# Inter-Office Memorandum

То	David Liddle	Date	October 18, 1978
From	John Wick	Location	Palo Alto
Subject	D0 Timing Simulation	Organization	SDD/SS/DE

XERUX

Filed on: [Iris] < Thistle > Doc > ThistleReport.bravo

DRAFT

This report describes a series of experiments conducted to evaluate the performance of a number of proposed display configurations running on a D0, the OIS processor. The primary objective of this study was to verify the expected performance of the processor with a single large format display, and to discover the effects of adding a second display.

Because the eventual hardware, firmware, and software configurations are not presently available, a simulation approach was adopted. A program called Thistle was written to simulate the timing characteristics of the D0 processor at the micro instruction level. Instruction traces of a number of real programs (such as Apex and DeskTop) running on Alto/Mesa 4.1 were used to drive the simulation. A dozen experiments were run simulating the current hardware/firmware configuration to verify correct operation. Six program samples were then run with five different display configurations to predict their expected performance.

# Simulator Input

Thistle requires two inputs to perform a simulation. The first is a trace of Mesa byte codes to be executed. The second is a description of the microcode which implements those instructions; provision for describing the display and memory refresh microcode is also included.

## Instruction Traces

To obtain the instruction traces, a modified version of the Alto/Mesa 4.1 microcode was written which traps to the RAM at the beginning of each Mesa instruction. The RAM microcode records the opcode and its parameters in a trace buffer, which is written to the disk periodically; normal execution is then resumed. In a number of cases, additional information about the machine state is also captured. For example, all control transfers (XFERs and jumps) record the destination PC, so that buffer refill can be properly simulated. The alignment of operands was also recorded for some opcodes. The details of the trace format are described in [JohnssonITF].

There was little attempt to compensate for the differences between the current Alto/Mesa instruction set and the set proposed in the PrincOps [ThackerOIS]. The data contained here is therefore mildly pessimistic.

# Instruction Profiles

Thistle also requires a description of the emulator and display microcode to be simulated. Because only timing charateristics of the processor are simulated, a rather terse description of the microcode is sufficient. It need only include processor and I/O memory references (and their alignment), memory interlocks and aborts, instruction buffer refill, and task switching. Microinstructions that are not otherwise interesting are grouped together into a count of execution cycles.

To arrive at this microcode description, we expanded on the idea of *instruction profiles* described in [Garner]. Instructions are divided into classes which exhibit the same memory and timing behavior. An instruction profile is then assigned to each class, as well as to the display and memory refresh tasks. Details of the instruction profile description can be found in [JohnssonTIP].

(Although we considered the possibility of a program which compiled actual microcode source files into their profiles, it became clear that this would be much too big a project given the time constraints. Therefore all instruction profiles were produced by hand, and are subject to transcription errors.)

The important data dependicies were handled by including extra data in the instruction trace (for example, buffer refill depends heavily on alignment constraints; hence, the trace includes the PC value after each XFER and jump). Most other data dependencies result in very small differences in execution time (e.g., shifting right requires one more cycle than shifting left); these differences were ignored by the simulator. However, instructions like BLT and BITBLT required special casing. Their profiles were based on knowledge of the types of BITBLTs used in the test cases (as well as on an analysis of the microcode). For the display experiments, the profile for BLT assumed a four word block, and the profile for BITBLT assumed that a character was being painted.

## Simulator Operation

The principle design objective of Thistle was to accurately simulate the interaction of the microprocessor and the memory. The instruction profiles for the Mesa emulator show the pattern of memory use that occurs while executing a given Mesa opcode. The main power of Thistle is that the interactions between adjacent opcodes and interactions between the emulator and other tasks (such as the display) can also be simulated, not for some abstract instruction mix, but for actual typical code sequences.

#### Automata

In addition to the microprocessor, the D0 contains two additional automata: the memory controllers MC1 and MC2. Thistle simulated the operation of MC1 and MC2 as described in [ThackerMT]; it also simulates the various kinds of aborts described in [ThackerD0]. Thus, if the profile calls for a PFETCH1 while MC1 is still active, the processor will undergo an MC1 abort for as many cycles as MC1 remains active. Likewise, referencing the data from a recent fetch will abort until MC2 finishes. Thistle keeps track of which task most recently used the memory, so the right thing happens if a task switch occurs between a fetch and use of the data.

### Tasks

Most returns occurring within microinstructions will cause a task switch if another microtask of higher priority is ready to run. The display task is special in that it will also allow a lower priority task to run when it tasks. Thistle simulates this situation using coroutines.

Each task has a profile to execute. Every task except the emulator task has a "next wakeup" time associated with it. After every tasking return in a profile, control is passed to the coroutine executing the profile of the highest priority task willing to run (the emulator is always willing to run). When a task is finished for a while, it updates its wakeup time.

For the display experiments, the only tasks simulated were the emulator, the display, and memory refresh. Other tasks can be added to Thistle without much difficulty.

#### Simulator Output

While the primary use of Thistle in this study is for large batch runs, it also has an interactive mode for debugging purposes. (We expect Thistle to continue to be of use in fine tunning the microcode with very little overhead.) The current state of the processor and memory controller, as well as accumulated statistics on all of the tasks (emulator, display, and memory refresh) are displayed continuously if desired, and Thistle has various forms of "single-stepping" at the micro and macro instruction level. Complete information on the operation of Thistle and its output format can be found in the *Thistle User's Guide* [JohnssonTUG].

For the purposes of this report, Thistle accumulates the number of cycles spent in each of the three tasks (emulator, display, and memory refresh). Cycles are assigned to tasks based on the value of the processor's current task register. The time in each task is broken down into running and waiting; the waiting time is further broken down into MC1, MC2, suspend, and (for the emulator task) NEWINST aborts. Details of these states can be found in the *D0 Functional Specification* [ThackerD0].

Thistle also records the number of Mesa instructions executed as well as the total cycles expended (the sum of the run and wait times discussed above). These together with the processor clock speed (85ns) are used to calculate a Kip rate (kilo instructions per second).

#### Benchmarks

Our first step was to verify correct operation of the simulator. These were run under current conditions, and should be carefully distinguished from the experiments described in the next section. We chose eight benchmark tests to match against actual D0 elapsed time. We also made several probes of a running D0 with a digital voltmeter to verify the various wait times reported by Thistle.

# Integer and String Sorting

Our primary benchmarks were the sort programs which have been in use for measuring Mesa performance since 1976; they were extended slightly to operate optionally with a full page display of random data (they perform no display related operations themselves). A total of eight tests were run: small and large integer and string sorts with the display on and off. A set of instruction profiles was derived from (the then current) microcode Version 1.5' (with the clock bug fixed -- PCR #20.53). All tests were run on EM016 after verifying its board revision levels. Note that these tests and their corresponding simulations were run with an IUTFP driving the 850 display and with old microcode which is known to have unacceptable diplay performance.

The results of these benchmarks are described in [Wick]. They show accuracy of execution time well within 10%, with the simulator running slightly faster than a real D0. Some possible explanations for this discrepancy can be found in the reference.

## Wait Times

To verify proper modeling of the memory controller and its interaction with the processor, a set of four signals (MC1 active, MC2 active, suspend, and abort) were measured and compared with corresponding figures produced by Thistle. Four cases were compared using the benchmark programs: integer and string sort with the display on and off.

The results of this benchmark are presented and discussed in [JohnssonTBV]. While comparisons with the actual voltages are not very meaningful (because the signals cannot be measured accurately), both the real D0 and Thistle exhibited the same behavior with respect to these four signals as the display was turned on and off, and this behavior was consistent across all of the test cases.

## **Experiments**

Several changes to the input were made before running the experimental data (the simulator itself was not changed after running the benchmark tests). New microcode was written for each display configuration; several hardware fixes were enabled, and key parts of the emulator microcode were rewritten. These modifications are described in more detail below.

#### Display Configurations

The hardware (UTVFC) is described in [Cameron]; [JarvisPDC] contains a functional specification for the device driver, including cursor, mouse, and keyboard support.

Three display devices were involved in the experiments, in a total of five different configurations. They are identified as follows:

LF One and two 17" Large Format displays FP One and two 850 Full Page displays QP Four Quarter Page displays

Detailed characteristics of these devices are described in [JarvisDC], which also contains a description of the microcode used to support each device and the assumptions made about it (particularly regarding scanline alignment).

#### Hardware

We assumed the presence of a number of fixes to the hardware which have not yet been installed (although most have been tested on Thacker's D0).

NEWINST aborts will be reduced from the end of MC1 (six to seventeen cycles) to completion of the mapping operation (four to six cycles) [Memory control board revision K].

A change to NEXTINST/NEXTDATA will result in tasking between Mesa instructions and climinate the need for the "time to task" counter [Control board revision I].

A change in the Misc board will allow the test for pending interrupts to be moved from the buffer refill code to NOOP [Misc board revision G]

LONGJUMP will be added to allow changing the current page and performing a jump in the same instruction [Control board revision I].

These changes are described in the documentation on D0 board revision levels maintained by ED.

#### Firmware

The current D0 microcode (version 1.5) was rewritten (on paper) to take advantage of the hardware changes and to include a number of known but as yet unimplemented improvements suggested by Chuck Thacker. The rewrite concentrated on three areas: XFER, jumps, and buffer refill. Quadword code alignment and proper code byte ordering were assumed, as was a hardware stack error check, and numerous TASKs were added throughout the microcode. We incorporated as many changes as we could track from the 2.0 microcode, which is still under development.

Due to time constraints, we were not able to implement the PrincOps microcode. The simulations were run with the Alto/Mesa instruction set as it currently exists (version 4.1), with process bytecodes implemented in Nova code, and an Alto compatible BITBLT.

#### Experimental Data

Six sample instruction traces were taken from three Alto/Mesa application programs; all samples involved display manipulation. One sample of each program focused on the inner loop containing the code to paint characters on the display.

DTest: a test program for the Alto/Mesa system display package. It writes characters on the display as if it were a Teletype, while also maintaining a typescript file.

DeskTop: Advanced Design/User Prototype's experimental Star like environment. Two traces involving opening a document and painting the screen were taken.

Apex: Product Software's applications executive. The three samples obtained involved moving a document into a folder, opening a document, and painting characters in a window.

The samples ranged from 0.48 to 2.86 seconds of simulated execution time; they varied from 121k to 468k Mesa instructions. More details on the samples can be found in [Sandman].

#### Results

The thirty test cases -- six instruction traces and five display configurations -- were run in about 56 hours of elapsed Alto time (about 36 seconds of simulated time). The raw data is summarized in Table 1; it shows the percentage of time running and waiting in the display and emulator tasks, followed by the sum of running and waiting for each task. (The memory refresh task accounts for a constand 2% of the cycles in all test cases.) The table also shows the instruction rate in Kips.

One display configuration was eliminated from the rest of the analysis. While running two Full Page displays, the simulator reported a large number (about 45%) of "misses", in which the display had missed a wakeup for a new scan line because it had not finished processing the previous one (this would show up as screen tearing). This explains why the Kip rates for the two FP case are only slightly smaller than with a single Full Page display.

Figures 1-4 summarize the run and run plus wait time (as a percentage of total cycles) for the display and emulator tasks. Figure 5 summarizes the Kip rates for all display configurations.

As we expected, one LF display consumes about 20% of the cycles, and two LF displays need just under 40%. One FP falls inbetween, at just under 30%, and four QP displays require a bit more

(just over 30%). The simulation indicates that two Full Page displays cannot be supported.

References

[Cameron]	Cameron, J., Thacker, C., Tseng, C. User Terminal Variable Format Controller (UTVFC) Specification. Revision 5.0. September 28, 1978.					
[Garner]	Garner, B. Mesa Opcode Timing. June 21, 1978.					
[JarvisPDC]	Jarvis, J. P. Functional Specification for the Prototype Display Controller. October 13, 1978.					
[JarvisDC]	Jarvis, J. P. Display Characteristics. October 12, 1978.					
[JohnssonITF]	Johnsson, R., Sandman, J., Wick, J. Instruction Trace Format. October 11, 1978.					
[JohnssonTUG]	Johnsson, R., Sweet, R., Wick, J. Thistle User's Guide. October 11, 1978.					
[JohnssonTIP]	Johnsson, R., Sweet, R., Wick, J. Thistle Instruction Profiles. October 11, 1978.					
[JohnssonTBV]	Johnsson, R., Wick, J. Thistle Benchmark: Voltages. October 12, 1978.					
[Sandman]	Sandman, J. Thistle Trace Data. October 13, 1978.					
[ThackerOIS]	Thacker, C. OIS Processor Principles of Operation. Version 2.0. April 9, 1977.					
[ThackerD0]	Thacker, C. D0 Processor Functional Specification. January 16, 1978.					
[ThackerMT]	Thacker, C. MemTiming.sil. July 14, 1978.					
[Wick]	Wick, J. Thistle Benchmark: Elapsed Time. October 12, 1978.					

