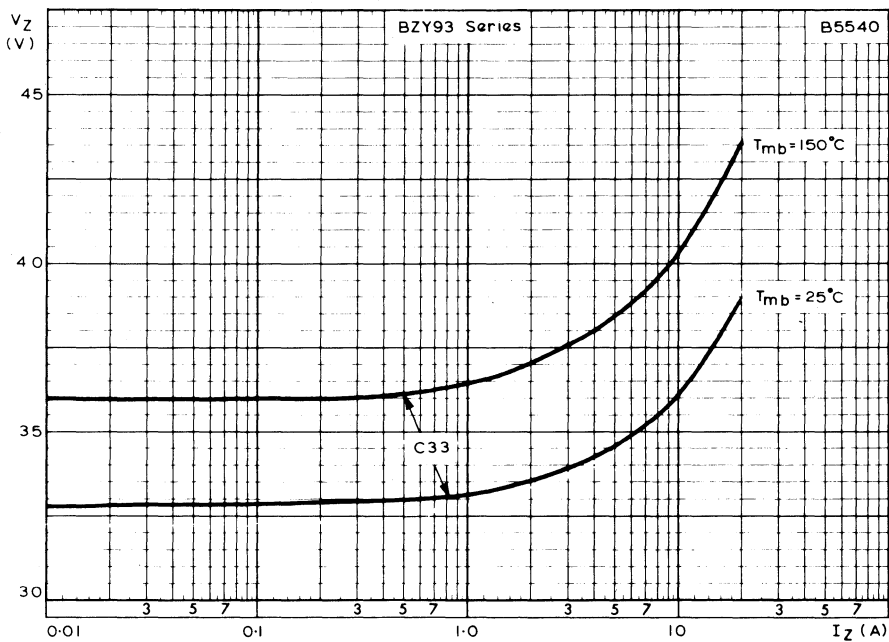


Fig. 7 Typical dynamic zener characteristics for BZY93-C33.

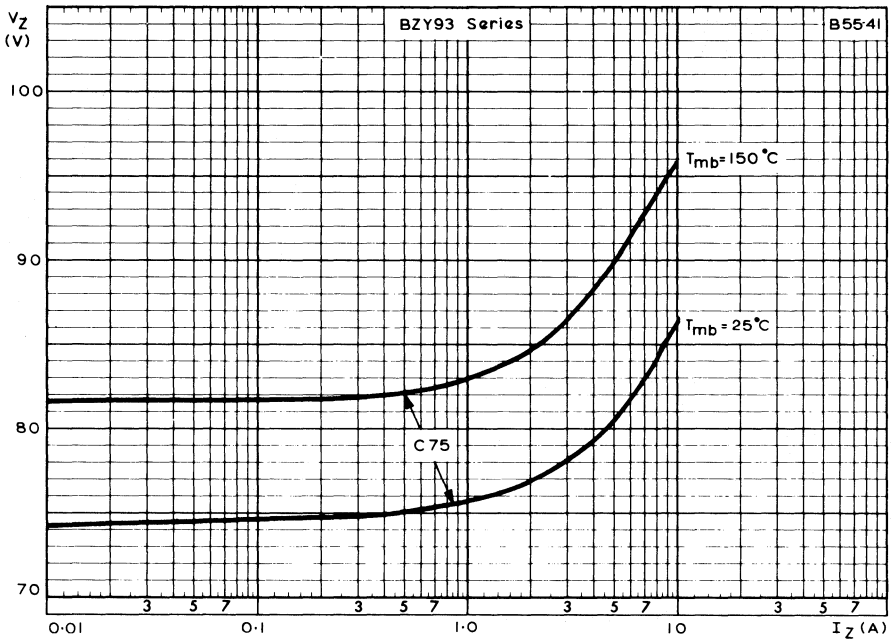


Fig. 8 Typical dynamic zener characteristics for BZY93-C75.

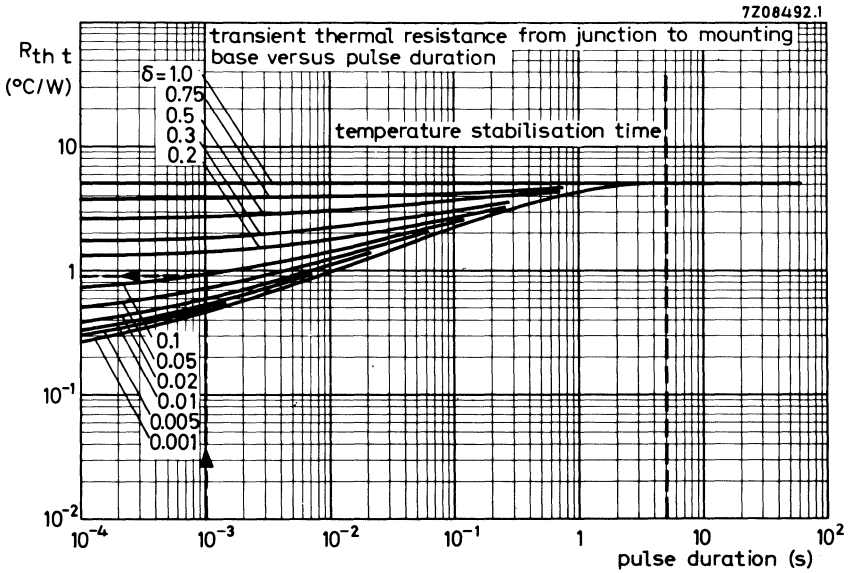


Fig. 9.

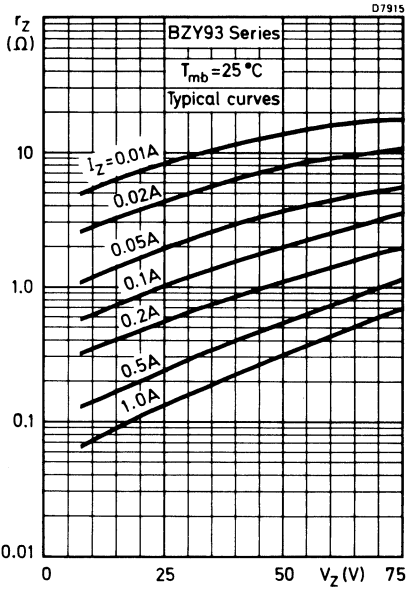


Fig. 10.

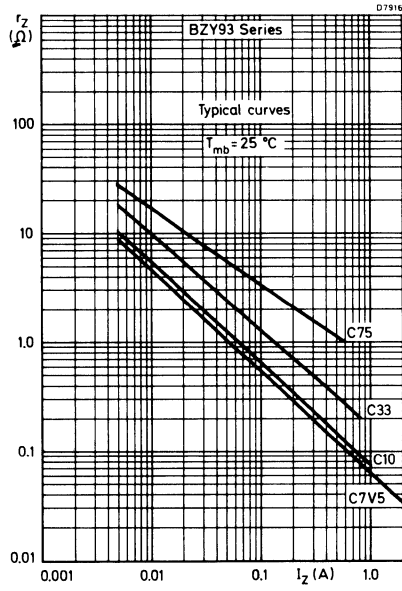


Fig. 11.

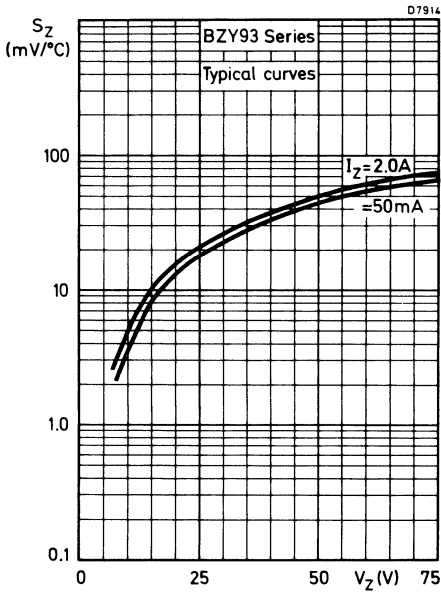


Fig. 12.

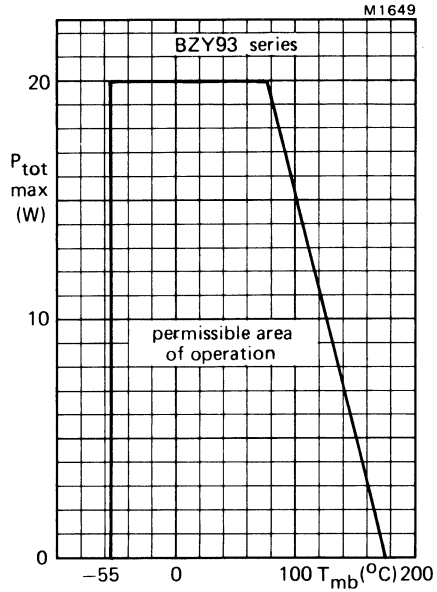


Fig. 13.

BZY93 SERIES

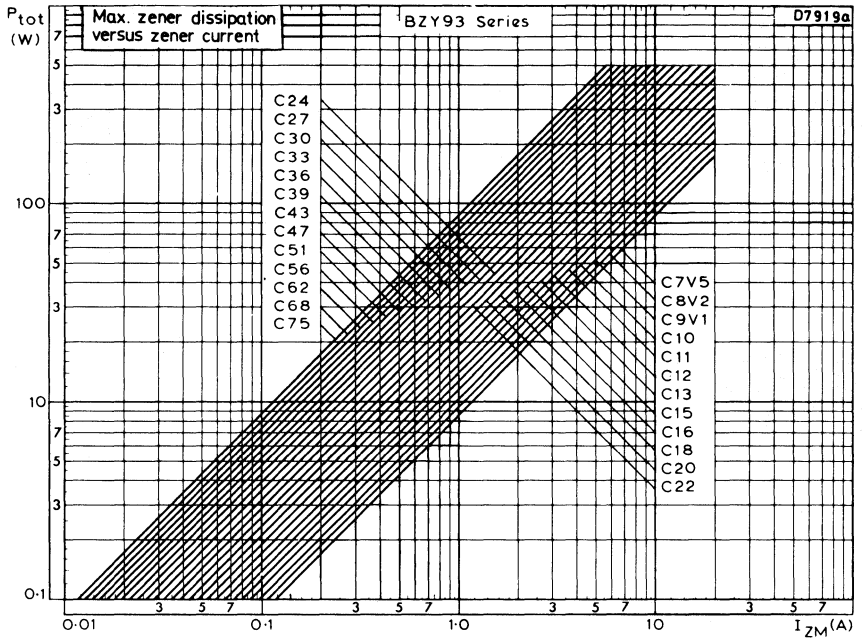


Fig. 14 Maximum permissible repetitive peak dissipation ($P_{tot} = P_{ZRM}$).

D7921

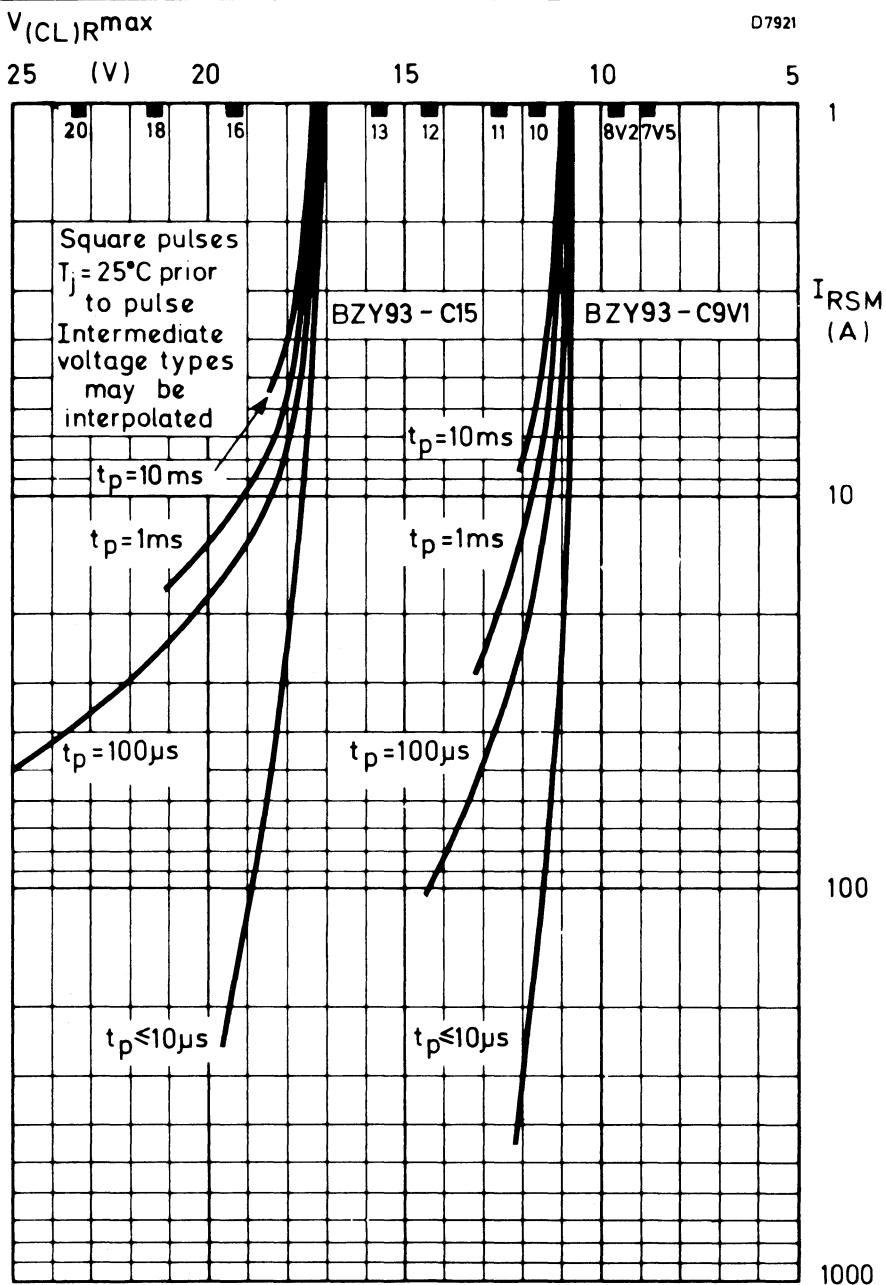


Fig. 15.

BZY93 SERIES

$V_{(CL)R\max}$

07920

125 (V) 100 75 50 25

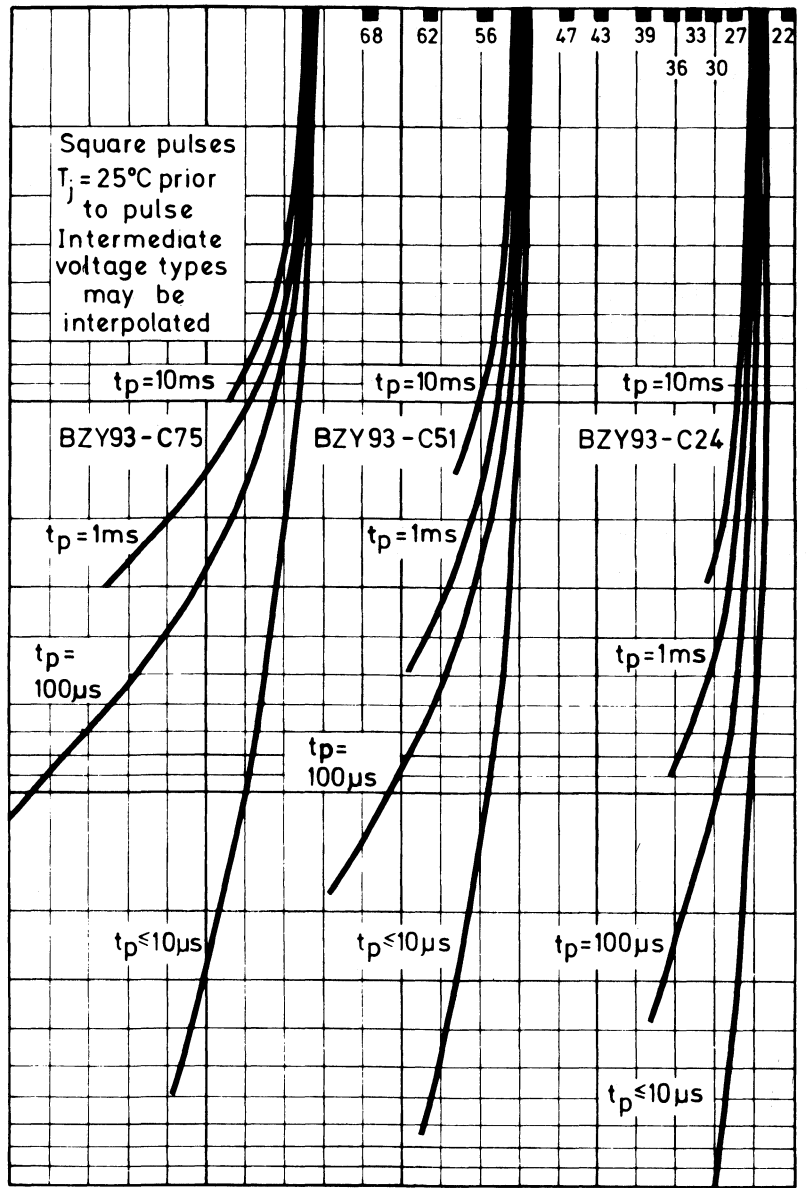


Fig. 16.

D7922

$V_{(CLR)max}$

25 (V) 20 15 10 5

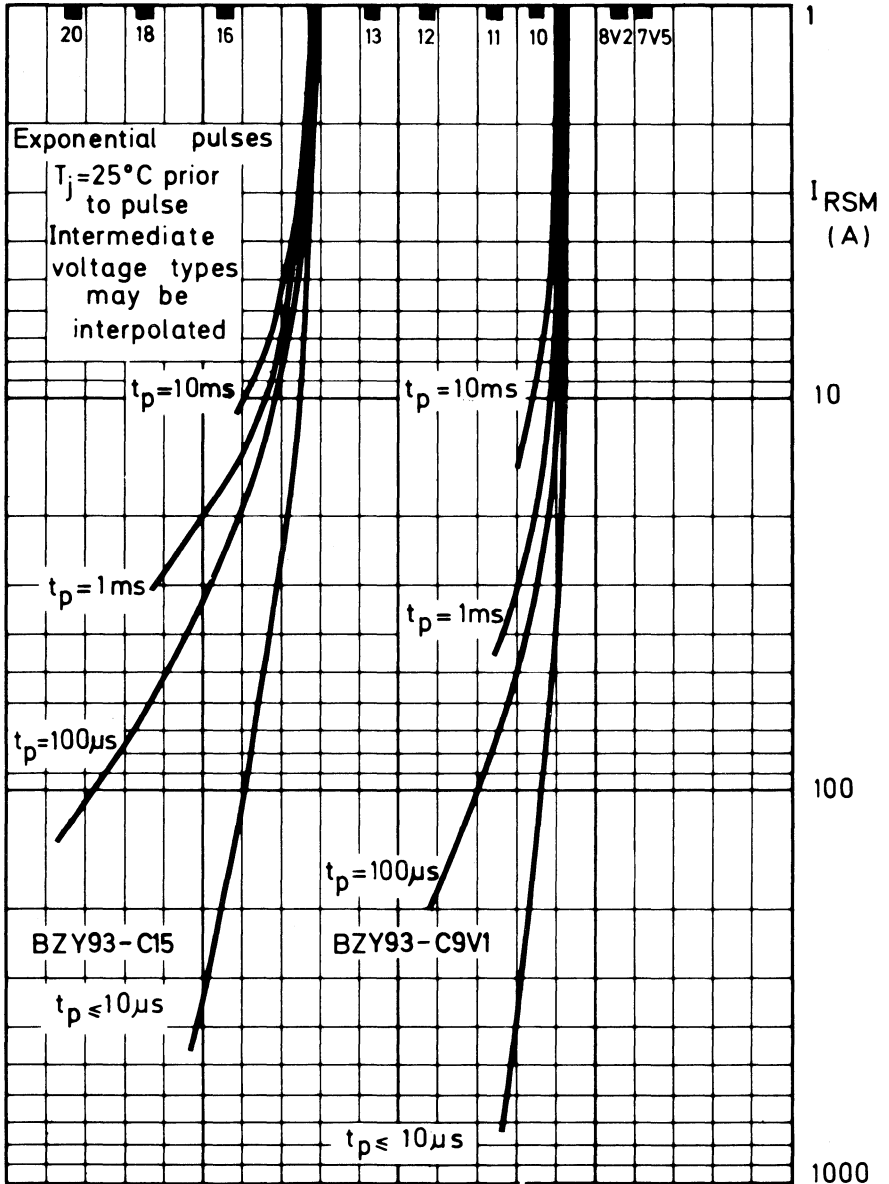


Fig. 17.

$V_{(CL)R}^{max}$

D7923

125 (V) 100 75 50 25

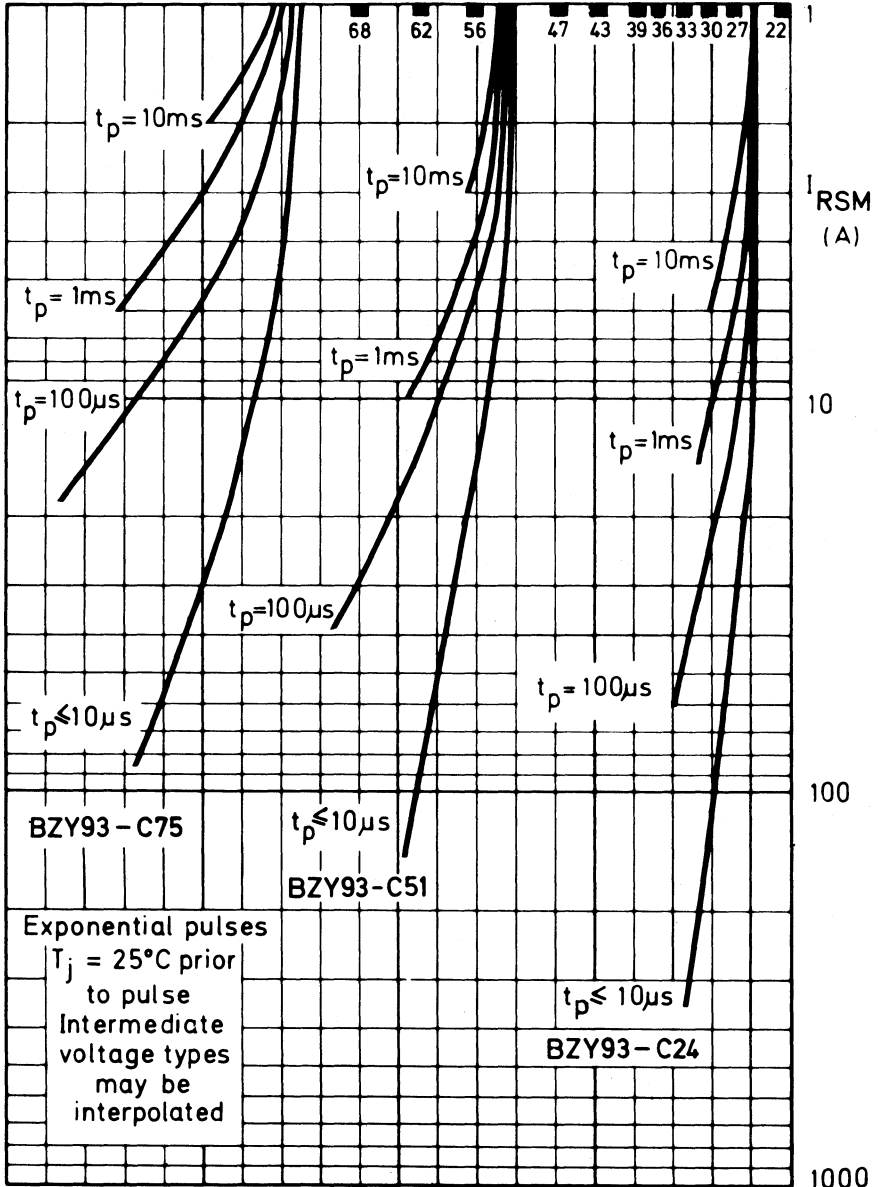


Fig. 18.