Distribution: Jarvis Lampson Lynch Metcalfe Thacker Weaver Mesa Group 6

	1	LF	2	LF	1	FP	2	FP	40	QP
АрөхА	56.4 22.5 78.9	14.4 $4.5$ $18.9$	$\begin{array}{r} 43.8\\ \underline{16.5}\\ 60.3 \end{array}$	27.4 <u>10.1</u> 37.5	51.5 18.8 70.3	18.7 8.8 27.5	50.5 18.2 68.7	19.3 <u>9.8</u> 29.1	50.9 <u>16.8</u> 67.7	21.2 $\frac{8.9}{30.1}$
	271	. 2	210	.5	247	.7	243	.0	244	.9
ApexB	54.7 <u>23.9</u> 78.6	$   \begin{array}{r}     14.4 \\     \underline{4.8} \\     \overline{19.2}   \end{array} $	42.4 <u>17.3</u> 59.7	27.4 <u>10.6</u> 38.0	49.9 <u>19.9</u> 69.8	$ \begin{array}{r} 18.7 \\ \underline{9.3} \\ 28.0 \end{array} $	48.9 <u>19.2</u> 68.1	19.4 <u>10.4</u> 29.8	49.3 <u>17.8</u> 67.1	$21.2$ $\frac{9.5}{30.7}$
	275	. 4	213	.6	251	.6	246	.3	248	. 5
ApexC	50.7 <u>27.3</u> 78.0	$   \begin{array}{r}     14.4 \\     5.3 \\     19.7   \end{array} $	39.0 <u>19.3</u> 58.3	27.4 <u>11.9</u> 39.3	46.2 <u>22.4</u> 68.6	18.7 <u>10.5</u> 29.2	44.3 20.9 65.2	20.6 11.9 32.5	45.7 <u>20.1</u> 65.8	21.2 <u>10.8</u> 32.0
	324	.6	249	.7	295	. 4	283	.7	292	.4
DeskTopA	58.7 <u>20.0</u> 78.7	$   \begin{array}{r}     14.4 \\     \underline{4.6} \\     19.0   \end{array} $	45.7 <u>14.2</u> 59.9	27.4 10.4 37.8	53.5 <u>16.7</u> 70.2	$   \begin{array}{r}     18.7 \\     9.0 \\     27.7   \end{array} $	$52.3$ $\frac{15.8}{68.1}$	19.5 <u>10.1</u> 29.6	52.8 <u>14.8</u> 67.6	$21.2$ $\underline{9.0}$ $30.2$
	265	. 3	206	.5	241	.5	236	. 4	238	.6
DeskTopB	$   \begin{array}{r}     60.5 \\     \underline{18.4} \\     \overline{78.9}   \end{array} $	14.4 $4.4$ $18.8$	47.3 <u>13.0</u> 60.3	27.4 9.9 37.3	55.1 15.4 70.5	$   \begin{array}{r}     18.7 \\     \underline{8.6} \\     27.3   \end{array} $	53.9 <u>14.6</u> 68.5	19.5 <u>9.7</u> 29.2	54.4 <u>13.7</u> 68.1	$21.3$ $\frac{8.5}{29.8}$
	253	.3	198	.1	231	.0	225	.9	227	.9
DTestA	52.2 25.9 78.1	14.4 <u>5.2</u> 19.6	40.7 <u>18.4</u> 59.1	27.4 11.1 38.5	47.8 21.5 69.3	$   \begin{array}{r}     18.7 \\     \underline{9.8} \\     28.5   \end{array} $	46.9 <u>20.5</u> 67.4	19.4 <u>10.9</u> 30.3	47.3 <u>19.1</u> 66.4	21.2 <u>10.2</u> 31.4
	210	. 5	164	.0	192	.6	189	. 3	190	. 6

Display Configuration

Emulator	Display
running	running
waiting	waiting
total	total

# Displays

1LF: one large format (17") display
2LF: two large format (17") displays
1FP: one full page (850) display
2FP: two full page (850) displays
1QP: four quarter page displays

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% Display Task (run)



% Display Task (run + wait)





# % Emulator Task (run + wait)



# Inter-Office Memorandum

To .	File	Date	October 11, 1978
From	R. Johnsson, J. Sandman, J. Wick	Location	Palo Alto
Subject	Instruction Trace Format	Organization	SDD/SD

XEROX

Filed on: [Iris] < Thistle > Doc > TraceFormat.bravo

# DRAFT

This memo describes the format of the instruction traces which are input to Thistle, a D0 timing simulator.

Thistle is driven by data obtained from a byte code trace of a running Alto/Mesa program. A special version of the Alto/Mesa 4.1 microcode was produced and installed in the second ROM which traps to the RAM on each instruction. Two versions of RAM microcode were then produced: the first records a trace of all instructions in a buffer; the second accumulates the dynamic frequency of each opcode.

## Instruction Trace

Instruction tracing is turned on and off by special forms of the CATCH instruction (with alpha bytes greater than or equal to 200B). These instructions can be compiled into any program at the desired point using machine code inline procedures. Alternately, a specialized breakpoint handler can be loaded with the subject program which reinterprets the meaning of conditional breakpoints as follows:

CATCH	Condition	Meaning
200B	0	Start tracing
201B	1	Stop tracing

This allows tracing to be turned on and off conviently by setting breakpoints, without modification to the traced program.

The contents of the trace file is as follows:

For each bytecode:

1. the bytecode.

2. alpha and beta if any (order is beta, alpha if both).

For conditional jumps:

3. a condition code for the relation of the operands:

40B - less (signed)

20B - equal

- 10B greater (signed)
- 04B less (unsigned)
- 02B greater (unsigned)

For zRD0, zRDB, zWD0, zWDB, zSFC:

4. the low order eight bits of top-of-stack.

For zwsdb:

5. the low order eight bits of top-of-stack minus two.

For XFERs, zCATCH, zBRK, zJIB, zJIW, monitor operations:

6. the low order eight bits of the new byte pc.

Each page of the data file begins with a zDWDC and a zLST from the trap handler (a total of 4 bytes of data). These are not a part of the bytecode trace. If the bytes for a bytecode overflow a page boundry, the bytecode is reexecuted after the trap, i.e. the same bytecode will appear again starting in the fifth byte of the new page. The pc from an XFER is not considered to be a part of the xfering bytecode for purposes of this restart, i.e. it may be the first significant byte of a page, with its matching XFER in the previous page.

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In addition, there are a few bytes of overhead associated with turning the trace on and off which are included in the trace data but are not part of the traced program. By opcode, they are as follows:

Instruction	Count	Instruction	Count
NOOP	1	SL0	1
SL6	1	LIO	1
LIB	2	RO	1
R2	1	W2	1
J8	1	IWDC	1
DWDC	1	CATCH	1
DST	1	LST	1
BRK	1		

Because these discrepancies are small, they are ignored by the simulator.

#### Instruction Frequencies

As a cross check on the instruction trace data, dynamic frequencies were also obtained for each of the data samples with another version of RAM microcode. This microcode is also controlled by special CATCH instructions or conditional breakpoints with the following meanings:

CATCH	Condition	Meaning
200B	0	Zero counters, start counting
201B	1	Start counting
202B	2	Stop counting
203B	3	Stop counting, store results

As in the instruction trace, there are a few bytes of overhead associated with turning the trace on and off which are included in the accumulated frequencies but are not part of the traced program. By opcode, they are as follows:

Instruction	Count	Instruction	Count
NOOP	1	SL0	1
SL6	1	L10	1
LIB	2	RO	1
R1 .	1.	W1	. 1
JB	1	IWDC	1
DWDC	1	DST	1
LST	1	BRK	1

A program was also written to scan the trace data file and accumulate the same frequencies, which were then compared with the microcode output. The microcode frquency output was also compared with a set of frequencies constructed by hand (by counting "legs" with the performance monitor); one error in the manually constructed data was found.

## Known Problems

There is one known bug in the tracing and frequency microcode: there are a number of extra NOOP intructions counted and recorded in the trace. Specifically, aligned three-byte pair instructions whose alpha byte is zero cause a spurious NOOP to be recorded (and counted). Any program which processes an instruction trace should take this case into account, as there appears to be no simple fix to the trace microcode.

# Inter-Office Memorandum

То	File	Date	October 11, 1978
From	R. Johnsson, R. Sweet, J. Wick	Location	Palo Alto
Subject	Thistle Instruction Profiles	Organization	SDD

XEROX

Filed on: [Iris] < Thistle > Doc > Profiles.bravo

# DRAFT

This memo describes the instruction classes and profiles used by Thistle, a D0 timing simulator. Thistle simulates the D0 (including interaction with main memory and among tasks) by "executing" the instruction profile for each opcode in the input instruction trace. The interpretation simulates only timing and memory contention; no other semantics are included. Hence, each profile must include complete information about memory operations as well as the number of micro cycles used, but it need not reflect any other properties of the actual D0 emulator microcode (from which the instruction profiles are derived).

## Instruction Profiles

Thistle deals with Mesa bytecodes (and the display and memory refresh tasks; see below). The bytecodes are grouped into equivalence classes. Two bytecodes are equivalent if the microcode which implements them has identical timing and memory characteristics. Names of bytecodes begin with the letter z, names of classes begin with the letter x. For example the bytecodes zLG0 and zLG1 are equivalent and belong to class xLGn; zLLB and zLGB are equivalent and belong to class xLGB. In general a class is named after the first bytecode in the class. Note that zLLB and zLGB are equivalent because their implementations have identical timing and memory characteristics; they clearly do not have the same semantics.

The profile for the classes and the class assignments are read from a parameter file when Thistle is started; they can also be edited interactively. The following slice from the parameter file illustrates the syntax for specifying class assignments:

zLGO: [xLGn] zLG1: [xLGn] zLG2: [xLGn] zLL0: [xLGn] zLL1: [xLGn] zLL2: [xLGn] zLGDB: [xLGDB,xLGDBQ] zLLDB: [xLGDB,xLGDBQ]

This slice shows classes being assigned for bytecodes zLG0-2, zLG0-2, zLGDB, and zLLDB. The load double bytecodes have two classes corresponding to the two cases in the implementation, i.e. the execution characteristics of the bytecode depends on some additional data. (In this case the additional data is whether or not the doubleword being addressed crosses a quadword boundry.)

### Thistle Instruction Profiles

Since Thistle does not understand the semantics of bytecodes, the bytecode trace must provide enough information for Thistle to select the correct class. Thistle also deals with alternatives for success/failure of conditional jumps, alignment, and XFER destination link type. See [Johnsson] for a complete description of the contents of the instruction trace data.

For each instruction class, Thistle requires an instruction profile characterizing the microcode that implements the class.

xLGn: "nb2fk1" xLGDB: "nb2fk24b4" xLGDBQ: "nb9fk12rfk1b4"

This slice shows the profiles of the above classes. These strings are similar to those in [Garner]. The meaning of the characters in the string is:

- n The next instruction contains NEWINST, i.e. abort until the previous emulator memory operation has mapped.
- b The next instruction contains NEXTINST or NEXTDATA, i.e. fetch a byte from the instruction buffer and invoke the buffer refill trap if necessary.
- 0-9 The number of cycles required by a sequence of instructions executed. Unless otherwise specified the other characters in the string do not include the execution time of the instruction referenced.
- () Enclose multidigit numbers.
- r The previous instruction contained a RETURN, i.e. switch tasks if appropriate.
  - Initiate a PFETCH of the size indicated in the following digit. If the following character is a k, the destination of the fetch is the STACK and the size digit follows the k. This operation takes two cycles (and leaves the memory busy).
- s Initiate a PSTORE of the size indicated in the following digit. This operation takes two cycles (and leaves the memory busy).
  - Initiate an IO operation as indicated by the next digit, which is one of the following:
    - 0 OUTPUT
    - 1 INPUT
    - 4 IOFETCH4
    - 6 IOFETCH16
    - 9 REFRESH

This operation takes two cycles (and leaves the memory busy).

are infrequent and must be included in the string.

The next instruction will abort until the last memory operation is complete, i.e. it

uses fetched data or changes data being stored. There is no provision for interlocking of the earlier of two currently active memory operations. These aborts

m

f

0

Like m except that the interlock is on the stack. The stack operation is indicated by the next character, which is one of the following:

> i Stack pointer incremented (aborts if store pending) d Stack pointer decremented (aborts if fetch pending)

In general, memory interlocks within a bytecode are marked by m; those between instructions are marked by k.

q

k

Macro. Invoke the string contained in the macro named by the next character (0-9 or A-Z). This simplifies the encoding of long sequences of common code, e.g. parts of XFER.

## Other Profiles

Other profiles for the display and memory refresh tasks are similar to the instruction profiles; the same command characters are used. For example, the parameters for the 850 full page display (IUTFP) and the current (Version 1.5) microcode are:

displayPeriod: 247 -- cycles displayScan: 1217 -- scan lines displayVisible: 1188 -- scan lines displayOnString: "400806(22)6062r6062r7(16)008(12)" displayOffString: "2(14)00m2004"

Currently, the profile and period for the memory refresh task are built into the simulator; they are "4096" and 704 cycles, respectively.

#### References

Garner, B. Mesa Opcode Timings. June 21, 1978.

Johnsson, R., Sandman, J., Wick, J. Instruction Trace Format. October 8, 1978.

# Inter-Office Memorandum

То	Thistle Users	Date	October 17, 1978
From	R. Johnsson, R. Sweet, J. Wick	Location	Palo Alto
Subject	Thistle User's Guide	Organization	SDD/SS/DE

XEROX

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# DRAFT

Thistle is a D0 timing simulator intended to help answer questions about the effects of changes in microcode or hardware on the performance of Mesa programs. Thistle interprets an encoding of D0 microcode and simulates interaction with main memory and among tasks. The interpretation simulates only timing and memory contention; no other semantics are included.

#### Instruction Profiles

Thistle deals primarily with Mesa bytecodes. The bytecodes are grouped into *equivalence classes*; two bytecodes are equivalent if the microcode which implements them has identical timing and memory characteristics. Each class is then assigned a *profile* which describes the operation of the microcode which implements it. Each profile is a short string that describes the memory and I/O operations, memory interlocks, instruction buffer refill, task switching, and the number of cycles performed by that instruction class.

The class assignments and the profiles for the classes are read from a parameter file when Thistle is started; they can also be edited interactively. There is a facility for including macros in the profiles, and characteristics of the display can also be specified. Complete details on the parameter file can be found in [Johnsson].

#### Running Thistle

Obtain Thistle.bcd and Thistle.params from [Iris] < Thistle > (or use the Basic Thistle Disk). You will also need Mesa.image and RunMesa.run from [Iris] < Mesa >. Insure you have a fixed pitch font in SysFont.al; Gachalo works best. Run Thistle by saying:

#### > Mesa Thistle

It will read the params file and display two windows on the screen. The top window contains the state of the machine; the bottom window accepts commands. It will first ask for a data file containing your instruction trace. (Several standard trace data files are available on [Iris] < Thistle > \*.tr; see [Sandman] for details.)

You can install Thistle with a constant parameter file by holding down the backspace-word key when Thistle fires up. After it has read the parameter file, it will checkpoint itself on Thistle image, which will start up much faster. Thistle can be run in single step, walk, or run modes; it will simulate faster if the Alto display is turned off. The complete set of commands is as follows:

- s Step: execute one Mesa instruction (if detailed tracing is enabled, execute one character of the instruction profile).
- r Run: simulates as fast as possible (stops when any character is typed).
- w Walk: same as run, but updates the screen at each step.
- 1 Long instruction trap toggle: if you don't expect any long pointer instructions in the trace, it's a good idea to trap them.
- t Task toggle: task between each Mesa instruction; when this toggle is off, the time-to-task counter is used instead.
- u Unknown instruction trap toggle: halts when garbage is discovered in the trace data.
- n NEWINST fix toggle: NEWINST after mapping only; if this toggle is off, NEWINST aborts until MC1 is complete.
- d D0 display toggle: turns off the simulated display (there is a profile for both display on and display off states).
- p Proceed (count): like run, but with a count of steps.
- q Quit: checkpoints the machine state onto the typescript file, clears the machine and asks for a new data file.
- a Alto display toggle: no display when running (this doesn't affect the D0 display being simulated, of course).
- e Detail trace toggle: reduces step size to cycles instead of Mesa instructions.
- i Input parameter file: overrides the current profiles.
- o Output parameter file: outputs current profiles in text format.
- b Binary (Load or Dump): like Input and Output, except in binary format.
- ↑r Reset: like Quit, except the display is not checkpointed.
- h Checkpoint: writes the machine state onto the typescript file.
- c Change parameter: replaces a single instruction profile and class assignment. Macros and any of the display parameters can also be changed.
- ? List these commands

Any other character halts the simulation.

#### Thistle Output

The Thistle screen is divided into six vertical regions, organized roughly by function. Below is a copy of the screen with a brief description of each region. (All numbers except the pc, the current opcode, and the trace file position are decimal.)

TIME		MEMORY		PENDING		Q	
usec	928510	mc1	17	strtMC2	11	6	pc 306
cycles	10923654	mc2	0	newInOK	0	6	buff 1
nxtDisp	10923709	lstMem	Ε	transfr	1	13	
nxtRef	10923968						

The first region shows simulated elapsed time and the status of the memory system and instruction buffer.

The first column describes the simulated clock. It tells the elapsed time of the simulation in microseconds and processor cycles (at 85 ns per cycle). It also gives the next wakeup time of the periodically scheduled tasks for the display and memory refresh.

The next column tells the number of remaining cycles during which the memory controller automata MC1 and MC2 will be active. It also tells which task (Emulator, Display, or Refresh) was the last to touch the memory.

The third column contains a list of events that are scheduled to occur in the future. In this example (immediately after a PSTORE1 microinstruction) MC2 will be started for 11 cycles in 6 cycles, a NEWINST function in a microinstruction will abort for 6 cycles, and the processor will be suspended (if not already aborted) for 1 cycle in 13 cycles in order that the memory may read from the processor's R-register.

The last column tell the value of the Mesa program counter (Modulo 256) and the number of remaining bytes in the quadword instruction buffer.

EMULATOR	TASK	%	WAIT		%
run	5629552	51.5	mc1	727207	6.6
totWait	2059591	18.8	mc2	580977	5.3
			suspend	451535	4.1
			NewInst	299872	2.7

When the microprocessor is "in" a given task, it is either running, aborted (waiting on the memory for one reason or another), or suspended while the memory is accessing the processor registers. This region of the screen divides the emulator task time into five different categories. All percentages are based on total elapsed time.

The first column contains the run category, which counts running microprocessor cycles and also the total of the four categories of column two.

The second column describes the time spent "waiting" during the emulator task. The mc1 category counts time spent in MC1 aborts (waiting to start a memory operation). The mc2 category counts time spent in MC2 aborts (waiting for data to arrive or be taken for a memory operation). The NewInst category counts time spent in NEWINST aborts (waiting until the previous Mesa instruction can no longer page fault). The suspend category counts time spent with the processor suspended. Time spent with the processor both aborted and suspended is only counted as suspended in order to keep the categories disjoint.

DISPLAY run totWait	TASK 2045907 970159	% 18.7 8.8	WAIT mc1 mc2 suspend	769327 0 200832	% 7.0 0.0 1.8
REFRESH run totWait	TASK 186192 32253	% 1.7 0.2	WAIT mc1 suspend	21826 10427	% 0.1 0.0

These two sections of the screen show the distribution of time while the microprocessor is running the display and memory refresh tasks.

COND JUMPS		ST LINE	CODE	DISPLAY ON	
count	18116	count	21324	count .	42339
%TRUE	40.1	ave	16.3	missed	0
		cur	12		

This region contains some interesting dynamic program statistics and the status of the display task.

The first column has a count of the number of conditional jumps and the percent of them which actually jump.

The second column has statistics about straight line code sequences in the instruction trace. The ave field is the average number of bytes of code executed between jumps actually taken (or other transfers such as procedure calls).

The third column describes the number of times that the display task has run, and the number of times that its wakeup had already passed before it finished a scan line.

INSTRUCTION	229951		% A	CTIVE	FLAGS	
[110] W2	dPa	ge 130	6 mc1	52.9	LONGT	ON
ŴNULĹ	dBy	te 74	2 mc2	48.6	UNKNT	ON
xWn	•		bzy	9.9	niFix	YES
	tas	k: Emul	ator	Task	between	

This region contains assorted information, some of it used primarily for stepping through trace files.

In the first row is a count of Mesa instructions executed in this trace.

The first column shows the current Mesa instruction (w2), its class (wNULL) that determines how the trace file is to be read, and the name of the equivalence class of the instruction (xWn). This equivalence class is used to select the profile string from the params file.

The next column show the stream index of the trace file, and the currently running microtask.

The third column tells the percent of time that the two memory controllers MC1 and MC2 are running. The bzy field tells the percent of the total time that MC1 is busy waiting for the MC2 of the previous memory operation to complete.

The last column tells the state of various simulator flags. The long instruction trap (LONGT) and unknown instruction trap (UNKNT) are used primarily to validate the trace data. The niFix field tells whether the improvement to the NEWINST abort logic is being simulated. The last entry of this columns tells whether the hardware change to allow tasking between instructions is being simulated,

# Thistle User's Guide

or whether the "time to task" counter is being simulated. If the count is used, its current value is also shown.

### q9 (11)f2mq6 ↑

These lines appear only when detailed tracing is on; they show the current instruction profile. Current macro names are displayed on top, and the arrow points to the current location in the profile.

#### References

Johnsson, R., Sweet, R., Wick, J. *Thistle Instruction Profiles.* October 11, 1978. Sandman, J. *Thistle Trace Data.* October 13, 1978.

# Inter-Office Memorandum

То	File	Date	October 12, 1978
From	John Wick	Location	Palo Alto
Subject	Thistle Benchmark: Elapsed Time	Organization	SDD/SS/DE

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XEROX

Filed on: [Iris] < Thistle > Doc > Benchmark.bravo

This memo describes one of the benchmark tests run on Thistle, a D0 timing simulator. The goal of this test was to reproduce, as accurately as possible, the actual elapsed time of a real D0 running a set of standard test programs. The tests chosen were the familiar sort programs, in use as Alto/Mesa benchmarks since 1976. These tests run the processor flat out, with no disk or interrupt activity. The tests have typically been run with the display off; they were modified to optionally display a full screen of arbitrary memory while running the sort.

DRAFT

Note that the data below is for benchmark purposes only and should not be the basis for evaluation of the D0's display support capabilities. Because this was a benchmark test, the simulation was constrained to use the current IUTFP controller and microcode (Version 1.5). This configuration is known to have unacceptable display performance. There are also a number of known hardware fixes left out of this simulation since they are not yet installed on our EMs.

Microseconds on EM016, microcode version 1.5' at 4-Oct-78 14:27; Thistle of 10-Oct-78 17:53

	D0 EM016	Thistlə	•
Integer 200, Display off	212695	189221	89.0%
Ratio on/off	309028 1 456	2/90/0	90.4% 101.6%
off/on	0.687	0.676	98.4%
Integer 1500, Display off	2284609	2030021	88.9%
Integer 1500, Display on	3323260	2988132	89.9%
Ratio on/off	1.455	1.47.2	101.2%
off/on	0.688	0.679	98.7%
String 100, Display off	515260	468561	90.9%
String 100, Display on	750766	700905	93.4%
Ratio on/off	1.457	1.496	102.7%
off/on	0.686	0.669	97.5%
String 400, Display off	3031377	2752357	90.8%

Thistle Benchmark: Elapsed Time

String 400, Display on	4415623	4112727	93.1%
Ratio on/off	1.457	1.494	102.5%
off/on	0.687	0.669	97.4%

There are a few known problems with the simulations which we have not yet had time to correct.

Thistle does not simulate the timer microcode, which requires 8 cycles out of every 448 (1.8%).

Thistle does not simulate the disk task. Since it wakes up only every 3ms and never has anything to do (except post status to memory), the effect is negligible.

The trace data run through the simulator has a number of spurious NOOP instructions. (Due to a bug in the trace microcode, aligned pair instructions whose alpha byte is zero cause a bogus NOOP to be recorded in the trace.)

The simulated display ran less often than it should have (every 247 cycles instead of every 243). This was a result of misinformation on the number of scanlines per frame for the IUTFP (1200 virsus 1217 actual).

I conjecture that the combination of these effects adds two or three percent to the above figures, bringing the simulator well within 10% accuracy, which should be adequate for our purposes. Perhaps more important, the effects of the display on the simulation match the characteristics of the D0 quite well.

# Inter-Office Memorandum

То	File	Date	October 12, 1978	
From	Richard Johnsson, John Wick	Location	Palo Alto	
Subject	Thistle Benchmark: Voltages	Organization	SDD/SS/DE	

Filed on: [Iris] < Thistle > Doc > Voltages.bravo

DRAFT

This memo describes one of the benchmark tests run on Thistle, a D0 timing simulator. We attempted to verify some of the hardware signals (as measured with a digital voltmeter) with corresponding figures generated by the simulator. The signals are all involved with processor/memory interaction; the four signals measured were:

abort: the number of cycles waiting for memory operations. This is the total wait time less the time during suspend (approximately).

mc1: the number of cycles during which MC1 was active.

mc2: the number of cycles during which MC2 was active.

suspend: the number of cycles waiting for actual data transfer between the memory controller and the processor.

Voltages measured 5-Oct-78 EM09 Microcode 1.5'

signal	high	low	range
abort'	3.75	0.30	3.45
mc1'	3.70	0.20	3.50
mc2'	3.60	0.15	3.45
suspend	3.70	0.20	3.50

The above signals were then calibrated against a known microcode loop of 19 cycles. Values in parentheses show true percentages for complemented signals. Values in brackets are calculated.

	obsrv	norm	pct	true	calculated	
abort'	1.15	0.85	24.6	(75.4)	[13/19 = 68.4]	+10%
mc1'	2.48	2.28	65.1	(34.9)	[6/19 = 31.6]	+10%
mc2'	2.64	2.49	72.2	(27.8)	[7/19 = 36.8]	-25%
suspend	0.42	0.22	6.3	6.3	[1/19 = 5.3]	+20%
normalized	= observed -	low		percent	on = normalized/	'range

This stage of the experiment verified that the measured voltages, while not very accurate, have roughly the expected behavior. The same signals were measured while EM09 was running the

benchmark tests (integer and string sorts). The tests were run with the display both on and off (this is the Dallas 850 Full Page display driven by the IUTFP, microcode version 1.5).