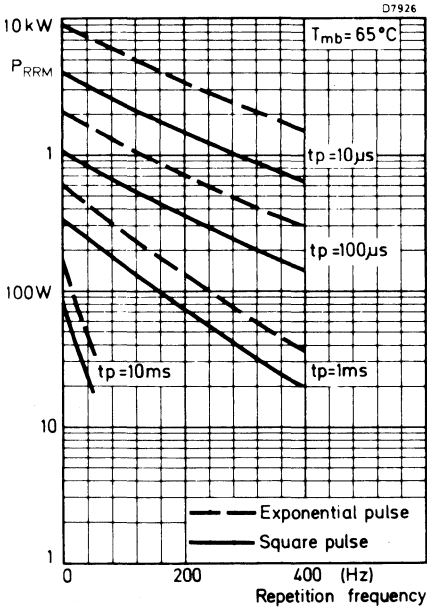


Fig. 19.

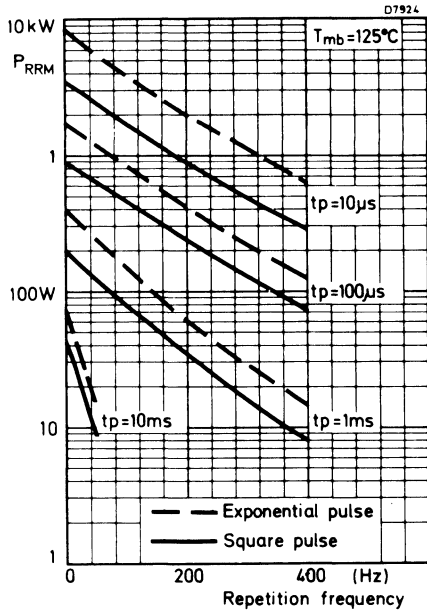


Fig. 20.

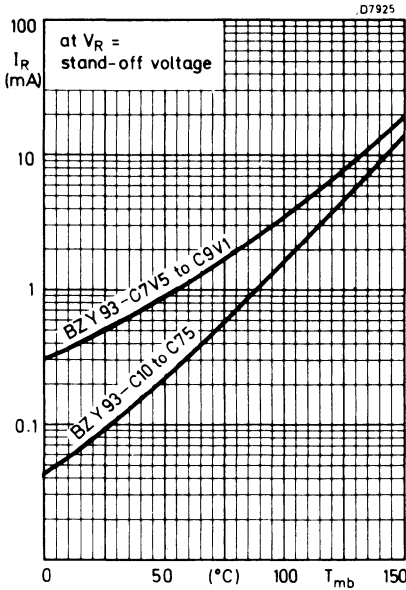


Fig. 21.

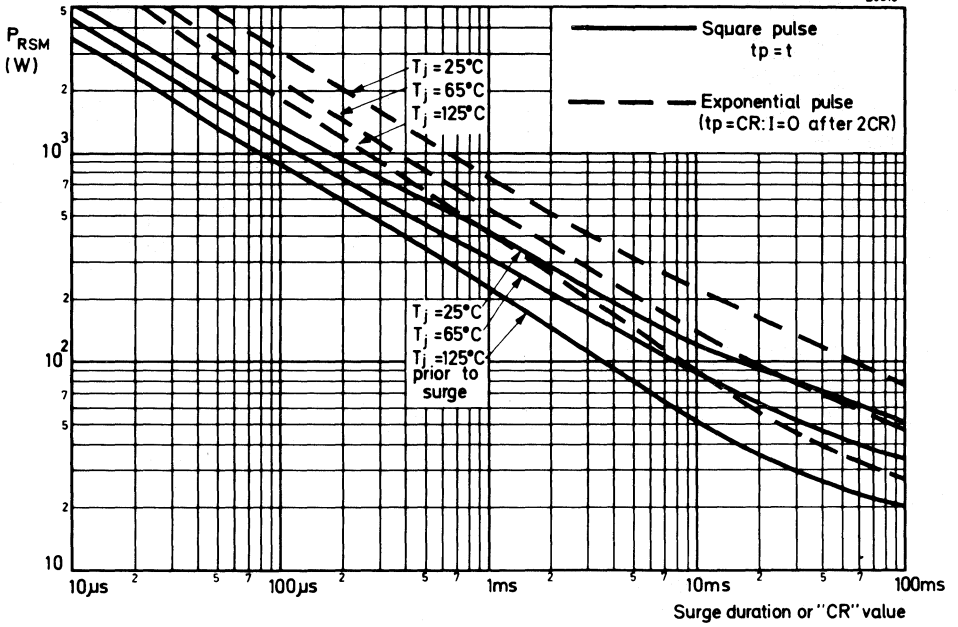


Fig. 22.

HIGH VOLTAGE RECTIFIER STACKS

OSB 9115 SERIES
 OSM 9115 SERIES
 OSS 9115 SERIES

All information applies to frequencies up to 400 Hz

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

		OSB9115 -4 -6		...		-34 -36		
		OSM9115 -4 -6		...		-34 -36		
Voltages	Crest working reverse voltage	V _{RWM}	max.	3	4.5	25.5	27	kV
			OSS9115 -3 -4		...		-35 -36	
	Crest working reverse voltage	V _{RWM}	max.	4.5	6	52.5	54	kV

Currents

Average forward current (averaged over any 20 ms period)
 in free air up to T_{amb} = 35 °C
 in oil up to T_{oil} = 100 °C

	I _{F(AV)}	max.	3.5	A
	I _{F(AV)}	max.	6	A
Repetitive peak forward current	I _{FRM}	max.	120	A
Non-repetitive peak forward current t = 10 ms; half sine-wave; T _j = 175 °C prior to surge	I _{FSM}	max.	125	A

Reverse power dissipation

Repetitive peak reverse power
 t = 10 μs (square-wave; f = 50 Hz)
 T_j = 175 °C

Non-repetitive peak reverse power
 t = 10 μs (square-wave)
 T_j = 25 °C prior to surge
 T_j = 125 °C prior to surge

		OSB9115 -4 -6		...		-34 -34	
		OSM9115 -4 -6		...		-34 -36	
Repetitive peak reverse power	PRRM	max.	1.2	1.8	10.2	10.8	kW
		OSS9115 -3 -4		...		-35 -36	
Non-repetitive peak reverse power	PRSM	max.	6	9	51	54	kW
		PRSM	max.	1.2	1.8	10.2	10.8
Repetitive peak reverse power dissipation	PRRM	max.	1.8	2.4	21	21.6	kW
		OSS9115 -3 -4		...		-35 -36	
Non-repetitive peak reverse power dissipation	PRSM	max.	9	12	105	108	kW
		PRSM	max.	1.8	2.4	21	21.6

Temperatures

Storage temperature	T _{stg}	-55 to +150	°C
Junction temperature	T _j	max. 175	°C

CHARACTERISTICS (See note 1)

		OSB9115 -4 -6		...	-34 -36	
		OSM9115 -4 -6		...	-34 -36	
Forward voltage						
$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	V_F	<	4 6	...	34 36	V
Reverse avalanche breakdown voltage*						
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	>	3.3 4.95	...	28 29.7	kV
		<	4.8 7.2	...	40.8 43.2	kV
		OSS9115 -3 -4		...	-35 -36	
Forward voltage						
$I_F = 20 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	V_F	<	6 8	...	70 72	V
Reverse avalanche breakdown voltage*						
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	>	4.95 6.6	...	57.8 59.4	kV
		<	7.2 9.6	...	84 68.4	kV
Reverse current						
$V_{RM} = V_{RWM \text{ max}}; T_j = 125 \text{ }^\circ\text{C}$	I_{RM}	<	0.6			mA

NOTES

1. The Ratings and Characteristics given apply **from centre tap to end**. (Not for OSS9115 series).

2. **Type number suffix**

The suffix consists of a figure indicating the total number of diodes, followed by a letter indicating the base.

- A = M6 studs at the ends
- B = 4 pin Super Jumbo (B4D)
- C = Goliath
- E = 4 pin Jumbo (B4F)
- F = A3-20

3. **Operating position**

The rectifier units can be operated at their maximum ratings when mounted in any position.

*The breakdown voltage increases by approximately 0.1% per $^\circ\text{C}$ with increasing junction temperature.

MECHANICAL DATA

Dimensions in mm

n = total number of diodes

Fig.4 OSM9115 -nA

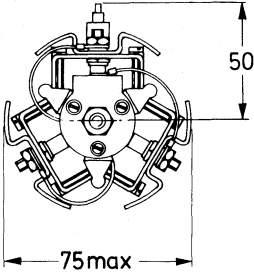


Fig.5 OSM9115 -nB

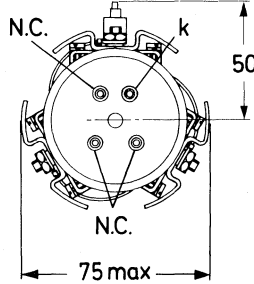
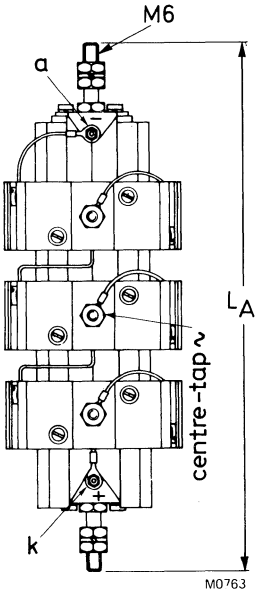
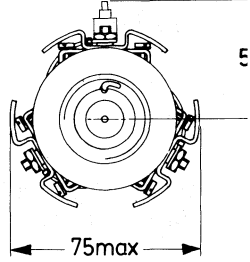
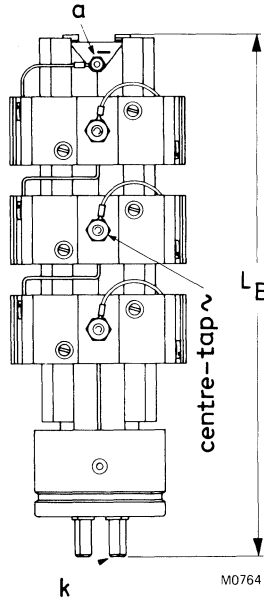


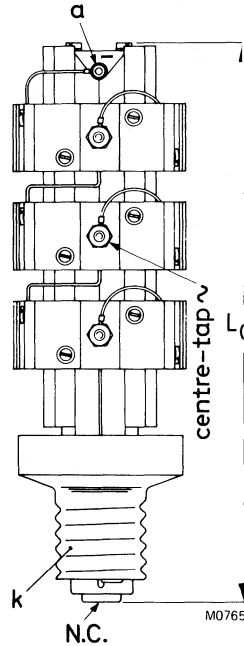
Fig.6 OSM9115 -nC



M0763



M0764



M0765

The drawings show the OSM9115 series; the OSB9115 and OSS9115 series differ in the following respects:

- OSB9115 series — terminals marked a (-) and k (+) in the drawings are both marked ~; the centre-tap is marked + (instead of ~ as in the drawings).
- OSS9115 series — has no centre-tap.

MECHANICAL DATA (continued)

n = total number of diodes.

Fig.7 OSM9115 -nE

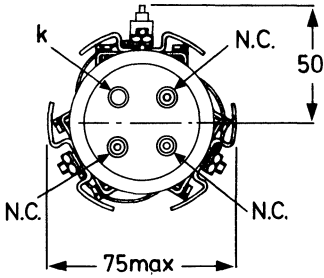
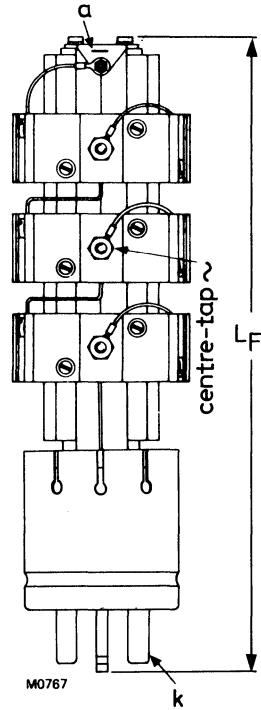
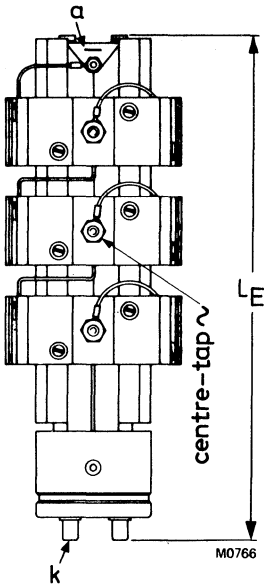
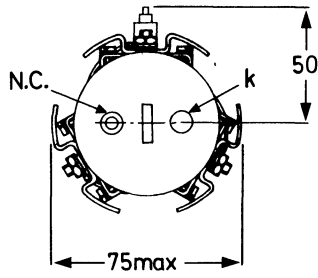


Fig.8 OSM9115 -nF



For lengths and weights see table on page 738.

Table of lengths and weights (mm and g)

number of diodes	n	3	4 to 6	7 to 9	10 to 12	13 to 15
maximum lengths	L _A	143	184	224	264	305
	L _B	147	188	228	268	309
	L _C	159	199	239	279	320
	L _E	132	173	213	253	294
	L _F	184	225	265	305	346
	weights	W _A	153	286	419	552
W _B = W _C = W _E		218	351	484	617	750
W _F		379	512	645	778	911

number of diodes	n	16 to 18	19 to 21	22 to 24	25 to 27	28 to 30
maximum lengths	L _A	345	385	426	466	506
	L _B	349	389	430	470	510
	L _C	360	400	441	481	521
	L _E	334	374	415	455	495
	L _F	386	426	467	507	547
	weights	W _A	818	951	1048	1217
W _B = W _C = W _E		883	1016	1149	1282	1415
W _F		1044	1177	1310	1443	1576

number of diodes	n	31 to 33	34 to 36
	L _A	546	586
	L _B	550	590
	L _C	561	601
	L _E	535	575
	L _F	587	627
	weights	W _A	1483
W _B = W _C = W _E		1548	1681
W _F		1709	1842

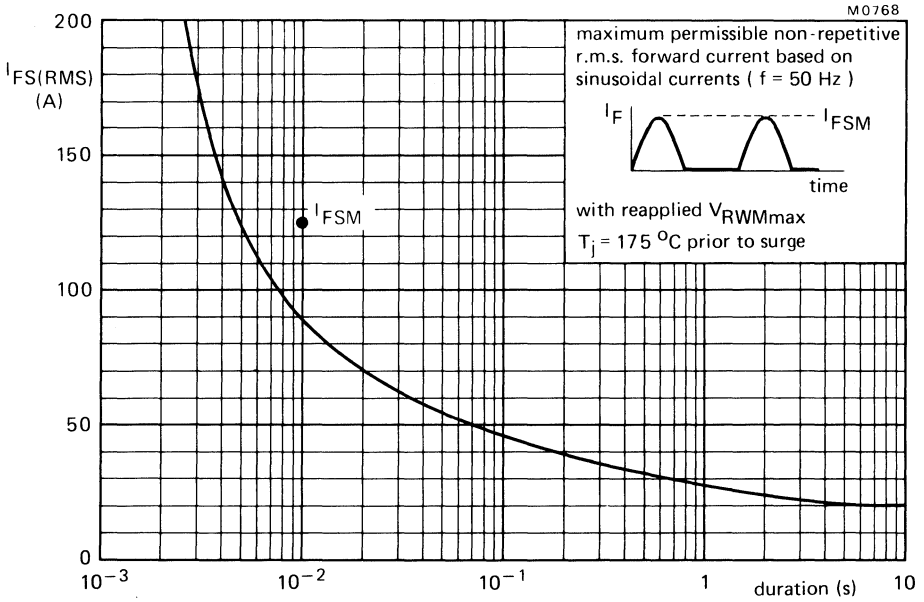


Fig.9

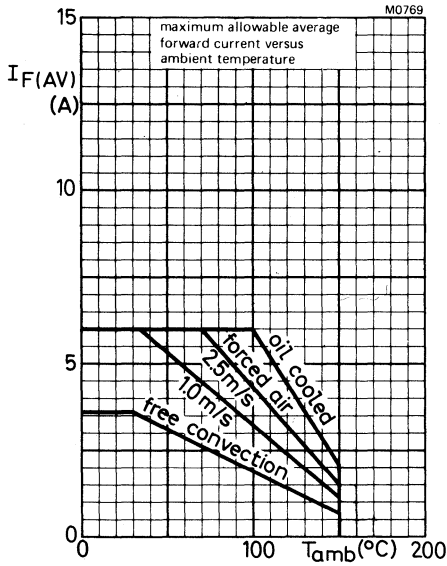


Fig.10

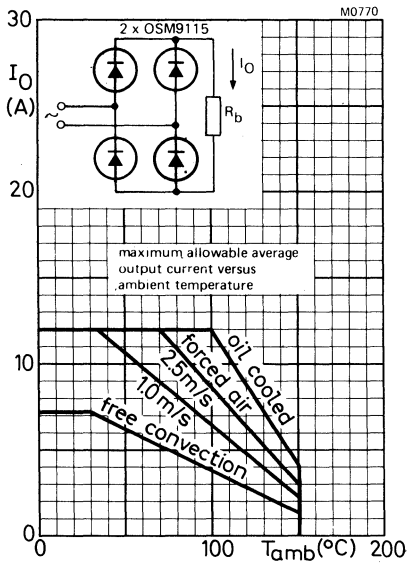


Fig.11

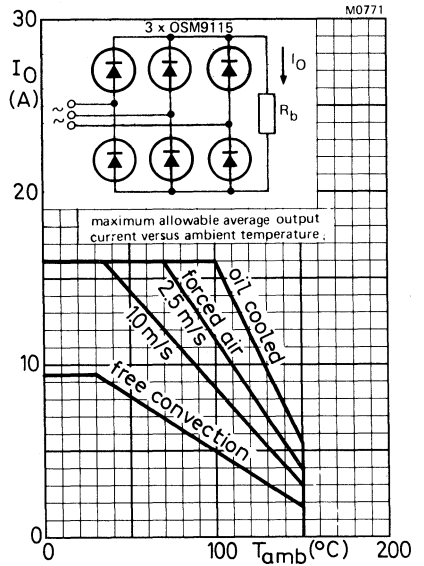


Fig.12

APPLICATION INFORMATION

Fig.13 OSB9115 -4

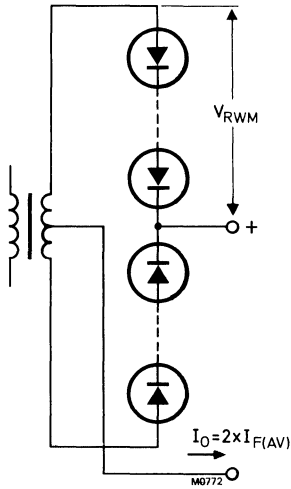
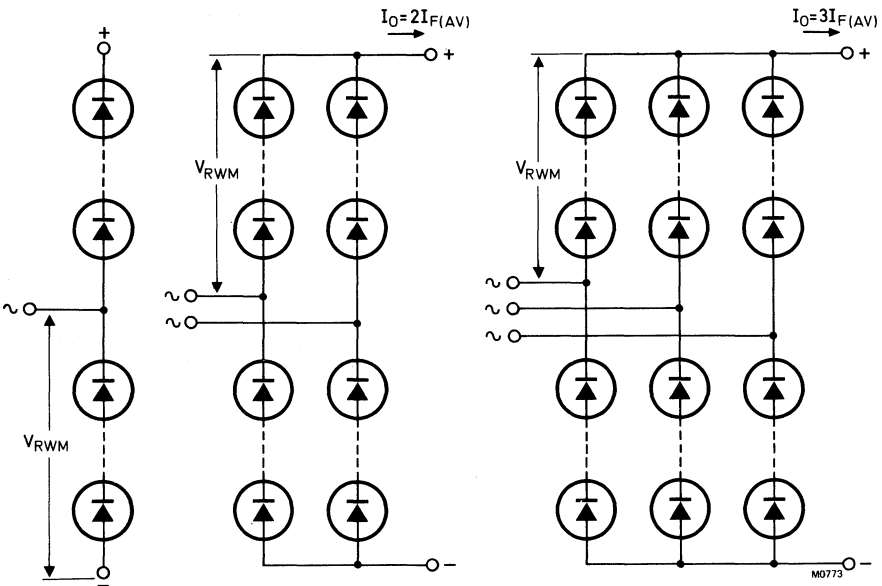


Fig.14 OSM9115 series



voltage doubler
1 x OSM9115

rectifier circuits with respectively
2 x OSM9115 and 3 x OSM9115

HIGH-VOLTAGE RECTIFIER STACKS

The OSB9215, OSM9215 and OSS9215 series are ranges of high-voltage rectifier assemblies, incorporating controlled avalanche diodes mounted on fire-proof triangular formers. The OSB9215 series is intended for application in two-phase half-wave rectifier circuits. The OSM9215 series is intended for application in single-phase or three-phase bridges or in voltage doubler circuits. The OSS9215 series is intended for all kinds of high-voltage rectification. The assemblies are supplied with M6 studs or with standard valve bases. The OSB9215 series and OSM9215 series are supplied with a centre tap (8-32UNC). The maximum crest working voltages of the OSB9215 and OSM9215 series cover the range from 3 kV to 27 kV, and of the OSS9215 series the range from 4.5 kV to 54 kV in 1.5 kV steps.

Configuration:

Fig. 1 OSB9215

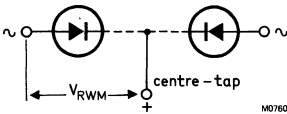


Fig. 2 OSM9215

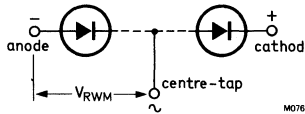
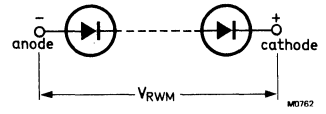


Fig. 3 OSS9215



QUICK REFERENCE DATA

		OSB9215	-4	-6	...	-34	-36
		OSM9215	-4	-6	...	-34	-36
Crest working reverse voltage from centre tap to end	V_{RWM}	max.	3	4.5	...	25.5	27 kV
			OSS9215	-3	-4	...	-35
Crest working reverse voltage	V_{RWM}	max.	4.5	6	...	52.5	54 kV
Average forward current with R and L load (averaged over any 20 ms period) in free air up to $T_{amb} = 35\text{ }^{\circ}\text{C}$ in oil up to $T_{oil} = 30\text{ }^{\circ}\text{C}$		$I_{F(AV)}$	max.	5	A		
		$I_{F(AV)}$	max.	20	A		
		I_{FSM}	max.	360	A		

MECHANICAL DATA (see pages 746 and 747)

All information applies to frequencies up to 400 Hz

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC134)

Voltages		OSB9215	-4	-6	...	4	-36
		OSM9215	-4	-6	...	-34	-36
Crest working reverse voltage	V_{RWM}	max.	3.0	4.5	...	25.5	27
Crest working reverse voltage	V_{RWM}	max.	4.5	6	...	52.5	54

Currents

Average forward current (averaged over any 20 ms period)

in free air up to $T_{amb} = 35\text{ }^{\circ}\text{C}$

$I_{F(AV)}$ max. 5 A

in oil up to $T_{oil} = 30\text{ }^{\circ}\text{C}$

$I_{F(AV)}$ max. 20 A

Repetitive peak forward current

I_{FRM} max. 440 A

Non-repetitive peak forward current

$t = 10\text{ ms}$; half sine-wave; $T_j = 175\text{ }^{\circ}\text{C}$ prior to surge

I_{FSM} max. 360 A

Reverse power dissipation

Repetitive peak reverse power

$t = 10\text{ }\mu\text{s}$ (square-wave; $f = 50\text{ Hz}$)

$T_j = 175\text{ }^{\circ}\text{C}$

		OSB9215	-4	-6	...	-34	-36
		OSM9215	-4	-6	...	-34	-36
P_{RRM}	max.	4	6	...	34	36	

Non-repetitive peak reverse power

$t = 10\text{ }\mu\text{s}$ (square-wave)

$T_j = 25\text{ }^{\circ}\text{C}$ prior to surge

$T_j = 175\text{ }^{\circ}\text{C}$ prior to surge

P_{RSM}	max.	26	39	...	221	234
P_{RSM}	max.	4	6	...	34	36

Repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$ (square-wave; $f = 50\text{ Hz}$)

$T_j = 175\text{ }^{\circ}\text{C}$

		OSS9215	-3	-4	...	-35	-36
P_{RRM}	max.	6	8	...	70	72	

Non-repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$ (square-wave)

$T_j = 25\text{ }^{\circ}\text{C}$ prior to surge

$T_j = 175\text{ }^{\circ}\text{C}$ prior to surge

P_{RSM}	max.	39	52	...	455	468
P_{RSM}	max.	6	8	...	70	72

Temperatures

Storage temperature

T_{stg} -55 to +150 $^{\circ}\text{C}$

Junction temperature

T_j max. 175 $^{\circ}\text{C}$

CHARACTERISTICS (see note 1)

		OSB9215	-4	-6	...	-34	-36		
		OSM9215	-4	-6	...	-34	-36		
Forward voltage									
$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	V_F	<	3.6	5.4	...	30.6	32.4	V	
Reverse breakdown voltage*									
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	>	3.3	4.95	...	28	29.7	kV	
		<	4.8	7.2	...	40.8	43.2	kV	
		OSS9215	-3	-4	...	-35	-36		
Forward voltage									
$I_F = 50 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	V_F	<	5.4	7.2	...	63	64.8	V	
Reverse breakdown voltage*									
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	>	4.95	6.6	...	57.8	59.4	kV	
		<	7.2	9.6	...	84	86.4	kV	
Reverse current									
$V_{RM} = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$					I_{RM}	<	0.6	mA	

Notes

1. The Ratings and Characteristics given apply **from centre tap to end**. (Not for OSS9215 series).

2. Type number suffix

The suffix consists of a figure indicating the total number of diodes, followed by a letter indicating the base.