	D0 EM09			
abort'	obsrv	norm	pct	true
Integer off	2.97	2.67	77.4	22.6
Integer on	3.31	3.01	87.2	12.8
String off	2.94	2.64	76.5	23.5
String on -	3.28	2.98	86.4	13.6
mc1'	obsrv	norm	pct	truə
Integer off	3.13	2.93	83.7	16.3
Integer on	2.33	2.13	60.9	39.1
String off	2.83	2.63	75.1	24.9
String on	2.14	1.94	55.4	44.6
mc2'	obsrv	norm	pct	true
Integer off	3.22	3.07	89.0	11.0
Integer on	2.46	2.31	67.0	33.0
String off	3.01	2.86	82.9	17.1
String on	2.34	2.19	63.5	36.5
suspend	obsrv	norm	pct	true
Integer off	0.41	0.21	6.0	6.0
Integer on	0.37	0.17	4.9	4.9
String off	0.43	0.23	6.6	6.6
String on	0.38	0.18	5.1	5.1

These are compared below with the corresponding figures produced by the simulator running both the small (200 integers, 100 strings) and large (1500 integers, 400 strings) benchmark instruction traces.

	DO	This	stle
	EM09	large	small
abort			
Integer off	22.6	23.3	23.3
Integer on	12.8	17.7	17.7
String off	23.5	22.1	22.3
String on	13.6	16.2	16.1
mc1			
Integer off	16.3	26.4	26.8
Integer on	39.1	38.9	39.2
String off	24.9	31.2	31.3
String on	44.6	42.6	42.7
mc2			
Integer off	11.0	25.0	25.2
Integer on	33.0	38.3	38.6
String off	17.1	27.6	27.6
String on	36.5	40.8	40.9

suspena			
Integer off	6.0	5.5	5.5
Integer on	4.9	3.9	3.9
String off	6.6	5,6	5.6
String on	5.1	3.9	3.9

Conclusion: when the display is turned on and off, Thistle behaves the same as a real D0.

# Inter-Office Memorandum

То	John Wick	Date	September 29, 1978
From	Pitts Jarvis	Location	Palo Alto
Subject	Functional Specification for the Prototype Display Controller	Organization	SDD

XERUX

## Filed on: [Iris] < Jarvis > prototype-display.bravo

This note describes the prototype display controller. The prototype display controller resembles the UTVFC controller and attempts to minimize the processor overhead necessary to refresh the IUTFP and to transmit keyboard and mouse data to main storage. Two features distinguish the prototype controller from the Alto like controller. The prototype controller does not have an IOCB structure. The controller refreshes the display from a single monolithic bit map described by the controller status block, CSB, located at 400B. The prototype controller writes keyboard and mouse data into a ring buffer described by the CSB. Each ring buffer entry specifies a state change in the keyboard and mouse. A state change would include key up, key down, and incremental changes to mouse coordinates.

CSB: TYPE = MACHINE DEPENDENT RECORD			
pad8: BYTE,	•••	0	begin quadword
bitMap: LONG POINTER,		0	
lineSize: WORD,		2	
lineCount: WORD,	••	3	
cursorX: word,		4	begin quadword
cursorY: WORD,	• •	5	
pad8a: byte,	•-	6	
cursor: LONG POINTER,	••	6	
keySynch: WORD,		8	begin quadword
ringBase: WORD,		9	
ringEnd: WORD,		10	
ringln: WORD,		11	
ringOut: WORD,		12	begin quadword
garbage: ARRAY [02] OF UNSPECIFIED]			

At the beginning of each field, the controller fetches the bit map and cursor parameters located in the first two quadwords in the CSB. LineSize holds the number of words in a scan. BitMap points to the first location of the bit map. The controller explicitly clears the low four bits of the bitMap and lineSize fields, *i.e.*, each scan line must be aligned on a sixteen word boundary. CursorX holds the cursor's abscissa, number of pixels from the left. CursorY holds the cursor's ordinate, the number of scan lines from the top. Cursor points to an array of sixteen words, the cursor bit map. There are not any alignment restrictions for the cursor bit map.

Whenever the keyboard or mouse changes state, the controller uses keySynch as bit mask to initiate interrupts after writing the ring buffer entry. The ring buffer must be quadword aligned and located somewhere in the first 64K of virtual storage. RingBase points to the first word of the buffer and ringEnd points to the first word past the end of the buffer. RingIn points at the first free entry in the buffer. RingOut points to the oldest entry in the ring. If the buffer is empty, ringIn equals ringOut.

# A ring buffer entry consists of a quadword.

RingEntry: TYPE = MACHINE DEPENDENT RECORD incrementX: BIT, decrementX: BIT, incrementY: BIT, decrementY: BIT, mouseLeft: BIT, mouseCenter: BIT, mouseRight: BIT, keyCode: [0..177B], keyUp: BOOLEAN, VS: BIT, unused: BIT, keyboardChange: BOOLEAN, unused: BIT, pad13: [0..1777B], garbage: ARRAY [0..1] OF UNSPECIFIED]

Other features of the Alto controller omitted from the prototype controller include HTAB, a black background bit, and less restrictive alignment constraints on the bit map.

c: Belleville, Irby, Kennedy, Lauer, Liddle, Lynch, Metcalfe, Purcell, Thacker

Inter-Office Memorandum

DRAFT - DRAFT - DRAFT - DRAFT

To .	John Wick	Date	October 12, 1978
From	Pitts Jarvis	Location	Palo Alto
Subject	Display Characteristics	Organization	SDD

XEROX

Filed on: [Iris] < Jarvis > displays.bravo

The following table summarizes the characteristics of some raster scanned displays which exist or planned for the D0. The characteristics of the Alto display are also given to provide some basis for comparison. The D0 displays include the 850 display designated by FP for full page, the large format display (a seventeen inch video monitor) designated by LF for large fromat, and the quarter page display, QP. f denotes the frame rate measured in frames per second. l denotes the number of lines scanned in a single frame; this includes the visible lines as well as the lines blanked during vertical retrace. T denotes the time, in microseconds, to scan a single line on the raster. T is a derived quantity given by the formula

T = 1/(f l).

x denotes the number of pixels on a scan line. y denotes the number of visible lines in a frame. s denotes the number of words necessary to store a single scan line after accounting for storage alignment restrictions. M denotes the number of words necessary to store a full bit map. Mn is the storage necessary to represent a bit map normalized by a full LF bit map. Finally, V gives the video bit rate measured in megabits per second. V is derived from x and T:

<b>T</b> /	4	CTT .
v	 ~ Y /	1
,	 ~	1.

	$f_{\dots}$	1	Т	x	у	S	M	Mn	V
Alto	30.0	875	38.1	606	808	38	30704	0.6	16.0
FP	37.5	1217	21.9	896	1188	56	66528	1.3	40.9
LF	40.0	875	28.6	1024	808	64	51712	1.0	35.8
QP	30.0	525	63.5	640	480	40	19200	0.4	10.1

Several simplifying assumptions were made for all displays when translating the display microcode into the strings used by the Thistle simulator. Since mouse coordinates, CSB, and cursor are processed only once each field, they were not taken into account by the simulation. The processing necessary for key strokes was also ignored because the bit rates were several orders of magnitude less than V; however, the processing necessary to check for the presence of key strokes once each scan line was taken into account.

Several storage alignment restrictions were also added for individual displays. All bit maps must begin on hexword boundaries. All bit maps for multiple displays driven by a single controller must be the same size. The size of each scan line is fixed at 40 and 56 words for quarter page and 850 displays respectively; the programmer cannot reduce the size of the bit map by specifying the number of words per line. For reasons of storage and bandwidth efficency, the loops which transfer data from main storage to the 850 and quarter page displays are open coded. Each scan line of a large format display must begin on a hexword boundary.

# Inter-Office Memorandum

То	File	Date	October 13, 1978
From	Sandman	Location	Palo Alto
Subject	Thistle Trace Data	Organization	SDD/DE

XEROX

Filed on: [Iris] < Thistle > Doc > TraceData.bravo

This memo documents the steps taken to generate data for Thistle, the D0 simulator. Three systems were used as a source of the data: Apex, DeskTop, and DTest (a display test program for Alto/Mesa). The operations traced were those involved in displaying text on the screen.

The data was collected by using the module TraceKernel which supplied a trap handler and a breakpoint handler. The trap handler was invoked when the microcode fill the buffer with trace data. It flushed the buffer onto a pre-existing file. Tracing was disabled if the file had filled up. The breakpoint handler understood special conditional breakpoints which served to turn tracing on and off. The TraceKernel required one page of memory for its code and one page for the buffer.

All traces were done with interrupts disabled. Otherwise, seventy five percent of each page of data was required to trace the interrupt routine. This is because the trap handler must run with interrupts disabled, and takes sufficiently long so that an interrupt occurs each time the trap handler returns.

Before each trace, the operation was performed to make sure all modules involved had been started, and their code was in memory.

## Apex

The Apex used was obtained from Jerry Morrison and found on [Iris] < Morrison > Apex5.5 >. The documents and folders involved the data generation were loaded from in [Iris] < Morrison > Apex5.5 > SFS3.dm. Three traces were taken from Apex. The first traced the inner loop of displaying characters in a window. The second traced the whole process of opening a window, including setting up the border and menu items. The last traced the moving of a document from the desktop into a folder.

#### Apex A

Start: Entry to FillScreen in DocSwnPack. End: Exit from FillScreen in DocSwnPack. Operation: Opening Document 3.

#### ApexB

Start: Entry to Open in DocWnPack. End: Exit from Open in DocWnPack. Operation: Opening Document 3.

#### ApexC

Start: Entry to Move in IconPack. End: Exit from Move in IconPack. Operation: Moving Document 2 from desktop into Folder 1 on the desktop

## DeskTop

The DeskTop used was obtained from Scott McGregor and found on [Iris] < DeskTop > September13 >. The DeskTop system contained the following components: Nub, Test, FormsPad, DocRef, FileCabinet and End. Two traces were taken from DeskTop. The first traced the whole process of opening a window while the second was just the inner loop of painting the text in that window.

## DeskTopA

Start: Entry to PaintlnWindow in WindowUtilities. End: Exit from PaintlnWindow in WindowUtilities. Operation: Opening a form containing HelpTrainingDoc.form.

#### *DeskTopB*

Start: Entry to PaintFromFrame in DeskFrame. End: Exit from PaintFromFrame in DeskFrame. Operation: Opening a form containing HelpTrainingDoc.form

#### DTest

DTest is a program written by Richard Johnsson that tests the display package contained in the standard Alto/Mesa system. It was used to write a text file onto the display by putting bytes from a disk stream onto the standard display stream (which also writes a typescript file). Only one trace was taken with DTest. The file displayed was a portion of HelpTrainingDoc.form used in the DeskTop traces. It is stored on [Iris] < Thistle > DTest > DTest.txt.

#### DTest A

Start: At line ResetControlDEL of TypeFile in DTest. End: Exit from TypeFile in DTest. Operation: Displaying DTest.txt

Before any trace data was collected, some dynamic instruction mix studies were conducted to get a quick picture of the trace data. After the traces were taken, they were analyzed to obtain dynamic instruction mix of the trace data itself. These independent frequency studies showed that the disabling interrupts during tracing had negligible effect. A general observation on the frequency data is that both Apex and DeskTop call relatively few procedures and have larger local frames than DTest, which tended to call many procedures and have smaller local frames.