- A = M6 studs at the ends
- B = 4 pin Super Jumbo (B4D)
- C = Goliath
- E = 4 pin Jumbo (B4F)
- F = A3-20

3. Operating position

The rectifier units can be operated at their maximum ratings when mounted in any position.

*The breakdown voltage increases by approximately 0.1% per $^\circ\text{C}$ with increasing junction temperature.

OSB 9215 SERIES
OSM9215 SERIES
OSS 9215 SERIES

MECHANICAL DATA

n = total number of diodes

Dimensions in mm

Fig. 4 OSM9215-nA

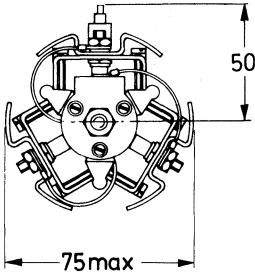


Fig. 5 OSM9215-nB

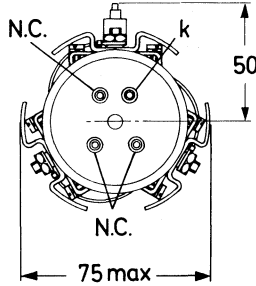
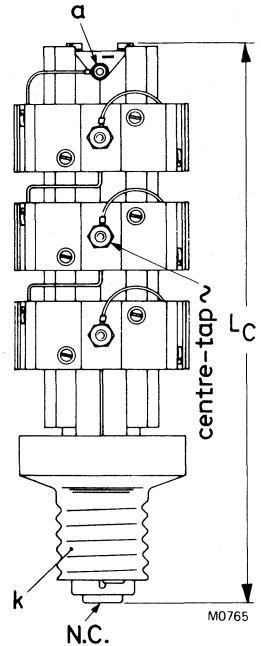
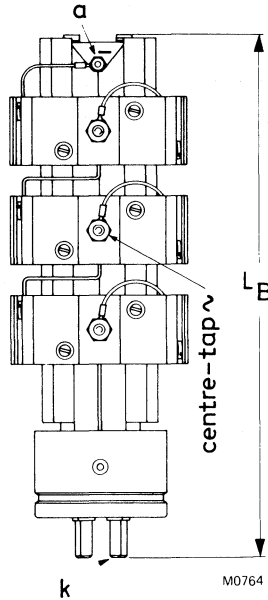
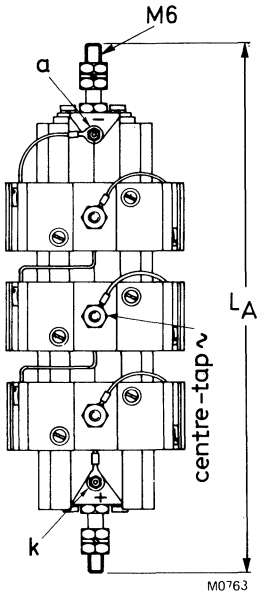
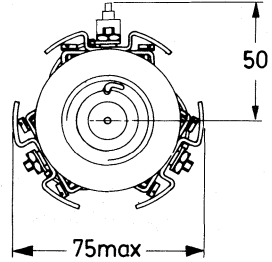


Fig. 6 OSM9215-nC



The drawings show the OSM9215 series; the OSB9215 and OSS9215 series differ in the following respects:

- OSB9215 series — terminals marked a(-) and k(+) in the drawings are both marked ~; the centre-tap is marked + (instead of ~ as in the drawings).
- OSS9215 series — has no centre-tap.

MECHANICAL DATA (continued)

n = total number of diodes.

Fig. 7 OSM9215-nE

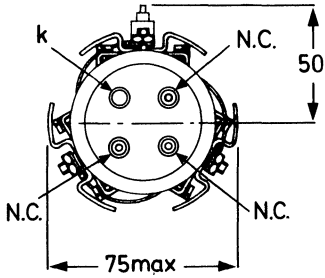
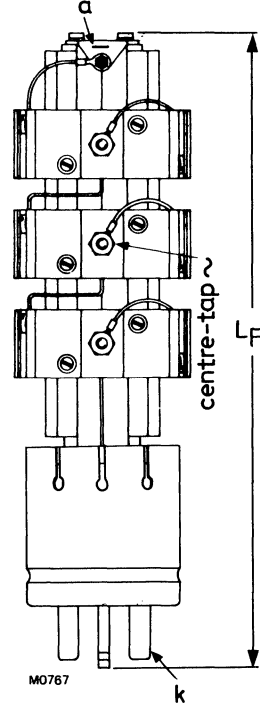
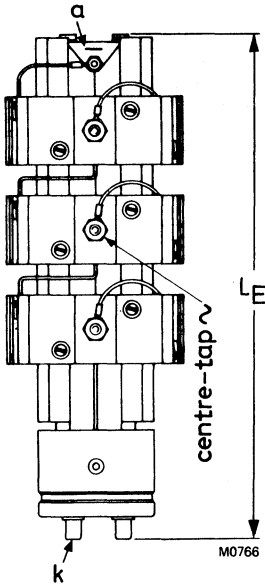
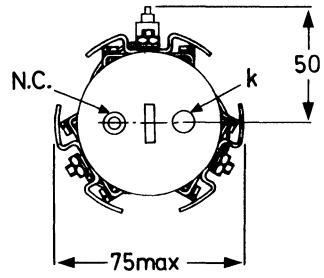


Fig. 8 OSM9215-nF



For lengths and weights see table on page 748.

Table of lengths and weights (mm and g)

number of diodes	n	3	4 to 6	7 to 9	10 to 12	13 to 15
maximum lengths	L _A	143	184	224	264	305
	L _B	147	188	228	268	309
	L _C	159	199	239	279	320
	L _E	132	173	213	253	294
	L _F	184	225	265	305	346
weight	W _A	153	286	419	552	685
	W _B = W _C = W _E	218	351	484	617	750
	W _F	379	512	645	778	911

number of diodes	n	16 to 18	19 to 21	22 to 24	25 to 27	28 to 30
maximum lengths	L _A	345	385	426	466	506
	L _B	349	389	430	470	510
	L _C	360	400	441	481	521
	L _E	334	374	415	455	495
	L _F	386	426	467	507	547
weights	W _A	818	951	1084	1217	1350
	W _B = W _C = W _E	883	1016	1149	1282	1415
	W _F	1044	1177	1310	1443	1576

number of diodes	n	31 to 33	34 to 36
maximum lengths	L _A	546	586
	L _B	550	590
	L _C	561	601
	L _E	535	575
	L _F	587	627
weights	W _A	1483	1616
	W _B = W _C = W _E	1548	1681
	W _F	1709	1842

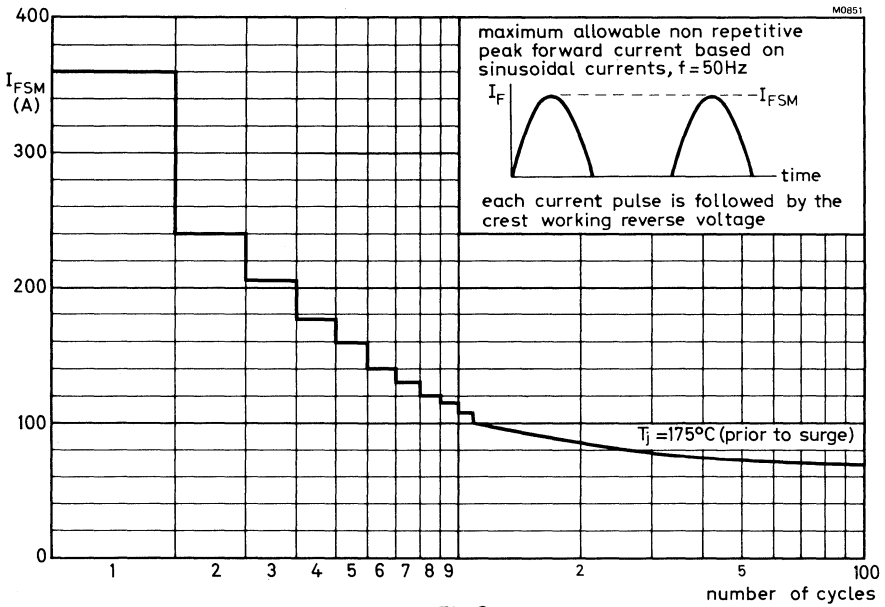


Fig. 9

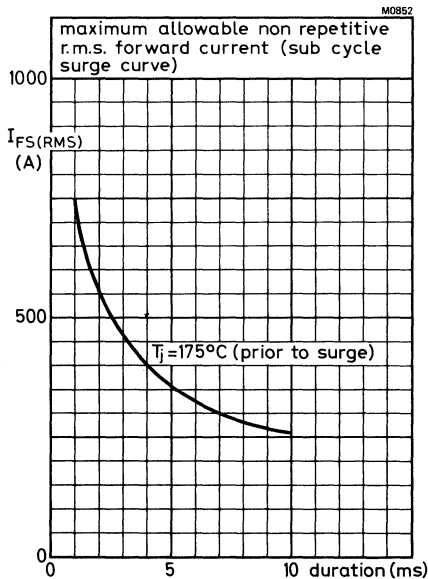


Fig. 10

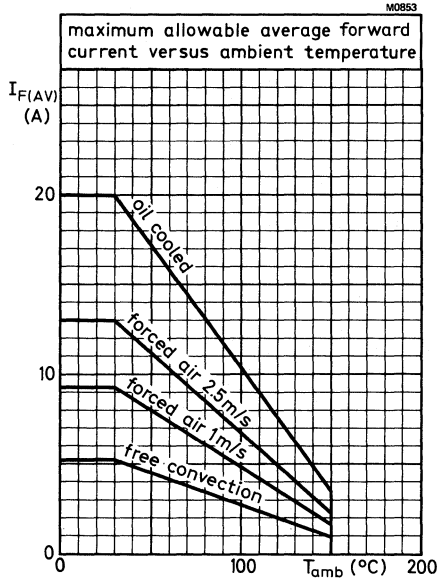


Fig. 11

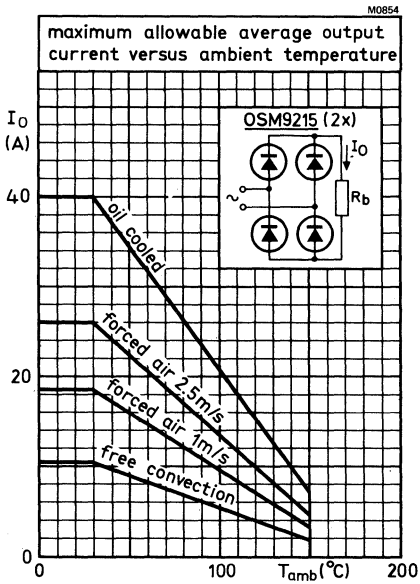


Fig. 12

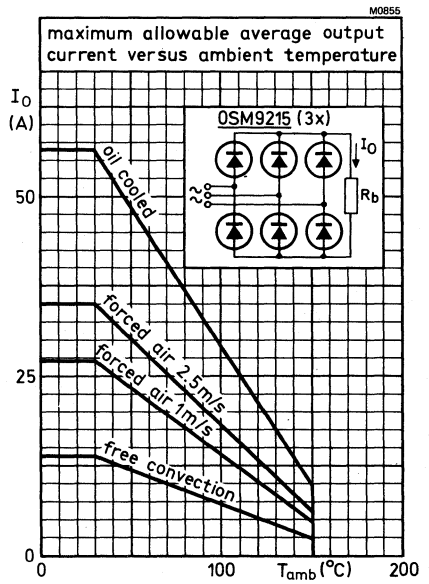


Fig. 13

APPLICATION INFORMATION

Fig. 14 OSB9215-4

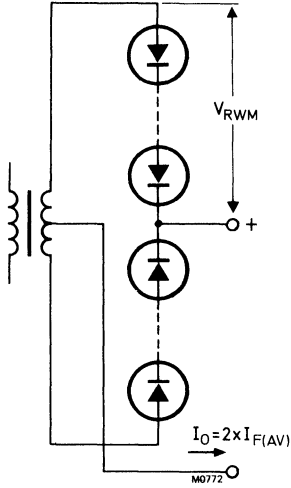
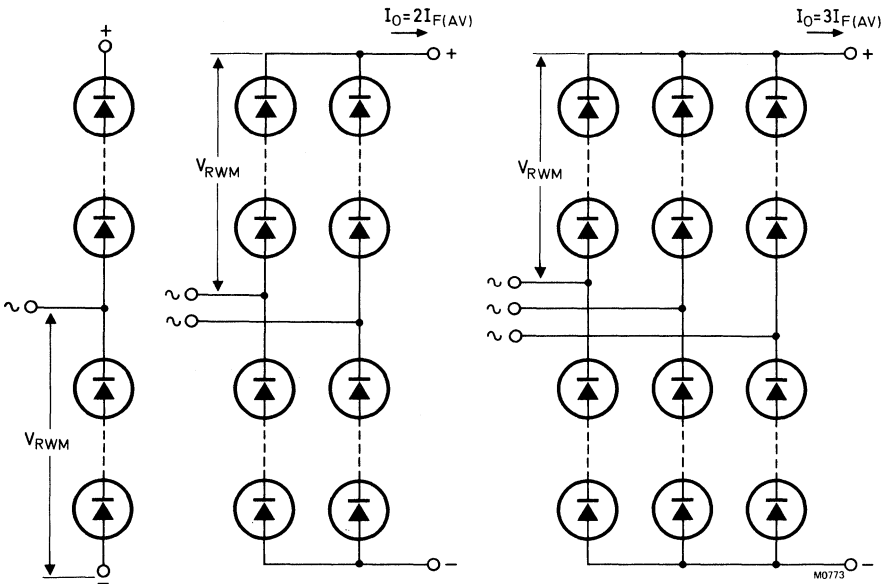


Fig. 15 OSM9215 series



voltage doubler
1x OSM9215

rectifier circuits with respectively
2x OSM9215 and 3x OSM9215

HIGH-VOLTAGE RECTIFIER STACKS

Ranges of high-voltage rectifier assemblies, incorporating controlled avalanche diodes mounted on fire-proof triangular formers. They are supplied with M6 studs.

The OSB9415 series is intended for application in two-phase half-wave rectifier circuits.

The OSM9415 series is intended for application in single-phase or three-phase bridges or in voltage doubler circuits.

The OSS9415 series is intended for all kinds of high-voltage rectification.

The OSB9415 series and OSM9415 series are supplied with a centre tap (8–32UNC).

The maximum crest working voltages of the OSB9415 and OSM9415 series cover the range from 3 kV to 27 kV, and of the OSS9415 series the range from 4.5 kV to 54 kV, in 1.5 kV steps.

Configuration:

Fig.1 OSB9415

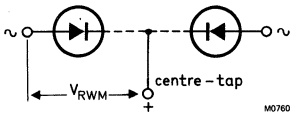


Fig.2 OSM9415

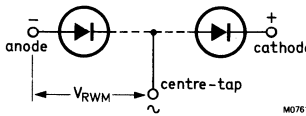
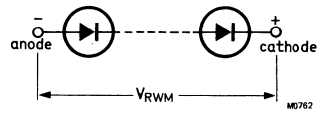


Fig.3 OSS9415



QUICK REFERENCE DATA

Crest working reverse voltage from centre tap to end	V_{RWM}	OSB9415	–4	–6	...	–34	–36	kV
		OSM9415	–4	–6	...	–34	–36	
Crest working reverse voltage	V_{RWM}	max.	3	4.5		25.5	27	kV
		OSS9415	–3	–4	...	–35	–36	
Average forward current with R and L load (averaged over any 20 ms period) in free air up to $T_{amb} = 35\text{ }^{\circ}\text{C}$	$I_F(AV)$	max.	4.5	6	...	52.5	54	kV
		in oil up to $T_{oil} = 35\text{ }^{\circ}\text{C}$						
Non-repetitive peak forward current $t = 10\text{ ms}$; half sine wave; $T_j = 175\text{ }^{\circ}\text{C}$ prior to surge	I_{FSM}	max.				800	A	

MECHANICAL DATA (see page 756)

All information applies to frequencies up to 400 Hz

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

		OSB9415	-4	-6	...	-34	-36		
		OSM9415	-4	-6	...	-34	-36		
Voltages	Crest working reverse voltage	V_{RWM}	max.	3	4.5	...	25.5	27	kV
			OSS9415	-3	-4	...	-35	-36	
	Crest working reverse voltage	V_{RWM}	max.	4.5	6	...	52.5	54	kV

Currents

Average forward current (averaged over any 20 ms period)

in free air up to $T_{amb} = 35\text{ }^\circ\text{C}$

$I_{F(AV)}$ max. 10 A

in oil up to $T_{oil} = 35\text{ }^\circ\text{C}$

$I_{F(AV)}$ max. 30 A

Repetitive peak forward current

I_{FRM} max. 450 A

Non-repetitive peak forward current

$t = 10\text{ ms}$; half sine-wave;

$T_j = 175\text{ }^\circ\text{C}$ prior to surge

I_{FSM} max. 800 A

Reverse power dissipation

		OSB9415	-4	-6	...	-34	-36			
		OSM9415	-4	-6	...	-34	-36			
Repetitive peak reverse power dissipation	$t = 10\text{ }\mu\text{s}$ (square-wave; $f = 50\text{ Hz}$)	$T_j = 175\text{ }^\circ\text{C}$	P_{RRM}	max.	9	13.5	...	76.5	81	kW

Non-repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$ (square-wave)

$T_j = 25\text{ }^\circ\text{C}$ prior to surge

$T_j = 175\text{ }^\circ\text{C}$ prior to surge

P_{RSM} max. 55 82 ... 467 495 kW

P_{RSM} max. 8.5 13 ... 72 77 kW

		OSS9415	-3	-4	...	-35	-36			
Repetitive peak reverse power dissipation	$t = 10\text{ }\mu\text{s}$ (square-wave; $f = 50\text{ Hz}$)	$T_j = 175\text{ }^\circ\text{C}$	P_{RRM}	max.	13.5	18	...	157	162	kW

Non-repetitive peak reverse power dissipation

$t = 10\text{ }\mu\text{s}$ (square-wave)

$T_j = 25\text{ }^\circ\text{C}$ prior to surge

$T_j = 175\text{ }^\circ\text{C}$ prior to surge

P_{RSM} max. 80 105 ... 919 945 kW

P_{RSM} max. 13 17 ... 149 153 kW

Temperatures

Storage temperature

T_{stg} -55 to +150 $^\circ\text{C}$

Junction temperature

T_j max. 175 $^\circ\text{C}$

CHARACTERISTICS (See note 1)

		OSB9415	-4	-6	. . .	-34	-36	
		OSM9415	-4	-6	. . .	-34	-36	
Forward voltage								
$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	V_F	<	3.6	5.4	. . .	30.6	32.4	V
Reverse avalanche breakdown voltage*								
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	>	3.3	4.95	. . .	28	29.7	kV
		<	4.8	7.2	. . .	40.8	43.2	kV
		OSS9415	-3	-4	. . .	-35	-36	
Forward voltage								
$I_F = 150 \text{ A}; T_j = 25 \text{ }^\circ\text{C}$	V_F	<	5.4	7.2	. . .	63	64.8	V
Reverse avalanche breakdown voltage*								
$I_R = 5 \text{ mA}; T_j = 25 \text{ }^\circ\text{C}$	$V_{(BR)R}$	>	4.95	6.6	. . .	57.8	59.4	kV
		<	7.2	9.6	. . .	84	86.4	kV
Reverse current								
$V_{RM} = V_{RWMmax}; T_j = 125 \text{ }^\circ\text{C}$								
						$I_{RM} < 1.6$		mA

NOTES

1. The Ratings and Characteristics given apply **from centre tap to end**..(Not for OSS9415 series).
2. **Type number suffix**
The suffix consists of a figure indicating the total number of diodes, followed by a letter indicating the base. .
A = M6 studs at the ends.
3. **Operating position**
The rectifier units can be operated at their maximum ratings when mounted in any position.

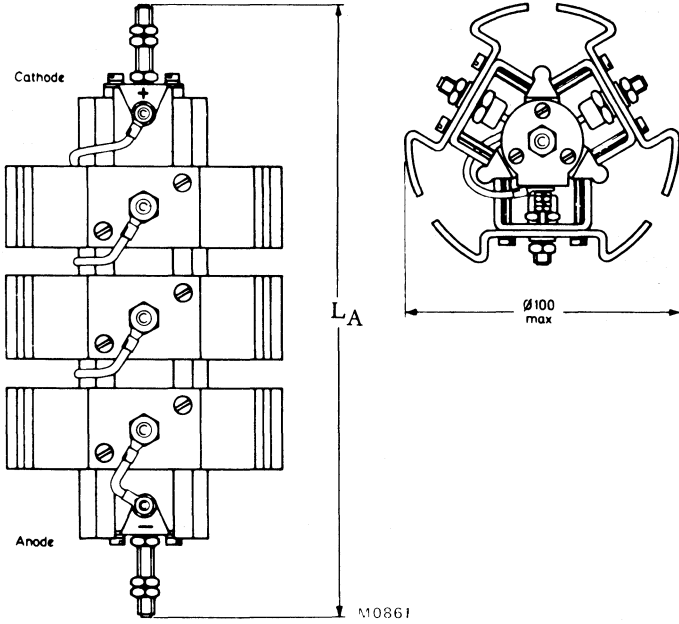
* The breakdown voltage increases, by approximately 0.1% per $^\circ\text{C}$ with increasing junction temperature.

MECHANICAL DATA

Dimensions in mm

n = total number of diodes.

Fig.4 OSS9415-nA



The drawing shows the OSS9415 series.

The OSB9415 and OSM9415 series differ in the following respects:

OSB9415 series — has a centre tap marked +; anode and cathode terminals are both marked ~.

OSM9415 series — has a centre tap marked ~.