Alto/Mesa 4.1 of 30-Aug-78 9:48 12-Oct-78 8:44 >thistle -- 146604B Tables loaded from Thistle.binaryThistle of 11-Oct-78 19:10:20 Data from file: ApexA.tr

IBinary ?????????????load from file: Thacker.Binary
IInput instruction data from: OneLF.params
-- One Large Format display 40 frames/sec
IAlto Display off
IRun (1:46:49)

TIME		M	EMORY		PEND	DING	(	3	
usec	848039	) ma	:1	17	strt	:MC2	11 6	5	pc 306
cycles	9976941	l mo	2	0	new]	[nOK	0 (	3	buff 1
nxtDisp	9977095	5 ]s	stMem	Ε	trar	nsfr	1 13	3	
nxtRef	9977088	3							
			9		ылтт				9
LHOLATON TAC	5620552		- /o		1 mo 1		600	2012	م م
1011	0029002		).4 )		IIIC I		700	2013	0.0
τοτωαιτ	2240832		2.5		mc z		/01	1294	7.6
					susper	nd	521	1661	5.2
					NewIns	st	359	3864	3.6
DISPLAY TASK	<b>κ</b>		%		WAIT				%
กับก	1441141	1 14	1.4		тс1		338	3256	3.3
totWait	457059	, <u> </u>	1.5		mc2			Õ	0.0
					susner	hd	11/	3803	1.1
					000000				
REFRESH TASK	κ		%		WAIT				%
run	170052	2 1	1.7		mc1		2 :	1621	0.2
totWait	32305	i (	).3		susper	nd	10	0684	0.1
COND JUMPS		57.1	THE (	יטטב		. D.	TSPLAY	/ OM	
count	19116	011	-10C (	.000	21321		ount		20603
VTDIE	10110	2001			16 2		iccod		20000
AINUL	40.1	ave			10.0	111	13360		0
		Cur			12				
INSTRUCTION	229951				% A(	TIVE		FI	AGS
[110] W2		dPage	1308	3	mc1	49.	6	L.	DNGT ON
wNIII I		dByte	742	,	mc2	43	8		KNT ON
y Wn		20,00	, 40	-	hzy	11	2	n -	ifiv VFS
<b>VU</b> 11		tack.	Emul		529	11.	Tack	hot	$11 1 \times 123$
		19271	LINUIC	1001			Iask	ner	NGCII 04

Alto/Mesa 4.1 of 30-Aug-78 9:48 12-Oct-78 9:43 >Thistle -- 146604B Tables loaded from Thistle.binary Thistle of 11-Oct-78 19:10:20 Data from file: ApexA.tr

lBinary load from file: Thacker.binary lInput instruction data from: TwoLF.params -- Two Large Format displays 40 frames/sec lAlto Display off lRun (1:38:47)

TIME		MEMORY		PENDING		0	
usec	1092368	mc1	17	strtMC2	11	6	pc 306
cycles	12851391	mc2	5	newInOK	0	6	buff 1
nxtDisp	12851239	lstMem	Ε	transfr	1	13	
nxtRef	12851520						

EMULATOR TAS	SK		%	WAIT			%
run	5629552	43	3.8	mc1	1050	533	8.1
totWait	2122443	18	5.5	mc2	446	229	3.4
				suspend	I 380	073	2.9
				NewInst	245	608	1.9
DISPLAY TASK	(		%	WAIT			%
run	3521538	27	1.4	mc1	994	506	7.7
totWait	1300554	. 10	1.1	mc2		0	0.0
				suspend	306	048	2.3
REFRESH TASK	۰. ۲		%	WAIT			%
run	219048	. 1	1.7	mc1	47	696	0.3
totWait	58256	(	.4	suspend	10	560	0.0
COND JUMPS		ST I	INE CODI	E	DISPLAY	ON	
count	18116	cour	nt	21324	count		38112
%TRUE	40.1	ave		16.3	missed		135
		cur		12			
INSTRUCTION	229951		. *	% ACT	IVE	FLAG	s
[110] W2		dPage	1306	mc1	64.6	LONG	TON
WNULL		dBvte	742	mc2	62.0	UNKN	TON
xWn		- ,		bzv	7.1	niFi	x YES
		task:	Emulato	r	Task	betwee	n 34

Alto/Mesa 4.1 of 30-Aug-78 9:48 11-Oct-78 19:28 >Thistle -- 148604B Tables loaded from Thistle.binary Thistle of 11-Oct-78 19:10:20 Data from file: ApexA.tr

IBinary load from file: Thacker.arams Binary file format wrong File not found IBinary load from file: Thacker.binary IInput instruction data from: OneFP.params -- One Full Page display 37.5 frames/sec IAlto Display off IRun (1:27:50)

TIME usec cycles nxtDisp nxtRef	928510 10923654 10923709 10923968	MEMORY mc1 mc2 lstMem	PEND 17 strt 0 newI E trans	ING MC2 11 nOK 0 sfr 1 1	0 6 pc 306 6 buff 1 3
					•
EMULATOR TA	SK	%	WAIT		%
run	5629552	51.5	mc1	72	7207 6.6
totWait	2059591	18.8	mc2	58	0977 5.3
			suspen	d 45	1535 4.1
			NewIns	t 29	9872 2.7
DISPLAY TAS	K.	%	WAIT		%
run	2045907	18.7	mc1	76	9327 7.0
totWait	970159	8.8	mc2		0 0.0
	0.0100	0.0	suspen	d 20	0832 1.8
REERESH TAS	ĸ	%	WAIT		%
run	186192	1.7	mc1	2	1826 0 1
totWait	32253	0.2	suspen	d 1	0427 0.0
	01100	0.1	ouopun	• •	0.0
COND JUMPS		ST LINE (	CODE	DISPLA	Y ON
count	18116	count	21324	count	42339
%TRUE	40.1	ave	16.3	missed	0
		cur	12		
INSTRUCTION	229951		% AC	TIVE	FLAGS
[110] W2		dPage 130	6 mc1	52.9	LONGT ON
WNULĹ		dByte 74	2 mc2	48.6	UNKNT ON
xWn		5	bzv	9.9	niFix YES
		task: Emula	ator	Task	between 34

Alto/Mesa 4.1 of 30-Aug-78 9:48 12-Oct-78 8:09 >thistle -- 146604B Tables loaded from Thistle.binary Thistle of 11-Oct-78 19:10:20 Data from file: ApexA.tr

lBinary load from file: Thacker.inary lInput instruction data from: TwoFP.params -- Two Full Page displays 37.5 frames/sec lAlto Display off lRun (1:29:25)

TIME		MEMORY		PENDING		0		
usec	946225	mc1	17	strtMC2	11	6	pc	306
cycles	11132064	mc2	0	newInOK	0	6	buft	f 1
nxtDisp	11132173	lstMem	Ε	transfr	1	13		
nxtRef	11132352							

EMULATOR TA run totWait	5K 5629552 2031155	50 18	% .5 .2	WAIT mc1 mc2 suspenc NewInst	771 548 1 431 278	1977 3623 1681 3874	% 6.9 4.9 3.8 2.5
DISPLAY TAS run totWait	<pre>{   2149090   1098363</pre>	19 9	% .3 .8	WAIT mc1 mc2 suspenc	873 I 224	3488 0 1875	% 7.8 0.0 2.0
REFRESH TAS run totWait	<pre>     189744     34160 </pre>	1 0	% .7 .3	WAIT mc1 suspenc	23 I 10	863 297	% 0.2 0.0
COND JUMPS count %TRUE	18116 40.1	ST L coun ave cur	INE COD t	E 21324 16.3 12	DISPLAY count missed	Y ON	23199 19948
INSTRUCTION [110] W2 wNULL xWn	229951	dPage dByte task:	1306 .742 Emulato	% ACT mc1 mc2 bzy r	IVE 54.4 50.5 9.4 Task	FLA LON UNK niF betwe	GS GT ON NT ON ix YES en 30

Alto/Mesa 4.1 of 30-Aug-78 9:48 12-Oct-78 9:48 >Thistle -- 146604B Tables loaded from Thistle.binary Thistle of 11-Oct-78 19:10:20 Data from file: ApexA.tr

lBinary load from file: Thacker.binary lInput instruction data from: FourQP.params -- Four Quarter Page display 30 frames/sec lAlto Display off lRun (1:30:19)

TIME usec cycles nxtDisp nxtRef	938850 11045296 11045389 11045760	MEMORY mc1 mc2 1stMem	17 0 E	PENDING strtMC2 newInOK transfr	11 0 1	0 6 13	pc 306 buff 1
EMULATOR	TASK	. %		WAIT			%
run	5629552	50.9		mc1	5	71334	5.1
totWait	1860762	16.8		mc2	5	57782	5.0
				suspend	4	35523	3.9
				NewInst	2	96123	2.6
DISPLAY 1	ASK	%		WAIT			%
run	2352336	21 2		mc1	7	54457	6.8

totWait	988539	) (	8.9	mc2		0	0.0
				suspend	234	082	2.1
REFRESH TAS	к		%	WAIT			%
run	188268	3 :	1.7	mc1	15	845	0.1
totWait	25839	• (	0.2	suspend	g	994	0.0
COND JUMPS		ST I	LINE COD	DE	DISPLAY	ON	
count	18116	cour	nt	21324	count		14786
%TRUE	40.1	ave		16.3	missed		0
		cur		12			
INSTRUCTION	229951			% ACT	IVE	FLAG	SS
[110] W2		dPage	1306	mc1	51.7	LONG	GT ON
ŴNULĹ		dByte	742	mc2	48.1	UNKN	IT ON
x₩n		5		bzy	10.0	niFi	ix YES
		task:	Emulato	or	Task	betwee	en 34

Alto/Mesa 4.1 of 30-Aug-78 9:48 12-Oct-78 10:29 >thistle -- 146604B Tables loaded from Thistle.binaryThistle of 11-Oct-78 19:10:20 Data from file: ApexB.tr

IBinary load from file: Thacker.binary IInput instruction data from: OneLF.params -- One Large Format display 40 frames/sec IAlto Display off IRun (2:30:20)

TIME		MEMORY	•	PENDING		Q	
usec	1552497	mc1	17	strtMC2	11	6	pc 306
cycles	18264677	mc2	2	newInOK	0	6	buff 1
nxtDisp	18264871	lstMem	Ε	transfr	1	13	
nxtRef	18265280						

EMULATOR TASK	%	WAIT		%
run 9991245	54.7	mc1	1214742	6.6
totWait 4379351	23.9	mc2	1572406	8.6
		suspend	980229	5.3
		NewInst	611974	3.3
DISPLAY TASK	%	WAIT		%
run 2637397	14.4	mc1	649821	3.5
totWait 881520	4.8	mc2	0	0.0
		suspend	231699	1.2
REFRESH TASK	%	WAIT		%
run 311328	1.7	mc1	42571	0.2
totWait 63836	0.3	suspend	21265	0.1
COND JUMPS	ST LINE COD	E	DISPLAY ON	
count 38658	count	47290	count	54359
%TRUE 45.8	ave	13.7	missed	0
	cur	12		
INSTRUCTION 427624		% ACTI	VE FLA	IGS
F1107 W2	dPage 2456	mc1 5	0.6 100	IGT ON
WNIII I	dByte 577	mc2 4	4.7 UNK	NT ON
xWn		hzv 1	1.9 niF	ix YES
	task: Emulato		Task betwe	en 12

Data from file: ApexB.tr

IBinary load from file: Thacker.binary
IInput instruction data from: TwoLF.params
-- Two Large Format displays 40 frames/sec
IAlto Display off
IRun (4:01:00)

TIME		MEMORY	PEND	ING	Q	
usec	2002181	mc1	17 strt	MC2 11	6	pc 306
cycles	23555077	mc2	0 newI	nOK 0	6	buff 1
nxtDisp	23555191	lstMem	E tran	sfr 1	13	
nxtRef	23555136					
	ASK	2	WATT			%
run	9991245	42 A	mc1	. 20	157070	87
totWait	4093849	17 3	mc2		132815	30
cocharb	4050045	17.0	SUSDAN	d	01076	2 0
			NewIns	t 4	102879	1.7
DISPLAY TA	SK	%	WAIT			%
run	6458762	27.4	mc1	19	02691	8.0
totWait	2499131	10.6	mc2		0	0.0
			suspen	d (	596440	2.5
REFRESH TA	SK	%	WAIT			%
run	401496	1.7	mc1	•	89490	0.3
<b>t</b> otWait	110594	0.4	suspen	d	21104	0.0
COND JUMPS	5	ST LINE (	ODE	DISPL	AY ON	
count	38658	count	47290	count	;	69893
%TRUE	45.8	ave	13.7	misse	ed	211
		cur	12			
INSTRUCTIO	N 427624		% AC	TIVE	FI	AGS
[110] W2		dPage 2456	6 mc1	65.4	L	DNGT ON
WNULL		dByte 577	mc2	62.7	UI	NKNT ON
xWn			bzy	7.4	n	ifix YES
		task: Emula	tor	Tas	sk betv	veen 34

Alto/Mesa 4.1 of 30-Aug-78 9:48 12-Oct-78 8:20 >thistle -- 146604B Tables loaded from Thistle.binaryThistle of 11-Oct-78 19:10:20 Data from file: ApexB.tr

IBinary load from file: Thacker.binary IInput instruction data from: OneFP.params -- One Full Page display 37.5 frames/sec IAlto Display off IRun (2:44:42)

340848

TIME		MEMORY		PENDING		0		
usec	1699718	mc1	17	strtMC2	11	6	pc 306	
cycles	19996693	mc2	0	newInOK	0	6	buff 1	
nxtDisp	19996795	lstMem	Ε	transfr	1	13		
nxtRef	19997120							
FMIII ATOR	TASK	%		WATT			%	
r!!n	9991245	49.9		mc1	14	27895	7.1	
totWait	3992694	19.9		mc2	12	20987	6.1	
				suspend	2	39479	4.1	
				NewInst	E	04333	2.5	
DISPLAY	TASK	%		WAIT			% .	
run	3744962	18.7		mc1	14	68095	7.3	
totWait	1864738	9.3		mc2		0	0.0	
				suspend	3	96643	1.9	
REFRESH	TASK	%		WAIT			%	

totWait	62206		1.3	suspend	20	)218	0.1
COND JUMPS		STI	LINE CODE		DISPLAY	ON	
count	38658	cour	าะ	47290	count		77506
%TRUE	45.8	ave		13.7	missed		0
		cur		12			
INSTRUCTION	427624			% AC1	IVE	FL	AGS
[110] W2		dPage	2456	mc1	53.8	LOI	NGT ON
WNULL		dByte	577	mc2	49.4	UNI	KNT ON
x₩n		•		bzy	10.4	nil	Fix YES
		task:	Emulator	-	Task	betwe	een 22

mc1

41988

0.2

1.7

Data from file:

run

Alto/Mesa 4.1 of 30-Aug-78 9:48 12-Oct-78 8:31 >thistle -- 146604B Tables loaded from Thistle.binaryThistle of 11-Oct-78 19:10:20 Data from file: ApexB.tr

IBinary load from file: Thacker.binary IInput instruction data from: TwoFP.params -- Two Full Page displays 37.5 frames/sec IAlto Display off IRun (2:48:19)

TIME		MEMORY		PENDING		0	
usec	1736251	mc1	17	strtMC2	11	6	pc 306
cycles	20426486	mc2	0	newInOK	0	6	buff 1
nxtDisp	20426623	lstMem	Ε	transfr	1	13	
nxtRef	20426560						

EMULATOR TA	SK	·	%	WAIT			%
run	9991245	48	3.9	mc1	1523	055	7.4
totWait	3922254	19	3.2	mc2	1127	045	5.5
				suspend	801	682	3.9
				NewInst	470	472	2.3
DISPLAY TAS	к		%	WAIT			%
run	3972292	19	3.4	mc1	1684	136	8.2
totWait	2126365	1	).4	mc2		0	0.0
				suspend	442	229	2.1
REFRESH TAS	к		%	WAIT			%
run	348168	1	1.7	mc1	45	483	0.2
totWait	66162	: (	).3	suspend	20	679	0.1
COND JUMPS		ST I	INE COD	)E	DISPLAY	ON	
count	38658	cour	nt	47290	count		42878
%TRUE	45.8	ave		13.7	missed		36294
		cur		12			
INSTRUCTION	427624			% ACT	IVE	FLA	GS
[110] W2		dPage	2456	mc1	55.5	LON	GT ON
WNULL		dByte	577	mc2	51.5	UNK	NT ON
xWn		0		bzy	9.9	niF	ix YES
		task:	Emulato	r	Task	betwe	en 22

lInput instruction data from: XXX lBinary load from file: Thacker.binary lInput instruction data from: FourQP.params -- Four Quarter Page display 30 frames/sec lAlto Display off lRun (2:52:43)

.

TIME usec cycles nxtDisp nxtRef	1720528 20241509 20241708 20242112	ME 3 mc 3 mc 3 1 s	EMORY 21 22 stMem	17 0 E	PEND strt newI tran	ING MC2 nOK sfr	11 ( 0 ( 1 13	3 5 5 3	pc 3 buff	306 1
EMULATOR TA run totWait	SK 9991245 3606859	i 49 i 17	% 9.3 7.8		WAIT mc1 mc2 suspen NewIns	d t	114 116 81 48	5910 1628 3006 6315	5 2 2	% 5.6 5.7 4.0 2.4
DISPLAY TAS run totWait	K 4310040 1937412	22	% L.2 J.5		WAIT mc1 mc2 suspen	đ	1482 454	2841 0 4571	7	% /.3 ).0 2.2
REFRESH TAS run totWait	X 345024 50929	4 1 ) (	% L.7 ).2		WAIT mc1 suspen	d	3 19	1284 9645	0	% ).1 ).0
COND JUMPS count %TRUE	38658 45.8	ST L cour ave cur	_INE ( ht	CODE	47290 13.7 12	DI co mi	SPLA unt ssed	YON	270	)97 0
INSTRUCTION [110] W2 wNULL xWn	427624	dPage dByte task:	2456 577 Emula	) n ator	% AC mc1 mc2 bzy	TIVE 52.6 48.9 10.5	Task	Fi L( UN n betw	.AGS DNGT C NKNT C IFix Y veen	)N )N (ES 22

IBinary load from file: Thacker.binary IInput instruction data from: OneLF.params -- One Large Format display 40 frames/sec IAlto Display off IRun (1:08:10)

TIME		ME	MORY		PEND	ING		Q		
usec	645063	l mo	:1	17	strt	MC2	11	6	pc 3	370
cycles	7588981	l mo	:2	-0	newI	nOK	0	6	buff	7
nxtDisp	7589143	1 15	tMem	Ε	tran	sfr	1	13		
nxtRef	7589120	)								
EMULATOR TAS	SK		%		WAIT					%
run	3853042	2 50	).7		mc1		5	43869	-	7.1
totWait	2072735	5 27	.3		mc2		8	30853	10	0.9
					suspen	d	4	50322	_	5.9
					NewIns	t	2	47691		3.2
DISPLAY TAS	<b>‹</b>		%		WAIT					%
run	1096398	3 14	1.4		mc1		2	98588		3.9
totWait	407836	6 5	i.3		mc2			0	. (	0.0
					suspen	d	1	09248		1.4
REFRESH TAS	<b>〈</b>		%		WAIT			-		%
run	129348	3 1	.7		mc1			<b>19656</b>	(	0.2
totWait	29622	<u>,</u>	).3		suspen	d		9966	(	0.1
COND JUMPS		ST L	INE	CODE		D	ESPL	AY ON		
count	29517	cour	nt		28096	C	ount		22	586
%TRUE	38.9	ave			11.4	៣	isse	d		0
		cur			12					
INSTRUCTION	209374				% AC	TIVE		F	LAGS	•
[110] W2		dPage	122	6	mc1	52.	5	L	ONGT (	DN
wNULĒ		dByte	41:	3	mc2	46.7	7	U	VKNT (	ON
xWn					bzy	13.	7	n	iFix `	YES
		task:	Emula	ator	•		Tas	k bet	ween	4

lBinary load from file: Thacker.binary lInput instruction data from: TwoLF.params -- Two Large Format displays 40 frames/sec lAlto Display off lRun (1:20:56)

TIME		ME	MORY		PEND	ING	0			
usec	838452	m	:1	17	strtM	1C2 1	1 6		pc	370
cvcles	9864147	m	:2	0	newIr	пОК	06		buff	7
nxtDisp	9864199	1:	stMem	Ε	trans	sfr	1 13			
nxtRef	9864448	1								
EMULATOR TAS	sĸ		%		WAIT					%
run	3853042	39	0.0		mc1		9353	308		9.4
totWait	1905053	19	.3		mc2		5118	380		5.1
					susnend	1	3146	684		3.1
					NewInst		1431	181		1.4
						-				
DISPLAY TASK	(		%		WAIT					%
run	2711296	27	1.4		mc1		8963	348		9.0
totWait	1177118	11	1.9		mc2			0		0.0
					suspend	ł	2807	770		2.8
DEEDEOU TACA	,		97		WATT					
REFRESH INSP	100100		/3   7		WALL		201			6 0 0
	100132				MC1		393	044		0.3
totwait	49000	• •	0.0		suspend		10	184		0.1
COND JUMPS		ST L	.INE (	CODE	•	DIS	PLAY	ON		
count	29517	cour	nt		28096	cou	nt		29	344
%TRUE	38.9	ave			11.4	mis	sed			13
		cur			12					
INSTRUCTION	209374				% ACT	TVF		FI	AGS	
F1107 W2	2000/4	dPane	1226	ì	mc1	66.8		10	NGT	ON
WNHI I		dBvte	410	3	mc2	64 2		HIM	KNT	0N
xWn		20900	710	-	hzv	8 4		ni	Fix	YES
A911		task:	Emula	ator	023	т Т	ask b	netw	een	4
						•				

lBinary load from file: Thacker.binary lInput instruction data from: OneFP.params -- One Full Page display 37.5 frames/sec lAlto Display off lRun (1:14:12)

TIME usec cycles nxtDisp nxtRef	708837 8339267 8339323 8339584	ME 7 mc 7 mc 3 1 s	EMORY :1 :2 stMem	17 0 E	PEND strt newI tran	ING MC2 nOK sfr	(0 11 6 0 6 1 13		pc buft	370 F 7
EMULATOR TAS	SK		%		WAIT					%
run	3853042	2 46	5.2		mc1		633	951		7.6
totWait	1874306	5 22	2.4		mc2		661	150		7.9
					suspen	d	379	1573		4.5
					NewIns	t	199	632		2.3
DISPLAY TAS	<		%		WAIT					%
run	1561730	) 18	3.7		mc1	· ·	688	719		8.2
totWait	878152	2 10	).5		mc2			0		0.0
		•			suspen	d	189	433		2.2
REFRESH TAS	ζ		%		WAIT					%
run	142140	) 1	.7		mc1		19	631		0.2
totWait	29897	7 (	).3		suspen	d	10	266		0.1
COND JUMPS		ST I	INE (		-	DI	SPI AY	ON		
count	29517	COUL	nt		28096	co	unt		32	2322
%TRUE	38.9	ave			11.4	mi	ssed			0
		cur			12					-
INSTRUCTION	209374				% AC	TIVE		FI	AGS	
[110] W2		dPage	1226	5	mc1	55.6	5	Ĺ	DNGT	ON
WNULL		dBvte	413	3	mc2	51.1		Ū	IKNT	ON
xWn		- J			bzv	12.0	)	'n	iFix	YES
		task:	Emula	ator			Task	betv	veen	4

IBinary load from file: Thacker.binary IInput instruction data from: TwoFP.params -- Two Full Page displays 37.5 frames/sec IAlto Display off IRun (1:16:45)

TIME		ME	MORY		PEND.	ING	0		
usec	737939	n mc	:1	17	strtl	MC2 1	1 6	pc	370
cycles	8681643	l mo	:2	0	newI	nOK	06	buf	f 7
nxtDisp	8681689	1 15	tMem	Ε	tran	sfr	1 13		
nxtRef	8681728	5							
EMULATOR TAS	SK .		%		WAIT				%
run	3853042	44	1.3		mc1		7282	64	8.3
totWait	1815598	20	).9		mc2		5505	38	6.3
					suspen	d	3526	79	4.0
					NewIns	t	1841	17	2.1
DISDIAV TAS	,		9		ωлтт				9/
DISFERI INSP	1702/60	20	/a ) 6		mc1		8170	9.9	0 /
+ 0+1421+	10/1007	1 20	0.0		101 mo2		01/9	00	9.4
LOLWAIL	1041007				EUCDOD.	d	2230	00	2.5
					auspen	u	2230	55	2.0
REFRESH TASH	κ		%		WAIT			-	%
run	147972	: 1	.7		mc1		216	36	0.2
totWait	31494	+ 0	).3		suspen	đ	98	58	0.1
COND JUMPS		ST L	INE (	CODE		DIS	PLAY	ON	
count	29517	cour	nt		28096	cou	int	1	9343
%TRUE	38.9	ave			11.4	mis	sed	1	4306
		cur			12				
INSTRUCTION	209374				% AC	TIVE		FLAGS	
E1107 W2	200014	dPane	1226	3	mc1	58 4		LONGT	ON
wNHIII		dRvte	413	, i	mc2	54 7		LUNKNT	ON
xWn		20300	-114		hzv	10.8		niFix	YES
		task:	Emula	ator	529	T	ask b	etween	4

lBinary load from file: Thacker.binary lInput instruction data from: FourQP.params -- Four Quarter Page display 30 frames/sec lAlto Display off lRun (1:15:49)

TIME		ME	MORY		PEND	ING		0	
usec	716112	mo	:1	17	strt	MC2	11	6	pc 370
cvcles	8424856	i no	:2	0	newI	nOK	0	6	buff 7
nxtDiso	8424913	15	tMem	Ē	tran	sfr	1 1	3	
nxtRef	8425472			-			~ .		
EMULATOR TAS	SK		%		WAIT				%
run	3853042	45	5.7		mc1		52	1485	6.1
totWait	1698736	20	).1		mc2		62	2447	7.3
					suspen	d	36	69908	4.3
					NewIns	t	. 18	84896	2.1
DISPLAY TASH	(		%		WAIT				%
run	1793568	21	1.2		mc1		69	9547	8.3
totWait	912221	. 10	).8		mc2			0	0.0
					suspen	d	21	2674	2.5
REFRESH TASH	c		2		WAIT				%
run	143604	L 1	1.7		mc1		1	4205	0.1
totWait	23685	6 (	).2		suspen	đ		9480	0.1
COND JUMPS		ST I	INE (	CODE		D:	ESPLA	Y ON	
count	29517	cour	it		28096	C	ount		11278
%TRUE	38.9	ave			11.4	m	issed	1	0
		cur			12				-
INSTRUCTION	209374		·		% AC	TIVE		F	AGS
E1107 W2		dPage	1221	6	mc1	54.3	3	L	DNGT ON
wNHII		dByte	41:	3	mc2	50	5	- E	NKNT ON
xWn			12	-	hzv	11.9	3	n.	iFix YES
		task:	Emula	ator			Task	: bet	ween 4

Thistle of 11-Oct-78 19:10:20 Data from file: DeskTopA.tr

lBinary load from file: Thacker.binary lInput instruction data from: OneLF.params -- One Large Format display 40 frames/sec lAlto Display off lRun (56:27)