Table of lengths and weights (mm and g)

number of diodes	n	3	4 to 6	7 to 9	10 to 12	13 to 15
maximum lengths	L _A	143	184	224	264	305
weights	W _A	215	413	611	809	1007

number of diodes	n	16 to 18	19 to 21	22 to 24	25 to 27	28 to 30	31 to 33	34 to 36
maximum lengths	L _A	345	385	426	466	506	546	586
weights	W _A	1208	1406	1604	1802	2000	2198	2396

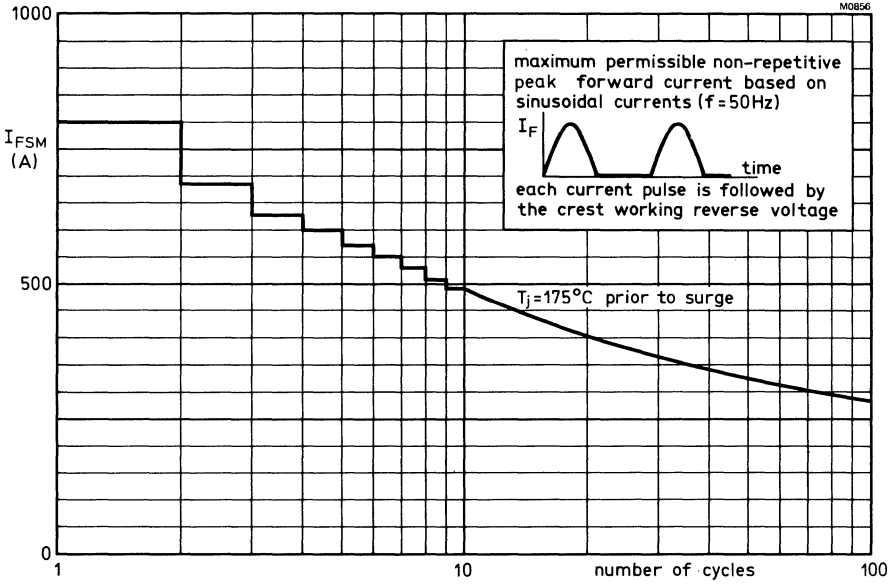


Fig.5

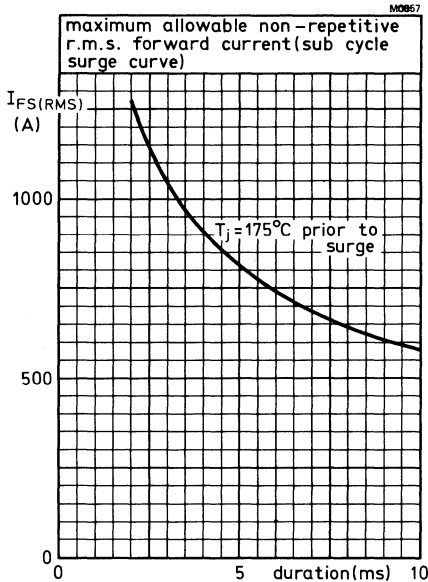
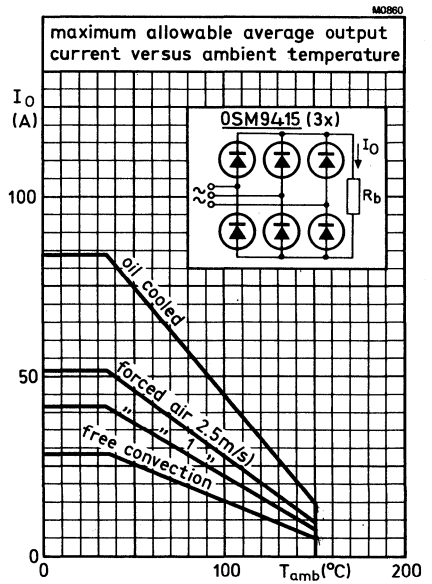
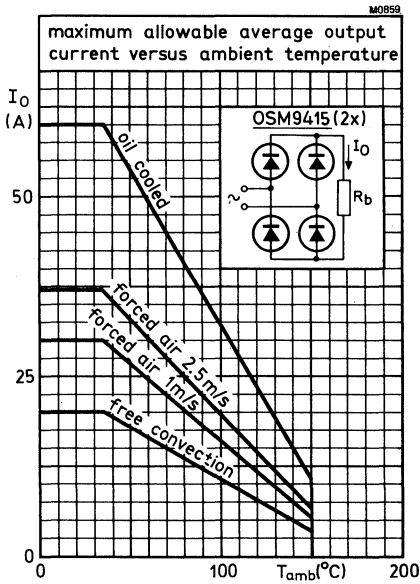
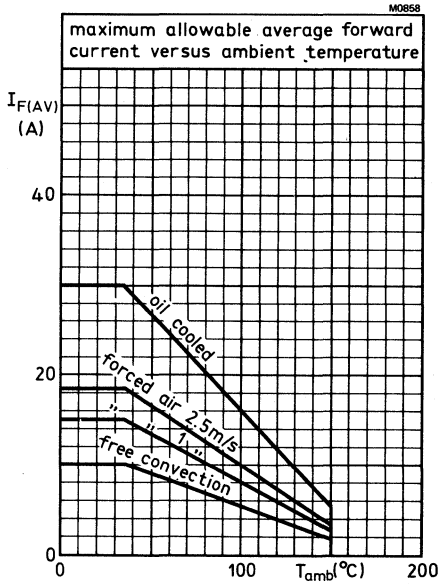


Fig.6



APPLICATION INFORMATION

Fig.10 OSB9415 series

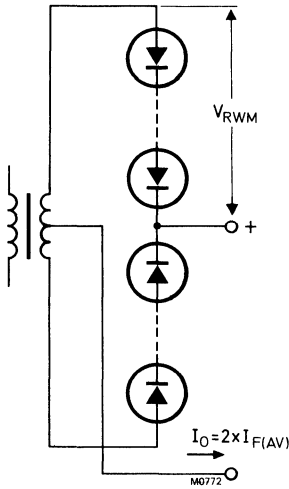
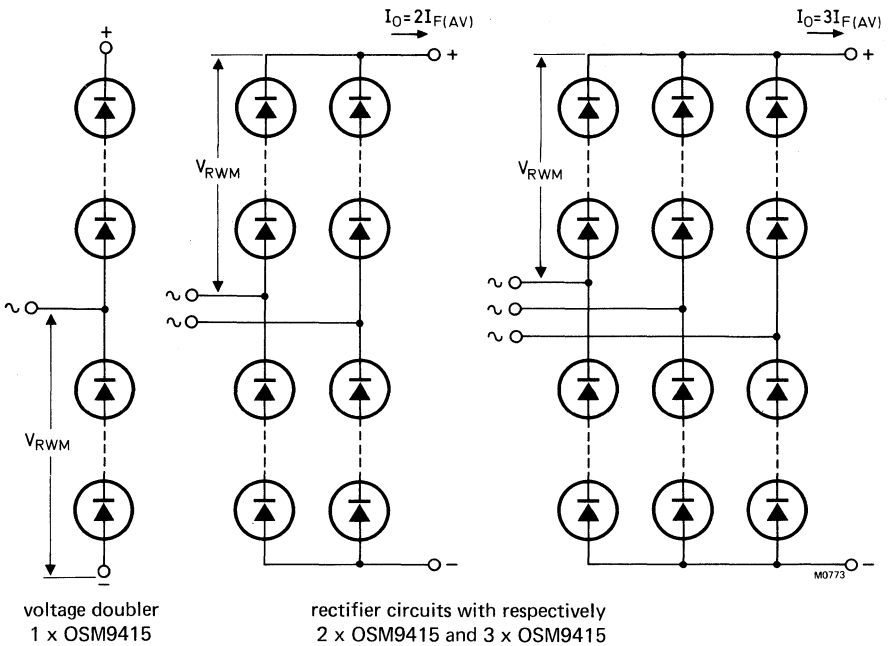


Fig.11 OSM9415 series





HIGH-VOLTAGE RECTIFIER STACK

The OSM9510-12 is a silicon rectifier stack for high voltage applications, up to 12kV in half-wave circuits, or up to 6kV as one of the arms of a bridge configuration, where the centre-tap is utilised. Because of its controlled avalanche characteristics it is capable of withstanding reverse transients generated in the circuit.

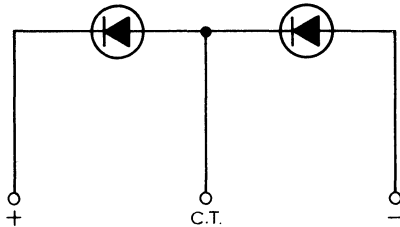
QUICK REFERENCE DATA

V_{RWM} max.	12	kV
$V_{(BR)R}$ min.	15	kV
$I_{F(AV)}$ max., in free air, $T_{amb} = 50^{\circ}\text{C}$	1.5	A
P_{RSM} max., $t = 10\mu\text{s}$, $T_{amb} = 25^{\circ}\text{C}$	20	kW

OUTLINE AND DIMENSIONS

For details see page 763

CIRCUIT DIAGRAM



RATINGS

Limiting values of operation according to the absolute maximum system. These ratings apply for the frequency range 50 to 400Hz. Simultaneous application of all ratings is inferred unless otherwise stated.

Electrical

V_{RWM} max.	Crest working reverse voltage	12	kV
$I_{F(AV)}$ max.	Mean forward current in free air, $T_{amb} \leq 50^{\circ}C$, 180 ^o conduction	1.5	A
See derating curves on page 764			
I_{FRM} max.	Repetitive peak forward current, 30 ^o conduction	15	A
I_{FSM} max.	Surge forward current, 1 cycle (10ms peak of half sinewave)	35	A
P_{RSM} max.	Non-repetitive peak reverse power (10 μ s square wave, $T_j = 25^{\circ}C$)	20	kW
P_{RRM} max.	50Hz repetitive peak reverse transient power (10 μ s square wave, $T_j = 150^{\circ}C$)	5.0	kW

Temperature

T_{stg}	Storage temperature	-55 to 150	^o C
T_j	Junction temperature	-55 to 150	^o C

ELECTRICAL CHARACTERISTICS ($T_j = 25^{\circ}C$ unless otherwise stated)

		Min.	Max.	
* V_F	Forward voltage at $I_F = 5A$	-	17.5	V
I_R	Reverse current at $V_{RWM}, T_j = 125^{\circ}C$	-	100	μA
$V_{(BR)R}$	**Avalanche breakdown voltage, $I_{(BR)R} = 1mA$	15	25	kV

*Measured under pulsed conditions so that T_j is at, or near, the stated value.

**The avalanche voltage increases by approximately 0.1%/degC with increasing T_j .

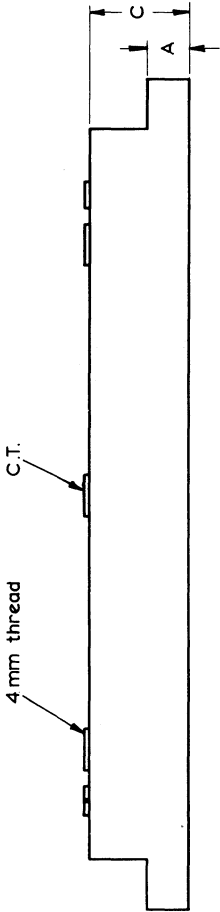
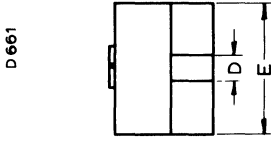
MECHANICAL DATA

Weight	130	g
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MOUNTING POSITION

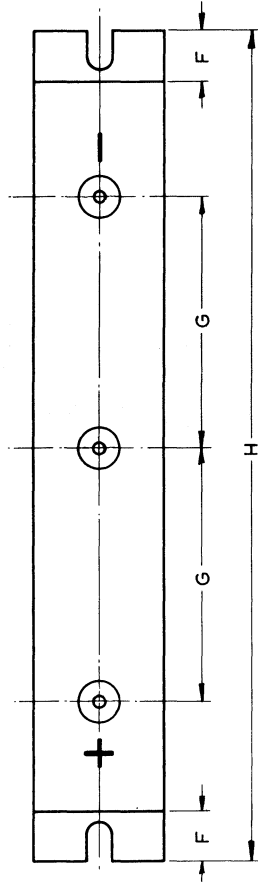
The rectifier units can be operated at their maximum ratings when mounted in any position.

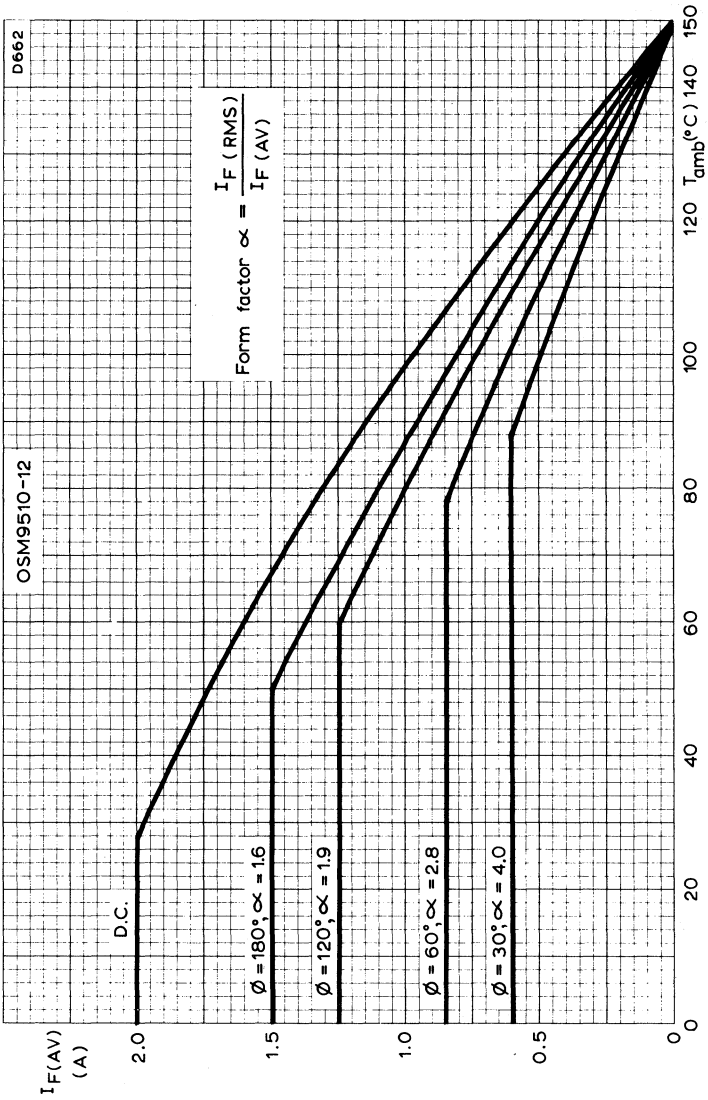
OUTLINE AND DIMENSIONS



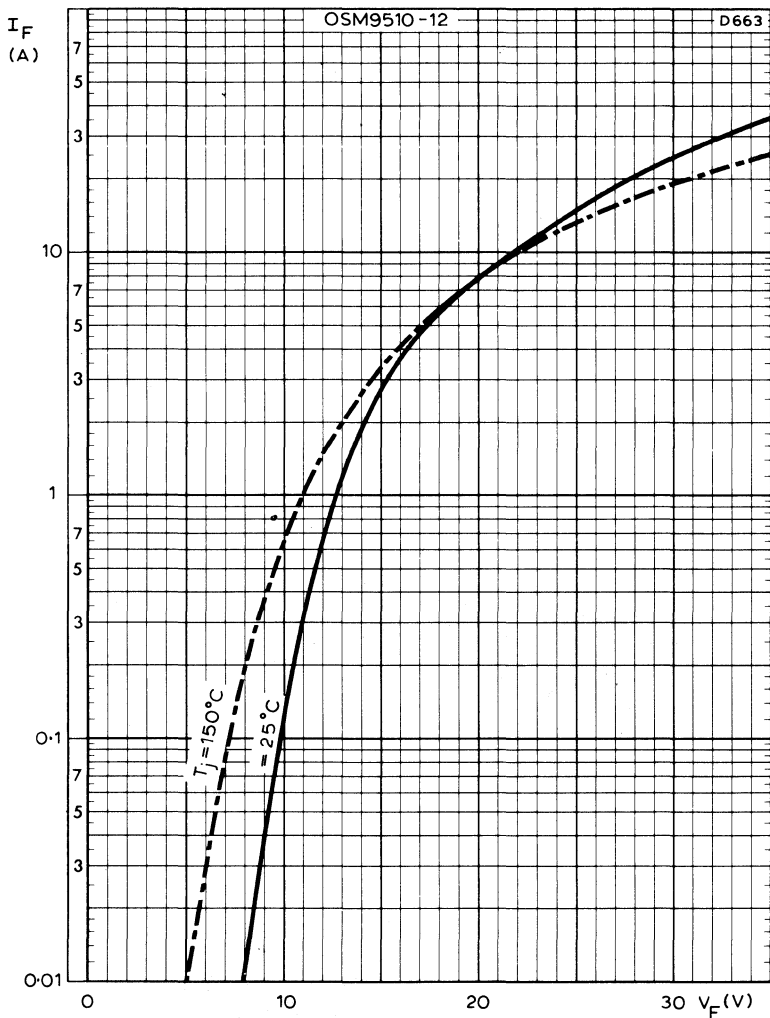
Millimetres

A	8.0
C	18.5
D	5.3
E	26
F	10
G	50
H	165

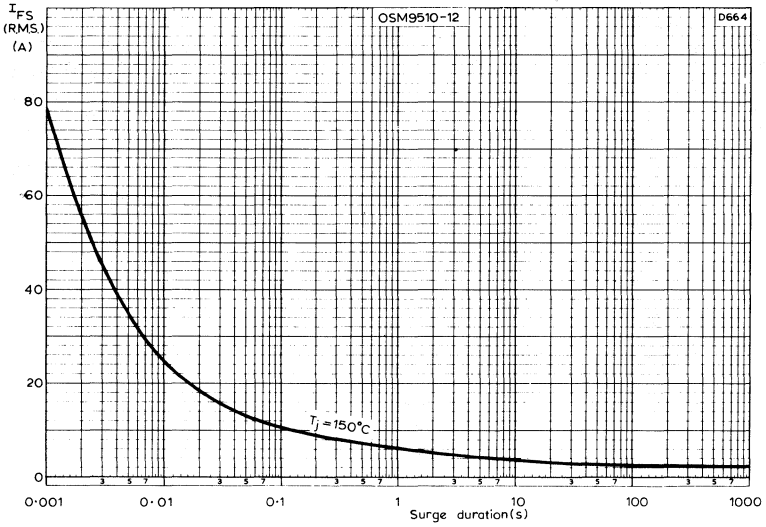




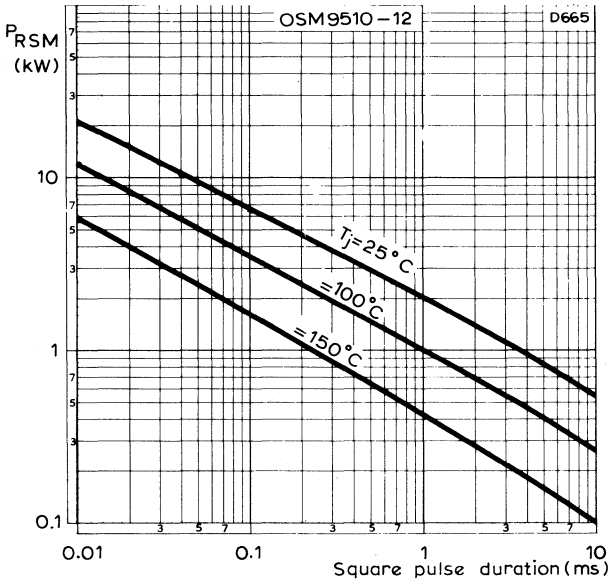
MAXIMUM MEAN FORWARD CURRENT AS A FUNCTION OF AMBIENT TEMPERATURE AND CONDUCTION ANGLE



MAXIMUM FORWARD CONDUCTION CHARACTERISTICS



MAXIMUM R.M.S. SURGE CURRENT PLOTTED AGAINST SURGE DURATION



NON-REPETITIVE PEAK REVERSE POWER PLOTTED AGAINST SQUARE PULSE DURATION

ACCESSORIES

TYPE NUMBER SUMMARY

type number	description	envelope
56264a	mica washer (up to 2000 V)	DO-5, TO-48
56264b	insulating bush	DO-5, TO-48
56295a	mica washer (up to 2000 V)	DO-4, TO-64
56295b	PTFE ring	DO-4, TO-64
56295c	insulating bush	DO-4, TO-64
56359b	mica washer (up to 1000 V)	TO-220
56359c	insulating bush (up to 800 V)	TO-220
56359d	rectangular insulating bush (up to 1000 V)	TO-220
56360a	rectangular washer	TO-220
56363	spring clip (direct mounting)	TO-220, SOT-186 ←
56364	spring clip (insulated mounting)	TO-220
56367	alumina insulator (up to 2000 V)	TO-220
56368b	insulating bush (up to 800 V)	SOT-93
56368c	mica insulator (up to 800 V)	SOT-93 ←
56369	mica insulator (up to 2000 V)	TO-220
56378	mica insulator (up to 1500 V)	SOT-93
56379	spring clip	SOT-93, SOT-112

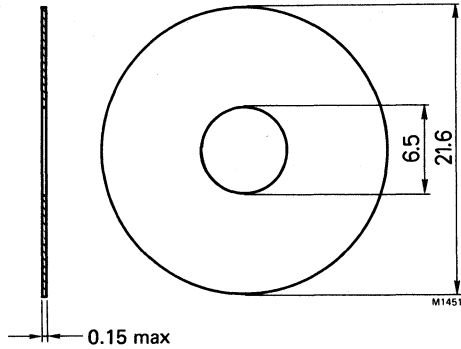
56264a

MICA WASHER

Insulator up to 2000 V

MECHANICAL DATA

Dimensions in mm

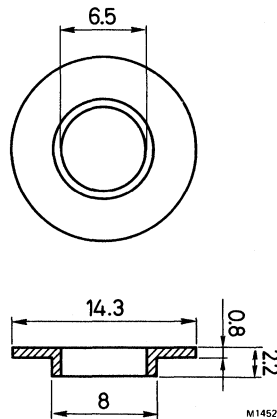


56264b

INSULATING BUSH

MECHANICAL DATA

Dimensions in mm



THERMAL RESISTANCE

From mounting base to heatsink

- with mica washer, without heatsink compound
- with mica washer, with heatsink compound

$R_{th\ mb-h}$	=	5	K/W
$R_{th\ mb-h}$	=	2.5	K/W

TEMPERATURE

Maximum allowable temperature

T_{max}	=	175	°C
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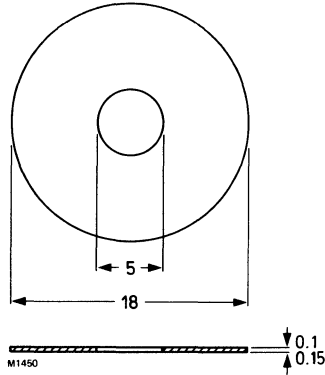
56295a

MICA WASHER

Insulator up to 2 kV.

MECHANICAL DATA

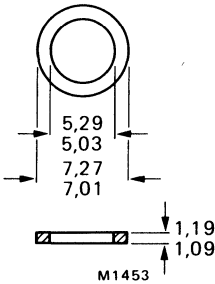
Dimensions in mm



56295b PTFE RING

MECHANICAL DATA

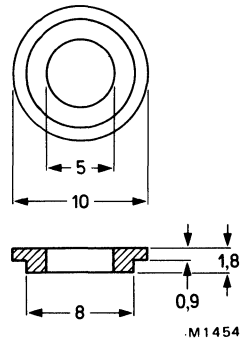
Dimensions in mm



56295c INSULATING BUSH

MECHANICAL DATA

Dimensions in mm



THERMAL RESISTANCE

From mounting base to heatsink
without heatsink compound
with heatsink compound

$R_{th\ mb-h}$ = 5 K/W
 $R_{th\ mb-h}$ = 2.5 K/W

TEMPERATURE

Maximum allowable temperature

T_{max} = 175 °C

ACCESSORIES
for TO-220

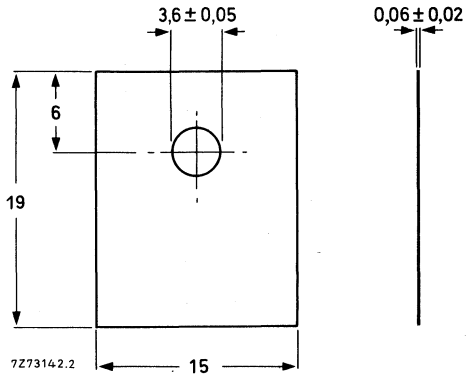
56359b

MICA WASHER

Insulator up to 1000 V.

MECHANICAL DATA

Dimensions in mm



56359c

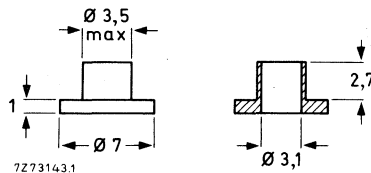
INSULATING BUSH

Insulator up to 800 V.

MECHANICAL DATA

Material: polyester

Dimensions in mm



TEMPERATURE

Maximum permissible
temperature

$T_{max} = 150\text{ }^{\circ}\text{C}$

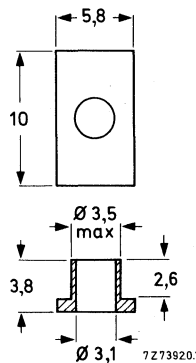
56359d

RECTANGULAR INSULATING BUSH

Insulator up to 1000 V.

MECHANICAL DATA

Dimensions in mm



TEMPERATURE

Maximum permissible
temperature

$T_{max} = 150\text{ }^{\circ}\text{C}$

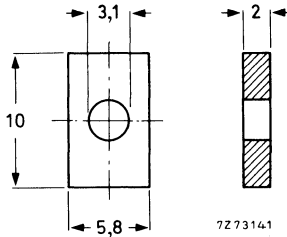
56360a

RECTANGULAR WASHER (For TO-220)

For direct and insulated mounting.

MECHANICAL DATA

Material: brass; nickel plated.



Dimensions in mm

56363

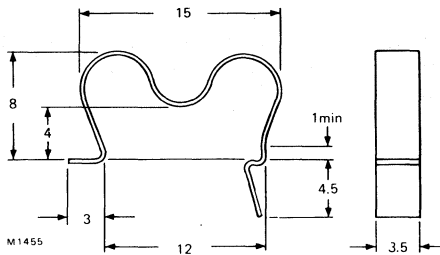
SPRING CLIP (For TO-220 and SOT-186)

For direct mounting.

MECHANICAL DATA

Material: stainless steel; for mounting on heatsink of 1.0 to 2.0 mm.

Recommended force of clip on device is 20 N (2 kgf).



Dimensions in mm

56364

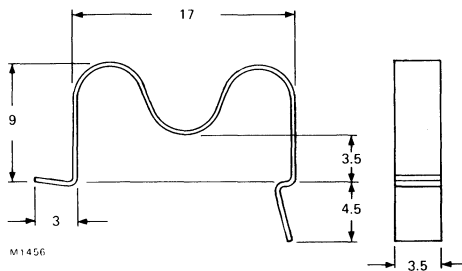
SPRING CLIP (For TO-220)

For insulated mounting.

MECHANICAL DATA

Material: stainless steel; for mounting on heatsink of 1.0 to 1.5 mm.

Recommended force of clip on device is 20 N (2 kgf).



Dimensions in mm

To be used in conjunction with insulators 56367 or 56369

56367

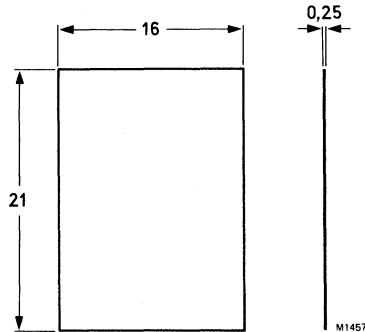
ALUMINA INSULATOR

For insulated clip mounting up to 2 kV.

MECHANICAL DATA

Material: 96-alumina.

Dimensions in mm



*Because alumina is brittle, extreme care must be taken when mounting devices not to crack the alumina, particularly when used without heatsink compound.

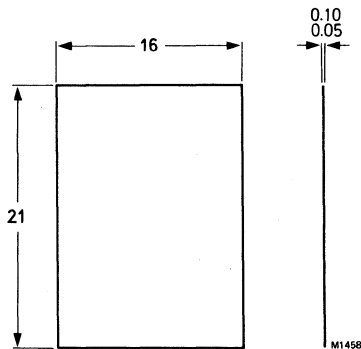
56369

MICA INSULATOR

For insulated clip mounting up to 2 kV.

MECHANICAL DATA

Dimensions in mm



56368b

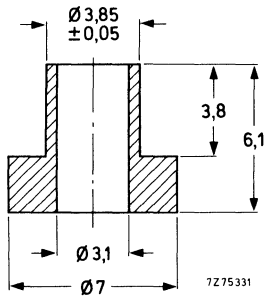
INSULATING BUSH

For insulated screw mounting up to 800 V.

MECHANICAL DATA

Material: polyester

Dimensions in mm



TEMPERATURE

Maximum permissible temperature

$T_{\max} = 150^{\circ}\text{C}$

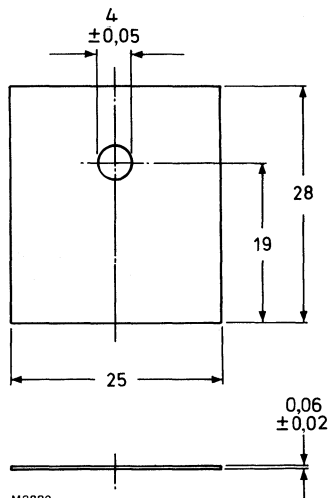
56368C

MICA INSULATOR

For insulated screw mounting up to 800 V.

MECHANICAL DATA

Dimensions in mm



56369: see preceding page.

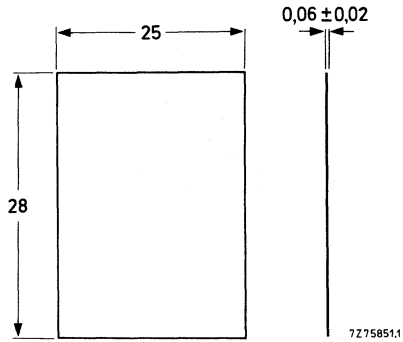
56378

MICA INSULATOR

For clip mounting up to 1500 V.

MECHANICAL DATA

Dimensions in mm



56379

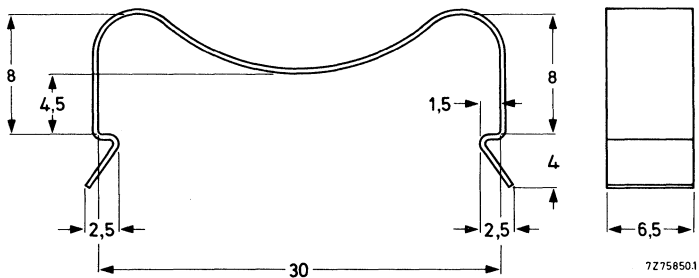
SPRING CLIP

For direct and insulated mounting of SOT-93 and SOT-112 envelopes.

MECHANICAL DATA

Dimensions in mm

Material:
CrNi steel NLN-939;
thickness 0.4 ± 0.04 .



MOUNTING INSTRUCTIONS

MOUNTING INSTRUCTIONS FOR TO-220 ENVELOPES

GENERAL DATA AND INSTRUCTIONS

General rules

1. First fasten the device to the heatsink before soldering the leads.
2. Avoid axial stress to the leads.
3. Keep mounting tool (e.g. screwdriver) clear of the plastic body.
4. The rectangular washer may only touch the plastic part of the body; it should not exert any force on that part (screw mounting).

Heatsink requirements

Flatness in the mounting area: 0,02 mm maximum per 10 mm.

Mounting holes must be deburred, see further mounting instructions.

Heatsink compound

Values of the thermal resistance from mounting base to heatsink ($R_{th\ mb-h}$) given for mounting with heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.

For insulated mounting, the compound should be applied to the bottom of both device and insulator.

Mounting methods for power devices

1. Clip mounting

Mounting with a spring clip gives:

- a. A good thermal contact under the crystal area, and slightly lower $R_{th\ mb-h}$ values than screw mounting.
- b. Safe insulation for mains operation.

2. M3 screw mounting

It is recommended that the rectangular spacing washer is inserted between screw head and mounting tab.

Mounting torque for screw mounting:

(For thread-forming screws these are final values. Do not use self-tapping screws.)

Minimum torque (for good heat transfer)	0,55 Nm (5,5 kgcm)
Maximum torque (to avoid damaging the device)	0,80 Nm (8,0 kgcm)

N.B.: When a nut or screw is not driven direct against a curved spring washer or lock washer (not for thread-forming screw), the torques are as follows:

Minimum torque (for good heat transfer)	0,4 Nm (4 kgcm)
Maximum torque (to avoid damaging the device)	0,6 Nm (6 kgcm)

3. Rivet mounting non-insulated

The device should not be pop-riveted to the heatsink. However, it is permissible to press-rivet providing that eyelet rivets of soft material are used, and the press forces are slowly and carefully controlled so as to avoid shock and deformation of either heatsink or mounting tab.

Thermal data

→ (Typical figures, for exact figures see data for each device type).

		clip mounting	screw mounting	
From mounting base to heatsink				
with heatsink compound, direct mounting	$R_{th\ mb-h}$	= 0,3	0,5	K/W
without heatsink compound, direct mounting	$R_{th\ mb-h}$	= 1,4	1,4	K/W
with heatsink compound and 0,1 mm maximum mica washer	$R_{th\ mb-h}$	= 2,2	—	K/W
with heatsink compound and 0,25 mm maximum alumina insulator	$R_{th\ mb-h}$	= 0,8	—	K/W
with heatsink compound and 0,05 mm mica washer insulated up to 500 V	$R_{th\ mb-h}$	= —	1,4	K/W
insulated up to 800 V/1000 V	$R_{th\ mb-h}$	= —	1,6	K/W
without heatsink compound and 0,05 mm mica washer insulated up to 500 V	$R_{th\ mb-h}$	= —	3,0	K/W
insulated up to 800 V/1000 V	$R_{th\ mb-h}$	= —	4,5	K/W

Lead bending

Maximum permissible tensile force on the body, for 5 seconds is 20 N (2 kgf).

The leads can be bent through 90° maximum, twisted or straightened. To keep forces within the above-mentioned limits, the leads are generally clamped near the body, using pliers. The leads should neither be bent nor twisted less than 2,4 mm from the body.

Soldering

Lead soldering temperature at > 3 mm from the body; $t_{sld} < 5$ s:

Devices with $T_j\ max \leq 175$ °C, soldering temperature $T_{sld\ max} = 275$ °C.

Devices with $T_j\ max \leq 110$ °C, soldering temperature $T_{sld\ max} = 240$ °C.

Avoid any force on body and leads during or after soldering: do not correct the position of the device or of its leads after soldering.

It is not permitted to solder the metal tab of the device to a heatsink, otherwise its junction temperature rating will be exceeded.

Mounting base soldering

Recommended metal-alloy of solder paste (85% metal weight)

62 Sm/36 Pb/2 Ag or 60 Sn/40 Pb.

Maximum soldering temperature ≤ 200 °C (tab-temperature).

Soldering cycle duration including pre-heating ≤ 30 sec.

For good soldering and avoiding damage to the encapsulation pre-heating is recommended to a temperature ≤ 165 °C at a duration ≤ 10 s.

INSTRUCTIONS FOR CLIP MOUNTING

Direct mounting with clip 56363

1. Apply heatsink compound to the mounting base, then place the device on the heatsink.
2. Push the short end of the clip into the narrow slot in the heatsink with clip at an angle of 10° to 30° to the vertical (see Figs 1 and 2).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear on the plastic body, not on the tab (see Fig.2a).
Do not insert more than 1 mm beyond final position.

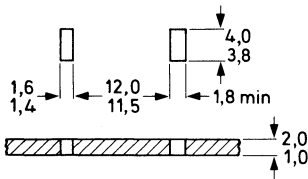


Fig. 1 Heatsink requirements.

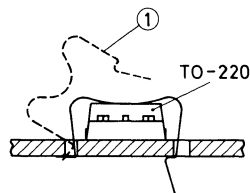


Fig. 2 Mounting.
(1) spring clip 56363.

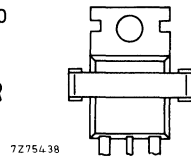


Fig. 2a Position of device (top view).

Insulated mounting with clip 56364

With the insulators 56367 or 56369 insulation up to 2 kV is obtained.

1. Apply heatsink compound to the bottom of both device and insulator, then place the device with the insulator on the heatsink.
2. Push the short end of the clip into the narrow slot in the heatsink with the clip at an angle of 10° to 30° to the vertical (see Figs 3 and 4).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear on the plastic body, not on the tab. Ensure that the device is centred on the mica insulator to prevent creepage.
Do not insert more than 1 mm beyond final position.

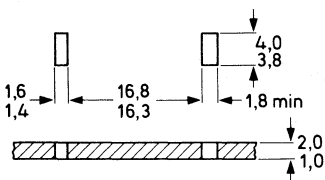


Fig. 3 Heatsink requirements.

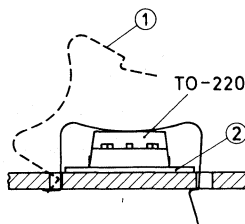


Fig. 4 Mounting.
(1) spring clip 56364.
(2) insulator 56369 or 56367.

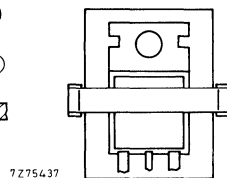


Fig.4a Position of device (top view).

INSTRUCTIONS FOR SCREW MOUNTING

Direct mounting with screw and spacing washer

Dimensions in mm

- *through heatsink with nut*

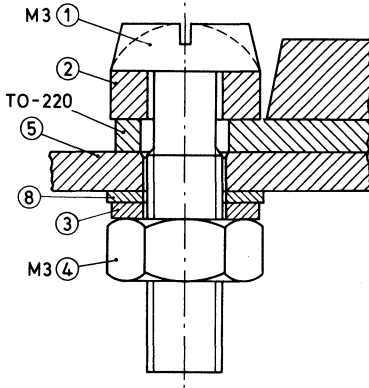


Fig. 5 Assembly.

- (1) M3 screw.
- (2) rectangular washer (56360a).
- (3) lock washer.
- (4) M3 nut.
- (5) heatsink.
- (8) plain washer.

- *into tapped heatsink*

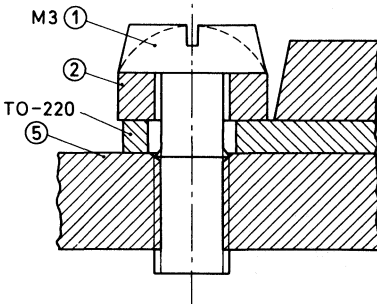
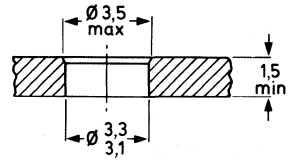


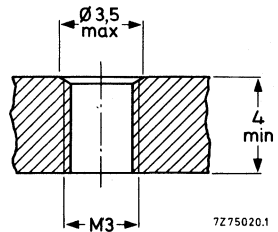
Fig. 7 Assembly.

- (1) M3 screw.
- (2) rectangular washer 56360a.
- (5) heatsink.



72 69693.2

Fig. 6 Heatsink requirements.



72 75020.1

Fig. 8 Heatsink requirements.

Insulated mounting with screw and spacing washer
(not recommended where mounting tab is on mains voltage)

Dimensions in mm

• *through heatsink with nut*

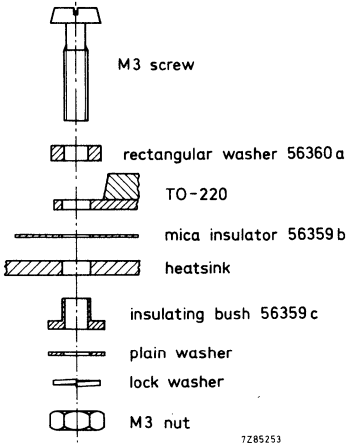


Fig. 9 Insulated screw mounting with rectangular washer. Known as a "bottom mounting".

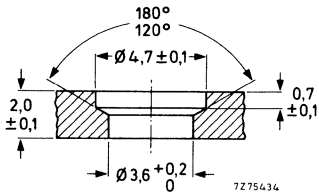


Fig. 10 Heatsink requirements for 500 V insulation.

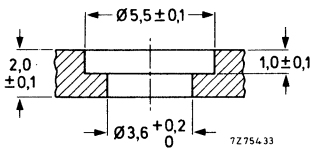


Fig. 11 Heatsink requirements for 800 V insulation.

• *into tapped heatsink*

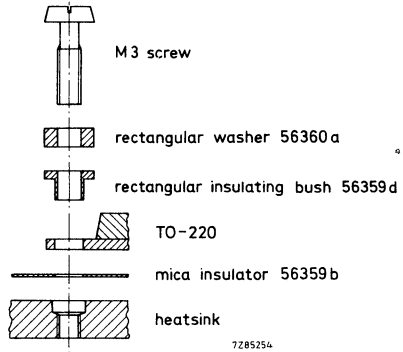


Fig. 12 Insulated screw mounting with rectangular washer into tapped heatsink. Known as a "top mounting".

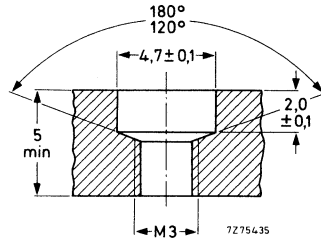


Fig. 13 Heatsink requirements for 500 V insulation.

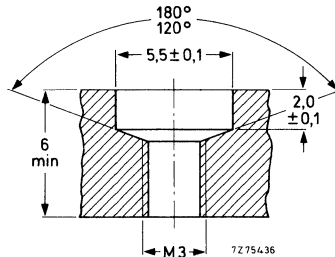


Fig. 14 Heatsink requirements for 1000 V insulation.

MOUNTING INSTRUCTIONS FOR TO-220 FULL-PACK (SOT-186) DEVICES

Use of full-pack (SOT-186 envelope) devices allows an insulated mounting with up to 1kV isolation. These devices require the assembly of less components than TO-220 devices with insulating washers.

GENERAL DATA AND INSTRUCTIONS

General rules

1. Mounting instructions for voltage isolation are given for guidance. Users should acquaint themselves with the relevant statutory and mandatory regulations if the heatsink is earthed or may be touched.
2. Fasten device to heatsink before soldering the leads.
3. Avoid axial stress to the leads.
4. Be careful to avoid damaging plastic with mounting tool (e.g. screwdriver).
5. If a rectangular washer (part no. 56360a) is used in screw mounting it may only touch the main part of the body, it should not exert any force on this part.

Heatsink requirements

Flatness in the mounting area: 0.02mm maximum per 10mm.

Mounting holes must be deburred.

Heatsink compound

Values of thermal resistance given using heatsink compound refer to the use of a metallic oxide-loaded compound. Ordinary silicone grease is not recommended.

Mounting methods for power devices

1. Clip mounting:

This gives better thermal contact under the crystal area than screw mounting.

For details of mounting force for spring clip mounting see data sheet "Accessories for TO-220".

2. M3 screw mounting:

It is recommended that a rectangular spacing washer (part no. 56360a) is inserted between the screw head and plastic mounting tab.

N.B. Data on accessories are given in separate data sheet "Accessories for TO-220".

Mounting torque for screw mounting:

(For thread-forming screws these are final values. Do not use self-tapping screws.)

Minimum torque (for good heat transfer)	0.55 Nm (5.5 kgcm)
Maximum torque (to avoid damaging the device)	0.80 Nm (8.0 kgcm)

N.B. When a nut or screw is not driven against a curved spring washer or lock washer (not for thread-forming screws) the torques are as follows:

Minimum torque (for good heat transfer)	0.40 Nm (4.0 kgcm)
Maximum torque (to avoid damaging device)	0.60 Nm (6.0 kgcm)

3. Rivet mounting:

This method is **NOT** recommended because it will damage the plastic encapsulation.

MOUNTING INSTRUCTIONS F-PACK

Lead bending

(Maximum permissible tensile force on the body, for 5 seconds is 20N (2kgf).

The leads should not be bent less than 2.4mm from the seal, and should be supported during bending.

The leads can be bent, twisted or straightened by 90° maximum. The minimum bending radius is 1mm.

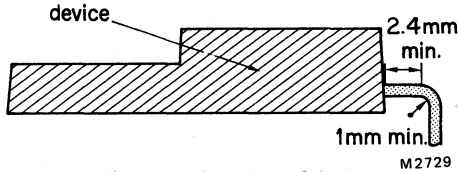


Fig.1 Lead bending of devices.

Soldering

Lead soldering temperature at >3mm from body for $t_{sld} < 5$ seconds:

Devices with $T_j \text{ max.} \leq 175^\circ\text{C}$, $T_{sld} \text{ max.} = 275^\circ\text{C}$.

Devices with $T_j \text{ max.} \leq 110^\circ\text{C}$, $T_{sld} \text{ max.} = 240^\circ\text{C}$.

Avoid any force on body and leads during or after soldering. Do not correct the position of the devices or of its leads after soldering.

INSTRUCTIONS FOR CLIP MOUNTING

1. Apply heatsink compound to the mounting base, then place device on heatsink.
2. Push the short end of clip (part no. 56363) into the narrow slot in the heatsink with the clip at an angle of between 10° to 30° to the vertical (see Figs.2 & 3).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear down on the main part of the body, not on the tab (see Fig.3a).

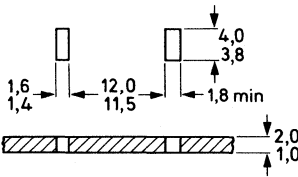


Fig.2 Heatsink requirements

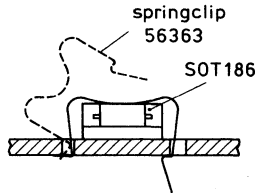


Fig.3 Mounting.

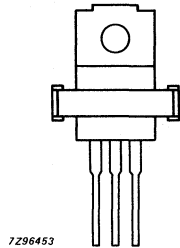


Fig.3a Position of device (top view).

INSTRUCTIONS FOR SCREW MOUNTING

Screw through heatsink with nut

Dimensions in mm

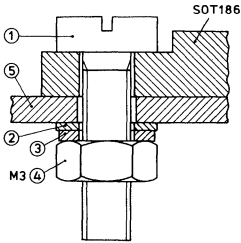


Fig.4 Assembly.

- (1) M3 screw
- (2) plain washer
- (3) lock washer
- (4) M3 nut
- (5) heatsink

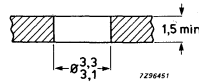


Fig.5 Heatsink requirements.

Into tapped heatsink

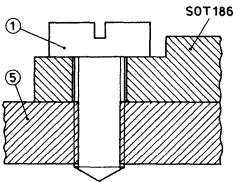


Fig.6 Assembly.

- (1) M3 screw
- (5) heatsink

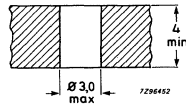


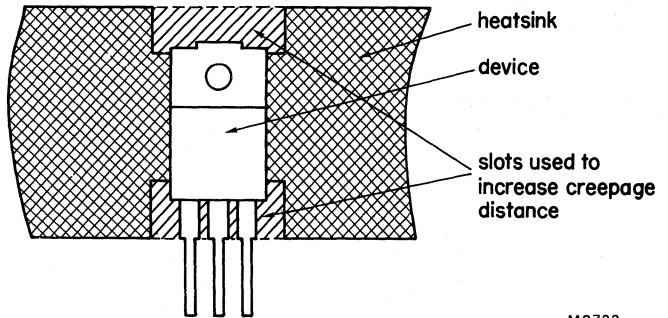
Fig.7 Heatsink requirements.

MOUNTING INSTRUCTIONS F-PACK

MOUNTING REQUIREMENTS FOR VOLTAGE ISOLATION

Full-pack devices may be used to maintain voltage isolation between the heatsink and the electrical circuit. However, users must ensure that there is a sufficient creepage distance between the exposed metal of the device (at both the lead and tab ends) and the heatsink. The distance required will vary according to the application and the regulations that may apply.

To increase the creepage distances the heatsink may be formed with slots or holes around the lead and tab ends of the device. The dimensions of the holes will vary according to the creepage distances required. For detail see Fig.8.



M2733

Fig.8 Slots formed in heatsink to increase creepage distance.

MOUNTING INSTRUCTIONS FOR SOT-93 ENVELOPES

GENERAL DATA AND INSTRUCTIONS

General rule

Avoid any sudden forces on leads and body; these forces, such as from falling on a hard surface, are easily underestimated. In the direct screw mounting an M4 screw must be used; an M3 screw in the insulating mounting.

Heatsink requirements

Flatness in the mounting area: 0,02 mm maximum per 10 mm.
The mounting hole must be deburred.

Heatsink compound

The thermal resistance from mounting base to heatsink ($R_{th\ mb-h}$) can be reduced by applying a metallic-oxide heatsink compound between the contact surfaces. For insulated mounting the compound should be applied to the bottom of both device and insulator.

Maximum play

The bush or the washer may only just touch the plastic part of the body, but should not exert any force on that part. Keep mounting tool (e.g. screwdriver) clear of the plastic body.

Mounting torques

For M3 screw (insulated mounting):

Minimum torque (for good heat transfer)	0,4 Nm (4 kgcm)
Maximum torque (to avoid damaging the device)	0,6 Nm (6 kgcm)

For M4 screw (direct mounting only):

Minimum torque (for good heat transfer)	0,4 Nm (4 kgcm)
Maximum torque (to avoid damaging the device)	1,0 Nm (10 kgcm)

Note: The M4 screw head should not touch the plastic part of the envelope.

Lead bending

Maximum permissible tensile force on the body for 5 s 20 N (2 kgf)

No torsion is permitted at the emergence of the leads.