TIME		ME	MORY		PEND	ING		0		
usec	627988	3 mc	:1	17	strt	MC2	11	6	pc 370	
cycles	7388105	i ma	:2	0	newI	nOK	0	6	buff 7	
nxtDisp	7388215	i 18	tMem	Ε	tran	sfr	1	13		
nxtRef	7388480	)								
EMULATOR TA	SK		%		WAIT				%	
run	4341578	i 58	3.7		mc1		3	80316	5.1	
totWait	1483082	2 20	).0		mc2		4	63740	6.2	
					suspen	d	3	84616	5.2	
					NewIns	t	2	54410	3.4	
DISPLAY TAS	к		%		WAIT				%	
run	1066988	3 14	1.4		mc1		2	57559	3.4	
totWait	345218	3 4	1.6		mc2			0	0.0	
					suspen	d		87659	1.1	
REFRESH TAS	к		%		WAIT				%	
run	125928	3 1	1.7		mc1			17088	0.2	
totWait	25314	ļ (	).3		suspen	d		8226	0.1	
COND JUMPS		ST I	INE	CODE	Ξ	D	ISPL	AY ON	*	
count	16509	cour	nt		17877	C	ount		21988	
%TRUE	77.4	ave			15.7	m	isse	d	0	
		cur			12					
INSTRUCTION	166584				% AC	TIVE		F	LAGS	
[110] W2		dPage	104	5	mc1	46.3	1	L	ONGT ON	
WNULL		dByte	25	6	mc2	41.2	2	U	NKNT ON	
xWn					bzy	10.	5	'n	iFix YES	
		task:	Emula	ator	•		Tas	k bet	ween 4	

Thistle of 11-Oct-78 19:10:20 Data from file: DeskTopA.tr

lBinary load from file: Thacker.binary lInput instruction data from: TwoLF.params -- Two Large Format displays 40 frames/sec lAlto Display off lRun (1:08:26)

TIME		ME	MORY		PENDI	NG	Q			
usec	806689	ma	:1	17	strtM	IC2 1	1 6		DC	370
cvcles	9490461	ma	2	6	newIn	IOK	0 6		bufi	7
nxtDisn	9490567	15	tMem	F	trans	fr	1 13			-
nxtRef	9490624			-						
								-		
EMULATOR TAS	SK		%		WAIT					%
run	4341575	45	5.7		mc1		629	409		6.6
totWait	1348104	. 14	1.2		mc2		279	638		2.9
					suspend	j	282	147		2.9
					NewInst	:	156	910		1.6
DISPLAY TASK	C C		%		WAIT					%
<b>r</b> บก	2608413	27	.4		mc1		763	078		8.0
totWait	987757	10	).4		mc2			0		0.0
					suspend	j	224	679		2.3
REFRESH TASH	(		%		WAIT					%
run	161760	) 1	.7		mc1		34	723		0.3
totWait	42852	(	).4		suspend	1	8	129		0.0
COND JUMPS		ST I	.INE (	CODE	E	DIS	PLAY	ON		
count	16509	cour	nt		17877	COL	int		28	3221
%TRUE	77.4	ave			15.7	mis	sed			24
		cur			12					
INSTRUCTION	166584				% AC1	IVE		FI	LAGS	
[110] W2		dPage	104	5	mc1	62.1		L	ONGT	ON
WNULĹ		dByťe	256	3	mc2	60.2		U	NKNT	ON
xWn		-			bzy	6.5		n	iFix	YES
		task:	Emula	ator	• -	T	ask	beti	ween	4

Thistle of 11-Oct-78 19:10:20 Data from file: DeskTopA.tr

lBinary load from file: Thacker.binary lInput instruction data from: OneFP.params -- One Full Page display 37.5 frames/sec lAlto Display off lRun (1:02:19)

TIME		ME	MORY		PEND	ING	0			
usec	689754	mo	:1	17	strtl	4C2 1	1 6	1	pc	370
cycles	8114764	mo	:2	0	newl	nOK	06	Ì	buff	7
nxtDisp	8114863	1 19	tMem	Ε	trans	sfr	1 13			
nxtRef	8115008	5								
EMULATOR TAS	SK		%		WAIT					%
run	4341575	i 53	1.5		mc1		4583	324		5.6
totWait	1356503	16	5.7		mc2		3658	328		4.5
					suspend	d	3310	)54		4.0
					NewIns	t	2012	297		2.4
DISPLAY TASK	(		%		WAIT					%
run	1519932	. 18	3.7		mc1		5831	l52		7.1
totWait	734040	) (	0.0		mc2			0		0.0
					suspen	d	1508	388		1.8
REFRESH TASK	< Contract of the second se		%		WAIT					%
run	138312	! 1	7		mc1 ·		163	379		0.2
totWait	24402	2 (	).3		suspend	d.	80	)23		0.0
COND JUMPS		ST I	.INE (	CODE		DIS	PLAY	ON		
count	16509	cour	nt		17877	cou	nt		31	452
%TRUE	77.4	ave			15.7	mis	sed			0
		cur			12					
INSTRUCTION	166584				% AC	TIVE		FL	AGS	
[110] W2		dPage	104	5	mc1	49.7		L0	NGT	ON
wNULL		dByte	256	5	mc2	46.2		UN	KNT	ON
xWn					bzy	9.1		ni	Fix	YES
		task:	Emula	ator		Т	ask t	petw	een	4

IBinary load from file: Thacker.binary IInput instruction data from: TwoFP.params -- Two Full Page displays 37.5 frames/sec IAlto Display off IRun (1:03:28)

TIME		ME	MORY		PEND	ING		0			
usec	704595	mc	1	17	strt	MC2	11	6	рc	370	
cycles	8289360	mc	2	5	newI	nOK	0	6	buf	f 7	
nxtDisp	8289271	. 1s	tMem	Ε	tran	sfr	1 1	13			
nxtRef	8289600	i									
EMULATOR TA	SK		%		WAIT				•	%	
run	4341575	52	.3		mc1		47	79809		5.7	
totWait	1316634	15	.8		mc2		33	37561		4.0	
					suspen	d	31	15817		3.8	
					NewIns	t	18	33447		2.2	
DISPLAY TAS	ĸ		%		WAIT					x	
run	1619763	19	. 5		mc1		67	/3523		8.1	
totWait	843478	10	.1		mc2			0		0.0	
					suspen	d	16	9955		2.0	
REFRESH TAS	κ		%		WAIT			•		%	
run	141288	1	.7		mc1		1	18922		0.2	
totWait	26622	. 0	.3		suspen	d		7700		0.0	
COND JUMPS		ST L	INE (	CODE		DJ	SPLA	Y ON			
count	16509	coun	t		17877	CC	ount		1	7479	
%TRUE	77.4	ave			15.7	i m	issec	1	1	4649	
		cur			12						
INSTRUCTION	166584				% AC	TIVE		F	LAĠS		
[110] W2		dPage	1049	5	mc1	51.5	)	L	ONGT	ON	
wNULL		dByte	256	5	mc2	48.5	;	U	NKNT	ON	
xWn					bzy	8.7	'	n	iFix	YES	
		task:	Emula	ator	•		Task	c bet	#een	4	

lBinary load from file: Thacker.binary lInput instruction data from: FourQP.params -- Four Quarter Page display 30 frames/sec lAlto Display off lRun (1:04:00)

TIME		MEMORY	PENDI	NG Q	
usec	698251	l mc1	17 strtM	C2 11 6	pc 370
cycles	8214727	/ mc2	0 newIn	OK 0 6	buff 7
nxtDisp	8215006	6 lstMem	E trans	fr 113	
nxtRef	8214976	5			
EMULATOR TA	SK	%	WAIT		%
run	4341578	52.8	mc1	35451	9 4.3
totWait	1218655	5 14.8	mc2	34533	2 4.2
			suspend	32228	5 3.9
			NewInst	19651	9 2.3
DISPLAY TAS	K	%	WAIT		%
้านก	1749496	5 21.2	mc1	57188	4 6.9
totWait	744239	9.0	mc2		0 0.0
			suspend	17235	5 2.0
PEEDESH TAS	x	9	WATT		9
run	140016	; 17	mc1	1288	5 0 1
totWait	20746	5 0 2	suspand	786	1 0.1
COCHAIS	20140	0.2	suspend	700	1 0.0
COND JUMPS		ST LINE C	ODE	DISPLAY O	N
count	16509	count	17877	count	10997
%TRUE	77.4	ave	15.7	missed	0
		cur	12	1 a.	
INSTRUCTION	166584		% ACT	IVE	FLAGS
[110] W2		dPage 1045	mc1	48.4	LONGT ON
WNULL		dByte 256	mc2	45.7	UNKNT ON
xWn		2	bzy	9.3	niFix YES
		task: Emula	tor	Task be	tween 4

lBinary load from file: Thacker.binary lInput instruction data from: OneLF.params -- One Large Format display 40 frames/sec lAlto Display off lRun (41:25)

TIME usec cycles nxtDisp nxtRef	478097 5624680 5624887 5624960	ME mo mo s l	MORY 1 2 tMem	17 0. E	PEND strti newI tran	ING MC2 nOK sfr	0 11 6 0 6 1 13	) ; ;	pc 37 buff	70 7
EMULATOR TA	sĸ		%	. 1	AIT					%
run	3404682	. 60	1.5	ſ	nc1		247	353	4.	. 3
totWait	1040486	5 18	. 4	ſ	nc2		322	716	5	.7
					susnen	d	288	864	5	1
				1	NewIns	t	181	553	3.	.2
DISPLAY TAS	к		%	١	AIT					%
run	812396	6 14	.4	ſ	nc1		187	895	3.	. 3
totWait	252699	) 4	1.4	ſ	nc2			0	0.	. 0
				:	suspen	d	64	1804	1.	. 1
REFRESH TAS	к		%	۱	TIAN			•		%
run	95868	3 1	7	ſ	nc1		12	2475	0.	. 2
totWait	18549	0	1.3	:	suspen	d	e	6074	0.	. 1
COND JUMPS		ST L	INE (	CODE		DI	SPLAY	ON		
count	13795	coun	nt		14167	co	unt		1674	40
%TRUE	82.2	ave			15.1	mi	ssed			0
		cur			12					
INSTRUCTION	121125				% AC	TIVE		F	AGS	
[110] W2		dPage	637	7	mc1	44.0	)	L	DNGT ON	1
WNULĹ		dByte	242	2	mc2	39.7	ŕ	U	IKNT ON	1
xWn		~			bzy	10.1	L	n	iFix YE	ES
		task:	Emula	ator	-		Task	bet	veen	4

Thistle of 11-Oct-78 19:10:20 Data from file: DeskTopB.tr

IBinary load from file: Thacker.binary IInput instruction data from: TwoLF.params -- Two Large Format displays 40 frames/sec IQuit [Confirm]XXX IAlto Display off IRun (50:33)

TIME		MEMORY		PENDING		Q	
usec	611508	mc1	17	strtMC2	11	6	pc 370
cycles	7194214	mc2	0	newInOK	0	6	buff 7
nxtDisp	7194343	lstMem	Ε	transfr	1	13	
nxtRef	7194880						

EMULATOR TA run totWait	SK 3404682 940683	47 13	% 7.3 3.0	WAIT mc1 mc2 suspend NewInst	4178 1983 2143 1103	300 160 399 324	% 5.8 2.7 2.9 1.5
DISPLAY TAS run totWait	K 1977801 716803	27	% 7.4 9.9	WAIT mc1 mc2 suspend	5513	325 0 478	% 7.6 0.0 2.3
REFRESH TAS run totWait	K - 122628 31617	1	% 1.7 ).4	WAIT mc1 suspend	256 59	694 923	% 0.3 0.0
COND JUMPS count %TRUE	13795 82.2	ST L cour ave cur	INE COD	E 14167 15.1 12	DISPLAY count missed	ON	21399 12
INSTRUCTION [110] W2 wNULL xWn	121125	dPage dByte task:	637 242 Emulato	% ACT mc1 mc2 bzy	IVE 60.5 59.1 6.3 Task H	FLA LON UNK niF	GS GT ON NT ON ix YES en 4

Thistle of 11-Oct-78 19:10:20 Data from file: DeskTopB.tr

lBinary load from file: Thacker.binary lInput instruction data from: OneFP.params -- One Full Page display 37.5 frames/sec lAlto Display off lRun (45:38)

TIME usec cycles nxtDisp nxtRef	524298 6168220 6168253 6168448	ME mo mo s 1s	MORY 1 2 tMem	17 0 E	PEND strt newI tran	ING MC2 1 nOK sfr	0 1 6 0 6 1 13	pc bufi	370 7 7
EMULATOR TA	SK		%		WAIT		2076		%
run	05200/	1 DC 1 16		1	mc1		3073	94	4.9
LULWAIL	902034	• 10			NICZ Gueren	d	2030	00 a <i>l</i> i	4.1
					NowTre	u +	1/20	26 .	4.0
					NGMT112	6	1429	30	2.5
DISPLAY TAS	ĸ		%	-	WATT				%
run	1155219	) 18	3.7		mc1		4204	92	6.8
totWait	532009	) 8	3.6		mc2			0	0.0
		-			suspen	d	1115	17	1.8
<b>REFRESH TAS</b>	К		%		WAIT				%
run	105132	2 1	.7	·	mc1		121	76	0.1
totWait	18084	+ (	).2		suspen	d	59	08	0.0
COND HIMPS		ст I	THE	-005		סזמ	עאוס	ON	
count	13795	COUR	-1195 ( 17	JUDL	14167	CO1	int	23	3907
XTRUE	82 2	ave	• •		15 1	mis	sed		,
ATTOL	00,2	CHC			12				Ũ
		007							
INSTRUCTION	121125				% AC	TIVE		FLAGS	
[110] W2		dPage	637	7	mc1	47.7		LONGT	ON
ŴNULĹ		dByte	242	2	mc2	44.8		UNKNT	ON
xWn					bzy	8.8		niFix	YES
		task:	Emula	ator		T	ask b	etween	. 4

lBinary load from file: Thacker.binary lInput instruction data from: TwoFP.params -- Two Full Page displays 37.5 frames/sec lAlto Display off lRun (47:46)