Bending or twisting is not permitted within a lead length of 0,3 mm from the body of the device. ←

The leads can be bent through 90° maximum, twisted or straightened; to keep forces within the above-mentioned limits, the leads should be clamped near the body. ←

Soldering

Recommendations for devices with a maximum junction temperature rating ≤ 175 °C:

a. Dip or wave soldering

Maximum permissible solder temperature is 260 °C at a distance from the body of > 5 mm and for a total contact time with soldering bath or waves of < 7 s.

b. Hand soldering

Maximum permissible temperature is 275 °C at a distance from the body of > 3 mm and for a total contact time with the soldering iron of < 5 s.

The body of the device must not touch anything with a temperature > 200 °C.

It is not permitted to solder the metal tab of the device to a heatsink, otherwise the junction temperature rating will be exceeded.

Avoid any force on body and leads during or after soldering; do not correct the position of the device or of its leads after soldering.

Thermal data

→ (Typical figures, for exact figures see data for each device type).

Thermal resistance from mounting base to heatsink

direct mounting

with heatsink compound

without heatsink compound

with 0,05 mm mica washer

with heatsink compound

without heatsink compound

	clip mounting	screw mounting
$R_{th\ mb-h}$ =	0,3	0,3 K/W
$R_{th\ mb-h}$ =	1,5	0,8 K/W
$R_{th\ mb-h}$ =	0,8	0,8 K/W
$R_{th\ mb-h}$ =	3,0	2,2 K/W

INSTRUCTIONS FOR CLIP MOUNTING

Direct mounting with clip 56379

- Place the device on the heatsink, applying heatsink compound to the mounting base.
- Push the short end of the clip into the narrow slot in the heatsink with the clip at an angle of 10° to 20° to the vertical (see Fig. 1b).
- Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear on the plastic body, not on the tab (see Fig. 1(c)).

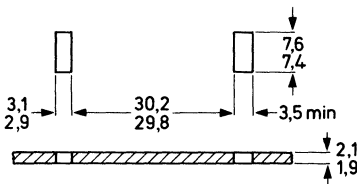


Fig. 1a Heatsink requirements.

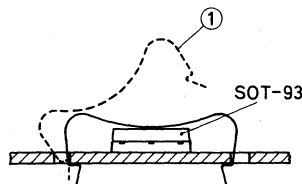


Fig. 1b Mounting.
(1) = spring clip 56379.

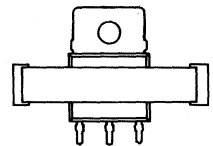


Fig. 1c Position of the device.

Insulated mounting with clip 56379

With the mica 56378 insulation up to 1500 V is obtained.

1. Place the device with the insulator on the heatsink, applying heatsink compound to the bottom of both device and insulator.
2. Push the short end of the clip into the narrow slot in the heatsink with the clip at an angle of 10° to 20° to the vertical (see Figs 2a and 2b).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot in the heatsink. The clip should bear on the plastic body, not on the tab (see Fig. 2c). There should be minimum 3 mm distance between the device and the edge of the insulator for adequate creepage.

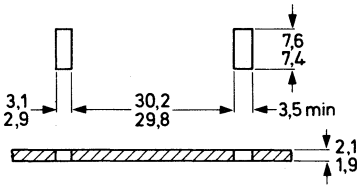


Fig. 2a Heatsink requirements.

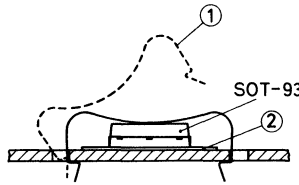


Fig. 2b Mounting.
(1) = spring clip 56379
(2) = insulator 56378

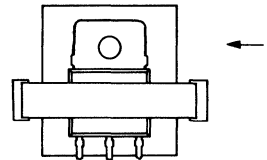


Fig. 2c Position of the device.

INSTRUCTIONS FOR SCREW MOUNTING

Direct mounting

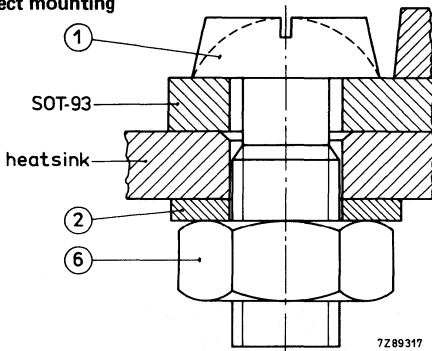


Fig. 3a Assembly through heatsink with nut.

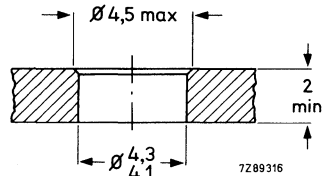


Fig. 3b Heatsink requirements.

When screw mounting the SOT-93 envelope, it is particularly important to apply a thin, even layer of heatsink compound to the mounting base, and to apply torque to the screw slowly so that the compound has time to flow and the mounting base is not deformed. Most SOT-93 envelopes contain a crystal larger than that in the other plastic envelopes, and it is more likely to crack if the mounting base is deformed.

Legend: (1) M4 screw; (2) plain washer; (6) M4 nut.

Where vibrations are to be expected the use of a lock washer or of a curved spring washer is recommended, with a plain washer between aluminium heatsink and spring washer.

Insulated screw mounting with nut; up to 800 V.

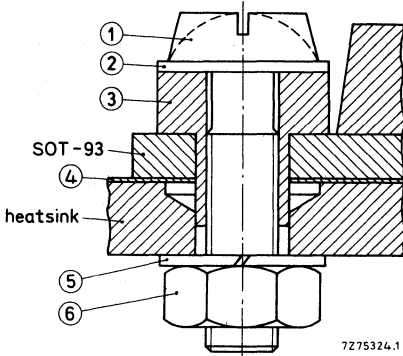


Fig. 4 Assembly.
See also Fig. 9.

- (1) M3 screw
- (2) plain washer
- (3) insulating bush (56368b)
- (4) mica insulator (56368c)
- (5) lock washer
- (6) M3 nut

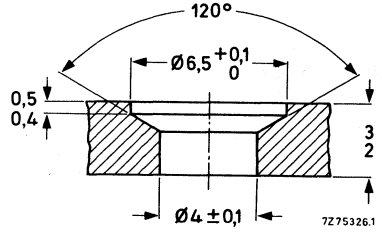


Fig. 5 Heatsink requirements
up to 800 V insulation.

Insulated screw mounting with tapped hole; up to 800 V.

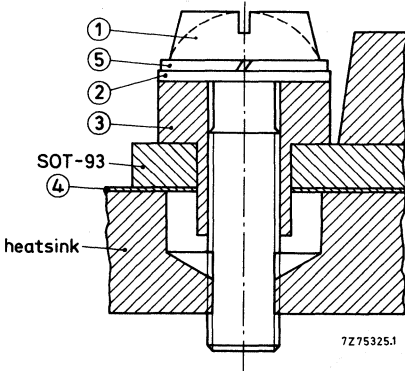


Fig. 6 Assembly.
See also Fig. 9.

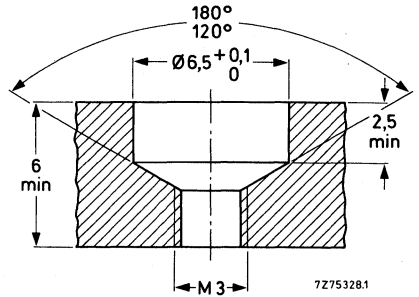


Fig. 7 Heatsink requirements
up to 800 V insulation.

- (1) M3 screw
- (2) plain washer
- (3) insulating bush (56368b)
- (4) mica insulator (56368c)
- (5) lock washer

Insulated screw mounting with insert nut; up to 500 V

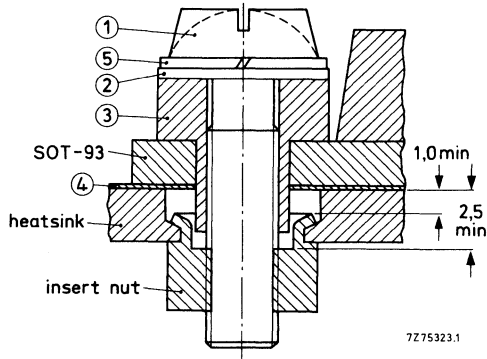


Fig. 8 Assembly and heatsink requirements for 500 V insulation. See also Fig. 3.

- (1) M3 screw
- (2) plain washer
- (3) insulating bush (56368b)
- (4) mica insulator (56368c)
- (5) lock washer

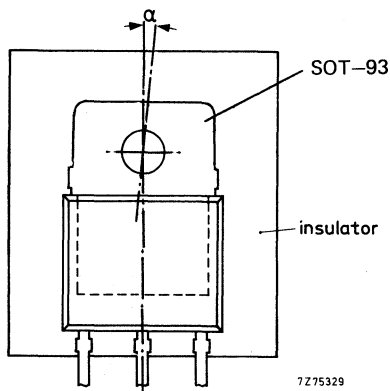


Fig. 9 Mica insulator.

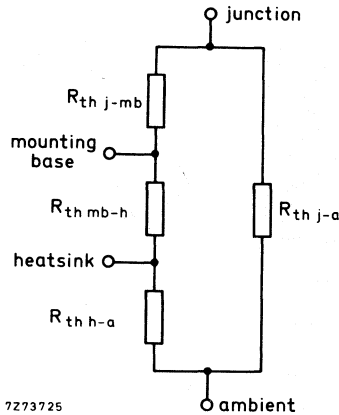
The axial deviation (α) between SOT-93 and mica should not exceed 5°.

MOUNTING CONSIDERATIONS FOR STUD-MOUNTED DEVICES

Losses generated in a silicon device must flow through the case and to a lesser extent the leads. The greatest proportion of the losses flow out through the case into a heat exchanger which can be either free convection cooled, forced convection or even liquid cooled. For the majority of devices in our range natural convection is generally adequate, however, where other considerations such as space saving must be taken into account then methods such as forced convection etc. can be considered. The thermal path from junction to ambient may be considered as a number of resistances in series. The first thermal resistance will be that of junction to mounting base, usually denoted by $R_{th\ j-mb}$. The second is the contact thermal resistance $R_{th\ mb-h}$ and finally there is the thermal resistance of the heatsink $R_{th\ h-a}$.

In the rating curves, the contact thermal resistance and heatsink thermal resistances are combined as a single figure - $R_{th\ mb-a}$.

In addition to the steady state thermal conditions of the system, consideration should also be given to the possibility of any transient thermal excursions. These can be caused for example by starting conditions or overloads and in order to calculate the effect on the device, a graph of transient thermal resistance $Z_{th\ j-mb}$ as a function of time is given in each data sheet.



When mounting the device on the heatsink, care should be taken that the contact surfaces are free from burrs or projections of any kind and must be thoroughly clean.

In the case where an anodised heatsink is used, the anodising should be removed from the contact surface ensuring good electrical and thermal contact.

The contact surfaces should be smeared with a metallic oxide-loaded grease to ensure good heat transfer. Where the device is mounted in a tapped hole, care should be taken that the hole is perpendicular to the surface of the heatsink. When mounting the device to the heatsink, it is essential that a proper torque wrench is used, applying the correct amount of torque as specified in the published data.

Excessive torque can distort the threads of the device and may even cause mechanical stress on the wafer, leading to the possible failure.

Where isolation of the device from the heatsink is required, it is common practice to use a mica washer between contact surfaces, and where a clearance hole is used, a p.t.f.e. insulating bush is inserted. A metallic oxide-loaded heatsink compound should be smeared on all contact surfaces, including the mica washer, to ensure optimum heat transfer. The use of ordinary silicone grease is not recommended.

MOUNTING INSTRUCTIONS FOR DO-4 AND TO-64 ENVELOPES

GENERAL DATA AND INSTRUCTIONS

Mounting instructions for up to 2000 V insulation using 56295c insulating bush and 56295a mica washer.

Mounting instructions for up to 2000 V insulation using 56295b insulating ring and two 56295a mica washers.

HEATSINK REQUIREMENTS

Mounting holes must be deburred.

MOUNTING TORQUES

Minimum torque (for good heat transfer)
Maximum torque (to avoid damaging device)

0.9 Nm (9 kg cm)
1.7 Nm (17 kg cm)

THERMAL DATA

The thermal resistance from mounting base to heatsink ($R_{th\ mb-h}$) can be reduced by applying a heat conducting compound between device and heatsink. For insulated mounting the compound should be applied to the bottom of both device and insulator.

Thermal resistance from mounting base to heatsink
(insulated mounting using 56295a mica washer)
without heatsink compound
with heatsink compound

$R_{th\ mb-h}$	=	5	K/W
$R_{th\ mb-h}$	=	2.5	K/W

MOUNTING INSTRUCTIONS FOR UP TO 2000 V INSULATION

Using 56295c insulating bush and 56295a mica washer.

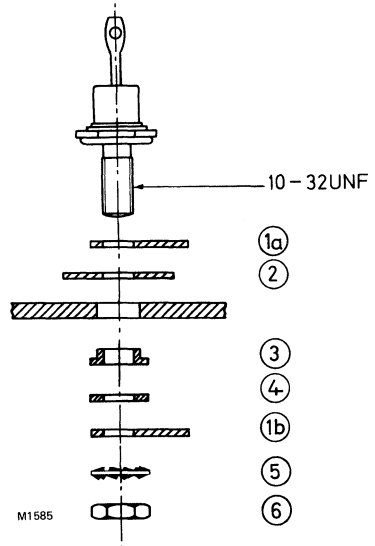


Fig.1

- (1a);(1b) tag – alternative positions
- (2) mica washer 56295a
- (3) insulating bush 56295c
- (4) plain washer (may be omitted if tag used in position 1b)
- (5) toothed lock washer (supplied with device)
- (6) 10-32 UNF nut (supplied with device)

MOUNTING INSTRUCTIONS DO-4; TO-64

MOUNTING INSTRUCTIONS FOR UP TO 2000 V INSULATION

Using insulating ring 56295b and two mica washers 56295a.

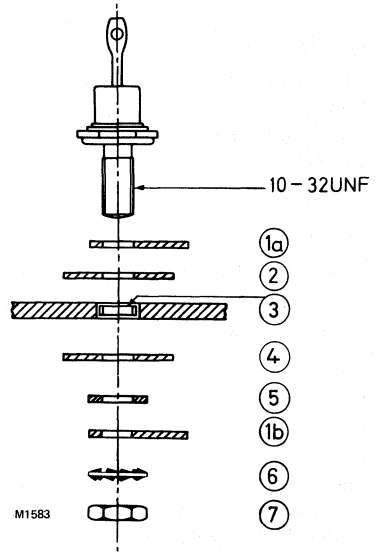


Fig. 2

- (1a); (1b) tag – alternative positions
- (2) mica washer 56295a
- (3) insulating ring 56295b
- (4) mica washer 56295a
- (5) plain washer (may be omitted
if tag used in position 1b)
- (6) toothed lock washer (supplied with device)
- (7) 10-32 nut (supplied with device)

**MOUNTING INSTRUCTIONS FOR DO-5 AND
TO-48 ENVELOPES**

GENERAL DATA AND INSTRUCTIONS

Mounting instructions for up to 2000 V insulation using 56264b insulating bush and 56264a mica washer.

HEATSINK REQUIREMENTS

Mounting holes must be deburred.

MOUNTING TORQUES

Minimum torque (for good heat transfer) 1.7 Nm (17 kg cm)
 Maximum torque (to avoid damaging device) 3.5 Nm (35 kg cm)

THERMAL DATA

The thermal resistance from mounting base to heatsink ($R_{th\ mb-h}$) can be reduced by applying a heat conducting compound between device and heatsink. For insulated mounting the compound should be applied to the bottom of both device and insulator.

Thermal resistance from mounting base
 to heatsink (insulated mounting using 56264a mica washer)
 without heatsink compound $R_{th\ mb-h} = 5$ K/W
 with heatsink compound $R_{th\ mb-h} = 2.5$ K/W

MOUNTING INSTRUCTIONS FOR UP TO 2000 V INSULATION

Using insulating bush 56264b and mica washer 56264a.

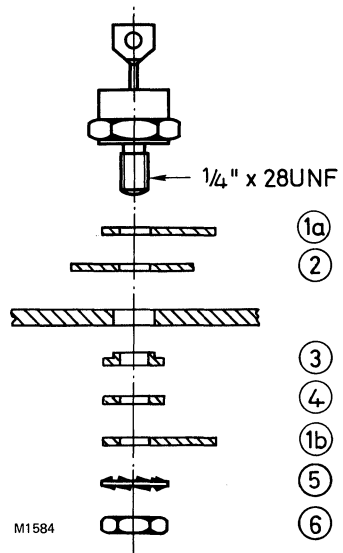


Fig.1

- (1a); (1b) tag — alternative positions
- (2) mica washer 56264a
- (3) insulating bush 56264b
- (4) plain washer (may be omitted if tag used in position 1b)
- (5) toothed lock washer (supplied with device)
- (6) 1/4" x 28 UNF nut (supplied with device)

MOUNTING INSTRUCTIONS FOR SOT-112 ENVELOPE

GENERAL DATA AND INSTRUCTIONS

Mounting instructions using 56379 spring clip.

THERMAL DATA

The thermal resistance from mounting base to heatsink ($R_{th\ mb-h}$) can be reduced by applying a metallic oxide heatsink compound between the contact surfaces.

Thermal resistance from mounting base to heatsink
with a metallic oxide loaded compound
without heatsink compound

$R_{th\ mb-h}$	=	1.0	K/W
$R_{th\ mb-h}$	=	2.0	K/W

INSTRUCTIONS FOR MOUNTING

1. Place the device on the heatsink, applying a metallic oxide loaded compound to the mounting base.
2. Push the short end of the clip into the narrow slot of the heatsink with the clip at an angle of 10° to 30° to the vertical (see Fig. 1b).
3. Push down the clip over the device until the long end of the clip snaps into the wide slot. The clip should bear down on the middle of the plastic body.

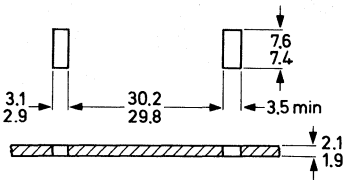


Fig. 1a Heatsink requirements.

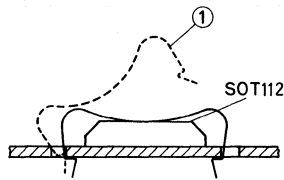


Fig. 1b Mounting.
(1) = spring clip 56379

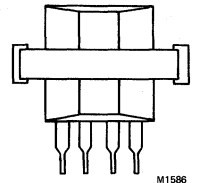


Fig. 1c Position of the device.

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The inclusion of a type number in this publication does not necessarily imply its availability.

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BA223	S1	T	BAS32	S7/S1	Mm/SD	BAV101	S7/S1	Mm/SD
BA281	S1	SD	BAS35	S7/S1	Mm/SD	BAV102	S7/S1	Mm/SD
BA314	S1	Vrg	BAS45	S1	SD	BAV103	S7/S1	Mm/SD
BA315	S1	Vrg	BAS56	S1/S7	SD/Mm	BAW56	S7/S1	Mm/SD
BA316	S1	SD	BAT17	S7/S1	Mm/T	BAW62	S1	SD
BA317	S1	SD	BAT18	S7/S1	Mm/T	BAX12	S1	SD
BA318	S1	SD	BAT54	S1/S7	SD/Mm	BAX14	S1	SD
BA423	S1	T	BAT74	S1/S7	SD/Mm	BAX18	S1	SD
BA480	S1	T	BAT81	S1	T	BAY80	S1	SD
BA481	S1	T	BAT82	S1	T	BB112	S1	T
BA482	S1	T	BAT83	S1	T	BB119	S1	T
BA483	S1	T	BAT85	S1	T	BB130	S1	T
BA484	S1	T	BAT86	S1	T	BB204B	S1	T
BA682	S1/S7	T/Mm	BAV10	S1	SD	BB204G	S1	T
BA683	S1/S7	T/Mm	BAV18	S1	SD	BB212	S1	T
BAS11	S1	SD	BAV19	S1	SD	BB215	S7/S1	Mm/SD
BAS15	S1	SD	BAV20	S1	SD	BB219	S7/S1	Mm/SD
BAS16	S7/S1	Mm/SD	BAV21	S1	SD	BB405B	S1	T
BAS17	S7/S1	Mm/Vrg	BAV23	S7/S1	Mm/SD	BB417	S1	T
BAS19	S7/S1	Mm/SD	BAV45	S1	Sp	BB809	S1	T
BAS20	S7/S1	Mm/SD	BAV45A	S1	Sp	BB909A	S1	T
BAS21	S7/S1	Mm/SD	BAV70	S7/S1	Mm/SD	BB909B	S1	T
BAS28	S7/S1	Mm/SD	BAV74	S1	SD	BBY31	S7/S1	Mm/T

Mm = Microminiature semiconductors
for hybrid circuits
SD = Small-signal diodes

Sp = Special diodes
T = Tuner diodes
Vrg = Voltage regulator diodes

INDEX

type no.	book	section	type no.	book	section	type no.	book	section
BBY39	S1	T	BC639	S3	Sm	BCW72;R	S7	Mm
BBY40	S7/S1	Mm/T	BC640	S3	Sm	BCW81;R	S7	Mm
BC107	S3	Sm	BC807	S7	Mm	BCW89;R	S7	Mm
BC108	S3	Sm	BC808	S7	Mm	BCX17;R	S7	Mm
BC109	S3	Sm	BC817	S7	Mm	BCX18;R	S7	Mm
BC140	S3	Sm	BC818	S7	Mm	BCX19;R	S7	Mm
BC141	S3	Sm	BC846	S7	Mm	BCX20;R	S7	Mm
BC146	S3	Sm	BC847	S7	Mm	BCX51	S7	Mm
BC160	S3	Sm	BC848	S7	Mm	BCX52	S7	Mm
BC161	S3	Sm	BC849	S7	Mm	BCX53	S7	Mm
BC177	S3	Sm	BC850	S7	Mm	BCX54	S7	Mm
BC178	S3	Sm	BC856	S7	Mm	BCX55	S7	Mm
BC179	S3	Sm	BC857	S7	Mm	BCX56	S7	Mm
BC200	S3	Sm	BC858	S7	Mm	BCX68	S7	Mm
BC264A	S5	FET	BC859	S7	Mm	BCX69	S7	Mm
BC264B	S5	FET	BC860	S7	Mm	BCX70*	S7	Mm
BC264C	S5	FET	BC868	S7	Mm	BCX71*	S7	Mm
BC264D	S5	FET	BC869	S7	Mm	BCY56	S3	Sm
BC327;A	S3	Sm	BCF29;R	S7	Mm	BCY57	S3	Sm
BC328	S3	Sm	BCF30;R	S7	Mm	BCY58	S3	Sm
BC337;A	S3	Sm	BCF32;R	S7	Mm	BCY59	S3	Sm
BC338	S3	Sm	BCF33;R	S7	Mm	BCY70	S3	Sm
BC368	S3	Sm	BCF70;R	S7	Mm	BCY71	S3	Sm
BC369	S3	Sm	BCF81;R	S7	Mm	BCY72	S3	Sm
BC375	S3	Sm	BCV26	S7	Mm	BCY78	S3	Sm
BC376	S3	Sm	BCV27	S7	Mm	BCY79	S3	Sm
BC546	S3	Sm	BCV61	S7	Mm	BCY87	S3	Sm
BC547	S3	Sm	BCV62	S7	Mm	BCY88	S3	Sm
BC548	S3	Sm	BCV71;R	S7	Mm	BCY89	S3	Sm
BC549	S3	Sm	BCV72;R	S7	Mm	BD131	S4a	P
BC550	S3	Sm	BCW29;R	S7	Mm	BD132	S4a	P
BC556	S3	Sm	BCW30;R	S7	Mm	BD135	S4a	P
BC557	S3	Sm	BCW31;R	S7	Mm	BD136	S4a	P
BC558	S3	Sm	BCW32;R	S7	Mm	BD137	S4a	P
BC559	S3	Sm	BCW33;R	S7	Mm	BD138	S4a	P
BC560	S3	Sm	BCW60*	S7	Mm	BD139	S4a	P
BC635	S3	Sm	BCW61*	S7	Mm	BD140	S4a	P
BC636	S3	Sm	BCW69;R	S7	Mm	BD201	S4a	P
BC637	S3	Sm	BCW70;R	S7	Mm	BD202	S4a	P
BC638	S3	Sm	BCW71;R	S7	Mm	BD203	S4a	P

* = series

FET = Field-effect transistors

Mm = Microminiature semiconductors
for hybrid circuits

P = Low-frequency power transistors

Sm = Small-signal transistors

T = Tuner diodes

type no.	book	section	type no.	book	section	type no.	book	section
BD204	S4a	P	BD332	S4a	P	BD828	S4a	P
BD226	S4a	P	BD333	S4a	P	BD829	S4a	P
BD227	S4a	P	BD334	S4a	P	BD830	S4a	P
BD228	S4a	P	BD335	S4a	P	BD839	S4a	P
BD229	S4a	P	BD336	S4a	P	BD840	S4a	P
BD230	S4a	P	BD337	S4a	P	BD841	S4a	P
BD231	S4a	P	BD338	S4a	P	BD842	S4a	P
BD233	S4a	P	BD433	S4a	P	BD843	S4a	P
BD234	S4a	P	BD434	S4a	P	BD844	S4a	P
BD235	S4a	P	BD435	S4a	P	BD845	S4a	P
BD236	S4a	P	BD436	S4a	P	BD846	S4a	P
BD237	S4a	P	BD437	S4a	P	BD847	S4a	P
BD238	S4a	P	BD438	S4a	P	BD848	S4a	P
BD239	S4a	P	BD645	S4a	P	BD849	S4a	P
BD239A	S4a	P	BD646	S4a	P	BD850	S4a	P
BD239B	S4a	P	BD647	S4a	P	BD933	S4a	P
BD239C	S4a	P	BD648	S4a	P	BD934	S4a	P
BD240	S4a	P	BD649	S4a	P	BD935	S4a	P
BD240A	S4a	P	BD650	S4a	P	BD936	S4a	P
BD240B	S4a	P	BD651	S4a	P	BD937	S4a	P
BD240C	S4a	P	BD652	S4a	P	BD938	S4a	P
BD241	S4a	P	BD675	S4a	P	BD939	S4a	P
BD241A	S4a	P	BD676	S4a	P	BD940	S4a	P
BD241B	S4a	P	BD677	S4a	P	BD941	S4a	P
BD241C	S4a	P	BD678	S4a	P	BD942	S4a	P
BD242	S4a	P	BD679	S4a	P	BD943	S4a	P
BD242A	S4a	P	BD680	S4a	P	BD944	S4a	P
BD242B	S4a	P	BD681	S4a	P	BD945	S4a	P
BD242C	S4a	P	BD682	S4a	P	BD946	S4a	P
BD243	S4a	P	BD683	S4a	P	BD947	S4a	P
BD243A	S4a	P	BD684	S4a	P	BD948	S4a	P
BD243B	S4a	P	BD813	S4a	P	BD949	S4a	P
BD243C	S4a	P	BD814	S4a	P	BD950	S4a	P
BD244	S4a	P	BD815	S4a	P	BD951	S4a	P
BD244A	S4a	P	BD816	S4a	P	BD952	S4a	P
BD244B	S4a	P	BD817	S4a	P	BD953	S4a	P
BD244C	S4a	P	BD818	S4a	P	BD954	S4a	P
BD329	S4a	P	BD825	S4a	P	BD955	S4a	P
BD330	S4a	P	BD826	S4a	P	BD956	S4a	P
BD331	S4a	P	BD827	S4a	P	BDT20	S4a	P

P = Low-frequency power transistors

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type no.	book	section	type no.	book	section	type no.	book	section
BDT21	S4a	P	BDT61C	S4a	P	BDV66B	S4a	P
BDT29	S4a	P	BDT62	S4a	P	BDV66C	S4a	P
BDT29A	S4a	P	BDT62A	S4a	P	BDV66D	S4a	P
BDT29B	S4a	P	BDT62B	S4a	P	BDV67A	S4a	P
BDT29C	S4a	P	BDT62C	S4a	P	BDV67B	S4a	P
BDT30	S4a	P	BDT63	S4a	P	BDV67C	S4a	P
BDT30A	S4a	P	BDT63A	S4a	P	BDV67D	S4a	P
BDT30B	S4a	P	BDT63B	S4a	P	BDV91	S4a	P
BDT30C	S4a	P	BDT63C	S4a	P	BDV92	S4a	P
BDT31	S4a	P	BDT64	S4a	P	BDV93	S4a	P
BDT31A	S4a	P	BDT64A	S4a	P	BDV94	S4a	P
BDT31B	S4a	P	BDT64B	S4a	P	BDV95	S4a	P
BDT31C	S4a	P	BDT64C	S4a	P	BDV96	S4a	P
BDT32	S4a	P	BDT65	S4a	P	BDW55	S4a	P
BDT32A	S4a	P	BDT65A	S4a	P	BDW56	S4a	P
BDT32B	S4a	P	BDT65B	S4a	P	BDW57	S4a	P
BDT32C	S4a	P	BDT65C	S4a	P	BDW58	S4a	P
BDT41	S4a	P	BDT81	S4a	P	BDW59	S4a	P
BDT41A	S4a	P	BDT82	S4a	P	BDW60	S4a	P
BDT41B	S4a	P	BDT83	S4a	P	BDX35	S4a	P
BDT41C	S4a	P	BDT84	S4a	P	BDX36	S4a	P
BDT42	S4a	P	BDT85	S4a	P	BDX37	S4a	P
BDT42A	S4a	P	BDT86	S4a	P	BDX42	S4a	P
BDT42B	S4a	P	BDT87	S4a	P	BDX43	S4a	P
BDT42C	S4a	P	BDT88	S4a	P	BDX44	S4a	P
BDT51	S4a	P	BDT91	S4a	P	BDX45	S4a	P
BDT52	S4a	P	BDT92	S4a	P	BDX46	S4a	P
BDT53	S4a	P	BDT93	S4a	P	BDX47	S4a	P
BDT54	S4a	P	BDT94	S4a	P	BDX62	S4a	P
BDT55	S4a	P	BDT95	S4a	P	BDX62A	S4a	P
BDT56	S4a	P	BDT96	S4a	P	BDX62B	S4a	P
BDT57	S4a	P	BDV64	S4a	P	BDX62C	S4a	P
BDT58	S4a	P	BDV64A	S4a	P	BDX63	S4a	P
BDT60	S4a	P	BDV64B	S4a	P	BDX63A	S4a	P
BDT60A	S4a	P	BDV64C	S4a	P	BDX63B	S4a	P
BDT60B	S4a	P	BDV65	S4a	P	BDX63C	S4a	P
BDT60C	S4a	P	BDV65A	S4a	P	BDX64	S4a	P
BDT61	S4a	P	BDV65B	S4a	P	BDX64A	S4a	P
BDT61A	S4a	P	BDV65C	S4a	P	BDX64B	S4a	P
BDT61B	S4a	P	BDV66A	S4a	P	BDX64C	S4a	P

P = Low-frequency power transistors

type no.	book	section	type no.	book	section	type no.	book	section
BDX65	S4a	P	BF247B	S5	FET	BF585	S4b	HVP
BDX65A	S4a	P	BF247C	S5	FET	BF587	S4b	HVP
BDX65B	S4a	P	BF256A	S5	FET	BF591	S4b	HVP
BDX65C	S4a	P	BF256B	S5	FET	BF593	S4b	HVP
BDX66	S4a	P	BF256C	S5	FET	BF620	S7	Mm
BDX66A	S4a	P	BF324	S3	Sm	BF621	S7	Mm
BDX66B	S4a	P	BF370	S3	Sm	BF622	S7	Mm
BDX66C	S4a	P	BF410A	S5	FET	BF623	S7	Mm
BDX67	S4a	P	BF410B	S5	FET	BF660;R	S7	Mm
BDX67A	S4a	P	BF410C	S5	FET	BF689K	S10	WBT
BDX67B	S4a	P	BF410D	S5	FET	BF763	S10	WBT
BDX67C	S4a	P	BF419	S4b	HVP	BF767	S7	Mm
BDX68	S4a	P	BF420	S3	Sm	BF819	S4b	HVP
BDX68A	S4a	P	BF421	S3	Sm	BF820	S7	Mm
BDX68B	S4a	P	BF422	S3	Sm	BF821	S7	Mm
BDX68C	S4a	P	BF423	S3	Sm	BF822	S7	Mm
BDX69	S4a	P	BF450	S3	Sm	BF823	S7	Mm
BDX69A	S4a	P	BF451	S3	Sm	BF824	S7	Mm
BDX69B	S4a	P	BF457	S4b	HVP	BF840	S7	Mm
BDX69C	S4a	P	BF458	S4b	HVP	BF841	S7	Mm
BDX77	S4a	P	BF459	S4b	HVP	BF857	S4b	HVP
BDX78	S4a	P	BF469	S4b	HVP	BF858	S4b	HVP
BDX91	S4a	P	BF470	S4b	HVP	BF859	S4b	HVP
BDX92	S4a	P	BF471	S4b	HVP	BF869	S4b	HVP
BDX93	S4a	P	BF472	S4b	HVP	BF870	S4b	HVP
BDX94	S4a	P	BF483	S3	Sm	BF871	S4b	HVP
BDX95	S4a	P	BF485	S3	Sm	BF872	S4b	HVP
BDX96	S4a	P	BF487	S3	Sm	BF926	S3	Sm
BDY90	S4a	P	BF494	S3	Sm	BF936	S3	Sm
BDY90A	S4a	P	BF495	S3	Sm	BF939	S3	Sm
BDY91	S4a	P	BF496	S3	Sm	BF960	S5	FET
BDY92	S4a	P	BF510	S7/S5	Mm/FET	BF964	S5	FET
BF198	S3	Sm	BF511	S7/S5	Mm/FET	BF966	S5	FET
BF199	S3	Sm	BF512	S7/S5	Mm/FET	BF967	S3	Sm
BF240	S3	Sm	BF513	S7/S5	Mm/FET	BF970	S3	Sm
BF241	S3	Sm	BF536	S7	Mm	BF979	S3	Sm
BF245A	S5	FET	BF550;R	S7	Mm	BF980	S5	FET
BF245B	S5	FET	BF569	S7	Mm	BF981	S5	FET
BF245C	S5	FET	BF579	S7	Mm	BF982	S5	FET
BF247A	S5	FET	BF583	S4b	HVP	BF989	S7/S5	Mm/FET

FET = Field-effect transistors
HVP = High-voltage power transistors
Mm = Microminiature semiconductors
for hybrid circuits

P = Low-frequency power transistors
Sm = Small-signal transistors
WBT = Wideband transistors

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type no.	book	section	type no.	book	section	type no.	book	section
BF990	S7/S5	Mm/FET	BFQ51	S10	WBT	BFT24	S10	WBT
BF991	S7/S5	Mm/FET	BFQ51C	S10	WBT	BFT25;R	S7	Mm
BF992	S7/S5	Mm/FET	BFQ52	S10	WBT	BFT44	S3	Sm
BF994	S7/S5	Mm/FET	BFQ53	S10	WBT	BFT45	S3	Sm
BF996	S7/S5	Mm/FET	BFQ63	S10	WBT	BFT46	S7/S5	Mm/FET
BFG23	S10	WBT	BFQ65	S10	WBT	BFT92;R	S7	Mm
BFG32	S10	WBT	BFQ66	S10	WBT	BFT93;R	S7	Mm
BFG34	S10	WBT	BFQ67	S7	Mm	BFQ67	S5	FET
BFG51	S10	WBT	BFQ68	S10	WBT	BFW11	S5	FET
BFG65	S10	WBT	BFQ136	S10	WBT	BFW12	S5	FET
BFG67	S7	Mm	BFR29	S5	FET	BFW13	S5	FET
BFG90A	S10	WBT	BFR30	S7/S5	Mm/FET	BFW16A	S10	WBT
BFG91A	S10	WBT	BFR31	S7/S5	Mm/FET	BFW17A	S10	WBT
BFG96	S10	WBT	BFR49	S10	WBT	BFW30	S10	WBT
BFP90A	S10	WBT	BFR53;R	S7	Mm	BFW61	S5	FET
BFP91A	S10	WBT	BFR54	S3	Sm	BFW92	S10	WBT
BFP96	S10	WBT	BFR64	S10	WBT	BFW92A	S10	WBT
BFQ10	S5	FET	BFR65	S10	WBT	BFW93	S10	WBT
BFQ11	S5	FET	BFR84	S5	FET	BFX29	S3	Sm
BFQ12	S5	FET	BFR90	S10	WBT	BFX30	S3	Sm
BFQ13	S5	FET	BFR90A	S10	WBT	BFX34	S3	Sm
BFQ14	S5	FET	BFR91	S10	WBT	BFX84	S3	Sm
BFQ15	S5	FET	BFR91A	S10	WBT	BFX85	S3	Sm
BFQ16	S5	FET	BFR92;R	S7	Mm	BFX86	S3	Sm
BFQ17	S7	Mm	BFR92A;R	S7	Mm	BFX87	S3	Sm
BFQ18A	S7	Mm	BFR93;R	S7	Mm	BFX88	S3	Sm
BFQ19	S7	Mm	BFR93A;R	S7	Mm	BFX89	S10	WBT
BFQ22S	S10	WBT	BFR94	S10	WBT	BFY50	S3	Sm
BFQ23	S10	WBT	BFR95	S10	WBT	BFY51	S3	Sm
BFQ23C	S10	WBT	BFR96	S10	WBT	BFY52	S3	Sm
BFQ24	S10	WBT	BFR96S	S10	WBT	BFY55	S3	Sm
BFQ32	S10	WBT	BFR101A;B	S7/S5	Mm/FET	BFY90	S10	WBT
BFQ32C	S10	WBT	BFS17;R	S7	Mm	BG2000	S1	RT
BFQ32S	S10	WBT	BFS18;R	S7	Mm	BG2097	S1	RT
BFQ33	S10	WBT	BFS19;R	S7	Mm	BGD102	S10	WBM
BFQ34	S10	WBT	BFS20;R	S7	Mm	BGD102E	S10	WBM
BFQ34T	S10	WBT	BFS21	S5	FET	BGD104	S10	WBM
BFQ42	S6	RFP	BFS21A	S5	FET	BGD104E	S10	WBM
BFQ43	S6	RFP	BFS22A	S6	RFP	BGY22	S6	RFP
BFQ43S	S6	RFP	BFS23A	S6	RFP	BGY22A	S6	RFP

FET = Field-effect transistors

Mm = Microminiature semiconductors
for hybrid circuits

RFP = R.F. power transistors and modules

RT = Tripler

Sm = Small-signal transistors

WBM = Wideband hybrid IC modules

WBT = Wideband transistors

type no.	book	section	type no.	book	section	type no.	book	section
BGY23	S6	RFP	BGY85A	S10	WBM	BLV57	S6	RFP
BGY23A	S6	RFP	BGY90A	S6	RFP	BLV59	S6	RFP
BGY32	S6	RFP	BGY90B	S6	RFP	BLV75/12	S6	RFP
BGY33	S6	RFP	BGY93*	S6	RFP	BLV80/28	S6	RFP
BGY35	S6	RFP	BGY94*	S6	RFP	BLV90	S6	RFP
BGY36	S6	RFP	BGY95A	S6	RFP	BLV90/SL	S6	RFP
BGY40A	S6	RFP	BGY95B	S6	RFP	BLV91	S6	RFP
BGY40B	S6	RFP	BGY96A	S6	RFP	BLV91/SL	S6	RFP
BGY41A	S6	RFP	BGY96B	S6	RFP	BLV92	S6	RFP
BGY41B	S6	RFP	BLF146	S6	RFP/FET	BLV93	S6	RFP
BGY43	S6	RFP	BLF242	S6	RFP/FET	BLV94	S6	RFP
BGY45A	S6	RFP	BLF244	S6	RFP/FET	BLV95	S6	RFP
BGY45B	S6	RFP	BLF245	S6	RFP/FET	BLV97	S6	RFP
BGY46A	S6	RFP	BLT90/SL	S6	RFP	BLV98	S6	RFP
BGY46B	S6	RFP	BLT91/SL	S6	RFP	BLV99	S6	RFP
BGY47*	S6	RFP	BLT92/SL	S6	RFP	BLW29	S6	RFP
BGY48*	S6	RFP	BLU20/12	S6	RFP	BLW31	S6	RFP
BGY50	S10	WBM	BLU30/12	S6	RFP	BLW32	S6	RFP
BGY51	S10	WBM	BLU45/12	S6	RFP	BLW33	S6	RFP
BGY52	S10	WBM	BLU50	S6	RFP	BLW34	S6	RFP
BGY53	S10	WBM	BLU51	S6	RFP	BLW50F	S6	RFP
BGY54	S10	WBM	BLU52	S6	RFP	BLW60	S6	RFP
BGY55	S10	WBM	BLU53	S6	RFP	BLW60C	S6	RFP
BGY56	S10	WBM	BLU60/12	S6	RFP	BLW76	S6	RFP
BGY57	S10	WBM	BLU97	S6	RFP	BLW77	S6	RFP
BGY58	S10	WBM	BLU98	S6	RFP	BLW78	S6	RFP
BGY58A	S10	WBM	BLU99	S6	RFP	BLW79	S6	RFP
BGY59	S10	WBM	BLV10	S6	RFP	BLW80	S6	RFP
BGY60	S10	WBM	BLV11	S6	RFP	BLW81	S6	RFP
BGY61	S10	WBM	BLV20	S6	RFP	BLW83	S6	RFP
BGY65	S10	WBM	BLV21	S6	RFP	BLW84	S6	RFP
BGY67	S10	WBM	BLV25	S6	RFP	BLW85	S6	RFP
BGY67A	S10	WBM	BLV30	S6	RFP	BLW86	S6	RFP
BGY70	S10	WBM	BLV30/12	S6	RFP	BLW87	S6	RFP
BGY71	S10	WBM	BLV31	S6	RFP	BLW89	S6	RFP
BGY74	S10	WBM	BLV32F	S6	RFP	BLW90	S6	RFP
BGY75	S10	WBM	BLV33	S6	RFP	BLW91	S6	RFP
BGY84	S10	WBM	BLV33F	S6	RFP	BLW95	S6	RFP
BGY84A	S10	WBM	BLV36	S6	RFP	BLW96	S6	RFP
BGY85	S10	WBM	BLV45/12	S6	RFP	BLW97	S6	RFP

* = series

FET = Field-effect transistors

RFP = R.F. power transistors and modules

WBM = Wideband hybrid IC modules

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type no.	book	section	type no.	book	section	type no.	book	section
BLW98	S6	RFP	BPW71	S8b	PDT	BSR30	S7	Mm
BLW99	S6	RFP	BPX25	S8b	PDT	BSR31	S7	Mm
BLX13	S6	RFP	BPX29	S8b	PDT	BSR32	S7	Mm
BLX13C	S6	RFP	BPX40	S8b	PDT	BSR33	S7	Mm
BLX14	S6	RFP	BPX41	S8b	PDT	BSR40	S7	Mm
BLX15	S6	RFP	BPX42	S8b	PDT	BSR41	S7	Mm
BLX39	S6	RFP	BPX61	S8b	PDT	BSR42	S7	Mm
BLX65	S6	RFP	BPX61P	S8b	PDT	BSR43	S7	Mm
BLX65E	S6	RFP	BPX71	S8b	PDT	BSR50	S3	Sm
BLX65ES	S6	RFP	BPX72	S8b	PDT	BSR51	S3	Sm
BLX67	S6	RFP	BR100/03	S2b	Th	BSR52	S3	Sm
BLX68	S6	RFP	BR101	S3	Sm	BSR56	S7/S5	Mm/FET
BLX69A	S6	RFP	BR210*	S2a	Th	BSR57	S7/S5	Mm/FET
BLX91A	S6	RFP	BR216*	S2a	Th	BSR58	S7/S5	Mm/FET
BLX91CB	S6	RFP	BR220*	S2a	Th	BSR60	S3	Sm
BLX92A	S6	RFP	BRY39	S3	Sm	BSR61	S3	Sm
BLX93A	S6	RFP	BRY56	S3	Sm	BSR62	S3	Sm
BLX94A	S6	RFP	BRY61	S7	Mm	BSS38	S3	Sm
BLX94C	S6	RFP	BRY62	S7	Mm	BSS50	S3	Sm
BLX95	S6	RFP	BS107	S5	FET	BSS51	S3	Sm
BLX96	S6	RFP	BS170	S5	FET	BSS52	S3	Sm
BLX97	S6	RFP	BSD10	S5	FET	BSS60	S3	Sm
BLX98	S6	RFP	BSD12	S5	FET	BSS61	S3	Sm
BLY87A	S6	RFP	BSD20	S5/7	FET	BSS62	S3	Sm
BLY87C	S6	RFP	BSD22	S5/7	FET	BSS63;R	S7	Mm
BLY88A	S6	RFP	BSD212	S5	FET	BSS64;R	S7	Mm
BLY88C	S6	RFP	BSD213	S5	FET	BSS68	S3	Sm
BLY89A	S6	RFP	BSD214	S5	FET	BSS83	S5/7	FET/Mm
BLY89C	S6	RFP	BSD215	S5	FET	BST15	S7	Mm
BLY90	S6	RFP	BSR12;R	S7	Mm	BST16	S7	Mm
BLY91A	S6	RFP	BSR13;R	S7	Mm	BST39	S7	Mm
BLY91C	S6	RFP	BSR14;R	S7	Mm	BST40	S7	Mm
BLY92A	S6	RFP	BSR15;R	S7	Mm	BST50	S7	Mm
BLY92C	S6	RFP	BSR16;R	S7	Mm	BST51	S7	Mm
BLY93A	S6	RFP	BSR17;R	S7	Mm	BST52	S7	Mm
BLY93C	S6	RFP	BSR17A;R	S7	Mm	BST60	S7	Mm
BLY94	S6	RFP	BSR18;R	S7	Mm	BST61	S7	Mm
BPF24	S8b	PDT	BSR18A;R	S7	Mm	BST62	S7	Mm
BPW22A	S8a/b	PDT	BSR19; A	S7	Mm	BST70A	S5	FET
BPW50	S8a/b	PDT	BSR20; A	S7	Mm	BST72A	S5	FET

FET = Field-effect transistors

Mm = Microminiature semiconductors
for hybrid circuits

PDT = Photodiodes or transistors

RFP = R.F. power transistors and modules

Sm = Small-signal transistors

Th = Thyristors

type no.	book	section	type no.	book	section	type no.	book	section
BST74A	S5	FET	BT139*	S2b	Tri	BU508D	S4b	SP
BST76A	S5	FET	BT139F*	S2b	Tri	BU705	S4b	SP
BST78	S5	FET	BT145*	S2b	Tri	BU706	S4b	SP
BST80	S5/S7	FET/Mm	BT149*	S2b	Th	BU706D	S4b	SP
BST82	S5/S7	FET/Mm	BT150	S2b	Th	BU806	S4b	SP
BST84	S5/S7	FET/Mm	BT151*	S2b	Th	BU807	S4b	SP
BST86	S5/S7	FET/Mm	BT151F*	S2b	Th	BU808	S4b	SP
BST90	S5	FET	BT152*	S2b	Th	BU824	S4b	SP
BST97	S5	FET	BT153	S2b	Th	BU826	S4b	SP
BST100	S5	FET	BT157*	S2b	Th	BUP22*	S4b	SP
BST110	S5	FET	BT169*	S2b	Th	BUP23*	S4b	SP
BST120	S5/S7	FET/Mm	BTA140*	S2b	Tri	BUS11;A	S4b	SP
BST122	S5/S7	FET/Mm	BTR59*	S2b	Tri	BUS12;A	S4b	SP
BSV15	S3	Sm	BTS59*	S2b	Tri	BUS13;A	S4b	SP
BSV16	S3	Sm	BTV58*	S2b	Th	BUS14;A	S4b	SP
BSV17	S3	Sm	BTV59*	S2b	Th	BUS21*	S4b	SP
BSV52;R	S7	Mm	BTV59D*	S2b	Th	BUS22*	S4b	SP
BSV64	S3	Sm	BTV60*	S2b	Th	BUS23*	S4b	SP
BSV78	S5	FET	BTV60D*	S2b	Th	BUT11;A	S4b	SP
BSV79	S5	FET	BTV70*	S2b	Th	BUT11A	S4b	SP
BSV80	S5	FET	BTV70D*	S2b	Th	BUT11AF	S4b	SP
BSV81	S5	FET	BTW23*	S2b	Th	BUV82	S4b	SP
BSW66A	S3	Sm	BTW38*	S2b	Th	BUV83	S4b	SP
BSW67A	S3	Sm	BTW40*	S2b	Th	BUV89	S4b	SP
BSW68A	S3	Sm	BTW42*	S2b	Th	BUV90;A	S4b	SP
BSX19	S3	Sm	BTW43*	S2b	Tri	BUW11;A	S4b	SP
BSX20	S3	Sm	BTW45*	S2b	Th	BUW12;A	S4b	SP
BSX45	S3	Sm	BTW58*	S2b	Th	BUW13;A	S4b	SP
BSX46	S3	Sm	BTW62*	S2b	Th	BUW84	S4b	SP
BSX47	S3	Sm	BTW62D*	S2b	Th	BUW85	S4b	SP
BSX59	S3	Sm	BTW63*	S2b	Th	BUX46;A	S4b	SP
BSX60	S3	Sm	BTY79*	S2b	Th	BUX47;A	S4b	SP
BSX61	S3	Sm	BTY91*	S2b	Th	BUX48;A	S4b	SP
BSY95A	S3	Sm	BU426	S4b	SP	BUX80	S4b	SP
BT136*	S2b	Tri	BU426A	S4b	SP	BUX81	S4b	SP
BT136F*	S2b	Tri	BU433	S4b	SP	BUX82	S4b	SP
BT137*	S2b	Tri	BU505	S4b	SP	BUX83	S4b	SP
BT137F*	S2b	Tri	BU506	S4b	SP	BUX84	S4b	SP
BT138*	S2b	Tri	BU506D	S4b	SP	BUX84F	S4b	SP
BT138F*	S2b	Tri	BU508A	S4b	SP	BUX85	S4b	SP