TIME		M	EMORY		PEND	ING		0		
usec	536090	) ma	:1	17	strt	MC2	11	6	pc 370	3
cvcles	6306951	L ma	:2	0	newI	nOK	0	6	buff .	7
nxtDisn	6307057	/ ]:	stMem	E	tran	sfr	1	13		
nxtRef	6307136	3		-		•••	-	~~		
	0007100	•								
	SK .		٧		WATT				•	X
run	3404682	5	şα		mc1		3	20479	5 (	3
totWait	022101	- 00	1 6		mc?		2	2/057	2 -	7
LUCWAIL	322101		Ŧ.U		11164 CUCDOD	А	2	20027	3.1	7
					NowToo	u 1	4	20021	3.	,
					MEATU2	6	1	20030	2.0	J
DISPLAY TASK	<b>(</b>		%		WAIT					K,
run	1235360	) 19	9.5		mc1		4	91675	7.3	7
totWait	617699	9. 9	9.7		mc2			0	0.0	)
					suspen	d	1	26024	1.9	9
DECOCOU TAR	,		9/		1.1 A T T					,
REFRESH INSP	107405		~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		WALL					6
FUN	107490	· ·	1.1		HIC L			14000	0.4	2
totwart	1961;	s i	1.3		suspen	a		5607	0.0	J
COND JUMPS		ST I	INE (	CODE		DI	SPL	AY ON		
count	13795	cour	nt		14167	cc	ount		13328	3
%TRUE	82.2	ave			15.1	mi	isse	d	11117	7
		cur			12					
THETOUCTION	101405					<b>7 1</b> 1 / 1 =				
INSTRUCTION	121125	10		-	% AC	I I VE		F	LAGS	
LIIN] WZ		arage	63	1	mc1	49.1		L	JNGI UN	
WNULL		dByte	247	2	mc2	47.2		U	NKNI ON	
xWn				_	bzy	8.3	3	n	iFix YES	S
		task:	Emula	ator			fas	k beti	ween 4	4

lBinary load from file: Thacker.binary lInput instruction data from: FourQP.params -- Four Quarter Page display 30 frames/sec lAlto Display off lRun (1:03:03)

TIME		ME	MORY		PEND	ING		0		
usec	531446	6 mc	:1	17	strt	MC2	11	6	pc 370	}
cycles	6252309	) ma	:2	0	newI	nOK	0	6	buff 7	· .
nxtDisp	6252637	/ 19	tMem	Ε	tran	sfr	1	13		
nxtRef	6252928	3								
EMULATOR TA	SK		%		WAIT				%	,
run	3404682	2 54	1.4		mc1		2	35360	3.7	
totWait	860832	2 13	3.7		mc2		2	40915	3.8	L .
					suspen	d	2	43901	3.9	)
					NewIns	t	1	40656	2.2	2
DISPLAY TAS	ĸ		%		WAIT				%	<u>;</u>
run	1332464	21	.3		mc1		4	06184	6.4	F
totWait	532844	4 4	3.5		mc2			0	0.0	)
					suspen	d	1	26660	2.0	)
REFRESH TAS	K		%		WAIT				2	5
run	106572	2 1	1.7		mc1			8994	0.1	
totWait	14918	i (	).2		suspen	d		5921	0.0	1
COND JUMPS		ST I	INE (	CODE	Ξ	D	ISPL	AY ON		
count	13795	cour	nt		14167	C	ount		8370	)
%TRUE	82.2	ave			15.1	m	isse	d	C	}
		cur			12					
INSTRUCTION	121125				% AC	TIVE		F	LAGS	
[110] W2		dPage	63	7	mc1	46.	5	L	ONGT ON	
WNULL		dByte	24	2	mc2	44.3	3	U	NKNT ON	
xWn					bzy	9.0	)	n	iFix YES	;
		task:	Emula	ator	•		Tas	k bet	ween 4	F.

IBinary load from file: Thacker.binary IInput instruction data from: OneLF.params -- One Large Format display 40 frames/sec IQuit [Confirm]XXX IAlto Display off IRun (3:30:03)

TIME usec cycles nxtDisp nxtRef	2225385 26181006 26181031 26181056	MEMO mc1 mc2 lstM	RY 17 0 em E	PENDI strtM newIn trans	NG C2 11 OK O fr 1	0 6 13	pc 370 buff 7
FMULATOR T	ASK	. %		WAIT			%
run	13687458	52.2		mc1	20	05059	76
totWait	6798525	25.9		mc2	28	12289	10 7
000000	0100010			susnend	15	14457	5.7
				NewInst	4	66720	1.7
	sx	2		WATT			%
run	3780205	14 4		mc1	. 10	15814	3.8
totWait	1367606	5.2		mc2		0	0.0
				suspend	3	51792	1.3
REFRESH TA	SX	%		WAIT			%
run	446256	1.7		mc1		71982	0.2
totWait	100956	0.3		suspend		28974	0.1
COND JUMPS	1	ST LIN	E CODE		DISPL	AY ON	
count	45197	count		73266	count		77919
%TRUE	38.1	ave		10.3	misse	d	0
		cur		12			
INSTRUCTIO	N 468492			% АСТ	IVE	FL	AGS
[110] W2		dPage 2	765	mc1	51.8	LC	NGT ON
พัพบเป		dByte	57	mc2	45.1	U	IKNT ON
x₩n		-		bzy	12.4	ni	Fix YES
		task: Em	ulator		Tas	k betv	leen 4

Thistle of 11-Oct-78 19:10:20 Data from file: blThacker.binary

Data from file: DTestA.tr

IBinary load from file: Thacker.binary IInput instruction data from: TwoLF.params -- Two Large Format displays 40 frames/sec IAlto Display off IRun (4:12:53)

.

TIME		MEMOR	Y	PEND	ENG	Q	
usec	2856278	mc1	17	strtM	4C2 11	6	pc 370
cvcles	33603282	mc2	0	newIr	10K 0	6	buff 7
nxtDisp	33603271	. 1stMei	m E	trans	sfr 1	13	
nxtRef	33603328	k i i i i i i i i i i i i i i i i i i i					
EMULATOR T	ASK	%	۷	<b>TIA</b>			%
run	13687458	40.7	n	nc1	31	47874	9.3
totWait	6188813	18.4	n	nc2	16	52542	4.9
			5	suspend	j 11	17838	3.3
			1	VewInst	t 2	70559	0.8
DISPLAY TA	SK	%	٧	VAIT			%
run	9240643	27.4	· n	nc1	28	82999	8.5
totWait	3751331	. 11.1	n	nc2		0	0.0
			5	suspend	8 <sup>'</sup> b	68332	2.5
				•			
REFRESH TA	SK.	%	٧	VAIT			%
run	572772	1.7	រា	nc1	1	31125	0.3
totWait	162265	0.4	5	suspend	ť	31140	0.0
COND JUMPS		ST LINE	CODE		DISPL	AY ON	
count	45197	count	7	73266	count		100003
%TRUE	38.1	ave		10.3	misse	d	. 6
		cur		12			
TNOTOLOTTO							
INSTRUCTIO	N 468492	10 07	<u>-</u>	% AL	IIVE	11	AGS
[110] WZ	•.	urage 2/	00	mc1	00.0		NGI UN
WNULL		anàra	51	mc2	03.3	UN	IKNI UN
xWn				bzy	1.6	ni	IFIX YES
		task: Emu	lator		Tas	k betv	veen 4

Alto/Mesa 4.1 of 30-Aug-78 9:48 12-Oct-78 9:22 >Thistle -- 146604B Tables loaded from Thistle.binary Thistle of 11-Oct-78 19:10:20 Data from file: DTestA.tr

IBinary load from file: Thacker.binary IInput instruction data from: OneFP.params -- One Full Page display 37.5 frames/sec IDO Display off IAlto Display off IDO Display on IRun (3:49:49)

TIME		MEI	40RY		PEND	ING	6	3			
usec	2432034	mc:	1 1	7	strti	MC2	11 E	3	pc	370	
cycles	28612171	mc:	2	0	newI	nOK	0 6	3	bufi	f 7	
nxtDisp	28612200	) 1s <sup>-</sup>	tMem	E.	tran	sfr	1 13	3			
nxtRef	28612672	2									
EMULATOR	TASK		%	W	AIT					%	
run	13687458	3 47	. 8	m	:1		2282	2026		7.9	
totWait	6167919	21	. 5	m	:2		2203	3124		7.6	
				S	uspen	d	131:	1729		4.5	
				N	ewIns	t	37:	1040		1.2	
DISPLAY 1	ASK		%	W	AIT					%	
run	5358339	18	.7	m	51		2227	7346		7.7	
totWait	2815023	3 9	. 8	m	c2 <sup>`</sup>	•		0		0.0	
				S	uspen	d	587	7677		2.0	
REFRESH T	ASK		%	Ŵ	AIT					%	
run	487704	1	.7	m	:1		66	5931		0.2	
totWait	95728	8 0	. 3	S	uspen	d	28	3797		0.1	
COND JUMF	PS .	ST L	INE CO	DE		DI	SPLAY	Y ON			
count	45197	coun	t	73	3266	co	unt		11(	0899	
%TRUE	38.1	ave			10.3	mi	ssed			0	
•		cur			12						
INSTRUCTI	ON 468492				% AC	TIVE		F	LAGS		
[110] W2		dPage	2765		mc1	55.1		L	ONGT	ON	
WNULL		dByte	57		mc2	49.8		U	VKNT	ON	
x₩n					bzy	10.7	,	n	iFix	YES	
		task: 1	Emulat	or			Task	bet	veen	4	

lBinary load from file: Thacker.binary lInput instruction data from: TwoFP.params -- Two Full Page displays 37.5 frames/sec lAlto Display off lRun (3:53:54)

TIME usec cycles nxtDisp nxtRef	2475519 29123766 29123545 29123776	MEMOR mc1 mc2 i lstMe	17 5 9m E	PENDI strtM newIn trans	NG C2 11 OK O fr 1	0 6 6 13	pc 370 buff 7
EMULATOR	TASK	%		WAIT			%
run	13687458	46.9		mc1	23	374882	8.1
totWait	5975763	20.5		mc2	19	84234	6.8
				suspend	12	260351	4.3
				NewInst	3	356296	1.2
DISPLAY T	ASK	%		WAIT			%
run	5668926	19.4		mc1	25	643619	8.7
totWait	3194246	10.9		mc2		0	0.0
				suspend	6	50627	2.2
REFRESH T	ASK	%		WAIT			%
run	496416	i 1.7		mc1		72245	0.2
totWait	100957	0.3		suspend		28712	0.0
COND JUMP	S	ST LINE	E CODE	-	DISPL	AY ON	
count	45197	count		73266	count		61192
%TRUE	38.1	ave		10.3	misse	ed	51689
		cur		12			
INSTRUCTI	ON 468492			% ACT	IVE	FI	_AGS
[110] W2		dPage 27	65	mc1	56.8	LC	ONGT ON
WNULL		dByte	57	mc2	52.0	Ū	WENT ON
xWn		<b>J</b>		bzv	10.2	n'	iFix YES
		task: Emu	lator	5	Tas	sk betv	veen 4

lBinary load from file: Thacker.binary lInput instruction data from: FourQP.params -- Four Quarter Page display 30 frames/sec lAlto Display off lRun (3:56:49)

TIME		MEMORY	PEND	ING O	}	
usec	2457841	mc1 :	17 strtl	4C2 11 6	) pc	370
cycles	28915791	mc2	0 newI	nOK 0 6	) buf	f 7
nxtDisp	28915870	lstMem	E trans	sfr 113	3	
nxtRef	28916096					
EMULATOR	TASK	%	WAIT			%
run	13687458	47.3	mc1	1878	3348	6.4
totWait	5540649	19.1	mc2	2045	5320	7.0
			suspen	d 1275	571 <b>2</b>	4.4
			NewIns	t 341	1269	1.1
DISPLAY T	ASK	%	WAIT			%
run	6157368	21.2	mc1	2289	070	7.9
totWait	2957370	10.2	mc2		0	0.0
			suspen	d 668	3300	2.3
REFRESH T	ASK	%	WAIT			%
run	492876	1.7	mc1	51	942	0.1
totWait	80070	0.2	suspen	1 28	3128	0.0
COND JUMP	S	ST LINE CO	DDE	DISPLAY	ON	
count	45197	count	73266	count	3	8709
%TRUE	38.1	ave	10.3	missed		0
		cur	12			
INSTRUCTI	ON 468492		% AC	TIVE	FLAGS	
[110] W2		dPage 2765	mc1	53.8	LONGT	ON
ŴNULĹ		dByłe 57	mc2	49.4	UNKNT	ON
x₩n			bzy	10.8	niFix	YES
		task: Emula	tor	Task	hetween	4