* = series

FET = Field-effect transistors

Mm = Microminiature semiconductors
for hybrid circuits

Sm = Small-signal transistors

SP = Low-frequency switching power transistors

Th = Thyristors

Tri = Triacs

INDEX

type no.	book	section	type no.	book	section	type no.	book	section
BUX85F	S4b	SP	BUZ54	S9	PM	BY609	S1	R
BUX86	S4b	SP	BUZ54A	S9	PM	BY610	S1	R
BUX87	S4b	SP	BUZ60	S9	PM	BY614	S1	R
BUX88	S4b	SP	BUZ60B	S9	PM	BY619	S1	R
BUX90	S4b	SP	BUZ63	S9	PM	BY620	S1	R
BUX98	S4b	SP	BUZ63B	S9	PM	BY627	S1	R
BUX98A	S4b	SP	BUZ64	S9	PM	BY707	S1	R
BUX99	S4b	SP	BUZ71	S9	PM	BY708	S1	R
BUY89	S4b	SP	BUZ71A	S9	PM	BY709	S1	R
BUZ10	S9	PM	BUZ72	S9	PM	BY710	S1	R
BUZ10A	S9	PM	BUZ72A	S9	PM	BY711	S1	R
BUZ11	S9	PM	BUZ73A	S9	PM	BY712	S1	R
BUZ11A	S9	PM	BUZ74	S9	PM	BY713	S1	R
BUZ14	S9	PM	BUZ74A	S9	PM	BY714	S1	R
BUZ15	S9	PM	BUZ76	S9	PM	BYD13*	S1	R
BUZ20	S9	PM	BUZ76A	S9	PM	BYD14*	S1	R
BUZ21	S9	PM	BUZ80	S9	PM	BYD17*	S1	R
BUZ23	S9	PM	BUZ80A	S9	PM	BYD33*	S1	R
BUZ24	S9	PM	BUZ83	S9	PM	BYD37*	S1	R
BUZ25	S9	PM	BUZ83A	S9	PM	BYD73*	S1	R
BUZ30	S9	PM	BUZ84	S9	PM	BYD74*	S1	R
BUZ31	S9	PM	BUZ84A	S9	PM	BYD77*	S1	R
BUZ32	S9	PM	BY224*	S2a	R	BYM26*	S1	R
BUZ33	S9	PM	BY225*	S2a	R	BYM36*	S1	R
BUZ34	S9	PM	BY228	S1	R	BYM56*	S1	R
BUZ35	S9	PM	BY229*	S2a	R	BYP21*	S2a	R
BUZ36	S9	PM	BY229F*	S2a	R	BYP22*	S2a	R
BUZ40	S9	PM	BY249*	S2a	R	BYP59*	S2a	R
BUZ41A	S9	PM	BY260*	S2a	R	BYQ28*	S2a	R
BUZ42	S9	PM	BY261*	S2a	R	BYR29*	S2a	R
BUZ43	S9	PM	BY329*	S2a	R	BYR29F*	S2a	R
BUZ44A	S9	PM	BY359*	S2a	R	BYT28*	S2a	R
BUZ45	S9	PM	BY438	S1	R	BYT79*	S2a	R
BUZ45A	S9	PM	BY448	S1	R	BYV10	S1	R
BUZ45B	S9	PM	BY458	S1	R	BYV18*	S2a	R
BUZ45C	S9	PM	BY505	S1	R	BYV19*	S2a	R
BUZ46	S9	PM	BY509	S1	R	BYV20*	S2a	R
BUZ50A	S9	PM	BY527	S1	R	BYV21*	S2a	R
BUZ50B	S9	PM	BY584	S1	R	BYV22*	S2a	R
BUZ53A	S9	PM	BY588	S1	R	BYV23*	S2a	R

* = series

PM = Power MOS transistors

R = Rectifier diodes

SP = Low-frequency switching power transistors

type no.	book	section	type no.	book	section	type no.	book	section
BYV24*	S2a	R	BYW95A	S1	R	BZX70*	S2a	Vrg
BYV26*	S1/S2a	R	BYW95B	S1	R	BZX75*	S1	Vrg
BYV27*	S1/S2a	R	BYW95C	S1	R	BZX79*	S1	Vrg
BYV28*	S1/S2a	R	BYW96D	S1	R	BZX84*	S7/S1	Mm/Vrg
BYV29*	S2a	R	BYW96E	S1	R	BZY91*	S2a	Vrg
BYV29F*	S2a	R	BYX10G	S1	R	BZY93*	S2a	Vrg
BYV30*	S2a	R	BYX25*	S2a	R	CFX13	S11	M
BYV31*	S2a	R	BYX30*	S2a	R	CFX21	S11	M
BYV32*	S2a	R	BYX32*	S2a	R	CFX30	S11	M
BYV32F*	S2a	R	BYX38*	S2a	R	CFX31	S11	M
BYV33*	S2a	R	BYX39*	S2a	R	CFX32	S11	M
BYV33F*	S2a	R	BYX42*	S2a	R	CFX33	S11	M
BYV34*	S2a	R	BYX46*	S2a	R	CNG35	S8b	PhC
BYV36*	S1	R	BYX50*	S2a	R	CNG36	S8b	PhC
BYV39*	S2a	R	BYX52*	S2a	R	CNR36	S8b	PhC
BYV42*	S2a	R	BYX56*	S2a	R	CNX21	S8b	PhC
BYV43*	S2a	R	BYX90G	S1	R	CNX35	S8b	PhC
BYV43F*	S2a	R	BYX96*	S2a	R	CNX35U	S8b	PhC
BYV44*	S2a	R	BYX97*	S2a	R	CNX36	S8b	PhC
BYV60*	S2a	R	BYX98*	S2a	R	CNX36U	S8b	PhC
BYV72*	S2a	R	BYX99*	S2a	R	CNX38	S8b	PhC
BYV73*	S2a	R	BZD23	S1	Vrg	CNX38U	S8b	PhC
BYV74*	S2a	R	BZD27	S1	Vrg	CNX39	S8b	PhC
BYV79*	S2a	R	BZT03	S1	Vrg	CNX39U	S8b	PhC
BYV92*	S2a	R	BZV10	S1	Vrf	CNX44	S8b	PhC
BYV95A	S1	R	BZV11	S1	Vrf	CNX44A	S8b	PhC
BYV95B	S1	R	BZV12	S1	Vrf	CNX46	S8b	PhC
BYV95C	S1	R	BZV13	S1	Vrf	CNX48	S8b	PhC
BYV96D	S1	R	BZV14	S1	Vrf	CNX48U	S8b	PhC
BYV96E	S1	R	BZV37	S1	Vrf	CNX62	S8b	PhC
BYW25*	S2a	R	BZV46	S1	Vrg	CNX72	S8b	PhC
BYW29*	S2a	R	BZV49*	S1/S7	Vrg/Mm	CNX82	S8b	PhC
BYW29F*	S2a	R	BZV55*	S7	Mm	CNX83	S8b	PhC
BYW30*	S2a	R	BZV80	S1	Vrf	CNX91	S8b	PhC
BYW31*	S2a	R	BZV81	S1	Vrf	CNX92	S8b	PhC
BYW54	S1	R	BZV85*	S1	Vrg	CNY17-1	S8b	PhC
BYW55	S1	R	BZW03*	S1	Vrg	CNY17-2	S8b	PhC
BYW56	S1	R	BZW14	S1	Vrg	CNY17-3	S8b	PhC
BYW92*	S2a	R	BZW86*	S2a	TS	CNY50	S8b	PhC
BYW93*	S2a	R	BZX55*	S1	Vrg	CNY57	S8b	PhC

* = series

M = Microwave transistors

Mm = Microminiature semiconductors
for hybrid circuits

PhC = Photocouplers

R = Rectifier diodes

TS = Transient suppressor diodes

Vrf = Voltage reference diodes

Vrg = Voltage regulator diodes

INDEX

type no.	book	section	type no.	book	section	type no.	book	section
CNY57A	S8b	PhC	CQW10B(L)	S8a	LED	CQY97A	S8a	LED
CNY57AU	S8b	PhC	CQW10U(L)	S8a	LED	Fresnel-	S8b	A
CNY57U	S8b	PhC	CQW11B(L)	S8a	LED	lens		
CNY62	S8b	PhC	CQW12B(L)	S8a	LED	H11A1	S8b	PhC
CNY63	S8b	PhC	CQW20A	S8a	LED	H11A2	S8b	PhC
CQF24	S8b	Ph	CQW21	S8a	LED	H11A3	S8b	PhC
CQL10A	S8b	Ph	CQW22	S8a	LED	H11A4	S8b	PhC
CQL13A	S8b	Ph	CQW24(L)	S8a	LED	H11A5	S8b	PhC
CQL16	S8b	Ph	CQW54	S8a	LED	H11B1	S8b	PhC
CQS51L	S8a	LED	CQW60(L)	S8a	LED	H11B2	S8b	PhC
CQS54	S8a	LED	CQW60A(L)	S8a	LED	H11B3	S8b	PhC
CQS82L	S8a	LED	CQW60U(L)	S8a	LED	H11B255	S8b	PhC
CQS82AL	S8a	LED	CQW61(L)	S8a	LED	KMZ10A	S13	SEN
CQS84L	S8a	LED	CQW62(L)	S8a	LED	KMZ10B	S13	SEN
CQS86L	S8a	LED	CQW89A	S8a/b	I	KMZ10C	S13	SEN
CQS93	S8a	LED	CQW93	S8a	LED	KP100A	S13	SEN
CQS93E	S8a	LED	CQW95	S8a	LED	KP101A	S13	SEN
CQS93L	S8a	LED	CQW97	S8a	LED	KP220G	S13	SEN
CQS95	S8a	LED	CQX24(L)	S8a	LED	KP221G	S13	SEN
CQS95E	S8a	LED	CQX51(L)	S8a	LED	KTY81*	S13	SEN
CQS95L	S8a	LED	CQX54(L)	S8a	LED	KTY83*	S13	SEN
CQS97	S8a	LED	CQX54D	S8a	LED	KTY84*	S13	SEN
CQS97E	S8a	LED	CQX64(L)	S8a	LED	LAE2001R	S11	M
CQS97L	S8a	LED	CQX64D	S8a	LED	LAE4001Q	S11	M
CQT10B	S8a	LED	CQX74(L)	S8a	LED	LAE4001R	S11	M
CQT24	S8a	LED	CQX74D	S8a	LED	LAE4002S	S11	M
CQT60	S8a	LED	CQY11B	S8b	LED	LAE6000Q	S11	M
CQT70	S8a	LED	CQY11C	S8b	LED	LBE1004R	S11	M
CQT80L	S8a	LED	CQY24B(L)	S8a	LED	LBE1010R	S11	M
CQV70(L)	S8a	LED	CQY49B	S8b	LED	LBE2003S	S11	M
CQV70A(L)	S8a	LED	CQY49C	S8b	LED	LBE2005Q	S11	M
CQV70U(L)	S8a	LED	CQY50	S8b	LED	LBE2008T	S11	M
CQV71A(L)	S8a	LED	CQY52	S8b	LED	LBE2009S	S11	M
CQV72(L)	S8a	LED	CQY53S	S8b	LED	LCE1010R	S11	M
CQV80L	S8a	LED	CQY54A	S8a	LED	LCE2003S	S11	M
CQV80AL	S8a	LED	CQY58A	S8a/b	I	LCE2005Q	S11	M
CQV80UL	S8a	LED	CQY89A	S8a/b	I	LCE2008T	S11	M
CQV81L	S8a	LED	CQY94B(L)	S8a	LED	LCE2009S	S11	M
CQV82L	S8a	LED	CQY95B	S8a	LED	LJE42002T	S11	M
CQW10A(L)	S8a	LED	CQY96(L)	S8a	LED	LKE1004R	S11	M

* = series

A = Accessories

I = Infrared devices

LED = Light-emitting diodes

M = Microwave transistors

Ph = Photoconductive devices

PhC = Photocouplers

SEN = Sensors

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type no.	book	section	type no.	book	section	type no.	book	section
PMLL5225B			RZ1214B125YS11	M		TIP127	S4a	P
to	S1	SD	RZ1214B150YS11	M		TIP130	S4a	P
PMLL5267B			RZ2833B45W	S11	M	TIP131	S4a	P
PO44	S8b	PhC	RZ3135B15U	S11	M	TIP132	S4a	P
PO44A	S8b	PhC	RZ3135B15W	S11	M	TIP135	S4a	P
PPC5001T	S11	M	RZ3135B25U	S11	M	TIP136	S4a	P
PQC5001T	S11	M	RZ3135B30W	S11	M	TIP137	S4a	P
PTB23001X	S11	M	RZB12100Y	S11	M	TIP140	S4a	P
PTB23003X	S11	M	RZB12350Y	S11	M	TIP141	S4a	P
PTB23005X	S11	M	RZZ1214B300YS11	M		TIP145	S4a	P
PTB32001X	S11	M	SL5500	S8b	PhC	TIP146	S4a	P
PTB32003X	S11	M	SL5501	S8b	PhC	TIP147	S4a	P
PTB32005X	S11	M	SL5502R	S8b	PhC	TIP2955	S4a	P
PTB42001X	S11	M	SL5504	S8b	PhC	TIP3055	S4a	P
PTB42002X	S11	M	SL5504S	S8b	PhC	1N821;A	S1	Vrf
PTB42003X	S11	M	SL5505S	S8b	PhC	1N823;A	S1	Vrf
PV3742B4X	S11	M	SL5511	S8b	PhC	1N825;A	S1	Vrf
PVB42004X	S11	M	TIP29*	S4a	P	1N827;A	S1	Vrf
PZ1418B15U	S11	M	TIP30*	S4a	P	1N829;A	S1	Vrf
PZ1418B30U	S11	M	TIP31*	S4a	P	1N914	S1	SD
PZ1721B12U	S11	M	TIP32*	S4a	P	1N916	S1	SD
PZ1721B25U	S11	M	TIP33*	S4a	P	1N3879	S2a	R
PZ2024B10U	S11	M	TIP34*	S4a	P	1N3880	S2a	R
PZ2024B20U	S11	M	TIP41*	S4a	P	1N3881	S2a	R
PZB16035U	S11	M	TIP42*	S4a	P	1N3882	S2a	R
PZB27020U	S11	M	TIP47	S4a	P	1N3883	S2a	R
RPY97	S8b	I	TIP48	S4a	P	1N3889	S2a	R
RPY100	S8b	I	TIP49	S4a	P	1N3890	S2a	R
RPY101	S8b	I	TIP50	S4a	P	1N3891	S2a	R
RPY102	S8b	I	TIP110	S4a	P	1N3892	S2a	R
RPY103	S8b	I	TIP111	S4a	P	1N3893	S2a	R
RPY107	S8b	I	TIP112	S4a	P	1N3909	S2a	R
RPY109	S8b	I	TIP115	S4a	P	1N3910	S2a	R
RV3135B5X	S11	M	TIP116	S4a	P	1N3911	S2a	R
RX1214B300YS11	M		TIP117	S4a	P	1N3912	S2a	R
RXB12350Y	S11	M	TIP120	S4a	P	1N3913	S2a	R
RZ1214B35Y	S11	M	TIP121	S4a	P	1N4001G	S1	R
RZ1214B60W	S11	M	TIP122	S4a	P	1N4002G	S1	R
RZ1214B65Y	S11	M	TIP125	S4a	P	1N4003G	S1	R
RZ1214B125WS11	M		TIP126	S4a	P	1N4004G	S1	R

* = series

I = Infrared devices

M = Microwave transistors

P = Low-frequency power transistors

PhC = Photocouplers

R = Rectifier diodes

SD = Small-signal diodes

Vrf = Voltage reference diodes

type no.	book	section	type no.	book	section	type no.	book	section
LKE2002T	S11	M	OM320	S10	WBM	PDE1003U	S11	M
LKE2004T	S11	M	OM321	S10	WBM	PDE1005U	S11	M
LKE2015T	S11	M	OM322	S10	WBM	PDE1010U	S11	M
LKE21004R	S11	M	OM323	S10	WBM	PEE1001U	S11	M
LKE21015T	S11	M	OM323A	S10	WBM	PEE1003U	S11	M
LKE21050T	S11	M	OM335	S10	WBM	PEE1005U	S11	M
LKE27010R	S11	M	OM336	S10	WBM	PEE1010U	S11	M
LKE27025R	S11	M	OM337	S10	WBM	PH2222;R	S3	Sm
LKE32002T	S11	M	OM337A	S10	WBM	PH2222A;R	S3	Sm
LKE32004T	S11	M	OM339	S10	WBM	PH2369	S3	Sm
LTE42005S	S11	M	OM345	S10	WBM	PH2907;R	S3	Sm
LTE42008R	S11	M	OM350	S10	WBM	PH2907A;R	S3	Sm
LTE42012R	S11	M	OM360	S10	WBM	PH2955T	S4a	P
LV1721E50R	S11	M	OM361	S10	WBM	PH3055T	S4a	P
LV2024E45R	S11	M	OM370	S10	WBM	PH5415	S3	Sm
LV2327E40R	S11	M	OM386B	S13	SEN	PH5416	S3	Sm
LV3742E16R	S11	M	OM386M	S13	SEN	PH13002	S4b	SP
LV3742E24R	S11	M	OM387B	S13	SEN	PH13003	S4b	SP
LWE2015R	S11	M	OM387M	S13	SEN	PHSD51	S2a	R
LWE2025R	S11	M	OM388B	S13	SEN	PRB3001U	S11	M
LZ1418E100RS11	M		OM389B	S13	SEN	PRB3003U	S11	M
MCA230	S8b	PhC	OM931	S4a	P	PRB3005U	S11	M
MCA231	S8b	PhC	OM961	S4a	P	PRB12005U	S11	M
MCA255	S8b	PhC	OSB9115	S2a	St	PRB20010U	S11	M
MCT2	S8b	PhC	OSB9215	S2a	St	PRB23001U	S11	M
MCT26	S8b	PhC	OSB9415	S2a	St	PRB23003U	S11	M
MKB12040WS	S11	M	OSM9115	S2a	St	PRB23005U	S11	M
MKB12100WS	S11	M	OSM9215	S2a	St	PRB25006T	S11	M
MKB12140W	S11	M	OSM9415	S2a	St	PRB32001U	S11	M
MO6075B200ZS11	M		OSM9510	S2a	St	PRB32003U	S11	M
MO6075B400ZS11	M		OSM9511	S2a	St	PRB32005U	S11	M
MRB12175YR	S11	M	OSM9512	S2a	St	PMBF4391	S7	Mm
MRB12350YR	S11	M	OSS9115	S2a	St	PMBF4392	S7	Mm
MS1011B700YS11	M		OSS9215	S2a	St	PMBF4392	S7	Mm
MS6075B800ZS11	M		OSS9415	S2a	St	PMLL4148	S1	SD
MSB12900Y	S11	M	P2105	S8b	I	PMLL4150	S1	SD
MZ0912B75Y	S11	M	PBMF4391	S5	FET	PMLL4151	S1	SD
MZ0912B150YS11	M		PBMF4392	S5	FET	PMLL4153	S1	SD
OM286; M	S13	SEN	PBMF4393	S5	FET	PMLL4446	S1	SD
OM287; M	S13	SEN	PDE1001U	S11	M	PMLL4448	S1	SD

FET = Field-effect transistors

I = Infrared devices

M = Microwave transistors

Mm = Microminiature semiconductors
for hybrid circuits

P = Low-frequency power transistors

PhC = Photocouplers

R = Rectifier diodes

SD = Small-signal diodes

SEN = Sensors

Sm = Small-signal transistors

SP = Low-frequency switching power transistors

St = Rectifier stacks

WBM = Wideband hybrid IC modules

type no.	book	section	type no.	book	section	type no.	book	section
1N4005G	S1	R	2N2907	S3	Sm	2N5400	S3	Sm
1N4006G	S1	R	2N2907A	S3	Sm	2N5401	S3	Sm
1N4007G	S1	R	2N3019	S3	Sm	2N5415	S3	Sm
1N4148	S1	SD	2N3020	S3	Sm	2N5416	S3	Sm
1N4150	S1	SD	2N3053	S3	Sm	2N5550	S3	Sm
1N4151	S1	SD	2N3375	S6	RFP	2N5551	S3	Sm
1N4153	S1	SD	2N3553	S6	RFP	2N6659	S5	FET
1N4446	S1	SD	2N3632	S6	RFP	2N6660	S5	FET
1N4448	S1	SD	2N3822	S5	FET	2N6661	S5	FET
1N4531	S1	SD	2N3823	S5	FET	4N25	S8b	PhC
1N4532	S1	SD	2N3866	S6	RFP	4N25A	S8b	PhC
1N5059	S1	R	2N3903	S3	Sm	4N26	S8b	PhC
1N5060	S1	R	2N3904	S3	Sm	4N27	S8b	PhC
1N5061	S1	R	2N3905	S3	Sm	4N28	S8b	PhC
1N5062	S1	R	2N3906	S3	Sm	4N35	S8b	PhC
1N5225B to	S1	SD	2N3924	S6	RFP	4N36	S8b	PhC
1N5267B			2N3926	S6	RFP	4N37	S8b	PhC
2N918	S10	WBT	2N3927	S6	RFP	4N38	S8b	PhC
2N929	S3	Sm	2N3966	S5	FET	4N38A	S8b	PhC
2N930	S3	Sm	2N4030	S3	Sm	502CQF	S8b	Ph
2N1613	S3	Sm	2N4031	S3	Sm	503CQF	S8b	Ph
2N1711	S3	Sm	2N4032	S3	Sm	504CQL	S8b	Ph
2N1893	S3	Sm	2N4033	S3	Sm	516CQF-B	S8b	Ph
2N2219	S3	Sm	2N4091	S5	FET	56201d	S4b	A
2N2219A	S3	Sm	2N4092	S5	FET	56201j	S4b	A
2N2222	S3	Sm	2N4093	S5	FET	56245	S3, 10	A
2N2222A	S3	Sm	2N4123	S3	Sm	56246	S3, 10	A
2N2297	S3	Sm	2N4124	S3	Sm	56261a	S4b	A
2N2368	S3	Sm	2N4125	S3	Sm	56264	S2a/b	A
2N2369	S3	Sm	2N4126	S3	Sm	56295	S2a/b	A
2N2369A	S3	Sm	2N4391	S5	FET	56326	S4b	A
2N2483	S3	Sm	2N4392	S5	FET	56339	S4b	A
2N2484	S3	Sm	2N4393	S5	FET	56352	S4b	A
2N2904	S3	Sm	2N4427	S6	RFP	56353	S4b	A
2N2904A	S3	Sm	2N4856	S5	FET	56354	S4b	A
2N2905	S3	Sm	2N4857	S5	FET	56359b	S2, 4b	A
2N2905A	S3	Sm	2N4858	S5	FET	56359c	S2, 4b	A
2N2906	S3	Sm	2N4859	S5	FET	56359d	S2, 4b	A
2N2906A	S3	Sm	2N4860	S5	FET	56360a	S2, 4b	A
			2N4861	S5	FET	56363	S2, 4b	A

A = Accessories
 FET = Field-effect transistors
 Ph = Photoconductive devices
 PhC = Photocouplers
 R = Rectifier diodes

RFP = R.F. power transistors and modules
 SD = Small-signal diodes
 Sm = Small-signal transistors
 WBT = Wideband transistors

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type no.	book	section
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56368c	S2, 4b	A
56369	S2, 4b	A
56378	S2, 4b	A
56379	S2, 4b	A
56387a, b	S4b	A
56397	S8b	A

A = Accessories

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